



# DT and CSC Alignments for 2<sup>nd</sup> CRAFT-09 Reprocessing

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30 October, 2009



- ▶ DT Alignment
  - ▶ parameters
  - ▶ global adjustment
  - ▶ differences with respect to hardware + link
  - ▶ segment difference plots
  - ▶ distribution of medians
  - ▶ map plots
  - ▶ fit plots
  
- ▶ CSC Alignment
  - ▶ parameters
  - ▶ ring adjustments
  - ▶ table of ring corrections
  
- ▶ Location of files



► Sequence:

1. Barrel\_Opt210-56.db: Hardware + Link-to-AR + internal layer alignment
2. adjust whole barrel global  $\delta_x$ ,  $\delta_y$ ,  $\delta_{\phi_z}$  by hand
3. track-based chamber alignment (keeping  $\delta_{\phi_x}$  fixed)

► Where each final aligned position/orientation comes from:

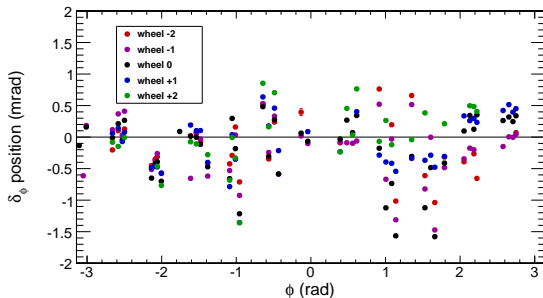
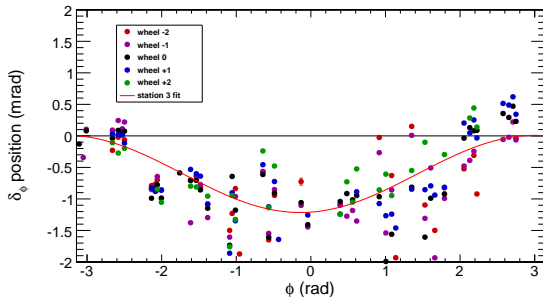
- all layers/superlayers relative to chamber center: (1) survey + tracks
- chambers poorly illuminated by cosmic rays, all parameters:  
(1) Hardware with (2) global adjustment
- all chambers local  $\delta_{\phi_x}$ , station 4  $\delta_y$ ,  $\delta_z$ ,  $\delta_{\phi_y}$ : (1) and (2)
- well-illuminated chambers, other params: (3) track-based chamber alignment

► Track-based chamber alignment parameters

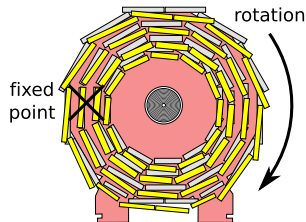
- Dataset: /Cosmics/CRAFT09-StreamMuAlGlobalCosmics-CRAFT09\_R\_V4-CosmicsSeq.v1/ALCARECO
- Run range: 109011–109624 (tracker “peak mode”)
- Release: CMSSW\_3\_2\_7
- GlobalTag: CRAFT09\_R\_V4::All
- Aligned parameters: stations 1–3  $\delta_x$ ,  $\delta_y$ ,  $\delta_z$ ,  $\delta_{\phi_y}$ ,  $\delta_{\phi_z}$   
station 4  $\delta_x$ ,  $\delta_{\phi_y}$ ,  $\delta_{\phi_z}$
- Tracks:  $100 < p_T < 200$  GeV, #tracker hits  $\geq 15$ , tracker  $\chi^2/\text{ndf} < 10$ , no rejection of TID/TEC
- No special correction for  $\vec{B}(\vec{x})$ ,  $dE/dx$
- Criterion for alignment: at least 30 hits and no Minuit fit failure
- 5 iterations (2 are necessary for most chambers)

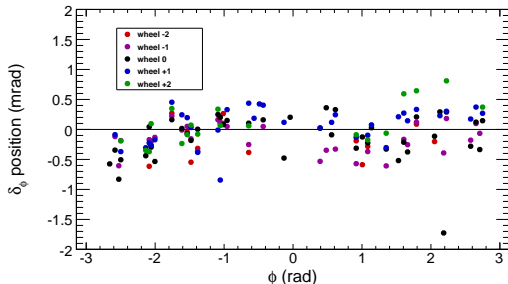
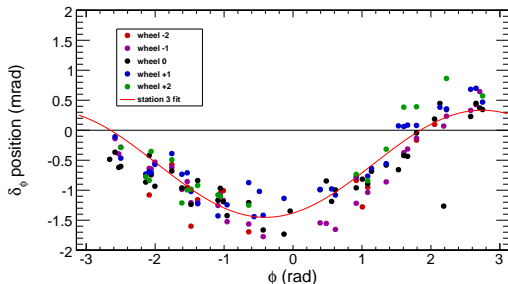
# Global adjustment

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- ▶ Plotting differences between hardware + link geometry and track-based geometry
- ▶ Global adjustment:  
 $\delta_x = 0.6$  mm,  
 $\delta_y = 3.8$  mm,  
 $\delta_{\phi_z} = 0.6$  mrad
- ▶ Almost perfect in  $\delta_x$
- ▶  $\delta_y$  and  $\delta_{\phi_z}$  are:

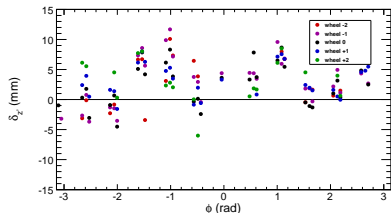
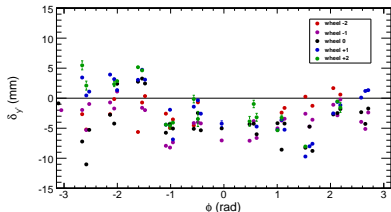
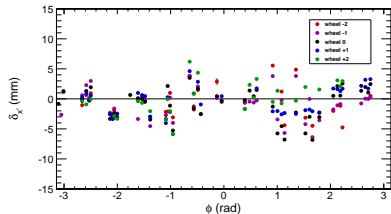




