

# Guaranteed Voronoi Diagrams of Uncertain Sites

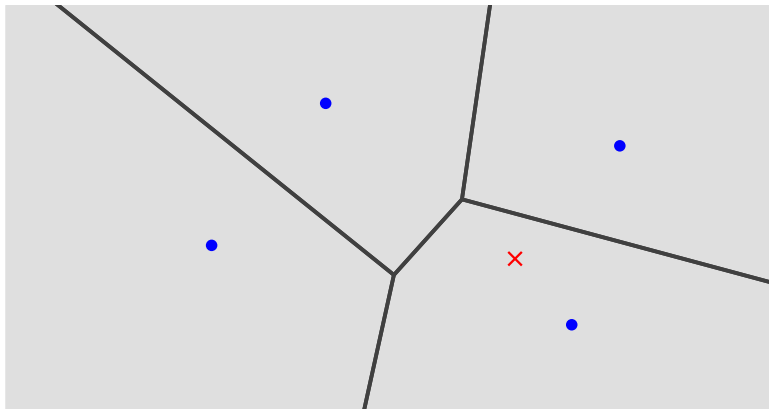
William Evans  
Jeff Sember

University of British Columbia

August 13-15, 2008

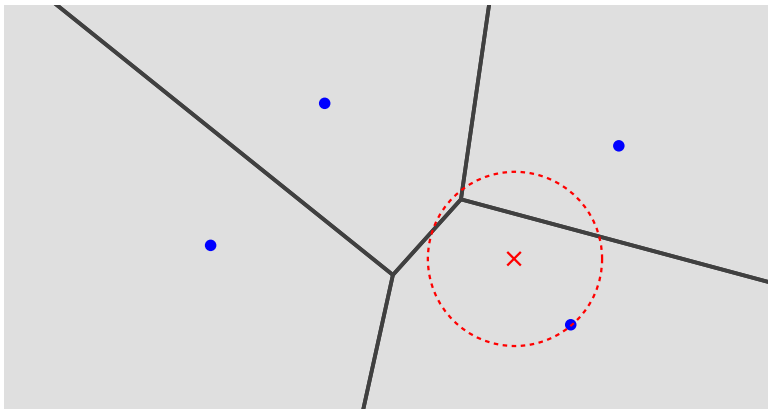
# Introduction

## Standard Voronoi diagram



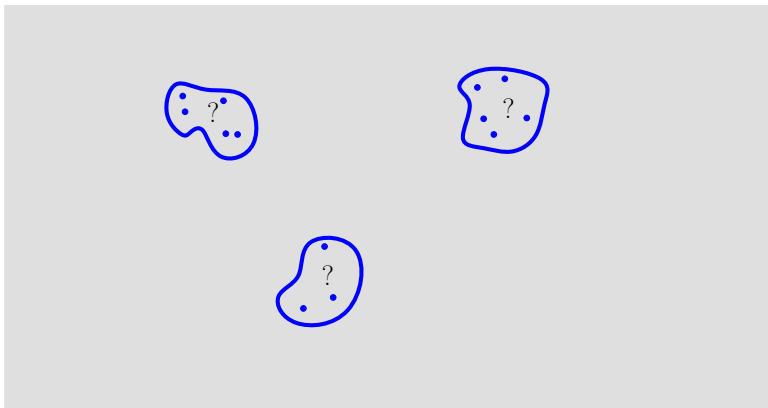
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## Standard Voronoi diagram



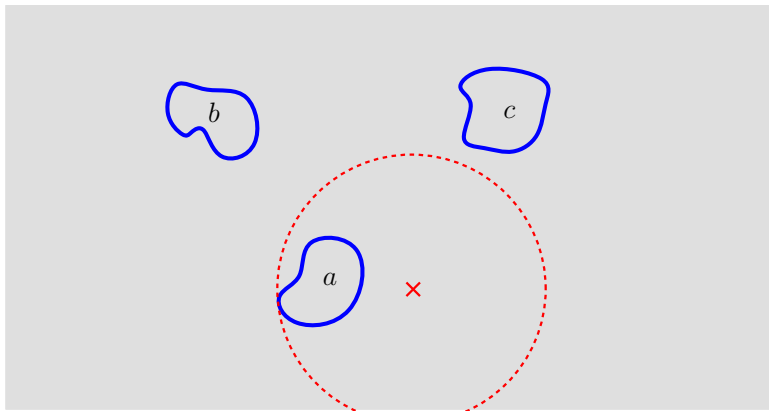
# Introduction

What if exact locations of sites are unknown?



