Pooled Rideshare, Human Factors, and the Reconsideration of Mode Shifting

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Project Objectives

Primary Objective:

Increase the usage of pooled ridesharing and decrease emissions through understanding and improving rideshare offerings.

Teams and Expertise:

Project partners like JD Power and ANL provide valuable information from different perspectives.

Topics for Today:

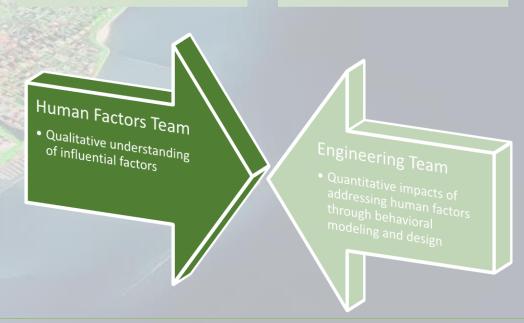
- Survey
- Choice Model
- Assignment Strategy
- Fleet Results
- Financial Results
- Mode Choice Results

Fleet Control Based Strategies

- Assignment
- Repositioning

Vehicle and Programmatic Designs

- In-built safety features
- Matching, advertising, incentives







Human Factors Survey

- Survey issued to 2,884 Americans in a nationally representative sample
- Stated choice question asked respondents to choose between pooled and solo
- Please see poster presentation TRBAM-24-06021

Example Question

Category	Option I	Option II
Trip Purpose/Time of Day	Urgent, Night	
Rideshare Type	Personal	Pooled
Travel Time	28	39-51
Trip Cost	22.12	12.61
Walking Distance	N/A	¼ Mile (about 6 mins)
Potential Additional Passengers	N/A	1 (Pre-screened)
Vehicle Type	Large (6 Passengers, 5 bags)	

Survey Sections

1. Your Transportation Needs

II. Willingness to Consider

III. Pooled/Solo Stated Choice

IV. Most Important Factors

V. Demographics





PR Choice Model

PR Choice Model

- Determines agent behavior when presented with alternative between PR and solo ride, Mixed Logit
- WTP formulation determines the discount offer based on calculated delay

PR Choice Model Factors		
Demographic Factors	Trip Factors	
Income	Trip Purpose (ex. Urgent/Leisure)	
Gender	Time of Day	
Age	Vehicle Size	
Education	Trip Length	
Employment	# of Additional Passengers	
Zone Type (ex. Urban, Rural)	Walking Time to Pickup Area	
# of Children	Passengers Safety Screened	
# of Vehicles in Household		
Previous Experience with PR		
Typical Transportation Mode		

WTP Required Discount Calculation

$$c = d * \left(\frac{u_d}{u_c} + h * \frac{u_{hd}}{u_c}\right)$$

where

c - % cost saving

d - % delay

h - the trip urgency (binary, 1 is urgent) u_d, u_c, u_{hd} - utilities for delay, cost, urgency/delay interaction

PR Choice Calculation

$$u = u_d * d + u_g * g + u_a * a + [...] + u_n * n$$

$$p = \frac{e^u}{1 + e^u}$$

Random draw from uniform distribution for choice





Heuristic PR Assignment with Discount

Rideshare Request Submission

PR Choice Model



Fixed rate discounts offered for improving pooling

Heuristic Assignment:

PR choice based on zonal average

Heuristic nearest vehicle search is used

predicted trip attributes

for vehicle assignment

Demographics attributes



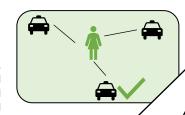
Zonal average approximation to predict trip attribute values prior to assignment

Vehicle Search

Wait Time Filtering

Nearest

On-board Passenger Check



Routing Delay =
Routed Solo Travel Time Routed Pooled Travel Time

Selection

Angular Incidence Calculation

Routing Calculation

Routing Delay Calculation

Selection of closest satisfactory vehicle



Assignment



Pooled ride

Solo ride

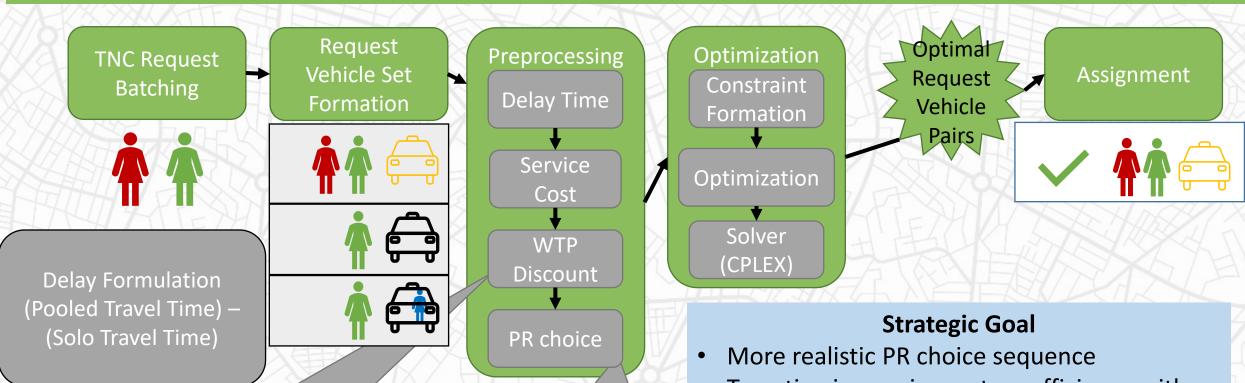
Strategy Notes:

