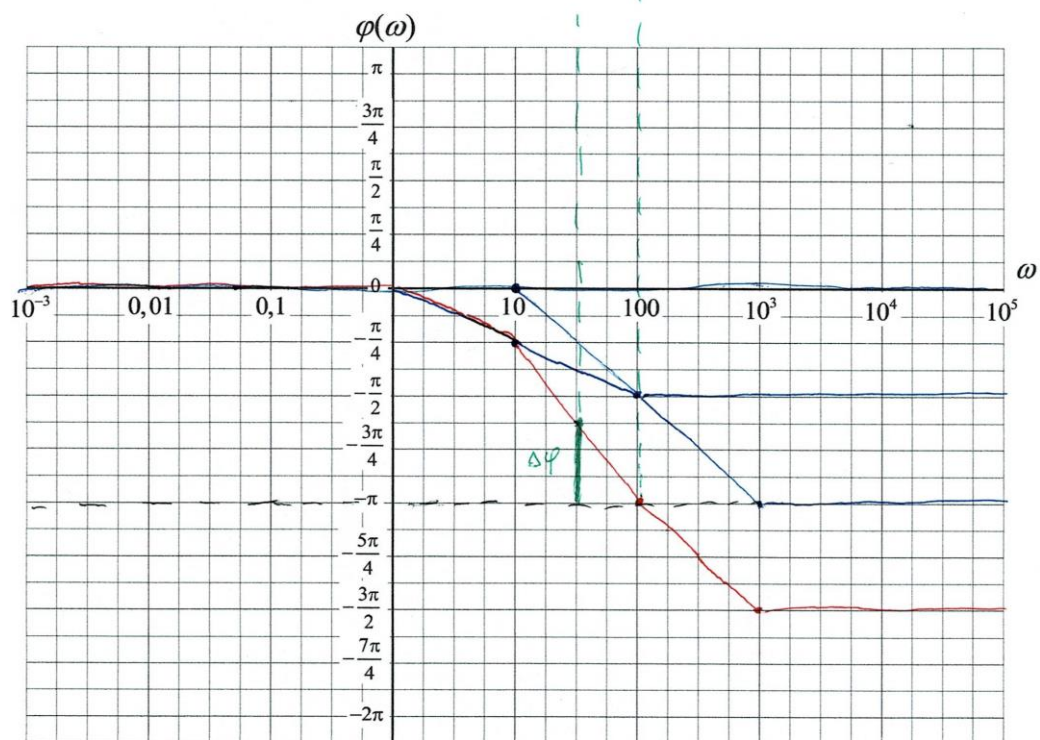
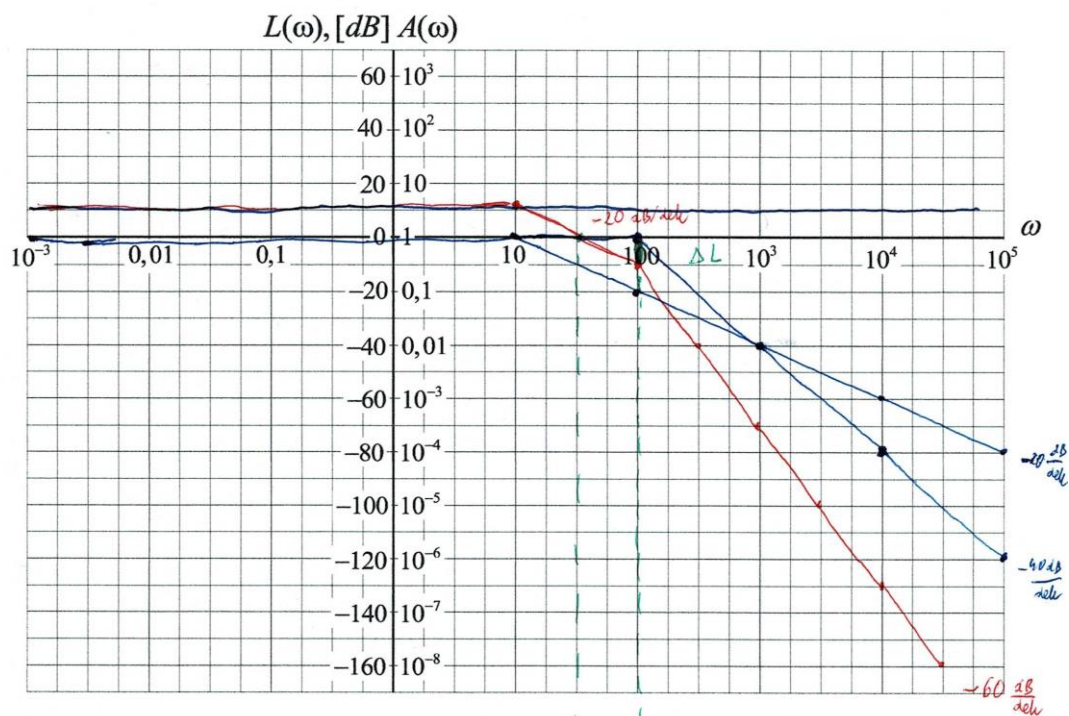


