



CSC Beam-Halo Alignment

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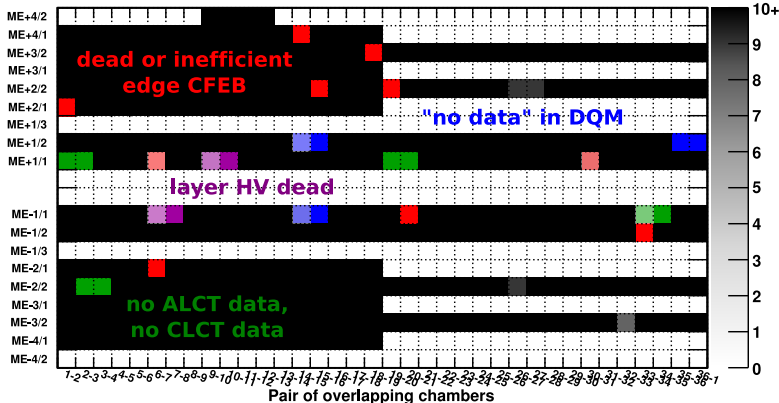
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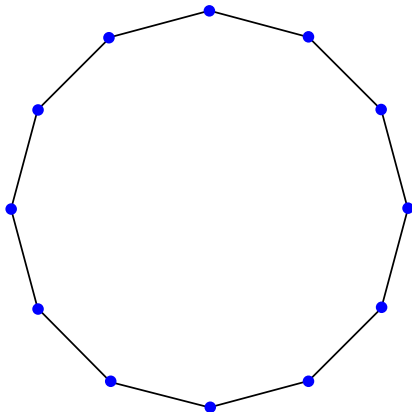
- ▶ Method to align all rings, not just complete ones
- ▶ Ring-radius corrections
- ▶ New constants
- ▶ Error analysis



- ▶ We can't rely on reading out data from all CSC edges
- ▶ Old procedure relied on complete rings for a full set of equations
- ▶ That left only 4 alignable rings— not acceptable

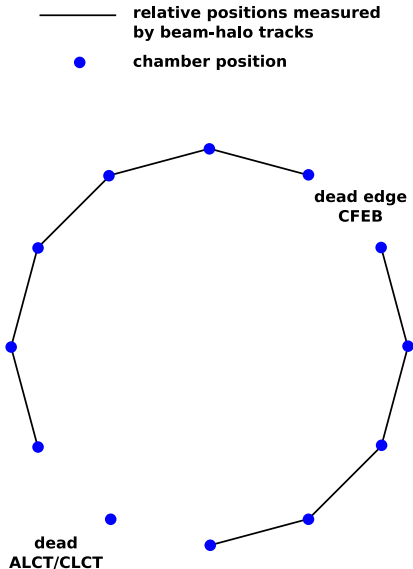


- relative positions measured
by beam-halo tracks
- chamber position



- ▶ Residuals relate chambers i and $i + 1$: for N chambers, that's N equations
- ▶ Rotation angle of whole ring cannot be determined, so really only $N - 1$ independent equations
- ▶ Last constraint is closure:

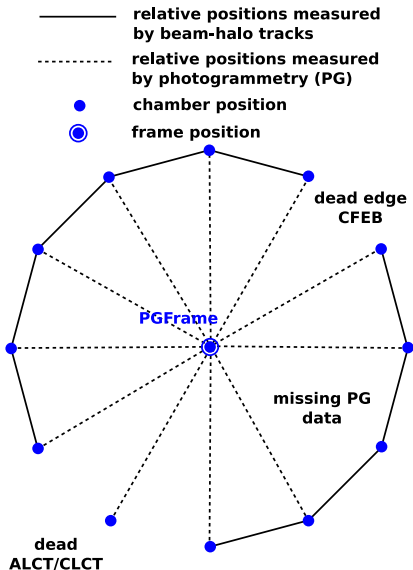
$$\frac{1}{N} \sum_i^N r_i \text{ should be zero}$$



