

Computation and the Fly Brain

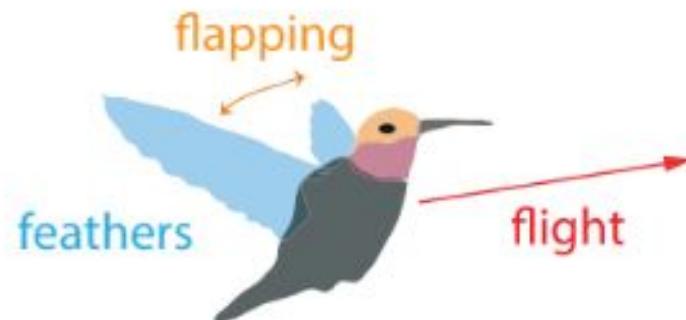
COMS 6998 Guest Lecture

10.3.2018

J. Portes jpp2139@



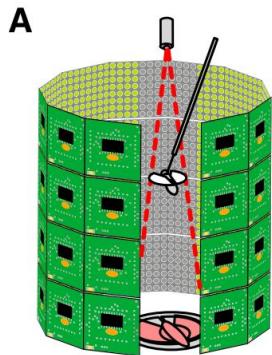
Marr's 3 Levels



Krakauer, John W., et al. "Neuroscience needs behavior: correcting a reductionist bias." *Neuron* 93.3 (2017): 480-490.

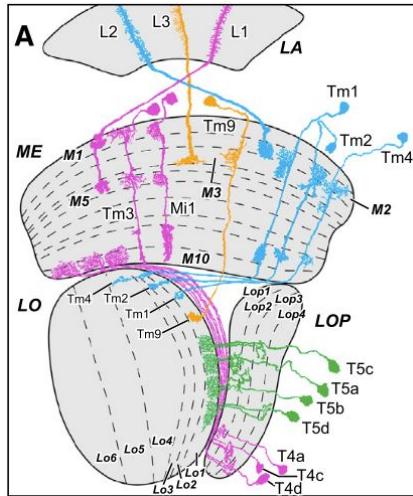
Why the Fly?

Behavioral Data



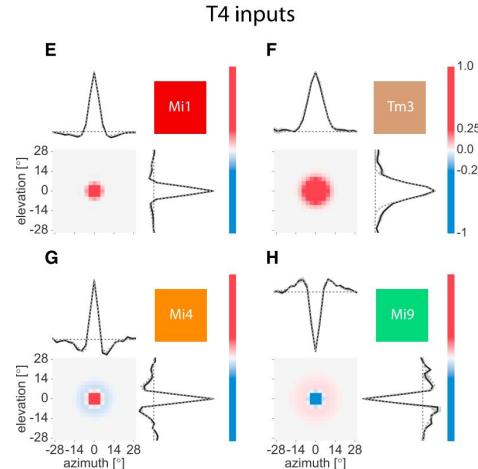
Tuthill et al. 2013

Anatomical Data



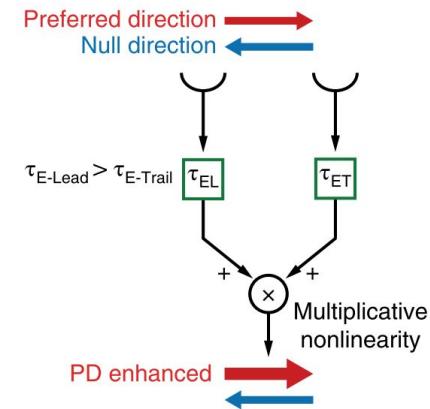
Shinomiya et al. 2014

Physiological Data



Arenz et al. 2017

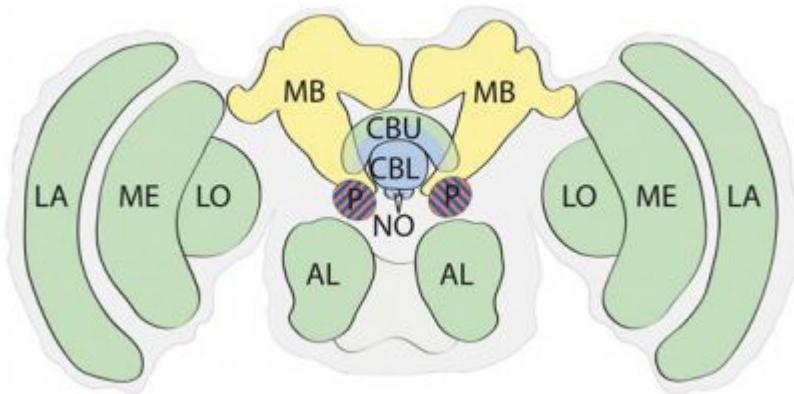
Conceptual Frameworks



Gruntman et al. 2018



~100,000 Neurons



Human

Fly Mouse



5cm

Fly Behavior - Aggression



https://www.youtube.com/watch?time_continue=1&v=gEh_y5GvH6A

Fly Behavior - Escape Behavior



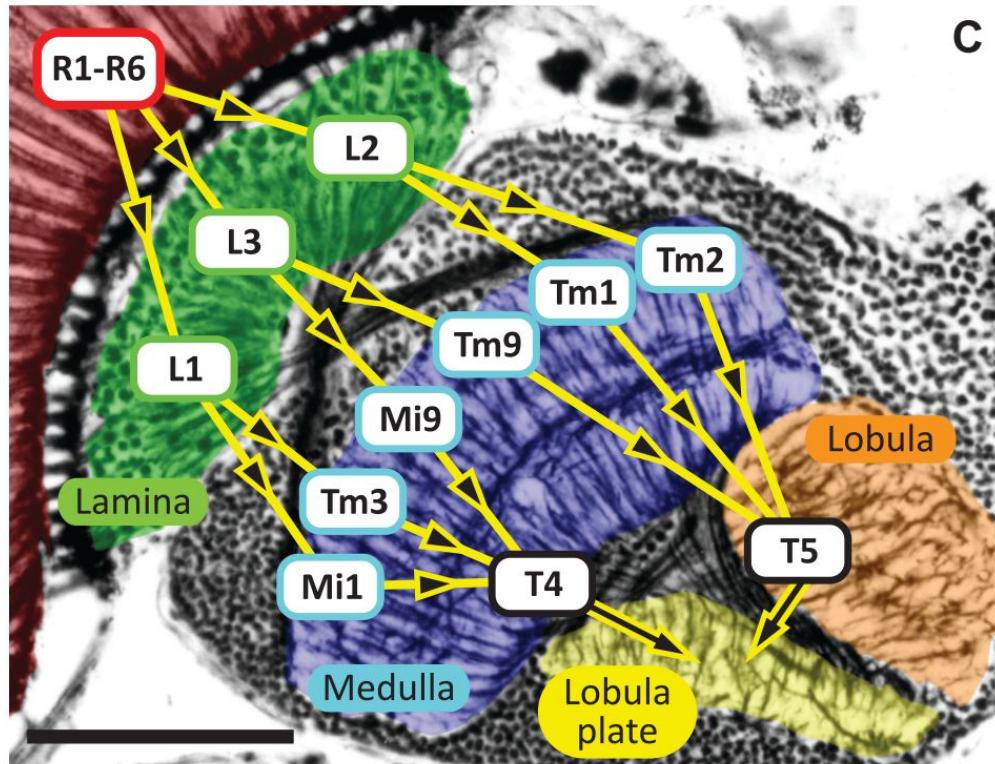
<https://www.youtube.com/watch?v=J-HmfRIe5xM>

