

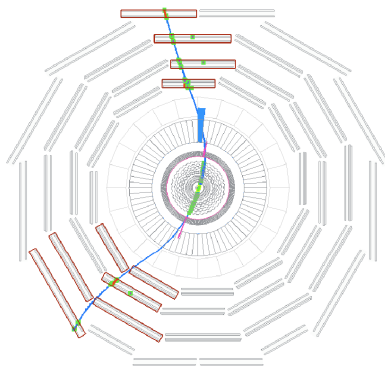


# Toward Precision Muon Tracking: Understanding the CMS Magnetic Field and Other Effects in CRAFT

Jim Pivarski

*Texas A&M University*

6 February, 2009



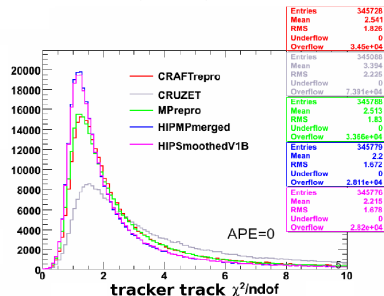
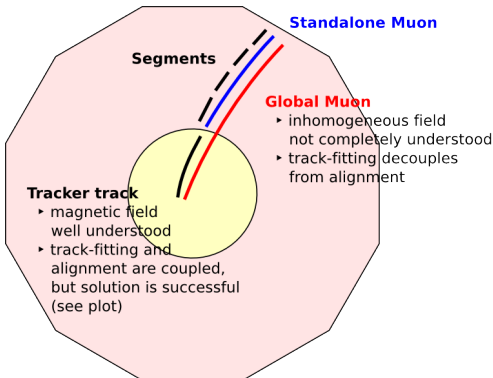
- ▶ We've all seen event displays, so we know that tracking basically works
- ▶ Now we need to use the millions of cosmic rays to test and correct tracking with high precision

# Muon tracking

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Tracker alignment group: J. Dröger, R. Castello, G. Flucke, A. Gritsan, E. Migliore, M. Musich, A. Bonato, N. Tran, M. Weber et al.



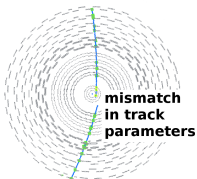
- Precision generally proceeds from the tracker outward
  - successful tracker alignment provides a good platform from which to resolve unknown  $\vec{B}(\vec{x})$  in the muon system
- But also from local chamber segments outward
- In both cases, the reference has a uniform magnetic field. . .

# Indication of a problem

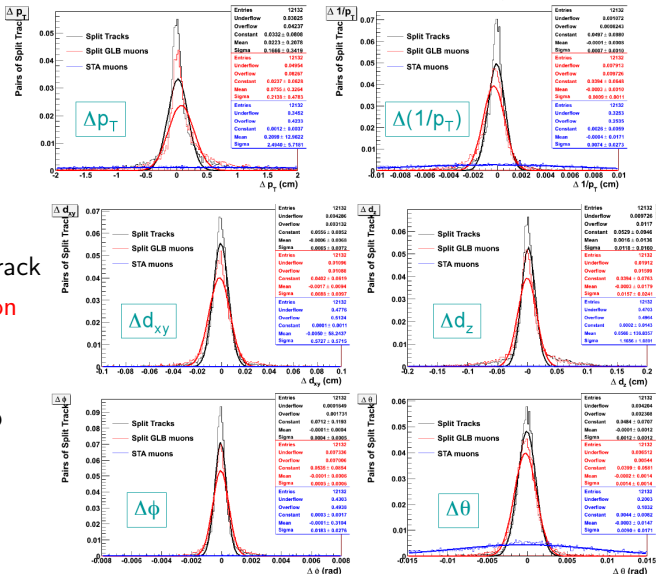
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Nhan Tran, Alessio Bonato



- Black: tracker track
- Red: global muon
- Adding muon hits is not expected to help low-momentum tracks much, but it shouldn't hurt!

