

# Making Do-Calculus Accessible in Econometrics

## DAGs as Complementary Tools for Causal Estimation

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# The Problem: Causal Inference Without Guidance

**Question:** How should we choose which variables to control for?

- Traditional econometrics: Controlling for all omitted variables
- Control for everything (Kitchen-sink): Can increase bias

DAGs provide a formal framework for encoding causal assumptions and deriving identification conditions.

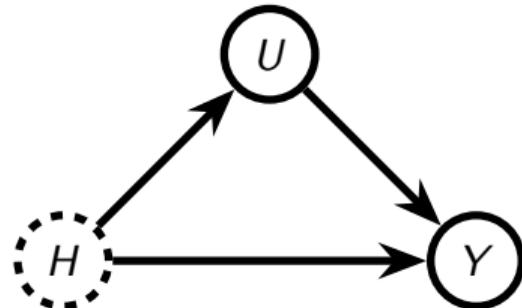
# What are DAGs? (Directed Acyclic Graphs)

## Formal Definition:

- Nodes = Variables
- Arrows = Direct causal effects
- Dashed nodes = Unobserved variables
- Acyclic = No feedback loops

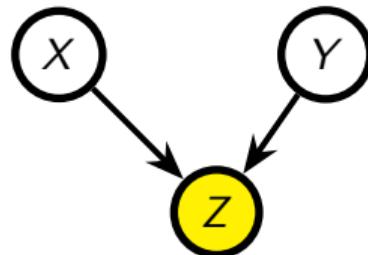
## Key Concept: D-Separation

- Tests conditional independence
- Determines which variables to control
- Automatically validated in data



# Example 1: Collider Bias (Synthetic)

## DAG: Collider Structure



Fact 1:  $X \perp\!\!\!\perp Y$

Problem:  $X \not\perp\!\!\!\perp Y | Z$

## Data Generating Process:

$$X \sim N(0, 1)$$

$$Y \sim N(0, 1)$$

$$Z = 0.5X + 0.5Y + \epsilon$$

## Key Insight:

Controlling for a collider creates spurious correlation.

## Simulation Result:

| Method             | Bias   | Coverage |
|--------------------|--------|----------|
| Naive (no control) | 0.000  | 95%      |
| Control $Z$        | -0.248 | 0%       |

True effect = 0. Controlling for  $Z$  produces bias

## Example 2: Frontdoor Criterion (Synthetic Bellemare)

### Research Question

Does allowing riders to authorize shared rides affect tipping?

### The Challenge:

- Generosity affects both treatment and outcome
- Generosity is unobserved

### Data Generating Process:

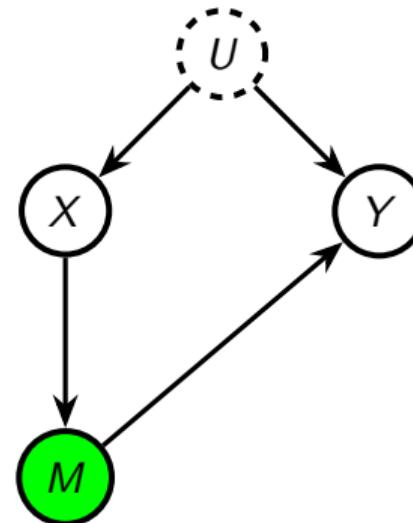
$$U \sim N(50, 15^2)$$

$$P(X = 1) = \text{logit}(-2 + 0.05U)$$

$$M = 60 - 12X + \epsilon_M$$

$$Y = 5 + 0.1U - 0.08M + \epsilon_Y$$

### DAG: Frontdoor Structure



$X$  = Share authorized,  $M$  = Actually shared  
 $Y$  = Tip,  $U$  = Unobserved generosity

## Example 2: Frontdoor Criterion (Synthetic Bellemare)

### How Frontdoor Works

- Stage 1: Estimate  $X \rightarrow M$  effect
- Stage 2: Estimate  $M \rightarrow Y$  effect
- Combine: Effect =  $\beta_1 \times \beta_2$

### Why It Works

- No confounding of  $X \rightarrow M$  path
- $M$  blocks all backdoor paths
- Unobserved  $U$  becomes irrelevant

