



CRAFT Paper: Muon Track-based Alignment

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- ▶ This talk is to present the scope and the contents of CMS CFT 09-016: *Alignment of the CMS Muon System with Cosmic Ray and Beam-Halo Tracks*
 - ▶ with a focus on new results (since the LHC Alignment Workshop)
- ▶ You are welcome to read the note on <https://twiki.cern.ch/twiki/bin/view/CMS/CFT-09-016-TrackBasedMuonAlignmentNote> and send comments!
- ▶ Status: currently under internal review by most closely-related communities: muon alignment, DT-DPG, CSC-DPG, and AICa
- ▶ If approved by DT-DPG, it will be submitted to an ARC on Thursday



- ▶ 24 pages (with blanks), 13 figures

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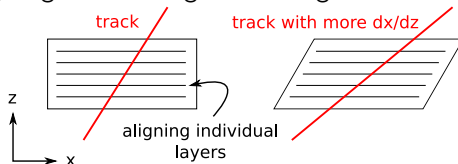
- ▶ Local alignments are alignments using “short” tracks that do not propagate through any layers of iron
- ▶ Global alignment is chamber alignment relative to the tracker
 - ▶ both HIP and MilliPede are represented, with MC studies and real-data cross-checks

Two local DT alignments

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1. Description of general layer alignment, combining tracks and survey data (quality control measurements and photogrammetry)
 - ▶ complete description of algorithm (good reference)
 - ▶ tracks-only alignment is degenerate: e.g. chambers can shear



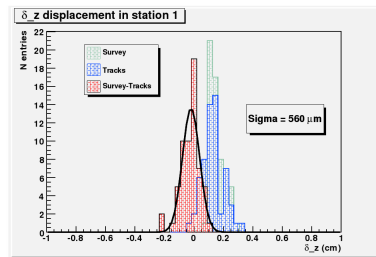
- ▶ no results to show because independent measurements are needed in the alignment procedure: no available cross-checks

2. Separate alignment of superlayers with tracks and photogrammetry independently, with cross-check

See Pablo's talk:

<http://indico.cern.ch/>

[conferenceDisplay.py?confId=59273](http://indico.cern.ch/conferenceDisplay.py?confId=59273)

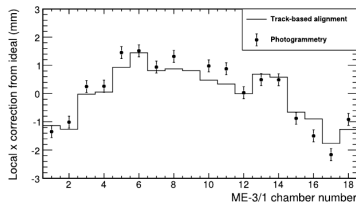
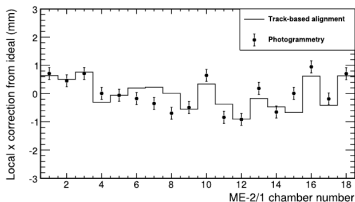




- ▶ This is the “CSC Overlaps method” (ring alignment from pairs of chambers using beam-halo or collisions):

<http://indico.cern.ch/conferenceDisplay.py?confId=46769>

- ▶ complete description of the method: propagation around ring
- ▶ Monte Carlo studies
- ▶ cross-check with photogrammetry (all 3 parameters \times 2 rings)



- ▶ Does not include discussion of layer alignment (only a brief comment)
 - ▶ demonstration would require higher statistics than 2008 beam-halo

Global alignment: algorithms

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- ▶ 2 sections: HIP and MillePede
- ▶ Complete description of Muon-HIP, how it differs from standard HIP:
 - ▶ tracks fixed by tracker
 - ▶ treatment of segment residuals: Δx , Δy , $\Delta \frac{dx}{dz}$, $\Delta \frac{dy}{dz}$ including CSC case
 - ▶ fit function: convolution of misalignment and propagation errors
 - ▶ sample fits (data only)
- ▶ Complete description of MillePede:
 - ▶ how it differs from the general case (fixed tracks)
 - ▶ detailed list of potential systematic errors

