

## Magnetic Field from a Muon Alignment Perspective

Jim Pivarski

Alexei Safonov

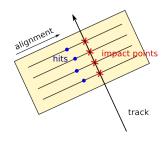
Texas A&M University

2 February, 2009



- ▶ The alignment of the muon chambers and the distribution of magnetic field are both imperfectly known
- Both cause deviations in muon trajectories with respect to tracks propagated from the tracker
- How can they be distinguished?
  - residuals from misalignment are independent of track momentum and charge
  - $\triangleright$  residuals from  $\vec{B}$ -field mismodelling depends on momentum and is antisymmetric with charge
- This talk will be about exploiting the above to
  - align the DT chambers
  - ightharpoonup verify  $\vec{B}$ -field error calculations using techniques developed for alignment





#### HIP algorithm: "Hits and Impact Points"

- Using a track as reference, alignment correction is the peak of the residuals distribution
- ightharpoonup Our residual  $\equiv$  (impact point) (hit)

Implementation is not exactly the same as that in the tracker

- ▶ Muon hits excluded from refitted tracks: tracker is external reference
  - ▶ breaks the circularity between fitting tracks and aligning chambers
  - no need to iterate: convergence in one step
- Muon chambers are much bigger than silicon wafers: study residuals as a function of position throughout each chamber

### Effect of $\vec{B}$ -field on residuals

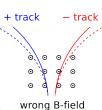
Jim Pivarski

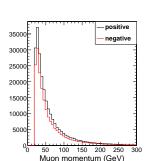


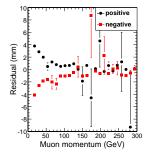


► Track propagation is sensitive to the integral of  $\vec{B}$ -field error along its path

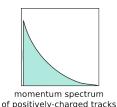
- ▶ Effect on residuals flips sign with charge
- The number of positively-charged tracks is not equal to the number of negatively-charged tracks
- ▶ But both charges have the same momentum distribution (a fact used in the cosmics charge ratio analysis)

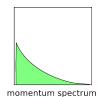




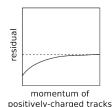


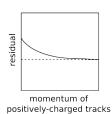






of negatively-charged tracks





- Measure residuals peak in two bins, one for each charge
- Non-weighted average is insensitive to  $\vec{B}$ -field errors

$$\mathsf{alignment} = \frac{R_+ + R_-}{2}$$

▶ Difference is maximally sensitive

error tracer = 
$$\frac{R_+ - R_-}{2}$$

- ▶ Alignment calculation effectively scales up negatively-charged muon contribution so that the  $\vec{B}$ -field errors cancel
- Systematic error = (error tracer) × (charge mismeasurement) ×  $\frac{0.3}{2.3}$  $\sim$  (error tracer)  $\times$  (a few percent or less)

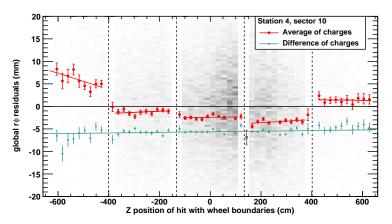
#### Demonstration in station 4

Jim Pivarski





- ▶ Station 4 has the largest  $\vec{B}$ -field mismodelling
- $\,\blacktriangleright\,$  The misalignment measure breaks cleanly at the chamber boundaries
- ▶ The tracer of  $\vec{B}$ -field errors is constant



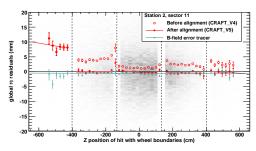
grey background is the raw 2-D residuals distribution linear fits are only a guide for the eye: not used in alignment!

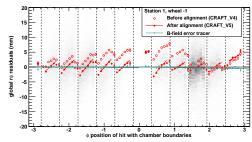


- ➤ Sample before-and-after residuals plots from alignment shown at right
- Complete set of 152 pages at last DT-DPG ("more information")

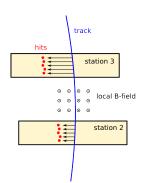
http://indico.cern.ch/ conferenceDisplay.py?confId=51267

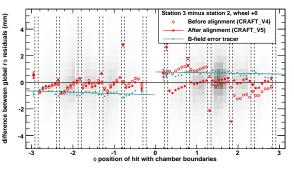
- ▶ Aligned local x, y,  $\phi_z$  for DT chambers with sufficient statistics
- ▶ Trend in  $r\phi$  residual vs.  $\phi$  suggests DT chamber description error (under investigation)
- ▶ 5–10 mm misalignments reduced to  $\mathcal{O}(1$ –2 mm)









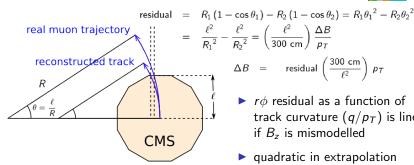


- ► Consider difference of residuals between stations on the same track: difference = (st. 3 track st. 3 hit) (st. 2 track st. 2 hit)
- Linearly-independent cross-check on alignment because it displays relative alignment of chambers, rather than absolute position
- lacktriangle Also sensitive to local  $\vec{B}$ -field error, rather than integral over path
  - $\,\blacktriangleright\,$  wrong sign in  $\phi>0$  part because cosmic muon's velocity is down