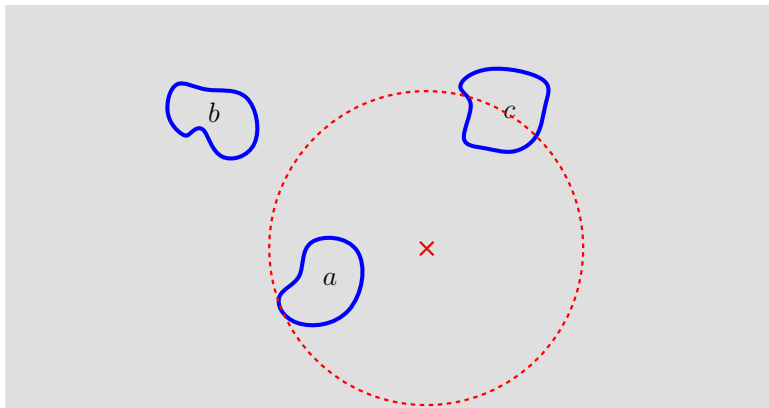
# Introduction

$X$  is guaranteed closest to  $a$



# Introduction

Is  $X$  closer to  $a$  than  $c$ ? Than  $b$ ?



# The Problem

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- exact location of  $n$  sites is unknown
- each site is known to lie within a region
- what can be said about arbitrary point in  $\mathbb{R}^2$ ?
- what does such a **Guaranteed Voronoi Diagram** look like?

# Outline

- 1 Properties
- 2 Uncertain discs
- 3 Uncertain polygons
- 4 Guaranteed Subset Voronoi Diagrams
- 5 Conclusion

# Properties

- Uncertain regions  $\mathcal{D} = \{D_1, \dots, D_n\}$

# Properties

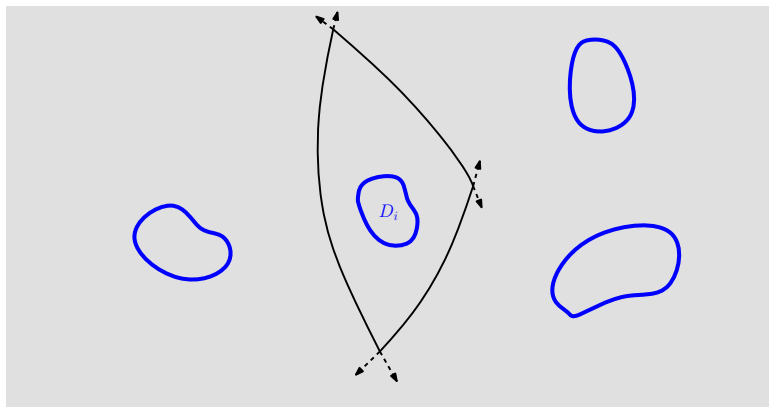
- Uncertain regions  $\mathcal{D} = \{D_1, \dots, D_n\}$
- Half plane  $H(i, j)$  :  
points guaranteed closer to  $D_i$  than  $D_j$

# Properties

- Uncertain regions  $\mathcal{D} = \{D_1, \dots, D_n\}$
- Half plane  $H(i, j)$  :  
points guaranteed closer to  $D_i$  than  $D_j$
- Edge  $\langle i, j \rangle$  :  
boundary of  $H(i, j)$   
farthest point in  $D_i$  as close as nearest point in  $D_j$