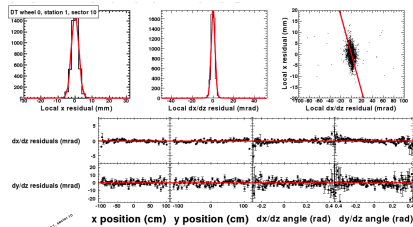
$$\begin{pmatrix} \Delta x^{\text{geom}} \\ \Delta y^{\text{geom}} \\ \Delta \frac{dx}{dz}^{\text{geom}} \\ \Delta \frac{dy}{dz}^{\text{geom}} \end{pmatrix} = \begin{pmatrix} 1 & 0 & -\frac{dx}{dz} & -y \frac{dx}{dz} & x \frac{dx}{dz} & -y \\ 0 & 1 & -\frac{dy}{dz} & -y \frac{dy}{dz} & x \frac{dy}{dz} & x \\ 0 & 0 & 0 & -\frac{dx}{dz} \frac{dy}{dz} & 1 + \left(\frac{dx}{dz}\right)^2 & -\frac{dy}{dz} \\ 0 & 0 & 0 & -\left(\frac{dy}{dz}\right)^2 & \frac{dx}{dz} \frac{dy}{dz} & \frac{dx}{dz} \end{pmatrix} \begin{pmatrix} \delta_x \\ \delta_y \\ \delta_z \\ \delta_{\phi_x} \\ \delta_{\phi_y} \end{pmatrix} \quad (22)$$

(The above matrix is an extension of Equation 17 in [8]). For CSCs, the curvilinear residuals $\Delta r\phi^{\text{geom}}$ and $\Delta d(r\phi)/dz^{\text{geom}}$ introduce corrections suppressed by r , the radial distance to the beamline:

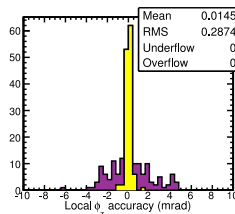
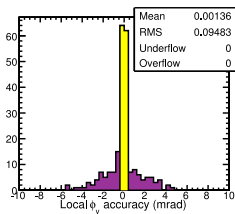
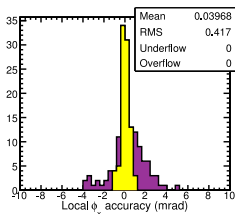
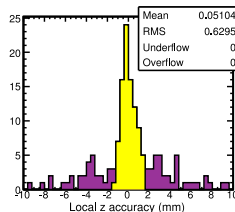
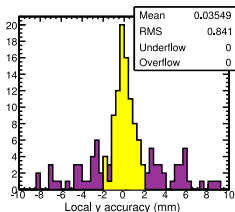
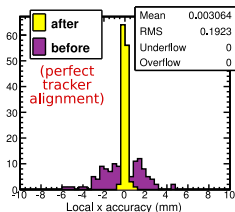
$$\begin{pmatrix} \Delta r\phi^{\text{geom}} \\ \Delta \frac{dr\phi}{dz}^{\text{geom}} \end{pmatrix} = \begin{pmatrix} 1 & \left[-\frac{x}{r} + 3\left(\frac{x}{r}\right)^3\right] & -\frac{dx}{dz} & -y \frac{dx}{dz} & x \frac{dx}{dz} & -y \\ 0 & -\frac{dx}{dz} \left(\frac{1}{2r}\right) & 0 & \left[\frac{x}{r} - \frac{dx}{dz} \frac{dy}{dz}\right] & 1 + \left(\frac{dx}{dz}\right)^2 & -\frac{dy}{dz} \end{pmatrix} \begin{pmatrix} \delta_x \\ \delta_y \\ \delta_z \\ \delta_{\phi_x} \\ \delta_{\phi_y} \end{pmatrix} \quad (23)$$

To extract geometric residuals from the measurements, we construct an ansatz describing all effects and fit it to the data. Each of the four observables is represented by a convolution of a Gaussian and a Lorentzian (to model the power-law scattering tails),

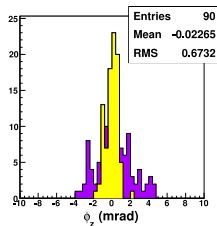
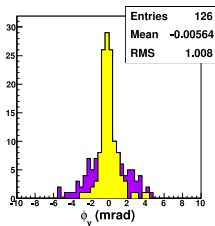
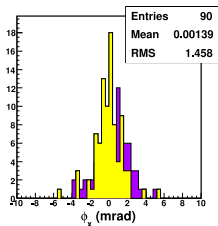
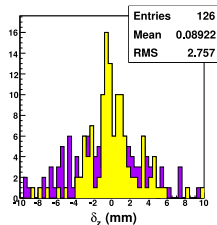
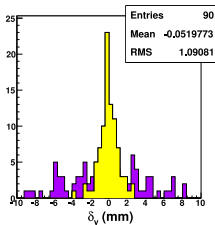
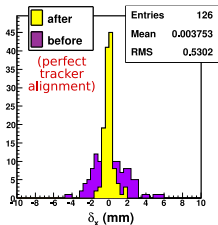
$$f(t; t_0, \sigma, \gamma) = \int_{-\infty}^{\infty} \frac{1}{\pi} \frac{\gamma}{(t-s-t_0)^2 + (\gamma)^2} \times \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{s^2}{2\sigma^2}\right) ds. \quad (24)$$