- ▶ Plotting differences between PG + cavern survey and track-based geometry
- ▶ Global adjustment:
  - $\delta_x = 2.2$  mm,
  - $\delta_y = 5.1$  mm,
  - $\delta_{\phi_z} = 0.6$  mrad
- ▶ Not apples-to-apples:
  - ▶ cavern global coords, not tracker coords
  - ▶ different internal geometry? (Luca?)
  - ▶  $\frac{1}{10}$  track sample
- ▶ But PG vs. tracks is narrower than HW vs. tracks

# Hardware vs. track-based

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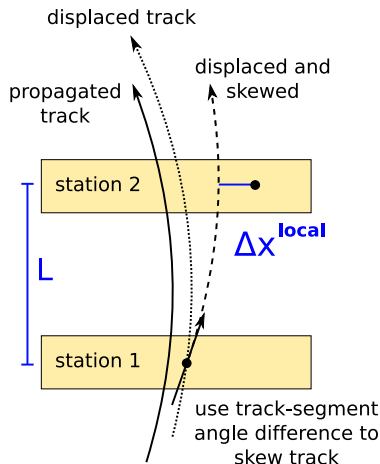
- ▶ Plotting differences between globally-adjusted hardware and track-based geometry
- ▶ Local  $x'$ ,  $y'$ , and  $z'$  vs.  $\phi$  (prime indicates consistent sign)
  - ▶  $x'$ : anti-clockwise  $r\phi$
  - ▶  $y'$ : parallel to beamline, pointing west
  - ▶  $z'$ : radial, pointing inward
- ▶ Semi-regular patterns emerge from the differences: could indicate discrepancies in chamber center assumptions
  - ▶ especially sectors 8, 9, 10 ( $-2.8 < \phi < -1.4$ )

# Segment differences (1)

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- ▶ Standard segment-extrapolation test was unavailable this week, so I implemented a version with more realistic track-propagation



- ▶ Local angle difference is difference of residuals with respect to the propagated tracker track

$$\Delta \frac{dx}{dz}^{\text{local}} = \Delta \frac{dx}{dz}_{\text{st.2}} - \Delta \frac{dx}{dz}_{\text{st.1}}$$

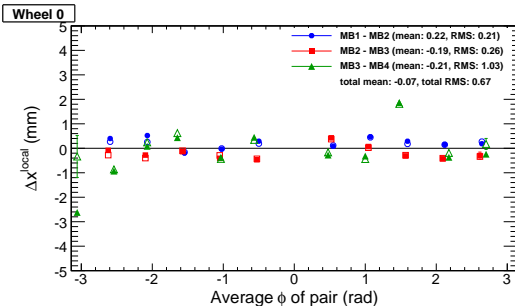
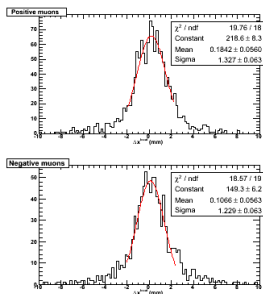
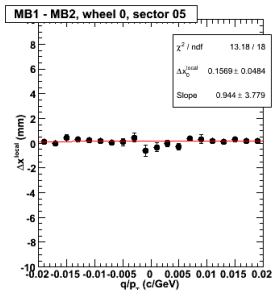
- ▶ Local position difference also needs to correct for segment direction by a linear transformation (see left)

$$\Delta x^{\text{local}} = \Delta x_{\text{st.2}} - \Delta x_{\text{st.1}} - L \cdot \Delta \frac{dx}{dz}_{\text{st.1}}$$

- ▶ In the limit of linear track propagation, this is exactly a linear segment extrapolation
- ▶ This is how Millepede applies track corrections to realistically-modelled tracks (small linear transforms)

# Segment differences (2)

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- ▶ Two fits: linear  $q/p_T \rightarrow 0$  and Gaussian of positive and negative separately
  - ▶ linear  $q/p_T \rightarrow 0$  results are *filled*  
 circles, squares, and triangles
  - ▶ average of Gaussian fits are *hollow*
- ▶  $1.7\text{--}2.5\times$  higher resolution in raw distributions and final results: RMS of stations 1–3 is 0.3 mm rather than 0.7 mm
- ▶ Reveals non-zero biases in alignment:  $\mathcal{O}(0.2 \text{ mm})$



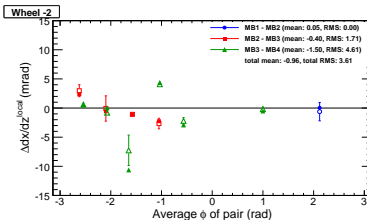
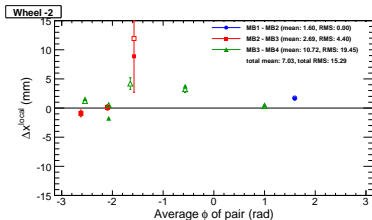
# Segment differences: wheel -2

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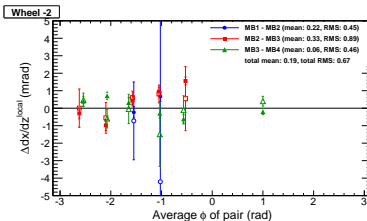
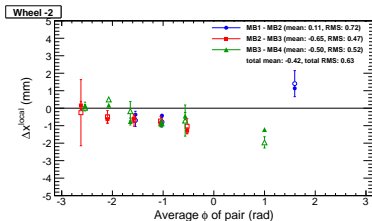


