



An Overview of the LoRA Family

LoRA, DoRA, AdaLoRA, Delta-LoRA, and more variants: adaptation.

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LoRA comes in different shapes and varieties. Photo by [Lucas Georg](#)

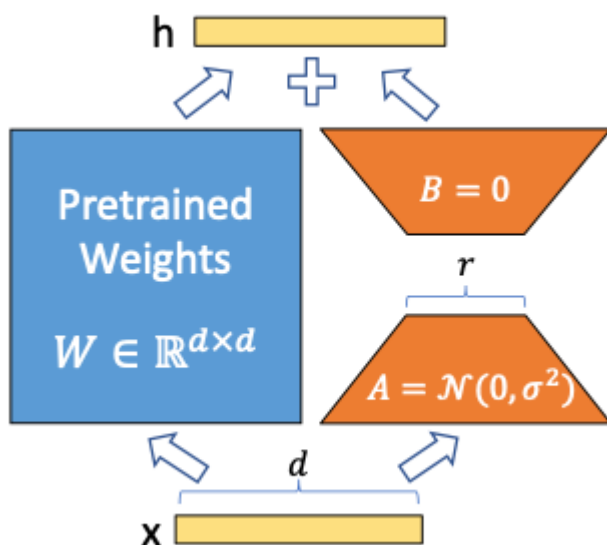
Low-Rank Adaptation (LoRA) can be considered a breakthrough towards the ability to train large language models for specific tasks efficiently. It is widely used today in many applications and has inspired research on how to



main ideas to achieve better performance or train models even faster.

In this article, I want to give an overview of some variants of LoRA, that promise to improve LoRAs capabilities in different ways. I will first explain the basic concept of LoRA itself, before presenting **LoRA+**, **VeRA**, **LoRA-FA**, **LoRA-drop**, **AdaLoRA**, **DoRA** and **DeltaLoRA**. I will introduce the basic concepts and mechanisms, and show, how these approaches deviate from the original LoRA concept. I will spare technical details, unless they are important for understanding the concepts, and will also not discuss evaluations. For readers interested, I linked the original papers at the end of the article.

Lora



The main idea of LoRA is to add two smaller tunable matrices A and B next to the pretrained weights W without changing the parameters of W. Image from [1].

Low-Rank Adaption (**LoRA**) [1] is a technique, that allows us to adapt large language models (LLMs) today to train large language models (LLMs). Large language models (LLMs) come with the capability to predict tokens of next in a natural language input. This is an astonishing achievement, but for solving many problems this is not enough. Most

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want to train an LLM on a given downstream task, such as classifying sentences or generating answers to given questions. The most straightforward way of doing that is fine-tuning, where you train some of the layers of the LLM with data of the desired task. That means training very big models with millions to billions of parameters though.

LoRA gives an alternative way of training that is easier to conduct due to a drastically reduced number of parameters. Next to the parameter weights of a trained LLM layer, LoRA introduces two matrices called *adapters* and that are much smaller. If the parameter matrix W is of size $d \times d$, the matrices A and B are of size $r \times d$, where r is much smaller (typically below 64). The parameter r is called the *rank*. That is, if you use $r=16$, these matrices are of shape $16 \times d$. The more parameters you train. That can lead to better results on the one hand but needs more computation time

Now that we have these new matrices A and B , how do we use them? The input fed to W is also given to BA , and its output is added to the output of the original matrix W . So we add some parameters on top and add their output to the original prediction, which allows you to influence the model without training W anymore, which is why we sometimes call the adapters *frozen*. Importantly, the addition of A and B is not done at the very end (which would just add a layer on top) but is distributed to layers deep inside the neural network.

That is the main idea of LoRA, and its biggest advantage is that you have to train fewer parameters than in fine-tuning to achieve comparable performance. One more technical detail to mention at this place: At the beginning, the mat

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with random values of mean zero, but with some variance around that mean. The matrix B is initialized as a matrix of complete zeros. This ensures, that the LoRA matrices don't change the output of the original W in a random fashion from the very beginning. The update of A and B on W's output should rather be an addition to the original output, once the parameters of A and B are being tuned in the desired direction. However, we will later see that some approaches deviate from this idea for different reasons.

LoRA as just explained is used very often with transformers. However, by now there are many variants of LoRA that deviate from the original method in different ways and aim at improving performance, or both. Some of these I want to point out in the following.

