



Stochastic Network Modeling (SNM)

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(DTMC)

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Transient
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Research
Example: Aloha

Finite
Absorbing
Chains

Stochastic Network Modeling (SNM)

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- I Introduction
- II Discrete Time Markov Chains (DTMC)
- III Continuous Time Markov Chains (CTMC)
- IV Queuing Theory



Part II

Discrete Time Markov Chains (DTMC)

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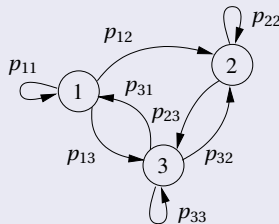
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Definition of a DTMC

State Transition Diagram

- We are interested in a **process that evolve in stages**.
- For the model to be tractable, it is convenient to represent the SP by giving all **possible states** (there may be ∞), and the **possible transitions** between them:



For the model to be consistent:

$$\sum_j p_{ij} = 1$$

- Mathematically:

$$p_{ij} = P(X(n) = j \mid X(n-1) = i)$$



Definition of a DTMC

Properties of a DTMC

- The event $X(n) = i$ (at step n the system is in state i) must satisfy (**memoryless property**):

$$P(X(n) = j \mid X(n-1) = i, X(n-2) = k, \dots) = P(X(n) = j \mid X(n-1) = i)$$

- If $P(X(n) = j \mid X(n-1) = i) = P(X(1) = j \mid X(0) = i)$ for any n we have an **homogeneous** DTMC. We shall only consider homogeneous DTMC.
- We call **one-step transition probabilities** to:

$$p_{ij} = P(X(n) = j \mid X(n-1) = i)$$

- The SP is called a Markov Process (MP) or Markov Chain (MC) depending on the state being continuous or discrete.



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Transition Matrix

- Transition probabilities:

$$p_{ij} = P(X(n) = j \mid X(n-1) = i)$$

- In matrix form:

$$\mathbf{P} = \begin{bmatrix} p_{11} & p_{12} & \cdots \\ p_{21} & p_{22} & \cdots \\ \cdots & \cdots & \cdots \end{bmatrix}$$



Definition of a DTMC

Transition Matrix

- We have

$$\mathbf{P} = \begin{bmatrix} p_{11} & p_{12} & \cdots \\ p_{21} & p_{22} & \cdots \\ \cdots & \cdots & \cdots \end{bmatrix}, \text{ where } p_{ij} = P(X(n) = j \mid X(n-1) = i)$$

- For the model to be consistent, the probability to move from i to any state must be 1. Mathematically:

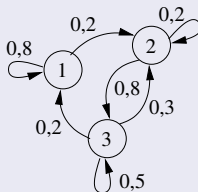
$$\sum_j p_{ij} = \sum_j P(X(n) = j \mid X(n-1) = i) = \sum_j \frac{P(X(n-1) = i \mid X(n) = j) P(X(n) = j)}{P(X(n-1) = i)} = \frac{P(X(n-1) = i)}{P(X(n-1) = i)} = 1$$

- \mathbf{P} is a **stochastic matrix**, i.e. a matrix which rows sum 1.

Definition of a DTMC

Example

- Assume a terminal can be in **3 states**:
 - State 1: Idle.
 - State 2: Active without sending data.
 - State 3: Active and sending data at a rate ν bps.



$$\begin{array}{c}
 \text{to state} \\
 \mathbf{P} = \begin{bmatrix} 1 & 2 & 3 \\ 0,8 & 0,2 & 0 \\ 0 & 0,2 & 0,8 \\ 0,2 & 0,3 & 0,5 \end{bmatrix} \begin{array}{l} 1 \\ 2 \\ 3 \end{array} \begin{array}{l} \text{from} \\ \text{state} \end{array}
 \end{array}$$

- The **average transmission rate** (throughput), ν_a , is:

$$\nu_a = P(\text{the terminal is in state 3}) \times \nu$$

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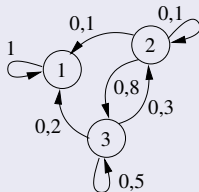
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Absorbing Chains

- It is possible to have chains with **absorbing states**.
- A state i is absorbing if $p_{ii} = 1$.
- Example: State 1 is absorbing.



$$\mathbf{P} = \begin{matrix} & \begin{matrix} \text{to state} \\ 1 & 2 & 3 \end{matrix} \\ \begin{matrix} \text{from state} \\ 1 & 2 & 3 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 \\ 0,1 & 0,1 & 0,8 \\ 0,2 & 0,3 & 0,5 \end{bmatrix} \end{matrix}$$