Fly Behavior - Courtship

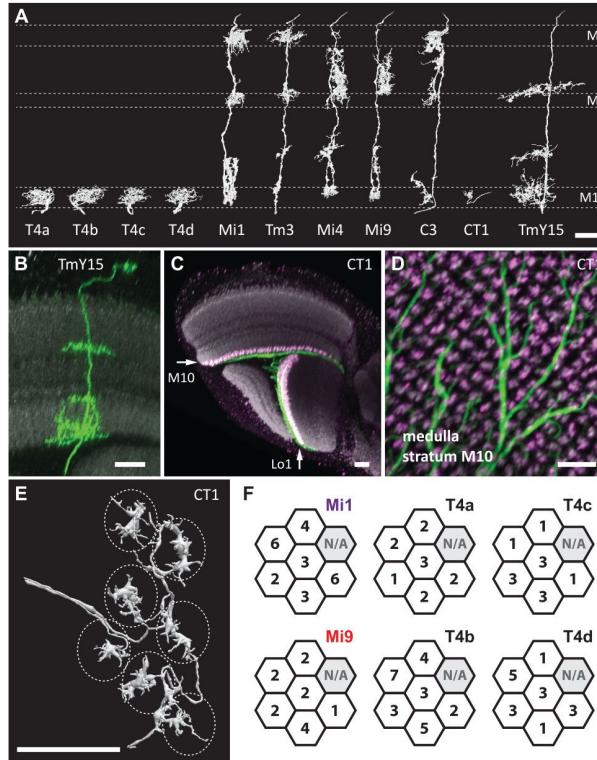


https://www.youtube.com/watch?time_continue=1&v=B-iK2D1mC10

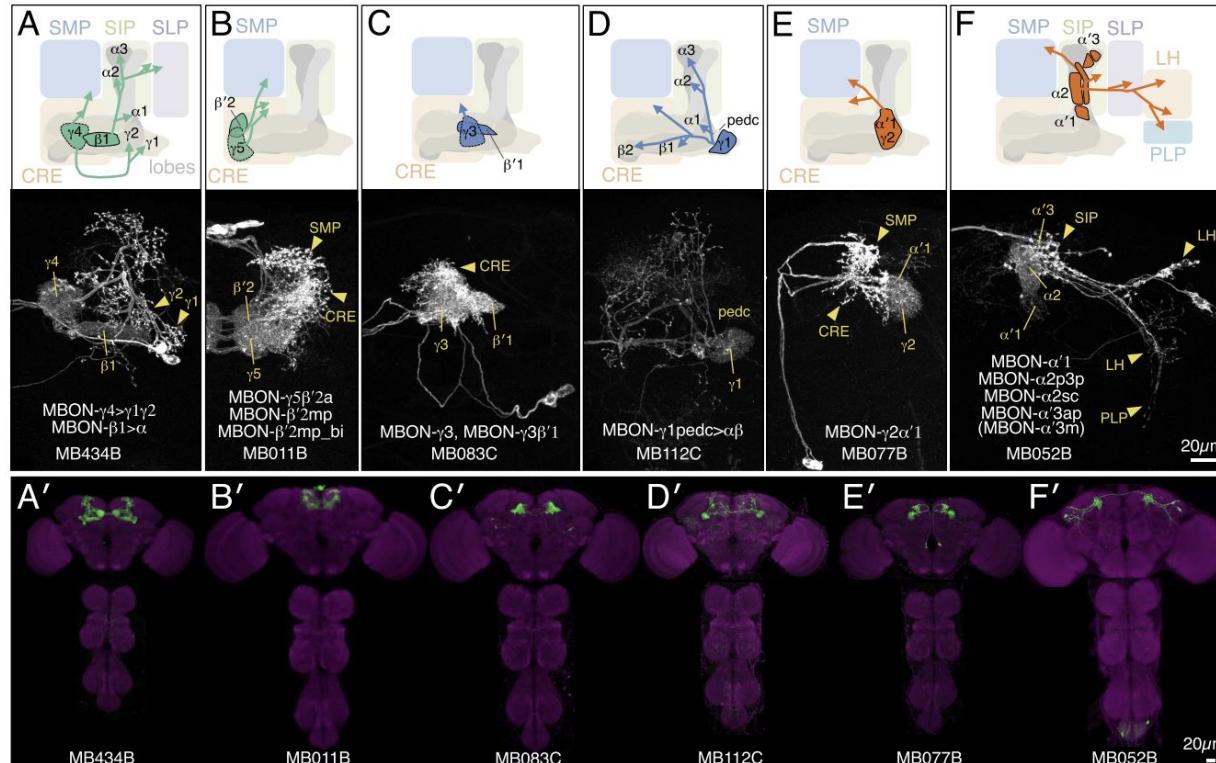
Fly Connectomics - The Visual System



Fly Connectomics - The Visual System



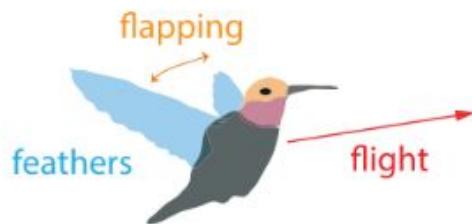
Fly Connectomics - The Mushroom Body



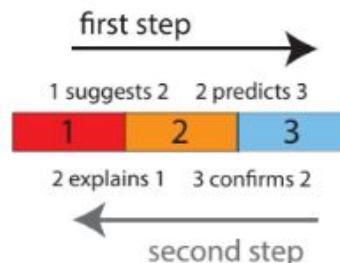
Aso, Yoshinori, et al. "The neuronal architecture of the mushroom body provides a logic for associative learning." *Elife* 3 (2014): e04577.

Marr's 3 Levels

A



B



C

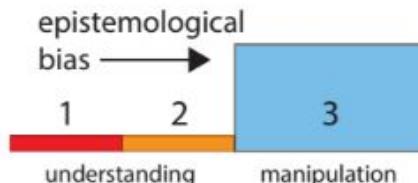


Figure 2. Marr's Three Levels of Analysis

(A) A bird attempts to fly (goal) by flapping its wings (algorithmic realization) whose aerodynamics depend on the features of its feathers (physical implementation). Feathers “have something to do” with flight and flapping, but what level of understanding do we achieve if we dissect the properties of the feathers alone? Bats fly but don’t have feathers, and birds can fly without flapping.

(B) The relationship between the three levels is not arbitrary; step 1 comes before step 2: the algorithmic level of understanding is essential to interpret its mechanistic implementation. Step 2: implementation level work feeds back to inform the algorithmic level.

(C) An epistemological bias toward manipulation-based view of understanding induced by technology (black filled arrow).

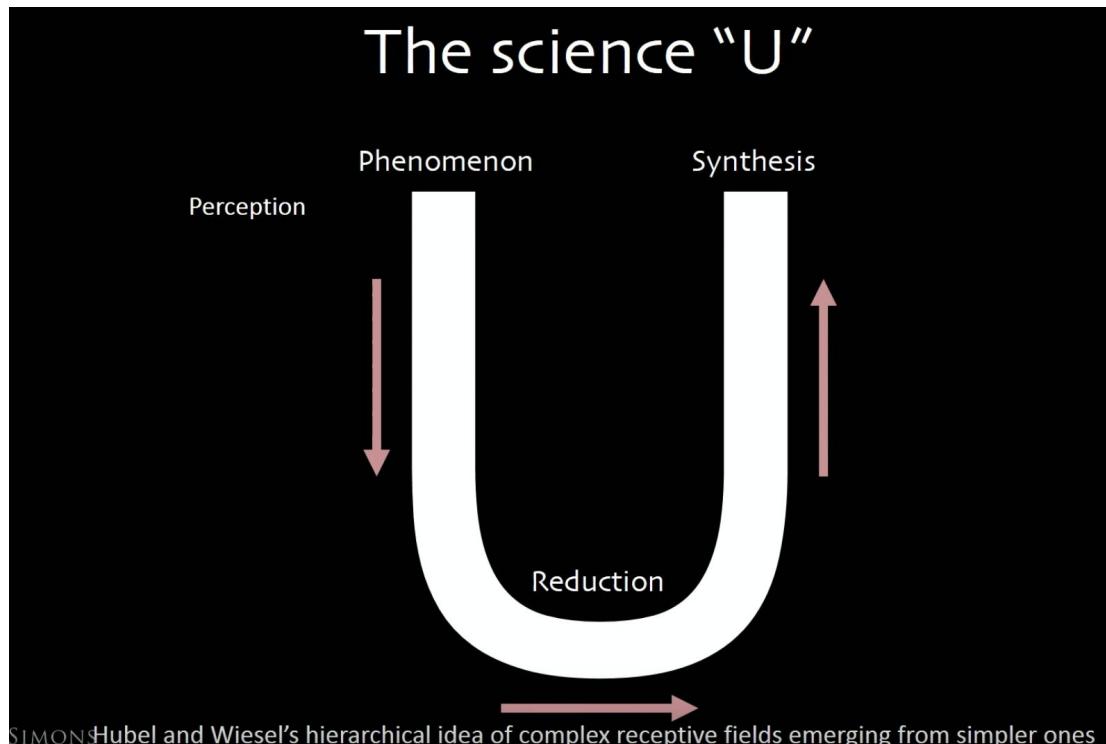
Outline - Canonical Computations in the Fly

1. Memory/Learning (MUSHROOM BODY)
 - a. Classical Conditioning
2. Navigation (CENTRAL COMPLEX)
 - a. Path Integration?
3. Vision (OPTIC LOBE)
 - a. Motion Detection
 - b. Optical Flow
 - c. Object Detection?

Goals for Lecture

- Convey basic algorithms
- Connect to HW4 → Lichtman Connectome Lectures (<https://www.youtube.com/watch?v=R2US2yVO4us&t=1s>)
- Possibly inspire ideas for class projects

Lichtman Lecture



<https://www.youtube.com/watch?v=R2US2yV04us&t=1s>

Fundamental Axioms of Neurobiology (Cajal's lasting influence)

- Neuron doctrine (n. is basic unit)
- Stereotyped cell types
- Law of dynamic polarization
- Canonical circuits

The Aspiration of Connectomics is to explore these fundamental axioms

- Goal to discover *all* the cell types (at least as manifested in variations in shape and connectivity)
- Goal to acquire complete *canonical circuits* at the level of synapses (as opposed to the hyper-sparse cartoons neuroscientists draw) to get physical instantiations of behaviors
- But might another goal be to *look* at the ultrastructural data per se to seek new biological regularities (rather than just use it to make a wiring diagram)?

In principle, c. is a bottom-up
approach; it shows what is there
physically in the brain
independent of what theories
exist.

Information and Understanding: the great complexity problem coming at us



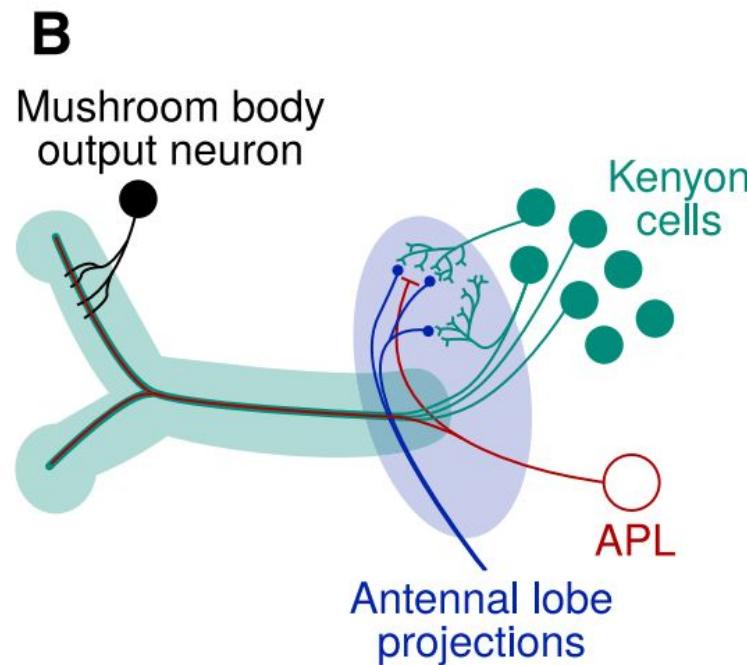
Biggest casualty of big data **maybe big ideas**

Totally
disagree

Outline - Canonical Computations in the Fly

- 1. Memory/Learning (MUSHROOM BODY)**
 - a. Classical Conditioning
- 2. Navigation (CENTRAL COMPLEX)**
 - a. Path Integration
- 3. Vision (OPTIC LOBE)**
 - a. Motion Detection
 - b. Optical Flow
 - c. Object Detection?

