



Proposal for new MC scenario

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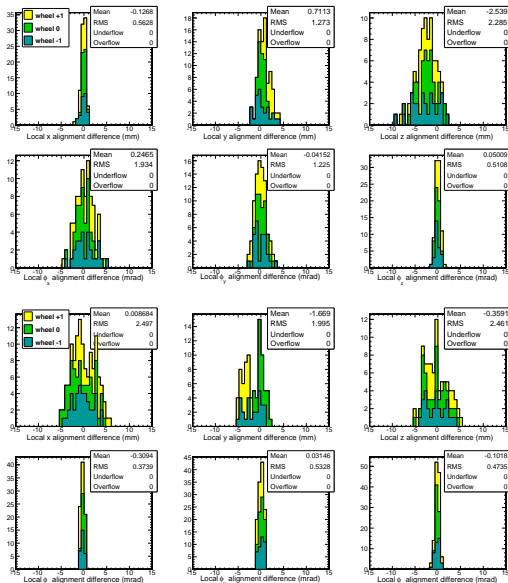
29 May, 2009

First, about the data-alignment

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Plots I showed on Monday used CRAFT_V11 tracker geometry, rather than the new one



- ▶ Differences between HIP and MillePede, using the same (newest) tracker geometry
- ▶ Only $560 \mu\text{m}$ in δ_x !
- ▶ They are in basic agreement, biggest differences in higher-order parameters
- ▶ Differences between old (V11) tracker and new tracker (that which will be signed off for reprocessing)
- ▶ 2–2.5 mm translational differences, though angular differences are small
- ▶ Refit lost 20% of the tracks (another indication that this tracker differs significantly)



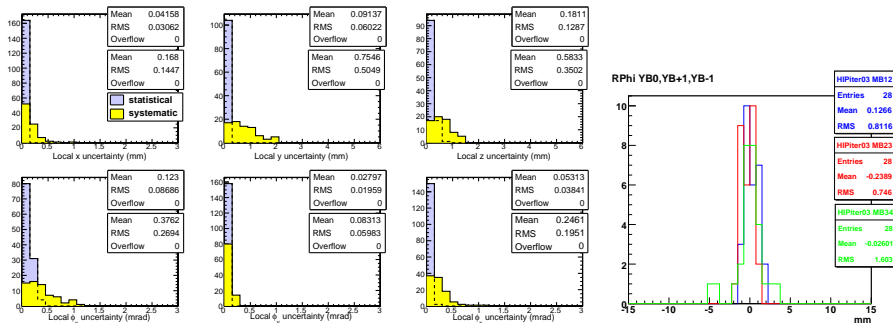
- ▶ Updated slides on Monday's Indico page, can view corrections side-by-side with the original
<http://indico.cern.ch/conferenceDisplay.py?confId=59610>
- ▶ SQLite file with finalized tracker geometry *is* correct:
`/castor/cern.ch/user/p/pivarski/
DTCRAFTiter03_withCenteredTracker.db`
(on CASTOR, use rfc; tag name is "DTAlignmentRcd")
- ▶ I've asked for updated segment-extrapolation validation
 - ▶ I don't expect this to change: in past experience, alignment moves chambers correlated along line-of-sight of tracks (as would be expected)
 - ▶ updated plots can be sent around by HyperNews
- ▶ I recommend the alignment above for sign-off (with APE=0)
 - ▶ next Wednesday
 - ▶ DT alignment, CSC alignment, and MC scenario would be a combined package



- ▶ Two levels of hierarchy for DT chambers: independent misalignment within sector-groups, correlated misalignment of sector-groups
- ▶ Two cases: aligned (wheels $-1, 0, +1$, except sec. 1 and 7) and unaligned
- ▶ Estimated from Monte Carlo, segment-matching, and p_T dependence
- ▶ Three levels for CSC chambers: chambers within disks (photogrammetry), disk-bending (SLM), and disk positions (tracks)
- ▶ Estimated from photogrammetry uncertainty, comparison of DCOPS with photogrammetry, ϕ_y from beam-halo measurements
- ▶ Also, layer uncertainties from DT track-survey comparisons and CSC beam-halo measurements

