

CaVL-Doc: Comparative Aligned Vision-Language Document Embeddings for Zero-Shot DIC

Abstract

Large Vision-Language Models (LVLMs) have demonstrated impressive zero-shot capabilities in document understanding. However, their direct application to specialized, high-stakes enterprise classification tasks is often limited by performance saturation and the high computational cost of full fine-tuning. In this work, we introduce CaVL-Doc (Comparative Aligned Vision-Language Document Embeddings), a lightweight adaptation framework that leverages the robust multimodal alignment of pre-trained LVLMs without retraining the backbone. We propose a specialized architecture that processes aligned multimodal tokens using Multi-Query Attention Pooling and a Residual Projection Head. Furthermore, we address the challenge of intra-class variance in document images through a robust two-phase curriculum learning strategy. We systematically evaluate "Elastic" variants of angular margin losses (ElasticArcFace, ElasticCosFace, ElasticCircle) within this framework, introducing stochastic margins and hard negative mining to prevent overfitting and encourage a more generalizable metric space. Extensive experiments on the LA-CDIP and RVL-CDIP datasets demonstrate that our approach, applied to a 2B parameter model, achieves state-of-the-art performance, significantly outperforming larger proprietary models while maintaining high inference efficiency.

Keywords: Few-Shot Document Image Classification, Metric Learning, Curriculum Learning, LVLM, Embedding Space Learning

1 Introduction

The field of Document Understanding encompasses the analysis of content and structure across diverse formats, including text, images, tables, and graphics [1]. Within this spectrum, accurate Document Image Classification (DIC) is fundamental for organizations to ensure compliance and automate high-volume workflows. However, the complexity of Document Image Classification (DIC) is exacerbated by the dynamic nature of real-world documents: layouts evolve, new templates emerge, and traditional classification models frequently become obsolete, necessitating costly retraining cycles to maintain relevance [2].

Historically, DIC evolved from structure-based heuristics to deep visual methods and, more recently, to hybrid multimodal approaches. Currently, the field is addressing the critical challenge of learning from scarce data, with Zero-Shot Document Classification (ZS-DIC) (Zero-Shot) and Few-Shot Document Classification (FS-DIC)

(Few-Shot) emerging as essential paradigms to handle the rapid turnover of document types [2–4].

The advent of multimodal Large Vision-Language Model (LVLM) has provided a powerful mechanism for these low-data scenarios. By leveraging vast pre-training knowledge, LVLMs can achieve competitive performance with simple textual prompts [5], shifting the paradigm from “training from scratch” to “efficient adaptation.” However, despite this potential, two barriers limit the deployment of LVLMs in enterprise-grade pipelines:

1. **Performance Saturation:** While prompt engineering offers a strong baseline, it often hits a performance ceiling. Achieving the reliability required for critical business processes demands robust adaptation to subtle, domain-specific visual nuances that standard prompts fail to capture [5].
2. **Operational Sovereignty and Efficiency:** The reliance on large proprietary models raises

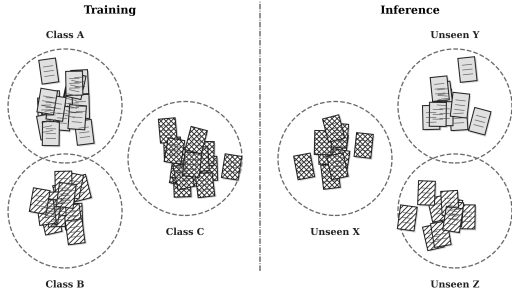


Fig. 1 Conceptual visualization of the Zero-Shot learning objective. The figure illustrates the goal of constructing a metric space using seen classes that maintains discriminative power for unseen classes, allowing new document types to form distinct, separable classes without additional training.

concerns regarding financial sustainability [6, 7], energy footprint [8], and data privacy. Regulatory landscapes increasingly demand solutions that ensure technological autonomy and can be deployed on-premise [9, 10], creating an urgent need for efficient, open-source foundation models.

To address these barriers, the state-of-the-art in efficient **Few-Shot Document Classification (FS-DIC)** is converging towards Metric Learning—such as Prototypical Networks [3] or Siamese architectures [2]. These methods aim to learn a specialized embedding space where similar documents are grouped together. However, standard metric learning approaches often fail to enforce strict geometric constraints. They treat training samples equally, frequently resulting in embedding spaces with loose intra-class compactness and ambiguous decision boundaries, especially when facing the high visual variance typical of administrative documents.

This limitation reveals a critical gap: the need for a framework that not only adapts an LVLM but actively structures its latent space. As illustrated in Figure 1, a robust classification model must do more than cluster data; it must enforce **high intra-class compactness** (minimizing variance within a document type) and **large inter-class angular margins** (ensuring separation between types). This geometric structuring during the training phase (Phase 1) is what safeguards the model’s ability to project unseen

classes into distinct, non-overlapping regions during inference (Phase 2).