- ▶ A complete set of linear and Gaussian fits is in SegmentDifferences.pdf
- ▶ Careful of difference in vertical scales

## Globally-adjusted hardware geometry



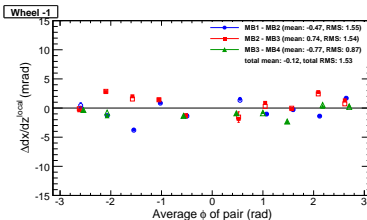
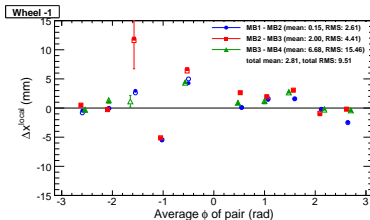
## Track-based geometry



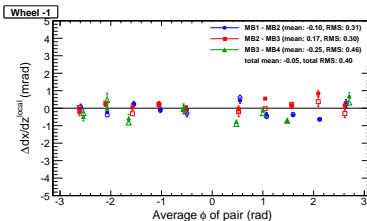
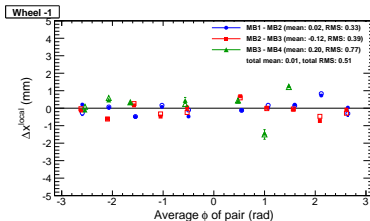


- ▶ A complete set of linear and Gaussian fits is in SegmentDifferences.pdf
- ▶ Careful of difference in vertical scales

## Globally-adjusted hardware geometry



## Track-based geometry



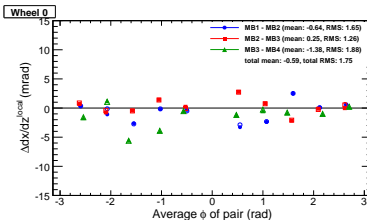
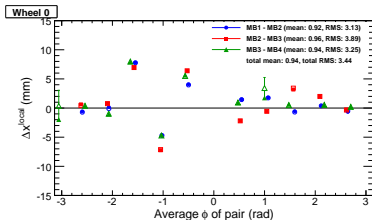
# Segment differences: wheel 0

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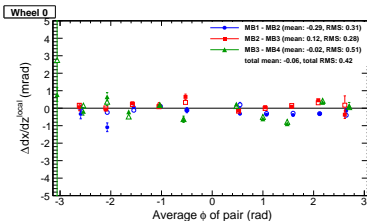
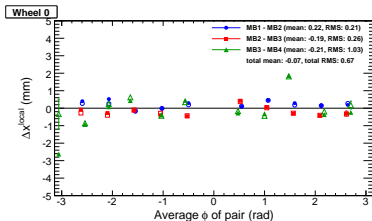


- ▶ A complete set of linear and Gaussian fits is in SegmentDifferences.pdf
- ▶ Careful of difference in vertical scales

## Globally-adjusted hardware geometry

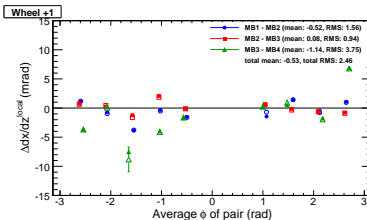
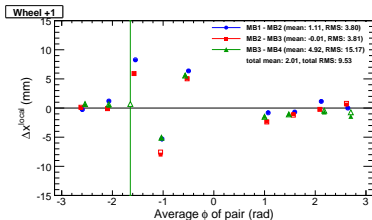


## Track-based geometry

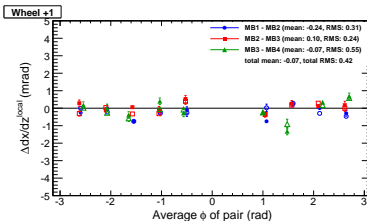
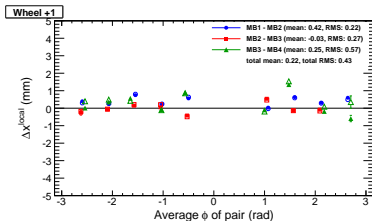


- ▶ A complete set of linear and Gaussian fits is in SegmentDifferences.pdf
- ▶ Careful of difference in vertical scales

## Globally-adjusted hardware geometry



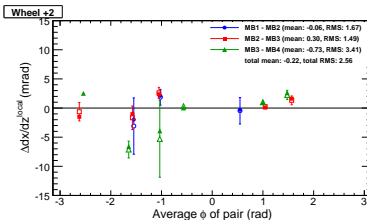
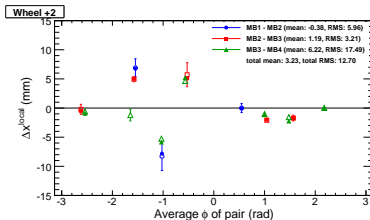
## Track-based geometry



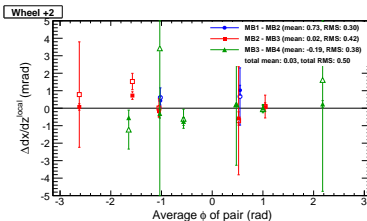
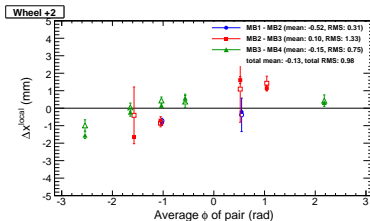