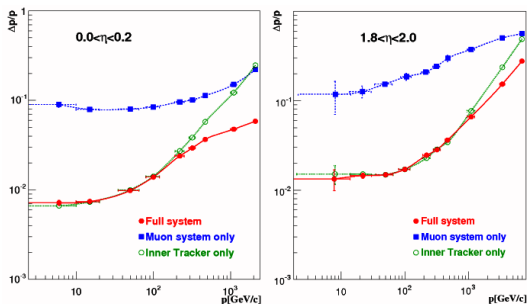


# Why is this important?

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- ▶ Why not use
  - ▶ tracker for high-precision tracking
  - ▶ muon system for particle-id?
- ▶ **Answer:** because we care about high-momentum muons!



Physics TDR

- ▶ Solving muon tracking issues could make the difference between discovering  $Z' \rightarrow \mu\mu$  in 2009/2010 and not having a significant peak
- ▶ Heavy Stable Charged Particle searches also depend on good muon tracking for completely different reasons



- ▶ **Magnetic field map**
  - ▶ exact shape of  $\vec{B}(\vec{x})$  is difficult to model and depends on CMS's environment
- ▶ **Alignment**
  - ▶ for the chambers' intrinsic resolution to be useful, their positions must be known with at least equal precision
- ▶ **Material budget**
  - ▶  $dE/dx$  corrections are smaller, especially for high-momentum
  - ▶ treat as negligible for now
- ▶ **Calibration**
  - ▶ can be solved independently of global tracking issues

## Outline for this talk

1. What  $\vec{B}$ -field errors do to tracks
2. Aligning the muon system with an imperfectly-known field
3. Measuring the field corrections with an imperfectly-known alignment



## ...inside the solenoid

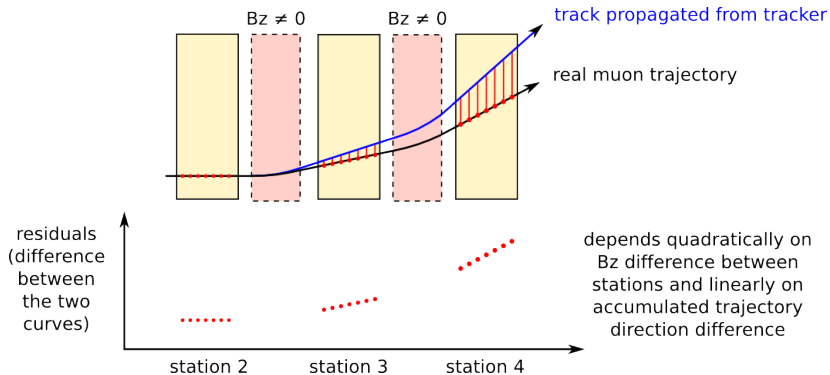
- ▶ Magnetic field mapper, NMR probes's 2006 and 2008 data, and simulation all agree at the 0.1% level

## ...in the far reaches of the muon system

- ▶ Flux-loop measurements disagree with simulation as much as 20% (2006 and 2008)
- ▶ Forces on CASTOR were larger than expected
- ▶ Evidence of  $B_z$  errors in CRAFT tracks
- ▶ Evidence of  $B_r$  errors in CRAFT DT calibration

# Effect of $B_z$ errors on residuals

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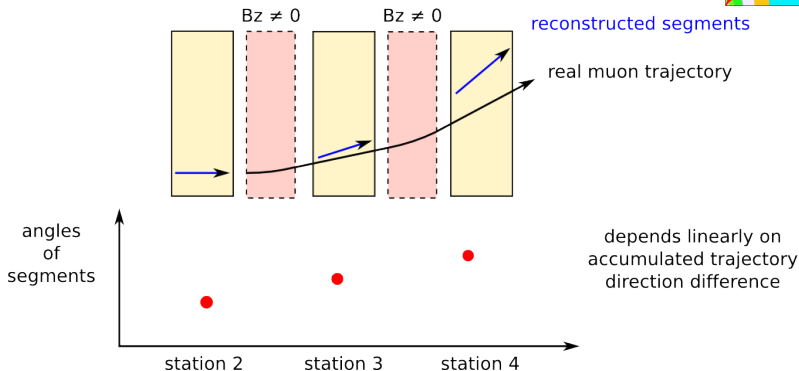


- ▶ Gap between propagated track and real muon grows quadratically in yoke when  $B_z$  is wrong
- ▶ Gap grows linearly elsewhere, dependent on history  
(This is like a Physics I displacement problem with regions of acceleration)