- ▶ If one constraint is missing, we could fill in the information by *assuming* closure
- ▶ Problem: closure became non-zero when the field was turned on (will revisit later in this talk)
- ▶ Another problem: many rings had more than one missing constraint— system is underdetermined
- ▶ However, in complete rings we find that photogrammetry (PG) is still accurate: can use PG as a new constraint

Mathematical framework

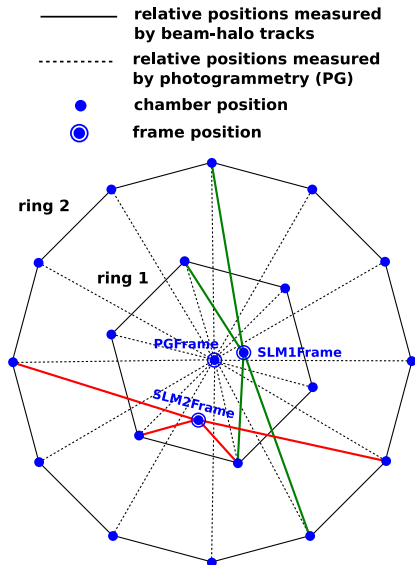
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- ▶ New framework to combine beam-halo and PG on an equal footing:
 - ▶ generalize equations to relate any i and j
 - ▶ PG measurements relate each chamber i with an external frame, a new chamber-like object
- ▶ Even with gaps in beam-halo and PG, the system is always constrained or overconstrained (graph is fully connected)

Mathematical framework

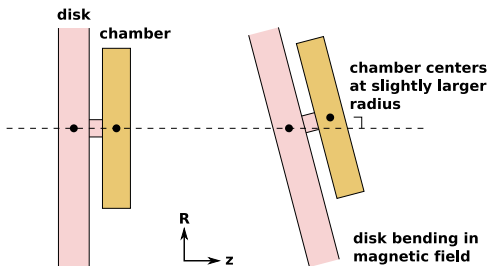
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- ▶ New framework to combine beam-halo and PG on an equal footing:
 - ▶ generalize equations to relate any i and j
 - ▶ PG measurements relate each chamber i with an external frame, a new chamber-like object
- ▶ Even with gaps in beam-halo and PG, the system is always constrained or overconstrained (graph is fully connected)
- ▶ Potential extension (not in this talk): SLMs also relate groups of chambers to frames; I made new software flexible enough to possibly include it



- ▶ Closure constraint in 2008 $\vec{B} = 0$ data uncovered detector width issue
- ▶ Shape of individual chambers has not changed (in reality and software)
- ▶ New data with full \vec{B} has non-zero closure, independent of momentum
- ▶ Non-zero closure is equivalent to either incorrect detector widths *or* incorrect ring radius
- ▶ Disk bending *does* change ring radius, since chamber centers are displaced in z from the disk: rotation is around a point outside the chamber





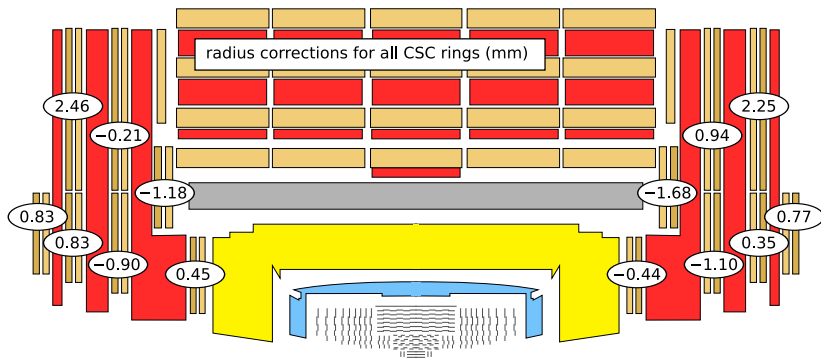
- ▶ Oleg did a back-of-the-envelope calculation and predicted that including this effect would account for half of the observed discrepancy
- ▶ Putting these numbers into the full reconstruction (accounting for the fact that even- and odd-numbered chambers have different length posts) yields Oleg's prediction