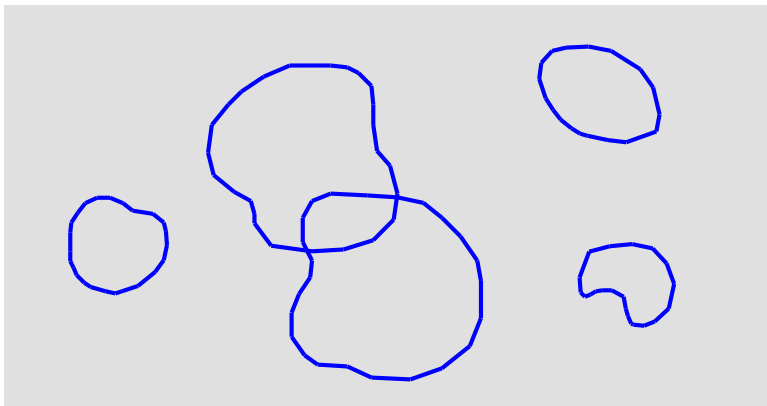
# Properties

Cell for  $D_i$  :  $\bigcap_{j \neq i} H(i,j)$



# Properties

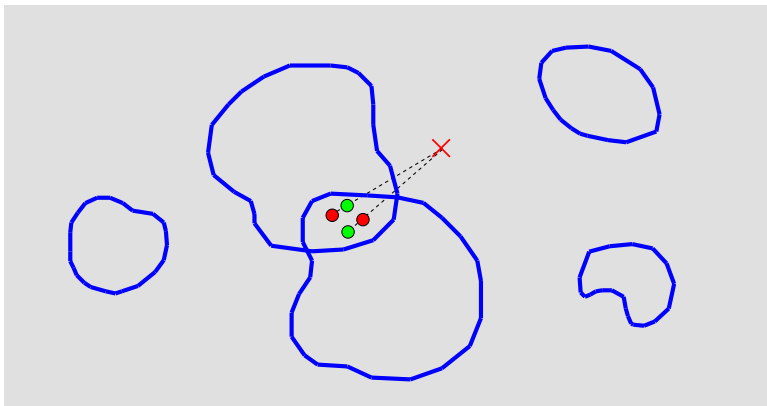
What if regions overlap?