# Effect of $B_z$ errors on segments

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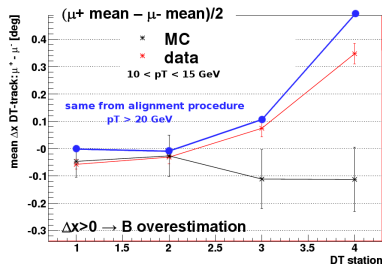
- ▶ Trajectory angle grows linearly in yoke when  $B_z$  is wrong  
(This is like a Physics I velocity problem with regions of acceleration)
- ▶ Difference in segment angles on the same track provides a direct measurement of  $B_z$  error
- ▶ Residuals method can provide a cross-check

# What do we observe?

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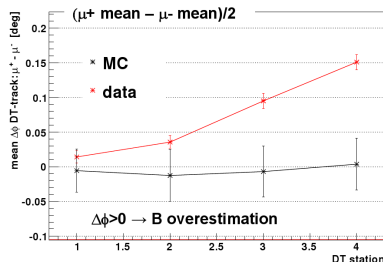


## Residuals



Sara Bolognesi, blue points: Jim Pivarski

## Segment angles



Sara Bolognesi

- ▶ Plots show integrated effect from tracker to each station
- ▶ Also shown to be  $\phi$  and  $z$  symmetric within each station
- ▶ Real magnetic field is *smaller* than what is used in the simulation

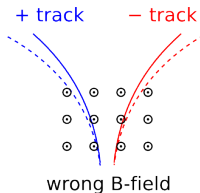
# $B_z$ error and alignment

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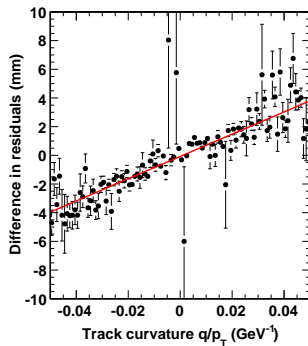
- ▶ Residuals from  $B_z$  error are as large as 5 mm
- ▶ Residuals from chamber misalignment were 5–10 mm
- ▶ How can we disentangle them?



- ▶ magnetic field effect depends on momentum and is antisymmetric with charge

$$\text{residual} = (q/p_T) \frac{\ell^2}{600 \text{ cm}} \Delta B$$

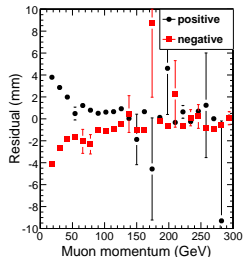
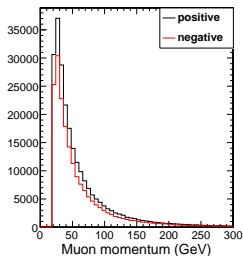
- ▶ misalignment effect is independent of momentum
- ▶ Residuals versus curvature ( $q/p_T$ ):
  - ▶  $B_z$  error introduces slope
  - ▶ misalignment is the value at infinite momentum ( $q/p_T \rightarrow 0$ )



# Measuring alignment

(magnetic field is a controlled systematic error)

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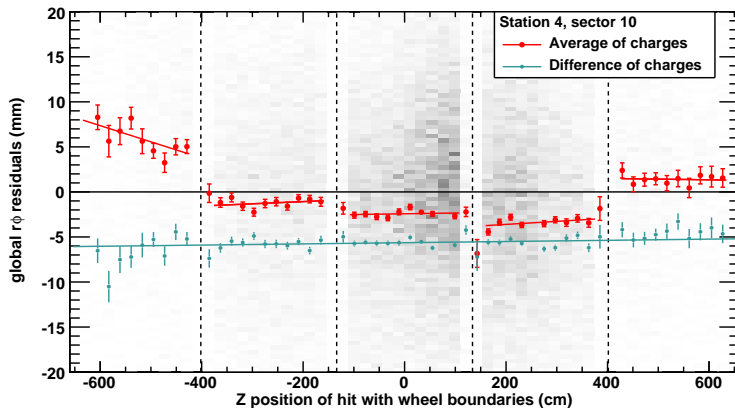
**Fact:** Momentum spectra for positively-charged and negatively-charged cosmic rays are equal, though the number of each differ (used in Cosmic Charge Ratio Analysis)

