# **CSE 30341 – Lecture 6**

**Scheduling - Proportional, Multiprocessor, Concurrency** 

February 2<sup>nd</sup>, 2023



### **Overview**

- Chapter 9 Proportional Scheduling
  - Probabilistic vs. Deterministic
- Chapter 10 Multiprocessor
  - Challenges
- Chapter 26 Introduction to Concurrency
  - Intro to pThreads / Vocabulary

### **Project 1**

#### Help / discussion on-line

Video / narration is posted

#### Recommendation

- Assume good arguments first
- Increase complexity after core

### If you have not started

- Have Level 1 functionality (assume good arguments) working by Thursday night
- Have Level 2 functionality working by Friday at 5 PM

### • Split - Partner

- One partner write the bit flip / reverse code
- One partner write the argument handling code

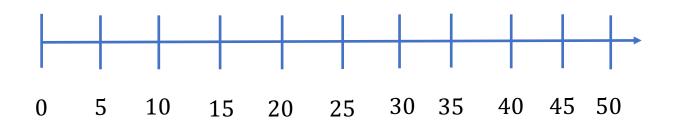


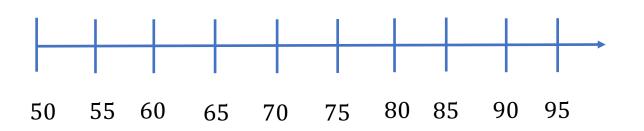
### **Key Points – Lecture 6 – Scheduling / Concurrency**

- Scheduling Chapter 8
  - Practice MLFQ
- Scheduling Chapters 9, 10
  - Describe **lottery** scheduling, **stride** scheduling
  - Compare / contrast: **deterministic**, **probabilistic**
  - Describe the challenges of multiprocessor scheduling
- **Concurrency** Chapter 26
  - Compare / contrast: thread, TCB, PCB.
  - What is a **race condition**?
  - What is a **critical section**?
  - What is **atomicity**?
  - What is **mutual exclusion**?

# Scheduling

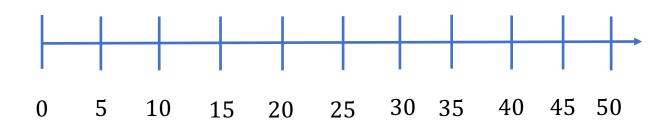
- Consider the following scenario
  - Four jobs  $P_0$  ..  $P_3$ 
    - $P_0 \rightarrow \{0, 30\}$
    - $P_1 \rightarrow \{10, 20\}$
    - $P_2 \rightarrow \{5, 30\}$
    - $P_3 \rightarrow \{30, 10\}$
  - What does the schedule look like?
    - STCF
  - Compute
    - Turnaround Time
    - Response Time





### **STCF**

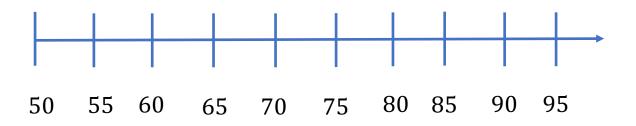
 $P_0 \rightarrow \{ 0, 30 \}$   $P_1 \rightarrow \{ 10, 20 \}$   $P_2 \rightarrow \{ 5, 30 \}$  $P_3 \rightarrow \{ 30, 10 \}$ 



Could you do this on an exam?

FIFO, SJF, STCF, RR?

Compute TT, RT?



### **MLFQ**

```
Slice = ??
Priority Levels = 3
```

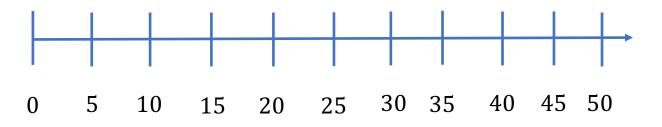
```
P_0 \rightarrow \{ 0, 30 \}

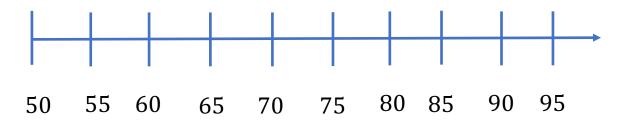
P_1 \rightarrow \{ 10, 20 \}

P_2 \rightarrow \{ 5, 30 \}

P_3 \rightarrow \{ 30, 10 \}
```

Boost (S) of 50





### Let's Do This

Slice = 5 Priority Levels = 3

 $P_0 \rightarrow \{ 0, 30 \}$   $P_1 \rightarrow \{ 10, 20 \}$   $P_2 \rightarrow \{ 5, 30 \}$  $P_3 \rightarrow \{ 30, 10 \}$ 

Boost (S) of 50

 $Q_0$ 

 $Q_1$ 

 $Q_2$ 

Working the example → separate recording

#### **Measure**

# Pre-emptions TT

# **Chapter 9 - Proportional Scheduling**

- Fairness
  - MLFQ?
- Two approaches
  - Lottery scheduling
    - Probabilistic
  - **Stride** scheduling
    - Deterministic

# **Lottery Scheduling**

- Tickets
- Probabilistic / Random
- Example
  - A = 75 tickets
  - B = 25 tickets

100 total tickets

75% chance to get picked25% chance to get picked

Over what time window is it fair?



