

机器学习介绍 Introduction of Machine Learning

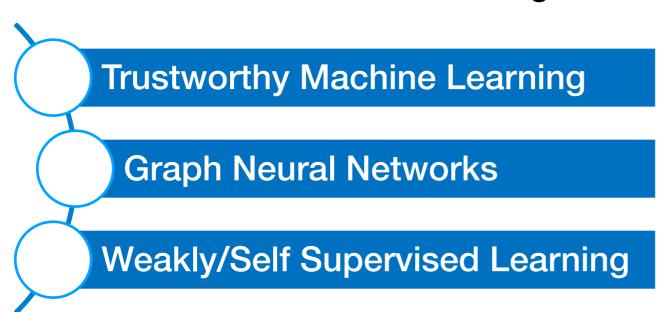


主讲人:王奕森



About Me

- Assistant Professor, Ph.D. Advisor
- Research Interests: Machine Learning



中国计算机学会推荐国际学术会议

(人工智能)





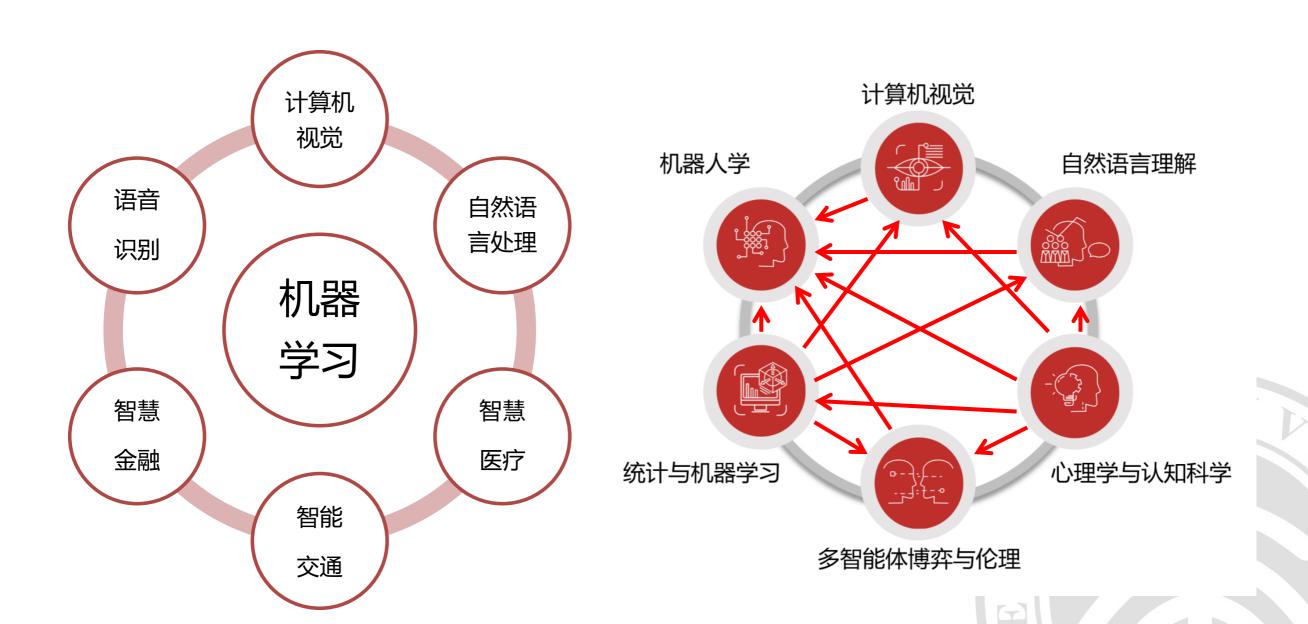
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序号	会议简称	会议全称	出版社	网址		
1	AAAI	AAAI Conference on Artificial Intelligence	AAAI	http://dblp.uni-trier.de/db/conf/aaai/		
2	NeurIPS	Annual Conference on Neural	MIT Press	http://dblp.uni-trier.de/db/conf/nips/		
	ACL	Information Processing Systems Annual Meeting of the				
3		Association for Computational Linguistics	ACL	http://dblp.uni-trier.de/db/conf/acl/		
4	CVPR	IEEE Conference on Computer Vision and Pattern Recognition	IEEE	http://dblp.uni-trier.de/db/conf/cvpr/		
5	ICCV	International Conference on Computer Vision	IEEE	http://dblp.uni-trier.de/db/conf/iccv/		
6	ICML	International Conference on Machine Learning	ACM	http://dblp.uni-trier.de/db/conf/icml/		
7	IJCAI	International Joint Conference on Artificial Intelligence	Morgan Kaufmann	http://dblp.uni-trier.de/db/conf/ijcai/		

ICLR, International Conference on Learning Representations



ML Is at The Core of AI & AI Class





What is Machine Learning?

 Machine Learning is for designing algorithms that can learn and build computable models from training data and then perform desired tasks on new data.

A computer program is said to learn from experience E with respect to some task T and some performance measure P, if its performance on T, as measure by P, improves with experience E.

So ML is not rule based and in principle it can enable machines to evolve.



Tom Mitchell (Member of NAE & AAAS, Prof. @ CMU)

Machine Learning

Machine Learning ≈ Looking for Function

Speech Recognition

$$f($$
 $)=$ "How are you"

Image Recognition



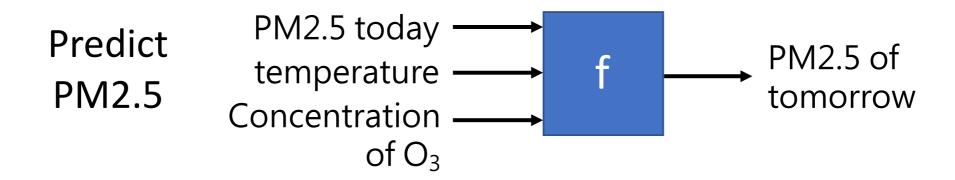
Playing Go



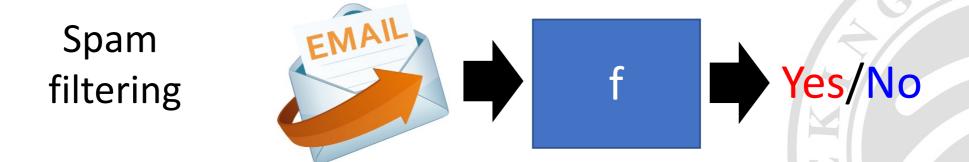


Different types of Functions

Regression: The function outputs a scalar.



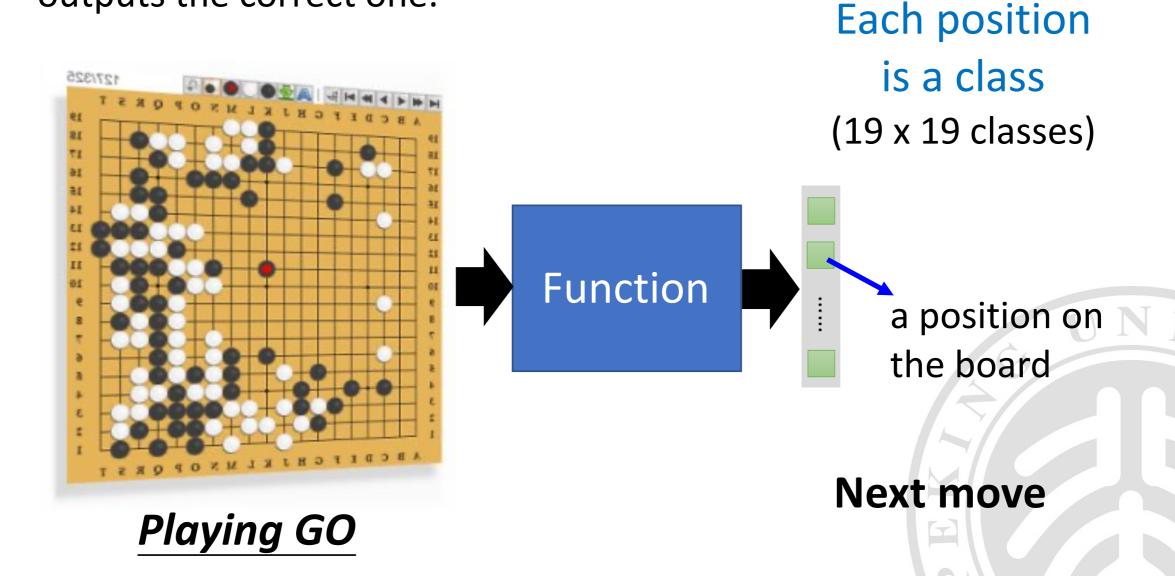
<u>Classification</u>: Given options (classes), the function outputs the correct one.