**Fact:** Effect of  $\vec{B}$  on residuals flips sign with charge

- ▶ Find peak of residuals in two bins:  
 $R_+$  (positively-charged) and  $R_-$  (negative)
- ▶ Misalignment residual  $\equiv \frac{R_+ + R_-}{2}$ 
  - ▶ effectively scales up negatively-charged population to cancel effect of positives
- ▶ Syst.  $= \left( \frac{R_+ - R_-}{2} \right)$  (charge confusion)  $\times \frac{0.3}{2.3}$ 
  - ▶ Always plot  $(R_+ - R_-)/2$  to trace systematic error (times a large factor)



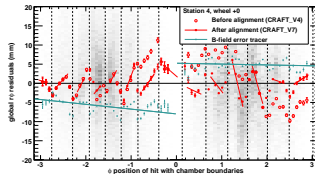
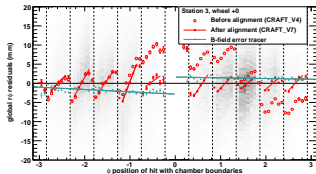
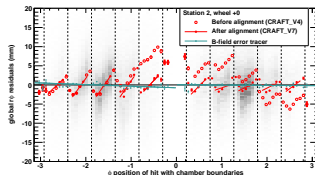
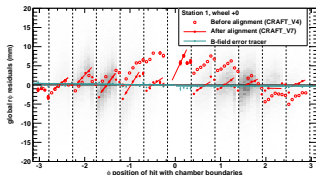
- ▶ Station 4 has the largest  $\vec{B}$ -field errors: plot residuals across barrel
- ▶ The **misalignment measure** breaks cleanly at the chamber boundaries
- ▶ The **tracer of  $\vec{B}$ -field errors** is independent of chamber



grey background is the raw 2-D residuals distribution

linear fits are only a guide for the eye: not used in alignment!

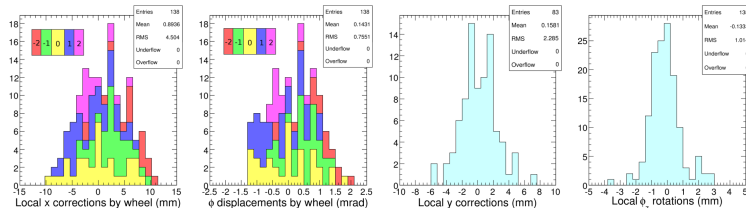
Same story when viewed as a function of  $\phi$  (wheel 0 shown for four stations)



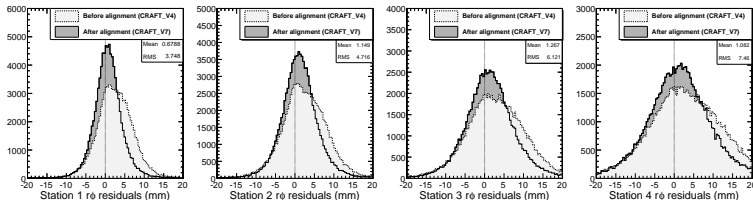
- ▶  $(R_+ - R_-)/2$  non-negligible in stations 3 and 4 only
- ▶ Flips sign in top of CMS ( $\phi > 0$ ) because of direction of muon velocity
- ▶ Linear trend inside each chamber (sawtooth shape) is unexplained: early investigations indicate non-rigid distortion of DT chambers
- ▶ See “more information” at <http://indico.cern.ch/conferenceDisplay.py?confId=51267>



- Pattern of alignment corrections do not correspond to a rotation



- Estimated residual misalignments: 1–2 mm (a factor-of-five improvement)
- Residuals visibly improve, despite unresolved “sawtooth” pattern



- CSCs are next, but will require a different technique due to vertical distribution of cosmic rays

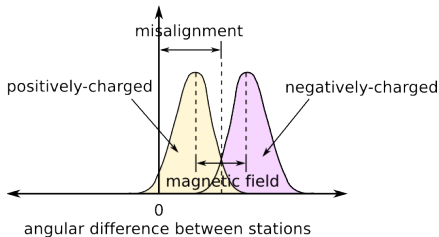
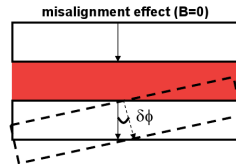
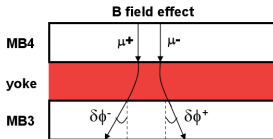
# Measuring $B_z$ with segments