LoRA+

	LoRA	LoRA+
Parameterization	<div><div>Pretrained Weights</div><div>$W \in \mathbb{R}^{n \times n}$</div></div> <div>+</div> <div><div>B</div><div>×</div><div>A</div></div>	
Training	<div>$A \leftarrow A - \eta \times G_A$</div> <div>$B \leftarrow B - \eta \times G_B$</div>	<div>$A \leftarrow A - \eta \times G_A$</div> <div>$B \leftarrow B - \lambda \eta \times G_B$</div> <div>$\lambda \gg 1$</div>

LoRA+ introduces different learning rates for the two matrices A and B, here introduced from [2].

LoRA+ [2] **** introduces a more efficient way of training LoRA adapters by introducing different learning rates for the two matrices A and B.

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B. Most of the time, when training a neural network, there is just one learning rate that is applied to all weight matrices the same way. However, for the adapter matrices used in LoRA, the authors of LoRA+ can show, that it is suboptimal to have that single learning rate. The training becomes more efficient by setting the learning rate of matrix B much higher than that of matrix A.

There is a theoretical argument to justify that approach, which is based on numerical caveats of a neural network model becomes very wide in terms of the number of parameters. However, the math required to prove that is quite involved. If you are really into it, feel free to take a look at this paper [2]). Intuitively, you may think that matrix B, which is initialized to zero, could use bigger update steps than the random matrix A. In addition, there is empirical evidence showing performance improvement by that approach. By setting the learning rate of matrix B 16 times higher than that of matrix A, they have been able to gain a small improvement in model performance (around 2%), while speeding up the training time by factors of 2, such as RoBERTa or Llama-7b.

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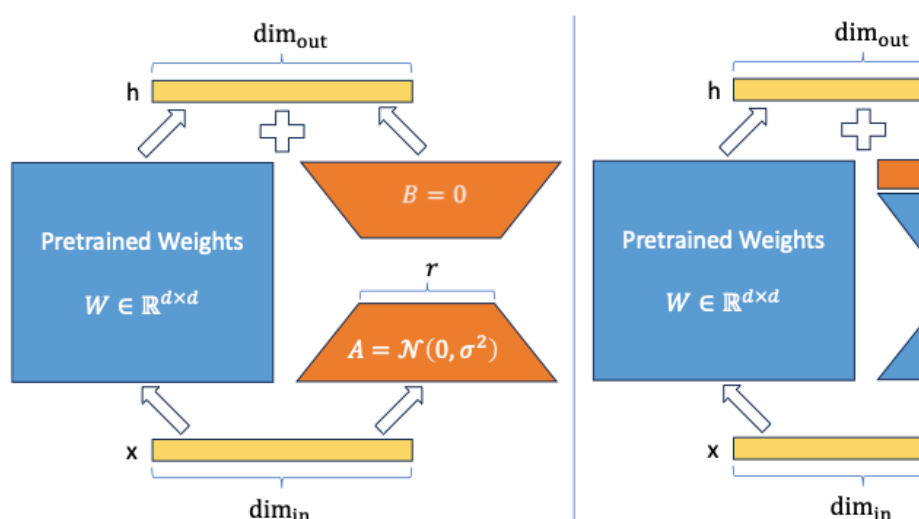
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VeRA



VeRA doesn't train A and B, but initializes them to a random projection and trains additional vectors d and b instead. Image from [3].

With **VeRA** (**Ve**ctor-based **R**andom Matrix **A**daptation) [3], the authors introduce an approach to drastically reduce the parameter size of the LoRA adapters. Instead of training the matrices A and B, which is the core idea of LoRA in the first place, they initialize these matrices with shared random weights (i.e. A and B in all the layers have the same weights) and add vectors d and b. Only these vectors d and b are following.

You may wonder how this can work at all. A and B are initialized with random weights. How should they contribute to the model's performance, if they are not trained at all? This is based on an interesting field of research on soft sparse projections. There is quite some research that in a large neural network only a small fraction of the parameters can steer the behavior and lead to the desired performance of the model was trained for. Due to the random initialization, parts of the model (or sub-networks) are contrived to steer towards the desired model behavior from the very beginning of the training, all parameters are trained though, which are the important subnetworks. That makes it very costly, as most of the parameters that are updated do not add value to the model's prediction.

Based on this idea, there are approaches to only update the relevant sub-networks. A similar behavior can be achieved by training the sub-networks themselves, but by adding vectors after the matrix. Due to the multiplication with the vector, this can lead to the same output as if only sparse parameters in the matrix would. That is the core idea of VeRA propose by introducing the vectors d and b.