Different types of Functions

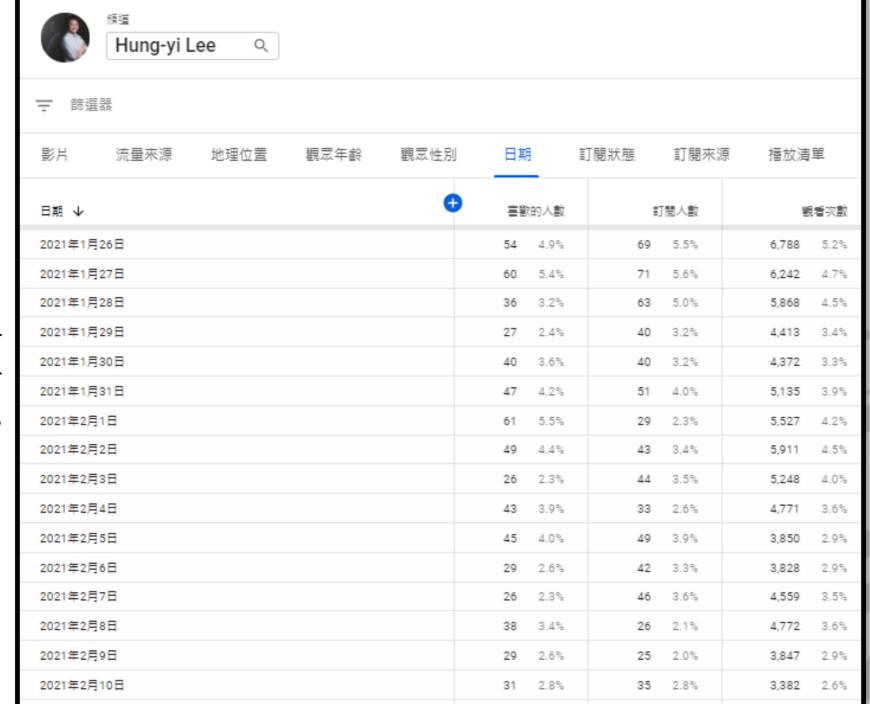
<u>Classification</u>: Given options (classes), the function outputs the correct one.





One example

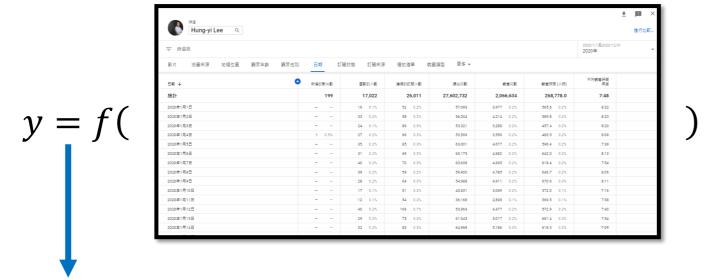
Taking examples (some slides) from Prof. Hungyi Lee@NTU



y = f(no. of views on 2/26



1) Function



Model $y = b + wx_1$ based on domain knowledge

feature

y: no. of views on 2/26, x_1 : no. of views on 2/25 w and b are unknown parameters (learned from data) weight bias



2) Loss

Defining Loss from Training Data > Loss: how good a set of

4.9k

- Loss is a function of parameters L(b, w)
- values is.

$$L(0.5k,1) \quad y = b + wx_1 \longrightarrow y = 0.5k + 1x_1 \quad \text{How good it is?}$$

$$Data \text{ from } 2017/01/01 - 2020/12/31$$

$$2017/01/01 \quad 01/02 \quad 01/03 \quad \dots \quad 2020/12/30 \quad 12/31$$

$$4.8k \quad 4.9k \quad 7.5k \qquad 3.4k \quad 9.8k$$

$$0.5k+1x_1 = y \quad 5.3k$$

$$0.5k+1x_1 = y \quad 5.3k$$

$$1 \text{ abel } \hat{y}$$

2) Loss

Defining Loss from Training Data > Loss: how good a set of

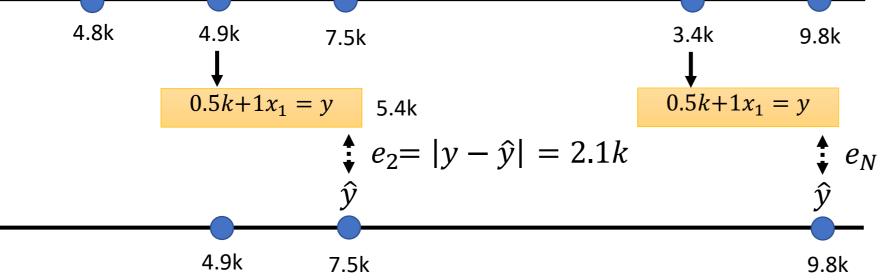
- Loss is a function of parameters L(b, w)
- values is.

$$L(0.5k, 1) y = b + wx_1 y = 0.5k + 1x_1 How good it is?$$

$$Data from 2017/01/01 - 2020/12/31$$

$$2017/01/01 01/02 01/03 2020/12/30 12/31$$

$$4.8k 4.9k 7.5k 3.4k 9.8k$$

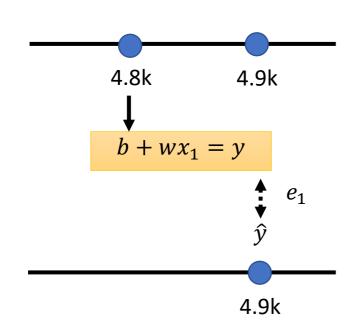




2) Loss

Defining Loss from Training Data > Loss: how good a set of

- Loss is a function of parameters L(b, w)
- values is.



Loss:
$$L = \frac{1}{N} \sum_{n} e_n$$

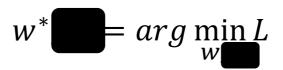
$$e = |y - \hat{y}|$$
 L is mean absolute error (MAE)

$$e = (y - \hat{y})^2$$
 L is mean square error (MSE)

If y and \hat{y} are both probability distributions \longrightarrow Cross-entropy $e = y \log \hat{y}$

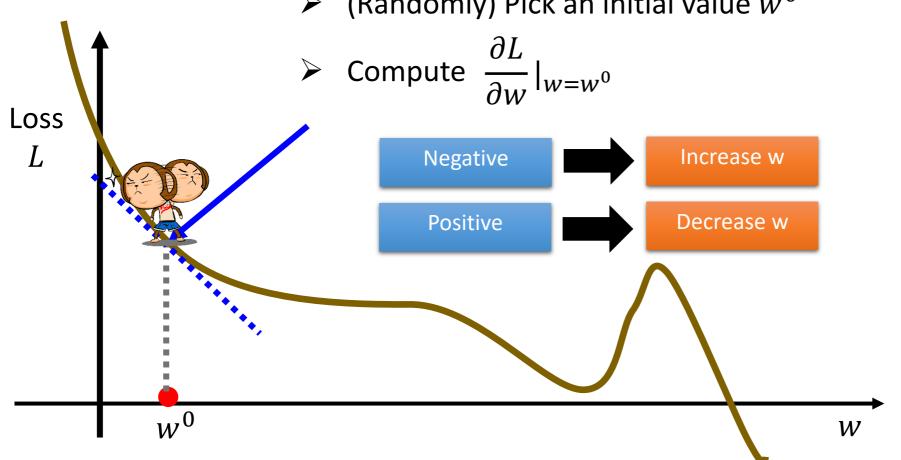


3) Optimization



Gradient Descent







3) Optimization

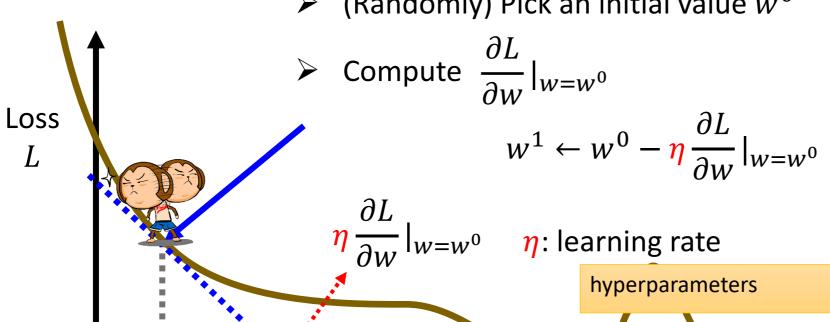
$$w^* = arg \min_{w} L$$

W

Gradient Descent

 w^1

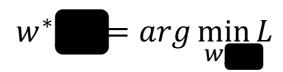
 \triangleright (Randomly) Pick an initial value w^0



Loss

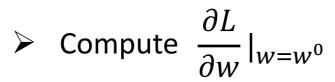
L

3) Optimization

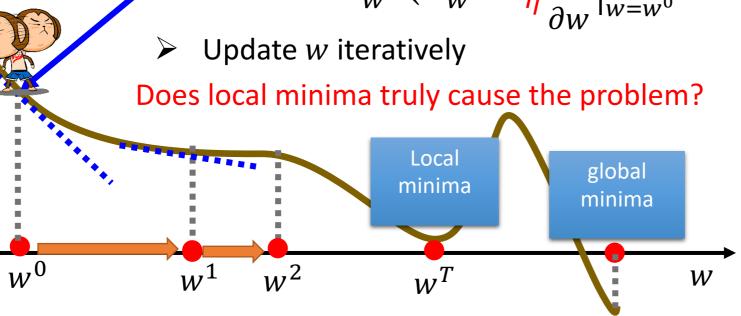


Gradient Descent

 \triangleright (Randomly) Pick an initial value w^0



$$w^1 \leftarrow w^0 - \frac{\partial L}{\partial w}|_{w=w^0}$$





3) Optimization

$$w^*, b^* = arg \min_{w,b} L$$

- \triangleright (Randomly) Pick initial values w^0 , b^0
- Compute

$$\frac{\partial L}{\partial w}|_{w=w^{0},b=b^{0}} \qquad w^{1} \leftarrow w^{0} - \eta \frac{\partial L}{\partial w}|_{w=w^{0},b=b^{0}}$$

$$\frac{\partial L}{\partial b}|_{w=w^{0},b=b^{0}} \qquad b^{1} \leftarrow b^{0} - \eta \frac{\partial L}{\partial b}|_{w=w^{0},b=b^{0}}$$

