



# Alignment of the DT chambers

Jim Pivarski

Alexei Safonov

*Texas A&M University*

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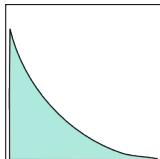
- ▶ We present alignment constants for the DT chambers, reducing misalignment from the 5–10 mm level down to the 1–2 mm level
  - ▶ links DT chambers to the tracker's coordinate system using globalMuons
  - ▶ compatible with the latest tracker description (geometry, APEs, Lorentz-angle), TIB and TOB only (best-aligned part)
  - ▶ this is an update to the CRAFT\_ALL\_V4 muon geometry description, updating only those chambers with adequate statistics, keeping previously-aligned layer and superlayer substructure
- ▶ Understanding of systematic effects
  - ▶ control of errors from  $\vec{B}$ -field mismodelling
  - ▶ for other systematic effects, see DT-DPG presentation  
<http://indico.cern.ch/conferenceDisplay.py?confId=51267>
- ▶ Validation plots: see DT-DPG “more information” for every chamber
  - ▶ a few examples shown here



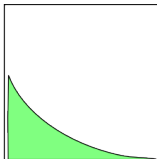
1. Refit globalMuons tracks with zero weight on the muon hits, so that the tracks are determined entirely by the tracker, yet contain muon hits
  - ▶ automatically in tracker's coordinate system
  - ▶ no coupling between track-fitting and alignment: convergence in one iteration (two performed)
2. Find the peak of the residuals distribution, note offset from zero
  - ▶ weighted-average 1-D hits in the same chamber on the same track, to properly account for their correlation
3. Apply corrections to move residuals to zero
  - ▶ DT local  $x$  (global  $r\phi$ ) coordinate: offset of local  $x$  residuals
  - ▶ DT local  $y$  (global  $z$ ) coordinate: offset of local  $y$  residuals
  - ▶ DT local  $\phi_z$  (rotation in layer's plane): slope in local  $x$  versus local  $y$
4. Follow-up with detailed validation plots



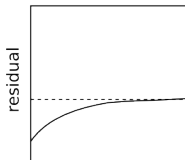
- ▶ Magnetic field is not properly described in reconstruction
- ▶ Track propagation is sensitive to integral of  $\vec{B}$ -field error along its path
- ▶ How can we get reliable residuals?



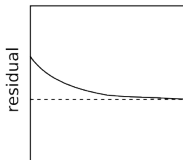
momentum spectrum  
of positively-charged tracks



momentum spectrum  
of negatively-charged tracks



momentum of  
positively-charged tracks

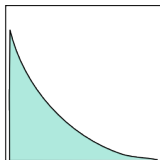


momentum of  
positively-charged tracks

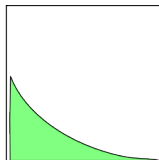
- ▶ Number of positively-charged and negatively-charged muons is not equal, but the momentum spectra are identical (fact used in charge ratio analysis)
- ▶ Small deviations of reconstructed track from average muon trajectory is antisymmetric with charge

# Effect of $\vec{B}$ -field mismodelling

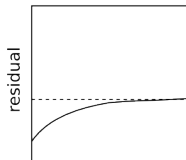
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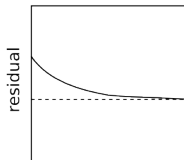
momentum spectrum  
of positively-charged tracks



momentum spectrum  
of negatively-charged tracks



momentum of  
positively-charged tracks



momentum of  
positively-charged tracks

- ▶ Measure residuals peak in two bins, one for each charge
- ▶ Non-weighted average is insensitive to  $\vec{B}$ -field errors

