Tutorial on Gecode Constraint Programming

Combinatorial Problem Solving (CPS)

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Gecode

- Gecode is environment for developing constraint-programming based progs
 - open source: extensible, easily interfaced to other systems
 - free: distributed under MIT license
 - ullet portable: rigidly follows the C++ standard
 - accessible: comes with a manual and other supplementary materials
 - efficient: very good results at competitions, e.g. MiniZinc Challenge
- Developed by C. Schulte, G. Tack and M. Lagerkvist
- Available at: http://www.gecode.org

Basics

- Gecode is a set of C++ libraries
- Models (= CSP's in this context) are C++ programs that must be compiled with Gecode libraries and executed to get a solution
- Models are implemented using spaces, where variables, constraints, etc. live
- Models are derived classes from the base class Space.
 The constructor of the derived class
 - declares the CP variables and their domains,
 - posts the constraints, and
 - specifies how the search is to be conducted.
- For the search to work, a model must also implement:
 - ◆ a copy constructor, and
 - ◆ a copy function

- Find different digits for the letters S, E, N, D, M, O, R, Y such that equation SEND+MORE=MONEY holds and there are no leading 0's
- Code of this example available at http://www.cs.upc.edu/~erodri/cps.html

```
// To use integer variables and constraints
#include <gecode/int.hh>

// To make modeling more comfortable
#include <gecode/minimodel.hh>

// To use search engines
#include <gecode/search.hh>

// To avoid typing Gecode:: all the time
using namespace Gecode;
```

```
class SendMoreMoney : public Space {
protected:
 IntVarArray x;
                       // *this is called 'home space'
public:
 SendMoreMoney(): \times(*this, 8, 0, 9) {
   IntVar s(x[0]), e(x[1]), n(x[2]), d(x[3]),
          m(x[4]), o(x[5]), r(x[6]), y(x[7]);
    rel(*this, s != 0);
   rel(*this, m!= 0);
    distinct(*this, x);
    rel(*this, 1000*s + 100*e + 10*n + d
               + 1000*m + 100*o + 10*r + e
   = 10000*m + 1000*o + 100*n + 10*e + y);
   branch(*this, x, INT_VAR_SIZE_MIN(), INT_VAL_MIN());
```

- The model is implemented as class SendMoreMoney, which inherits from the class Space
- Declares an array x of 8 new integer CP variables that can take values from 0 to 9
- To simplify posting the constraints, the constructor defines a variable of type IntVar for each letter. These are synonyms of the CP variables, not new ones!
- distinct: values must be \neq pairwise (aka all-different)
- Variable selection: the one with smallest domain size first (INT_VAR_SIZE_MIN())
- Value selection: the smallest value of the selected variable first (INT_VAL_MIN())

```
SendMoreMoney(SendMoreMoney& s)
    : Space(s) {
    x.update(*this, s.x);
  virtual Space* copy() {
    return new SendMoreMoney(*this);
  void print() const {
    std::cout << x << std::endl;</pre>
}; // end of class SendMoreMoney
```

- The copy constructor must call the copy constructor of Space and then copy the rest of members (those with CP variables by calling update)
 In this example this amounts to invoking Space(s)
 and updating the variable array x with x.update(*this, s.x);
- A space must implement an additional copy() function that is capable of returning a fresh copy of the model during search.
 Here it uses copy constructor: return new SendMoreMoney(*this);
- We may have other functions (like print () in this example)

```
int main() {
    SendMoreMoney* m = new SendMoreMoney;

DFS<SendMoreMoney> e(m);
    delete m;

while (SendMoreMoney* s = e.next()) {
    s->print();
    delete s;
}
```

- Let us assume that we want to search for all solutions:
 - 1. create a model and a search engine for that model
 - (a) create an object of class SendMoreMoney
 - (b) create a search engine DFS<SendMoreMoney> (depth-first search) and initialize it with a model.

As the engine takes a clone, we can immediately delete m after the initialization

2. use the search engine to find all solutions

The search engine has a next() function that returns the next solution, or NULL if no more solutions exist

A solution is again a model (in which domains are single values). When a search engine returns a model, the user must delete it.

■ To search for a single solution: replace while by if

- Gecode may throw exceptions when creating vars, etc.
- It is a good practice to catch all these exceptions.