Can be done in one line in most deep learning frameworks

 \triangleright Update w and b interatively

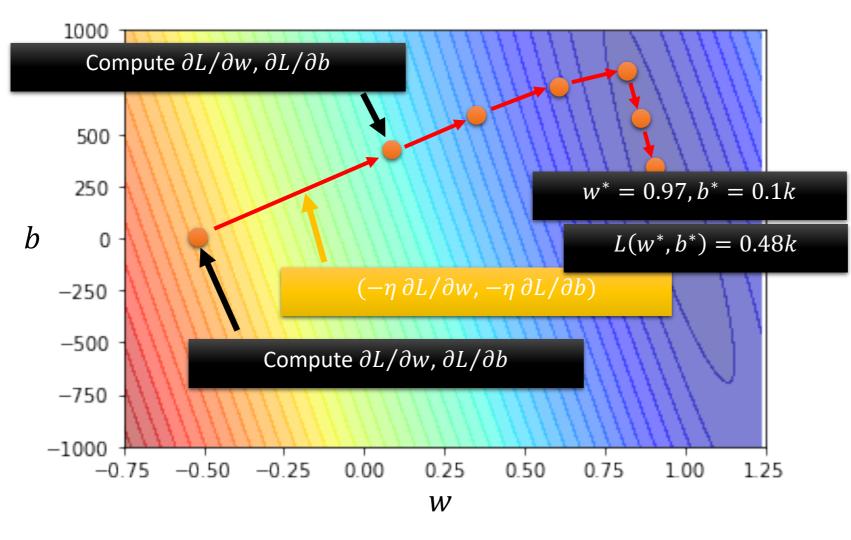




3) Optimization

Model
$$y = b + wx_1$$

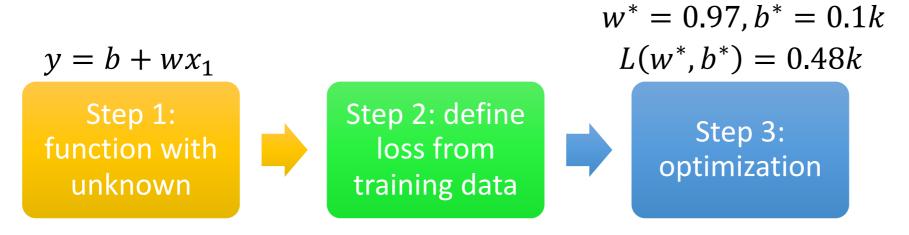
 $w^*, b^* = arg \min_{w,b} L$







Pipeline Summary







Machine Learning Pipeline



Training

 $y = 0.1k + 0.97x_1$ achieves the smallest loss L = 0.48k on data of 2017 – 2020 (training data)

How about data of 2021 (unseen during training)?

$$L' = 0.58k$$





More Inputs

$$y = b + wx_1$$

$$L = 0.48k$$

$$L = 0.48k$$
 $L' = 0.58k$

$$y = b + \sum_{j=1}^{7} w_j x_j$$

$$L = 0.38k$$

$$L = 0.38k$$
 $L' = 0.49k$

b	w_1^*	w_2^*	w_3^*	w_4^*	w_5^*	w_6^*	w_7^*
0.05k	0.79	-0.31	0.12	-0.01	-0.10	0.30	0.18

$$y = b + \sum_{i=1}^{28} w_i x_i$$

$$= 0.33k$$

$$L = 0.33k \qquad \qquad L' = 0.46k$$

$$y = b + \sum_{i=1}^{56} w_i x_i$$

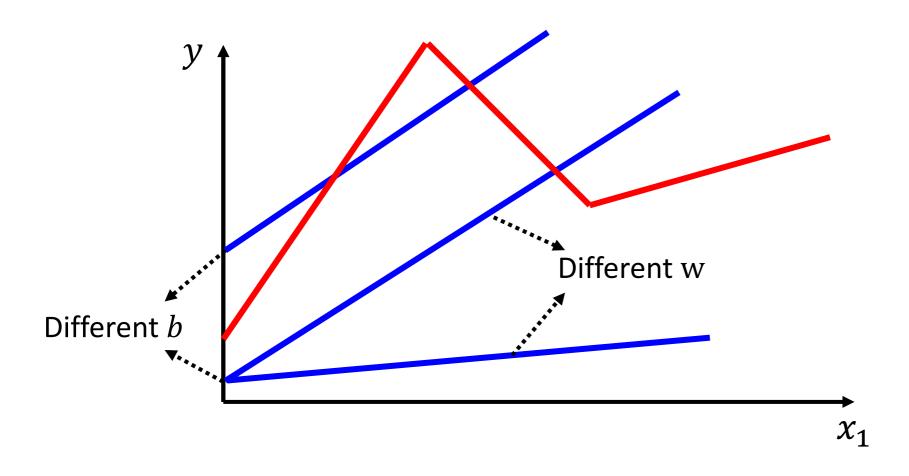
$$L = 0.32k \qquad \qquad L' = 0.46k$$

$$L' = 0.46k$$

Linear models



Linear models are always linear

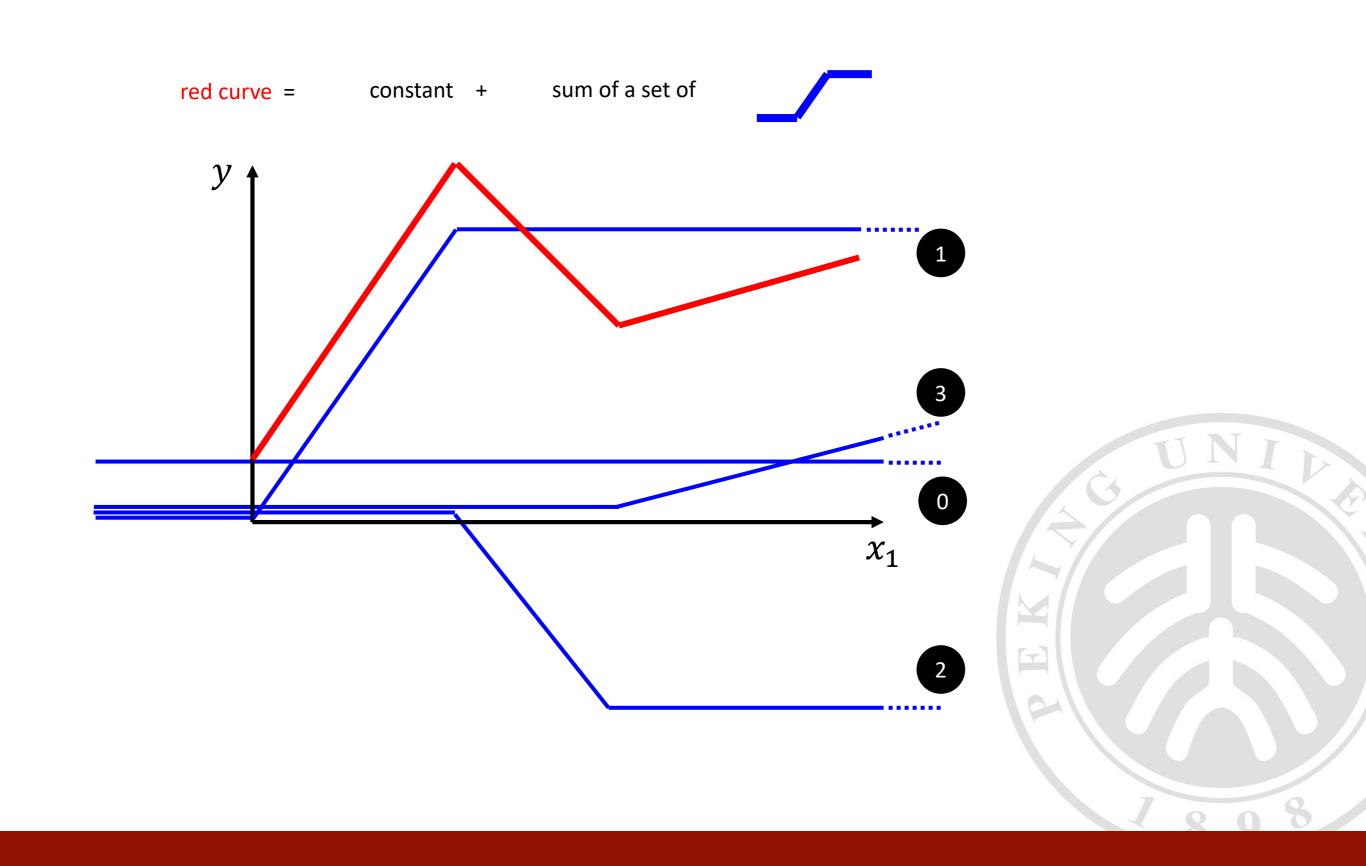


Linear models have severe limitation. *Model Bias*We need a more flexible model!