- ▶ A complete set of linear and Gaussian fits is in SegmentDifferences.pdf
- ▶ Careful of difference in vertical scales

## Globally-adjusted hardware geometry



## Track-based geometry

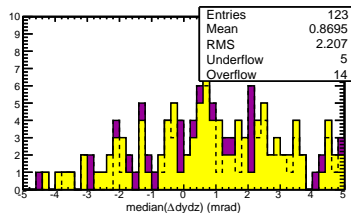
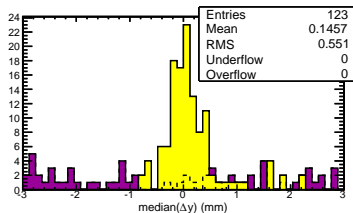
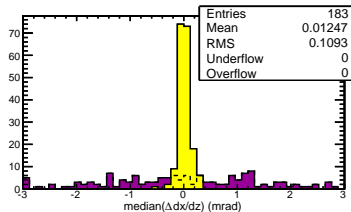
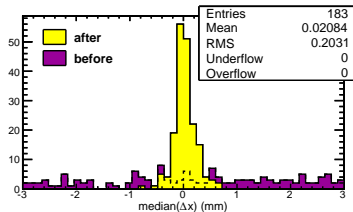


# Distribution of medians (1)

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- ▶ Each histogram entry is one chamber's median of residuals
  - ▶ tests self-consistency; median is a different way to be insensitive to residuals tails than the fitting method
- ▶ CRAFT-08 RMS  $\Delta x$ : 0.190 mm  $\Delta \frac{dx}{dz}$ : 0.085 mrad  $\Delta y$ : 0.166 mm  $\Delta \frac{dy}{dz}$ : 0.885 mrad; now we don't align  $\Delta \frac{dy}{dz}$ , which feeds into  $\Delta y$

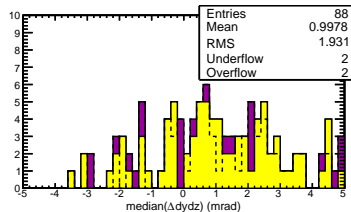
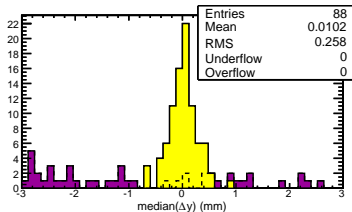
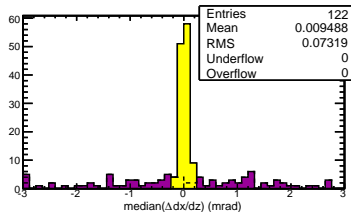
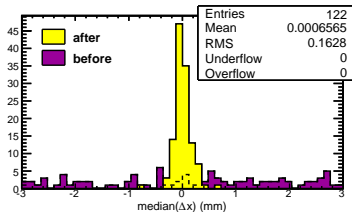


# Distribution of medians (2)

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- ▶ CRAFT-08 RMS  $\Delta x$ : 0.190 mm  $\Delta \frac{dx}{dz}$ : 0.085 mrad  $\Delta y$ : 0.166 mm  $\Delta \frac{dy}{dz}$ : 0.885 mrad; now we don't align  $\Delta \frac{dy}{dz}$ , which feeds into  $\Delta y$
- ▶ Now also restricting to the set of CRAFT-08 chambers (wheel  $-1, 0, +1$ , all sectors except 1 and 7)

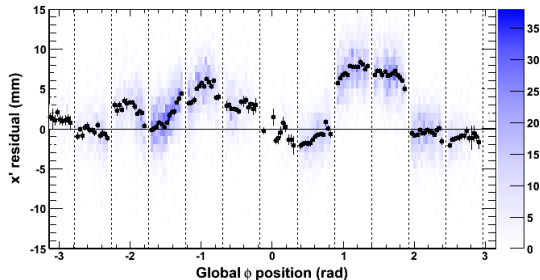


# Map plots

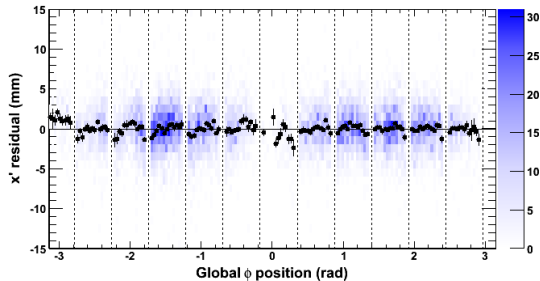
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wheel +0, station 1



wheel +0, station 1

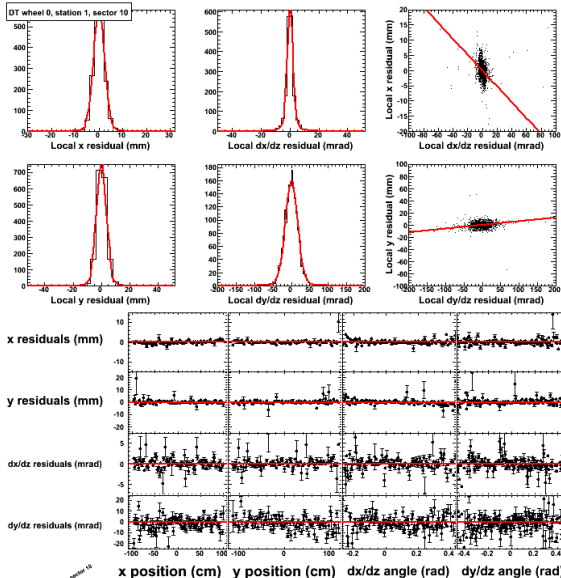


- ▶ Residuals as a function of  $\phi$ ,  $z$  with chamber boundaries as dashed lines, color scale is 2-D plot, points are profile
- ▶ Top: globally-adjusted hardware geometry, bottom: track-based
- ▶ If the discrepancy were due to distortions in the track source or propagation, it wouldn't change abruptly at chamber boundaries
- ▶ Complete set in MapPlots.pdf