 Wrap the entire body of main into a try statement:

```
int main() {
 try {
    SendMoreMoney* m = new SendMoreMoney;
    DFS<SendMoreMoney> e(m);
    delete m:
    while (SendMoreMoney* s = e.next()) {
      s->print();
      delete s;
  catch (Exception e) {
    cerr << "Exception: " << e.what() << endl;
    return 1;
```

Compiling and Linking

Template of Makefile for compiling p.cpp and linking:

Executing

- Gecode is installed as a set of shared libraries
- Environment variable LD_LIBRARY_PATH has to be set to include <dir>/lib, where <dir> is installation dir
- E.g., edit file ~/.tcshrc (create it if needed) and add line

setenv LD_LIBRARY_PATH <dir>

■ In the lab: <dir> is /usr/local/lib

- lacktriangle Find different digits for the letters S, E, N, D, M, O, T, Y such that
 - lacktriangle equation SEND + MOST = MONEY holds
 - there are no leading 0's
 - lack MONEY is maximal
- Searching for a best solution requires
 - a function that constrains the search to consider only better solutions
 - ◆ a best solution search engine
- The model differs from SendMoreMoney only by:
 - ◆ a new linear equation
 - ◆ an additional constrain() function
 - a different search engine

New linear equation:

```
IntVar s(x[0]), e(x[1]), n(x[2]), d(x[3]), m(x[4]), o(x[5]), t(x[6]), y(x[7]);

...

rel(*this, 1000*s + 100*e + 10*n + d + 1000*m + 100*o + 10*s + t = 10000*m + 1000*o + 10*e + y);
```

constrain() function (_b is the newly found solution):

```
virtual void constrain(const Space& _b) {
 const SendMostMoney& b =
   static_cast < const SendMostMoney&>(_b);
IntVar e(x[1]), n(x[2]), m(x[4]), o(x[5]), y(x[7]);
IntVar b_e(b.x[1]), b_n(b.x[2]), b_m(b.x[4]),
        b_{-0}(b.x[5]), b_{-y}(b.x[7]);
int money = (10000*b_m.val()+1000*b_o.val()
               +100*b_n.val()+10*b_e.val()+b_y.val());
rel(*this, 10000*m + 1000*o + 100*n + 10*e + y > money);
```

■ The main function now uses a branch-and-bound search engine rather than plain depth-first search:

```
SendMostMoney* m = new SendMostMoney;
BAB<SendMostMoney> e(m);
delete m;
```

- The loop that iterates over the solutions found by the search engine is the same as before:
 - solutions are found with an increasing value of MONEY

Variables

- Integer variables are instances of the class IntVar
- Boolean variables are instances of the class BoolVar
- There exist also
 - ◆ FloatVar for floating-point variables
 - ◆ SetVar for integer set variables

(but we will not use them; see the reference documentation for more info)

Creating Variables

- An IntVar variable points to a variable implementation (= a CP variable). The same CP variable can be referred to by many IntVar variables
- New CP integer variables are created with a constructor:

```
IntVar \times(home, l, u);
```

This:

- declares a program variable x of type IntVar in the space home
- lacktriangle creates a new integer CP variable with domain $l, l+1, \ldots, u-1, u$
- makes x point to the newly created CP variable
- Domains can also be specified with an integer set IntSet:

```
IntVar \times (home, IntSet\{0, 2, 4\});
```

Creating Variables

- The default constructor and the copy constructor of an IntVar do not create a new variable implementation
- Default constructor:
 the variable doesn't refer to any variable implementation (it dangles)
- Copy constructor: the variable refers to the same variable implementation

```
IntVar x(home, 1, 4);
IntVar y(x);
```

x and y refer to the same variable implementation (they are synonyms)

Creating Variables

- Domains of integer vars must be included in [Int :: Limits :: min, Int :: Limits :: max] (implementation-dependent constants)
- Typically Int :: Limits :: $\max = 2147483646 \ (= 2^{31} 2)$, Int :: Limits :: $\min = -$ Int :: Limits :: \max
- Example of creation of a Boolean variable:

```
BoolVar x(home, 0, 1);
```

Note that the lower and upper bounds must be passed even it is Boolean!

Operations with Variables

- Min/max value in the current domain of a variable x: x.min() / x.max()
- To find out if a variable has been assigned: x.assigned()
- Value of the variable, if already assigned: x.val()
- \blacksquare To print the domain of a variable: cout $<< \times$
- To make a copy of a variable (e.g., for the copy constructor of the model): update

```
E.g. in
```

```
x.update(home, y);
```

variable x is assigned a copy of variable y

Arrays of Variables

- Integer variable arrays IntVarArray have similar functions to integer vars
- For example,

```
IntVarArray \times (home, 4, -10, 10);
```

creates a new array with 4 variables containing newly created CP variables with domain $\{-10, \ldots, 10\}$.

