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Games with pure equilibria

Fall 2020

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Best response dynamics

Consider a strategic game
$$\Gamma = \langle N, (A_i)_{i \in N}, (u_i)_{i \in N} \rangle$$
 with $N = \{i, \dots, n\}$

 PNE are defined as the fix point among mutually best responses.

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- It seems natural to consider variants of the process of local changes to try to get a PNE.

Best response dynamics

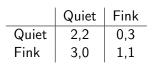
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- PNE are defined as the fix point among mutually best responses.
- It seems natural to consider variants of the process of local changes to try to get a PNE.
- Consider the algorithm:
 - choose $s \in A_1 \times \cdots \times A_n$
 - while s is not a NE do choose $i \in \{1, ..., n\}$ such that $s_i \notin BR(s_{-i})$ Set s_i to be an action in $BR(s_{-i})$
- The process looks similar to local search algorithms. Is there any difference?

Best response graph

- The Nash dynamics or Best Response graph has
 - $V = A_1 \times \cdots \times A_n$
 - An edge $(s, (s_{-i}, s'_i))$ for $i \in N$, $s_i \notin BR(s_{-i})$ and $s'_i \in BR(s_{-i})$.
- Performing local search on the best response graph
 - Does it produce a PNE?
 - If so, how much time?
 - Let's look to some examples.

	Quiet	Fink
Quiet	2,2	0,3
Fink	3,0	1,1





	Bach	Stravinsky
Bach	2,1	0,0
Stravinsky	0,0	1,2

	Bach	Stravinsky
Bach	2,1	0,0
Stravinsky	0,0	1,2



	Head	Tail
Head	1,-1	-1,1
Tail	-1,1	1,-1



Other games

- sending from s to t?
- congestion games?

In those games we cannot get the best response graph in polynomial time.

However we can perform a local improvement step in polynomial time.

Although, even assuring convergence, it might take exponential time to reach a NE.

Best response graph: properties

- A NE is a sink (a node with out-degree 0) in the best response graph.
- The existence of a cycle in the best response graph does not rule out the existence of a PNE.
- If the best response graph is acyclic, the game has a PNE.

Best response graph: properties

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- The existence of a cycle in the best response graph does not rule out the existence of a PNE.
- If the best response graph is acyclic, the game has a PNE.
 Furthermore, best response dynamics converges to a PNE, maybe with a lot of time.

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(Monderer and Shapley 96)

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- A function $\Phi: S \to \mathbb{R}$ is an exact potential function for Γ if

$$\forall i \in N \,\forall s \in S \,\forall s_i' \in A_i \,\, u_i(s) - u_i(s_{-i}, s_i') = \Phi(s) - \Phi(s_{-i}, s_i')$$

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or $(u_i(s) - u_i(s_{-i}, s'_i))(\Phi(s) - \Phi(s_{-i}, s'_i)) > 0$

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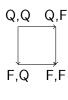
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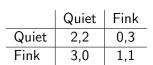
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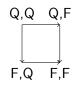
• Γ is a potential game if it admits a potential function.



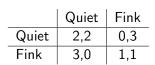


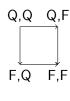






Φ	Quiet	Fink
Quiet	1	2
Fink	2	3



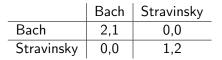


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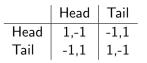
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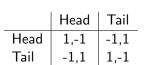


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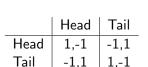








This is not a potential game





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The property on Φ cannot hold along a cycle in the best response graph.

Theorem

A strategic game is a potential game iff the best response graph is acyclic

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Proof.

• Let G be the best response graph of Γ .

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A strategic game is a potential game iff the best response graph is acyclic

Proof.

- Let G be the best response graph of Γ .
- The existence of a potential function Φ and the fact that, for each pair of connected strategy profiles in G, at least one player improves, implies the non existence of cycles in G.
- If G is acyclic, a topological sort of the graph provides a potential function for Γ.



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Any potential game has a PNE

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As the best response graph is acyclic it must have a sink.

Potential games

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We have a way to show that a game has a PNE by showing that it is a potential game.

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Congestion games

Congestion games

A congestion game

- is defined on a finite set E of resources.
- There is a delay function d mapping $E \times \mathbb{N}$ to the integers.
- Player's actions are subsets of E (all or some).
- The cost functions are the following:

$$c_i(a_1,\ldots,a_n) = \left(\sum_{e\in a_i} d(e,f(a_1,\ldots,a_n,e))\right)$$

being
$$f(a_1, ..., a_n, e) = |\{i \mid e \in a_i\}|$$
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• A singleton congestion game has $A_i = \{\{r\} \mid e \in E\}.$

 We have a factory with two end production lines, each having a cutting and a packing unit. Orders are cut down and then packed.