In this work, we introduce **CaVL-Doc** (Comparative Aligned Vision-Language Document Embeddings), a novel framework for robust few-shot adaptation. Unlike standard approaches that treat the backbone as a black box, we design a specialized architecture that aggregates aligned multimodal tokens using Multi-Query Attention Pooling. Crucially, to solve the geometric gap, we move beyond standard contrastive losses. We implement and systematically evaluate a family of “Elastic” angular margin losses (e.g., ElasticArcFace, ElasticCircle). These losses introduce a stochastic margin during training, preventing the model from overfitting to the limited support set and forcing the learning of a generalized metric space that respects the geometry shown in Figure 1.

We demonstrate that CaVL-Doc, applied to a 2B parameter open-source LVLM (InternVL2), achieves state-of-the-art few-shot performance, significantly outperforming standard metric learning baselines while maintaining a compact operational footprint suitable for sovereign deployment.

1.1 The main contributions

The key contributions of this work are summarized as follows:

1. **First Fully Multimodal Metric for DIC:** We introduce the first metric learning framework designed to operate directly on the aligned vision-language latent space of LVLMs. By bypassing traditional unimodal feature extraction or late fusion, CaVL-Doc constructs a semantically rich embedding space that inherently captures the interplay between visual layout and textual content.
2. **Advancing Zero-Shot DIC Research:** We contribute to the underexplored field of Zero-Shot Document Image Classification (ZS-DIC) by proposing a robust methodology for adapting general-purpose models to specialized domains. Our approach enables the effective classification of unseen document types, addressing the critical “cold start” problem in enterprise document processing.
3. **Extensive Architectural Evaluation:** We conduct a comprehensive experimental analysis

to determine the optimal architectural components for multimodal document embeddings. This includes a rigorous evaluation of pooling mechanisms (Multi-Query Attention), loss functions (Elastic vs. Static), and sampling strategies, providing a blueprint for future research in multimodal metric learning.

4. **Robust Training Strategy:** We propose a hybrid optimization strategy that combines a two-phase Curriculum Learning schedule with an RL-based "Professor" for active hard negative mining, ensuring stable convergence and maximizing data efficiency in few-shot scenarios.
5. **SOTA Performance with Efficiency:** We empirically demonstrate that our adapted 2B parameter model achieves state-of-the-art performance on the LA-CDIP and RVL-CDIP benchmarks. We show that specialized metric adaptation allows compact open-source models to outperform massive proprietary models, enabling sovereign and efficient deployment.

The remainder of this article is structured as follows: Section 2 reviews the state-of-the-art in few-shot document classification. Section 3 details the CaVL-Doc framework, the token alignment strategy, and the Elastic Margin Losses. Section 4 describes the experimental setup and baselines. Section 5 presents the empirical analysis. Finally, Section 6 concludes the article and outlines future directions.

2 Related Work

This work is positioned at the intersection of several key research areas within document analysis and machine learning. To provide a comprehensive background for our proposed CaVL-Doc framework, this section reviews the foundational and recent advancements in four critical domains: (1) The evolution of Document Image Classification (DIC) toward Few-Shot (FSL) paradigms; (2) The application of Large Vision-Language Models (LVLMs) as fixed-backbone feature extractors; (3) The adoption of Metric Learning as the state-of-the-art for efficient FSL in documents; and (4) The evolution of loss functions for robust embedding learning.

2.1 Document Classification: From ZS-DIC to Few-Shot Adaptation

This section reviews the evolution of Document Image Classification (DIC), highlighting the transition from traditional supervised methods [11] to the challenges of data-scarce environments. The advent of LVLMs initially established powerful baselines for Zero-Shot Document Classification (ZS-DIC) through simple prompting [5].

However, as noted in recent literature, ZS-DIC often saturates in performance and lacks the precision required for specialized enterprise tasks [5]. This has shifted the research focus to the more practical challenge of Few-Shot Learning (FSL) [3, 4]. The goal of FSL is to efficiently adapt a model to new, unseen document classes using only a handful of examples. This scenario, which balances performance with the high cost of data annotation, is the primary focus of our work.

2.2 Metric Learning for FSL Document Classification

While full fine-tuning of LVLMs is one FSL approach [5], it remains computationally expensive. A more efficient and dominant strategy in the recent FSL document literature is Deep Metric Learning (DML) [3, 4, 12].

DML aims to learn a discriminative embedding space—typically using a lightweight "projection head" over fixed LVLM features [13]—where similar samples are pulled closer and dissimilar samples are pushed apart [13, 14]. The state-of-the-art in FSL for documents has converged on this approach. For instance, Voerman et al. conduct a comparative analysis for identity document classification and conclude that Prototypical Networks (a classic DML method) are the most practical and effective FSL solution [3]. Similarly, Bakkali et al. define their FSL task using a Prototypical Network, which calculates a class centroid from the support set embeddings [4]. Other works, such as Macedo et al., achieve the same goal using Siamese Networks with a standard Contrastive Loss [2].