	2008 (no \vec{B})	2010 (full \vec{B})	corrected 2010
ME+3/1		+298 mm	+100 \pm 9 μm
ME-2/1	-40 \pm 23 μm		
ME-3/1	-20 \pm 28 μm	+486 mm	+278 \pm 9 μm
ME-3/2		+572 mm	+446 \pm 27 μm
ME-4/1		+440 mm	+267 \pm 10 μm

- ▶ We can calculate approximate closure of incomplete rings by averaging the residuals we do see:

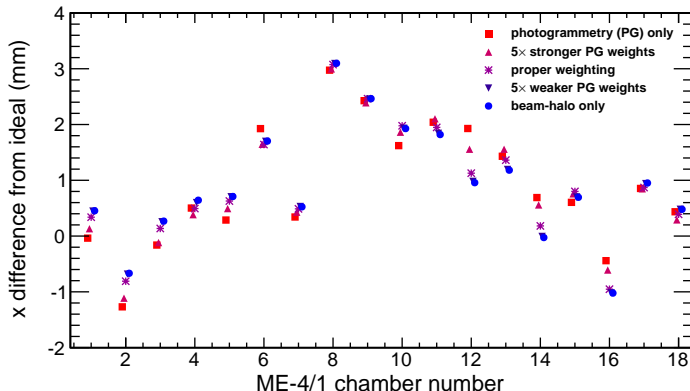
$$c = \frac{1}{N_{\text{visible}}} \sum_i^{N_{\text{visible}}} r_i \approx \frac{1}{N} \sum_i^N r_i \quad \Delta\text{radius} = \frac{c \times N}{2\pi}$$

- ▶ Pattern has a compelling symmetry/antisymmetry: strongly suggests a real effect (for which we don't have a complete model)





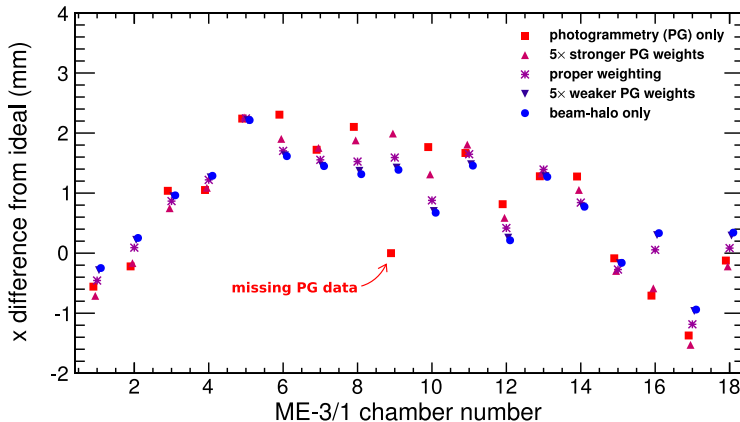
- If we apply the observed closures as *measurements* of ring radii, we can move on to align $r\phi$ and ϕ_z of all CSCs (except ME1/3)
- Let's look at some of the $r\phi$ alignment results, given the new radii



- Pure PG is not very far from pure beam-halo, but now we can align them in a combined fit (demonstrated by varying weights)

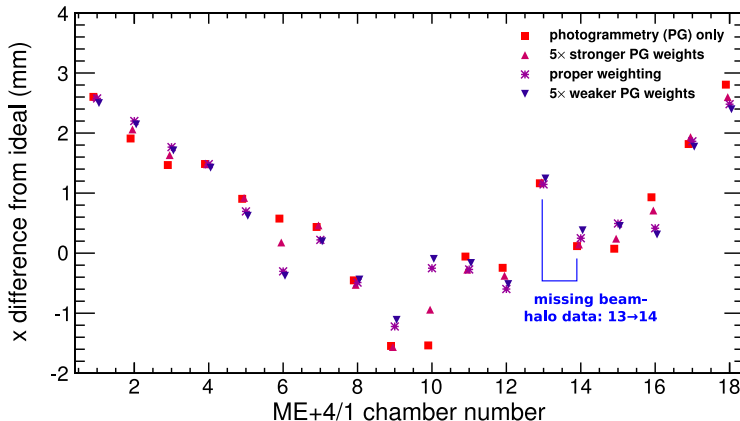


- ▶ Another example: this ring has incomplete PG
- ▶ Pure PG has no information about this chamber (set to ideal), but even strongly-weighted PG yields a reasonable value for the missing chamber because it is “filled in” by beam-halo data