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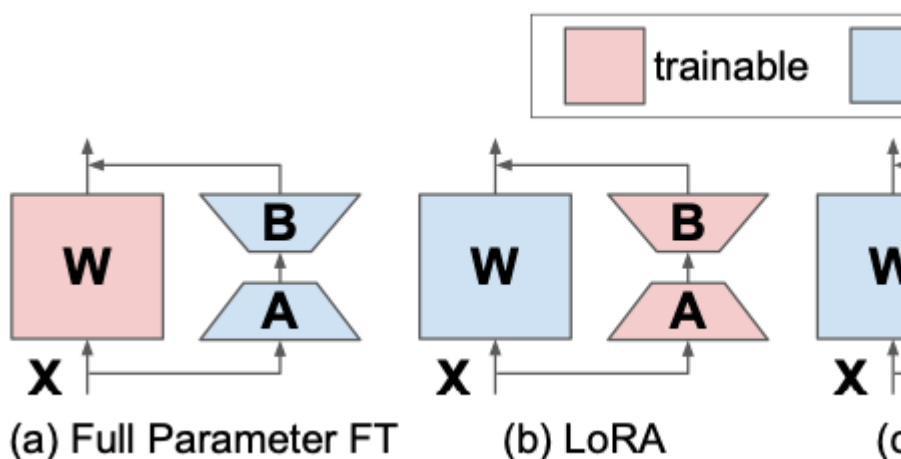
are trained, while the matrices A and B are frozen. Also, in contrast to the original LoRA approach, matrix B is not set to zero anymore but is initialized randomly just as matrix A.

This approach naturally leads to a number of parameters that is much smaller than the full matrices A and B. For example, if you introduce LoRA-layers of rank 16 to GPT-3, you would have 75.5M parameters. With VeRA, you only have 2.8M (a reduction of 96.3%). But how is the performance with such a small number of parameters? The authors of VeRA performed an evaluation on some common benchmarks such as GLUE or E2E based on RoBERTa and GPT2 Medium. Their results show that the VeRA model yields performance that is only slightly lower than models that are fully finetuned or that use the full parameter technique.

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LoRA-FA



LoRA-FA freezes matrix A and only trains matrix B. Image by the author.

Another approach, **LoRA-FA** [4], which stands for **Frozen-A**, is going in a similar direction as VeRA. In this approach, matrix A is frozen after initialization and hence serves as a static projection. Instead of adding new vectors, matrix B is trained to learn the necessary adjustments. Matrix B, though, after being initialized with zeros (just as

LoRA). This halves the number of parameters while having comparable performance to normal LoRA.

LoRa-drop

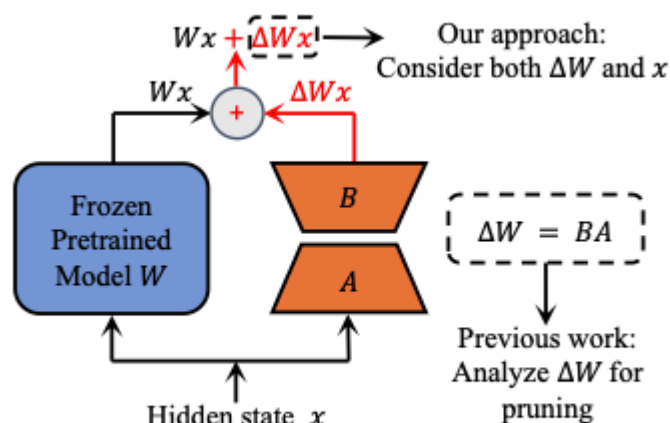


Figure 1: The diagram of LoRA

LoRA-drop uses the output of $B \cdot A$ to decide, which LoRA-layers are worth to

In the beginning, I explained, that you can add L layer in the neural network. **LoRA-drop** [5] intro to decide which layers are worth to be enhance which this is not worth the effort. Even if training much cheaper than finetuning the whole model adapters you add, the more expensive is the tra

LoRA-drop consists of two steps. In the first step subset of the data and train the LoRA adapters. Then you calculate the importance of each LoRA where A and B are the LoRA matrices, and x is simply the output of the LoRA adapters that is a of the frozen layer each. If this output is big, it behavior of the frozen layer more drastically. If it indicates that the LoRA adapter has only little in frozen layer and could as well be omitted.

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Given that importance, you now select the LoRA layers that are most important. There are different ways of doing that. You can sum up the importance values until you reach a threshold, which is controlled by a hyperparameter, or you just take the top n LoRA layers with the highest importance for a fixed n . In any case, in the next step, you conduct the full training on the whole dataset (remember that you used a subset of data for the first step) but only on those layers that you just selected. This is fixed to a shared set of parameters that won't be updated during training.