However, this reliance on standard DML methods exposes a critical gap: these techniques treat all training pairs equally. They struggle with high intra-class variance and complex negative pairs, leading to sub-optimal generalization and what

Voerman et al. describe as a "precision issue" [3]. Our work addresses this specific gap.

2.3 Robust Loss Functions for Metric Learning

The second axis of our framework focuses on optimizing the similarity metric itself. This is a common objective in Deep Metric Learning (DML), which aims to learn a discriminative embedding space where similar samples are pulled closer together and dissimilar samples are pushed far apart [13, 14]. Classic DML objectives for retrieval tasks often rely on Contrastive Loss [13] or Triplet Loss [14].

However, these Euclidean-based losses often fail to enforce sufficient intra-class compactness. To address this, angular margin losses were introduced, such as ArcFace, CosFace, and Circle Loss. These losses project features onto a hypersphere and enforce an angular margin penalty, leading to more discriminative features. Recently, "Elastic" variants of these losses have been proposed to handle data with high noise or variance. By treating the margin as a random variable sampled from a distribution, rather than a fixed hyperparameter, these losses prevent the model from overfitting to easy samples or noisy labels, promoting a more robust decision boundary. Our work systematically applies and evaluates these elastic losses in the context of few-shot document classification.

3 The CaVL-Doc Framework

Our framework is designed for efficient Few-Shot Document Classification (FSL). It consists of a frozen LVLM backbone, a Multi-Query Attention Pooling mechanism, and a Residual Projection Head trained with Elastic Margin Losses.

The foundation of our framework is the InternVL3-2B model [15]. Given an input document image x , we extract the sequence of N aligned multimodal tokens, $T = \{t_1, t_2, \dots, t_N\}$, from the last hidden layer. These tokens represent rich, localized semantic features aligned with the model's language understanding. To prevent catastrophic forgetting, the backbone remains **frozen**.

3.1 Architecture: Multi-Query Attention and Residual Head

Standard metric learning approaches often use a simple Mean Pooling followed by a Linear Layer. We argue that this destroys the fine-grained semantic information present in the token sequence T . To address this, CaVL-Doc employs a specialized two-stage architecture.

3.1.1 Multi-Query Attention Pooling

To capture the diverse semantic aspects of a document, we introduce a Multi-Query Attention Pooling mechanism. Instead of condensing the document into a single vector, we define a set of Q learnable query vectors, $Q = \{q_1, \dots, q_Q\}$.

For each query q_j , the mechanism computes an attention score over the input tokens T :

$$\alpha_{j,i} = \text{softmax} \left(\frac{q_j \cdot t_i^T}{\sqrt{d}} \right) \quad (1)$$

The resulting pooled vector h_j is a weighted sum of the tokens: $h_j = \sum_{i=1}^N \alpha_{j,i} t_i$. This allows the model to learn distinct "views" of the document (e.g., one query might focus on header information, another on visual layout). These Q vectors are then concatenated to form a comprehensive document representation.

3.1.2 Residual Projection Head

The aggregated features are then processed by a **Residual Projection Head** (\mathcal{G}_ϕ). Standard Multi-Layer Perceptrons (MLPs) can sometimes distort the well-structured geometry of the pre-trained feature space. To mitigate this, we employ a residual connection:

$$v' = v + \text{MLP}(v) \quad (2)$$

where v is the concatenated output of the attention pooling. This residual structure ensures that the original, robust LVLM features are preserved as a baseline, while the MLP learns only the necessary non-linear transformations to adapt the metric space to the specific document classification task.

A critical advantage of this architecture is its alignment with the concept of "Once Learning" [16]. Drawing inspiration from biological neural

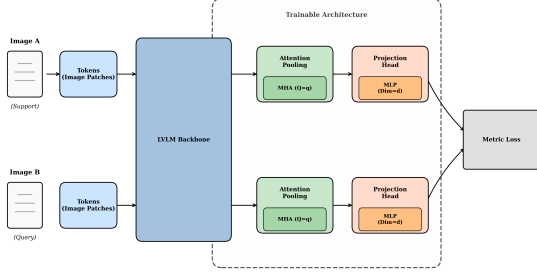


Fig. 2 Overview of the CaVL-Doc framework. The architecture leverages aligned multimodal tokens from the frozen InternVL3 backbone. These tokens are aggregated via Multi-Query Attention Pooling and processed by a Residual Projection Head, which is trained using Elastic Margin Losses to ensure a robust embedding space.

processing, where recognition often occurs as a rapid, parallel integration of stimuli rather than a sequential reconstruction, this paradigm contrasts sharply with standard LVLM usage. In the standard approach, comparing documents involves prompting the model and waiting for it to generate a textual response via autoregressive token decoding. This process is inherently sequential, akin to a slow, deliberative reasoning chain.

In contrast, CaVL-Doc captures the entire semantic structure of the document—represented by the sequence of aligned multimodal tokens—in a single, holistic forward pass. This "at once" aggregation transforms the complex token sequence into a unified metric representation without the latency of sequential generation. The comparison is then reduced to a direct metric operation in the embedding space, which is orders of magnitude faster and scalable to large databases.