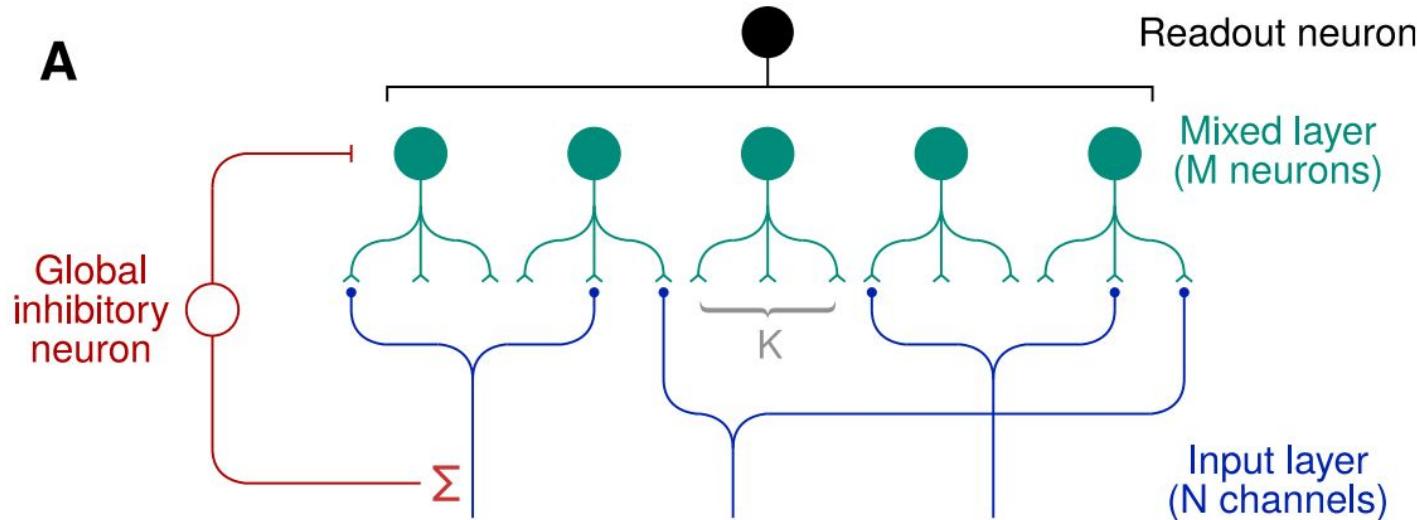
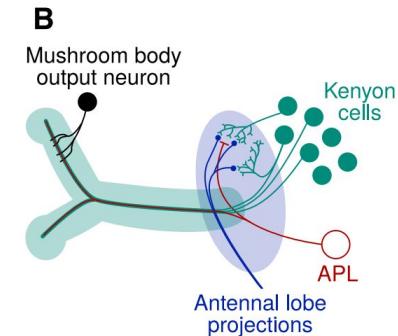
What does the Mushroom Body Do?



Litwin-Kumar, Ashok, et al. "Optimal degrees of synaptic connectivity." *Neuron* 93.5 (2017): 1153-1164.

Classical Conditioning

Mushroom Body as a site of plasticity and learning



Litwin-Kumar, Ashok, et al. "Optimal degrees of synaptic connectivity." *Neuron* 93.5 (2017): 1153-1164.

Outline - Canonical Computations in the Fly

- 1. Memory/Learning (MUSHROOM BODY)**
 - a. Classical Conditioning
- 2. Navigation (CENTRAL COMPLEX)**
 - a. Path Integration?
- 3. Vision (OPTIC LOBE)**
 - a. Motion Detection
 - b. Optical Flow
 - c. Object Detection?

Path integration – a network model

Thomas Wittmann, Helmut Schwegler

Zentrum für Kognitionswissenschaften, Institut für Theoretische Physik, Universität Bremen, D-28334 Bremen, Germany

Received: 25 April 1995 / Accepted in revised form: 30 May 1995

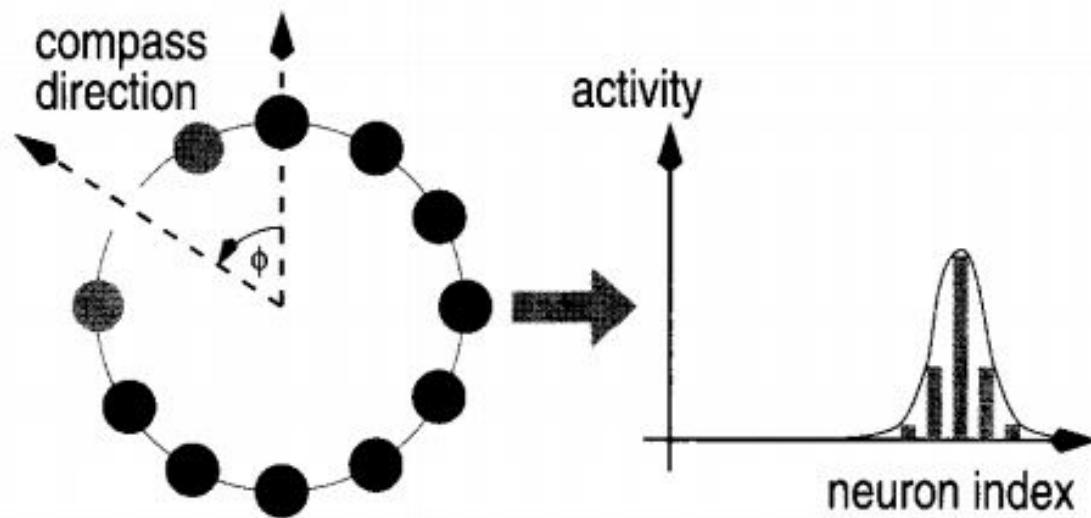


Fig. 3. Representation of compass direction as an activity pattern on a circular group of neurons

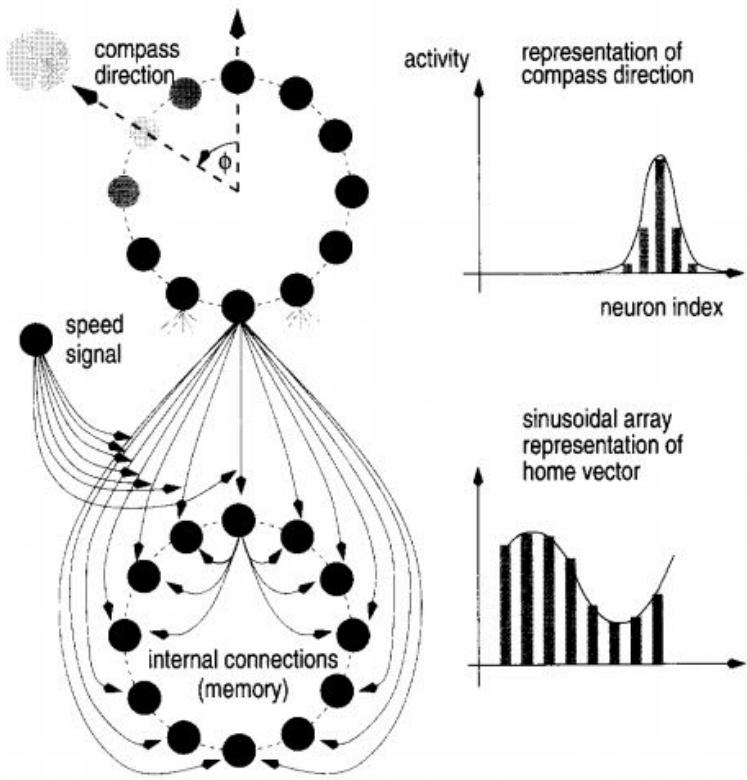


Fig. 4. Summary of the model. The compass direction is encoded as an activity pattern on a dedicated neuron group; this pattern is transformed into a sinusoidal array encoding by connections (8) and added to the vector computed so far. For consideration of speed the connections between both neuron groups have to be modulated by a speed signal

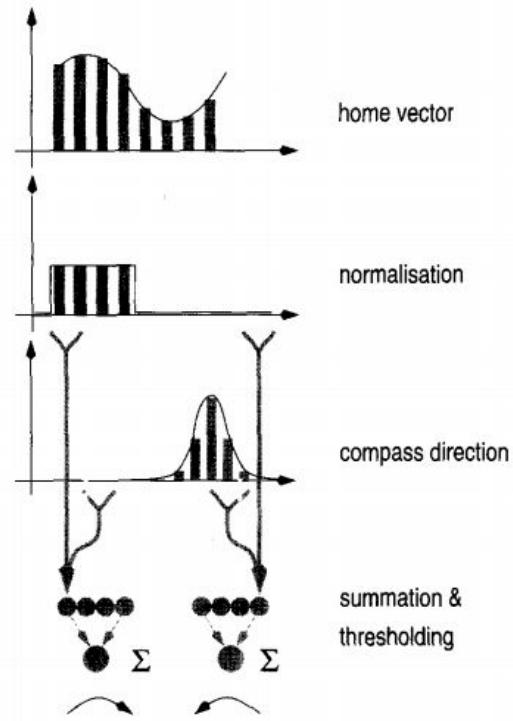
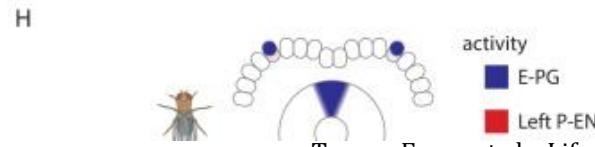
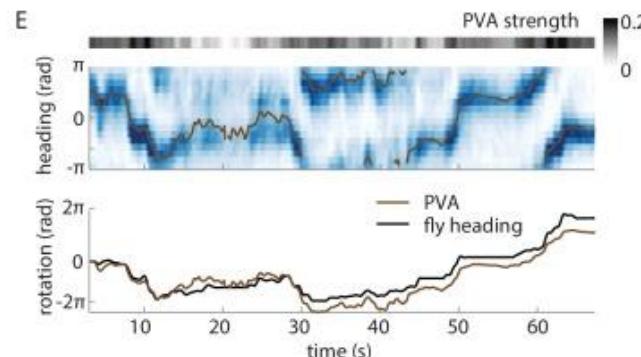
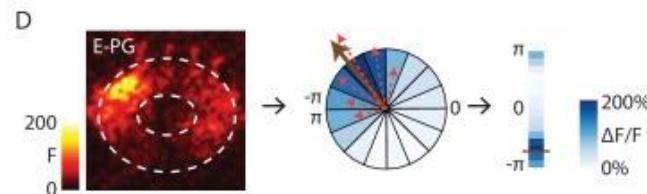
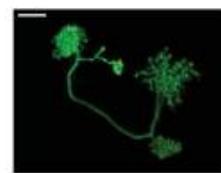
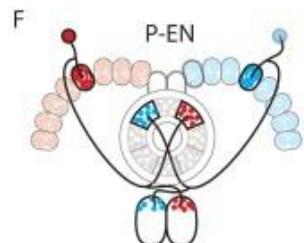
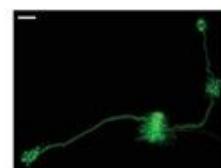
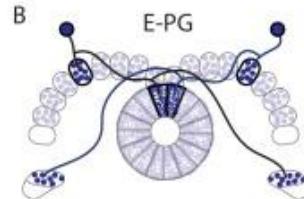
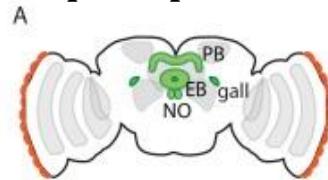