- ▶ Both algorithms studied in Monte Carlo, MillePede plot is new
- ▶ This is the HIP plot (old)

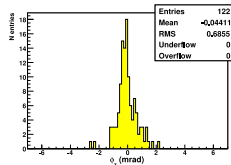
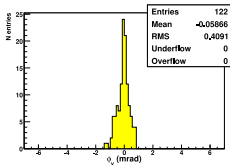
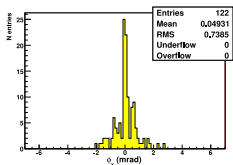
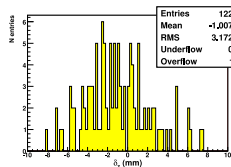
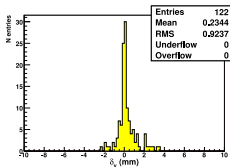
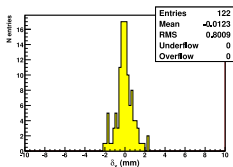


- ▶ Both algorithms studied in Monte Carlo, MillePede plot is new
- ▶ This is the MillePede plot (new)





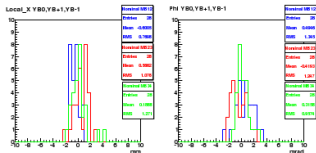
- ▶ The only “results” that make sense to show in an alignment paper are cross-checks
 - ▶ baselines like IDEAL and “before CRAFT” don’t mean anything to an outside reader
- ▶ First check: procedures converged (comment in words)
- ▶ Second: comparison of the two algorithms



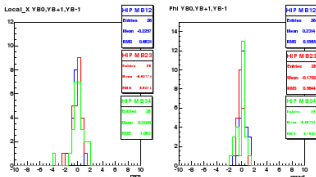
- ▶ Scale of differences can be understood from Monte Carlo

Results: cross-checks

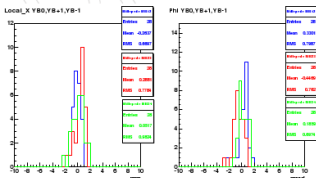
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(a) Before global alignment



(b) Results from the HEP algorithm



(c) Results from the MilleFe algorithm

- ▶ Third check: extrapolation of segments between neighboring chambers
 - ▶ local track data is partly independent of global track data
- ▶ Procedure:
 1. group chambers into pairs in neighboring stations, same sector
 2. select $p_T > 50$ GeV segments
 3. collect differences in extrapolated $r\phi$ positions and angles
 4. correct for non-linearity of tracks by averaging μ^+ and μ^- results
 5. peak of each chamber-pair distribution is an entry in the histograms



► Fourth check: momentum resolution from cosmic track splitting

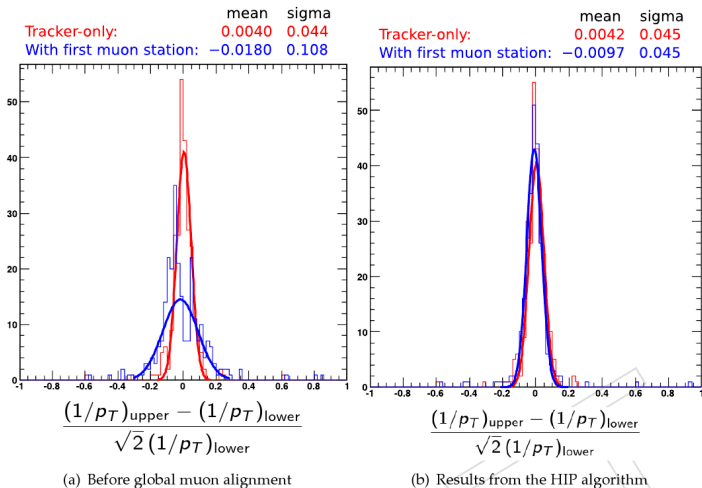


Figure 13: Top vs. bottom $1/p_T$ comparison for $p_T \gtrsim 200$ GeV split cosmic rays.