Definition of a DTMC

n-step transition probabilities

- Transition probabilities: $p_{ij} = P(X(n) = j \mid X(n-1) = i)$
- In matrix form:

$$\mathbf{P} = \begin{bmatrix} p_{11} & p_{12} & \cdots \\ p_{21} & p_{22} & \cdots \\ \cdots & \cdots & \cdots \end{bmatrix}$$

- We define the **n-step** transition probabilities:

$$p_{ij}(n) = P(X(n) = j \mid X(0) = i)$$

$$\mathbf{P}(n) = \begin{bmatrix} p_{11}(n) & p_{12}(n) & \cdots \\ p_{21}(n) & p_{22}(n) & \cdots \\ \cdots & \cdots & \cdots \end{bmatrix}$$

- \mathbf{P} and $\mathbf{P}(n)$ are **stochastic matrices**: Their rows sum 1.



Definition of a DTMC

State Probabilities

- Define the probability of being in state i at step n :

$$\pi_i(n) = P(X(n) = i)$$

- In vector form (row vector)

$$\boldsymbol{\pi}(n) = (\pi_1(n), \pi_2(n), \dots) = (P(X(n) = 1), P(X(n) = 2), \dots).$$

- Thus, the vector $\boldsymbol{\pi}(n)$ is the distribution of the random variable $X(n)$, and it is called the **state probability at step n** .



Definition of a DTMC

State Probabilities

- State probability:

$$\boldsymbol{\pi}(n) = (\pi_1(n), \pi_2(n), \dots) = (P(X(n) = 1), P(X(n) = 2), \dots).$$

- Law of total prob. $P(A) = \sum_n P(A \cap B_n) = \sum_n P(A|B_n)P(B_n)$:

$$\pi_i(n) = \sum_k P(X(n-1) = k) P(X(n) = i \mid X(n-1) = k) = \sum_k \pi_k(n-1) p_{ki}$$

$$\pi_i(n) = \sum_k P(X(0) = k) P(X(n) = i \mid X(0) = k) = \sum_k \pi_k(0) p_{ki}(n)$$

- In matrix form:

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(n-1) \mathbf{P}$$

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(0) \mathbf{P}(n)$$

where $\boldsymbol{\pi}(0)$ is the **initial distribution**.



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State Probabilities

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(n-1) \mathbf{P}$$

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(0) \mathbf{P}^n$$

- Iterating

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(n-1) \mathbf{P} = \boldsymbol{\pi}(n-2) \mathbf{P} \mathbf{P} = \boldsymbol{\pi}(n-3) \mathbf{P} \mathbf{P} \mathbf{P} = \cdots = \boldsymbol{\pi}(0) \mathbf{P}^n$$

- Thus:

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(0) \mathbf{P}^n = \boldsymbol{\pi}(0) \mathbf{P}^n$$



Definition of a DTMC

Chapman-Kolmogorov Equations

$$p_{ij}(n) = \sum_k p_{ik}(r) p_{kj}(n-r)$$

• **Proof:**

$$\begin{aligned} p_{ij}(n) &= P(X(n) = j \mid X(0) = i) = \sum_k P(X(n) = j, X(r) = k \mid X(0) = i) \\ &= \sum_k \frac{P(X(n) = j, X(r) = k, X(0) = i)}{P(X(0) = i)} \times \frac{P(X(r) = k, X(0) = i)}{P(X(r) = k, X(0) = i)} \\ &= \sum_k P(X(n) = j \mid X(r) = k, X(0) = i) P(X(r) = k \mid X(0) = i) \\ &= \sum_k P(X(n) = j \mid X(r) = k) P(X(r) = k \mid X(0) = i) \\ &= \sum_k p_{ik}(r) p_{kj}(n-r) \end{aligned}$$

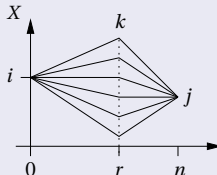


Definition of a DTMC

Chapman-Kolmogorov Equations

$$p_{ij}(n) = \sum_k p_{ik}(r) p_{kj}(n-r)$$

- Graphical interpretation:



- In matrix form:

$$\mathbf{P}(n) = \mathbf{P}(r) \mathbf{P}(n-r)$$



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Chapman-Kolmogorov Equations

$$\mathbf{P}(n) = \mathbf{P}(r) \mathbf{P}(n-r)$$

- Particularly:

$$\mathbf{P}(n) = \mathbf{P}(1) \mathbf{P}(n-1) = \mathbf{P} \mathbf{P}(n-1) = \mathbf{P}(n-1) \mathbf{P}$$