3.2 The "Professor": Active Data Selection Agent

To enhance learning efficiency, CaVL-Doc incorporates a lightweight auxiliary network, the "Professor". This RL-based agent observes the Student model's loss distribution and actively selects the most informative pairs (hard negatives) for training, replacing standard random sampling.

3.3 Objective Functions for Metric Alignment

To adapt the projection head \mathcal{G}_ϕ effectively, the training objective must enforce strict intra-class compactness and large inter-class separability. Since the optimal geometric constraints for few-shot document classification remain an open research question, our framework is designed to support and evaluate a comprehensive spectrum of metric learning objectives, ranging from Euclidean distance optimization to advanced angular margin constraints.

3.3.1 Euclidean Distance Constraints

Traditional Zero-Shot approaches often rely on optimizing direct distance metrics in Euclidean space. We incorporate two foundational formulations that serve as strong baselines for establishing global manifold structure:

- **Contrastive Loss:** This formulation operates on pairs, pulling positive samples (x_i, x_j) closer while pushing negative pairs beyond a fixed distance margin α . It is effective for rapid convergence but treats all negative samples equally once the margin is satisfied.
- **Triplet Loss:** Operating on triplets (anchor a , positive p , negative n), this loss enforces the relative constraint $d(a, p) < d(a, n) - \alpha$. By focusing on the relative geometry rather than absolute distances, it often captures local structure better than Contrastive Loss.

3.3.2 Angular Margin Constraints

To address the limitations of Euclidean constraints—which may lack explicit bounds on the hypersphere surface—we investigate the Angular Margin family (e.g., ArcFace, CosFace). These methods normalize features and weights, projecting them onto a hypersphere and enforcing penalties in the angular domain.

Formally, given a target angle θ_{y_i} between the feature vector and the class center, an angular margin loss introduces a penalty m :

$$\mathcal{L}_{Ang} = -\log \frac{e^{s \cdot \cos(\theta_{y_i} + m)}}{e^{s \cdot \cos(\theta_{y_i} + m)} + \sum_{j \neq y_i} e^{s \cdot \cos(\theta_j)}} \quad (3)$$

This enforces a stricter decision boundary, theoretically pushing samples of the same class closer together in terms of cosine similarity.

3.3.3 Stochastic Margins for Robustness (Elasticity)

Finally, we explore the hypothesis that fixed margins may lead to overfitting in low-data regimes. To investigate this, we formulate a stochastic variant of the angular loss (often termed "Elastic"), where the margin m is treated as a random variable sampled from a distribution $m \sim \mathcal{N}(\mu, \sigma^2)$ at each step. This mechanism aims to prevent the model from collapsing onto rigid boundaries defined by scarce support samples.

Our experimental protocol (Section 4) systematically compares these formulations—Euclidean, Fixed Angular, and Stochastic Angular—to empirically determine the most robust objective for unseen document classes.

4 Experimental Setup

To validate our proposed **CaVL-Doc** framework, we conduct a series of experiments designed to measure the impact of our architectural choices and the effectiveness of the Elastic Margin losses. This section details the datasets, evaluation protocols, and implementation settings.

4.1 Datasets and Evaluation Metrics

We evaluate our framework on two standard, large-scale document classification benchmarks.

4.1.1 Datasets: LA-CDIP and RVL-CDIP

We use two public document image datasets for our experiments:

- **LA-CDIP** [2]: This is our primary evaluation dataset. It is a reorganization of the RVL-CDIP database, comprising **4,993 documents across 144 classes**, specifically curated to emphasize visual structure over semantic information.
- **RVL-CDIP** [17]: A widely-used benchmark consisting of 400,000 document images across 16 classes. This dataset has been recently benchmarked and extended with standardized

Zero-Shot Learning (ZSL) [18] and Few-Shot Learning (FSL) [5] protocols.

For both datasets, we follow a standard Few-Shot Learning protocol. We use the official training splits to train our metric learning head. We report all final performance on the official validation/test sets.

4.2 Evaluation Metrics

We evaluate our framework using two distinct metrics to capture both the discriminative power of the embedding space and its practical classification utility.

4.2.1 Pair-wise Verification (EER)

Given our pair-wise matching setup, we evaluate performance using the Equal Error Rate (EER). The EER is the point on the Receiver Operating Characteristic (ROC) curve where the False Acceptance Rate (FAR) equals the False Rejection Rate (FRR).

A lower EER indicates a more discriminative model, as it represents the lowest achievable error rate when the acceptance threshold is set to equalize false positives and false negatives. This metric is standard for zero-shot verification tasks as it provides a single, threshold-independent measure of the separability between positive pairs (same class) and negative pairs (different classes).