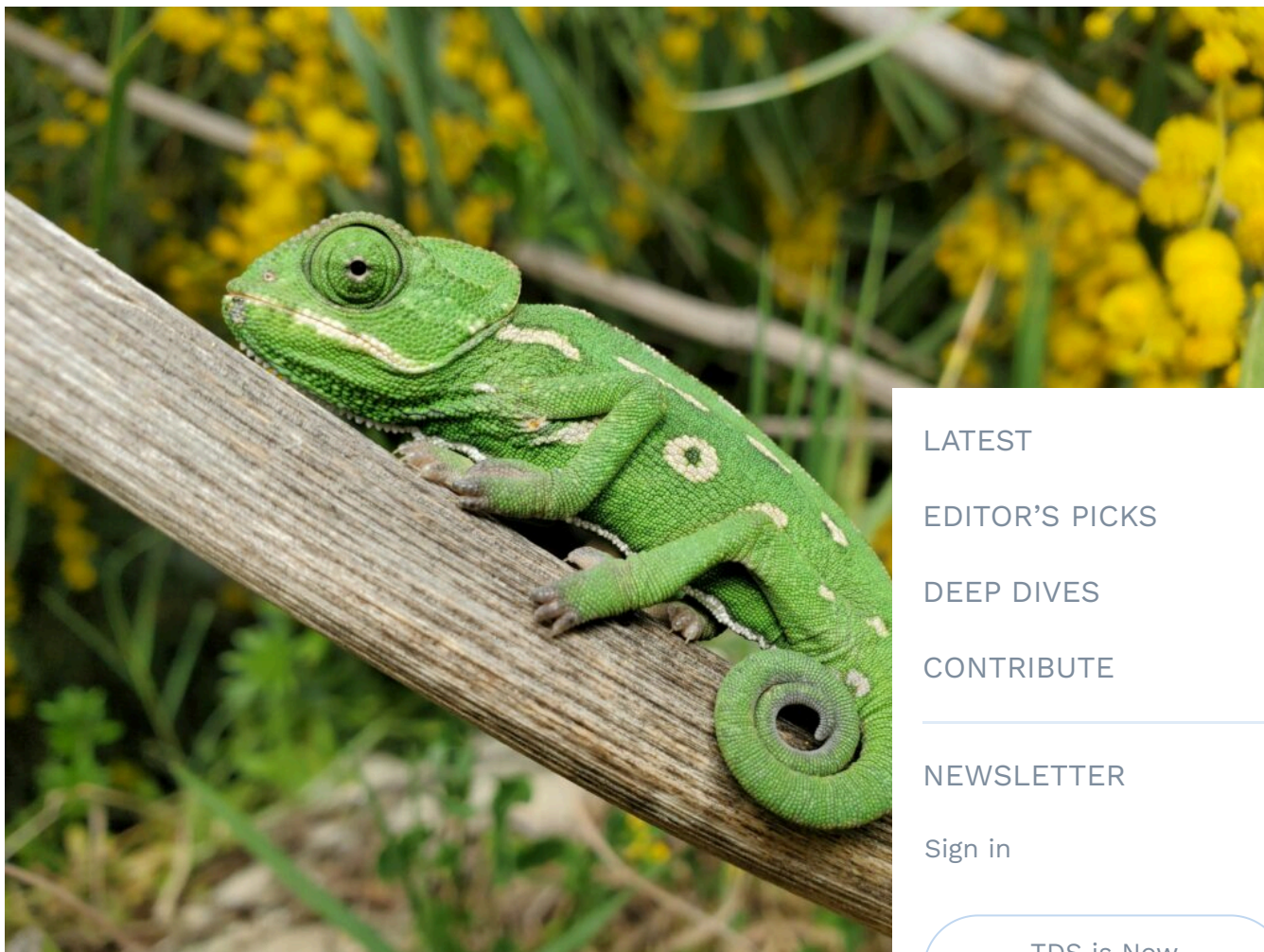
The algorithm of LoRA-drop hence allows to train just a subset of the LoRA layers. The authors provide evidence that indicates only marginal changes in performance compared to training all LoRA layers, but at reduced time due to the smaller number of parameters that are trained.

AdaLoRA

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AdaLoRA allows to adapt the rank of the LoRA matrices dynamically. Photo by [Unsplash](#)

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There are alternative ways how to decide which are more important than others. In this section, **AdaLoRA** [6], which stands for **Adaptive** LoRa. What is adaptive here? It is the rank (i.e. the size) of the LoRA matrices. The rank of the main problem is the same as in the previous section. When adding LoRA matrices A and B to each layer, the LoRA training may be more important (i.e. more change in the model's behavior) than for context. That importance, the authors of AdaLoRA propose to use the singular values of the LoRA matrices as indicators of importance.