- x.assigned() returns if all variables in the array are assigned
- x. size () returns the size of the array
- For making copies update works as with integer variables

- Gecode provides argument arrays to be passed as arguments in functions that post constraints
 - ◆ IntArgs for integers
 - ◆ IntVarArgs for integer variables
 - BoolVarArgs for Boolean variables

For example:

```
IntVar s(x[0]), e(x[1]), n(x[2]), d(x[3]),
      m(x[4]), o(x[5]), r(x[6]), y(x[7]);
IntArgs c(4+4+5); IntVarArgs z(4+4+5);
c[0] = 1000; c[1] = 100; c[2] = 10; c[3] = 1;
z[0] = s; z[1] = e; z[2] = n; z[3] = d;
c[4] = 1000; c[5] = 100; c[6] = 10; c[7] = 1;
z[4] = m; z[5] = o; z[6] = r; z[7] = e;
c[8] = -10000; c[9] = -1000; c[10] = -100; c[11] = -10; c[12] = -1;
z[8] = m; z[9] = o; z[10] = n; z[11] = e; z[12] = y;
linear(*this, c, z, IRT_EQ, 0); // c.z = 0, where . is dot product
```

Or equivalently:

```
IntVar s(x[0]), e(x[1]), n(x[2]), d(x[3]),
      m(x[4]), o(x[5]), r(x[6]), y(x[7]);
IntArgs c({
         1000, 100, 10, 1,
        1000, 100, 10, 1,
-10000, -1000, -100, -10, -1});
IntVarArgs z({
           s, e, n, d,
         m, o, r, e,
     m, o, n, e, y } );
linear(*this, c, z, IRT_EQ, 0);
```

- Integer argument arrays with simple sequences of integers can be generated using IntArgs :: create(n, start, inc)
 - n is the length of the array
 - start is the starting value
 - inc is the increment from one value to the next (default: 1)

```
IntArgs::create(5,0)  // creates 0,1,2,3,4
IntArgs::create(5,4,-1) // creates 4,3,2,1,0
IntArgs::create(3,2,0)  // creates 2,2,2
IntArgs::create(6,2,2)  // creates 2,4,6,8,10,12
```

Posting Constraints

- Next: focus on constraints for integer/Boolean variables
- We will see the most basic functions for posting constraints.
 (post functions)

Look up the documentation for more info.

- Relation constraints are of the form $E_1 \bowtie E_2$, where E_1 , E_2 are integer/Boolean expressions, \bowtie is a relation operator
- Integer expressions are built up from:
 - ◆ arithmetic operators: +, -, *, /, %
 - integer values
 - integer/Boolean variables
 - ◆ sum(x): sum of the array x
 - sum(c,x): weighted sum (dot product)
 - min(x): min of the array x
 - ♦ max(x): max of the array x
 - element(x, i): the i-th element of the array x
 - **♦** ...

Relations between integer expressions are:

```
==,!=,<=,<,>=,>
```

Relation constraints are posted with function rel

```
rel(home, x+2*sum(z) < 4*y);
rel(home, a+b*(c+d) == 0);
```

- Boolean expressions are built up from:
 - Boolean variables
 - lack element(x, i): the i-th element of the Boolean array x
 - integer relations
 - ♦ !: negation
 - ◆ &&: conjunction
 - ♦ ||: disjunction
 - ◆ ==: equivalence
 - ♦ >>: implication

■ Examples:

■ An alternative less comfortable interface:

rel (home, E_1 , \bowtie , E_2); where \bowtie for integer relations may be:

- ◆ IRT_EQ: equal
- ◆ IRT_NQ: different
- ◆ IRT_GR: greater than
- ◆ IRT_GQ: greater than or equal
- ◆ IRT_LE: less than
- ◆ IRT_LQ: less than or equal

and for Boolean relations is one of:

- ◆ BOT_AND: conjunction
- ◆ BOT_OR: disjunction
- ◆ BOT_EQV: equivalence
- ◆ BOT_IMP: implication
- **•** ...