► Uncertainty within sectors

$x \sim 0.8$ mm segment-matching $\phi_x \sim 0.7$ mrad from MC
 $y \sim 1$ mm from MC $\phi_y \sim 0.7$ mrad segment-matching
 $z \sim 1$ mm from MC $\phi_z \sim 0.3$ mrad from MC



► Uncertainty of sector-groups: $x \sim 0.5$ mm from track source (e.g. p_T dependence)

Unaligned DT chambers

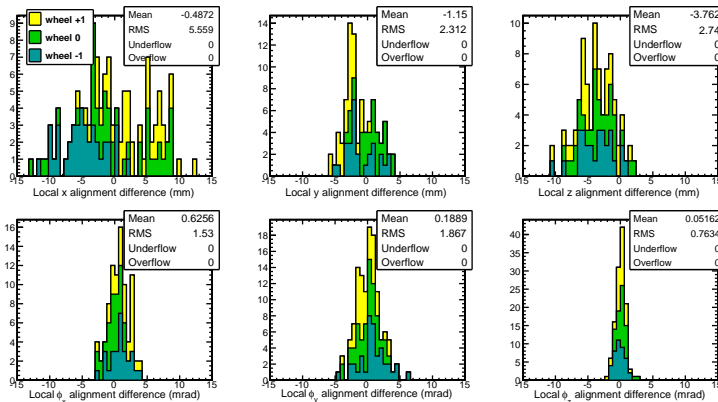
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► Uncertainty within sectors

$x \sim 0.8$ mm same as aligned $\phi_x \sim 1.6$ mrad from alignment
 $y \sim 2.4$ mm from alignment $\phi_y \sim 2.1$ mrad from alignment
 $z \sim 4.2$ mm from alignment $\phi_z \sim 1$ mrad from alignment

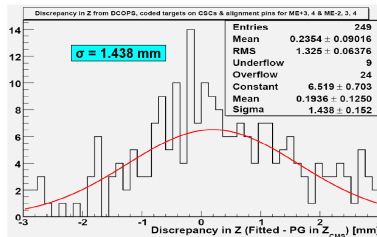
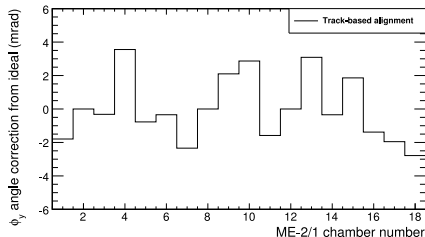
with -3.5 mm bias



► Uncertainty of unaligned sector-groups: $x \sim 6.5$ mm



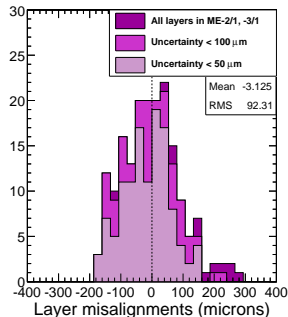
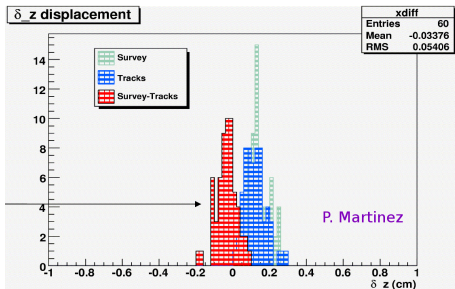
- ▶ Chambers relative to disks: photogrammetry, 0.3 mm isotropic, 0.15 mrad ϕ_z rotations (from pins and length of chambers)
- ▶ 2.3 mrad ϕ_y rotations observed in beam-halo tracks