- Iterating:

$$\mathbf{P}(n) = \mathbf{P}^n$$

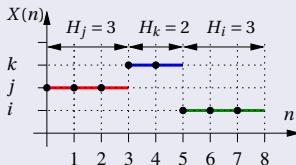
- Thus:

$$\boldsymbol{\pi}(n) = \boldsymbol{\pi}(0) \mathbf{P}(n) = \boldsymbol{\pi}(0) \mathbf{P}^n$$

Definition of a DTMC

Sojourn or Holding Time

- Sojourn** or **holding time** in state k : Is the RV H_k equal to the number of steps that the chain remains in state k before leaving to a different state:



- The Markov property implies:

$$H_i(n) = P(H_i = n) = p_{ii}^{n-1} (1 - p_{ii}), n \geq 1$$

- Which is a **geometric** distribution with mean:

$$E[H_i] = \sum_{n=1}^{\infty} n P(H_i = n) = \frac{1}{1 - p_{ii}}.$$



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Sojourn or Holding Time

- NOTE: We allow that:

$$p_{ii} = 0 \Rightarrow H_i(n) = I(n = 1) = \begin{cases} 1, & n = 1, \\ 0, & \text{otherwise.} \end{cases}, \text{ and}$$

$$p_{ii} = 1 \Rightarrow E[H_i] = \infty \text{ (absorbing state)}.$$



Definition of a DTMC

Theorem

A stochastic process is a DTMC if and only if the sojourn times are geometrically distributed.

Proof.

- We have seen that a DTMC has a sojourn time

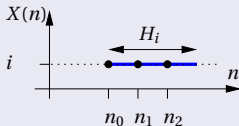
$$H_i(n) = P(H_i = n) = p_{ii}^{n-1} (1 - p_{ii}), n \geq 1$$

- Which is **geometrically** distributed.
- We need to prove that the geometric distribution satisfies the memoryless property (aka Markov property).



Definition of a DTMC

The geometric distribution satisfies the Markov property (1)



Proof

- Markov property:

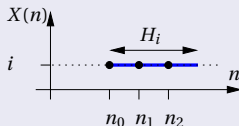
$$P(X(n_2) = i \mid X(n_1) = i, X(n_0) = i) = P(X(n_2) = i \mid X(n_1) = i)$$

- Thus, the Markov property **in terms of the sojourn time** can be written as:

$$P(H_i > n_2 - n_0 \mid H_i > n_1 - n_0) = P(H_i > n_2 - n_1)$$

Definition of a DTMC

The geometric distribution satisfies the Markov property (2)



$$P(H_i > n_2 - n_0 \mid H_i > n_1 - n_0) = P(H_i > n_2 - n_1)$$

- Since

$$P(H_i > k) = 1 - P(H_i \leq k) = 1 - \sum_{n=1}^k p^{n-1}(1-p) = 1 - (1-p) \frac{1-p^k}{1-p} = p^k$$

- We have:

$$P(H_i > n_2 - n_0 \mid H_i > n_1 - n_0) = \frac{P(H_i > n_2 - n_0, H_i > n_1 - n_0)}{P(H_i > n_1 - n_0)} =$$

$$\frac{P(H_i > n_2 - n_0)}{P(H_i > n_1 - n_0)} = \frac{p^{n_2 - n_0}}{p^{n_1 - n_0}} = p^{n_2 - n_1} = P(H_i > n_2 - n_1) \quad \square$$



Master in Innovation and Research in Informatics (MIRI)
Computer Networks and Distributed Systems
Stochastic Network Modeling (SNM)

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Transient Solution

- If we are interested in the **transient evolution** we shall study $\pi(n) = \pi(0) \mathbf{P}^n$.
- If we can **diagonalize \mathbf{P}** , we can obtain the transient evolution in **close form**.
- \mathbf{P} can be **diagonalized** if \mathbf{P} can be decomposed as:

$$\mathbf{P} = \mathbf{L}^{-1} \mathbf{\Lambda} \mathbf{L}$$

where \mathbf{L} is some invertible matrix and $\mathbf{\Lambda}$ is the diagonal matrix

$$\mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_N) = \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_N \end{bmatrix}$$

with λ_l , $l = 1, \dots, N$ the **eigenvalues** of \mathbf{P} .