Fig. 5. Read-out mechanism. A turn signal that turns the animal into the homewards direction can be derived by comparison of the sinusoidal array representation of the home vector and the encoding of the compass direction; if the maxima of both patterns are at corresponding positions the animal is oriented homeward. A turn signal is generated by neurons that are sensitive to a certain displacement of the maximum on one neuron group with respect to the other

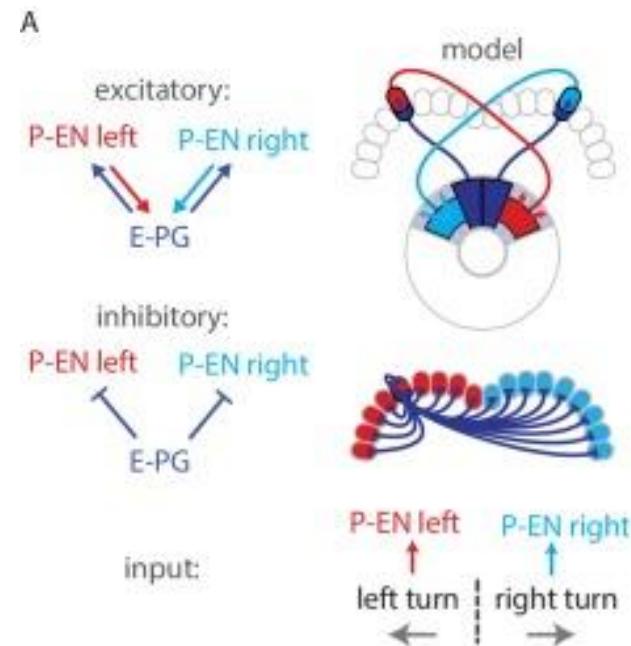
Fly Ring Attractor!

(although not quite path integration)



The Model (in words)

- Our model consists of **three populations** of neurons corresponding to the E-PG neurons, the P-EN neurons for the left side and the P-EN neurons for the right side.
- We assume that the **E-PG neurons make excitatory synapses onto the P-EN neurons** and that the **P-EN neurons, in turn, make excitatory synapses onto the E-PG neurons**.
- Finally, we assume **global inhibition**, a necessary requirement for obtaining localized bumps of activity.



The Model (in math)

$E(\theta, t)$: firing rate for E-PG neurons

$P(\theta, t)$: firing rate for P-EN neurons ($l = \text{left}$, $r = \text{right}$)

K : kernel describing connectivity in ellipsoid body
(circular!)

$$eq: model \tau \frac{dE(\theta_i, t)}{dt} = -E(\theta_i, t) + \left[\alpha \sum_{N(i)} P_l(\theta_{N(i)}, t) K_l(\theta_i - \theta_{N(i)}) \right]_+$$

$$\tau \frac{dE(\theta_j, t)}{dt} = -E(\theta_j, t) + \left[\alpha \sum_{N(j)} P_r(\theta_{N(j)}, t) K_r(\theta_j - \theta_{N(j)}) \right]_+$$

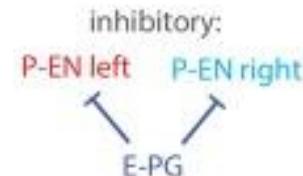
$$\tau_p \frac{dP_l(\theta_k, t)}{dt} = -P_l(\theta_k, t) + \left[\frac{\alpha}{3} \sum_{m \in \mathcal{N}_k^l} E(\theta_m, t) - \frac{\beta}{N} \sum_n E(\theta_n, t) + 1 + v_+ \right]_+$$

$$\tau_p \frac{dP_r(\theta_k, t)}{dt} = -P_r(\theta_k, t) + \left[\frac{\alpha}{3} \sum_{m \in \mathcal{N}_k^r} E(\theta_m, t) - \frac{\beta}{N} \sum_n E(\theta_n, t) + 1 + v_- \right]_+$$

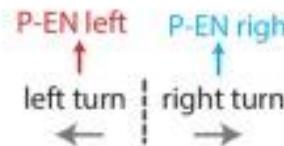
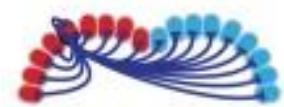
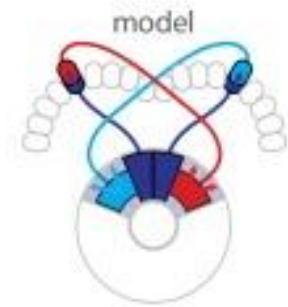
Local excitation

Global inhibition

A



input:

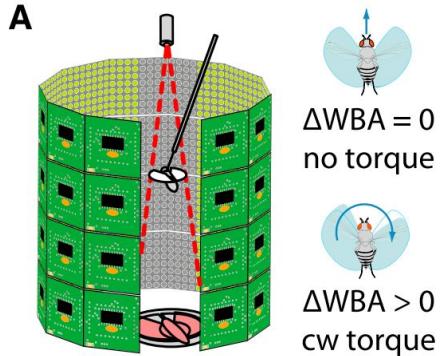


Outline - Canonical Computations in the Fly

- 1. Memory/Learning (MUSHROOM BODY)**
 - a. Classical Conditioning
- 2. Navigation (CENTRAL COMPLEX)**
 - a. Path Integration
- 3. Vision (OPTIC LOBE)**
 - a. Motion Detection
 - b. Optical Flow
 - c. Object Detection?

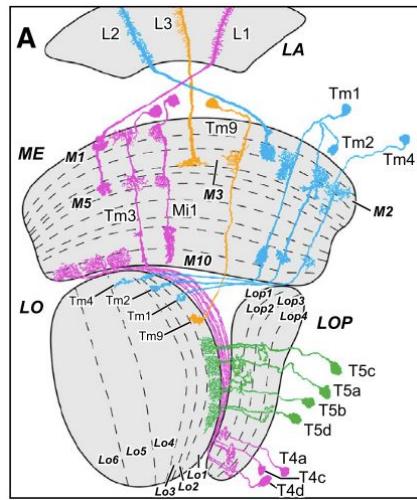
Fly Motion Detection: a well constrained, well defined problem...

Behavioral Data



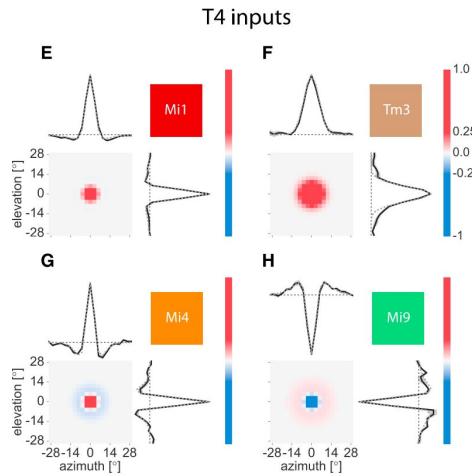
Tuthill et al. 2013

Anatomical Data



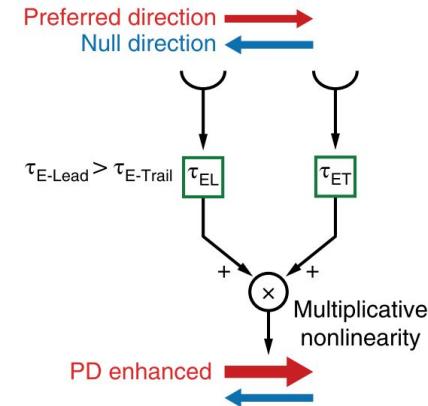
Shinomiya et al. 2014

Physiological Data



Arenz et al. 2017

Conceptual Frameworks



Gruntman et al. 2018

The Problem:

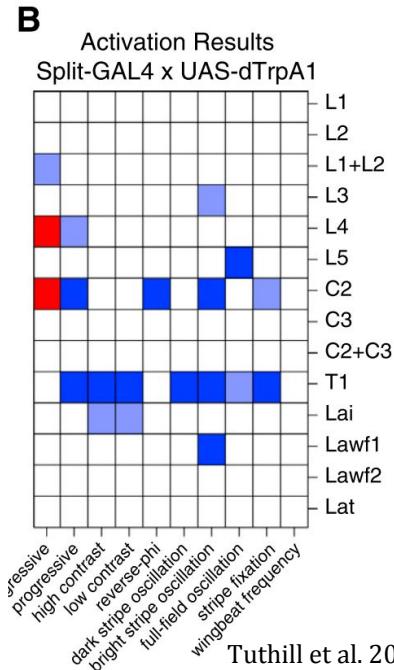
*“...Nevertheless, as a field, we cannot claim to have “**solved**” elementary motion detection. We cannot satisfactorily answer the question, **How do flies compute motion?** There exists no model that describes the elementary motion detection algorithm and its mechanistic implementation by **specific neurons, synapses, molecules, and circuits.**”*

Yang & Clandinin

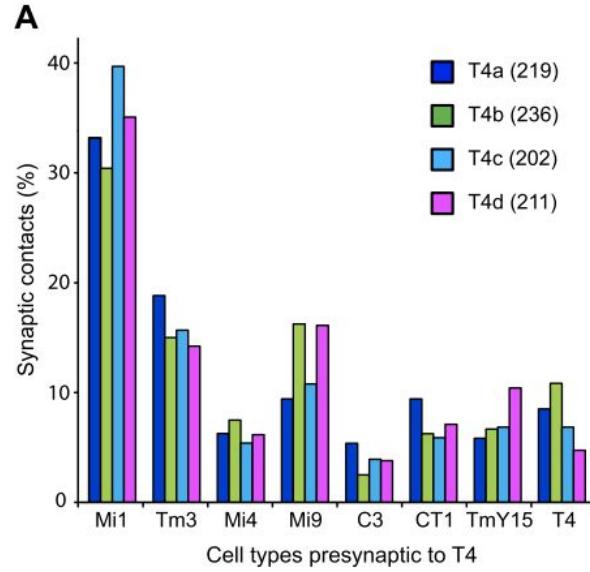
*Elementary Motion Detection in Drosophila:
Algorithms and Mechanisms (2018)*

Why?

