# Shaping the chameleon

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#### Abstract

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### 1 Introduction

#### 2 The model

The equations are

$$\nabla^2 \phi = -\frac{\Lambda^5}{\phi^2} + \frac{\rho}{M},\tag{2.1a}$$

$$\nabla^2 \Phi = -\rho \tag{2.1b}$$

We compute the forces due to the chameleon and gravitational scalars by taking their gradients:

$$\mathbf{F}_{(\phi)} = \nabla \phi, \qquad \mathbf{F}_{(\Phi)} = \nabla \Phi$$
 (2.2)

## 3 Numerical methods

- Solve (2.1a) via gradient flow; finite difference derivatives discretized to fourth order accuracy.
- Solve (2.1b) via SoR; discretized to second order accuracy.
- The forces (2.2) are computed with finite difference derivatives discretized to fourth order

## Acknowledgements

## A Schemes

SoR

$$Q_{i,j}^{n+1} = (1-\omega)Q_{i,j}^n + \frac{\omega}{4} \left[ Q_{i+1,j}^n + Q_{i-1,j}^{n+1} + Q_{i,j+1}^n + Q_{i,j-1}^{n+1} + h^2 \rho \right]$$
(A.1)

### $Fourth\ order\ finite\ difference\ derivatives$

$$\frac{\partial Q}{\partial x} \approx \frac{-Q_{i+2} + 8Q_{i+1} - 8Q_{i-1} + Q_{i-2}}{12h}$$
 (A.2)

$$\frac{\partial^2 Q}{\partial x^2} \approx \frac{-Q_{i+2} + 16Q_{i+1} - 30Q_i + 16Q_{i-1} - Q_{i-2}}{12h^2}$$
 (A.3)