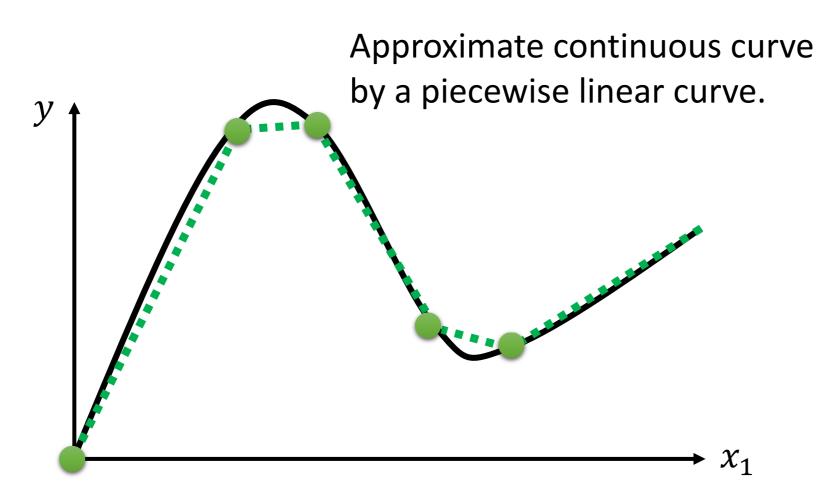


Piecewise Linear Curves





Beyond Piecewise Linear

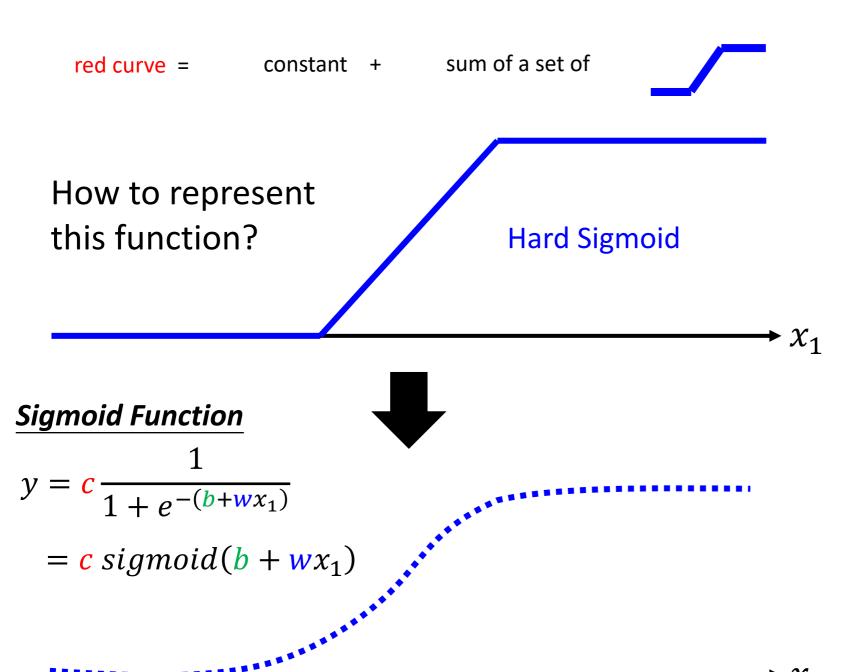


To have good approximation, we need sufficient pieces.





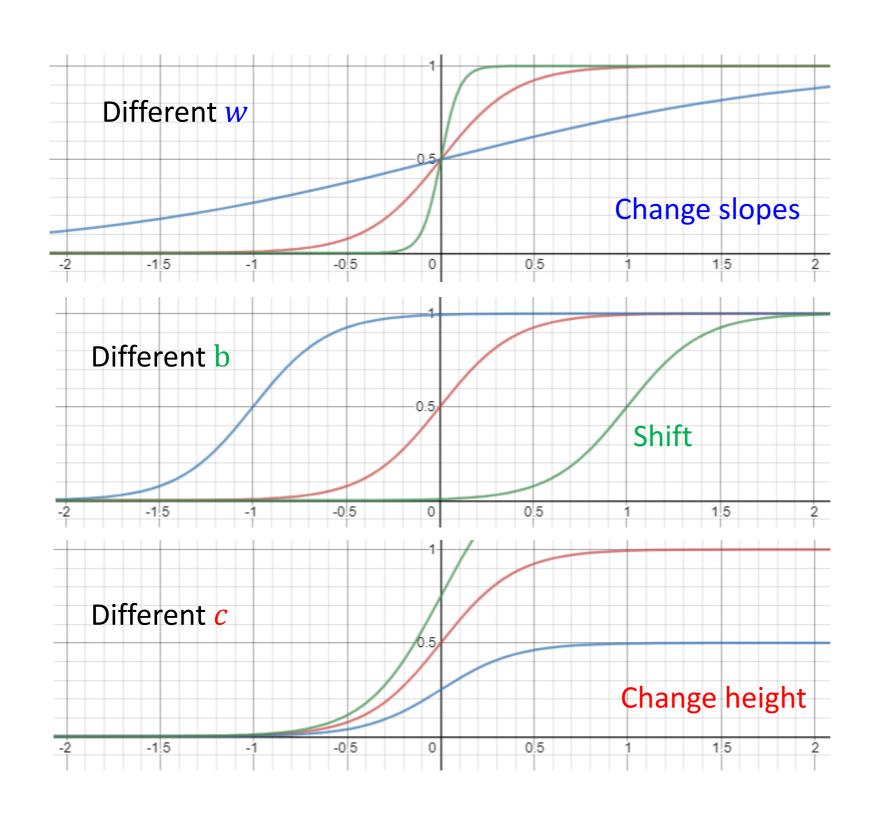
How to represent?





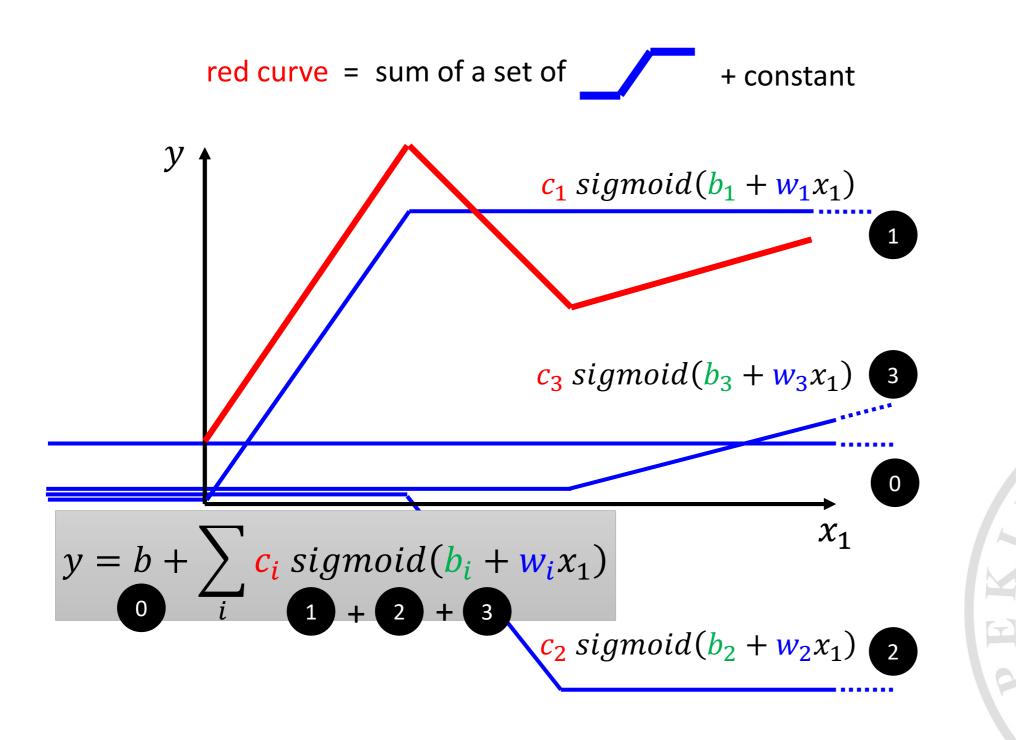


Property of sigmoid





The nonlinear becomes...





Similar for more inputs

$$y = b + wx_{1}$$

$$y = b + \sum_{i} c_{i} sigmoid(b_{i} + w_{i}x_{1})$$

$$y = b + \sum_{j} w_{j}x_{j}$$

$$y = b + \sum_{i} c_{i} sigmoid(b_{i} + \sum_{i} w_{ij}x_{i})$$



One example

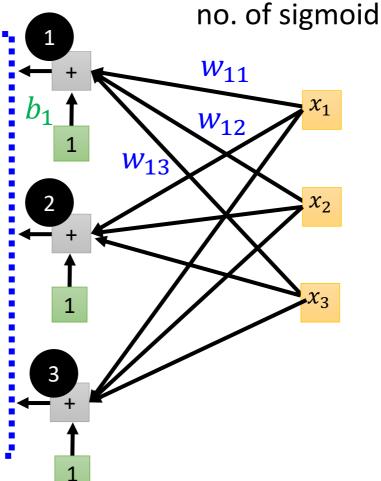
$$y = b + \sum_{i} c_{i} \ sigmoid \left(b_{i} + \sum_{j} w_{ij} x_{j}\right) \begin{array}{l} j: 1,2,3 \\ \text{no. of features} \\ i: 1,2,3 \end{array}$$

 $r_1 = b_1 + w_{11}x_1 + w_{12}x_2 + w_{13}x_3 \leftarrow +$

 w_{ij} : weight for x_j for i-th sigmoid

$$r_2 = b_2 + w_{21}x_1 + w_{22}x_2 + w_{23}x_3$$

$$r_3 = b_3 + w_{31}x_1 + w_{32}x_2 + w_{33}x_3$$





Matrix representation

$$y = b + \sum_{i} c_{i} \operatorname{sigmoid} \left(b_{i} + \sum_{j} w_{ij} x_{j} \right)$$
 i: 1,2,3 j: 1,2,3

$$r_1 = b_1 + w_{11}x_1 + w_{12}x_2 + w_{13}x_3$$

$$r_2 = b_2 + w_{21}x_1 + w_{22}x_2 + w_{23}x_3$$

$$r_3 = b_3 + w_{31}x_1 + w_{32}x_2 + w_{33}x_3$$

$$\begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} + \begin{bmatrix} w_{11} & w_{12} & w_{13} \\ w_{21} & w_{22} & w_{23} \\ w_{31} & w_{32} & w_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$|r| = |b| + |w|$$

