

Updating QR Factorization Under Sparse Updates.

James Fairbanks¹ Domenic Carr²

¹School of CSE

²School of ECE

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Overview

- In a least squares problem, the data might change. If the change occurs in a sparse way the QR decomposition can be updated faster than recomputation.
- First goal: Present a method that leverages the specialized structure of the update to accelerate QR computation
- Second goal: Experimentally determine the crossover point for different m , n , k values at which recomputation is faster than specialized updating.

Updating Algorithms

The total number of fill-in entries eliminated is

$$Lazy = \sum_{j=1}^k \sum_{t=1}^j (i_{j+1} - i_j - t) = \sum_{j=1}^k j(i_{j+1} - i_j - \frac{j+1}{2})$$

This is called the lazy elimination strategy because we defer elimination of fill-in entries until the last possible moment.

The eager strategy eliminates fill-in as soon as it is created. The total number of fill-in entries removed is

$$Eager = \sum_{j=1}^k j(n - i_j) = n \sum_{j=1}^k j - \sum_{j=1}^k j i_j = \frac{nk(k+1)}{2} - \sum_{j=1}^k j i_j$$

Both methods must eliminate the original nonzeros which are counted by $\sum_{j=1}^k n - i_j$.

Crossover Theory

For a fixed m large enough, the Householder based methods are cubic in n and the sparse updating methods are quadratic in n because we need to accumulate Q . Thus making this simplification we can model the performance ratio as

$$r_e(m, n, k) = \frac{C_m n^3}{n^2 k} = \frac{Cn}{k} \quad (1)$$

The relationship between m and n is accounted for in the dependence of C_m on m . When $r_e = 1$ the two methods will take the same amount of time, and the k for which this occurs is called the break even point.

Results

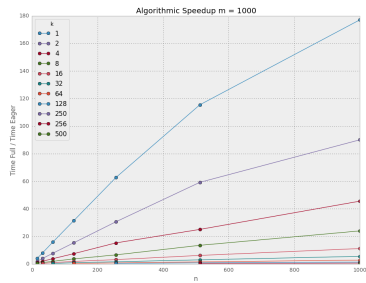
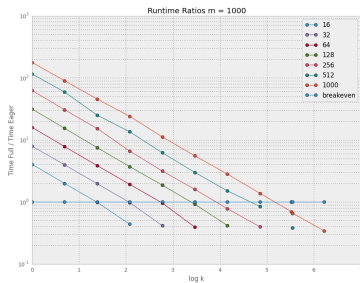


Figure: r_e as a function of k (left) and as a function of n (right)