Conclusions (of this talk)

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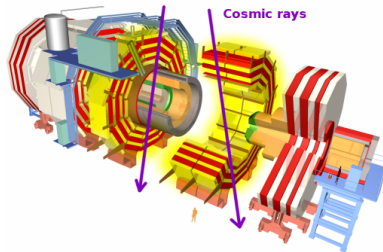
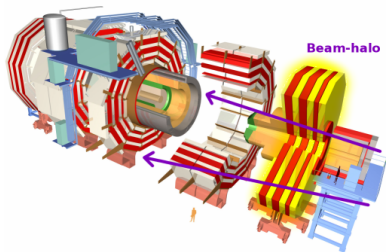


- ▶ I hope I've given you a good overview of what is in the paper and a chance to ask questions/raise issues about it in person
- ▶ To answer questions about the content of the paper itself, I've attached a set of slides on the content, to use as backup



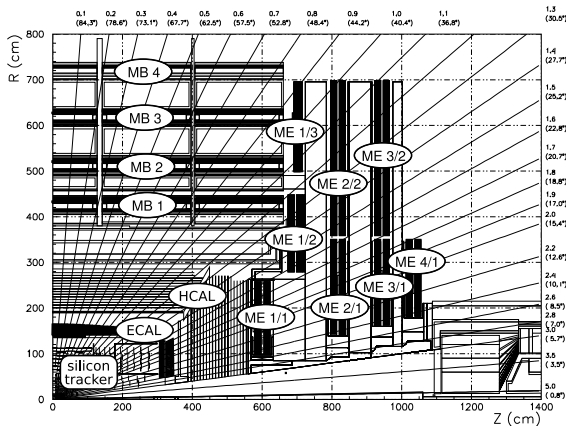
Backup

- ▶ Quick overview of the CMS muon system
- ▶ Alignment strategies
- ▶ Endcap results with 2008 LHC beam-halo
- ▶ Barrel results with CRAFT cosmic rays





- ▶ Tracking in modular chambers: 6 to 12 layers each
- ▶ Global track formed from chambers' segments and the silicon tracker

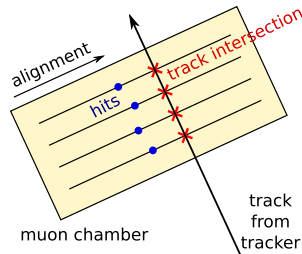


- ▶ Barrel (drift tube) chambers grouped into 4 radial stations, 5 longitudinal wheels
- ▶ Endcap (cathode strip) chambers grouped into 8 rings per endcap

- ▶ This talk will be about aligning the individual chambers
- ▶ Target for alignment is scale of $r\phi$ hit resolutions: $\mathcal{O}(100\text{--}300 \mu\text{m})$



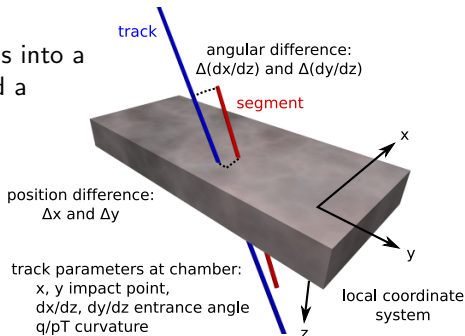
- ▶ **Consideration:** Tracks measured with high precision in the silicon tracker, then pass through thick layers of iron (solenoid return yoke)
 - ▶ resolution of global tracks is dominated by tracker data (for $p_T \lesssim 200$ GeV in barrel, $p_T \lesssim 500$ GeV in endcap)
 - ▶ scattering in iron can be confused for misalignment with a single track, but scattering is random; misalignment is systematic
- ▶ **Strategy:** fit tracks to the tracker only, then propagate to the muon system
 - ▶ misalignment given by the *peak* of the residuals distribution (residual = track – hit)
 - ▶ control for propagation effects: material budget, $\vec{B}(\vec{x})$, etc. have different dependencies on momentum and charge





- ▶ **Consideration:** no obstacles to track-fits inside the chambers
 - ▶ gas volume with negligible scattering
 - ▶ low magnetic field: field lines follow iron yoke between chambers

- ▶ **Strategy:** combine residuals into a 2-D position difference and a 2-D angle difference (4-component “residuals”)