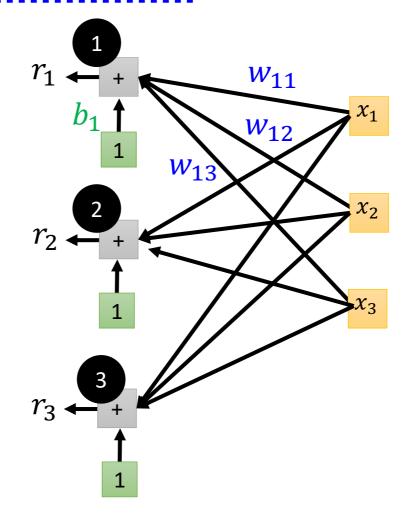




Matrix representation

$$y = b + \sum_{i} c_{i} sigmoid \left(b_{i} + \sum_{j} w_{ij} x_{j}\right)$$
 i: 1,2,3 j: 1,2,3

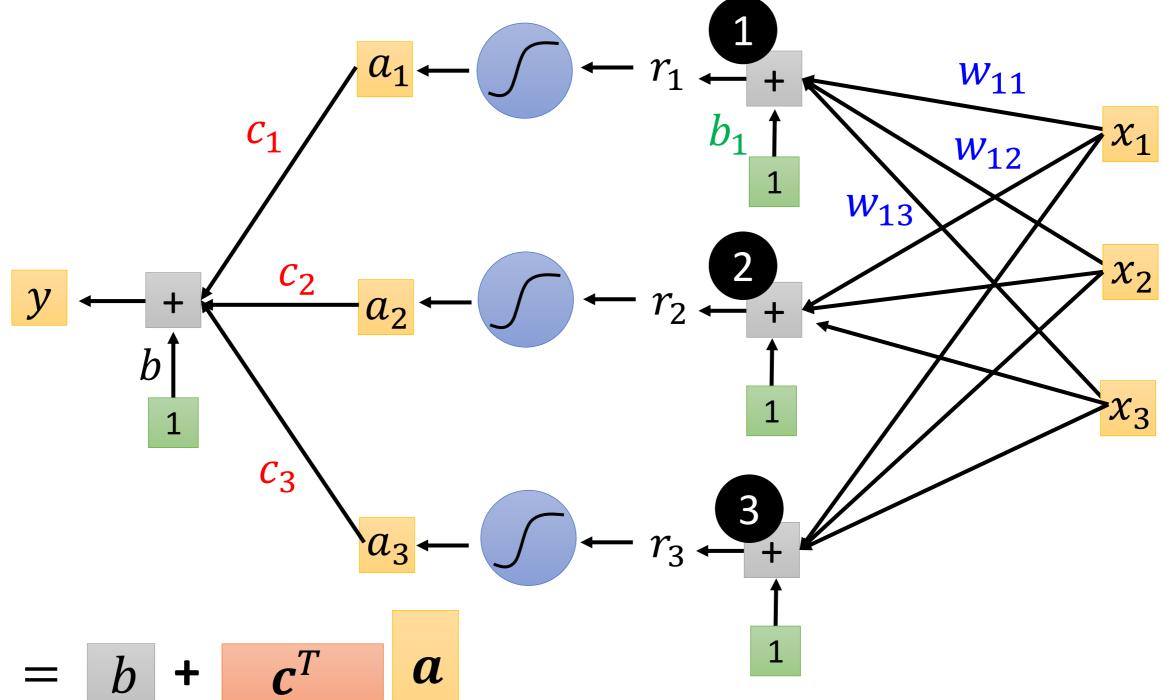
$$|r| = |b| + |W| x$$

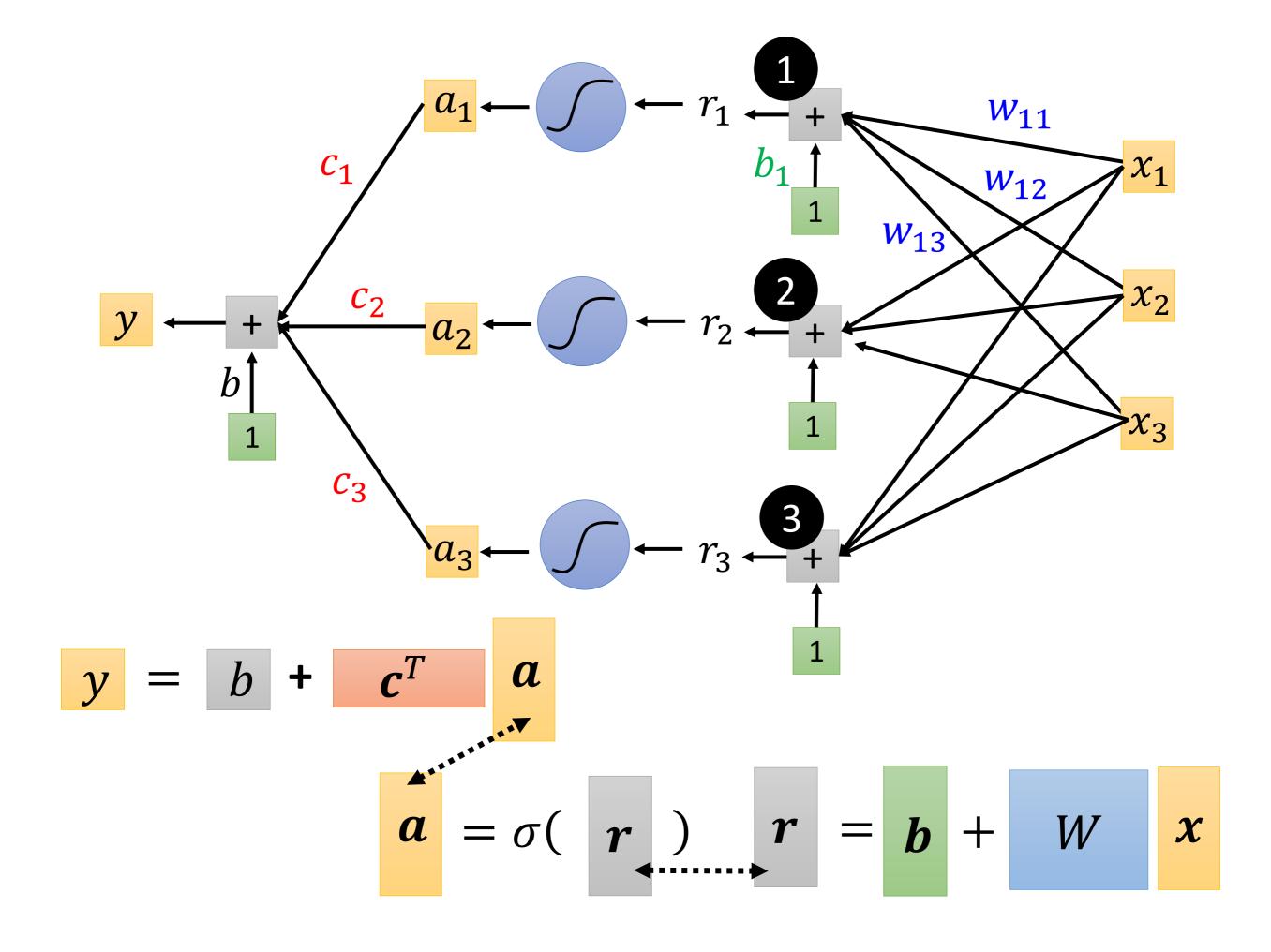


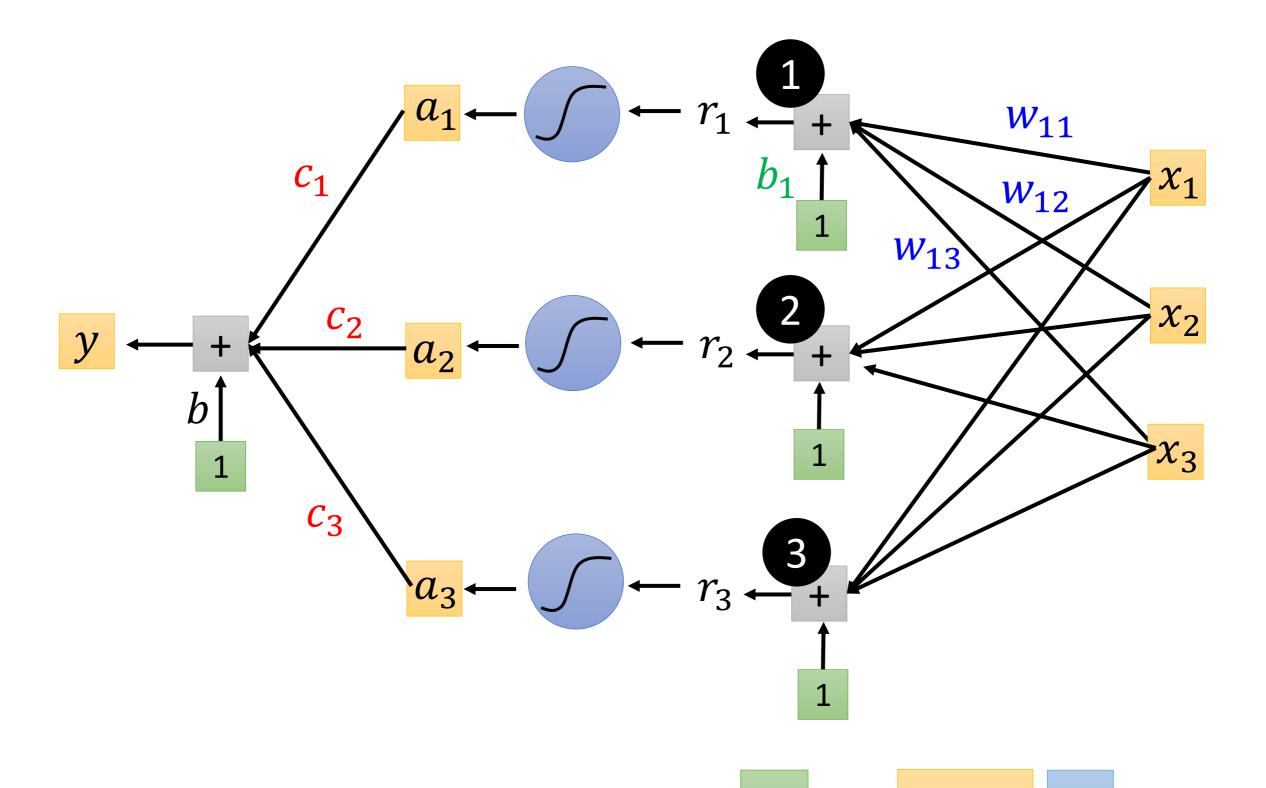


$$a = \sigma(r)$$
 $a_3 \leftarrow f \leftarrow r_3 \leftarrow f$

$$y = b + \sum_{i} c_{i} \operatorname{sigmoid}\left(b_{i} + \sum_{j} w_{ij}x_{j}\right) \qquad i: 1,2,3$$
$$j: 1,2,3$$