Here x, y are arrays of integer variables, z an integer variable

- rel (home, x, IRT_LQ, z): all vars in x are $\leq z$
- rel (home, x, IRT_LE, y): x is lexicographically smaller than y
- Inear (home, a, x, \bowtie, z): $a^T x \bowtie z$
- linear (home, x, \bowtie , z): $\sum x_i \bowtie z$

Distinct Constraint

distinct (home, x) enforces that integer variables in array x take pairwise distinct values (aka alldifferent)

```
IntVarArray \times(home, 10, 1, 10);
distinct(home, \times);
```

distinct (home, c, \times); for an array c of type IntArgs and an array of integer variables \times of same size, constrains the variables in \times such that

$$x_i + c_i \neq x_j + c_j$$

for
$$0 \le i < j < |\mathbf{x}|$$

Channel Constraints

- Channel constraints link integer to Boolean variables, and integer variables to integer variables. For example:
 - For Boolean variable array x and integer variable y, channel(home, x, y) posts $x_i = 1 \leftrightarrow y = i$ for $0 \le i, j < |x|$
 - For two integer variable arrays x and y of same size, channel(home, x, y) posts $x_i = j \leftrightarrow y_j = i$ for $0 \le i, j < |x|$

Reified Constraints

Some constraints have reified variants: satisfaction is monitored by a Boolean variable (indicator/control variable) When allowed, the control variable is passed as a last argument: e.g.,

```
rel(home, x == y, b);
```

posts $b = 1 \Leftrightarrow x = y$, where x, y are integer variables and b is a Boolean variable

Reified Constraints

- Instead of full reification, we can post half reification: only one direction of the equivalence
- Functions eqv, imp, pmi take a Boolean variable and return an object that specifies the reification:

```
rel(home, x == y, eqv(b)); // b = 1 \Leftrightarrow x = y rel(home, x == y, imp(b)); // b = 1 \Rightarrow x = y rel(home, x == y, pmi(b)); // b = 1 \Leftarrow x = y
```

Hence passing eqv(b) is equivalent to passing b

Propagators

- For many constraints, Gecode provides different propagators with different pruning power
- Post functions take an optional argument that specifies the propagator
- Possible values:
 - ◆ IPL_DOM: perform domain propagation.

 Sometimes domain consistency (i.e., arc consistency) is achieved.
 - ◆ IPL_BND: perform bounds propagation.

 Sometimes bounds consistency is achieved
 - **♦** ...
 - ◆ IPL_DEF: default of the constraint (check reference documentation)
- Different propagators have different tradeoffs of cost/pruning power.

Branching

- Gecode offers predefined variable-value branching: when calling branch(home, x, ?, ?) for branching on array of integer vars x,
 - ◆ 3rd arg defines the heuristic for selecting the variable
 - 4th arg defines the heuristic for selecting the values
- E.g. for an array of integer vars x the following call

```
branch (home, x, INT_VAR_MIN_MIN(), INT_VAL_SPLIT_MIN());
```

- selects the var y with smallest min value in the domain (if tie, the 1st)
- lacktriangle creates a choice with two alternatives $y \leq n$ and y > n where

$$n = \frac{\min(y) + \max(y)}{2}$$

and chooses $y \leq n$ first

Integer Variable Selection

- INT_VAR_NONE(): first unassigned
 INT_VAR_RND(r): randomly, with random number generator r
 INT_VAR_DEGREE_MIN(): smallest degree
 INT_VAR_DEGREE_MAX(): largest degree
- INT_VAR_SIZE_MIN(): smallest domain size
- INT_VAR_SIZE_MAX(): largest domain size
- **.**..

Boolean Variable Selection

- BOOL_VAR_NONE(): first unassigned
- \blacksquare BOOL_VAR_RND(r): randomly, with random number generator r
- BOOL_VAR_DEGREE_MIN(): smallest degree
- BOOL_VAR_DEGREE_MAX(): largest degree
- **.**.

Integer Value Selection

- INT_VAL_RND(r): random value
 INT_VAL_MIN(): smallest value
 INT_VAL_MAX(): largest value
 INT_VAL_SPLIT_MIN(): values not great
- INT_VAL_SPLIT_MIN(): values not greater than $\frac{min+max}{2}$
- INT_VAL_SPLIT_MAX(): values greater than $\frac{min+max}{2}$
- ..

Boolean Value Selection

- BOOL_VAL_RND(r): random value■ BOOL_VAL_MIN(): smallest value
- BOOL_VAL_MAX(): largest value
- **.**..