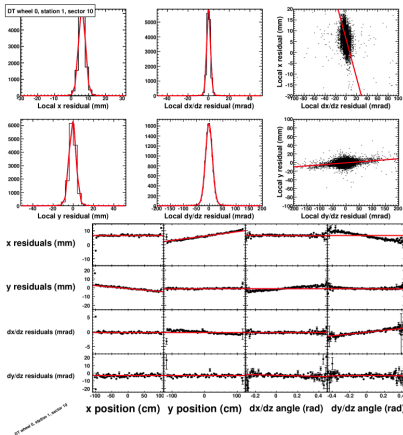
- ▶ more highly constrained than traditional approach
- ▶ compute 6 rigid-body degrees of freedom (3 translations and 3 rotations) from inversion of 6×4 matrix, rather than 6×2

Sample fits: Monte Carlo

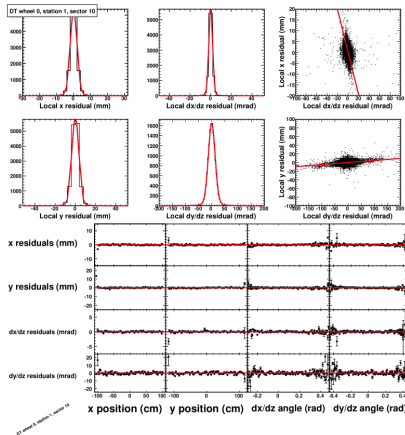
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Before alignment



After alignment



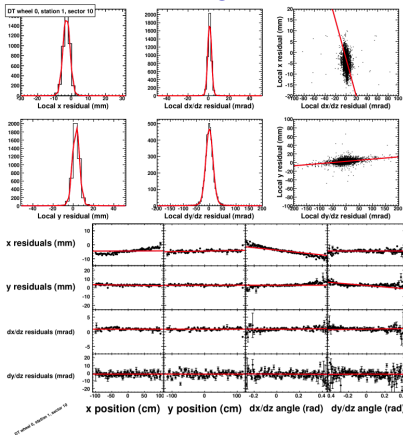
- ▶ Projection of fits (all parameters = 0 other than the one shown) overlaid on *simulated* data for one chamber
- ▶ Method works well in Monte Carlo

Sample fits: real cosmic rays

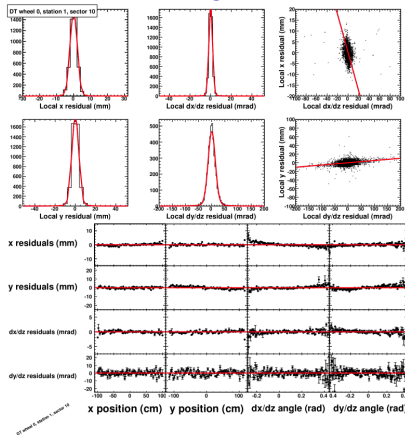
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Before alignment



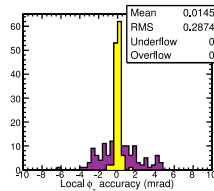
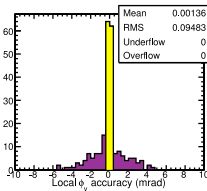
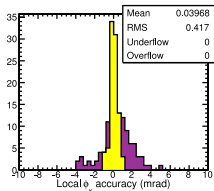
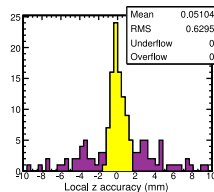
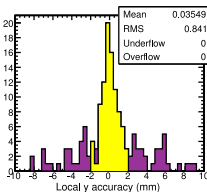
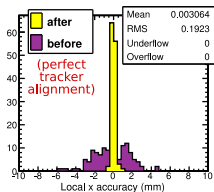
After alignment



- Projection of **fits** (all parameters = 0 other than the one shown) overlaid on *real* data for the same chamber
- Largely the same behavior in data; studying small discrepancies



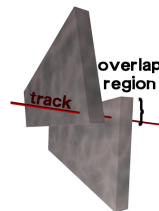
- Plot aligned-minus-true value of each of the 6 parameters for every chamber (histogram entries are chambers)
 - achieved 100–300 μm goal in $r\phi$ (local x coordinate: top-left)
 - systematics-dominated event sample



Note: this is a study of the muon alignment only, given a perfectly-aligned silicon tracker for input tracks.