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- The cutting machine on the first line takes 1 hour to process a single order, 2 hours to process 2 and 4 hours to process 3.
 The cutting machine on the second line takes 4, 5 and 9 hours respectively.

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- We have 3 orders that have to be send to one of the end production lines.
- The cutting machine on the first line takes 1 hour to process a single order, 2 hours to process 2 and 4 hours to process 3.
 The cutting machine on the second line takes 4, 5 and 9 hours respectively.
- The packing machine on the first line takes 2 additional hours to pack a single order, 3 hours to pack 2 and 7 hours to pack
 The packing machine on the second line takes instead 0, 2 and 9 hours respectively.

- We have 4 resources C_1, C_2, P_1, P_2 and 3 players $N = \{1, 2, 3\}$
- $A_i = \{\{C_1, P_1\}, \{C_2, P_2\}\}, i = 1, 2, 3$
- Delay functions are defined by the processing times.

	1	2	3
$\overline{C_1}$	1	2	4
C_2	4	5	9
P_1	2	3	7
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$$\begin{array}{c|cccc} & 1 & 2 & 3 \\ \hline C_1 & 1 & 2 & 4 \\ C_2 & 4 & 5 & 9 \\ P_1 & 2 & 3 & 7 \\ P_2 & 0 & 2 & 9 \\ \end{array}$$

Does this game have a PNE?

Rosenthal's theorem

Theorem (Rosenthal 73)

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Every congestion game is a potential game,

• For a strategy profile $s = (a_1, \ldots, a_n)$, define

$$\Phi(s) = \sum_{e \in r(s)} \sum_{k=1}^{f(s,e)} d(e,k)$$

where $r(s) = \bigcup_{i \in N} a_i$.

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Let us show that Φ is a potential function.

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$$\Phi(s) - \Phi(s') = \sum_{e \in r(s)} \sum_{k=1}^{f(s,e)} d(e,k) - \sum_{e' \in r(s')} \sum_{k=1}^{f(s',e')} d(e',k)$$

Cost difference

Note that

Cost difference

- Note that
 - $e \in a_i \cap a_i'$: f(s,e) = f(s',e)
 - $e \notin a_i$ and $e \notin a'_i$: f(s, e) = f(s', e)

Cost difference

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$$c_i(s) - c_i(s_{-i}, s_i') = \left(\sum_{e \in a_i} d(e, f(s, e))\right) - \left(\sum_{e' \in a_i'} d(e, f(s', e'))\right)$$

= $\sum_{e \in a_i, e \notin a_i'} d(e, f(s, e)) - \sum_{e \notin a_i, e \in a_i'} d(e, f(s', e'))$

• Furthermore,

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 - $e \in a_i$ and $e \notin a_i'$: f(s, e) = f(s', e) + 1
 - $e \notin a_i$ and $e \in a_i'$: f(s, e) + 1 = f(s', e)

$$\begin{split} \Phi(s) - \Phi(s') &= \sum_{e \in r(s)} \sum_{k=1}^{f(s,e)} d(e,k) - \sum_{e' \in r(s')} \sum_{k=1}^{f(s',e')} d(e',k) \\ &= \sum_{e \in a_i, e \notin a_i'} [\sum_{k=1}^{f(s',e)+1} d(e,k) - \sum_{k=1}^{f(s',e)} d(e,k)] \\ &+ \sum_{e \notin a_i, e \in a_i'} [\sum_{k=1}^{f(s,e)} d(e,k) - \sum_{k=1}^{f(s,e)+1} d(e,k)] \end{split}$$

$$= \sum_{e \in a_{i}, e \notin a'_{i}} \left[\sum_{k=1}^{f(s',e)+1} d(e,k) - \sum_{k=1}^{f(s',e)} d(e,k) \right]$$

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$$= \sum_{e \in a_{i}, e \notin a'_{i}} d(e,f(s',e)+1) - \sum_{e \notin a_{i}, e \in a'_{i}} d(e,f(s,e)+1)$$

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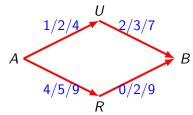
$$= c_{i}(s) - c_{i}(s_{-i},s'_{i})$$

Network congestion games

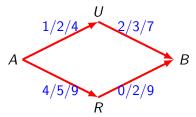
- A network congestion game is a congestion game defined by a directed graph G and a collection of pairs of vertices (s_i, t_i) .
 - The set of resources are the arcs in G.
 - The acrions, for player i, are the $s_i \rightarrow t_i$ paths on G.
- A network congestion game is symmetric when $s_i = s$ and $t_i = t$, for $i \in N$.

