Perceptron Convergence Theorem

We will prove the Rosenblatt theorem for convergence of a learning algorithm. If there is a solution, this is, if there is a vector **B** that separates a set of vectors in the correct categories with a certain margin k, then in a finite number of steps it is possible to find some vector that also achieves this separation. We call hit when $\mathbf{J}(t) \cdot \zeta_{\mu} \sigma_{\mu} > \sqrt{N}k$, otherwise we call a miss.

The vectors of the training set will be considered sequentially and presented to the perceptron, if the classification is correct nothing is done. If an error occurs, a change in the weight vector $\mathbf{J}(t)$ is required. The process is repeated with the next element of list until convergence is achieved. We start from $\mathbf{J}(0) = 0$. The learning dynamics is given by:

$$\mathbf{J}(t+1) = \mathbf{J}(t) + \frac{f_{\mu}}{\sqrt{N}} \cdot \boldsymbol{\zeta}_{\mu} \boldsymbol{\sigma}_{\mu}$$

where f_{μ} is 0 if we have a hit and 1 otherwise. This is an error correction algorithm.

We suppose that exists **B** where $\mathbf{B} \cdot \mathbf{B} = N$ such that:

$$\frac{1}{\sqrt{N}}\zeta_{\mu} \cdot \mathbf{B} \ \sigma_{\mu} \ge k > 0 \tag{1.1}$$

At a given time t, we have $F = \sum f_{\mu}$ and $\mathbf{J}(t) = \sum \frac{1}{\sqrt{N}} f_{\mu} \zeta_{\mu} \sigma_{\mu}$, respectively the number of effective learning steps and the perceptron weights. We want to show that F it remains finite. Multiplying (1.1) by f_{μ} and summing:

$$\sum \frac{1}{\sqrt{N}} f_{\mu} \boldsymbol{\zeta}_{\mu} \cdot \mathbf{B} \ \sigma_{\mu} = \mathbf{J} \cdot \mathbf{B} \ge Fk$$

We introduce $\rho = \frac{\mathbf{J} \cdot \mathbf{B}}{|\mathbf{J}| \cdot |\mathbf{B}|}$. It is easy to show that ρ is between -1 and 1, because is the cosine of the angle between the two vectors. $\mathbf{J} \cdot \mathbf{B} = \rho \sqrt{N} |\mathbf{J}|$ (because $\mathbf{B} \cdot \mathbf{B} = N$). Squaring the inequality we have:

$$\rho^2 N \mid \mathbf{J} \mid^2 \ge (Fk)^2$$

Analysing the learning dynamic we have:

$$|\mathbf{J}(t+1)|^2 = |\mathbf{J}(t)|^2 + 2\frac{1}{\sqrt{N}}\mathbf{J}(t)\cdot\boldsymbol{\zeta}_{\mu}\sigma_{\mu} + \frac{1}{N}|\boldsymbol{\zeta}_{\mu}|^2$$

We can use the scale $|\zeta_{\mu}|^2 = N$ because the classification does not depend of modules.

$$|J(t+1)|^2 = |J(t)|^2 + 2\frac{1}{\sqrt{N}}J(t)\cdot\zeta_{\mu}\sigma_{\mu} + 1$$

Analysing the element μ , if he is changing the dynamic of J then he was not correct classified. It was a miss, so we have $\frac{1}{\sqrt{N}}J(t)\cdot\zeta_{\mu}\sigma_{\mu} < k$ hence:

$$|\mathbf{J}(t+1)|^2 \le |\mathbf{J}(t)| + 2k + 1 \le F(2k+1)$$

Because every increase step is smaller than 2k+1, so if were given F steps, than $F(2k+1) \ge |\mathbf{J}(t)|$. Finally we have:

$$(Fk)^2 \le N |\mathbf{J}(t+1)|^2 \le NF(2k+1)$$

 $F \le N(2k^{-1} + k^{-2})$

So F is limited.