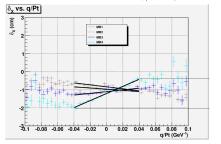
### Calculating $B_7$ error in Tesla Jim Pivarski

9/14





P. Martinez:  $r\phi$  residual vs.  $q/p_T$  by station



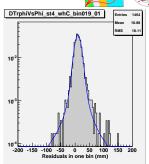
- $\Delta B = \operatorname{residual}\left(\frac{300 \text{ cm}}{\ell^2}\right) p_T$
- $ightharpoonup r\phi$  residual as a function of track curvature  $(q/p_T)$  is linear if  $B_z$  is mismodelled
- quadratic in extrapolation length  $(\ell)$
- charge confusion with charge ratio  $\neq 1$  distorts linear dependence at small  $|q/p_T|$  if extrapolation length is large
  - use residuals differences
- scattering distorts linear dependence at large  $|q/p_T|$

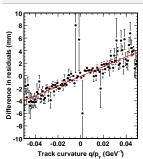


- Scattering processes have power-law distributions, while experimental resolution is Gaussian
- "Peak" of residuals distribution used in alignment comes from an unbinned fit to Lorentzian-Gaussian convolution

$$f(x) = \int_{-\infty}^{\infty} \frac{1}{\pi} \frac{\Gamma/2}{(x-\xi)^2 + (\Gamma/2)^2} \times \frac{1}{\sqrt{2\pi}\sigma} \exp\left(\frac{-\xi^2}{2\sigma^2}\right) d\xi$$

- ▶ Regular mean  $(\sum x_i/N)$  = center of an unbinned Gaussian fit; this just adds tails
  - outliers matter less in peak-finding
- $\triangleright$  For  $B_z$  measurement, make peak a linear function of  $q/p_T$  (red is crest of 2-D fit)



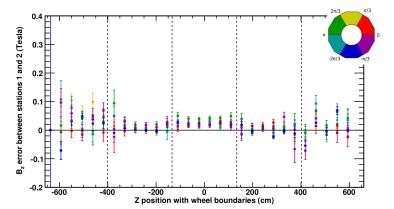


### $B_z$ error between stations 1&2





- ightharpoonup Points calculated from unbinned 2-D fits to  $r\phi$  residuals and q/pT
- lacktriangle Assumptions:  $B_x=B_y=0$ , uniform  $B_z$  between stations, no dE/dx error
- lacktriangle Shown as a function of  $\phi$ , z (same magnitude as combined fit)
  - ▶ largest  $B_z$  errors seem to be 8% between stations 3&4 (dataset is all 3.8 T: 66604-66904, 67126-67225, 67534-67647, 67680-68087)
  - ▶ slight wheel-by-wheel dependence? or dE/dx error?

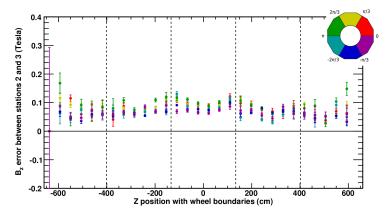


## $B_z$ error between stations 2&3

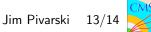




- ▶ Points calculated from unbinned 2-D fits to  $r\phi$  residuals and q/pT
- lacktriangle Assumptions:  $B_x=B_y=0$ , uniform  $B_z$  between stations, no dE/dx error
- lacktriangle Shown as a function of  $\phi$ , z (same magnitude as combined fit)
  - ▶ largest  $B_z$  errors seem to be 8% between stations 3&4 (dataset is all 3.8 T: 66604-66904, 67126-67225, 67534-67647, 67680-68087)
  - ▶ slight wheel-by-wheel dependence? or dE/dx error?

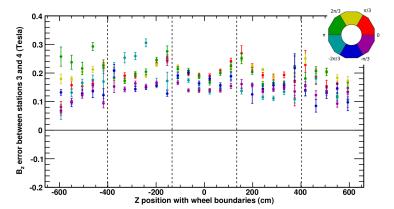


# $B_z$ error between stations 3&4





- ightharpoonup Points calculated from unbinned 2-D fits to  $r\phi$  residuals and q/pT
- Assumptions:  $B_x = B_y = 0$ , uniform  $B_z$  between stations, no dE/dx error
  - lacktriangle Shown as a function of  $\phi$ , z (same magnitude as combined fit)
    - ▶ largest  $B_z$  errors seem to be 8% between stations 3&4 (dataset is all 3.8 T: 66604-66904, 67126-67225, 67534-67647, 67680-68087)
    - ▶ slight wheel-by-wheel dependence? or dE/dx error?





- ightharpoonup Misalignments and  $\vec{B}$ -field errors can be disentangled
- $\triangleright$  Alignment validation plots quantify systematic error from  $\vec{B}$ -field (times a large factor) in millimeters
- ightharpoonup Residuals differences localize  $\vec{B}$  error between stations, rather than integrated along the whole track
- $\triangleright$   $B_7$  error in Tesla can be calculated from linear dependence in  $r\phi$ residuals vs.  $q/p_T$
- ▶ Largest  $B_z$  errors seem to be only 8% of 3.8 T