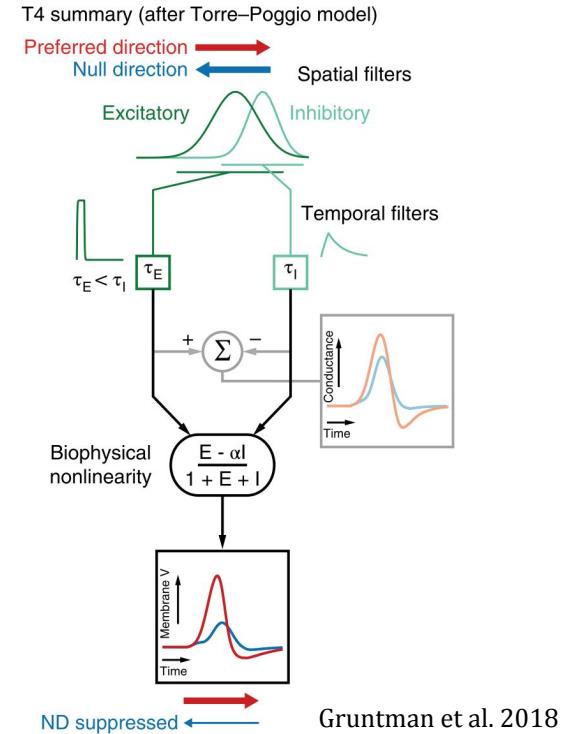
Some Data is hard to interpret/contradictory



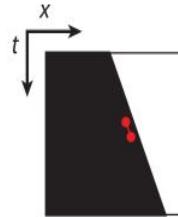
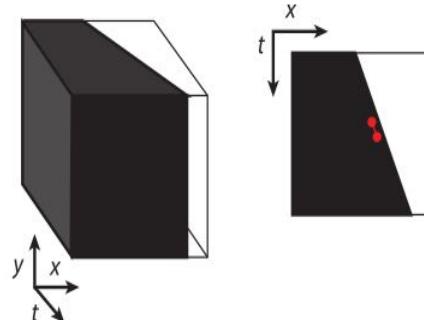
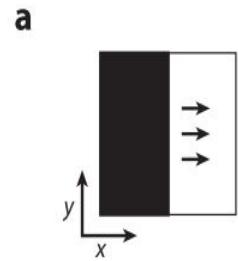
Some data is very new!



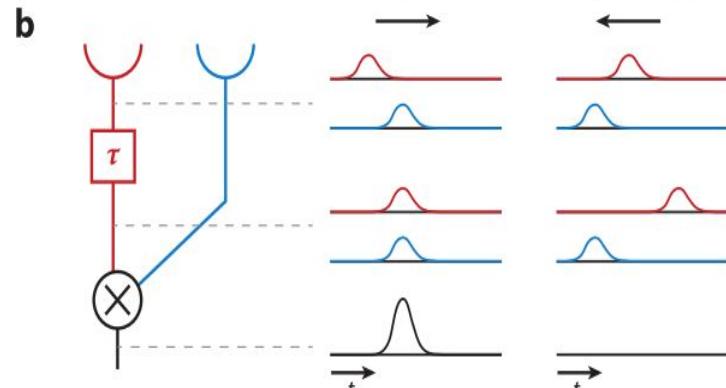
No consensus on models



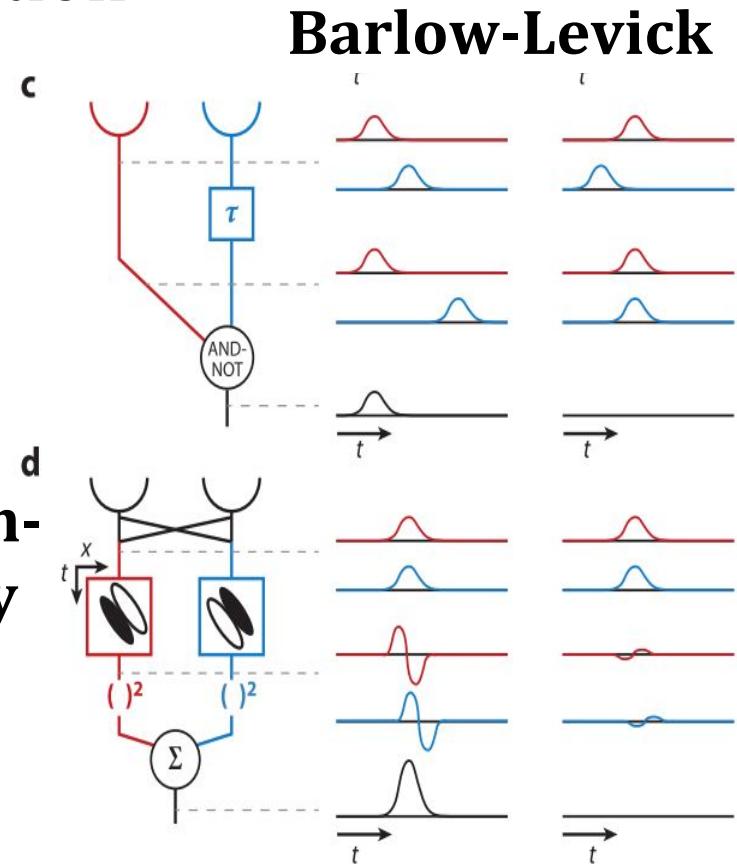
Simple Models for Motion Detection



HRC



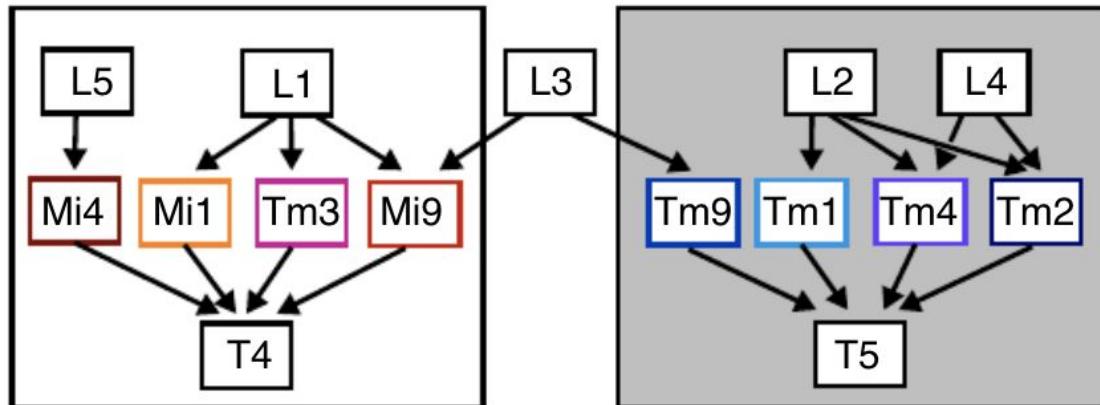
Motion-Energy



ON and OFF Pathways in the Fly

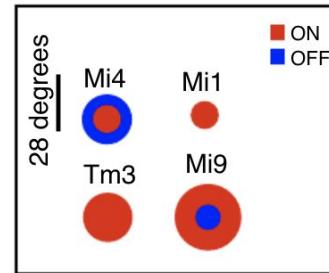
(e)

ON-OFF pathways
*Shinomiya, 2014; Serbe et al, 2016;
Takemura et al, 2017; Arenz et al, 2017*



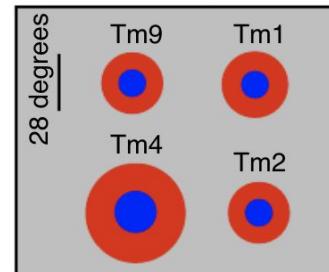
(f)

ON receptive fields
Arenz et al, 2017



(h)

OFF receptive fields
Arenz et al, 2017



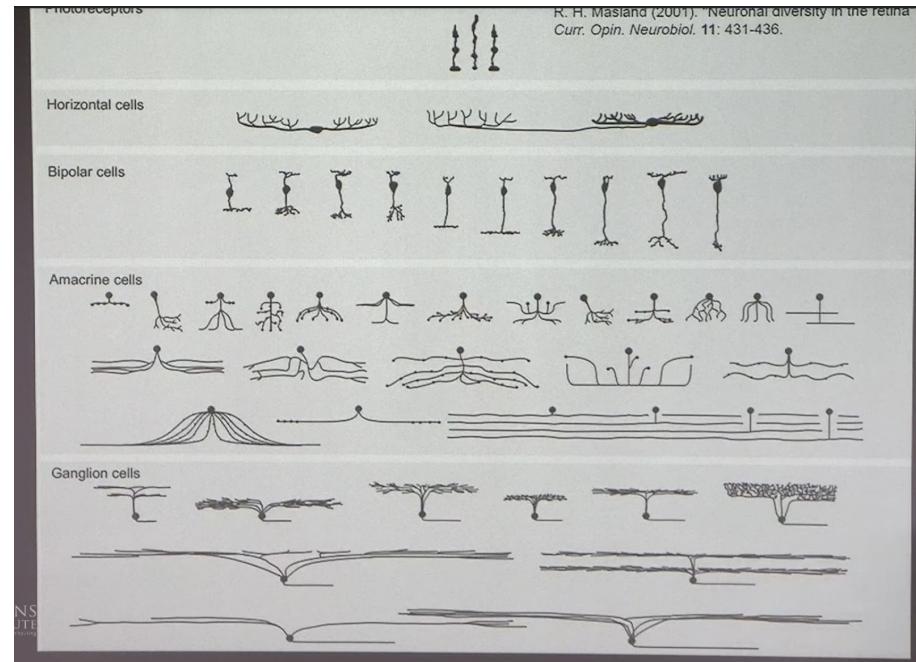
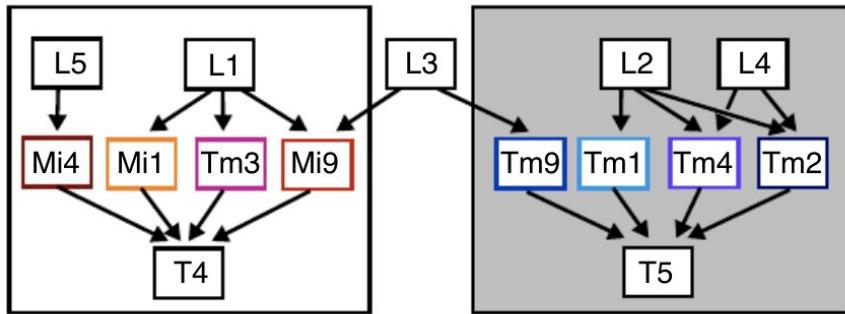
Current Opinion in Insect Science