- There are three players.
- and a network (with a delay function on arcs)

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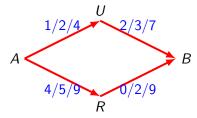


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• Player's objective: going from s = A to t = B as fast as possible.

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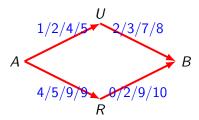
- Player's objective: going from s = A to t = B as fast as possible.
- Strategy profiles: paths from A to B.
- A NE?



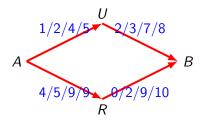
• There are three players with weights 1,1,2

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- Player's objective: send w_i units from s = A to t = B as fast as possible.
- Strategy profiles: paths from A to B.
- A NE?



Results on convergence time

Theorem (Fabrikant, Papadimitriou, Talwar (STOC 04))

There exist network congestion games with an initial strategy profile from which all better response sequences have exponential length.

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There exist network congestion games with an initial strategy profile from which all better response sequences have exponential length.

Theorem (leong, McGrew, Nudelman, Shoham, Sun (AAAI 05))

In singleton congestion games all best response sequences have length at most n^2 m.

Complexity classification?



Optimization problem

An optimization problem is a structure $\Pi = (I, sol, m, goal)$, where

- C is the input set to Π ;
- sol(x) is the set of feasible solutions for an input x.
- m is an integer measure defined over pairs (x, y), $x \in I$ and $y \in sol(x)$.
- goal is the optimization criterium MAX or MIN.

An optimization problem is a function problem whose goal, with respect to an instance x, is to find an optimum solution, that is, a feasible solution y such that

$$y = goal\{(m(x, y') \mid y' \in sol(x)\}.$$

Example: Given a graph and two vertices, obtain a path joining them with minimum length.

- A local search problem is an optimization problem with
- A neighborhood structure is defined on the solution set $\mathcal{N}(\operatorname{sol}(x))$.

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A local search problems belongs to PLS (Polynomial Local Search) if polynomial time algorithms exist for

- finding initial feasible solution $s \in sol(x)$,
- computing the objective measure m(x, y),
- checking whether a solution is a local optimum and if not finding a better solution in the neighborhood.

PLS reductions

A PLS reduction from (Π_1, \mathcal{N}_1) to (Π_1, \mathcal{N}_1) is

- ullet a polynomial time computable function $f: \mathsf{I}_{\Pi_1} o \mathsf{I}_{\Pi_2}$ and
- a polynomial time computable function $g: sol(f(x)) \rightarrow sol(x)$, for $x \in I_{\Pi_1}$ such that
- if $s_2 \in \text{sol}(f(x))$ locally optimal then $g(s_2)$ is locally optimal.

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- if $s_2 \in \operatorname{sol}(f(x))$ locally optimal then $g(s_2)$ is locally optimal.
- If a local opt.of Π_2 is easy to find then a local opt.of Π_1 is easy to find.
- If a local opt.of Π_1 is hard to find then a local opt.of Π_2 is hard to find.

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A PLS problem (Π, \mathcal{N}) is PLS-complete if every problem in PLS is PLS-reducible to (Π, \mathcal{N}) .

PLS complete problems

- MAX-SAT (maximum satisfiability) problem
 - Given a Boolean formula in conjunctive normal form with a positive integer weight for each clause.
 - A solution is an assignment of the value 0 or 1 to all variables.
 - Its weight, to be maximized, is the sum of the weights of all satisfied clauses
 - As neighborhood consider the Flip-neighborhood, where two
 assignments are neighbors if one can be obtained from the
 other by fliipping the value of a single variable.

PLS complete problems

- MaxCut problem.
 - Given a graph G = (V, E) with non-negative edge weights.
 - A feasible solution is a partition of V into two sets A and B.
 - The objective is to maximize the weight of the edges between the two sets A and B.
 - In the Flip-neighborhood two solutions are neighbors if one can be obtained from the other by moving a single vertex from one set to the other.

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- We provide a reduction from MaxCut under the Flip-neigborhood.

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 - The players correspond to the nodes in V, $v \in V$ has strategies $S_v^a = \{e^a \mid v \text{ incident to } e\}$ and $S_v^b = \{e^b \mid v \text{ incident to } e\}$

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 - Solutions (A, B) of MaxCut corresponds to strategy S_{ν}^{a} for $\nu \in A$ and S_{ν}^{b} for $\nu \in B$.
 - Furthermore, the local optima of the MaxCut instance coincide with the Nash equilibria of the congestion game.
- We have a PLS-reduction from MaxCut.

- Best response dynamics
- 2 Potential games
- 3 Congestion games
- 4 References

Reference

B. Vöcking, Congestion Games: Optimization in Competition