

# Eigenvalues and Eigenvectors<sup>1</sup>

## Definition

Let  $A \in \mathbb{R}^{n \times n}$ , then we define:

1. An **eigenvector** of  $A$  is a vector  $\mathbf{v} \neq \mathbf{0}$  such that  $A\mathbf{v} = \lambda\mathbf{v}$  for some scalar  $\lambda$ .
2. An **eigenvalue** of  $A$  is a scalar  $\lambda$  such that there is some  $\mathbf{v} \neq \mathbf{0}$  such that  $A\mathbf{v} = \lambda\mathbf{v}$ .

Note: Since the definitions of eigenvalues and eigenvectors depend on each other, we sometimes refer to the ordered pair

$$(\lambda, \mathbf{v})$$

as an **eigenpair** of  $A$ .

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<sup>1</sup>Aside: The word “eigen” comes from German and roughly translates to either “own/self” or “characteristic”.

## Another Framing of Eigenvalues and Eigenvectors

From the definition of the eigenpair  $(\lambda, \mathbf{v})$ , we see that  $\mathbf{v}$  is a non-trivial solution to the system

$$\mathbf{0} = A\mathbf{v} - \lambda\mathbf{v} = (A - \lambda I_n)\mathbf{v}$$

So, if  $\lambda$  is an eigenvalue of  $A$ , then the matrix  $A - \lambda I$  has a non-trivial null space, and the eigenvectors will be the vectors of this null space!

## Finding Eigenvectors for an Eigenvalue Example

Let's verify if  $\lambda = 2$  is an eigenvalue of the following matrix, and if it is, find an eigenvector.

$$A = \begin{bmatrix} 3 & 4 & 6 \\ 2 & 12 & 14 \\ 1 & 6 & 10 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 4 & 6 \\ 2 & 12 & 14 \\ 1 & 6 & 10 \end{bmatrix} \xrightarrow{A=A-\lambda I} \begin{bmatrix} 1 & 4 & 6 \\ 2 & 10 & 14 \\ 1 & 6 & 8 \end{bmatrix} \xrightarrow[\substack{R_2=R_2-2R_1 \\ R_3=R_3-R_1}]{R_2=R_2-2R_1} \begin{bmatrix} 1 & 4 & 6 \\ 0 & 2 & 2 \\ 0 & 2 & 2 \end{bmatrix} \xrightarrow{R_3=R_3-R_2} \begin{bmatrix} 1 & 4 & 6 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

So  $\lambda = 2$  is an eigenvalue! Let's find an eigenvector.

$$\xrightarrow{R_2=\frac{R_2}{2}} \begin{bmatrix} 1 & 4 & 6 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1=R_1-4R_2} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \mathbf{v} = \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \text{ is an eigenvector of } A.$$

## Finding Eigenvectors for an Eigenvalue Practice

Determine if  $\lambda = 1$  is an eigenvalue of the following matrix and if so, determine an eigenvector associated with  $\lambda = 1$ .

$$A = \begin{bmatrix} 2 & 2 & 9 \\ 2 & 8 & 30 \\ 1 & 4 & 18 \end{bmatrix}$$

$$\left( 1, \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix} \right)$$

is an eigenpair. See that

$$A\mathbf{v} = \begin{bmatrix} 2 & 2 & 9 \\ 2 & 8 & 30 \\ 1 & 4 & 18 \end{bmatrix} \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix} = - \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} - 4 \begin{bmatrix} 2 \\ 8 \\ 4 \end{bmatrix} + \begin{bmatrix} 9 \\ 30 \\ 18 \end{bmatrix} = \begin{bmatrix} -2 - 8 + 9 \\ -2 - 32 + 30 \\ -1 - 16 + 18 \end{bmatrix} = \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix} = 1\mathbf{v}$$

# Eigenspace

## Definition

We define the **Eigenspace** of  $A$  associated with eigenvalue  $\lambda$  to be

$$E(A, \lambda) = \{\mathbf{v} \in \mathbb{R}^n \mid A\mathbf{v} = \lambda\mathbf{v}\}$$

Or equivalently

$$E(A, \lambda) = \text{Nul}(A - \lambda I_n)$$

Since the eigenspace is really just a nullspace, we know how to find a basis of it!

## Basis for an Eigenspace

A basis for an eigenspace of  $E(A, \lambda)$  is just a basis for  $\text{Nul}(A - \lambda I_n)$ . So, in order to find such a basis, we can

1. Set up  $A - \lambda I_n$ .
2. Reduce to RREF
3. Write out a basis of this space as before

## Basis for an Eigenspace Example

Find a basis for the eigenspaces  $E(A, 1)$  for

$$A = \begin{bmatrix} 7 & 0 & 6 \\ -3 & 4 & -6 \\ -3 & 0 & -2 \end{bmatrix}$$

$$\begin{aligned} \begin{bmatrix} 7 & 0 & 6 \\ -3 & 4 & -6 \\ -3 & 0 & -2 \end{bmatrix} &\xrightarrow{A=A-\lambda I} \begin{bmatrix} 6 & 0 & 6 \\ -3 & 3 & -6 \\ -3 & 0 & -3 \end{bmatrix} \xrightarrow{R_1=\frac{R_1}{6}} \begin{bmatrix} 1 & 0 & 1 \\ -3 & 3 & -6 \\ -3 & 0 & -3 \end{bmatrix} \xrightarrow{\substack{R_2=R_2+3R_1 \\ R_3=R_3+3R_1}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{bmatrix} \\ &\xrightarrow{R_2=\frac{R_2}{3}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \text{Nul}(A - I) = \text{Span} \left( \begin{pmatrix} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \end{pmatrix} \right) \end{aligned}$$

## Basis for an Eigenspace Practice

Find a basis for the eigenspaces  $E(A, 4)$  for

$$A = \begin{bmatrix} 7 & 0 & 6 \\ -3 & 4 & -6 \\ -3 & 0 & -2 \end{bmatrix}$$

$$E(A, 4) = \text{Span} \left( \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right)$$



# The Eigenspace Associated With 0

What does  $E(A, 0)$  look like?

$$E(A, 0) = \text{Nul}(A - 0I) = \text{Nul}(A)$$

So, if this space has a non-trivial basis, then  $A\mathbf{x} = \mathbf{0}$  has a non-trivial solution!

Meaning we can say that a matrix is **invertible** if and only if 0 is **not** an eigenvalue of  $A$ .

# Linearly Independent Eigenvectors

## Theorem

*If  $(\lambda_1, \mathbf{v}_1)$  and  $(\lambda_2, \mathbf{v}_2)$  are two eigenpairs of a matrix  $A$  such that  $\lambda_1 \neq \lambda_2$ , then  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly independent.*

## Proof.

We will prove this via a contradiction. IE assume  $\lambda_1 \neq \lambda_2$  but  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly dependent. Then, we show that this leads to nonsense. If  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly dependent, then there is some constant  $c$  such that  $\mathbf{v}_1 = c\mathbf{v}_2$ . See that

$$\lambda_1 \mathbf{v}_1 = A\mathbf{v}_1 = cA\mathbf{v}_2 = \lambda_2 c\mathbf{v}_2 = \lambda_2 \mathbf{v}_1$$

So,

$$\lambda_1 \mathbf{v}_1 - \lambda_2 \mathbf{v}_1 = \mathbf{0}$$

meaning that  $\lambda_1 = \lambda_2$ , which contradicts our assumption that these eigenvalues are distinct. □