Dyakova et al. 2017, Current Opinion in Insect Science

(e)

ON-OFF pathways

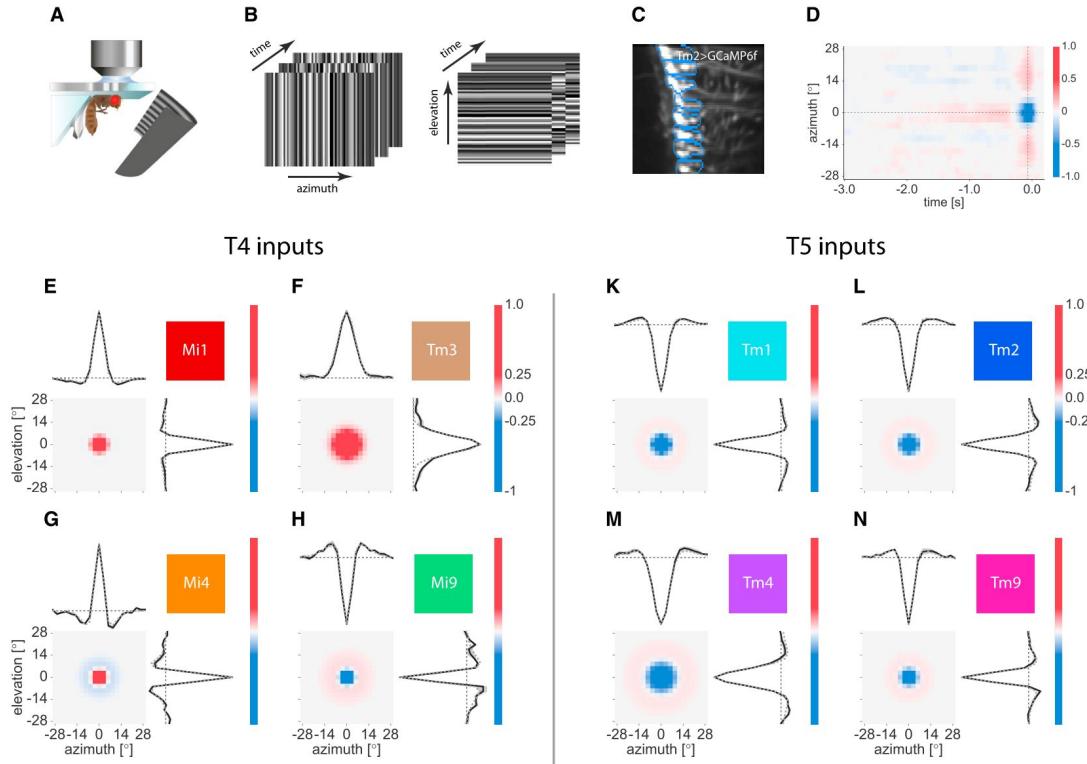
Shinomiya, 2014; Serbe et al, 2016;
Takemura et al, 2017; Arenz et al, 2017



<https://www.youtube.com/watch?v=R2US2yV04us&t=1>

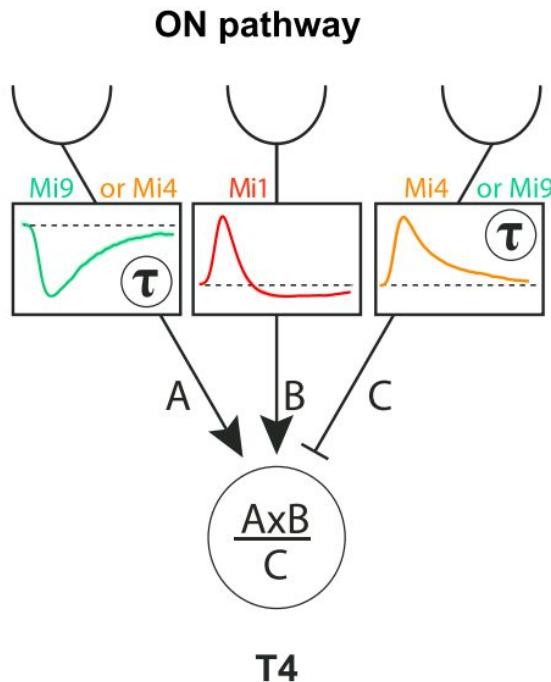
S

Functional Properties of Cells

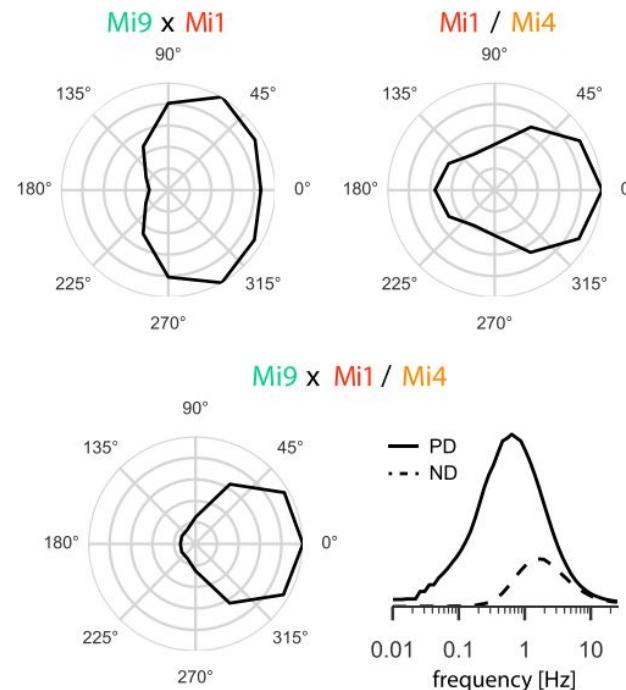


A Simple Model (HRC and BL inspired)

A



B

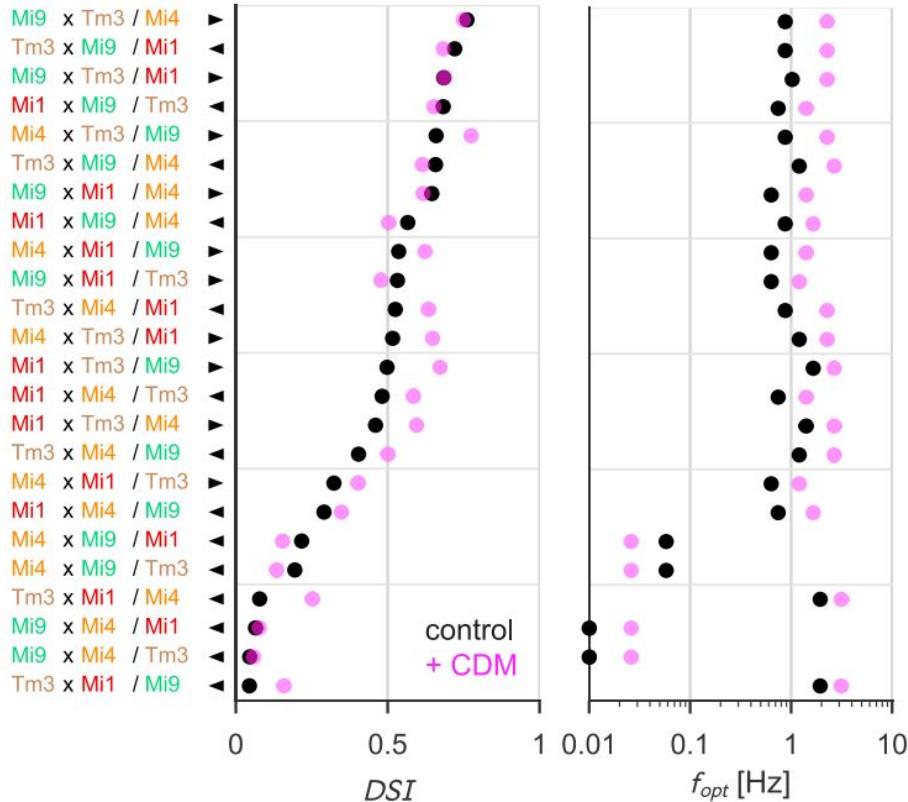


Model works with all
cell-type combinations...