What is meant by that? First, we have to understand that matrix multiplication can also be seen as applying a function to the input.

When dealing with neural networks, this is quite obvious: Most of the time you use neural networks as functions, i.e. you give an input (say, a matrix of pixel values) and obtain a result (say, a classification of an image). Under the hood, this function application is powered by a sequence of matrix multiplications. Now, let's say you want to reduce the number of parameters in such a matrix. That will change the function's behavior, but you want it to change as little as possible. One way to do this is to compute the eigenvalues of the matrix, which tell you how much variance is captured by the rows of the matrix. If you decide to set some rows to zero, that captures only a small portion of the variance, and hence don't add much information to the function. This is the main idea of AdaLoRA since the aforementioned singular values are exactly the square roots of the eigenvalues. That is, based on the singular values, you can decide which rows of which LoRA matrices are more important and which can be omitted. This effectively shrinks the rank of the matrix, which have many rows that don't contribute much to the function. An important difference to LoRA-drop from the original LoRA approach, the adapter of a layer is selected to be used fully, or not trained at all. AdaLoRA can also decide to use different adaptors for some layers but with lower rank. This means that, in the end, different adaptors can have different ranks. In the original LoRA approach, all adaptors have the same rank.

There are some more details to the AdaLoRA approach that are omitted for brevity. I want to mention two of them. First, the AdaLoRA approach does not calculate the singular values explicitly all the time (as that would be very costly). Instead, it decomposes the weight matrices with a singular value decomposition. This decomposition is another way to store the same information as in a single matrix, but with the singular values directly, without costly computation.

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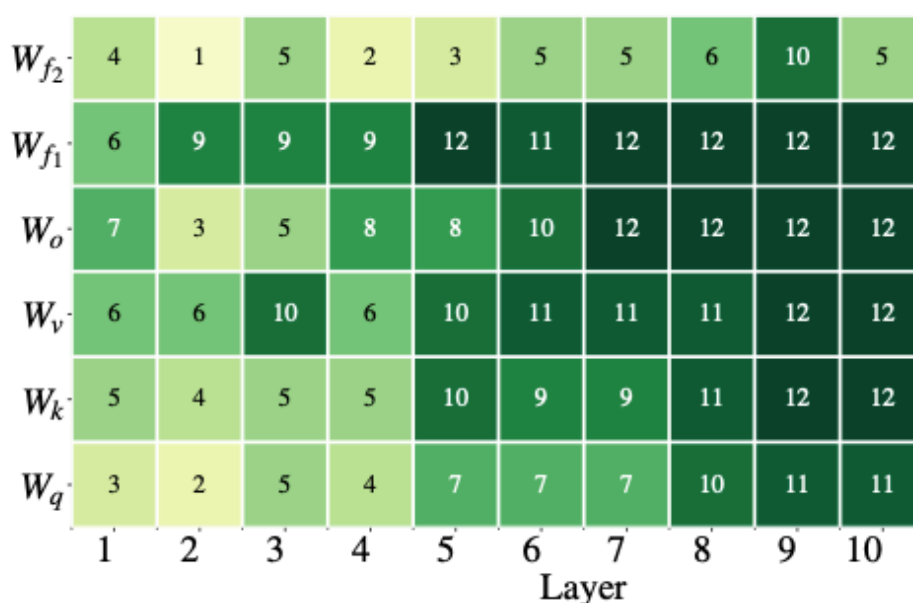


Second, AdaLoRA does not decide on the singular values alone but also takes into account the sensitivity of the loss to certain parameters. If setting a parameter to zero has a large influence on the loss, this parameter is said to have high sensitivity. When deciding where to shrink the rank, the mean sensitivity of a row's elements is taken into consideration in addition to the singular value.

