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- 2. Do operations in reverse following previous rules!

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# Now you try!

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}$$

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We claim that in both cases, the determinant of A is the product of the elements on the diagonal

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & 0 & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix} \xrightarrow{R_2 = R_2 - \frac{a_{23}}{a_{33}} R_3} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & 0 & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$$

What does this look like?

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This idea extends to larger matrices too! Try to think about what that proof would look like!

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And:

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And:

$$\det(A) = \det(B) \cdot a_{11} \cdot a_{22} \cdot a_{33} = a_{11}a_{22}a_{33}$$

### General $2 \times 2$ formula

#### Theorem

Let

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Then

$$\det\left(A\right)=ad-bc$$

a=0 case

Proof.

If a = 0, we need to have a pivot in  $A_{11}$ 

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See that det(A) = -det(B) = -bc

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See that  $det(A) = det(B) = a(d - \frac{bc}{a})$ 

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See that  $det(A) = det(B) = a(d - \frac{bc}{a}) = ad - bc$ .



### General $3 \times 3$ formula

We could derive this formula, but it would be easier with Section 4.2, which we will not be covering in class.

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#### **Theorem**

Let

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

Then

$$\det(A) = a(ei - fh) - b(di - fg) + c(dh - eg)$$

### More Practice

Determine if the determinant of the following systems is 0 or not.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 4 \\ 1 & 2 & 2 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 4 \\ 1 & 2 & 2 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 4 & 4 & 2 \\ 1 & 2 & 2 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

These are provable with what we have now, but we will take them for granted for now. I would think about how to demonstrate the second property though! Let  $A, B \in \mathbb{R}^{n \times n}$ .

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- 3. det(AB) = det(A) det(B)
- 4.  $\det\left(A^{\top}\right) = \det\left(A\right)$