zad. 1 - variant 8



1

1.

A.

$$a) u(t) = \sin t$$

$$y(t) = \sqrt{10} \sin(t + 0) = 3,16 \sin t$$

$$b) u(t) = \sin 10t$$

$$y(t) = \sqrt{10} \sin\left(10t - \frac{\pi}{4}\right) = 3,16 \sin(10t - 0,79)$$

B.

$$\omega_0 = \sqrt{10 \cdot 100} = 31,62 \frac{\text{rad}}{\text{s}}$$

$$\omega_{-\pi} = 100 \frac{\text{rad}}{\text{s}}$$

$$\Delta L = 0 - (-10) = 10 \text{ dB}$$

$$\Delta \varphi = -\frac{5}{8}\pi - (-\pi) = \frac{3}{8}\pi = 1,18 \text{ rad} = 67,5^\circ$$

C.

$$T_{0x} = \frac{2\pi}{\omega_{-\pi}} = \frac{2\pi}{100} = 0,063 \text{ s}$$

(2)

D. $T_0 = \frac{\frac{1}{2} \Delta \varphi}{\omega_0} = \frac{\frac{1}{2} \cdot 118}{39,62} = 0,019s$

E.

$$20 \log k = -\Delta L$$

$$k = 10^{\frac{-\Delta L}{20}} = 10^{\frac{-10}{20}} = 0,32$$

$$k = 10^{\frac{-10}{20}} = 10^{\frac{-10}{20}} = 0,32$$

$$k = \frac{P_2(1-\alpha)}{P_1(1-\alpha)} = \frac{10 \cdot 0,9}{10 \cdot 0,9} = 1$$

D. $T_0 = \frac{P_0}{P_1 \cdot \omega_1} = \frac{10 \cdot 10^3}{10 \cdot 10^4} = 0,002s$

3

2. A.

a) ~~$u(t) = \sin(10t)$~~ $u(t) = \sin t$

$$G_o(j\omega) = A(\omega) e^{j\varphi(\omega)}$$

$$A(\omega) = \sqrt{10} \cdot \frac{1}{(\sqrt{0.01\omega^2 + 1})^2 (0.0001\omega^2 + 1)}$$

$$\varphi(\omega) = -\arctg \frac{\omega}{10} - 2 \arctg \frac{\omega}{100}$$

~~$A(10)$~~

$$A(1) = \sqrt{10} \cdot \frac{1}{(\sqrt{0.01 + 1})^2 (0.0001 + 1)} = 3,15$$

~~$\varphi(1)$~~

$$\varphi(1) = -\arctg \frac{1}{10} - 2 \arctg \frac{1}{100} = -0,12 \text{ rad}$$

$$y(t) = 3,15 \sin(t - 0,12)$$

b) $u(t) = \sin 10t$

$$A(10) = \sqrt{10} \cdot \frac{1}{(\sqrt{0.01 \cdot 10^2 + 1})^2 (0.0001 \cdot 10^2 + 1)} = \cancel{3,01} = 2,21$$

$$\varphi(10) = -\arctg \frac{10}{10} - 2 \arctg \frac{10}{100} = -0,98 \text{ rad}$$

~~$y(t) = 3,01 \sin(10t - 0,98)$~~

$$y(t) = 2,21 \sin(10t - 0,98)$$

(9)