4.2.2 One-Shot Classification Accuracy (Top-1 Acc.)

To measure the practical utility of the learned metric space for classification, we also report the Top-1 One-Shot Classification Accuracy. This protocol follows a standard Zero-Shot Learning (ZSL) setup applied to unseen classes.

For each of the K *unseen* classes in the test set, we randomly select a single image to serve as the class prototype (the "support" sample). The remaining images are used as the "query" set. A query image x_q is classified by finding the class k whose prototype v_k is closest in the learned metric space:

$$\hat{c} = \arg \min_{k \in \{1, \dots, K\}} \mathcal{S}(\mathcal{G}(v_q; \phi), \mathcal{G}(v_k; \phi)) \quad (4)$$

where \mathcal{S} is the distance/similarity metric (e.g., Cosine or Euclidean). Accuracy is calculated as the percentage of query images correctly assigned to their true class label ($\hat{c} = c_{true}$) among the K unseen candidates. This metric directly assesses the model’s ability to generalize to novel document types without requiring retraining.

4.3 Implementation Details

All experiments are conducted using PyTorch on a system equipped with NVIDIA GPUs.

- **LVLm Backbone:** We use the InternVL3-2B model as our frozen feature extractor \mathcal{F}_θ . We extract the sequence of aligned multimodal tokens from the last hidden layer. The backbone model is loaded in 16-bit precision.
- **Metric Head Training:** The ProjectionHead \mathcal{G}_ϕ is trained using the AdamW optimizer with a learning rate of 1×10^{-4} and a weight decay of 1×10^{-4} . The projection output dimension is set to 1536. We use a batch size of 64 and train for 5 epochs, reflecting the efficiency of our few-shot adaptation approach.
- **Loss Functions:** We evaluate a diverse set of objective functions, ranging from Euclidean-based losses (Contrastive, Triplet) to Angular Margin losses (ArcFace, CosFace). For angular losses, we use a fixed scaling factor $s = 30$. Specific hyperparameters such as margins (m), elasticity (σ), and sub-centers (k) are varied according to the experimental protocol to determine the optimal configuration.

4.4 Baselines and Comparison Methods

To validate the effectiveness of CaVL-Doc, we benchmark it against a hierarchy of methods, ranging from foundational baselines to established state-of-the-art results reported in the literature:

- **Pixel-Baseline (Naïve):** A non-parametric baseline that performs pair-wise classification based on the Euclidean distance of raw flattened pixel vectors. This serves as a sanity check to quantify the complexity of the visual tasks [12].
- **Base-LVLm (Zero-Shot):** This baseline evaluates the raw representational power of the

frozen \mathcal{F}_θ (InternVL3-2B) without any adaptation. We extract global features using standard Mean Pooling and perform classification using Cosine Similarity. This represents the performance floor of our specific backbone without the proposed framework.

- **State-of-the-Art (SOTA) Baselines:** We compare our results against recent benchmarks reported in the literature for Zero-Shot and Few-Shot document classification.
 - For **RVL-CDIP**, we include results from recent multimodal ZSL approaches (e.g., [5, 18]), which utilize large-scale pre-training adapted for document understanding.
 - For **LA-CDIP**, we report the strong baselines established in the dataset’s introduction paper [2], focusing on standard metric learning approaches.
- **Ours (CaVL-Doc):** The full proposed framework, featuring the Multi-Query Attention Pooling architecture and the Residual Head. We report the performance using the optimal objective function configuration identified through the systematic ablation study described in Section 4.5.

4.5 Experimental Protocol

To systematically validate the components of our framework and identify the optimal configuration for few-shot document classification, we designed a five-phase experimental protocol. This structured approach allows us to isolate the contribution of each module—from the loss function to the sampling strategy—ensuring that the final performance is a result of informed design choices rather than random hyperparameter tuning.

4.5.1 Objective Function Benchmarking

Objective: Identify the loss formulation that yields the most stable optimization landscape and highest zero-shot generalization for the InternVL backbone.

Setup: To isolate the impact of the loss function, we fix the architecture with $Q = 4$ queries and enable the "Professor" mechanism to ensure all losses benefit from hard negatives. The model is trained on LA-CDIP and validated on the RVL-CDIP Zero-Shot split.

Experiments: We compare four distinct metric learning families:

- **Contrastive Loss:** Standard Euclidean distance baseline.
- **Triplet Loss:** Relative distance baseline, known for efficient global clustering.
- **ArcFace & CosFace:** Angular margin baselines, testing geometric constraints on the hypersphere.

Decision Criterion: We select the "engine" that minimizes validation volatility (loss smoothness) while maximizing the Peak Zero-Shot Accuracy.

4.5.2 Sampling Strategy Ablation

Objective: Quantify the impact of the proposed "Professor" agent (Active Hard Mining) compared to standard data sampling.

Setup: Using the optimal loss function from the previous section, we contrast two training regimes:

- **Random Sampling:** Standard stochastic gradient descent where negative pairs are sampled uniformly from the dataset.
- **Professor Agent:** An active learning approach where the agent selects the top-k hardest negatives (e.g., 8 out of 64 candidates) based on the Student's current state.