- ▶ Disk-bending (z and ϕ_x): 1.438 mm and 0.57 mrad uncertainty from agreement between DCOPS and photogrammetry at 0 T
- ▶ Disk position/rotation: 0.5 mm and 0.1 mrad (after track alignment)



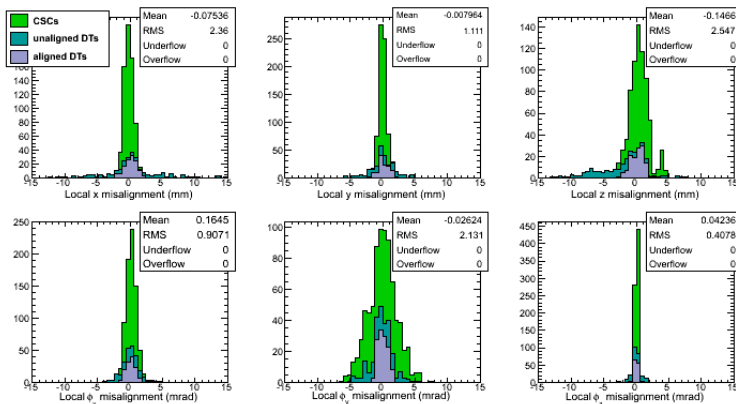
- DT superlayer misalignment: 0.54 mm in z from track/survey comparison



- CSC layer misalignment: 0.092 mm in x from beam-halo measurement



► Distribution of misalignment constants



► Location of SQLite files on CASTOR

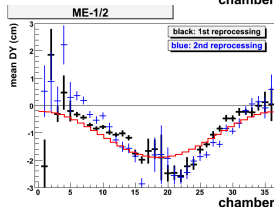
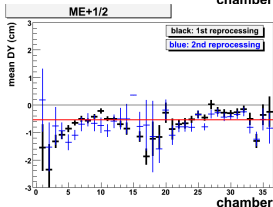
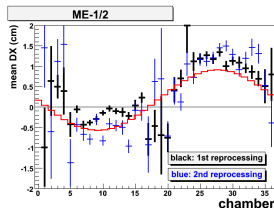
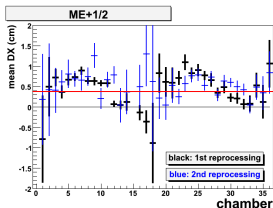
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/castor/cern.ch/user/p/pivarski/MCScenario_CRAFT1.31X_V02-09-04.db



- ▶ Optimized disk positions to reproduce plots shown by Michael Schmitt and myself
- ▶ Michael's plots: residuals in global coordinates

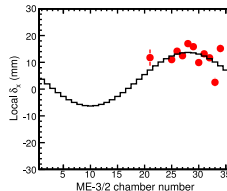
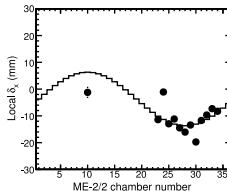
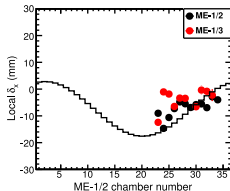
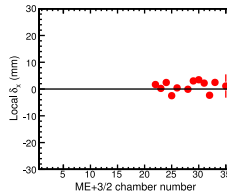
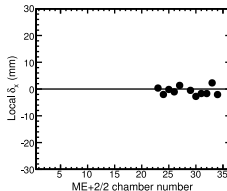
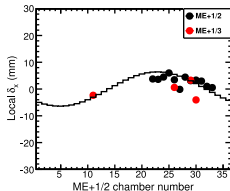
— Disk alignment correction



- ▶ ME-1: 4 x, -5 mm y; ME+1: 2 x, -10 mm y, 2 mrad



► My plots: local x coordinates



- Same $ME \pm 1$, $ME - 2, 3$: 10 mm x , 0.7 mrad, $ME + 2, 3$: nothing
- Curves produced by actual alignment scenario implemented in CMSSW
- Disk corrections applied on top of signed-off photogrammetry and hardware alignment