Empirical evidence for the value of the approach is provided by comparing AdaLoRA with standard LoRA of the same size. That is, both approaches have the same number of trainable parameters total, but these are distributed differently. In LoRA, all layers have the same rank, while in AdaLoRA, some layers have a lower rank, which leads to the same number of trainable parameters in the end. In many scenarios, AdaLoRA achieves higher scores than the standard LoRA approach, indicating a more effective distribution of trainable parameters on parts of the model of particular importance for the given task. The following figure is an example, of how AdaLoRA distributed the ranks across the layers of a model. As we see, it gives higher ranks to the later layers of the model, indicating that adapting these

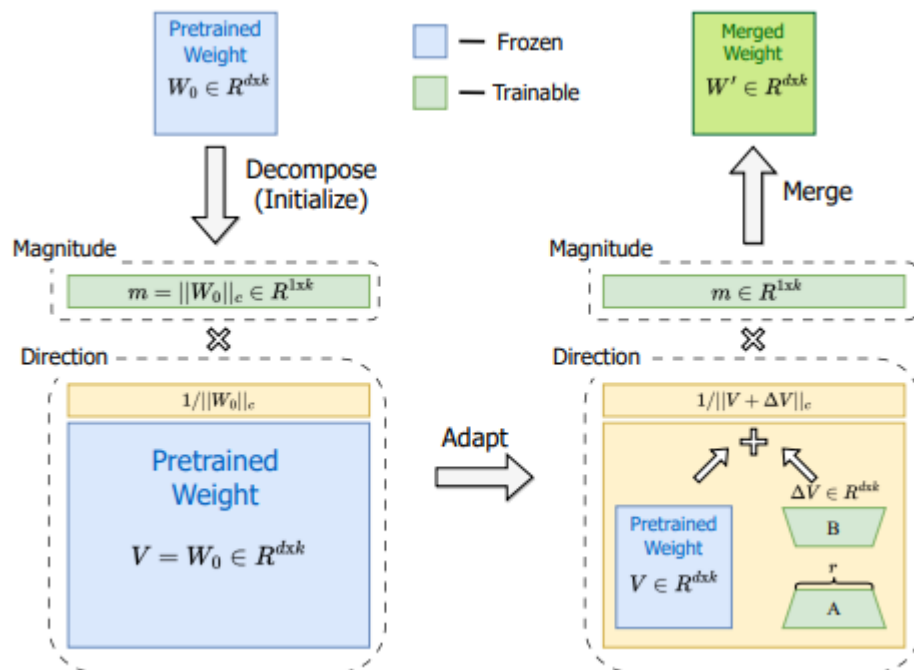
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On different layers of the network, the LoRA matrices are given different rank

DoRA



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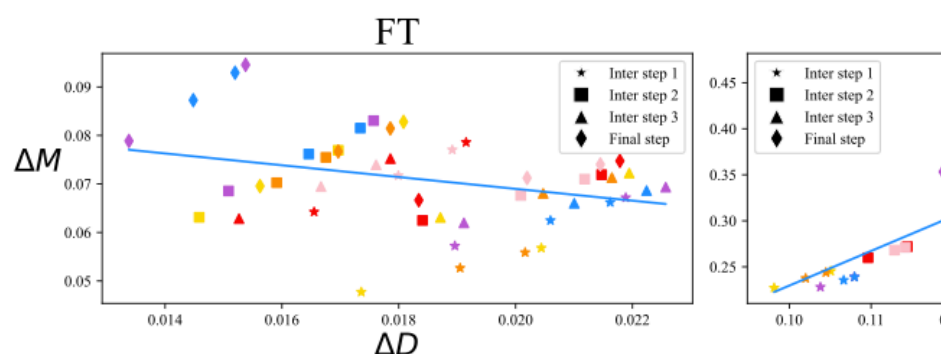
In DoRA, the weight matrix W is decomposed into magnitude m and direction V .
Image from [7].

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Another approach to modify LoRa to get better performance is **DoRA** (Weight-Decomposed Low-Rank Adaption), or **DoRA** with the idea, that each matrix can be decomposed into the product of a magnitude and a direction. For a vector, you can easily visualize that: A vector is nothing more than starting at the position of zero and ending at a point in a vector space. With the vector's entries, you specify the point by saying $x=1$ and $y=1$, if your space has two dimensions. Alternatively, you could describe the very same point the same way by specifying a magnitude and an angle (i.e. polar coordinates) as $m=\sqrt{2}$ and $a=45^\circ$. That means that you start at the origin and move in the direction of 45° with an arrow length of $\sqrt{2}$ to lead you to the same point ($x=1, y=1$).



This decomposition into magnitude and direction can also be done with matrices of higher order. The authors of DoRA apply this to the weight matrices that describe the updates within the training steps for a model trained with normal fine-tuning and a model trained with LoRA adapters. A comparison of these two techniques we see in the following plot:



Finetuning and LoRA differ in the relationship between the changes in magnitude and direction.

