

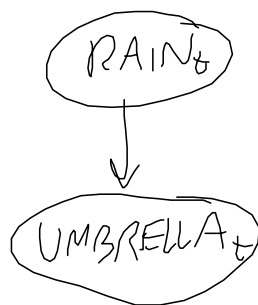
Rain example transition and sensor model

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transition $(RAIN_{t-1}) \rightarrow (RAIN_t)$

R_{t-1}	$P(R_t = TRUE R_{t-1})$	$P(R_t = FALSE R_{t-1})$
T	0.7	0.3
F	0.3	0.7

sensor model



R_t	$P(U_t = TRUE R_t)$	$P(U_t = FALSE R_t)$
T	0.9	0.1
F	0.2	0.8