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1 Generative Models

Problem 1.1

IWAE

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By Jensen's Inequality, $f(E[X]) \leq E[f(x)], \forall f(.)$ is a convex function $\because log(.)$ isn't a convex function

$$\Rightarrow IWAE(K) = E_{q(z|x,\phi)}[log(\frac{1}{K}\sum_{k=1}^{K} \frac{p(z^{(k)},x;\theta)}{a(z^{(k)}|x;\phi)})]$$

$$\leq log(\frac{1}{K} \sum_{k=1}^{K} E_{q(z|x,\phi)}[\frac{p(z^{(k)},x;\theta)}{q(z^{(k)}|x;\phi)}]) = logp(x;\theta)$$

$$\Rightarrow IWAE(K) \le logp(x; \theta) - (1)$$

$$\sum_{k=1}^{K} log(\frac{p(z^{(k)}, x; \theta)}{q(z^{(k)}|x, \phi)}) \le log(\frac{1}{K} \sum_{k=1}^{K} \frac{p(z^{(k)}, x; \theta)}{q(z^{(k)}|x, \phi)})$$

$$\Rightarrow \tfrac{1}{K} \sum_{k=1}^K E_{q(z|x,\phi)} [log(\tfrac{p(z^{(k)},x;\theta)}{q(z^{(k)}|x,\phi)})] \leq E_{q(z|x,\phi)} [log(\tfrac{1}{K} \sum_{k=1}^K \tfrac{p(z^{(k)},x;\theta)}{q(z^{(k)}|x,\phi)})]$$

$$\Rightarrow E_{q(z|x,\phi)}[log(\tfrac{p(z,x;\theta)}{q(z|x,\phi)})] \leq E_{q(z|x,\phi)}[log(\tfrac{1}{K}\sum_{k=1}^K \tfrac{p(z^{(k)},x;\theta)}{q(z^{(k)}|x,\phi)})]$$

$$\Rightarrow IWAE(1) \leq IWAE(K) - (2)$$

By(1),(2)

⇒
$$IWAE(1) \le IWAE(K) \le logp(x; \theta)$$
得证

2

首先得
$$lim_{k\to+\infty} \frac{1}{K} \sum_{k=1}^{K} \frac{p(z^{(k)}, x; \theta)}{q(z^{(k)})} = E_{q(z|x,\phi)} \left[\frac{p(z,x;\theta)}{q(z|x,\phi)} \right] = p(z,x;\theta)$$

$$\therefore lim_{k\to+\infty} IWAE(K) = lim_{k\to+\infty} E_{q(z|x,\phi)} \left[log(\frac{1}{K} \sum_{k=1}^{K} \frac{p(z^{(k)}, x; \theta)}{q(z^{(k)}|x;\phi)}) \right]$$

$$= E_{q(z|x,\phi)} \left[log(lim_{k\to+\infty} \frac{1}{K} \sum_{k=1}^{K} \frac{p(z^{(k)}, x; \theta)}{q(z^{(k)}|x;\phi)}) \right]$$

$$= E_{q(z|x,\phi)}[logp(z,x;\theta)]$$

$$= log p(z, x; \theta)$$

$$\Rightarrow lim_{k\to+\infty}IWAE(K) = logp(z, x; \theta)$$
得证

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:: log(.) is a monotonic function

Problem 1.2

Affine VAE and probabilistic PCA

Problem 1.3

GAN

$$\begin{split} &By \, min_{G} max_{D}(E_{p_{data(x)}}[logD(X)] + E_{p(x)}[log(l-D(G(Z)))]) \\ &D(x) = argmax_{D} E_{p_{data(x)}}[logD(X)] + E_{p(x)}[log(l-D(G(Z)))] \\ &= argmax_{D} \int p_{data(x)}[logD(x)] dx + \int p(x)[log(l-D(G(Z)))] dz \\ &= argmax_{D} \int p_{data(x)}[logD(x)] dx + \int p(G^{-1}(x))[log(l-D(G(x)))] \frac{1}{(G^{-1}(x))'} dx \\ &= argmax_{D} \int p_{data(x)}[logD(x)] dx + p(G^{-1}(x))[log(l-D(G(x)))] \frac{1}{(G^{-1}(x))'} dx \\ &= argmax_{D} D(x)^{p_{data(x)}}(1-D(x))^{p_{model(x)}} \\ &\Rightarrow D(x) = \frac{p_{data(x)}}{p_{data(x)} + p_{model(x)}}$$
得证

2 Reinforcement Learning

Problem 2.1

Policy Improvement Theorem

在Markov Decision Process,有policy π ,可用下述方式将 π 更新至 π' : $\forall s \in S, \pi'(s) = argmax_a q^{\pi}(s, a)$ 欲证 $\forall s \in S, v^{\pi'}(s) \geq v^{\pi}(s)$

下证:

By definition of state – value function and action function, $v^{\pi}(s) = \sum_{a} \pi(a|s)q^{\pi}(s,a) \le q^{\pi}(s,\pi'(s))$ $\Rightarrow v^{\pi}(s) \le \pi'(s)$

$$\exists q^{\pi}(s, \pi'(s)) = E_{\pi}[R_{t+1} + \dots | S_t = s, A_t = \pi'(s]]$$

故证 $q^{\pi}(s, \pi'(s)) = \pi'(s) \le v^{\pi}(s)$,则 $v^{\pi'}(s) \ge v^{\pi}(s)$ 即可得证

现令
$$\pi'(s) = f(1), \ v^{\pi}(s) = f(\infty)$$
,并求证 $f(k) \le f(k+1)$

$$f(k) = \sum_{i=0}^{k-1} \gamma^{i} E_{\pi'}[R_{t} + i + 1 | S_{t} = s] + \sum_{s_{1}} \dots \sum_{s_{k}} \sum_{a} P_{ss_{1}}^{\pi'(s)} P_{s_{1}s_{2}}^{\pi'(s_{1})} \dots P_{s_{k-1}s_{k}}^{\pi'(s_{k-1})} \pi(a|s_{k}) E_{\pi}[\sum_{j=k}^{\infty} \gamma^{j} R_{t+1}] P_{ss_{1}s_{2}}^{\pi'(s)} P_{ss_$$

$$= \sum_{i=0}^{k-1} \gamma^k E_{\pi'}[R_t+i+1|S_t=s] + \sum_{s_1} \cdots \sum_{s_k} \sum_{a} P_{ss_1}^{\pi'(s)} P_{s_1s_2}^{\pi'(s_1)} \cdots P_{s_{k-1}s_k}^{\pi'(s_{k-1})} \pi(a|s_k) \gamma^k q^{\pi}(s_k,a)$$

$$\leq \sum_{i=0}^{k-1} \gamma^k E_{\pi^{'}}[R_t+i+1|S_t=s] + \sum_{s_1} \dots \sum_{s_k} \sum_{a} P_{ss_1}^{\pi^{'}(s)} P_{s_1s_2}^{\pi^{'}(s_1)} \dots P_{s_{k-1}s_k}^{\pi^{'}(s_{k-1})} \gamma^k q^{\pi}(s_k,\pi^{'}(s_k)) = f(k+1)$$

$$\Rightarrow f(1) \leq f(\infty)$$

$$\Rightarrow \pi'(s) \leq v^{\pi}(s)$$

$$\Rightarrow v^{\pi}(s) \leq \pi'(s) \leq v^{\pi}(s)$$

$$\Rightarrow v^{\pi}(s) \leq v^{\pi}(s)$$
得证