Infinite window = Perfectly fair Short period = TBD

### **Code It**

```
// counter: used to track if we've found the winner yet
    int counter = 0;
    // winner: use some call to a random number generator to
               get a value, between 0 and the total # of tickets
    int winner = getrandom(0, totaltickets);
7
    // current: use this to walk through the list of jobs
    node_t *current = head;
10
    // loop until the sum of ticket values is > the winner
11
                                                                     Stop at the end of the linked list
    while (current) {
        counter = counter + current->tickets;
13
        if (counter > winner)
            break; // found the winner
15
        current = current->next;
16
17
    // 'current' is the winner: schedule it...
```

Figure 9.1: Lottery Scheduling Decision Code

### Example

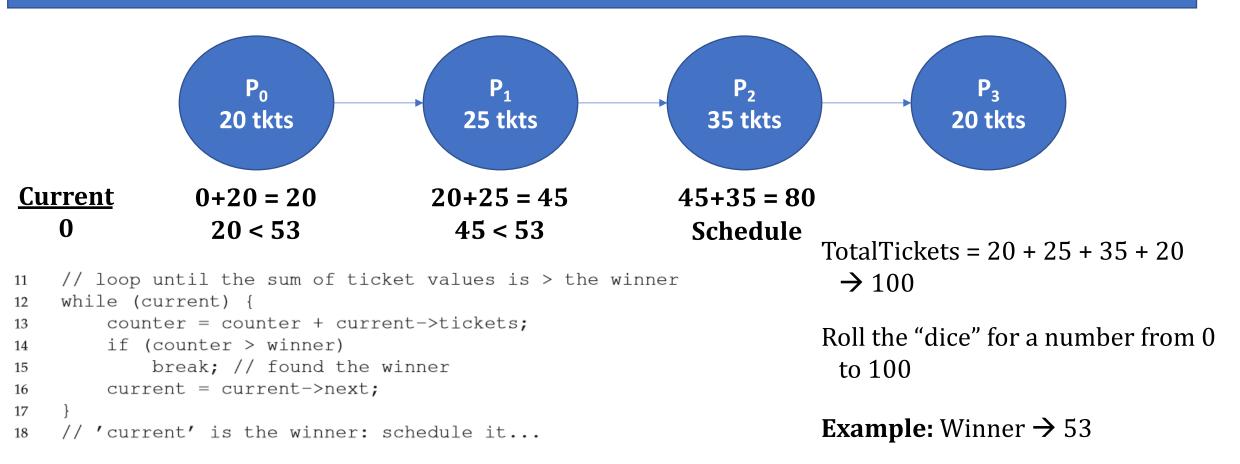


Figure 9.1: Lottery Scheduling Decision Code

# **Stride Scheduling**

- Deterministic vs. Probabilistic
- **Stride** vs. Tickets
  - Large # / Tickets = Stride
  - Pass -> Counter, Start at zero
  - Schedule / increment Pass
  - Use pass to prioritize

## Stride Scheduling – Example

P0  $\rightarrow$  100 tickets P1  $\rightarrow$  50 tickets

Use 1,000 for our "big number"