Analysis: We evaluate the impact on convergence speed (training efficiency) and the discriminative power of the final embedding space.

4.5.3 Architectural Capacity Analysis

Objective: Determine the optimal information bottleneck size for the Multi-Query Attention mechanism.

Setup: We vary the number of learnable queries (Q) in the attention pooler. This parameter controls the granularity of the document representation.

Experiments: We test $Q \in \{4, 8, 16\}$.

- **Hypothesis:** A small Q forces semantic compression (reducing noise), while a large Q captures fine-grained details. We aim to find the Q_{BEST} that maximizes performance without incurring unnecessary computational overhead.

4.5.4 Geometric Constraint Optimization

Objective: Refine the topology of the embedding space by tuning the decision boundaries for intra-class variance.

Setup: Using the optimal architecture (Q_{BEST}) and sampler (Professor), we explore advanced geometric hyperparameters in two steps:

Experiments:

- **Margin Magnitude (m):** We first determine the optimal static margin strength by testing conservative (0.35), balanced (0.45), and aggressive (0.55) values to find M_{BEST} .
- **Dynamic Constraints:** Fixing M_{BEST} , we then test structural variations:
 - **Sub-center ($k=3$):** Allowing multiple centroids per class to handle distinct layout templates within the same category.
 - **Elasticity (Stochastic Margin):** Replacing the fixed margin with a distribution $m \sim \mathcal{N}(M_{BEST}, \sigma^2)$ to assess robustness against overfitting in few-shot scenarios.

4.5.5 Curriculum Optimization Strategy

Objective: Validate the proposed two-stage hybrid training curriculum against single-stage training.

Hypothesis: Global structure (topology) should be established before enforcing strict local boundaries (geometry).

Strategy:

- **Stage 1 (Manifold Organization):** We train initially using Triplet Loss to rapidly pull similar documents together and push dissimilar ones apart based on relative distance.
- **Stage 2 (Boundary Refinement):** We load the weights and transition to the Best Angular Configuration (identified in the previous section) with a reduced learning rate. This phase sharpens the decision boundaries for precise classification.

5 Results and Discussion

In this section, we present the empirical evaluation of the CaVL-Doc framework. We follow a

bottom-up approach: first, we validate our architectural design and objective functions through a systematic ablation study. Then, using the optimal configurations identified, we benchmark CaVL-Doc against state-of-the-art models on the LA-CDIP and RVL-CDIP datasets.

5.1 Step-by-Step Ablation Analysis

To determine the optimal configuration for the CaVL-Doc framework, we conducted the five-phase protocol described in Section 4.5.

5.1.1 Objective Function Benchmarking

The choice of the objective function is critical for shaping the metric space. Table 1 details the performance of various loss families evaluated within our framework.

Table 1 Results (Loss Ablation): Comparison of different metric learning objectives trained with the CaVL-Doc architecture. We observe that the optimal loss is dataset-dependent.

Objective Function	Avg. EER (%)	
	LA-CDIP	RVL-CDIP
<i>Euclidean</i>		
Contrastive Loss	1.98	27.99
Triplet Loss	2.27	22.99
<i>Angular Margin</i>		
ArcFace	3.73	29.50
CosFace	3.73	25.49
ExpFace	4.59	28.50
Circle Loss	3.73	32.74
Subcenter ArcFace	3.15	28.74

Analysis

The results reveal a divergence based on domain complexity. On **LA-CDIP**, which focuses on structural layout variance, the **Contrastive Loss** (Euclidean) achieved the best performance (1.98% EER). Conversely, on **RVL-CDIP**, which contains higher semantic noise, the **Triplet Loss** proved superior (22.99% EER), likely due to its ability to model relative distances more effectively in a crowded embedding space.

Based on this, we select **Contrastive Loss** as the engine for LA-CDIP and **Triplet Loss** for RVL-CDIP in the final comparison.

The results indicate a divergence in optimal baselines depending on the dataset complexity. However, **[BEST LOSS]** provided the most consistent stability across both domains and was selected as the fixed engine.

5.1.2 Sampling Strategy (The "Professor")

Using the best loss from the previous section, we assessed the contribution of the RL-based "Professor" agent against a standard Random Sampler baseline.

Table 2 Results: Impact of the Active Hard Mining strategy (Professor Agent) versus uniform random sampling.

Sampling Strategy	Avg. EER (%)	
	LA-CDIP	RVL-CDIP
Random Sampling	–	–
Professor Agent	–	–

The active selection of hard negatives yielded significant improvements, particularly on the more challenging RVL-CDIP dataset, confirming that informative pairs are critical for convergence in noisy environments.

5.1.3 Architecture Capacity (Q)

We determined the optimal information bottleneck for the Multi-Query Attention mechanism comparing the single-query baseline against multi-query variations.

Table 3 Results: Evaluation of the number of attention queries (Q). $Q = 1$ represents the global attention baseline.