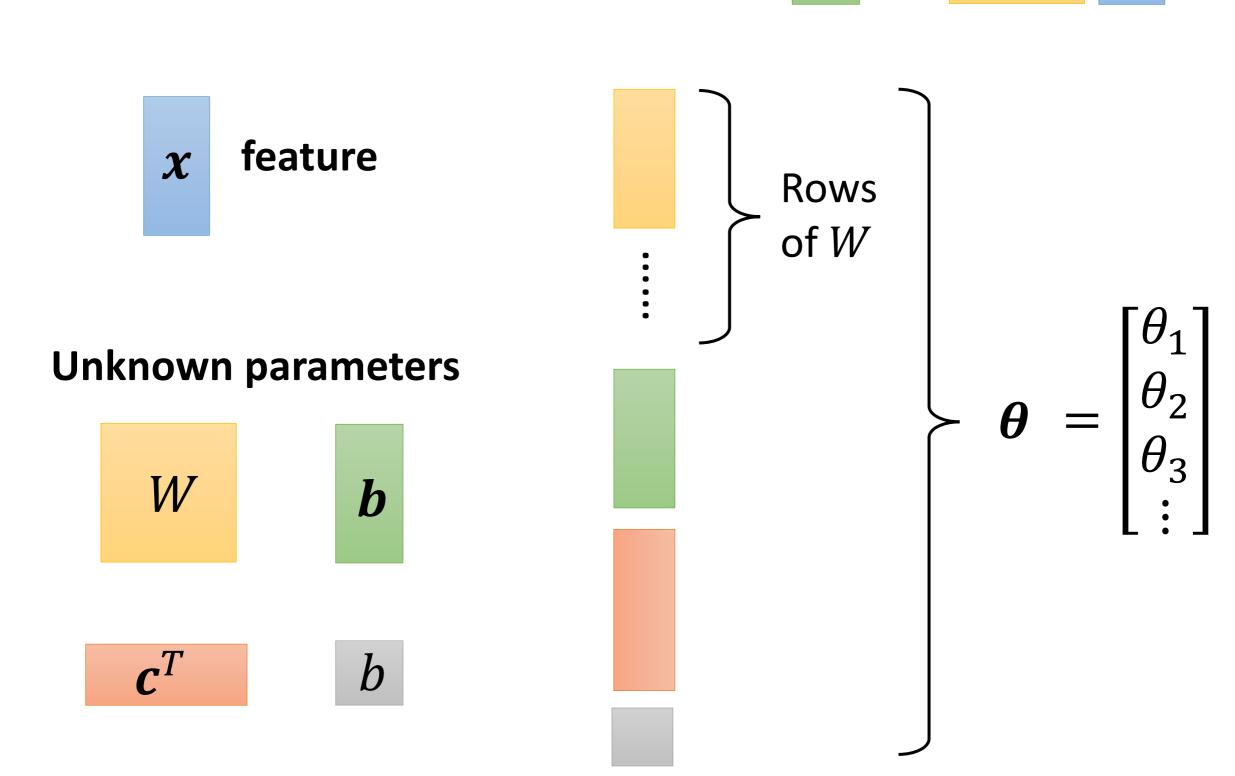




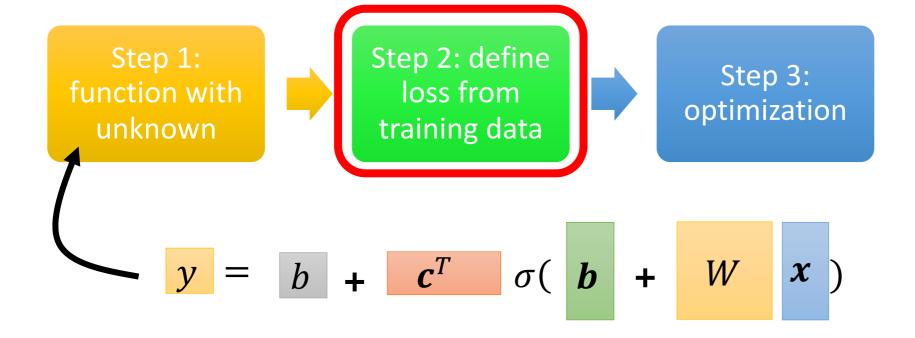
$$y = b + c^T \sigma(b + W x)$$

Function with unknown parameters

$$y = b + c^T \sigma(b + W x)$$



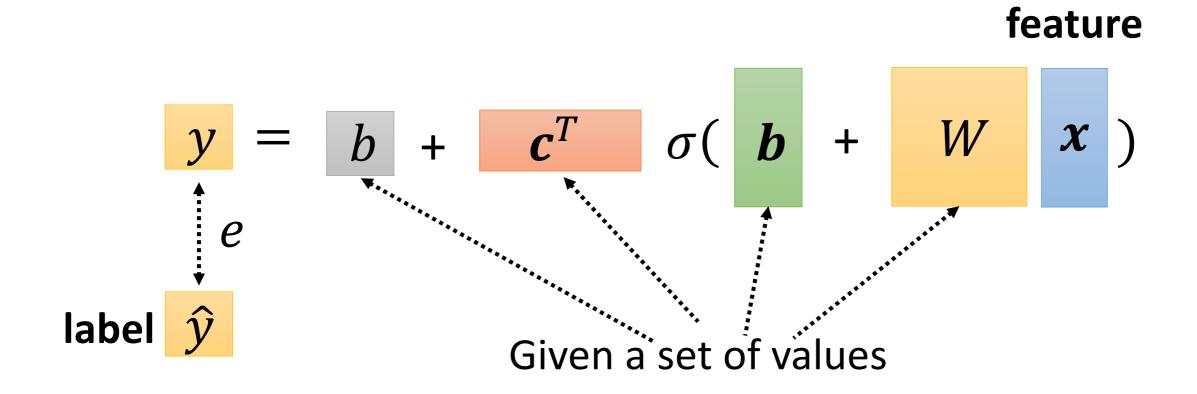
Loss





Loss

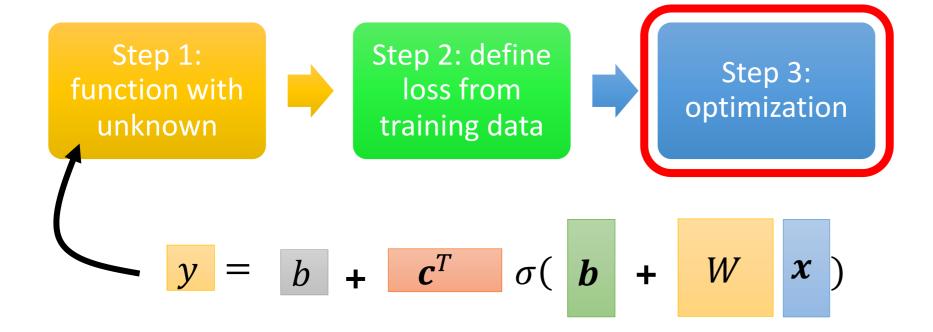
- \succ Loss is a function of parameters $L(\theta)$
- Loss means how good a set of values is.



Loss:
$$L = \frac{1}{N} \sum_{n} e_n$$



Optimization





Optimization of New Model

$$\boldsymbol{\theta}^* = arg \min_{\boldsymbol{\theta}} L$$

$$m{ heta} = egin{bmatrix} heta_1 \\ heta_2 \\ heta_3 \\ heta_3 \end{bmatrix}$$

 \succ (Randomly) Pick initial values $\boldsymbol{\theta}^0$

$$\mathbf{g} = \begin{bmatrix} \frac{\partial L}{\partial \theta_1} |_{\theta = \theta^0} \\ \frac{\partial L}{\partial \theta_2} |_{\theta = \theta^0} \end{bmatrix} \quad \begin{bmatrix} \theta_1^1 \\ \theta_2^1 \\ \vdots \end{bmatrix} \leftarrow \begin{bmatrix} \theta_1^0 \\ \theta_2^0 \\ \vdots \end{bmatrix} - \begin{bmatrix} \mathbf{\eta} \frac{\partial L}{\partial \theta_1} |_{\theta = \theta^0} \\ \mathbf{\eta} \frac{\partial L}{\partial \theta_2} |_{\theta = \theta^0} \end{bmatrix}$$
 gradient

$$\boldsymbol{g} = \nabla L(\boldsymbol{\theta}^0)$$
 $\boldsymbol{\theta}^1 \leftarrow \boldsymbol{\theta}^0 - \boldsymbol{\eta} \boldsymbol{g}$