B. $\omega_0 \in (0, \infty)$

ω_0 :

$$|G_0(j\omega_0)| = 1$$

$$\sqrt{10} \frac{1}{(\sqrt{0,01\omega_0^2+1})(\sqrt{0,0001\omega_0^2+1})^2} = 1$$

$$10 = (0,01\omega_0^2+1)(0,0001\omega_0^2+1)^2$$

$$10^{-10}\omega_0^6 + 2,01 \cdot 10^{-6}\omega_0^4 + 0,0102\omega_0^2 - 9 = 0$$

$$\omega_0 = -27,63 \frac{\text{rad}}{\text{s}} \quad \vee \quad \underline{\omega_0 = 27,63 \frac{\text{rad}}{\text{s}}}$$

$\omega_0 \notin D \quad \quad \quad \omega_0 \in D$

$\omega_{-\pi} \in (0, \infty)$

$\omega_{-\pi}$:

$$\arg\{G_0(j\omega_{-\pi})\} = -\pi$$

$$-\arctg\left(\frac{\omega_{-\pi}}{10}\right) - 2\arctg\left(\frac{\omega_{-\pi}}{100}\right) = -\pi$$

$$\omega_{-\pi} = 109,54 \frac{\text{rad}}{\text{s}}$$

$$A(\omega_{-\pi}) = 0,13$$

ΔL :

$$\Delta L = 20 \lg \frac{1}{A(\omega_{-\pi})} = 20 \lg \frac{1}{0,13} = 17,68 \text{ dB}$$

$\Delta \varphi$:

$$\Delta \varphi = \pi + \arg\{G_0(j\omega_0)\} = \pi - 1,76 = 1,38 \text{ rad} = 79^\circ$$

C. $T_{osc} = \frac{2\pi}{\omega_{-\pi}} = \frac{2\pi}{109,54} = 0,057 \text{ s}$

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D.

$$T_0 = \frac{\frac{1}{2} \Delta \varphi}{\omega_0} = \frac{\frac{1}{2} \cdot 1,38}{27,63} = 0,025 \text{ s}$$

E.

$$20 \log k = -\Delta L$$

$$k = 10^{\frac{-\Delta L}{20}} = 10^{\frac{-17,68}{20}} = 0,13$$

~~$$P = \frac{P_{\text{max}}}{1 + \left(\frac{f}{f_0}\right)^2} = \frac{1}{1 + \left(\frac{10}{10}\right)^2} = \frac{1}{2} = 0,5$$~~

E.

~~$$\frac{1}{Q} = \frac{1}{Q_0} = \frac{1}{10} = 0,1$$~~

6

	Wartości dokładne	wartości na podstawie charakterystyki
A.		
a) $y(t); A=1; U=1$	$3,15 \text{ mm}(t - 0,12)$	$3,16 \text{ mm } t$
b) $y(t); A=1; U=10$	$2,21 \text{ mm}(10t - 0,98)$	$3,16 \text{ mm}(10t - 0,99)$
B.		
ω_0	$27,63 \frac{\text{rad}}{\text{s}}$	$37,87 \frac{\text{rad}}{\text{s}}$
ω_{-11}	$109,54 \frac{\text{rad}}{\text{s}}$	$100 \frac{\text{rad}}{\text{s}}$
ΔL	$77,68 \text{ dB}$	10 dB
$\Delta \varphi$	49°	$67,5^\circ$
C.		
T_{0x}	$0,057 \text{ s}$	$0,063 \text{ s}$
D.		
T_0	$0,025 \text{ s}$	$0,019 \text{ s}$
E.		
k	3,85 0,13	4,58 0,32

$$3. \quad G(s) = \frac{G_0(s)}{1+G_0(s)} = \frac{3,16 \cdot 10^5}{(s+147,9)(s^2+62,11s+2814)}$$

$$K = G(0) = \frac{3,16 \cdot 10^5}{147,9 - 2814} = 0,76$$

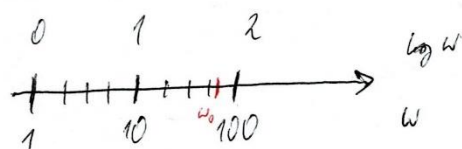
$$4. \quad u(t) = 1(t)$$

$$e_{\text{stat}} = \frac{1}{1+G_0(0)} = \frac{1}{1+\sqrt{10}} = 0,24$$

5) $C(s) = k_p$, więc charakterystyka frcowa nie ulega zmianie, zatem z wykresem:

$$\Delta\varphi = \frac{\pi}{8} \text{ dla } \omega_0 = 10^{\frac{11}{6}} = 68,13 \frac{\text{rad}}{\text{s}}$$