(misalignment is a controlled systematic error)

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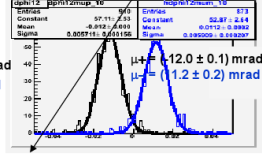
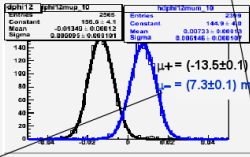
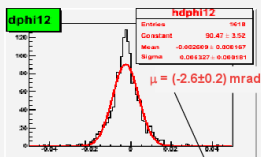
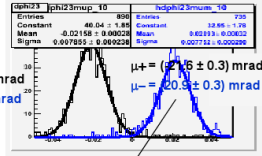
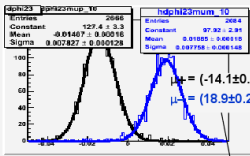
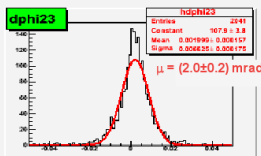
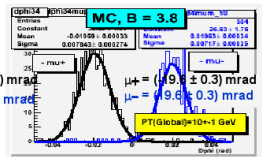
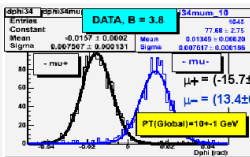
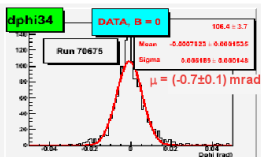
- ▶ Same principle:  
 $B_z$  is isolated through the difference between positive and negatively-charged bins, misalignment is the average
- ▶ Instead of residuals, plot segment angle difference between two stations on the same track
- ▶ Quantifies  $B_z$  in the yoke between them





Sara Bolognesi

$\delta\phi$  (wheel 0, sector 4,  $p_T=10\pm 1$  GeV)



$(\mu^+ - \mu^-)/2 \sim$  field bending

$(\mu^+ + \mu^-)/2 \sim$  misalignment

MC:  $[(-21.6 \pm 0.3) - (20.9 \pm 0.3)]/2$  mrad =  $(42.5 \pm 0.4)$  mrad

$[(-13.5 \pm 0.1) + (7.3 \pm 0.1)]/2$  mrad =  $(3.1 \pm 0.2)$  mrad

DATA:  $[(-14.1 \pm 0.2) - (18.9 \pm 0.2)]/2$  mrad =  $(33.0 \pm 0.3)$  mrad

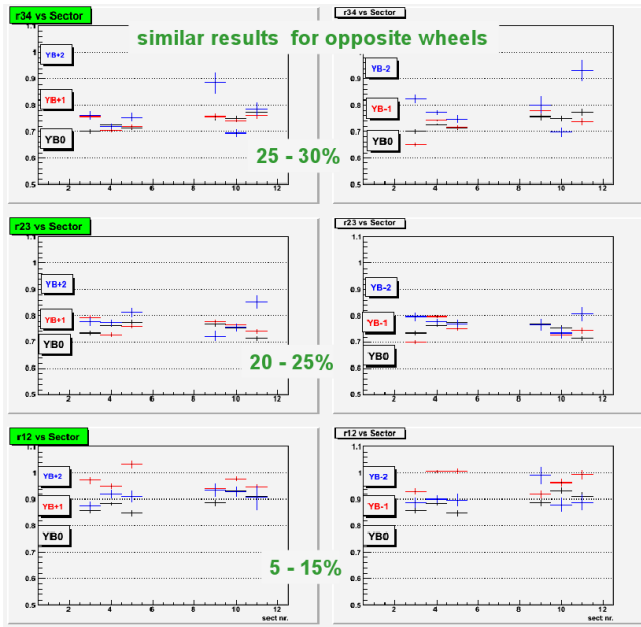
# Summary of $B_z$ measurements

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$$(B_z|_{\text{data}}) / (B_z|_{\text{MC}})$$

$$10 < p_T < 50 \text{ GeV}$$

Real  $B_z$  is generally smaller than simulated



- ▶ “data/MC” is the fractional  $B_z$  error determined by segments
- ▶ The agreement is coarse at best