- ▶ **Consideration:** Complimentary information available from global and local track propagations
 - ▶ propagation from the silicon tracker conveys information about the global CMS coordinate system
 - ▶ propagation from one chamber to its neighbor is less susceptible to scattering
 - ▶ partially-independent datasets from the same muons!
- ▶ **Strategy:** Develop alignment methods for both and cross-check
 - ▶ in the endcap, Cathode Strip Chambers (CSCs) overlap along their edges
 - ▶ propagate relative alignment information through all overlapping CSC pairs
 - ▶ provides a complete alignment within a consistent local coordinate system

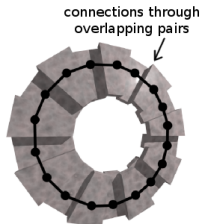


Alignment from CSC Overlaps

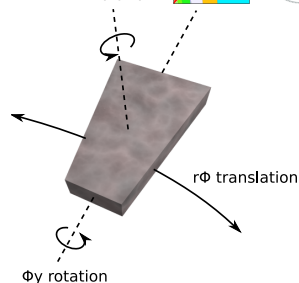
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Φ_z rotation

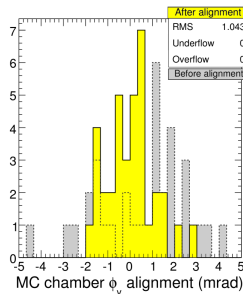
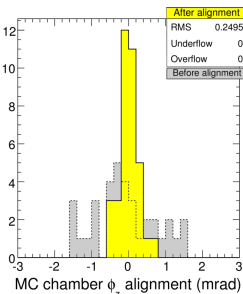
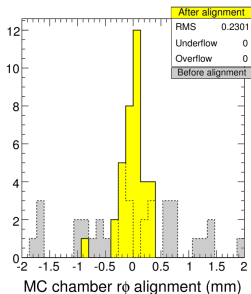


- ▶ Align a ring of CSCs with only local tracks by solving a system of 18 or 36 equations (for 18, 36 chambers per ring)
- ▶ Apply to 3 degrees of freedom



Monte Carlo accuracy

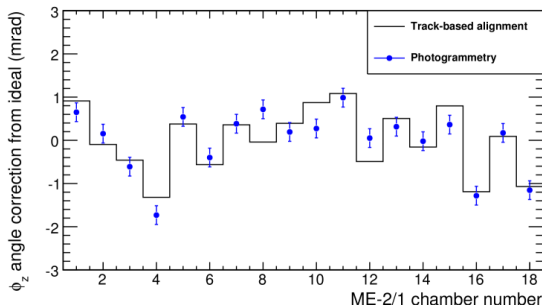
(statistics limited, similar sample size as data)





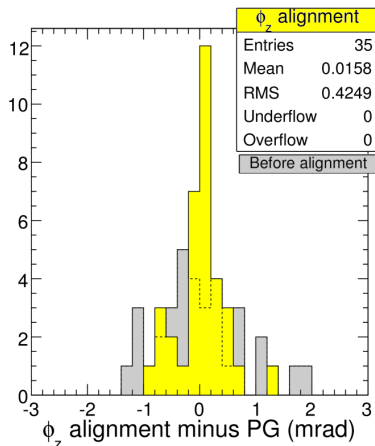
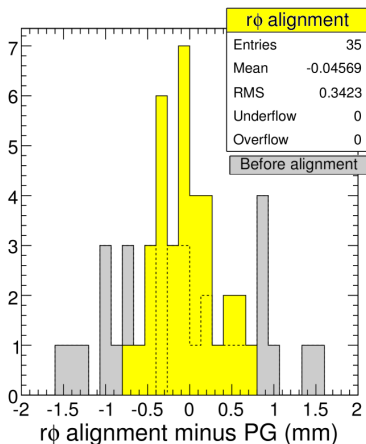
- ▶ Captured a total of 12 minutes of LHC muons, Sept 10–19, 2008
- ▶ Enough to align CSC rings closest to the beamline (33,000 events in overlapping edges)
- ▶ Local alignment cross-checked by photogrammetry: measurements from a literal photograph of the detector

Both methods observed (expected) differences with respect to the design geometry, with high correlation