~~z wykresem~~, skąd nie możemy $\omega_0 = 10^{\frac{11}{6}}$?



$$\log w_0 = 1 \frac{3}{4} + \frac{1}{3} \cdot \frac{1}{4} = 1 \frac{10}{12} = 1 \frac{5}{6} = \frac{11}{6} \Leftrightarrow w_0 = 10^{\frac{11}{6}}$$

$k_p = ?$

Trzeba podnieść charakterystykę modułową o $20 \log k_p$ dB tak żeby $w_0 = 10^{\frac{11}{6}}$

$$20 \log k_p = \frac{2 \cdot 10}{3} \Leftrightarrow k_p = 10^{\frac{2 \cdot 10}{3 \cdot 20}} = \cancel{10} 2,15$$

$$\Delta L = 10 - \frac{2}{3} \cdot 10 = 3,33 \text{ dB}$$

5)

$$G(s) = k_p, \quad G_o(s) = C(s)P(s) = \frac{k_p \sqrt{10}}{(0,1s+1)(0,01s+1)^2}$$

$$\Delta\varphi = \pi + \arg\{G_o(j\omega_0)\} = \frac{\pi}{8}$$

$$\arg\{G_o(j\omega_0)\} = -\frac{7}{8}\pi$$

$$-\arctg \frac{\omega_0}{10} - 2 \arctg \frac{\omega_0}{100} = -\frac{7}{8}\pi$$

$$\omega_0 = 76,64 \frac{\text{rad}}{\text{s}}$$

~~$$k_p$$~~
$$|G_o(j\omega_0)| = 1$$

$$k_p \sqrt{10} \cdot \frac{1}{(\sqrt{0,01\omega_0^2+1})(\sqrt{0,0001\omega_0^2+1})^2} = 1$$

$$k_p = \frac{\sqrt{0,01 \cdot 7664^2 + 1} \cdot (\sqrt{0,0001 \cdot 7664^2 + 1})^2}{\sqrt{10}} = 3,88$$

$$\Delta L = 20 \lg \frac{1}{|A(\omega_0)| k_p} = 20 \lg \frac{1}{0,13 \cdot 3,88} = 5,94 \text{ dB}$$