Transient Solution

Eigenvalues

- The **eigenvalues** λ_l of a matrix \mathbf{A} are scalars that satisfy: $\mathbf{l}\mathbf{A} = \lambda_l \mathbf{l}$ (or $\mathbf{A}\mathbf{r} = \lambda_l \mathbf{r}$) for some row vectors \mathbf{l} (column vectors \mathbf{r}), referred to as **left and right eigenvectors**, respectively.

$$\mathbf{l}\mathbf{A} = \lambda_l \mathbf{l} \Rightarrow \mathbf{l}(\mathbf{A} - \mathbf{I}\lambda_l) = 0 \Rightarrow \det(\lambda_l \mathbf{I} - \mathbf{A}) = 0$$

$$\mathbf{A}\mathbf{r} = \lambda_l \mathbf{r} \Rightarrow (\mathbf{A} - \mathbf{I}\lambda_l)\mathbf{r} = 0 \Rightarrow \det(\lambda_l \mathbf{I} - \mathbf{A}) = 0$$

- Thus, λ_l solve the **characteristic polynomial** $\det(\lambda \mathbf{I} - \mathbf{A}) = 0$.
- Note that, in general, **left and right eigenvectors** are different, but eigenvalues are the same (they solve the same **characteristic polynomial**).
- A matrix can be **diagonalized** if all eigenvalues are single (multiplicity = 1). If a matrix cannot be diagonalized it is called **defective**.



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Determinants

$$\det \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11} a_{22} - a_{12} a_{21}$$

$$\det \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{aligned} &+ a_{11} a_{22} a_{33} + a_{12} a_{23} a_{31} + a_{21} a_{32} a_{13} \\ &- a_{31} a_{22} a_{13} - a_{12} a_{21} a_{33} - a_{23} a_{32} a_{11} \end{aligned}$$

- **Cofactor Formula:** expanding along a row i :

$$\det \mathbf{A} = \sum_{j=1}^N a_{ij} (-1)^{i+j} \det M_{ij},$$

where the **minor matrices** M_{ij} are obtained removing the row i and column j from \mathbf{A} . $(-1)^{i+j} \det M_{ij}$ is called the **cofactor** of a_{ij} .



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Properties of the determinants

$$\det \mathbf{A} = \prod \text{eigenvalues of } \mathbf{A}$$

$$\text{trace } \mathbf{A} = \sum \text{eigenvalues of } \mathbf{A}$$

where $\text{trace } \mathbf{A} = \sum \text{elements of the diagonal of } \mathbf{A}$.



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Transient Solution

- Assume a **finite DTMC** with N states. Then $\mathbf{P} = \mathbf{P}^{N \times N}$.
- Assume that \mathbf{P} can be **diagonalized**: $\mathbf{P} = \mathbf{L}^{-1} \Lambda \mathbf{L}$, where Λ is the diagonal matrix $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_N)$, with $\lambda_l, l = 1, \dots, N$ the eigenvalues of \mathbf{P} .
- Since $\Lambda^n = \text{diag}(\lambda_1^n, \dots, \lambda_N^n)$, we have that

$$\begin{aligned}\boldsymbol{\pi}(n) &= \boldsymbol{\pi}(0) \mathbf{P}^n = \boldsymbol{\pi}(0) \mathbf{P}^n = \boldsymbol{\pi}(0) (\mathbf{L}^{-1} \Lambda^n \mathbf{L}) = \\ &\quad \boldsymbol{\pi}(0) (\mathbf{L}^{-1} \text{diag}(\lambda_1^n, \dots, \lambda_N^n) \mathbf{L})\end{aligned}$$



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- But $\mathbf{L}^{-1} \text{diag}(\lambda_1^n, \dots, \lambda_N^n) \mathbf{L}$ are linear combinations of $\lambda_1^n, \dots, \lambda_N^n$. Thus, the probability of being in state i is given by:

$$\pi_i(n) = (\boldsymbol{\pi}(n))_i = \sum_{l=1}^N a_i^{(l)} \lambda_l^n$$

where the **unknown coefficients** $a_i^{(l)}$ can be obtained solving the system of equations:

$$\sum_{l=1}^N a_i^{(l)} \lambda_l^n = (\boldsymbol{\pi}(n))_i = (\boldsymbol{\pi}(0) \mathbf{P}^n)_i, n = 0, \dots, N-1$$



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Example

- Assume a DTMC with

$$\mathbf{P} = \begin{bmatrix} 4/5 & 1/5 \\ 2/5 & 3/5 \end{bmatrix}$$

- We want the probability of being in state 2 in n steps starting from state 1: $\pi_2(n)$ with $\boldsymbol{\pi}(0) = [1 \quad 0]$.