Optimization of New Model

$$\boldsymbol{\theta}^* = arg \min_{\boldsymbol{\theta}} L$$

- \succ (Randomly) Pick initial values $\boldsymbol{\theta}^0$
- ightharpoonup Compute gradient $m{g} = \nabla L(m{\theta}^0)$

$$\boldsymbol{\theta}^1 \leftarrow \boldsymbol{\theta}^0 - \boldsymbol{\eta} \boldsymbol{g}$$

 \succ Compute gradient $g = \nabla L(\theta^1)$

$$\theta^2 \leftarrow \theta^1 - \eta g$$

ightharpoonup Compute gradient $oldsymbol{g} =
abla L(oldsymbol{ heta}^2)$

$$\theta^3 \leftarrow \theta^2 - \eta g$$

Optimization of New Model

1 epoch = see all the batches once

$$m{ heta}^* = arg \min_{m{ heta}} L$$

> (Randomly) Pick initial values $m{ heta}^0$

B batch

Compute gradient $m{g} = \nabla L^1(m{ heta}^0)$

L¹

batch

update $m{ heta}^1 \leftarrow m{ heta}^0 - \eta m{g}$

batch

vupdate $m{ heta}^2 \leftarrow m{ heta}^1 - \eta m{g}$

batch

Compute gradient $m{g} = \nabla L^2(m{ heta}^1)$

update $m{ heta}^2 \leftarrow m{ heta}^1 - \eta m{g}$

batch

batch

update $m{ heta}^3 \leftarrow m{ heta}^2 - \eta m{g}$

batch

Summary

Training data: $\{(x^1, \hat{y}^1), (x^2, \hat{y}^2), ..., (x^N, \hat{y}^N)\}$

Training:

Step 1: function with unknown



Step 2: define loss from training data



Step 3: optimization

$$y = f_{\theta}(x)$$

$$L(\boldsymbol{\theta})$$

$$\boldsymbol{\theta}^* = arg \min_{\boldsymbol{\theta}} L$$

Testing data: $\{x^{N+1}, x^{N+2}, \dots, x^{N+M}\}$

Use $y = f_{\theta^*}(x)$ to label the testing data

$$\{y^{N+1}, y^{N+2}, \dots, y^{N+M}\}$$

Evaluation

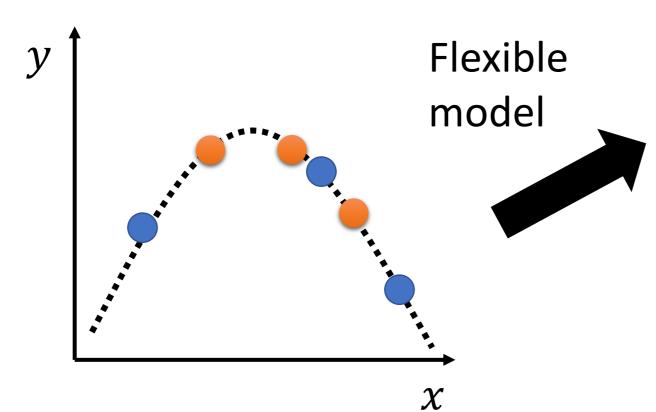
• Small loss on training data, large loss on testing data.

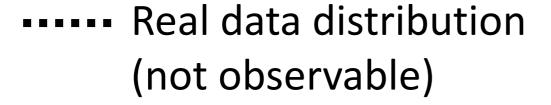
An extreme example

Training data:
$$\{(x^1, \hat{y}^1), (x^2, \hat{y}^2), ..., (x^N, \hat{y}^N)\}$$

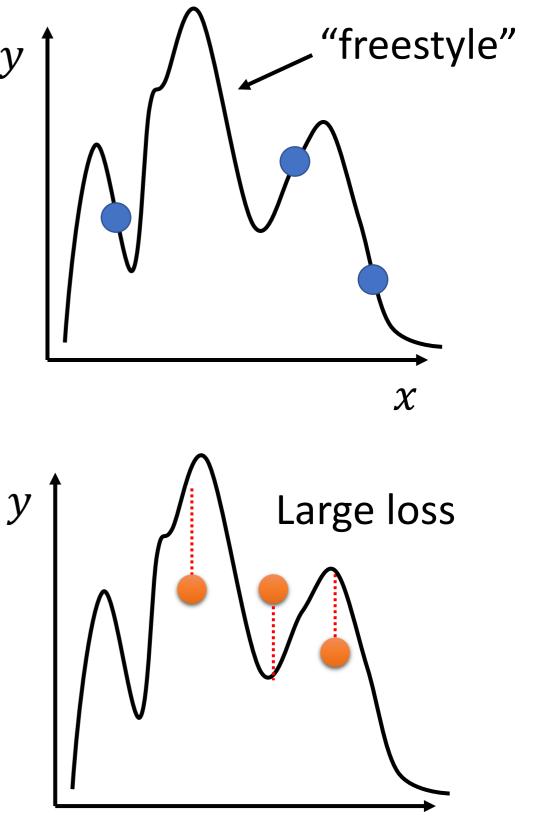
$$f(x) = \begin{cases} \hat{y}^i & \exists x^i = x \\ random & otherwise \end{cases}$$
 Less than useless ...

This function obtains zero training loss, but large testing loss.