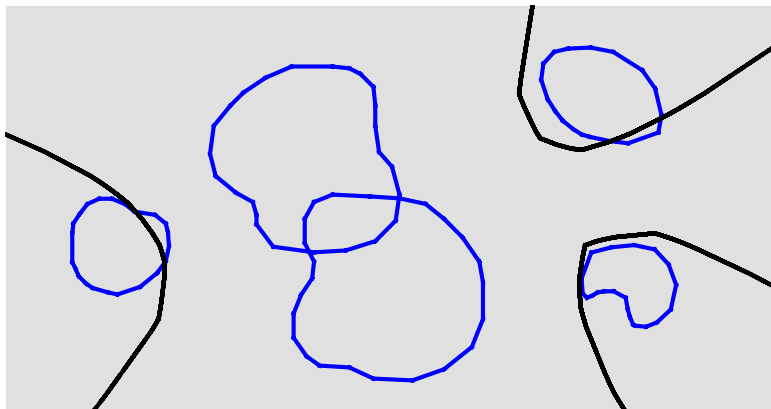
# Properties

No guarantee possible



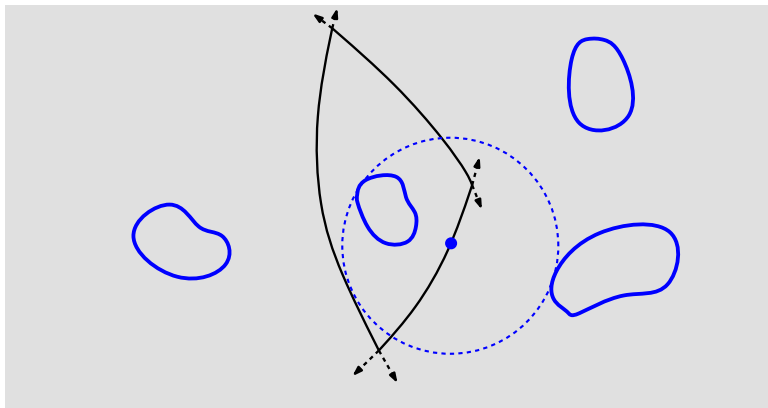
# Properties

Cell for both regions is empty



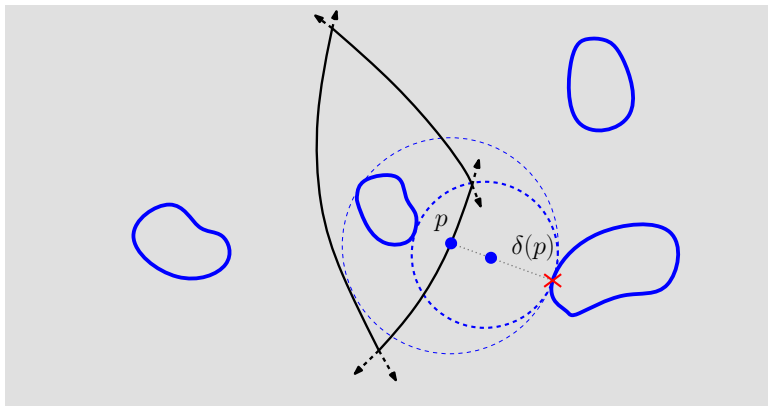
# Properties

## Lemma 1



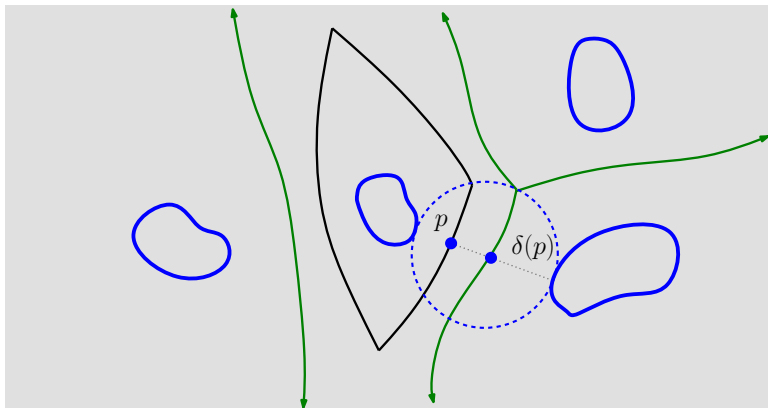
# Properties

$\delta(\cdot)$  function



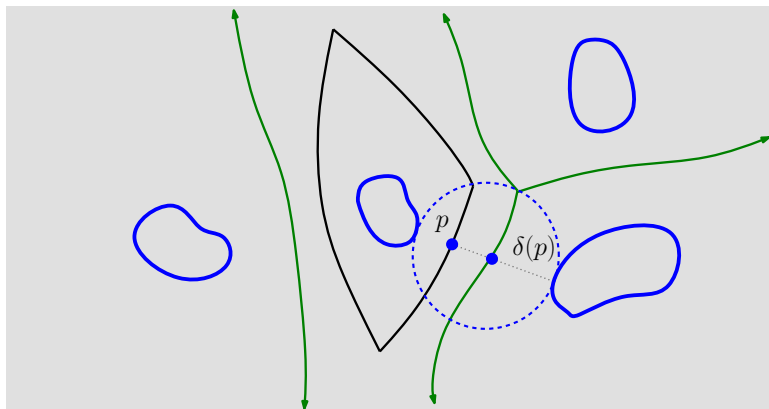
# Properties

Maps points on **guaranteed** edges to **standard** edges



# Properties

Lemma 3:  $\delta(\cdot)$  preserves ccw order

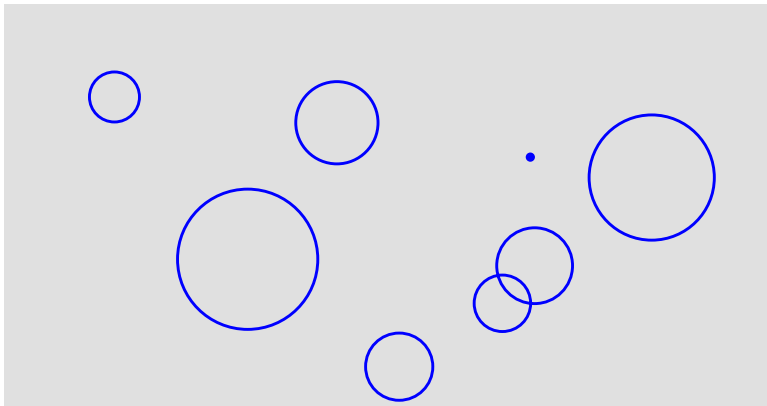


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# Uncertain discs

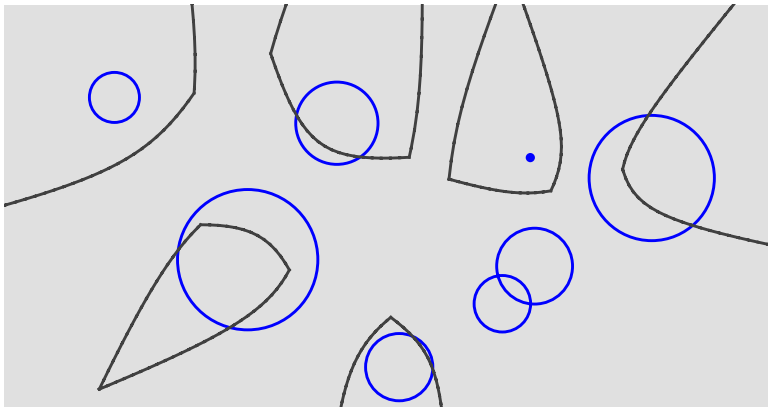
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# Uncertain discs