- Simplistic formulation is robust and behaves predictably
- Heuristic strategy is timeefficient but could not achieve the best performance in maximizing the factor effects
- High sensitivity to density





Optimization Discount Assignment Strategy



Delay Trip Willingness Discount Requirement Urgency to Pay



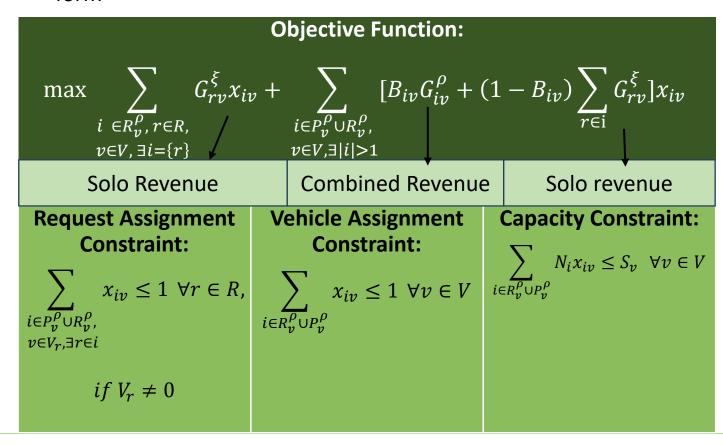
- Targeting increasing system efficiency with active management of discounting/subsidy
- Non-heuristic with practical time of execution for deployment



Core Optimization

Objective

 Maximize gross profit as the linear combination of profits from solo requests and pooled requests, both in parallel and sequential form



Variable	Definition
R	Set of all individual requests r
V	Set of all individual vehicles \emph{v}
$R_{v}^{ ho}$	Subset of feasible pooled requests i that can be
$P_v^{ ho}$	served by v Subset of feasible solo requests that can be served by v
I	Set of combinations of requests $\forall r \in R$ such that $ i > 1$ is pooled and $ i = 1$ is solo
B_{iv}	Binary, 1 if requests in $\it i$ served by $\it v$ overlap and 0 otherwise
$G_{iv}^{ ho}$	Revenue of servicing combine trips i with vehicle $\emph{\emph{v}}$
G_{rv}^{ξ}	Revenue of servicing solo trip r with vehicle v
N_i	Sum of riders in requests r in request set i
S_v	Available seats in \emph{v}
X_{iv}	Binary, 1 if request set i assigned to vehicle v

Mixed Integer Linear Programming (MILP)

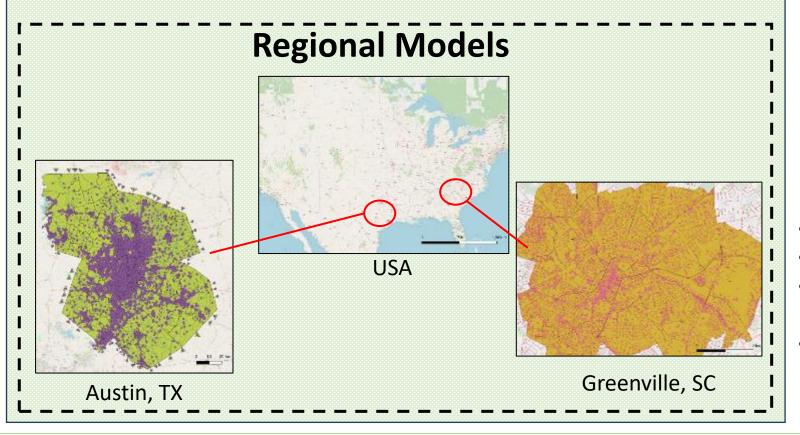
- Fast enough to use real time
- Optimality
- Batching, sensitive to larger action spaces





Numerical Experiments

- POLARIS, agent-based simulation used for testing
- Heuristic based strategy used for comparison
 - Heuristic matches nearest vehicle with pooling pre-approval



Cities	Fleet Sizes	Strategy
Greenville, SC (GSC)	200, 300, 500	Heuristic (H), Discount Based (D), Optimization Only (ND)
Austin, TX (ATX)	15K, 25K, 35K	Heuristic (H), Discount Based (D), Optimization Only (ND)