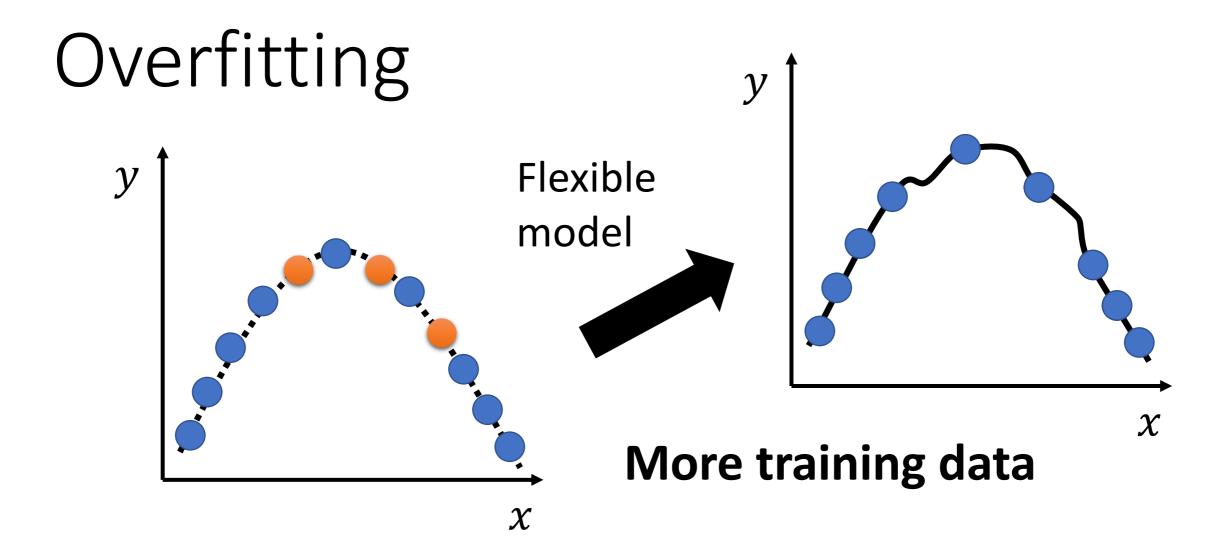




- Training data
- Testing data



 χ



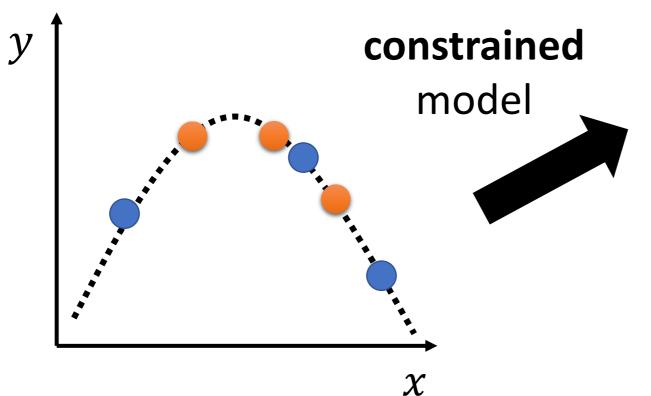
Data augmentation

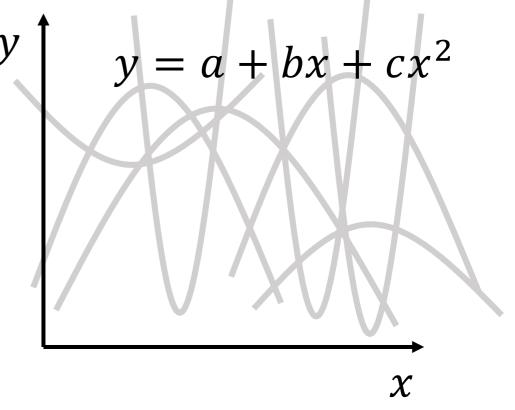




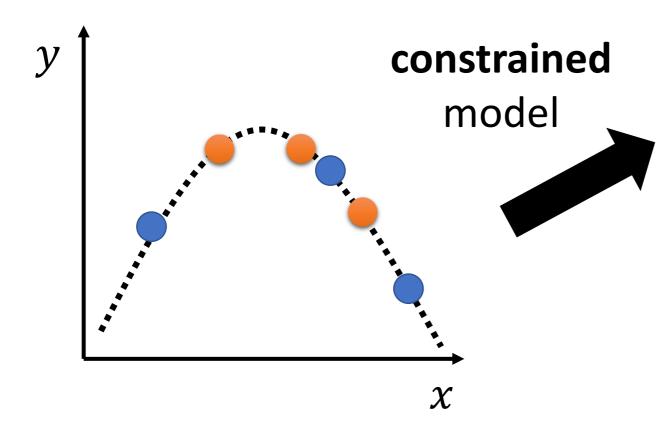


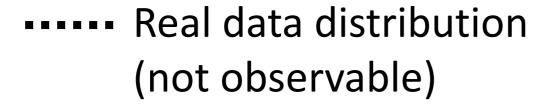




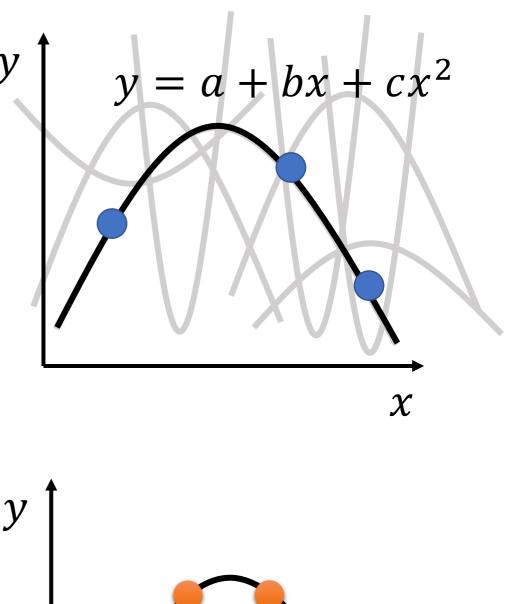


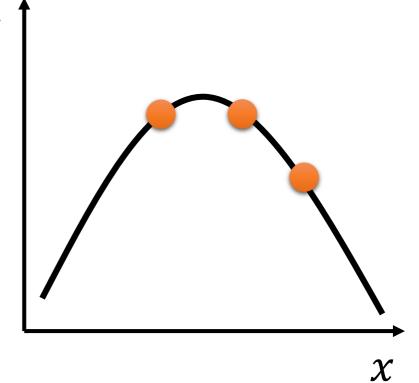
- Real data distribution (not observable)
 - Training data
 - Testing data

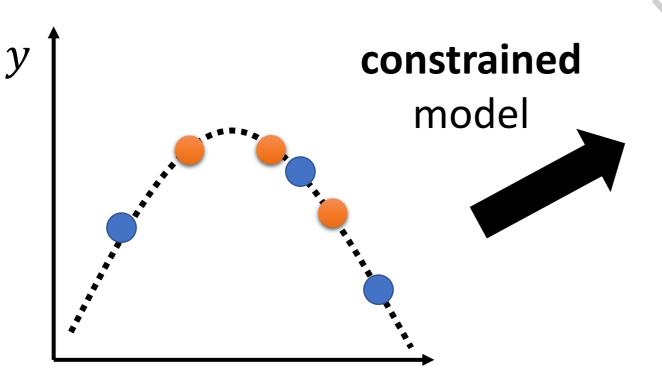


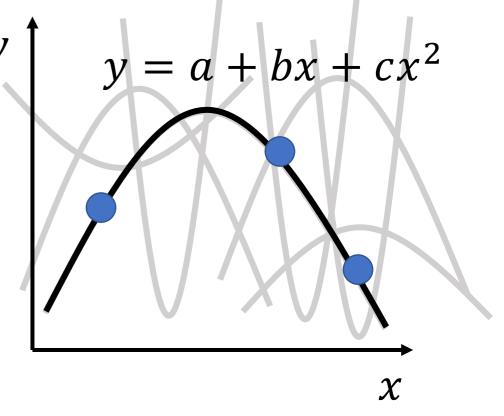


- Training data
- Testing data





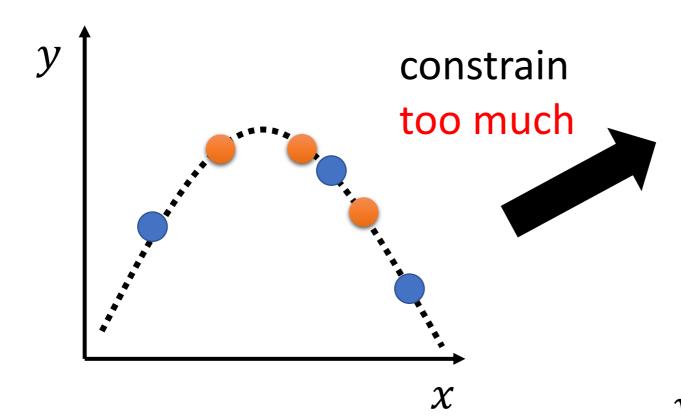


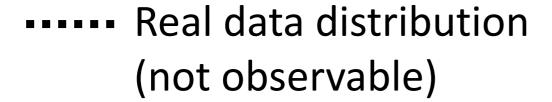


Less parameters, sharing parameters

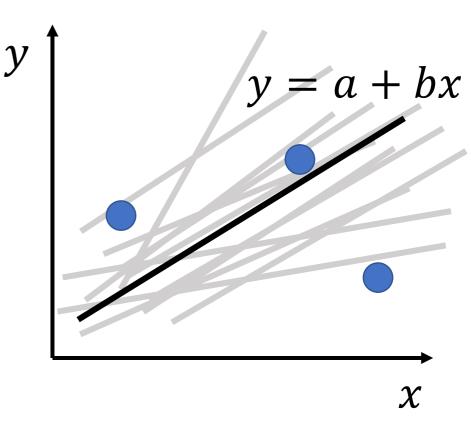
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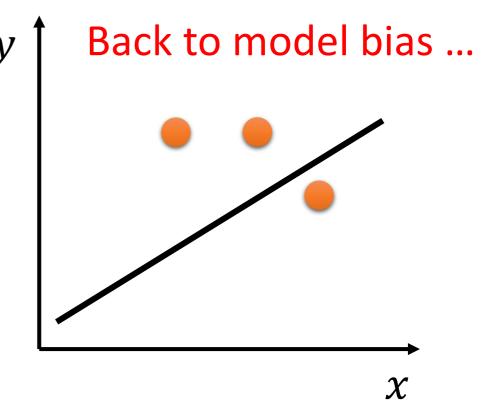
- Less features
- Early stopping
- Regularization
- Dropout



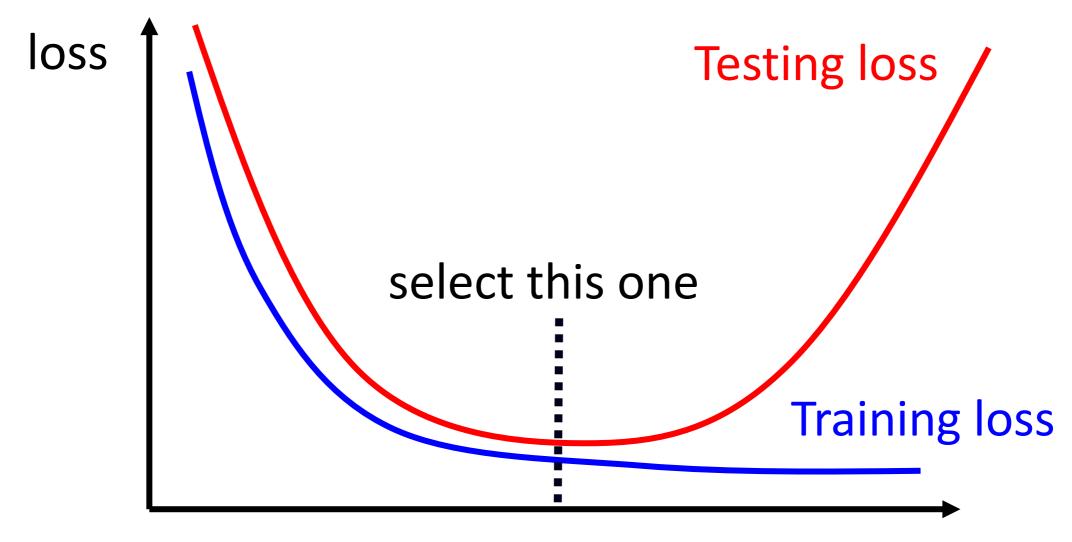


- Training data
- Testing data





Bias-Complexity Trade-off



Model becomes complex (e.g. more features, more parameters)



Model Selection

N-Fold Cross Validation

Training Set

Train

Train

Val

Train

Val

Train

Val

Train

Train

Model 1

Model 2 Model 3

mse = 0.2 mse = 0.4 mse = 0.4

mse = 0.4 mse = 0.5 mse = 0.5

mse = 0.3 mse = 0.6 mse = 0.3

Avg mse

= 0.3

Avg mse Avg mse = 0.5= 0.4

Testing Set



More Learning Paradigms

- What information is available for learning?
 - What does the data look like?
 - How is it annotated?

- What output is desired?
 - What should the algorithm produce?
 - How will it be used?





Supervised Learning

- Learning with a teacher
 - Explicit feedback in the form of labeled examples
 - Goal: make prediction
 - Pros: Good performance
 - Cons: Labeled data is difficult to find
 - "Classical" (labeled data simply there; do your best)
 - Query-based (can ask for labeled examples)
- Examples
 - Classification
 - Is an email spam or not?
 - Regression
 - What is the expected rate of return on a specific investment?





Unsupervised Learning

- Learning without labels
 - Only observed unlabeled examples
 - Goal: uncover structure in data
 - Pros: Easy to find lots of data
 - Cons: what are we looking for?



- Clustering
 - Group emails by topic
- Manifold learning
 - Find a low dimensional data representation





Reinforcement Learning

 Learn a behavior policy by interacting with the world

- How to navigate in a world
- Success measured by rewards received for actions taken
- Maximize sum of rewards
- Examples
 - Chess (and checkers)
 - Robot control
 - Piloting an airplane