Transient Solution

Solution

- It can be easily found that the **eigenvalues** of \mathbf{P} are $\lambda_1 = 1$ and $\lambda_2 = 2/5$.

$$\pi_2(n) = \lambda_1^n a + b \lambda_2^n = a + b(2/5)^n$$

- Imposing the **boundary conditions** $\pi_i(n) = (\boldsymbol{\pi}(0) \mathbf{P}^n)_i$:

$$\pi_2(0) = a + b = ([1 \quad 0] \mathbf{P}^0)_2 = (\mathbf{P}^0)_{12} = 0$$

$$\pi_2(1) = a + b(2/5) = ([1 \quad 0] \mathbf{P}^1)_2 = (\mathbf{P})_{12} = 1/5$$

we have that $a = 1/3$, $b = -1/3$, thus:

$$\pi_2(n) = 1/3 - 1/3 (2/5)^n, \quad n \geq 0$$

$$\pi_1(n) = 1 - \pi_2(n) = 2/3 + 1/3 (2/5)^n, \quad n \geq 0$$

Transient Solution

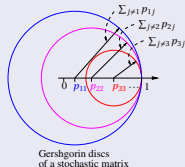
Eigenvalues of a Stochastic Matrix

- \mathbf{P} has **an eigenvalue equal to 1** ($\mathbf{P}\mathbf{x} = \lambda\mathbf{x}$, for $\lambda = 1$).

Proof: $\mathbf{P}\mathbf{e} = \mathbf{e}$, where $\mathbf{e} = [1 \ 1 \ \dots]^T$ is a column vector of 1 (all rows of \mathbf{P} add to 1). □

- All eigenvalues of \mathbf{P} are $|\lambda_i| \leq 1$.

Proof: Using Gerschgorin's theorem *The eigenvalues of a matrix $\mathbf{P}_{n \times n}$ lie within the union of the n circular disks with center p_{ii} and radius $\sum_{j \neq i} |p_{ij}|$ in \mathbb{C} . Since $\sum_j p_{ij} = 1$, the property is proved.* □

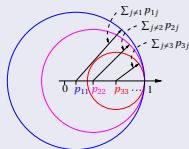


- The eigenvalue **$\lambda = 1$** is **single** if **\mathbf{P} is irreducible** (Perron-Frobenius theorem). \mathbf{P} is irreducible if all states communicate: for some n , $p_{ij}(n) = (\mathbf{P}^n)_{ij} > 0$, $\forall i, j$.

Transient Solution

Proof of Gerschgorin's theorem

Gerschgorin's theorem: *The eigenvalues of a matrix $\mathbf{P}_{n \times n}$ lie within the union of the n circular disks with center p_{ii} and radius $\sum_{j \neq i} |p_{ij}|$ in \mathbb{C} .*



Gerschgorin discs
of a stochastic matrix

Proof: From $\mathbf{P}\mathbf{x} = \lambda\mathbf{x}$ we have

$$\sum_j p_{ij} x_j = \lambda x_i \quad \forall i \in \{1, \dots, n\}.$$

We choose i such that $|x_i| = \max_j |x_j|$. Thus,

$\sum_{j \neq i} p_{ij} x_j = \lambda x_i - p_{ii} x_i$, and

$$|\lambda - p_{ii}| = \left| \sum_{j \neq i} p_{ij} \frac{x_j}{x_i} \right| \leq \sum_{j \neq i} \left| p_{ij} \frac{x_j}{x_i} \right| \leq \sum_{j \neq i} |p_{ij}|$$

and the equation $|\mathbf{x} - \mathbf{c}| \leq r$, $\mathbf{x}, \mathbf{c} \in \mathbb{C}, r \in \mathbb{R}$ is a disk of center \mathbf{c} and radius r in \mathbb{C} . □



Transient Solution

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Example: Aloha

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Chain with a Defective Matrix

- What if \mathbf{P} cannot be diagonalized? (**defective** matrix).
- Let λ_l , $l = 1, \dots, L$ be the eigenvalues of $\mathbf{P}^{N \times N}$, each with multiplicity k_l ($k_l \geq 1$, $\sum_l k_l = N$), and a possible eigenvalue $\lambda_1 = 0$ with multiplicity k_1 . Then [1]:

$$\pi_j(n) = \sum_{m=0}^{k_1-1} a_j^{(1,m)} I(n=m) + \sum_{l=2}^L \lambda_l^n \sum_{m=0}^{k_l-1} a_j^{(l,m)} n^m, \\ 1 \leq j \leq N, n \geq 0$$

$I(n=m)$ is the indicator func.: $I(n) = 1$ if $n = m$, $I(n) = 0$ if $n \neq m$.

- [1] Llorenç Cerdà-Alabern. *Transient Solution of Markov Chains Using the Uniformized Vandermonde Method*. Tech. rep. UPC-DAC-RR-XCSD-2010-2. Universitat Politècnica de Catalunya, Dec. 2010. URL: https://www.ac.upc.edu/app/research-reports/html/research_center_index-XCSD-2010,en.html.