*Is this a good model?
Or too simple?*

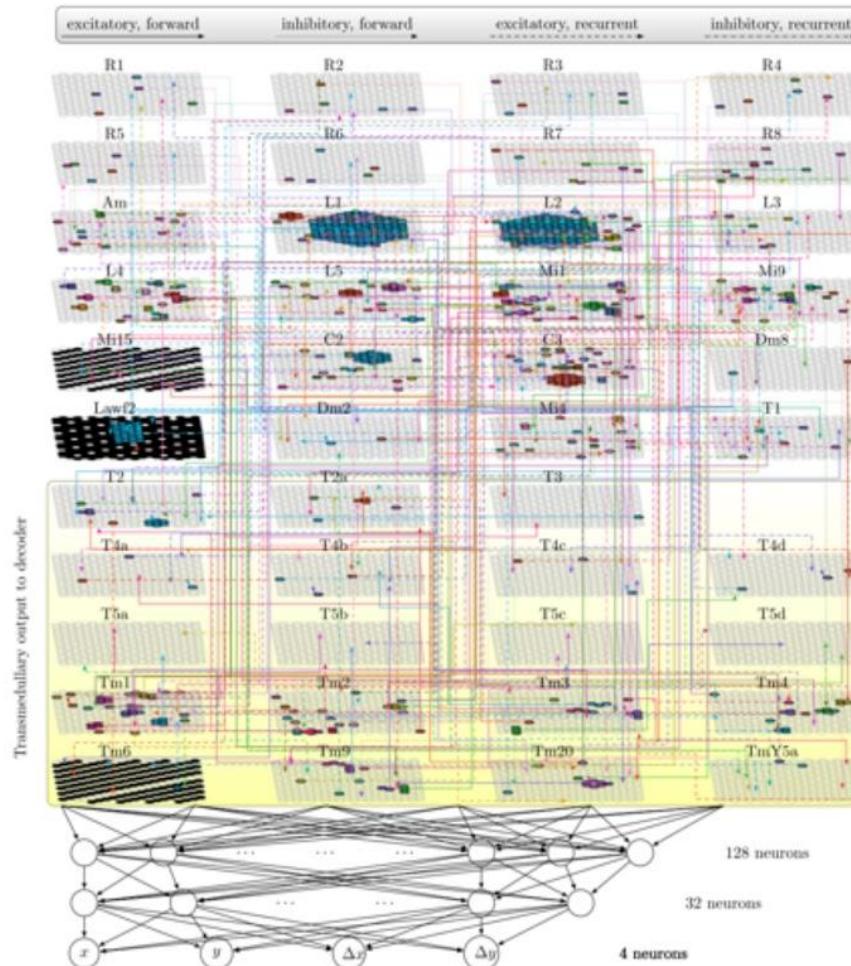
B

T4 pathway

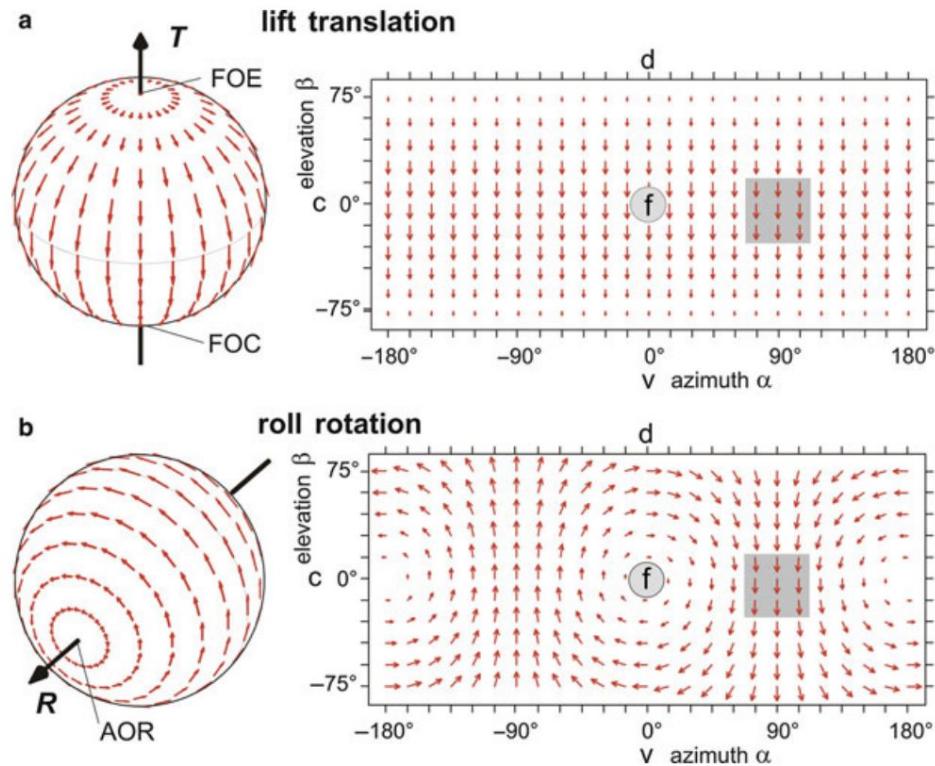


CNN-LSTM + Connectome Approach

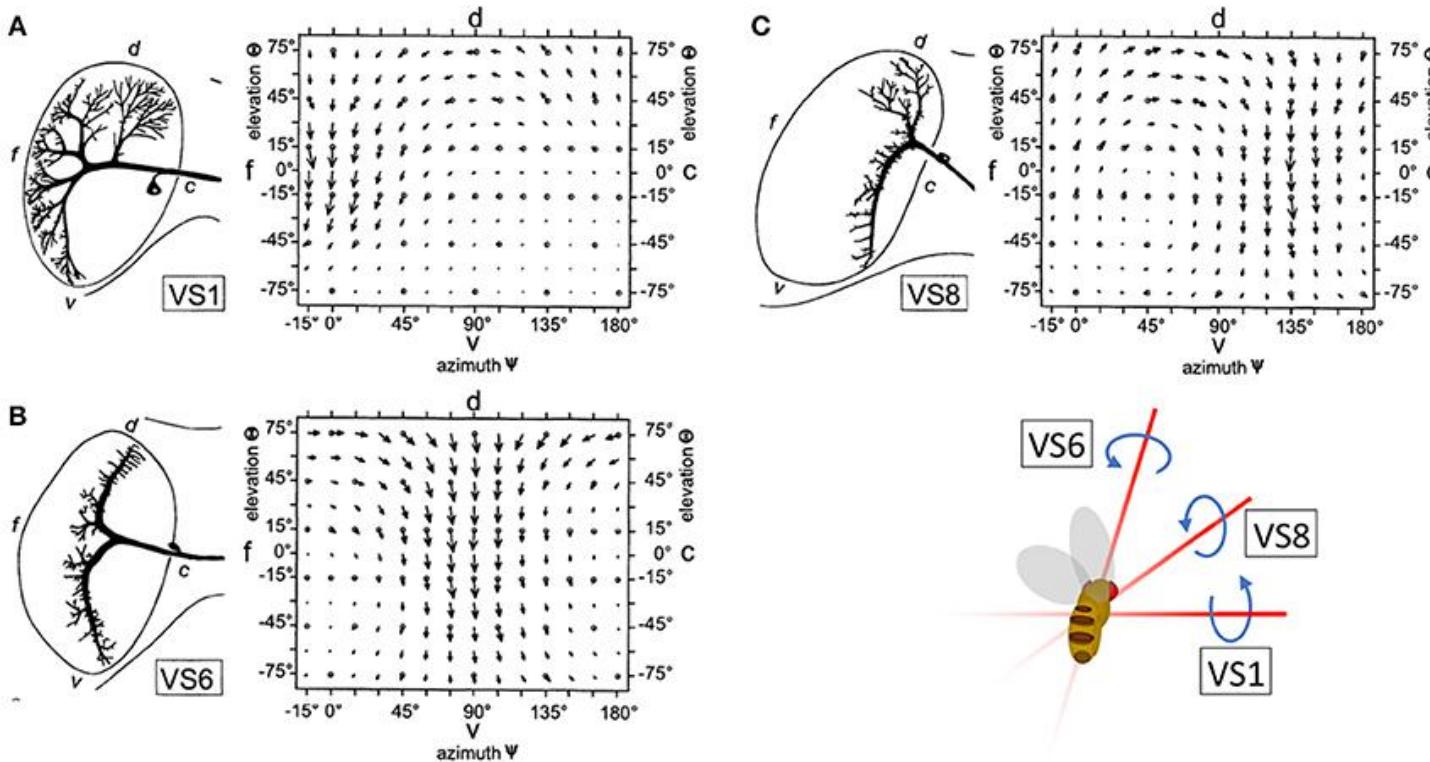
*Is this a good model?
Or too complicated?*



Optical Flow



Optical Flow Neurons in the Fly



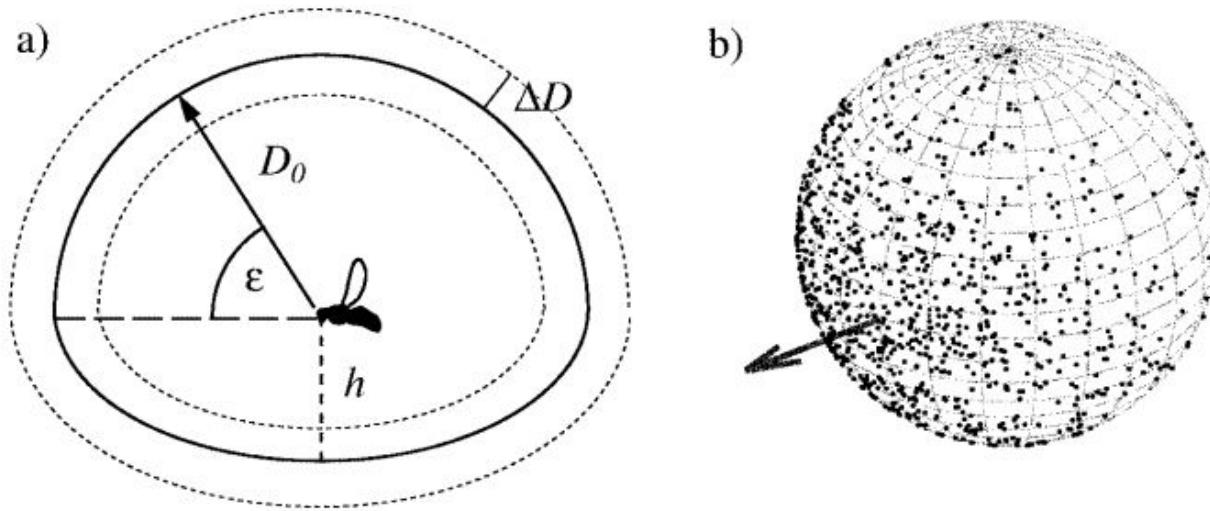
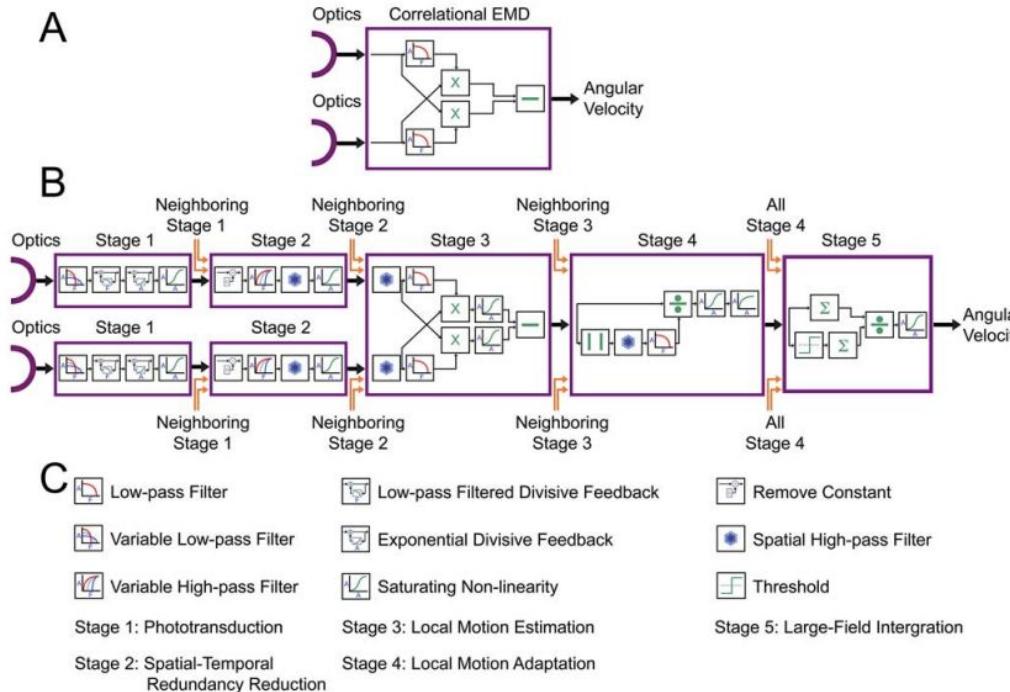
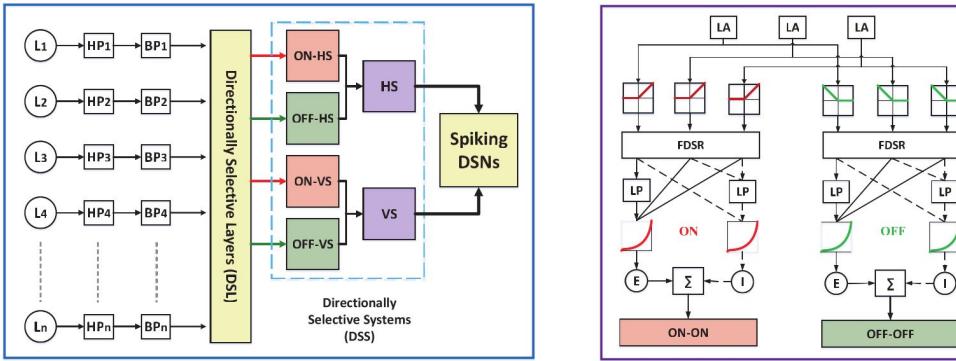