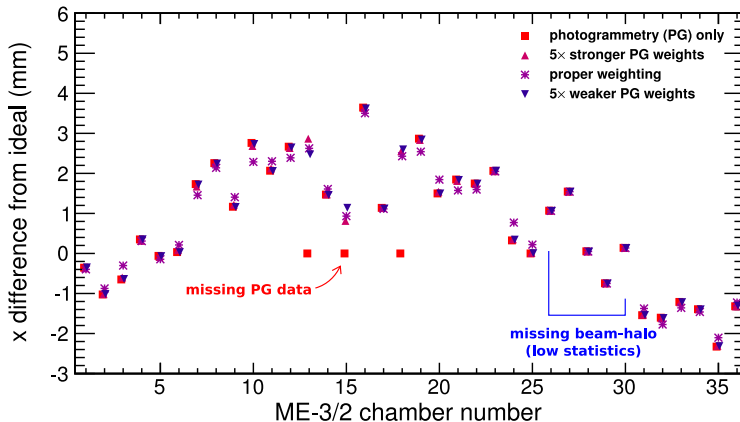


- ▶ This ring has incomplete beam-halo; system of equations cannot be solved without external information
- ▶ Even weakly-weighted PG yields a reasonable value for the missing overlap



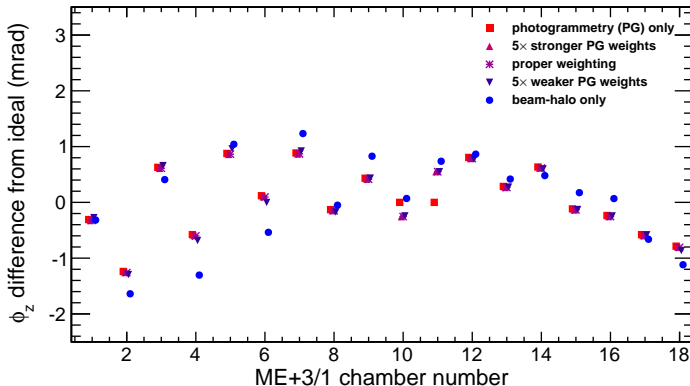


- ▶ An outer ring (low beam-halo statistics) with several missing chambers in a row: the relative positions of these are entirely determined by PG





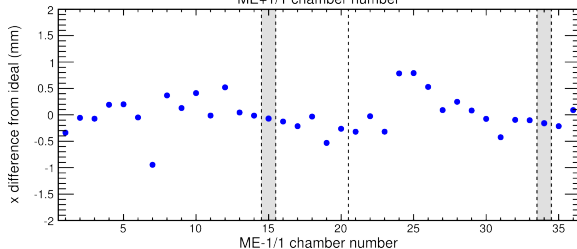
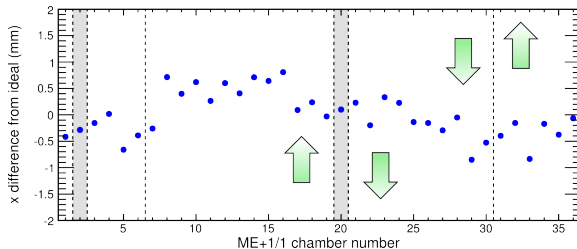
- ▶ Also works for ϕ_z rotation angle



- ▶ Two alignment parameters, $r\phi$ and ϕ_z , in addition to ring radii
 - ▶ third possible parameter, ϕ_y , is imprecise when measured with beam-halo (ideal geometry is more accurate, so leave as ideal)



- ▶ ME1/1 is a special case: no PG constraints available, and some chambers are missing (alignment graph is not fully connected)