# Fit plots

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- ▶ Overlay of fit function on residuals projections (after alignment)
- ▶ Bell-curves are Gaussians + tails, should be centered (except unaligned  $\Delta \frac{dy}{dz}$ )
- ▶ Scatter plots are position-angle correlations, should *not* be flat (propagation)
- ▶ Points with error bars are residuals versus everything, should be flat (geometric)
- ▶ Complete set in FitFunctions.pdf

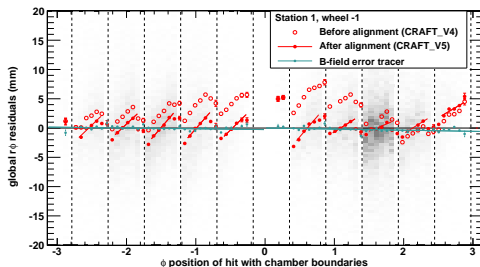
DT wheel 0, station 1, sector 10

# Sawtooth effect?

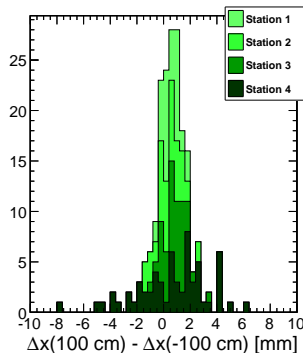
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- ▶ Sawtooth effect is not very evident, scanning through map and fit plots
- ▶ Below is an old example plot showing the sawtooth:

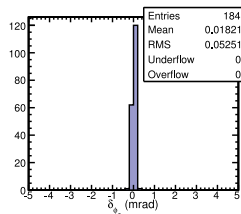
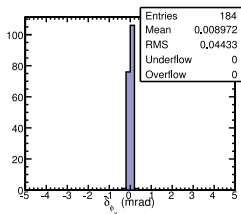
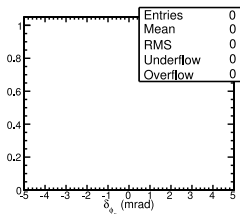
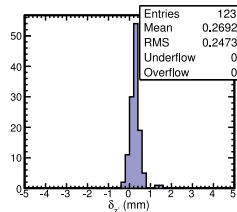
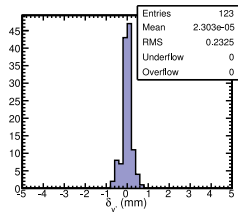
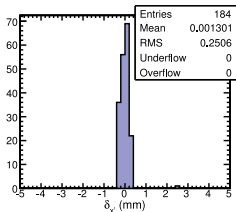


- ▶  $\sim 5$  mm difference in  $\Delta x$  residuals from  $x = -100$  to  $+100$  cm
- ▶ How much is it now?  
Fit all  $\Delta x$  vs.  $x$  distributions, evaluate at  $\pm 100$  cm (new histogram on right)
- ▶ Less than half as large, and not all in the same direction
- ▶ Maybe due to calibration, and that was improved? (a guess)





- ▶ At the time that all of these plots were made, the tracker alignment group was making a final decision between their `HIPCenteredObject.db` and `MergedCenteredObject.db`
- ▶ Two muon alignments were produced, one for each tracker description in parallel
- ▶ All of the plots shown here were made with `MergedCenteredObject.db`, but the final tracker alignment is `HIPCenteredObject.db`.
- ▶ The differences in muon alignment (DT and CSC) are on the  $250\ \mu\text{m}$  level





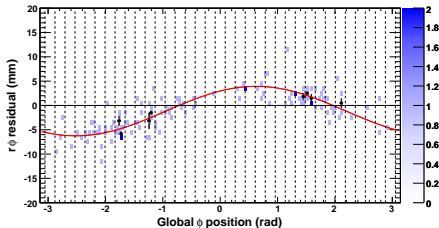
- ▶ Sequence:
  1. 2009 hardware alignment ( $\delta_z$  and  $\delta_{\phi_x}$ )
  2. adjust each ring's global  $\delta_x$ ,  $\delta_y$ ,  $\delta_{\phi_z}$  by hand
- ▶ Where each final aligned position/orientation comes from:
  - ▶ all internal layers relative to chamber center: ideal
  - ▶ all chambers  $\delta_{\phi_x}$  and  $\delta_z$ : (1) hardware
  - ▶ all chambers  $\delta_x$ ,  $\delta_y$ ,  $\delta_{\phi_z}$ : (2) ring adjustment
- ▶ Track-based alignment parameters
  - ▶ Dataset: /Cosmics/CRAFT09-CSCSkim\_BFieldStudies-CRAFT09\_R\_V4-CosmicsSeq\_v1/RAW-RECO
  - ▶ Run range: 109011–109624 (tracker “peak mode”)
  - ▶ Release: CMSSW\_3\_2\_7
  - ▶ GlobalTag: CRAFT09\_R\_V4::All
  - ▶ Tracks:  $100 < p_T < 200$  GeV, #tracker hits  $\geq 15$ , tracker  $\chi^2/\text{ndf} < 10$ , no rejection of TID/TEC
  - ▶ No special correction for  $\vec{B}(\vec{x})$ ,  $dE/dx$
  - ▶ Alignment performed by fitting map plots
- ▶ Note: statistical errors in individual-chamber alignments are unacceptably high: 1 mrad in  $\phi_y$ ; that's why they were only collectively aligned
- ▶ This procedure compliments the beam-halo procedure well (which aligns individual chambers, but not the rings relative to the tracker)