Transient Solution

Example

- Assume a DTMC with

$$\mathbf{P} = \begin{bmatrix} 3/4 & 1/4 & 0 \\ 0 & 3/4 & 1/4 \\ 1 & 0 & 0 \end{bmatrix}$$

- We want the probability of being in state 1 in n steps starting from state 1: $\pi_1(n)$ with $\pi_1(0) = 1$.
- It can be easily found that the **eigenvalues** of \mathbf{P} are $\lambda_1 = 1$ and $\lambda_2 = 1/4$ with multiplicity 2. We guess:

$$\pi_1(n) = a + 1/4^n(b + cn)$$

- Imposing $\pi_1(0) = 1$, $\pi_1(1) = 3/4$, $\pi_1(2) = (3/4)^2$, we have:

$$\pi_1(n) = \frac{4}{9} + \frac{1}{4^n} \left(\frac{5}{9} + \frac{2}{3} n \right)$$



Part II

Discrete Time Markov Chains (DTMC)

Outline

- Definition of a DTMC
- Transient Solution
- **Classification of States**
- Steady State
- Reversed Chain
- Reversible Chains
- Research Example: Aloha
- Finite Absorbing Chains

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Objective

- Identify the different **types of behavior** that the chain can have.
- Introduce the concepts of **first passage probability** and **mean recurrence time**.



Classification of States

Irreducibility

- A state j is said to **communicate** with i , $i \leftrightarrow j$, if $p_{ij}(m_1) > 0$, $p_{ji}(m_2) > 0$ for some $m_1, m_2 \geq 0$.
- We define an **irreducible closed set, ICS** C_k as a set where all states communicate with each other, and have no transitions to other states out of the set:

$$i \leftrightarrow j, \forall i, j \in C_k \text{ and } p_{ij} = 0, \forall i \in C_k, j \notin C_k$$
 (note that for $i \in C_k, j \notin C_k$ we have: $p_{ij}(2) = \sum_k p_{ik} p_{kj} = 0$, since $p_{ik} = 0$ if $k \notin C_k$, and $p_{kj} = 0$ if $k \in C_k$. Thus, $p_{ij}(n) = 0, \forall n$.)
- An **absorbing state** form an ICS of only one element. This state, i , must have $p_{ii} = 1, p_{ij} = 0 \forall j \neq i$.
- Transient states** do not belong to any ICS.
- A MC is **irreducible** if all the states form a unique ICS.



Classification of States

Irreducibility

- Assume a MC has **M ICSs**: By properly numbering the states, we can write \mathbf{P} as an M block diagonal matrix with the probabilities of the transient states in the last rows.
- Example**, if $M = 3$:

$$\mathbf{P} = \begin{array}{|c|c|c|c|} \hline \mathbf{P}_1 & & & \\ \hline & \mathbf{P}_2 & & \\ \hline & & \mathbf{P}_3 & \\ \hline \text{at least} & & & \mathbf{T} \\ \text{one} & & & \\ > 0 & & & \\ \hline \end{array}$$

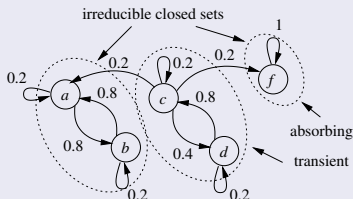
$$\Rightarrow \boldsymbol{\pi}(n) = \boldsymbol{\pi}(0) \mathbf{P}^n = \boldsymbol{\pi}(0)$$

$$\begin{array}{|c|c|c|c|} \hline \mathbf{P}_1^n & & & \\ \hline & \mathbf{P}_2^n & & \\ \hline & & \mathbf{P}_3^n & \\ \hline \text{at least} & & & \mathbf{T}^n \\ \text{one} & & & \\ > 0 & & & \\ \hline \end{array}$$

- Note that **the M sub-matrices are stochastic** (their rows sum 1).

Classification of States

Example



$$\mathbf{P} = \begin{array}{c} \begin{matrix} a & b & f & c & d \end{matrix} \\ \begin{matrix} a \\ b \\ f \\ c \\ d \end{matrix} \begin{bmatrix} 0,2 & 0,8 & 0 & 0 & 0 \\ 0,8 & 0,2 & 0 & 0 & 0 \\ 0 & 0 & 1,0 & 0 & 0 \\ 0,2 & 0 & 0,2 & 0,2 & 0,4 \\ 0 & 0 & 0 & 0,8 & 0,2 \end{bmatrix} \end{array}$$

$$\mathbf{P}^{\infty} = \begin{array}{c} \begin{matrix} a & b & f & c & d \end{matrix} \\ \begin{matrix} a \\ b \\ f \\ c \\ d \end{matrix} \begin{bmatrix} 0,5 & 0,5 & 0 & 0 & 0 \\ 0,5 & 0,5 & 0 & 0 & 0 \\ 0 & 0 & 1,0 & 0 & 0 \\ 0,25 & 0,25 & 0,5 & 0 & 0 \\ 0,25 & 0,25 & 0,5 & 0 & 0 \end{bmatrix} \end{array}$$

- What is the meaning of the probabilities in \mathbf{P}^{∞} ? (recall that $(\mathbf{P}^n)_{ij} = p_{ij}(n) = P(X(n) = j \mid X(0) = i)$).