 $1000 / 100 \rightarrow 10$ P0 Stride

 $1000 / 50 \rightarrow 20$ P1 Stride

$$P0.Pass = 0, P1.Pass = 0$$

Pick Min of  $[0, 0] \rightarrow P0$ P0.Pass = P0.Pass + P0.Stride 0 + 10 = 10

Pick Min of  $[10, 0] \rightarrow P1$ P1.Pass = P1.Pass + P1.Stride 0 + 20 = 20

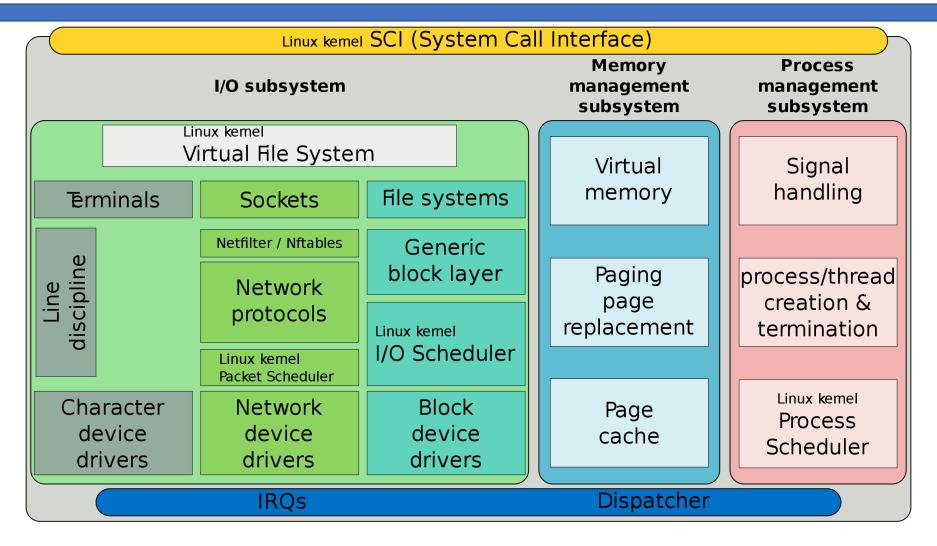
Pick Min of  $[10, 20] \rightarrow P0$ P0.Pass = P0.Pass + P0.Stride 10 + 10 = 20

Pick Min of  $[20, 20] \rightarrow P0$ P0.Pass = P0.Pass + P0.Stride 20 + 10 = 30

# **Takeaways**

- Random is not always bad
  - Better than you think
- Random draws -> not free
  - Magic to generate random numbers
- Deterministic
  - Worse can be way, way worse
  - Better if we can manage it

### Linux - CFS - Completely Fair Scheduler



### Linux - CFS - Completely Fair Scheduler

#### Introduced in 2007

Each per-CPU run-queue of type cfs\_rq sorts sched\_entity structures in a time-ordered fashion into a red-black tree (or 'rbtree' in Linux lingo), where the leftmost node is occupied by the entity that has received the least slice of execution time (which is saved in the vruntime field of the entity). The nodes are indexed by processor "execution time" in nanoseconds. [3]

A "maximum execution time" is also calculated for each process to represent the time the process would have expected to run on an "ideal processor". This is the time the process has been waiting to run, divided by the total number of processes.

When the scheduler is invoked to run a new process:

- 1. The leftmost node of the scheduling tree is chosen (as it will have the lowest spent *execution time*), and sent for execution.
- 2. If the process simply completes execution, it is removed from the system and scheduling tree.
- 3. If the process reaches its *maximum execution time* or is otherwise stopped (voluntarily or via interrupt) it is reinserted into the scheduling tree based on its newly spent *execution time*.
- 4. The new leftmost node will then be selected from the tree, repeating the iteration.

### Linux - CFS

Con Kolivas's work with scheduling, most significantly his implementation of "fair scheduling" named Rotating Staircase

Deadline, inspired Ingo Molnár to develop his CFS, as a replacement for the earlier O(1) scheduler, crediting Kolivas in his announcement. CFS is an implementation of a well-studied, classic scheduling algorithm called weighted fair queuing. Originally invented for packet networks, fair queuing had been previously applied to CPU scheduling under the name stride scheduling. CFS is the first implementation of a fair queuing process scheduler widely used in a general-purpose operating system.



Stride = Deterministic selection

If your process does not run for its full "slice" the stride that gets added is proportional to its actual run duration

When your interactive process wakes up, it gets a higher priority.

## Chapter 10 – Multi-processor

- Multiprocessor / multicore challenges
  - Briefly cover now revisit later
  - Caching
  - Affinity
  - Locking
  - Consistency

# Caching

- Cache on each processor
  - Populated based on running code
    - Temporal locality
    - Spatial locality
  - What happens if we ignore this relationship?
- Issues
  - Coherence
  - Affinity

## **Affinity**

- SQMS
  - One queue multiple processors
  - Affinity
    - Run on same processor
- MQMS
  - Multiple queues multiple processors
  - Issue
    - Load balancing

### **Key Points – Lecture 6 – Scheduling**

- Scheduling Chapters 9, 10
  - Describe lottery scheduling, stride scheduling
  - Compare / contrast: deterministic, probabilistic
  - Describe the challenges of multiprocessor scheduling

### **Chapter 26 – Intro to Concurrency**

### Sharing

- **CPU** Discuss now
- Memory Discuss later

### Concept

- Thread
- Multi-Threaded
- Context Switch
- TCB
- PCB
- Thread-Local Storage

### Threads vs. Processes

#### Process

- Major unit of organization for a running program
- OS schedules a process
- Parallelism
  - Run multiple instances of the program
  - Fork / run multiple children
    - Each child has its own "independent" memory space

#### Threads

- Exist within a process
  - Allows for intra-process parallelism
  - Memory is shared amongst threads in a process