We see two plots, one for a fine-tuned model (left) and one for a model trained with LoRA adapters (right). On the x-axis, we see the change in direction, and on the y-axis, we see the change in magnitude. Each scatter point in the plots belongs to a specific training step of a model. There is an important difference between the two training methods. In the left plot (fine-tuning), there is a small negative correlation between the update in direction and the update in magnitude. While in the right plot (LoRA), there is a positive relationship, which is much stronger. You may wonder which is better, but it's hard to say. Remember, the main idea of LoRA is to achieve the same performance as fine-tuning, but with fewer parameters. That means, ideally, we want LoRA to have as many properties with fine-tuning as possible, as long as it doesn't increase the costs. If the correlation between magnitude and direction is slightly negative in fine-tuning, this is a desirable property for LoRA as well, if it is achievable. In conclusion, the relationship between direction and magnitude is a key factor in evaluating the efficiency of different training methods.

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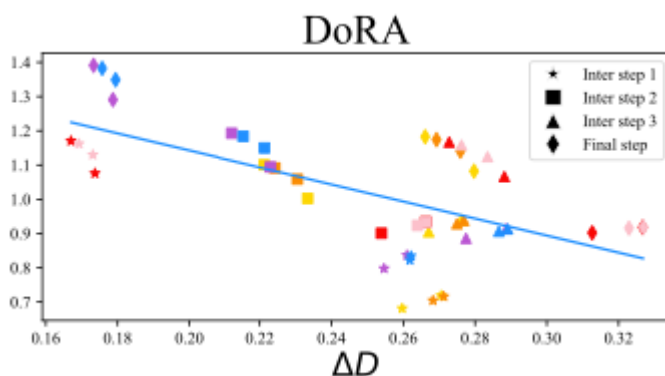
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compared to full fine-tuning, this may be one of the reasons why LoRA sometimes performs less well than fine-tuning.

The authors of DoRA introduce a method to train magnitude and direction independently by separating the pretrained matrix W into a magnitude vector m of size $1 \times d$ and a direction matrix V . The direction matrix V is then enhanced by B^*A , as known from the standard LoRA approach, and m is trained as it because it has just one dimension. While LoRA trains both magnitude and direction together (as indicated by the positive correlation between these two), DoRA can adjust the one without the other, or compensate with negative changes in the other. We can see this from the relationship between direction and magnitude is more like the



For DoRA, the relationship between magnitude and direction is more like the

On several benchmarks, DoRA outperforms LoRA. Decomposing the weight updates into magnitude and direction allow DoRA to perform a training that is closer to full fine-tuning, while still using the smaller parameter budget introduced by LoRA.

Delta-LoRA

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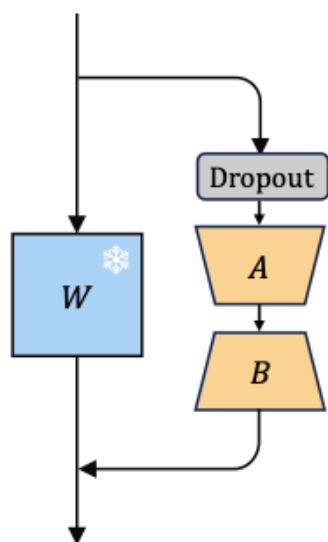
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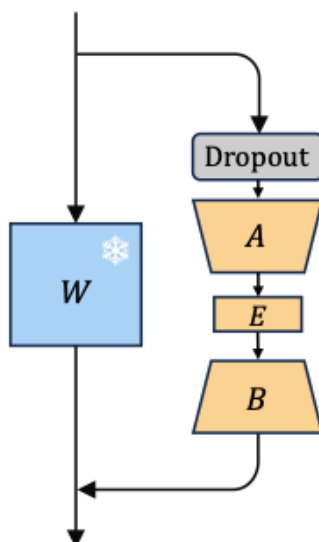
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(a) LoRA/DyLoRA



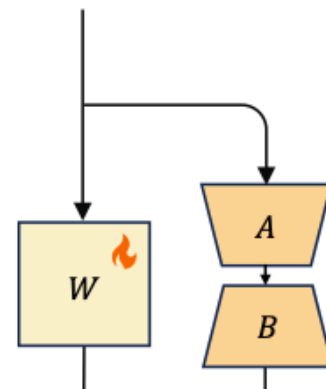
(b) AdaLoRA

Delta-LoRA doesn't freeze the matrix W but updates it with the gradient obtained from the downstream task.

