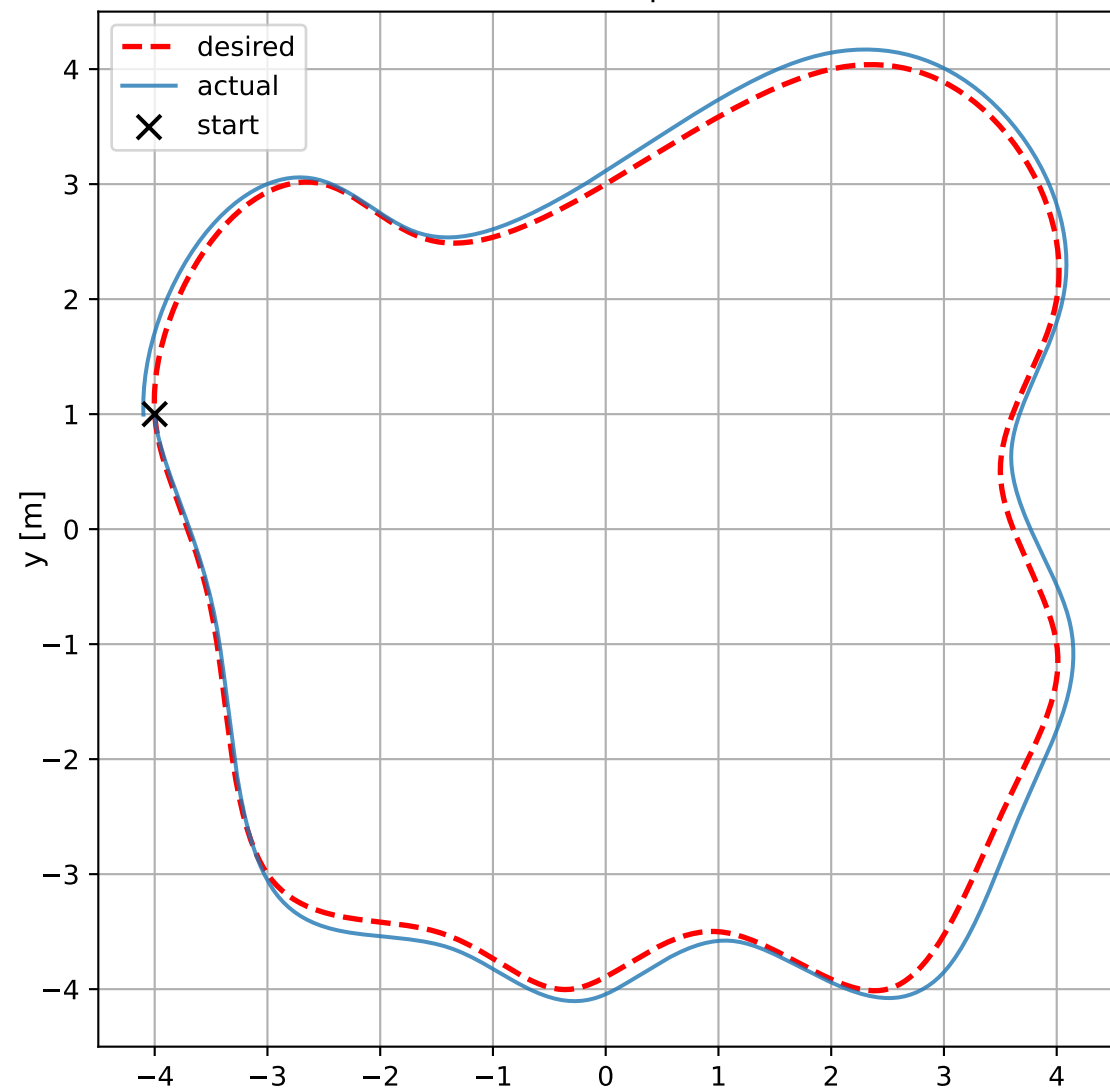


# Desired vs Actual trajectory of Tractor0

First lap



Fifth lap