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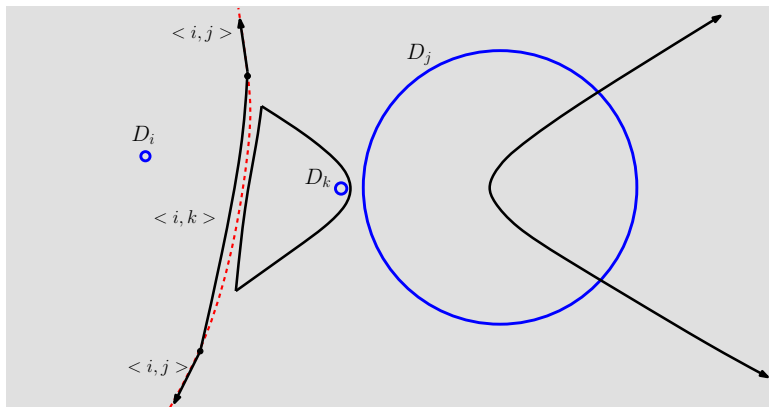
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- $\langle i, j \rangle = \{ p \mid \text{dist}(p, S_j) - \text{dist}(p, S_i) = \text{constant} \}$
- $\langle i, j \rangle$  is a hyperbolic arc

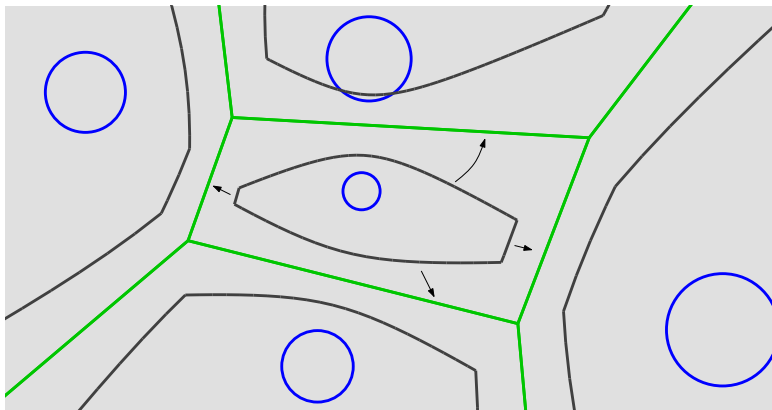
# Uncertain discs

More than one edge  $\langle i, j \rangle$  can appear



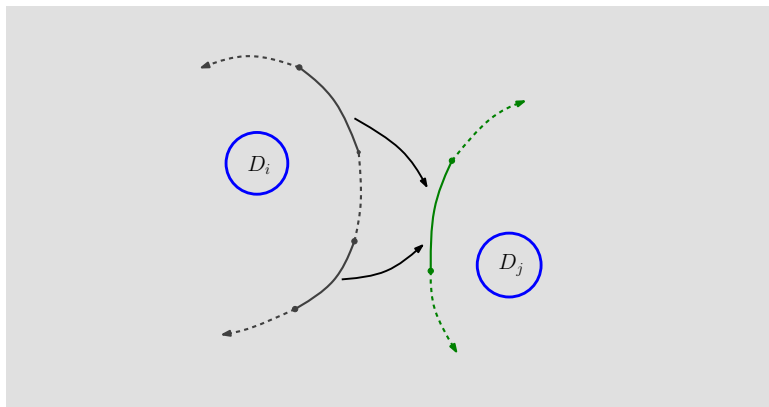
# Uncertain discs: Complexity

Each edge  $\langle i, j \rangle$  charged to edge of **standard Voronoi diagram**



# Uncertain discs: Complexity

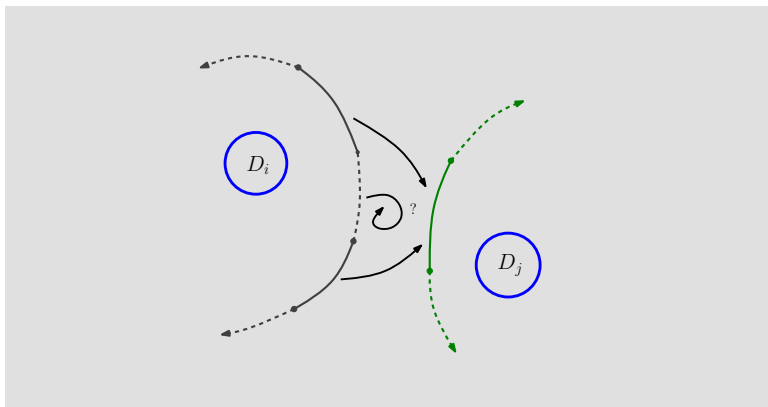
Suppose distinct edges  $\langle i, j \rangle$  charged to same standard edge. . .