Delta-LoRA [8] **** introduces yet another idea. This time, the pre-trained matrix W comes into play. Remember that the main idea in LoRA is to not fine-tune the pre-trained matrix W , as that is too costly (and that's why we have LoRA). However, those smaller matrices have less parameters and can learn the downstream task, which is why the performance of a LoRA-trained model is often lower than the performance of a fully fine-tuned model. Tuning W during training would be a game-changer if we could afford that?

The authors of Delta-LoRA propose to update the pre-trained matrix W with the gradients of AB , which is the difference between the outputs of A and B at consecutive time steps. This gradient is scaled by a hyperparameter λ , which controls, how big the update should be. In the original LoRA setup, α and r (the rank) are hyperparameters that control the scaling of the update. In the Delta-LoRA setup:

$$\mathbf{W}^{(t+1)} = \mathbf{W}^{(t)} + \lambda \cdot \frac{\alpha}{r} \cdot \Delta \mathbf{AB}, \text{ where } \Delta \mathbf{AB} = \mathbf{A}^{(t)} \mathbf{B}^{(t)} - \mathbf{A}^{(t-1)} \mathbf{B}^{(t-1)}$$



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W is updated with the difference of AB in two consecutive steps. Image from [8].

That introduces more parameters to be trained at almost no computational overhead. We do not have to calculate the gradient for the whole matrix W , as we would within finetuning, but update it with a gradient we already got in the LoRA training anyway. The authors compared this method on a number of benchmarks using models like RoBERTA and GPT-2 and found a boost in performance over the standard LoRA approach.

Summary



Congrats. You've made it to the end. Photo by [david Griffith](#).

We just saw a number of approaches, that vary from the standard LoRA to reduce computation time or improve performance (or both). In the end, I will give a short summary of the different approaches:

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- **LoRA** introduces low-rank matrices A and B that are trained, while the pre-trained weight matrix W is frozen.
- **LoRA+** suggests having a much higher learning rate for B than for A.
- **VeRA** does not train A and B, but initializes them randomly and trains new vectors d and b on top.
- **LoRA-FA** only trains matrix B.
- **LoRA-drop** uses the output of $B \cdot A$ to determine which weights are worth to be trained at all.
- **AdaLoRA** adapts the ranks of A and B in different layers dynamically, allowing for a higher rank in the layers that contribute more to the model's performance.
- **DoRA** splits the LoRA adapter into two components: magnitude and direction and allows to train them independently.
- **Delta-LoRA** changes the weights of W by the output of the adapter.

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The field of research on LoRA and related methods is very vivid, with new contributions every other day. In this article, I wanted to explain the core ideas of some approaches that were only a selection of such, that is far away from a complete review.

I hope that I have been able to share some knowledge that possibly inspire you to new ideas. LoRA and related methods are a field of research with great potential, as we saw in recent breakthroughs in improving performance or reducing training time of large language models can be expected.

References and Further Reading

These are the papers on the concepts explained in this article.



- **[1] LoRA:** Hu, E. J., Shen, Y., Wallis, P., Allen-Zhu, Z., Li, Y., Wang, S., ... & Chen, W. (2021). Lora: Low-rank adaptation of large language models. *arXiv preprint arXiv:2106.09685*.
- **[2] LoRA+:** Hayou, S., Ghosh, N., & Yu, B. (2024). LoRA+: Efficient Low Rank Adaptation of Large Models. *arXiv preprint arXiv:2402.12354*.
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- **[4]: LoRA-FA:** Zhang, L., Zhang, L., Shi, S., C (2023). Lora-fa: Memory-efficient low-rank : language models fine-tuning. *arXiv preprint*
- **[5] LoRA-drop:** Zhou, H., Lu, X., Xu, W., Zhu, (2024). LoRA-drop: Efficient LoRA Paramete Output Evaluation. *arXiv preprint arXiv:2402.*
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- **[7] DoRA:** Liu, S. Y., Wang, C. Y., Yin, H., Molcl F., Cheng, K. T., & Chen, M. H. (2024). DoRA: Decomposed Low-Rank Adaptation. *arXiv pr arXiv:2402.09353*.
- **[8]: Delta-LoRA:** Zi, B., Qi, X., Wang, L., Wang Zhang, L. (2023). Delta-lora: Fine-tuning hig with the delta of low-rank matrices. *arXiv pr arXiv:2309.02411*.

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For some core ideas on random projection, as n section on VeRA, this is one of the major contrik

- Frankle, J., & Carbin, M. (2018). The lottery ti Finding sparse, trainable neural networks. *arXiv:1803.03635*.

For a more fine-grained explanation of LoRA and DoRA, I can recommend this article:

- <https://magazine.sebastianraschka.com/p/lora-and-dora-from-scratch>

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