Fig. 5. Simplified “world model” of a blowfly flying at an average height h over ground. **a** Anisotropic distribution of the average distances in the visual field. The distance deviation ΔD is assumed to be independent of the viewing direction. **b** one thousand samples generated by the two-dimensional von Mises distribution of the translation directions. The *arrow* indicates the maximum of the distribution that is in the forward direction

Model of Optical Flow in the Fly (2009)

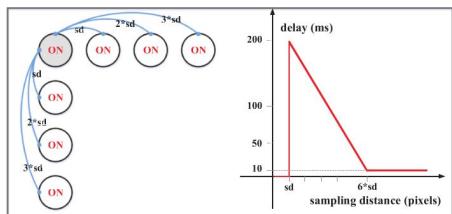


Model of Optical Flow in the Fly (2018) → still old school

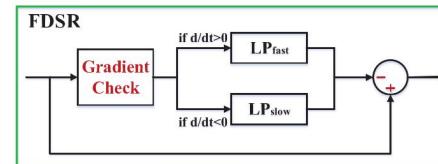


(a) a schema of DSNN

(b) a schema of DSL in DSNN

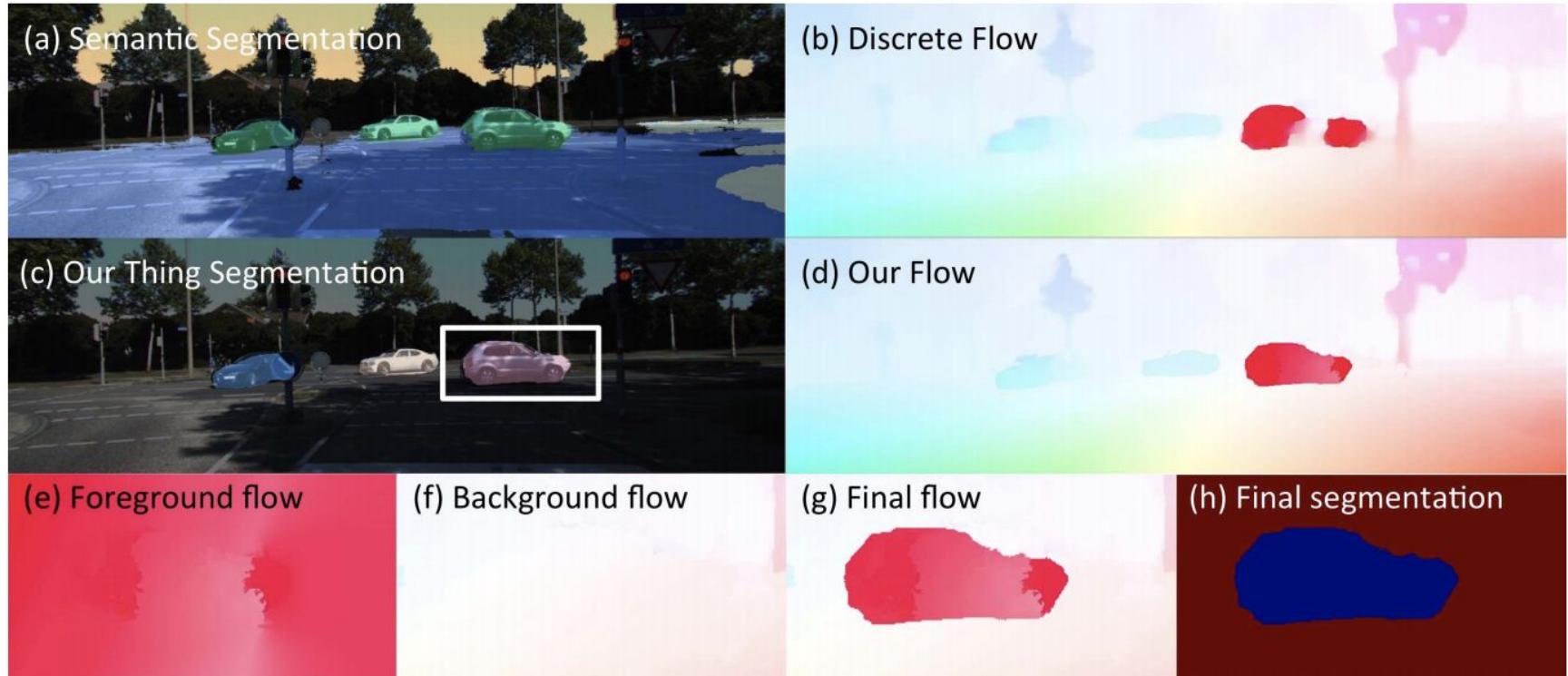


(c) spatiotemporal dynamics in DSL



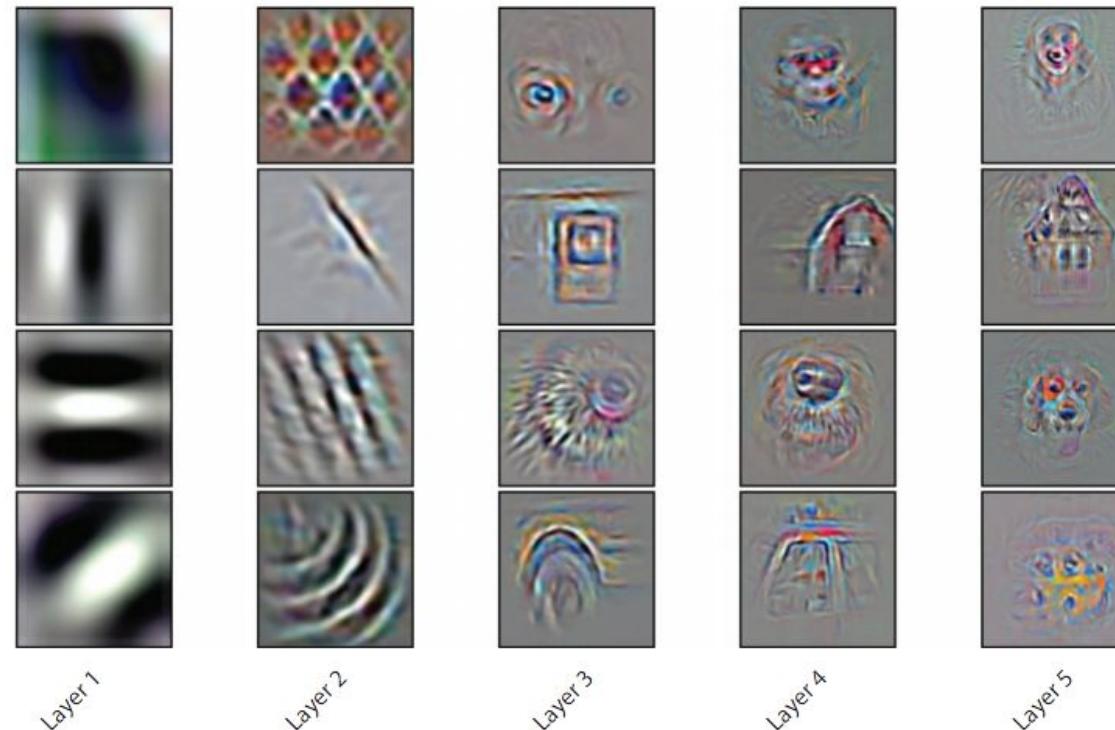
(d) FDSR mechanism

Optical Flow in CS → Much Better Performance



Chen, Qifeng, and Vladlen Koltun. "Full flow: Optical flow estimation by global optimization over regular grids." Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition. 2016.

Does the Fly “Recognize” Objects?



Kriegeskorte, Nikolaus. "Deep neural networks: a new framework for modeling biological vision and brain information processing." *Annual review of vision science* 1 (2015): 417-446.

Potential Project Ideas

- Build a MB inspired FF circuit that classifies MNIST
 - Litwin-Kumar, Ashok, et al. "Optimal degrees of synaptic connectivity." *Neuron* 93.5 (2017): 1153-1164.
- Build a MB inspired spiking model
 - <https://link.springer.com/content/pdf/10.1007/s00422-008-0241-1.pdf>
- Build a Central Complex inspired ring attractor model that performs path integration
 - Turner-Evans et al. eLife 2017, SS Kim et al. Science 2017
- Build a motion detection circuit using HRC and BL and compare performance
 - Arenz, Alexander, et al. "The temporal tuning of the Drosophila motion detectors is determined by the dynamics of their input elements." *Current Biology* 27.7 (2017): 929-944.
- Use HRC in tensorflow and optimize over natural movies
 - Tschopp, Fabian David, Michael B. Reiser, and Srinivas C. Turaga. "A Connectome Based Hexagonal Lattice Convolutional Network Model of the Drosophila Visual System." arXiv preprint arXiv:1806.04793 (2018).
- Build a Optic Lobe + MB circuit that categorizes images
- Review the class of algorithms that can be performed by the MB
- Summarize the literature on ring attractor algorithms