## Example 2 Results: Frontdoor vs. Naive

### Simulation Results (Synthetic Bellemare, n=100,000)

| Estimator          | Effect  | Interpretation |
|--------------------|---------|----------------|
| Naive OLS          | +0.03pp | Biased         |
| Standard Frontdoor | -0.95pp | Accurate       |
| True Effect        | -0.96pp | —              |

## Example 2 (Continued): Comparing Estimation Approaches

**Do Both Approaches Give Similar Results?**

| Estimator               | Effect  | Error from True |
|-------------------------|---------|-----------------|
| Parametric Frontdoor    | -0.95pp | 1.0%            |
| Nonparametric Frontdoor | -0.84pp | 12.3%           |
| True Effect             | -0.96pp | —               |

## Example 2 (Continued): Comparing Estimation Approaches

### Parametric

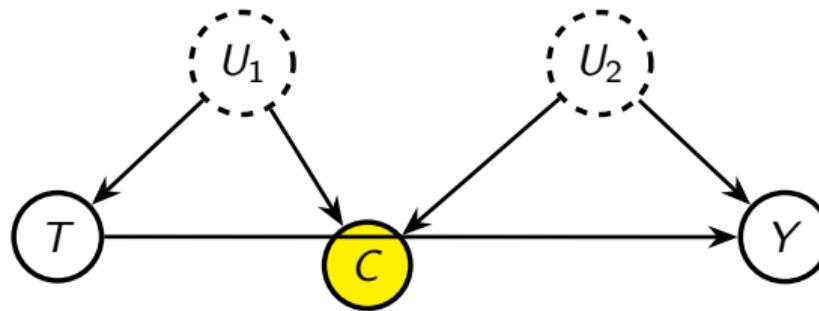
- Stage 1: Linear regression
- Stage 2: Linear regression
- Delta method SEs
- More efficient

### Nonparametric

- Bin mediator values
- Estimate densities
- Pearl's formula directly
- No linearity assumption

# Example 3: M-Bias (Synthetic)

## The M-Bias Structure



$C$  is a **pre-treatment collider**

## The Problem

- Traditional wisdom: “Control for  $C$ ”
- DAG analysis: Controlling for  $C$  induces bias

Why?

- Controlling for  $C$  opens blocked path

$$U_1 \sim N(0, 1)$$

$$U_2 \sim N(0, 1)$$

$$C = 0.6U_1 + 0.4U_2 + \epsilon_C$$

$$T = 0.5U_1 + 0.3C + \epsilon_T$$

$$Y = 0.4T + 0.5U_2 + \epsilon_Y$$

## Insight:

Traditional guidance contradicts the DAG, leads to bias

# Example 3 Results: Why DAG Guidance Matters

## Simulation Results: Bias for Different Strategies

| Estimator                  | Bias  | vs. Naive    |
|----------------------------|-------|--------------|
| Naive (no controls)        | 0.087 | Baseline     |
| Traditional (control $C$ ) | 0.215 | +148%        |
| DAG-Guided (no control)    | 0.087 | Minimal Bias |
| True effect                | 0.000 | —            |

### Key Takeaway:

Controlling for a pre-treatment collider can **double the bias!**

# Making Assumptions Testable

**Strategy:** Use data to validate DAG assumptions

## D-Separation Tests

- Test conditional independence
- Expected to hold if DAG is correct
- Apply to synthetic and real data

## Placebo Tests

- Test effects that should be zero
- Test relationships that shouldn't exist
- Validates causal structure

## DAGs and Traditional Methods are Complementary

| DAGs Provide              | Traditional Provides | Together:        |
|---------------------------|----------------------|------------------|
| Systematic identification | Efficient estimation | Robust inference |
| Assumption validation     | Hypothesis testing   | Credible results |
| Covariate selection       | Standard errors      | Publishable      |

## Best Practice:

- ① Draw the DAG (encode causal assumptions)
- ② Use d-separation (determine controls)
- ③ Run regression (estimate effect)

# Key Takeaways

- ① DAGs provide **systematic rules** for covariate selection
- ② Traditional guidance can increase bias (colliders, M-bias)
- ③ D-separation enables identification in new contexts (frontdoor)
- ④ Assumptions are testable with falsification tests
- ⑤ Combine DAGs with traditional econometrics for best results

Questions?