# Ring fits (1/8)

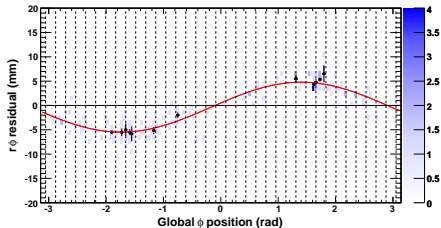
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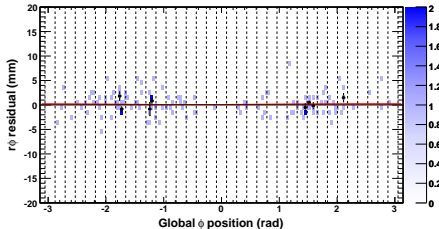
ME-1/1 before ring alignment



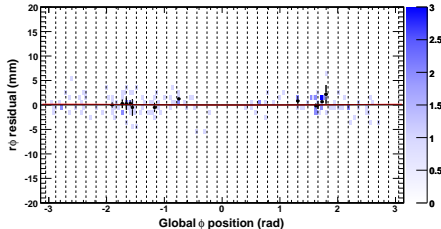
ME+1/1 before ring alignment



ME-1/1 after ring alignment



ME+1/1 after ring alignment

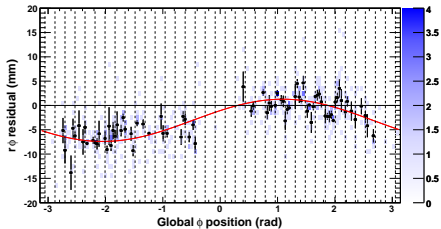


# Ring fits (2/8)

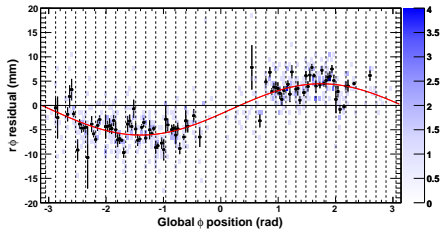
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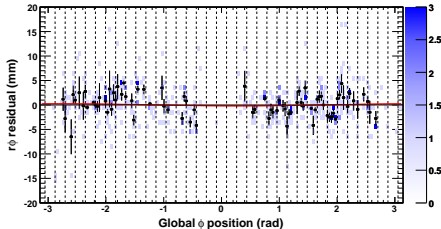
ME-1/2 before ring alignment