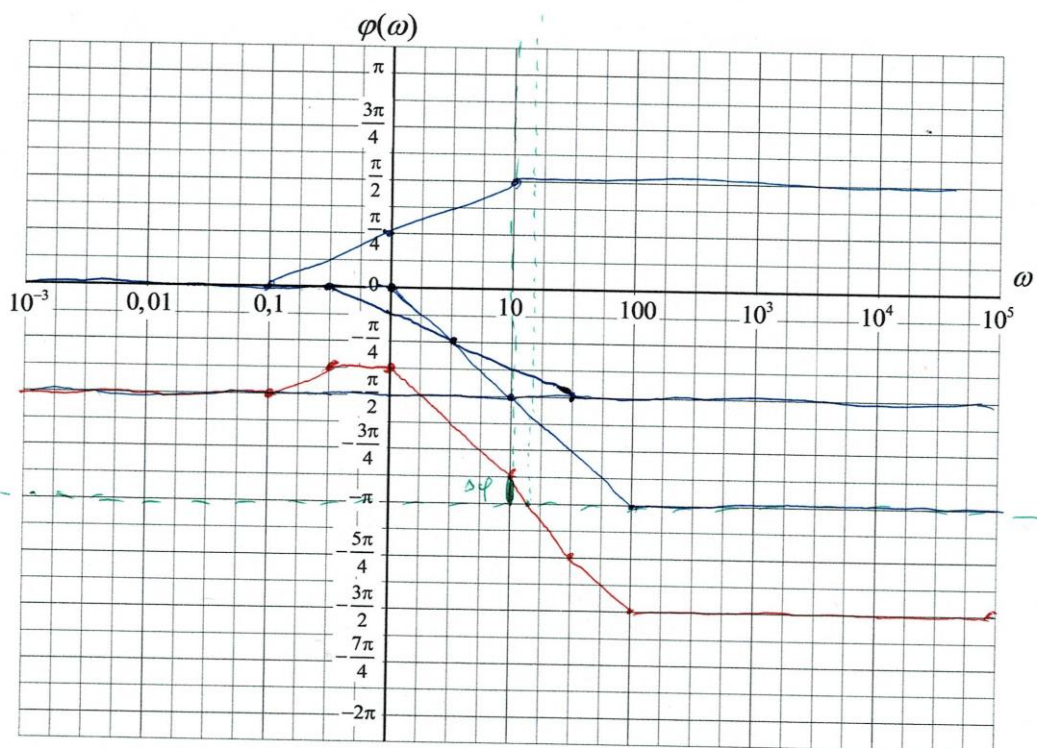
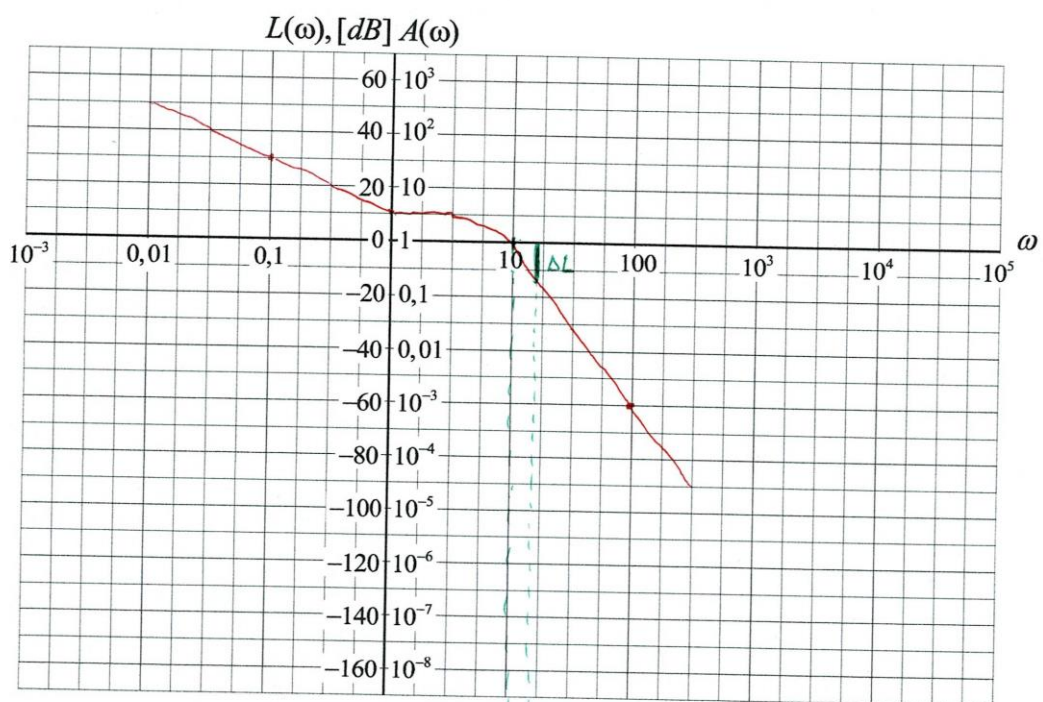
zad. 2 warant 0

$$1. G_0(s) = \sqrt{10} \cdot \frac{1}{s} (s+1) \left(\frac{1}{\frac{s}{\sqrt{10}} + 1} \right) \left(\frac{1}{\frac{s}{10} + 1} \right)^2 =$$
$$= \frac{\sqrt{10} (s+1)}{s \left(\frac{s}{\sqrt{10}} + 1 \right) \left(\frac{s}{10} + 1 \right)^2}$$

~~2.~~

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2.