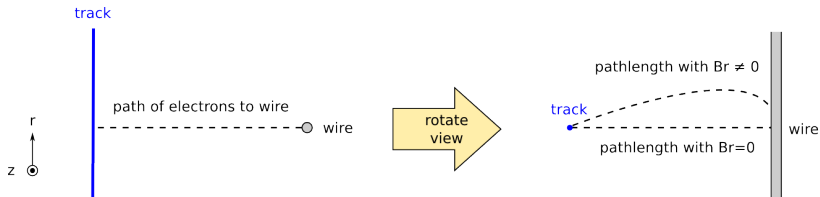
		MB1-2	MB2-3	MB3-4	
data/MC	wheel -2	10%	26%	30%	<ul style="list-style-type: none"> <li>• same results for opposite wheels from cosmic data</li> <li>• deficit <b>increasing toward outer stations</b> in both cases</li> </ul>
	wheel +2	7%	25%	30%	
flux-loop	wheel -2	0.1%	11.5%	21.8%	<ul style="list-style-type: none"> <li>• rescaling is <b>~10% bigger in cavern</b> (more iron in green structures and far endcap regions)</li> <li>→ (crazy flux-loop measurement: 2.4T)</li> </ul>
data/MC	wheel -1	4%	27%	30%	
	wheel +1	2%	24%	26%	<ul style="list-style-type: none"> <li>• measurement from cosmic data made on a <b>population not flat in z</b></li> </ul>
flux-loop	wheel -1	15.2%	7.0%	15.4%	
data/MC	wheel 0	7%	24%	25%	
flux-loop	wheel 0	0.9%	6.0%	10.5%	

# What about $B_r$ errors?

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Inside of a DT drift cell:

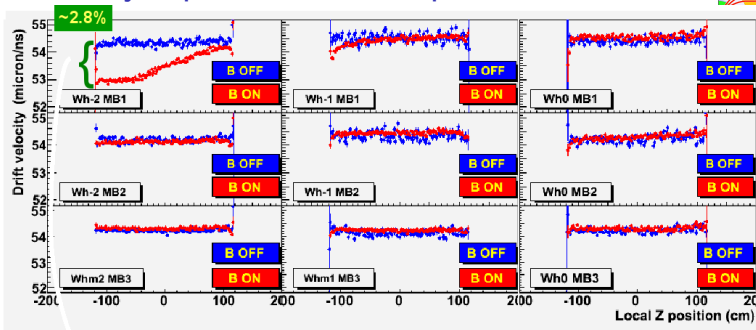


- ▶ While muon momentum may be parallel with the radial direction, current of electrons drifting to wire is always perpendicular
- ▶ Path is distorted by field, yielding a reduction in the apparent drift velocity (when computed as distance between track and wire/drift time)
- ▶ Variations in  $v_{\text{drift}}$  are sensitive to  $B_r$ , including any error with respect to simulation
- ▶ Independent of misalignment, though not a cross-check (because this is  $B_r$ , not  $B_z$ )

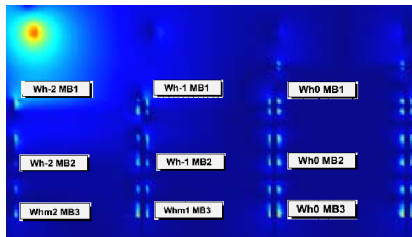
# Qualitatively reproduces $B_r$ map

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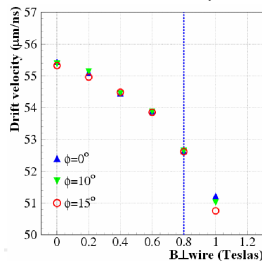
21/26



Field map:

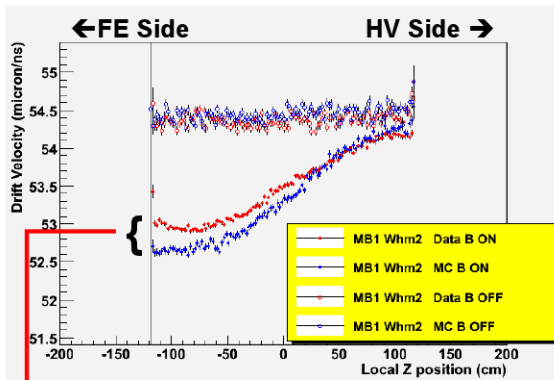


Conversion to  $B_r$  (test beam):



