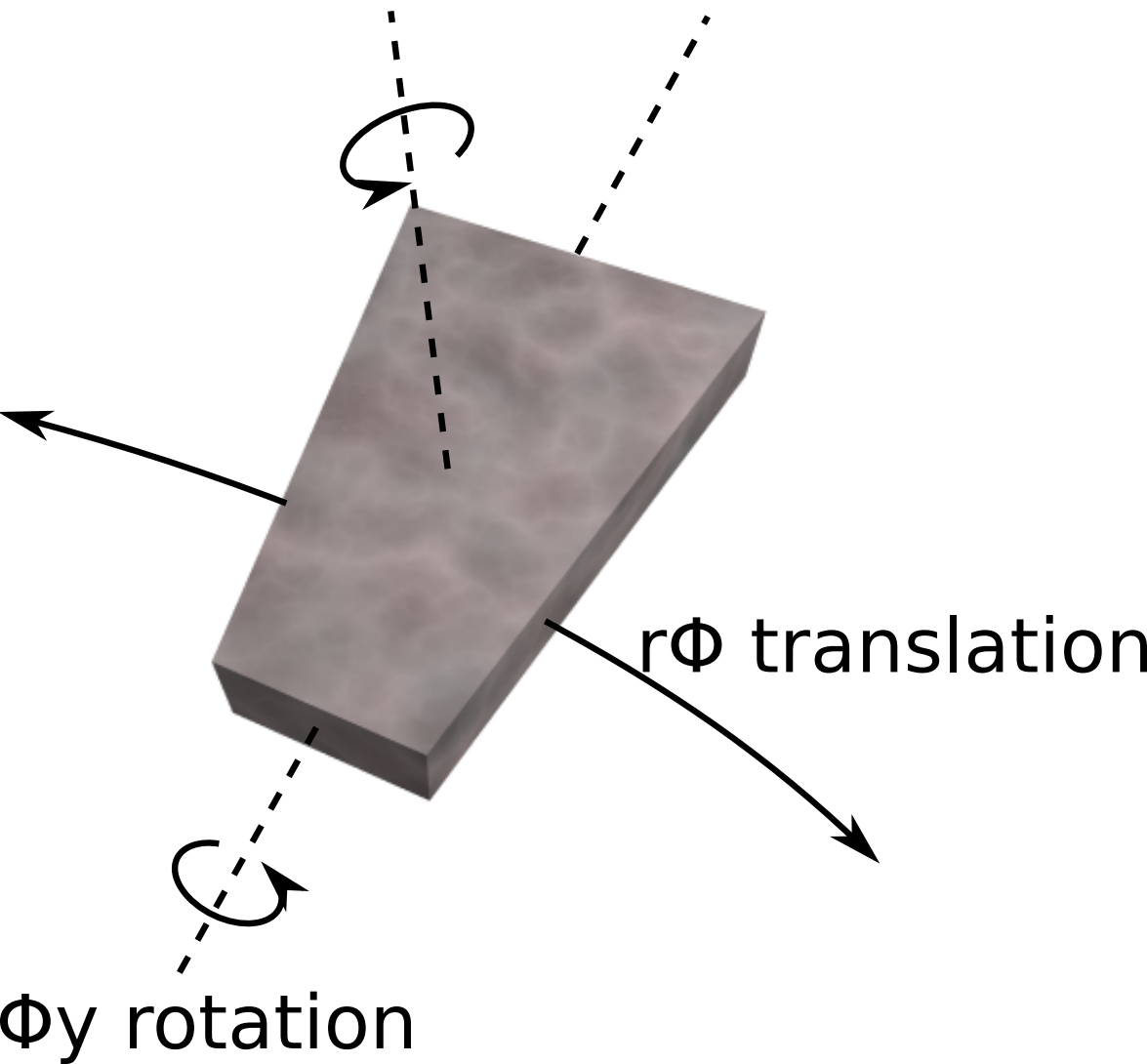


Φ_z rotation



$r\Phi$ translation

Φ_y rotation