**Example:** Apache web server

**Example:** One thread to handle user input (scanf), another to wait for network data

### Pthread example code - What happens?

```
#include <stdio.h>
    #include <assert.h>
    #include <pthread.h>
    void *mythread(void *arg) {
        printf("%s\n", (char *) arg);
                                            void * is back!
        return NULL;
   int
    main(int argc, char *argv[]) {
        pthread_t p1, p2;
12
        int rc;
        printf("main: begin\n");
        rc = pthread_create(&p1, NULL, mythread, "A"); assert(rc == 0);
15
        rc = pthread_create(&p2, NULL, mythread, "B"); assert(rc == 0);
        // join waits for the threads to finish
        rc = pthread_join(p1, NULL); assert(rc == 0);
        rc = pthread_join(p2, NULL); assert(rc == 0);
        printf("main: end\n");
        return 0;
22
```

Figure 26.2: Simple Thread Creation Code (t0.c)

### Take it up a notch

```
#include <stdio.h>
    #include <pthread.h>
    #include "mythreads.h"
    static volatile int counter = 0;
                                           A nice, friendly global variable
    // mythread()
   // Simply adds 1 to counter repeatedly, in a loop
   // No, this is not how you would add 10,000,000 to
    // a counter, but it shows the problem nicely.
   void *
   mythread(void *arg)
16
       printf("%s: begin\n", (char *) arg);
        int i;
        for (i = 0; i < 1e7; i++) {
            counter = counter + 1;
        printf("%s: done\n", (char *) arg);
        return NULL;
```

static = local to this file only

**volatile** = Please do not optimize me compiler

Is volatile helpful for multi-threaded code?



### Take it up a notch

25

```
#include <stdio.h>
   #include <pthread.h>
    #include "mythreads.h"
    static volatile int counter = 0;
    //
    // mythread()
   // Simply adds 1 to counter repeatedly, in a loop
   // No, this is not how you would add 10,000,000 to
   // a counter, but it shows the problem nicely.
   void *
   mythread(void *arg)
16
       printf("%s: begin\n", (char *) arg);
        int i;
18
        for (i = 0; i < 1e7; i++) {
            counter = counter + 1;
20
        printf("%s: done\n", (char *) arg);
        return NULL;
23
```

Each thread should add 10M to the global variable counter

28

### Take it up a notch – Part 2

```
25
26
    // main()
28
    // Just launches two threads (pthread_create)
    // and then waits for them (pthread_join)
    //
31
    int
32
    main(int argc, char *argv[])
33
34
        pthread_t p1, p2;
35
        printf("main: begin (counter = %d) \n", counter);
36
        Pthread_create(&p1, NULL, mythread, "A");
37
        Pthread_create(&p2, NULL, mythread, "B");
38
39
        // join waits for the threads to finish
40
        Pthread_join(p1, NULL);
41
        Pthread_join(p2, NULL);
42
        printf("main: done with both (counter = %d) \n", counter);
43
        return 0;
44
45
```



Figure 26.6: Sharing Data: Uh Oh (t1.c)

### Take it up a notch - What happens?

```
#include <stdio.h>
    #include <pthread.h>
    #include "mythreads.h"
    static volatile int counter = 0;
    //
    // mythread()
   // Simply adds 1 to counter repeatedly, in a loop
   // No, this is not how you would add 10,000,000 to
   // a counter, but it shows the problem nicely.
   void *
   mythread(void *arg)
16
        printf("%s: begin\n", (char *) arg);
        int i;
        for (i = 0; i < 1e7; i++) {
            counter = counter + 1;
20
        printf("%s: done\n", (char *) arg);
        return NULL;
23
```

riegel

## Why?

- Shared data
  - Global or reference
- Scheduler variability
  - Who knows what runs when?
- Atomic operations
  - Test and set

```
% objdump -d main
the Tally = the Tally + 5;
/* alternatively */
the Tally += 5;
if (isLocked == 0)
   isLocked = 1;
   /* Do atomic operation */
   isLocked = 0;
```

### **Assembly Decomposition**

```
theTally = theTally + 5;

/* alternatively */
theTally += 5;

if (isLocked == 0)
{
   isLocked = 1;
   /* Do atomic operation */
   isLocked = 0;
}
```

### Vocabulary

- Concurrency
  - Critical section
  - Race Condition
  - Indeterminate program
  - Deterministic
  - Mutual exclusion
  - Deadlock

### **Key Points – Lecture 6 – Scheduling / Concurrency**

- Scheduling Chapter 8
  - Practice MLFQ
- Scheduling Chapters 9, 10
  - Describe lottery scheduling, stride scheduling
  - Compare / contrast: deterministic, probabilistic
  - Describe the challenges of multiprocessor scheduling
- Concurrency Chapter 26 (if time allows)
  - Compare / contrast: thread, TCB, PCB.
  - What is a race condition?
  - What is a critical section?
  - What is atomicity?
  - What is mutual exclusion?