Mary-Cruz Fouz

$B_r$  is also smaller than simulation Jim Pivarski 22/26  
but only in high-field chambers

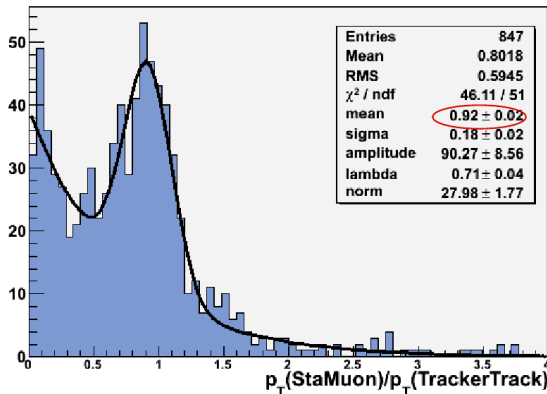


Wh +2, -2:  
Smaller effect from B in data than in MC

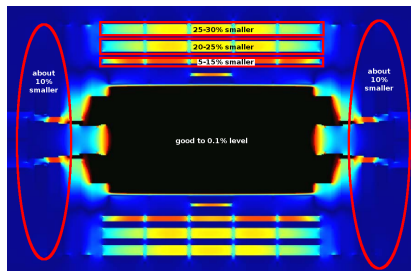
It seems that B inside the MB  
chambers is lower than expected



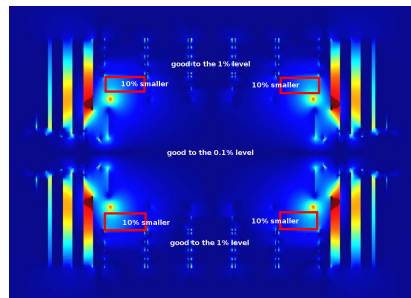
- ▶ Compares  $p_T$  of endcap stand-alone muons with tracker tracks
- ▶ Sensitive to integral of  $B_z$  error over path of tracks
- ▶ Result:  $B_z$  is about 10% lower in data than in simulation (assuming correct tracker momentum scale)
- ▶ Work in progress!



$B_z$



$B_r$



- ▶ If the field is at full strength in the tracker but smaller everywhere else, where are the field lines going?
  - ▶ close to the beamline? Maybe that explains the CASTOR forces...?
- ▶ Ultimately, the field measurements must be understood in terms of an updated simulation



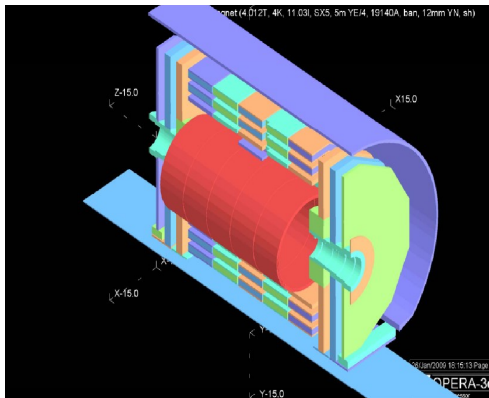
# What went wrong?

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- ▶ The magnetic field was simulated with CMS in isolation; no surrounding green structure as is in the cavern
- ▶ Quick check: adding a conducting pillbox around CMS can overcorrect for the effect
- ▶ Magnitude of corrections are therefore in the right ballpark
- ▶ Challenge will be to make the simulation more realistic

Dietrich Liko





- ▶ Muon tracking is far from perfect, but we're finding and correcting the kinds of distortions one might expect
  - ▶ improvements to barrel alignment in second CRAFT re-processing
  - ▶ emerging picture of magnetic field map
- ▶ Tracking datasets are rich: many problems that appear to be entangled can be cleanly decoupled by considering the right variables
  - ▶ but comparisons with completely independent methods, such as the hardware alignment system and  $\vec{B}$ -field flux loops, is always helpful
- ▶ CRAFT has been a productive shakedown cruise so far