12

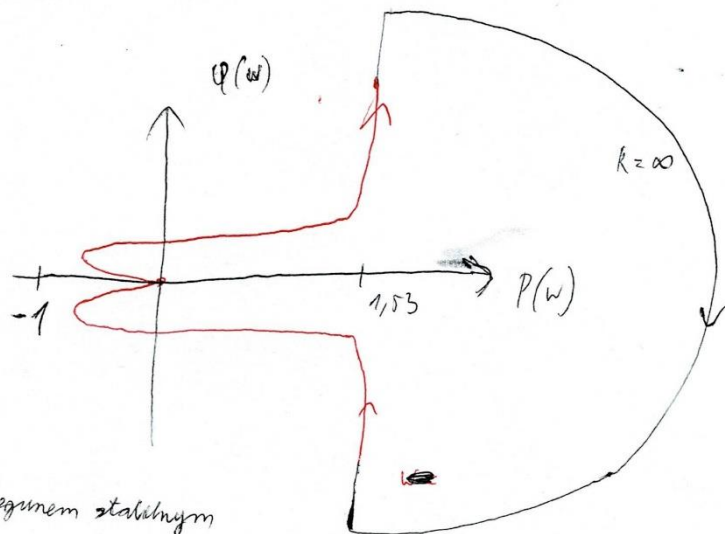
3.

$$G_O(j\omega) = P(\omega) + jQ(\omega)$$

$$P(\omega) = \frac{-22,62(\omega - 2,63)(\omega + 2,63)}{(\omega^2 + 10)(\omega^2 + 100)^2}$$

$$Q(\omega) = \frac{1000(\omega + 11,93)(\omega - 11,93)(\omega^2 + 2,22)}{(\omega^2 + 10)(\omega^2 + 100)^2}$$

ω	0^+	...	$2,627$...	∞
$P(\omega)$	$1,53$	$-$	0	$+$	0
$Q(\omega)$	$-\infty$	$-$	$-2,43$	$-$	0



zatem, że $s=0$ jest biegunem stabilnym

Układ jest stabilny, ponieważ punkt $(-1, 0j)$ nie leży wewnętrznie charakterystyki

z charakterystyk asymptotycznych:

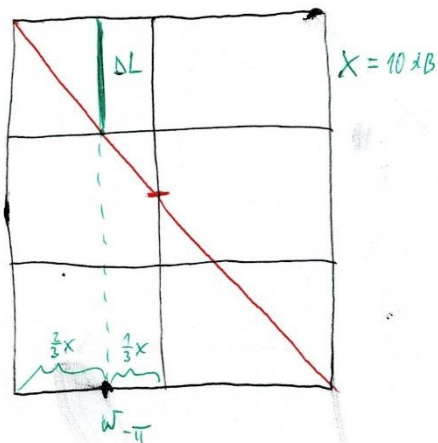
~~dlaczego~~

$$\omega_0 = 10 \frac{\text{rad}}{\text{s}}$$

$$\Delta\varphi = \frac{1}{8}\pi = 22,5^\circ$$

$$\omega_{-\pi} = 10^{1 + \frac{2}{3} \cdot \frac{1}{4}} = 14,68 \frac{\text{rad}}{\text{s}}$$

$$\Delta L =$$



$$\Delta L = 10 \text{ dB}$$

$$\tau < \tau_{kr} = \frac{\Delta\varphi}{\omega_0} = \frac{\frac{1}{8}\pi}{10} = 0,04 \text{ s}$$

$$Q < h < 10^{\frac{\Delta L}{20}} = 10^{\frac{10}{20}} = \sqrt{10}$$

Wzrostowa dodatnia:

$$G_0(j\omega) = A(\omega) e^{j\varphi(\omega)}$$

$$A(\omega) = \frac{\sqrt{10} \sqrt{\omega^2 + 1}}{\omega \sqrt{\frac{\omega^2}{10} + 1} \cdot \left(\frac{\omega^2}{100} + 1\right)}$$

$$\varphi(\omega) = \arctg \omega - \frac{\pi}{2} - \arctg \frac{\sqrt{10}}{10} \omega - 2 \arctg \frac{\omega}{10}$$

$$\omega_{-\pi}: \arg \{G_0(j\omega_{-\pi})\} = -\pi$$
$$\omega_{-\pi} = 11,93 \frac{\text{rad}}{\text{s}}$$

ω_0 :

$$A(\omega_0) = 1$$

$$\omega_0 = 6,43 \frac{\text{rad}}{\text{s}}$$

$$\Delta L = 20 \log \frac{1}{A(\omega_{-\pi})} = 9,49 \text{ dB}$$

$$\Delta \varphi = \pi + \arg \{G_0(j\omega_0)\} = 0,73 \text{ rad} = 41,83^\circ$$

$$n < 10^{\frac{\Delta L}{20}} = 2,98$$

$$\tau_0 < \frac{\Delta \varphi}{\omega_0} = 0,11 \text{ s}$$

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