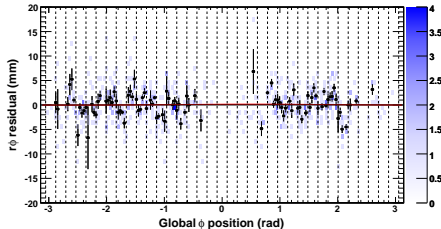
ME+1/2 before ring alignment



ME-1/2 after ring alignment



ME+1/2 after ring alignment

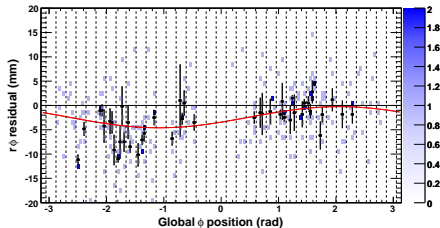


# Ring fits (3/8)

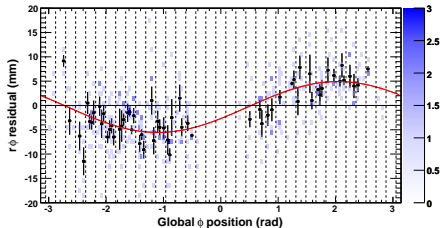
Jim Pivarski 23/30



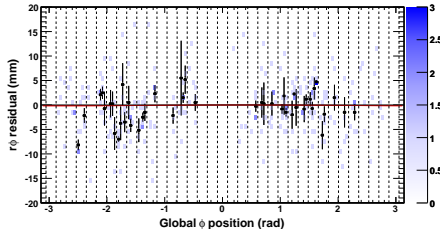
ME-1/3 before ring alignment



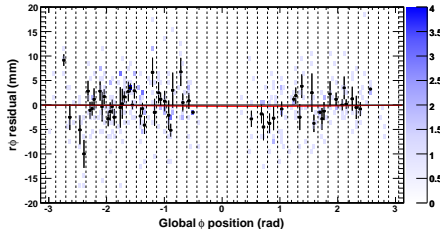
ME+1/3 before ring alignment



ME-1/3 after ring alignment



ME+1/3 after ring alignment

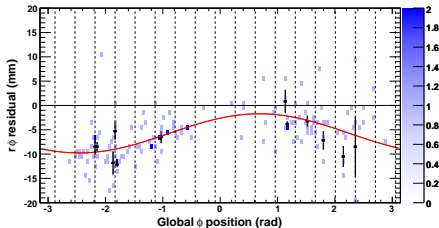


# Ring fits (4/8)

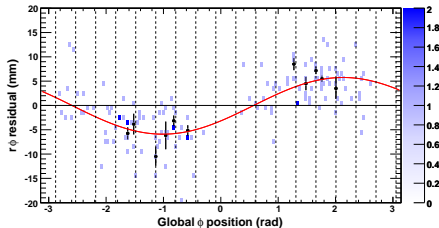
Jim Pivarski 24/30



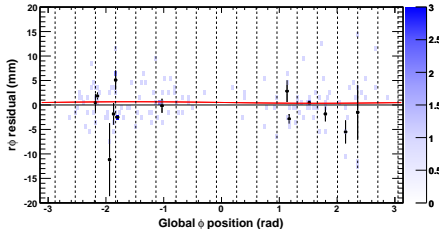
ME-2/1 before ring alignment



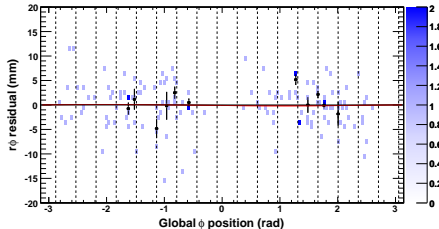
ME+2/1 before ring alignment



ME-2/1 after ring alignment



ME+2/1 after ring alignment



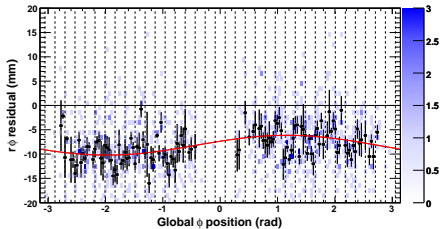


# Ring fits (5/8)

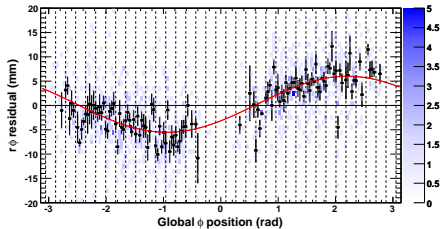
Jim Pivarski 25/30



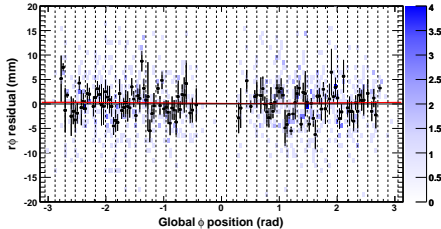
ME-2/2 before ring alignment



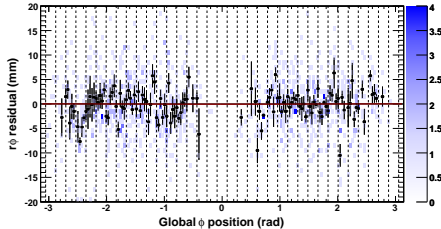
ME+2/2 before ring alignment



ME-2/2 after ring alignment



ME+2/2 after ring alignment

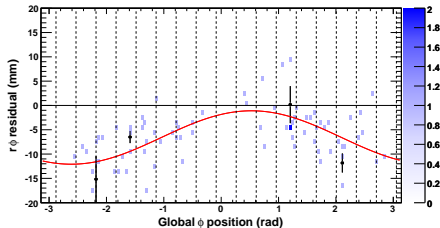


# Ring fits (6/8)

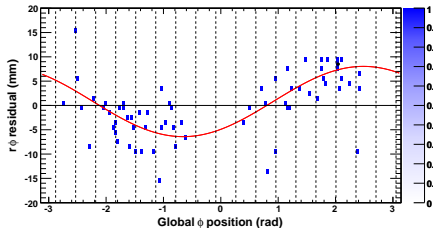
Jim Pivarski 26/30



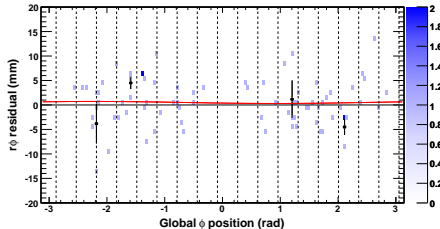
ME-3/1 before ring alignment



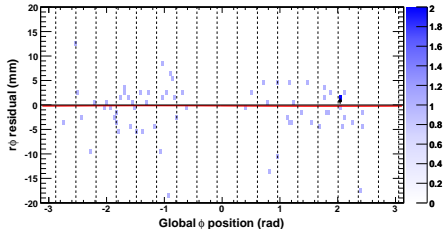
ME+3/1 before ring alignment



ME-3/1 after ring alignment



ME+3/1 after ring alignment

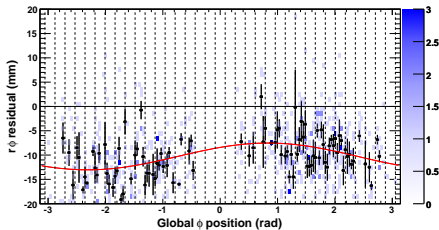


# Ring fits (7/8)

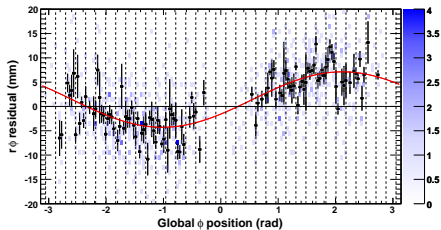
Jim Pivarski 27/30



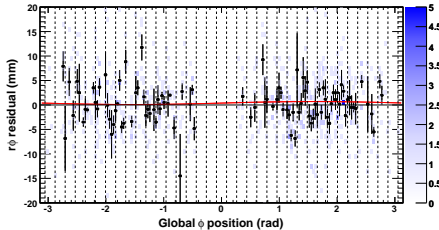
ME-3/2 before ring alignment



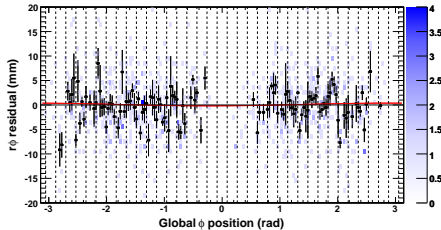
ME+3/2 before ring alignment



ME-3/2 after ring alignment



ME+3/2 after ring alignment

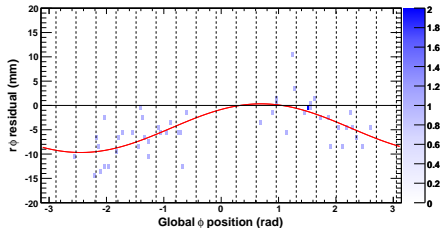


# Ring fits (8/8)

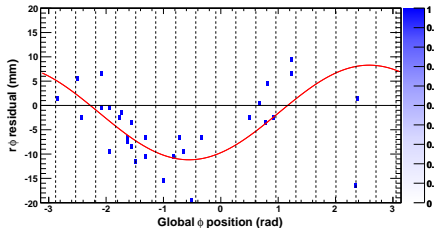
Jim Pivarski 28/30



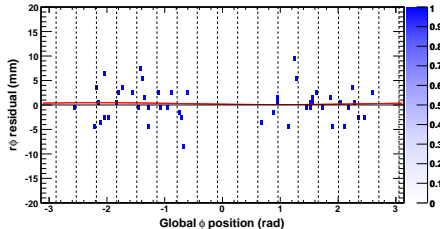
ME-4/1 before ring alignment



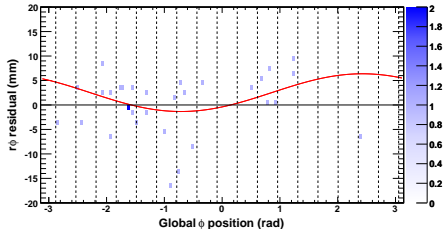
ME+4/1 before ring alignment



ME-4/1 after ring alignment



ME+4/1 after ring alignment