$$\text{alignment} = \frac{R_+ + R_-}{2}$$

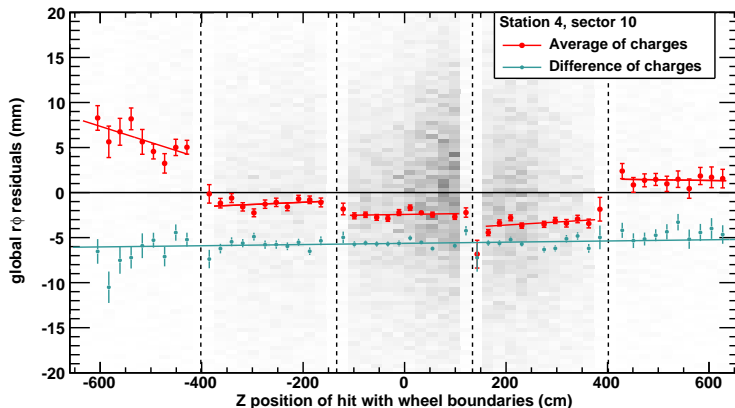
- ▶ Difference is maximally sensitive

$$\text{error tracer} = \frac{R_+ - R_-}{2}$$

- ▶ Effectively scales up negatively-charged muon statistics such that the two curves cancel
- ▶ Systematic error = (error tracer)  $\times$  (charge mismeasurement)  $\times \frac{0.3}{2.3}$   
 $\sim$  (error tracer)  $\times$  (a few percent or less)



- Demonstration in station 4 (largest  $\vec{B}$ -field errors):
  - despite large  $(R_+ - R_-)/2$  difference (“error tracer”),  
the  $(R_+ + R_-)/2$  average cleanly breaks at chamber boundaries

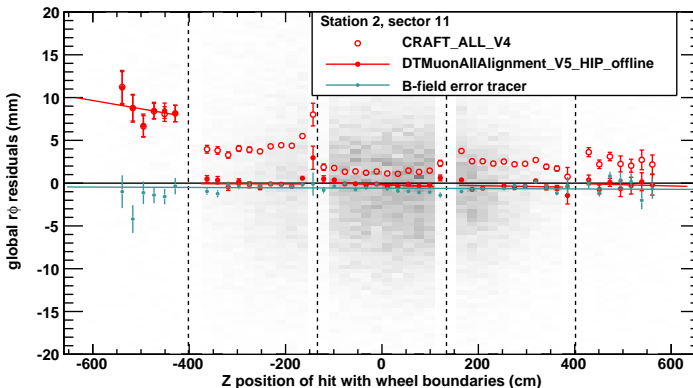


grey background is the raw 2-D residuals distribution

linear fits are only a guide for the eye: not used in alignment!



- ▶ Plot residuals with more detail than the alignable level
  - ▶ dataset is divided such that you're only ever looking at one chamber at a time
  - ▶ grey background is the raw 2-D residuals distribution
  - ▶ linear fits are only a guide for the eye, not used in alignment
  - ▶ example of unaligned chamber: wheel -2, station 2, sector 11
  - ▶ see DT-DPG Indico page “more information” for 152 pages

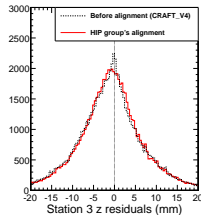
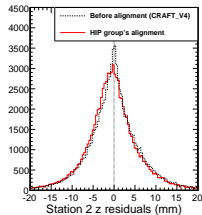
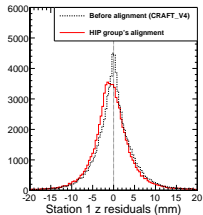
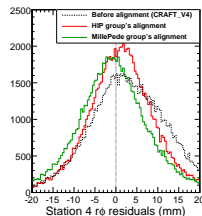
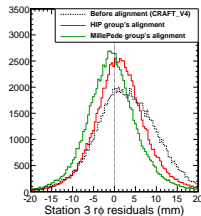
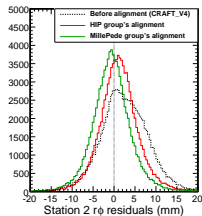
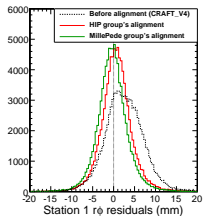


