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Parcial 1.

A. Determinar la distancia entre las dos señales

$$d^2(X_1, X_2) = \bar{P}_{X_1 - X_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |X_1(t) - X_2(t)|^2 dt$$

$$X_1(t) = A e^{j\omega_0 t}$$

$$X_2(t) = B e^{j5\omega_0 t}$$

$$\begin{aligned} \bar{P}_{X_1 - X_2} &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |X_1(t) - X_2(t)|^2 dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_T (X_1(t) - X_2(t)) (X_1(t) - X_2(t))^* dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_T (X_1(t) - X_2(t)) (X_1(t)^* - X_2(t)^*) dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_T X_1(t) X_1(t)^* - X_1(t) X_2(t)^* - X_1(t)^* X_2(t) + X_2(t) X_2(t)^* dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |X_1(t)|^2 dt - 2 \int_T X_1(t) X_2(t)^* dt + \int_T |X_2(t)|^2 dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \left(\underbrace{\int_T |X_1(t)|^2 dt}_{(1)} - 2 \underbrace{\int_T X_1(t) X_2(t)^* dt}_{(2)} + \underbrace{\int_T |X_2(t)|^2 dt}_{(3)} \right) \end{aligned}$$

$$\begin{aligned} (1) \quad \int_0^T |X_1(t)|^2 dt &= \int_0^T |A e^{j\omega_0 t}|^2 dt = \int_0^T |A|^2 |e^{j\omega_0 t}|^2 dt \\ &= A^2 \int_0^T (e^{j\omega_0 t} \cdot e^{-j\omega_0 t}) dt \\ &= A^2 \int_0^T e^0 dt \\ &= A^2 \int_0^T 1 dt \\ &= A^2 (T - 0) = A^2 T \end{aligned}$$

$$\begin{aligned} (3) \quad \int_T |X_2(t)|^2 dt &= \int_0^T |B e^{j5\omega_0 t}|^2 dt \\ &= \int_0^T |B|^2 |e^{j5\omega_0 t}|^2 dt \\ &= B^2 \int_0^T (e^{j5\omega_0 t} \cdot e^{-j5\omega_0 t}) dt \\ &= B^2 \int_0^T e^0 dt \\ &= B^2 \int_0^T 1 dt \\ &= B^2 (T - 0) \\ &= B^2 T \end{aligned}$$

$$\begin{aligned} (2) \quad 2 \int_T X_1(t) X_2(t)^* dt &= 2 \int_0^T X_1(t)^* X_2(t) dt \\ &= 2 \int_0^T A e^{-j\omega_0 t} B e^{j5\omega_0 t} dt \\ &= 2AB \int_0^T e^{j4\omega_0 t} dt \\ &= \frac{2AB}{j4\omega_0} \int_0^T e^u du \\ &= \frac{2AB}{j4\omega_0} e^u \Big|_0^T \\ &= \frac{2AB}{j4\omega_0} (e^{j4\omega_0 T} - e^{j4\omega_0 \cdot 0}) \\ &= \frac{2AB}{j4\omega_0} (e^{j4\omega_0 T} - 1) \\ &= \frac{2AB}{j4\omega_0} (\cos(8\pi) + j\sin(8\pi) - 1) \\ &= \frac{2AB}{j4\omega_0} (1 + 0 - 1) \\ &= \frac{2AB}{j4\omega_0} (0) \\ &= 0 \end{aligned}$$

$$\begin{aligned} u &= j4\omega_0 t \\ du &= j4\omega_0 dt \\ dt &= \frac{du}{j4\omega_0} \end{aligned}$$

Entonces:

$$\begin{aligned} &= \lim_{T \rightarrow \infty} \frac{1}{T} (A^2 T - 0 + B^2 T) \\ &= \lim_{T \rightarrow \infty} A^2 - 0 + B^2 \\ &= A^2 + B^2 \end{aligned}$$

$$B. \quad X(t) = 3 \cos 1000 \pi t + 5 \sin 2000 \pi t + 10 \cos 11000 \pi t$$

$$F_s = 5 \text{ KHz}$$

$$\omega_1 = 1000 \pi \quad \therefore \quad F_1 = \frac{1000 \pi}{2 \pi} = 500$$

$$\omega_2 = 2000 \pi \quad \therefore \quad F_2 = \frac{2000 \pi}{2 \pi} = 1000$$

$$\omega_3 = 11000 \pi \quad \therefore \quad F_3 = \frac{11000 \pi}{2 \pi} = 5500 \quad \text{No cumple Nyquist}$$

Como no cumple Nyquist, no es apropiado $F_s = 5000 \text{ Hz}$, entonces usamos $F_s > 2F_{\max}$

$$\text{Usamos } F_s = 12000 \text{ Hz}$$

Entonces

$$\text{Discretizamos } t = n T_s = \frac{n}{F_s}$$

Con la nueva F_s

$$X(t) = 3 \cos \frac{1000 \pi}{12000} t + 5 \sin \frac{2000 \pi}{12000} t + 10 \cos \frac{11000 \pi}{12000} t$$

$$= 3 \cos \frac{1}{12} \pi t + 5 \sin \frac{1}{6} \pi t + 10 \cos \frac{11}{12} \pi t$$

$$= 3 \cos \frac{\pi}{12} n + 5 \sin \frac{\pi}{6} n + 10 \cos \frac{11}{12} \pi n$$

$$\omega_1 = \frac{\pi}{12} ; \omega_2 = \frac{\pi}{6} ; \omega_3 = \frac{11}{12} \pi$$

$$X[n] = 3 \cos \frac{\pi}{12} n + 5 \sin \frac{\pi}{6} n + 10 \cos \frac{11}{12} \pi n$$