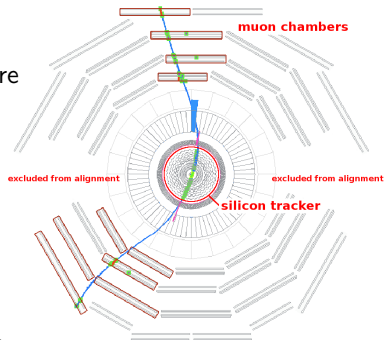
- ▶ Chamber-by-chamber comparisons with photogrammetry (PG):
 - ▶ agreement with $270\ \mu\text{m}$ position and $0.35\ \text{mrad}$ angular accuracy
 - ▶ for these chambers, intrinsic hit uncertainty is $166\ \mu\text{m}$
 - ▶ statistics-limited: reach $\sigma_{\text{align}} \lesssim \sigma_{\text{hits}}$ with an hour of beam





- ▶ Cosmic Rays At Four Tesla (CRAFT): 1 month of cosmic rays
 - ▶ all systems taking data concurrently: can align major subsystems relative to one another
 - ▶ solenoid at full field (3.8 T): can select high-momentum tracks

- ▶ Applied global alignment procedure to top and bottom of barrel (central 3 wheels, 10/12 sectors, due to vertical distribution of cosmic rays)

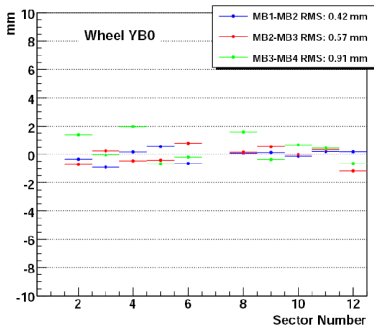


- ▶ Data and MC are both systematics-limited in most chambers

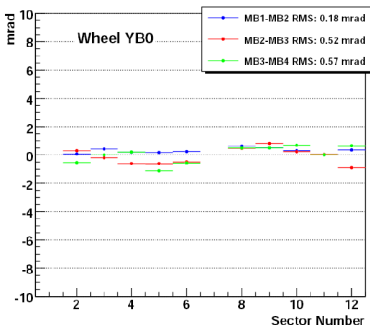


- ▶ Cross-check of global alignment with local data
 - ▶ propagate chamber segments through only one layer of iron with aligned geometry, check for consistency
 - ▶ RMS of differences: 0.42 mm, 0.18 mrad for innermost chambers

LocalX Segment differences between consecutive chambers



Phi Segment differences between consecutive chambers

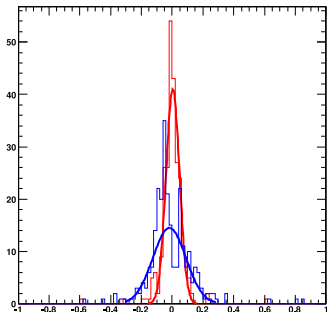




- High-level test: split each cosmic ray into two LHC-like halves, fit top and bottom independently
 - any mismatch in $1/p_T$ is purely instrumental
 - select $p_T \gtrsim 200$ GeV to emphasize contribution of the muon alignment (long lever arm for resolution of small sagitta)

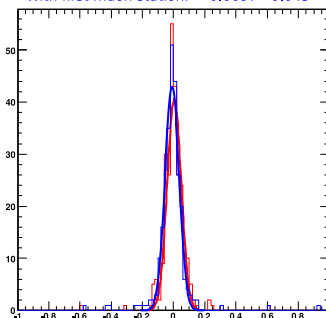
Before muon alignment

	mean	sigma
Tracker-only:	0.0040	0.044
With first muon station:	-0.0180	0.108

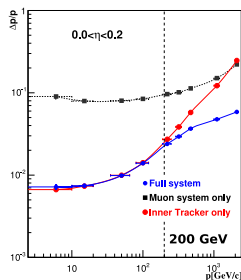


After muon alignment

	mean	sigma
Tracker-only:	0.0042	0.045
With first muon station:	-0.0097	0.045



Plot from Technical Design Report (no misalignment)



$\sigma \sim 0.025$ at
200 GeV for a perfect
detector



- ▶ Alignment strategy tailored to unique characteristics of the CMS muon system
- ▶ Procedures are well-understood in Monte Carlo, with reasonably good agreement with data
- ▶ Different methods based on global and local data for cross-checks
- ▶ Demonstrated excellent performance in beam-halo and cosmic rays: a good sign for alignment with first collisions!