# Summary of residuals

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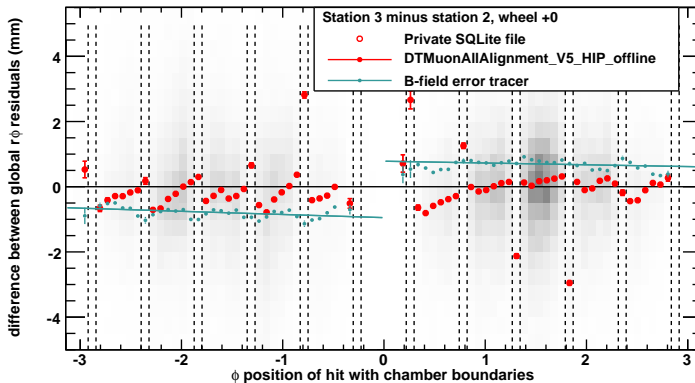
- ▶ To summarize, project all residuals ( $p_T > 80$  GeV, all chambers)
  - ▶ like the tracker's  $\chi^2/N_{\text{dof}}$  plot, but unweighted
  - ▶ less sensitive measure of alignment, but convenient
- ▶ Residuals in plots are calculated the same way as residuals in alignment





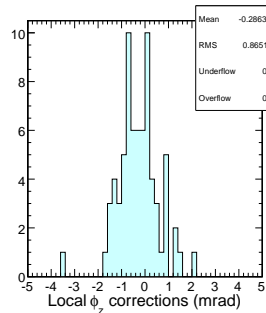
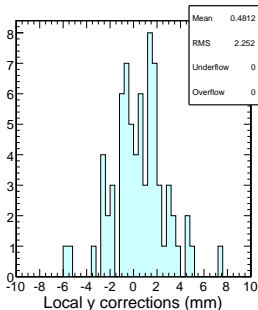
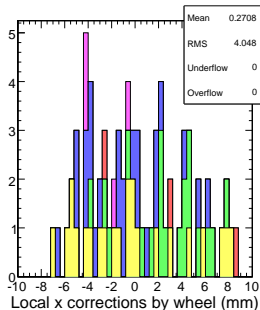


- ▶ Linearly-independent test: residuals differences between pairs of stations  
difference = (st. 3 track – st. 3 hit) – (st. 2 track – st. 2 hit)
  - ▶ shows *relative* positions of chambers; globalMuon is just a ruler
  - ▶ therefore, this is a real consistency check
  - ▶ note zoomed vertical scale: accuracy is 1–2 mm
  - ▶ also shows  $\vec{B}$ -field error between the stations, not integrated



# Values of the corrections

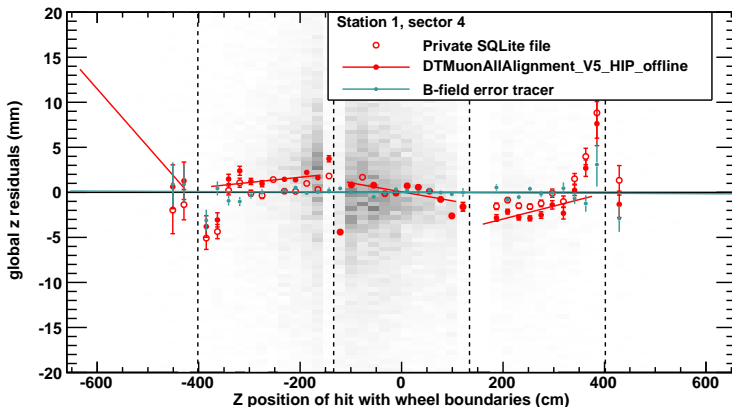
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- ▶ 5–10 mm changes in  $r\phi$  positions, and they don't correspond to an overall rotation of the wheels
- ▶ A scan of residuals differences plots suggests that remaining misalignment is on the order of 1–2 mm



- Constants were successfully uploaded to the database, but an additional  $2 \text{ mm} \times \text{wheel number}$  was applied to the  $z$  positions
  - track residuals do not prefer this additional translation
  - but  $z$  residuals still have other effects on the same order, so the resolution is about  $2 \text{ mm}$  anyway
  - see Muon Alignment Hypernews for full SQLite-DB comparison





- ▶ New DT chamber alignment, in the same coordinate system as the tracker, reduces misalignment from the 5–10 mm level down to the 1–2 mm level
- ▶ Covers mostly wheels  $-1$ ,  $0$ , and  $+1$  (wherever statistics was sufficient)
- ▶ Controls for systematics, not a blind minimization of residuals
  - ▶ see DT-DPG for more
- ▶ Constants are in the database, but with an extra  $z$  translation that worsens the average  $z$  residual