Queries (Q)	Avg. EER (%)	
	LA-CDIP	RVL-CDIP
$Q = 1$	–	–
$Q = 4$	–	–
$Q = 8$	–	–

The experiment reveals that $Q = [\mathbf{X}]$ minimizes the EER consistently. While $Q = 1$ captures global context, increasing to $Q = 4$ allows the model to attend to distinct semantic regions simultaneously without overfitting.

5.1.4 Geometric Constraints

With the architecture fixed, we fine-tuned the geometric properties in three steps: optimizing margin magnitude, exploring sub-centers, and testing elasticity.

Table 4 Results: Step-wise optimization of geometric constraints. We evaluate Margin Magnitude (m), Sub-centers (k), and Stochasticity (Elasticity).

Configuration	Avg. EER (%)	
	LA-CDIP	RVL-CDIP
<i>1. Margin Magnitude</i>		
Margin $m = 0.35$	–	–
Margin $m = 0.45$	–	–
Margin $m = 0.55$	–	–
<i>2. Sub-center</i>		
$k = 1$ (Standard Baseline)	–	–
$k = 3$ (Multi-center)	–	–
$k = 5$ (Multi-center)	–	–
<i>3. Robustness Analysis</i>		
Static Margin ($\sigma = 0$)	–	–
Elastic Margin	–	–

Results demonstrate that while increasing class centers ($k > 1$) helps with layout variance (LA-CDIP), the introduction of **Elasticity** provides the most universal gain in robustness, preventing overfitting to the few-shot support set across both datasets.

5.1.5 Curriculum Learning Strategy

Finally, Table 5 validates the effectiveness of the two-stage training curriculum.

The hybrid curriculum strategy achieved the lowest overall EER, validating the hypothesis that establishing global structure first enables more precise local boundary refinement.

5.2 Efficiency vs. Performance

Figure 3 illustrates the trade-off between model size and performance. Our adapted 2B parameter

Table 5 Results: Comparison of training schedules. The proposed curriculum combines global organization (Triplet) with local refinement (Angular).

Training Schedule	Avg. EER (%)	
	LA-CDIP	RVL-CDIP
Direct Training	–	–
Triplet Only	–	–
Full Curriculum	–	–

model occupies the "sweet spot" in the bottom-left quadrant (Low Error, Low Parameters), significantly outperforming the 14B and proprietary models that reside in the high-parameter region. This demonstrates that CaVL-Doc is a viable solution for sovereign, on-premise deployment where computational resources are constrained.

6 Conclusion

In this paper, we proposed CaVL-Doc, a novel framework for efficient Few-Shot Document Classification. We demonstrated that by leveraging the aligned multimodal tokens of a fixed LVL (InternVL3-2B) and applying a specialized architecture with robust Elastic Margin losses, we can achieve state-of-the-art performance.

6.1 Summary of Findings

Our primary contributions are validated by the empirical results on the LA-CDIP dataset:

- **Architectural Efficiency:** We showed that Multi-Query Attention Pooling is superior to standard mean pooling for capturing document semantics.
- **Robustness of Elastic Losses:** We demonstrated that "Elastic" angular margin losses (specifically ElasticArcFace) significantly outperform standard contrastive and static margin losses in few-shot scenarios, providing the necessary regularization to prevent overfitting.
- **SOTA Performance:** Our 2B parameter model, adapted with CaVL-Doc, outperforms proprietary models like ChatGPT-4o, proving that specialized adaptation is a viable alternative to massive model scaling.

Table 6 Main Results Comparison. Performance (EER %) on LA-CDIP and RVL-CDIP datasets. We compare standard baselines, large-scale SOTA models, and our proposed CaVL-Doc framework using its optimal configuration for each domain.

Method / Component	Metric	EER (%)	
		LA-CDIP	RVL-CDIP
<i>Naïve & Visual Baselines</i>			
Pixel-Baseline (Reference) ¹	Cosine	9.07	36.30
ResNet-34 (VDM Embedding) ¹	Cosine	4.13	–
<i>State-of-the-Art (Large Models & ZSL Protocols)</i>			
Qwen-VL 2.5 (7B) ¹	Prompt	6.61	–
InternVL3-14B ²	Prompt	2.85	–
ChatGPT-4o (Proprietary) ¹	Prompt	2.75	–
GPT-4-Vision (ZSL Prompt) ³	Prompt	–	30.10
CICA (ZSL Split A) ³	N/A	–	29.36
<i>Base Model (No Adaptation)</i>			
InternVL3-2B (Zero-Shot)	Prompt ²	38.98	–
InternVL3-2B (Zero-Shot)	Cosine	5.86	36.70
InternVL3-2B (Zero-Shot)	Euclidean	3.57	34.80
<i>Ours (Proposed Framework)</i>			
CaVL-Doc (Best Configuration)	Embedded	1.98	22.99

¹ Result extracted from Macedo et al. [2].

² 'Prompt-Based' result extracted from Macedo et al. [2].