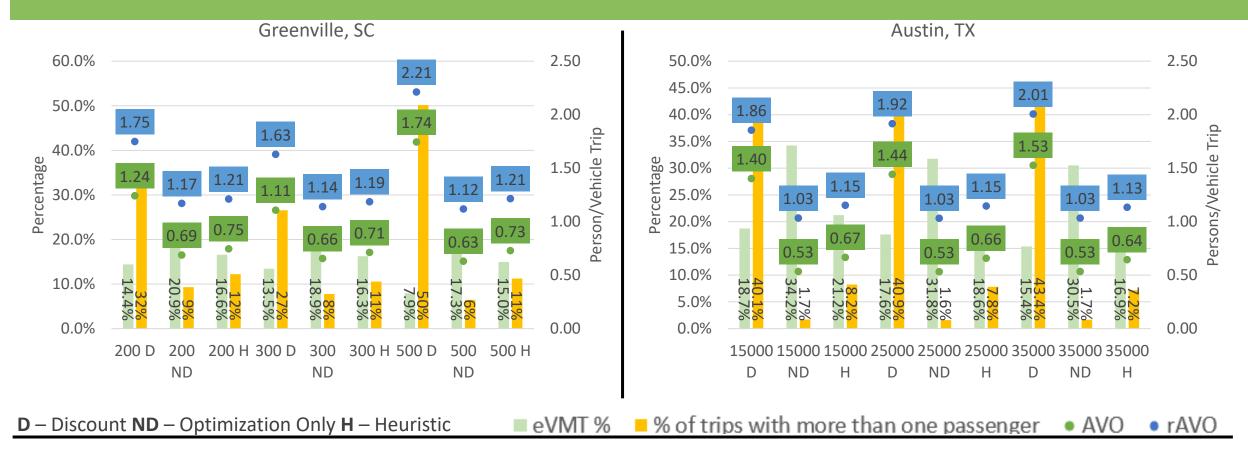
Test Cases

- Discount runs executed first
- Effective overall discount rate calculated
- Heuristic strategy run for each fleet size with calculated homogeneous discount rate
- Supply Demand Mismatch Characteristics:
 - GVL Excess Supply, ATX- Excess Demand





Fleet Level Results



Conclusions: Discount strategy significantly improves eVMT, Trip Pooling, rAVO, and AVO in both regions.

eVMT: $\sqrt{7.1\%}$ GSC, $\sqrt{2.5\%}$ ATX Trip Pooling(raw %): \uparrow 39% GSC, \uparrow 36% ATX

AVO: ↑ 1.01 persons/trip GSC, ↑ 0.89 persons/trip ATX **rAVO:** ↑ 1.00 persons/trip GSC, ↑ 0.88 persons/trip ATX



Financial Calculations

- Fare Calculations
 - Fare model calibrated from Chicago TNC Dataset (2023)
 - $f = b + milage * b_{mile} + time * b_{min}$
- Revenue
 - $r = f d_r * f$
- Assumptions
 - Fare calculated on experienced trip (future work to address)
 - Driver costs not considered

Model Attribute	Variable	Value
Fare	f	-
Intercept	b	\$5.09
Per Mile Rate	b_{mile}	\$0.89/mile
Per Minute Rate	b_{min}	\$0.29/min
Number of observations	-	11,973,880
R^2	-	0.67
Ride Discount	d_r	-
Revenue	r	-
Per Mile Operating Cost	-	High: \$0.80/mile Low: \$0.50/mile [1]

[1] J. Farhan and T. D. Chen, "Impact of ridesharing on operational efficiency of shared autonomous electric vehicle fleet," *Transportation Research Part C: Emerging Technologies*, vol. 93, pp. 310–321, Aug. 2018, doi: 10.1016/j.trc.2018.04.022.





Financial Results



Conclusions: Discount strategy improves profitability significantly in Austin, but decreases slightly in Greenville, likely due to supply/demand.

Max Profit (Low Cost - Raw): \downarrow \$13.4K GSC, \uparrow \$1.40M ATX

Max Profit (High Cost - Raw): ↓ \$40.8K GSC, ↑ \$1.44M ATX

Max Profit(Low Cost - %): \downarrow 12% GSC, \uparrow 408% ATX

Max Profit(High Cost - %): ↓ 11% GSC, ↑ 403% ATX





Level of Service Changes



Conclusions: Discount strategy increases average weight time, average trip time and average fare (before discount applied).

Average Wait Time: ↑ 11.4 min ATX **Average Travel Time:** ↑ 15.9 min ATX **Average Fare:** ↑ \$5.60 ATX

Underlying shifts in demand due to sharing and handling likely contribute to increases on top of pooling.



Conclusions



Proactive Assignment

- Realistic consideration of rider behavior
- Possibility of profitability and public transportation replacement



Future work

- Autonomie Emissions Study
- Repositioning strategy LP modifications
- RL based repositioning strategy



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