- ▶ Grouped items are physically connected to the same disk; values are correlated but not exactly equal within fitting errors
- ▶ Large  $\chi^2/\text{ndf}$  expected from incomplete chamber alignment

ring	$\delta_x$ (mm)	$\delta_y$ (mm)	$\delta_{\phi_z}$ (mrad)	$\chi^2/\text{ndf}$
ME-4/1	$3.20 \pm 0.17$	$-3.85 \pm 0.29$	$1.78 \pm 0.05$	12.7426
ME-3/2	$2.03 \pm 0.05$	$-1.86 \pm 0.08$	$1.95 \pm 0.01$	52.4465
ME-3/1	$2.77 \pm 0.13$	$-4.75 \pm 0.21$	$2.61 \pm 0.04$	24.2564
ME-2/2	$1.87 \pm 0.05$	$-0.82 \pm 0.07$	$1.55 \pm 0.01$	41.8597
ME-2/1	$2.54 \pm 0.10$	$-3.12 \pm 0.17$	$2.37 \pm 0.04$	27.4691
ME-1/3	$1.93 \pm 0.08$	$1.01 \pm 0.12$	$0.41 \pm 0.01$	45.7221
ME-1/2	$3.86 \pm 0.06$	$-2.00 \pm 0.09$	$0.83 \pm 0.01$	17.4924
ME-1/1	$2.97 \pm 0.11$	$-4.13 \pm 0.17$	$0.64 \pm 0.05$	9.08853
ME+1/1	$5.06 \pm 0.11$	$-0.86 \pm 0.16$	$0.19 \pm 0.05$	3.48464
ME+1/2	$5.20 \pm 0.06$	$0.92 \pm 0.09$	$0.22 \pm 0.01$	17.3722
ME+1/3	$4.66 \pm 0.07$	$2.37 \pm 0.11$	$0.05 \pm 0.01$	32.8144
ME+2/1	$4.94 \pm 0.10$	$3.10 \pm 0.16$	$0.03 \pm 0.04$	20.9203
ME+2/2	$4.65 \pm 0.04$	$3.41 \pm 0.07$	$-0.05 \pm 0.01$	43.0836
ME+3/1	$4.42 \pm 0.14$	$5.72 \pm 0.24$	$-0.32 \pm 0.05$	55.0455
ME+3/2	$4.86 \pm 0.05$	$2.98 \pm 0.08$	$-0.27 \pm 0.01$	46.2096
ME+4/1	$\sim 5.13 \pm 0.25$	$\sim 8.27 \pm 0.30$	$\sim 0.55 \pm 0.08$	78.0725



- ▶ DT alignment constructed from hardware, link, and tracks:

```
/afs/cern.ch/user/p/pivarski/public/DTAlignmentRcd.CRAFT09.segments-hardware-globalMuons_3XY.v8.offline.db  
.../DTAlignmentRcd.CRAFT09.segments-hardware-globalMuons_3XY.v8.offline.RELTOIDEAL.xml  
.../DTAlignmentRcd.CRAFT09.segments-hardware-globalMuons_3XY.v8.offline.RELTONONE.xml
```

- ▶ tags: DTAlignmentRcd and DTAlignmentErrorRcd (infinite for unaligned chambers)

- ▶ CSC alignment constructed from hardware and tracks:

```
/afs/cern.ch/user/p/pivarski/public/CSCAlignmentRcd.CRAFT09.hardware-globalMuons_3XY.v4.offline.db  
.../CSCAlignmentRcd.CRAFT09.hardware-globalMuons_3XY.v4.offline.RELTOIDEAL.xml  
.../CSCAlignmentRcd.CRAFT09.hardware-globalMuons_3XY.v4.offline.RELTONONE.xml
```

- ▶ tags: only CSCAlignmentRcd, use ideal errors

- ▶ Corresponding tracker geometry: `HIPCenteredObject.db`

- ▶ updated Oct 30, 20:15 European time