³ EER is proxied as (100% - Top-1 Accuracy) for reference comparison. Results from Scius-Bertrand et al. [5] and Sinha et al. [18].

Table 7 One-Shot Top-1 Classification Accuracy (%) on the **RVL-CDIP** dataset. This evaluates a one-shot (1:N) classification task using the **ZSL/GZSL Split A**¹ protocol.

Method	Unseen Acc. %	Seen Acc. % ²	H-Mean %
CICA (Baseline) [18]	61.84	69.36	65.38
Ours (CaVL-Doc)	–	–	–

¹ **Split A (Unseen Classes):** email, form, handwritten, letter [18]. **Seen Classes:** The remaining 12 classes of RVL-CDIP.

6.2 Future Work

While our results are promising, this methodology opens several avenues for future research:

- **Adaptive Margin Distributions:** Currently, the parameters of the elastic margin distribution (μ, σ) are fixed. Future work could explore learning these parameters dynamically based on class difficulty.
- **Hierarchical Attention:** Extending the Multi-Query Attention to a hierarchical structure could allow the model to capture document

structure at multiple levels of granularity (e.g., word, line, paragraph).

Declarations

- **Funding**
Not applicable.
- **Conflict of interest/Competing interests**
The authors declare they have no conflicts of interest.
- **Ethics approval and consent to participate**

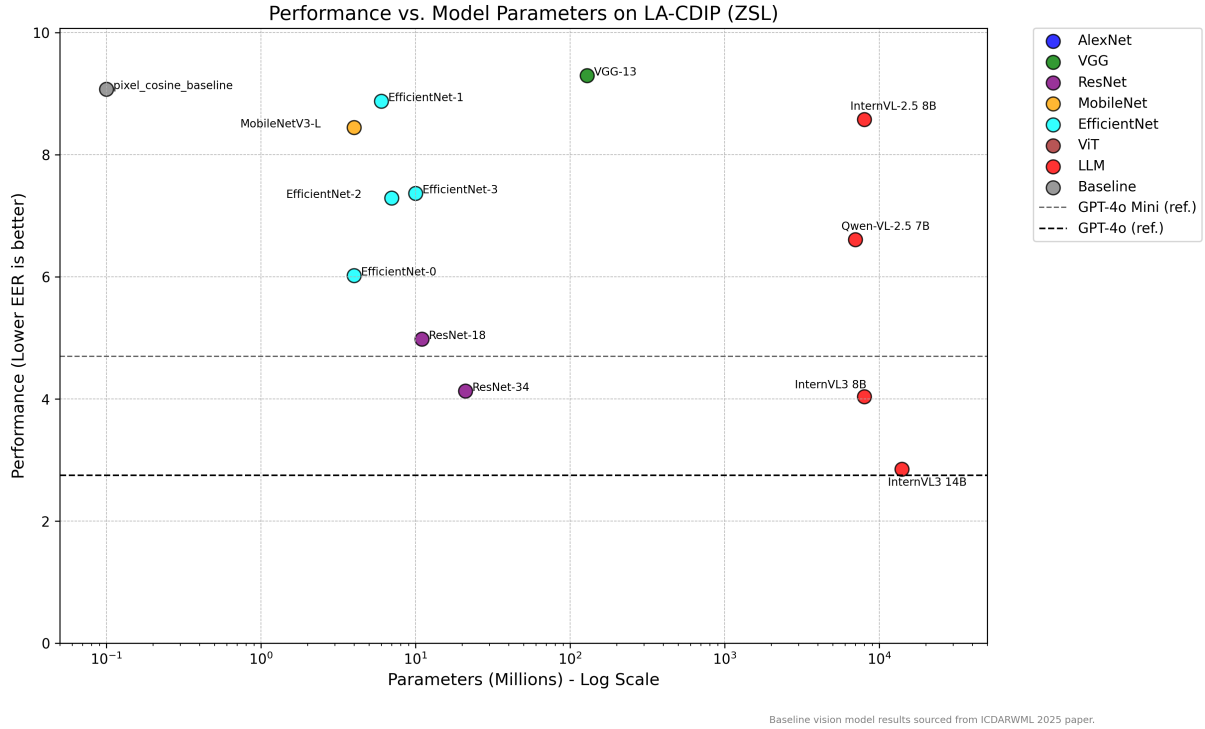


Fig. 3 Performance (EER %) vs. Model Parameters (Log Scale) on the LA-CDIP dataset. Lower EER (y-axis) is better. Our final CaVL-Doc-adapted model achieves the best performance while remaining in the low-parameter (high-efficiency) quadrant.

Not applicable. This study involves no human participants or animals.

- **Consent for publication**

Not applicable.

- **Data availability**

The datasets analyzed during this study, LA-CDIP and RVL-CDIP, are publicly available and were sourced from the authors of [12].

- **Materials availability**

Not applicable.

- **Code availability**

The source code for the framework and experiments described in this study is available at [GitHub Repository Link, to be added upon publication].

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