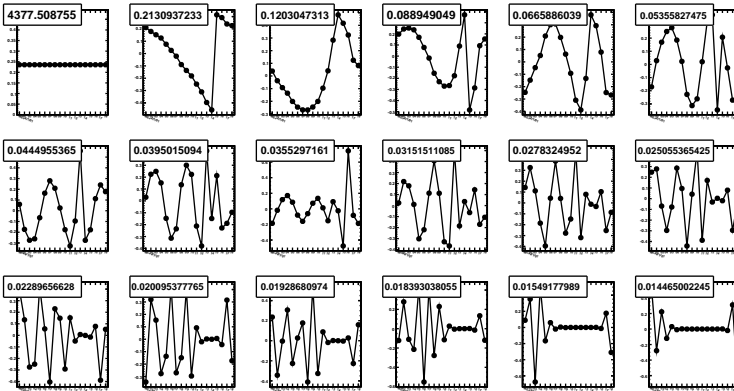


- ▶ Dashed lines indicate missing connections
- ▶ We can align the disconnected sections, but these sections will later need to be positioned relative to the tracker using globalMuons
- ▶ ME1/1 geometry is very nearly ideal



- ▶ What is the uncertainty in chamber positions?
- ▶ ... a complicated question because chamber uncertainties are highly correlated by the system of equations
- ▶ However, the equations can be represented as a matrix, and that matrix can be diagonalized to identify a basis of linearly-independent combinations of alignment parameters
- ▶ These are “modes”: modes with small uncertainties are strong modes, modes with large uncertainties are *weak modes*
- ▶ There are as many modes as there are chambers in the alignment

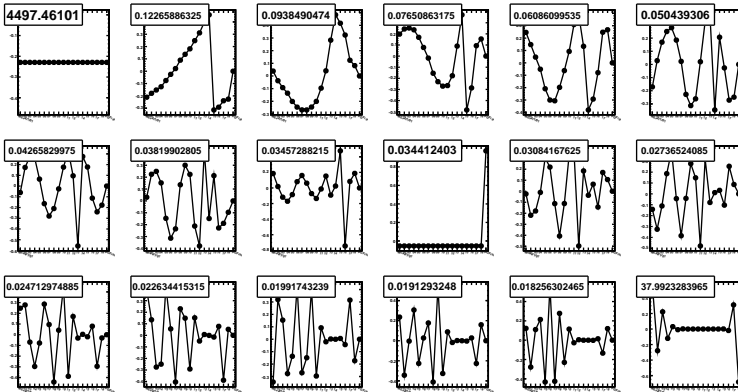
- Uncertainty in each mode (mm) for ME+4/1 with a plot of the mode as normalized eigenfunction versus chamber number



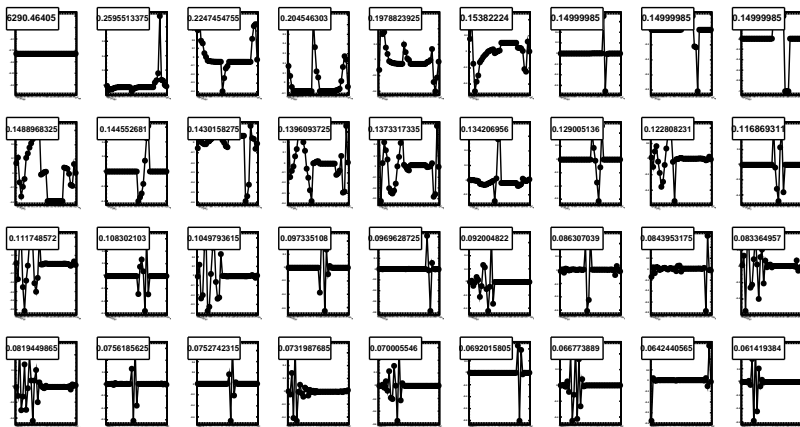
- First mode is uncertainty in the position of the whole ring, proportional to an arbitrary constant λ (set to a large number)
- Whole ring position (relative to tracker) requires external globalMuons