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$$\mathbf{P} = \begin{array}{|c|c|c|} \hline \mathbf{P}_1 & & \mathbf{0} \\ \hline & \mathbf{P}_2 & \\ \hline \mathbf{0} & & \mathbf{P}_3 \\ \hline \text{at least} & & \\ \text{one } > 0 & & \mathbf{T} \\ \hline \end{array}$$

Theorem *The multiplicity of the eigenvalue $\lambda = 1$ is equal to the number of irreducible closed sets.*

Proof The characteristic polynomial of \mathbf{P} is equal to the product of the characteristic polynomials of the sub-matrices \mathbf{P}_i and \mathbf{T} . Since \mathbf{P}_i are irreducible stochastic, each will have a single eigenvalue equal to 1. For the transitorial states it must be $\lim_{n \rightarrow \infty} \mathbf{T}^n = \mathbf{0}$. Thus, all the eigenvalues of \mathbf{T} must be $|\lambda| < 1$. \square

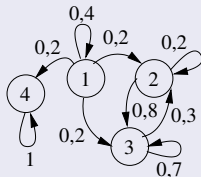
NOTE: in the closed form solution there is only one unknown associated with $\lambda = 1$, otherwise $\sum_{m=0}^{k_l-1} a_j^{(l,m)} n^m$ will diverge as $n \rightarrow \infty$ (i.e. $a_j^{(l,m)} = 0, m > 0$), and $a_j^{(l,0)} = \lim_{n \rightarrow \infty} \pi_j(n)$.



Classification of States

Transient and Recurrent

- **Recurrent**: States that, being visited, they are visited again with probability 1. They are visited an infinite number of times when $n \rightarrow \infty$.
- **Transient**: States that, being visited, have a probability > 0 of never being visited again. They are visited a finite number of times when $n \rightarrow \infty$.
- **Absorbing**: A single (recurrent) state where the chain remains with probability = 1.



State 1 is **transient**
States 2 and 3 are **recurrent**
State 4 is **absorbing**

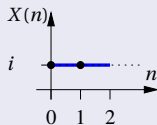


Classification of States

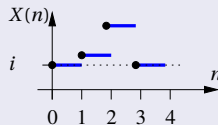
First Passage (Transition) Probabilities

- To derive a classification criteria, we shall study the distribution of the number of steps to **go for the first time from a state i another state j** . Definition:

$$f_{ij}(n) = P\left(\begin{array}{l} \text{first transition into state } i \\ \text{in } n \text{ steps starting from } i \end{array}\right)$$



first transition in 1 step



first transition in 3 steps

- Do **not confuse** with the n -step transition probability $p_{ij}(n)$, where the state i can be visited in the intermediate states.



Classification of States

Relation between $f_{ii}(n)$ and $p_{ii}(n)$

- $f_{ii}(n)$ and $p_{ii}(n)$ satisfy:

$$f_{ii}(1) = p_{ii}(1)$$

$$p_{ii}(n) = \sum_{l=1}^n f_{ii}(l) p_{ii}(n-l), n \geq 1$$

- The probability that the MC **eventually enters state i starting from i** is given by:

$$f_{ii} = \sum_{n=1}^{\infty} f_{ii}(n)$$

- If $f_{ii} = 1$ we say i is a **recurrent state**.
- If $f_{ii} < 1$ we say i is a **transient state**.



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Generalization to Any State Pair

- Analogously to $f_{ii}(n)$, we define the probability of the **first passage to state j starting from any state i** in n steps: $f_{ij}(n)$.
- $f_{ij}(n)$ and $p_{ij}(n)$ satisfy:

$$p_{ij}(n) = \sum_{l=1}^n f_{ij}(l) p_{ij}(n-l), \quad n \geq 1$$



Classification of States

Recursive Equation for the First Passage Probabilities

- Recall that the The probability that the MC **eventually enters state j starting from i** is given by: $f_{ij} = \sum_{n=1}^{\infty} f_{ij}(n)$
- f_{ij}** can be computed as follows: Assume we are in i . With probability p_{ij} we will go to j in one step. Otherwise, we will go to k , $k \neq j$, and then we will reach j with probability f_{kj} . Thus:

$$f_{ij} = p_{ij} + \sum_{k \neq j} p_{ik} f_{kj}$$

- If there are more than 1 **absorbing states**, we can compute the probability to reach them using this method (if there is only 1, say j , then $f_{ij} = 1, \forall i$).