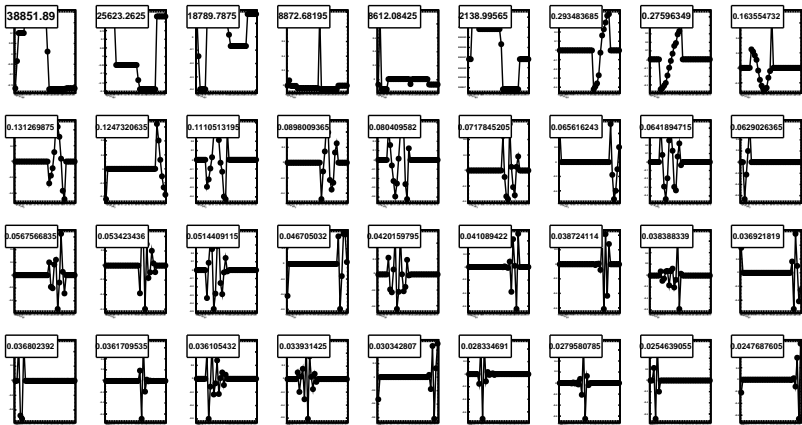
- Uncertainty in each mode (mm) for ME+4/1, this time with PG constraint: “PGFrame” is last point, right edge of plot window



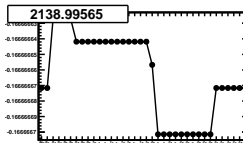
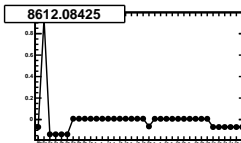
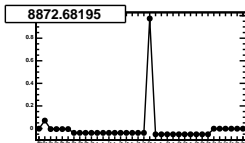
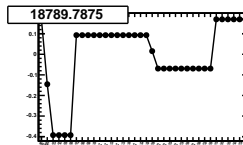
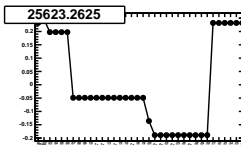
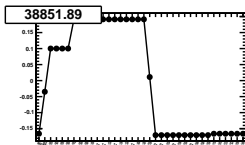
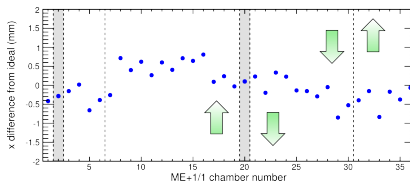
- ▶ A bigger example: ME+2/2
- ▶ The largest meaningful uncertainty is 0.26 mm



- ▶ The special case: ME+1/1
- ▶ The first 6 modes are proportional to λ , indicating separate sections



- ▶ Remember that ME1/1 has break-points with missing data (no PG and missing chambers for beam-halo)
- ▶ These modes describe arbitrary positions of each of the sections relative to the others: just a reminder that we'll need to align the sections as rigid bodies later





- Statistical uncertainties are in the range of a few hundred microns

ring	largest mode (mm)	sum in quadrature (mm)
ME+1/1	0.29	0.54
ME+1/2	0.20	0.60
ME+2/1	0.14	0.23
ME+2/2	0.26	0.76
ME+3/1	0.11	0.19
ME+3/2	0.24	0.70
ME+4/1	0.12	0.21
ME-1/1	0.47	0.79
ME-1/2	0.15	0.51
ME-2/1	0.13	0.21
ME-2/2	0.15	0.69
ME-3/1	0.09	0.18
ME-3/2	0.19	0.67
ME-4/1	0.10	0.18



- ▶ Missing chambers forced a re-formulation of beam-halo alignment
- ▶ Complete rings reveal that PG is still valid; use PG as a constraint
- ▶ Need to interpret non-zero closure as radial corrections, but they form a suggestive pattern in the two endcaps
- ▶ Beam-halo + PG combination has the right limits as weight of PG constraint is varied
- ▶ Statistical uncertainty in the result can be calculated by decomposing into modes (a few hundred microns)
- ▶ ME1/1 ring is incomplete, only aligned in sections
- ▶ Whole rings (and ME1/1 sections) will need to be aligned relative to the tracker with globalMuons; work on this using CRAFT-10 cosmics is underway, following same procedure as CRAFT-09