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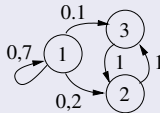
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Example: Recurrence Times Using the Definition



$$\mathbf{P} = \begin{bmatrix} 0,7 & 0,2 & 0,1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$f_{21}(n) = f_{31}(n) = 0$$

$$f_{11}(n) = 0,7 I(n=1)$$

$$f_{22}(n) = f_{33}(n) = I(n=2)$$

$$f_{23}(n) = f_{32}(n) = I(n=1)$$

$$f_{11} = 0,7$$

$$f_{12} = f_{13} = 1 \quad f_{22} = f_{23} = 1$$

$$f_{32} = f_{33} = 1 \quad f_{21} = f_{31} = 0$$

$$f_{12}(n) = \begin{cases} 0,2, & n=1 \\ 0,7^{n-1} 0,2 + 0,7^{n-2} 0,1, & n>1 \end{cases}$$

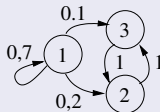
$$f_{13}(n) = \begin{cases} 0,1, & n=1 \\ 0,7^{n-1} 0,1 + 0,7^{n-2} 0,2, & n>1 \end{cases}$$

- State 1 is **transient**. States 2 and 3 are **recurrent**.



Classification of States

Example: First Passage Probability Using Recursion



$$\mathbf{P} = \begin{bmatrix} 0,7 & 0,2 & 0,1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

- We have:

$$f_{12} = p_{11}f_{12} + p_{12} + p_{13}f_{32}$$

- Clearly $f_{32} = 1$, thus:

$$f_{12} = 0,7f_{12} + 0,2 + 0,1 \times 1 \Rightarrow f_{12} = 1$$

as before.



Classification of States

Mean Recurrence Time

- If $f_{ii} = 1$ we say i is a **recurrent state**.
- If $f_{ii} < 1$ we say i is a **transient state**.
- When $f_{ii} = 1$, we define the **mean recurrence time** m_{ii} as:

$$m_{ii} = \sum_{n=1}^{\infty} n f_{ii}(n)$$

- m_{ii} is the **average number of steps to eventually reach i starting from i** . If $f_{ii} < 1$ (**transient state**) then we define $m_{ii} = \infty$.
- Classification of **recurrent states** ($f_{ii} = 1$):
 - If $m_{ii} = \infty$ the state is **null recurrent**: it takes an ∞ time to reach the state after leave it. Can only happen in chains with an infinite number of states.
 - If $m_{ii} < \infty$ the state is **positive recurrent**: the state is reached in a finite time after leave it.



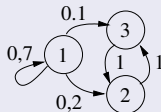
Classification of States

Property of States

In **finite MC**:

- 1 States can be only of type positive recurrent or transient.
- 2 At least one state must be positive recurrent.
- 3 There are not null recurrent states.

• **Example:**



- State 1 is transient. States 2 and 3 are positive recurrent.



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Generalization to Any State Pair

- When $f_{ij} = 1$, the average number of steps to eventually reach j starting from i , m_{ij} is given by:

$$m_{ij} = \sum_{n=1}^{\infty} n f_{ij}(n)$$

- If state j can not be reached starting from state i with probability one (if $f_{ij} < 1$), then we define $m_{ij} = \infty$.



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Recursive Equation for the Mean Recurrence Time

- Recall that the **mean recurrence time** $m_{ij} = \sum_{n \geq 1} n f_{ij}(n)$ is the average number of steps to eventually reach j starting from i , i.e. it is the mean first passage time from state i to j .
- When $f_{ij} = 1$, m_{ij} can be computed as follows: Assume we are in i . With probability p_{ij} we will go to j in one step. Otherwise, we will go to k , $k \neq j$, and then it will take m_{kj} steps to reach j . Thus:

$$m_{ij} = p_{ij} + \sum_{k \neq j} p_{ik} (1 + m_{kj}) = 1 + \sum_{k \neq j} p_{ik} m_{kj}$$

since $\sum_j p_{ij} = 1$.



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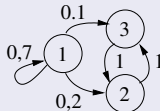
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$$\mathbf{P} = \begin{bmatrix} 0,7 & 0,2 & 0,1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

- We have:

$$m_{12} = p_{12} + p_{11} (1 + m_{12}) + p_{13} (1 + m_{32}) = 1 + p_{11} m_{12} + p_{13} m_{32}$$

- Clearly $m_{32} = 1$, thus:

$$m_{12} = 1 + 0,7 m_{12} + 0,1 \times 1 \Rightarrow m_{12} = 11/3.$$