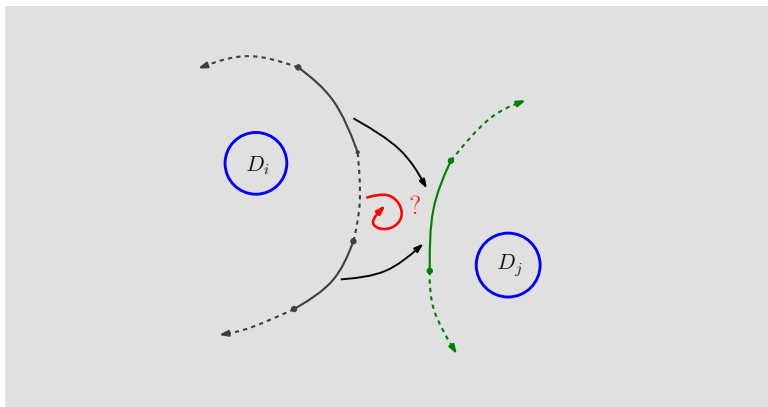
# Uncertain discs: Complexity

... edge between them must be charged somewhere...



# Uncertain discs: Complexity

... violates **Lemma 3** (ccw order of  $\delta$  mapping)



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## Theorem 4

**Guaranteed Voronoi Diagram** for discs has linear complexity

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- construct standard Voronoi diagram of discs  
in  $O(n \log n)$  time [S. Fortune, '86]

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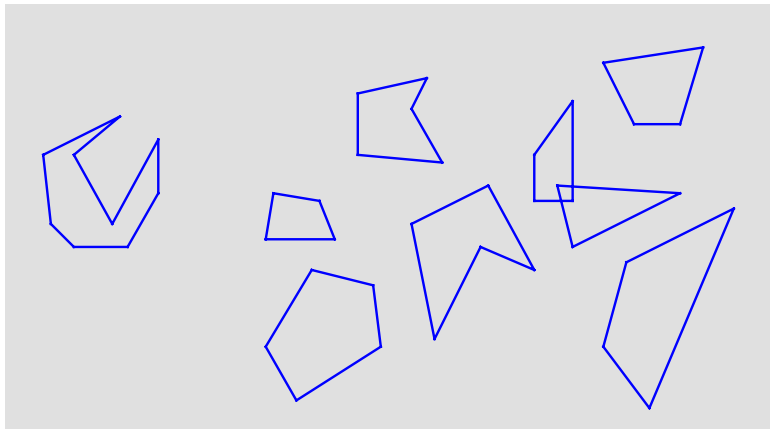
## Theorem 6

**Guaranteed Voronoi Diagram** for discs  
can be constructed in  $O(n \log n)$  time

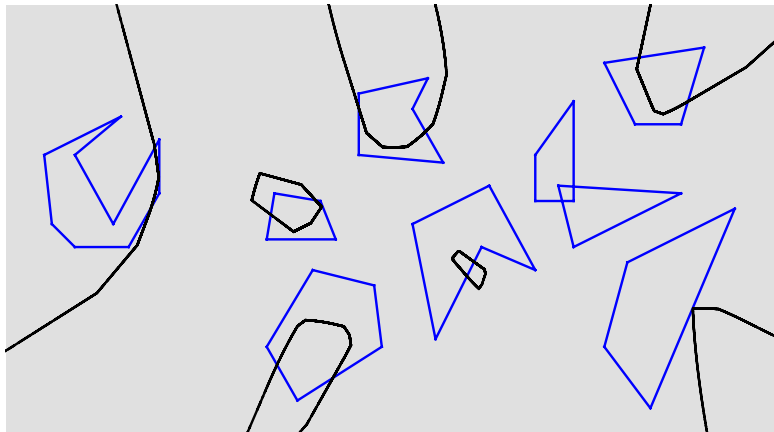
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# Uncertain polygons

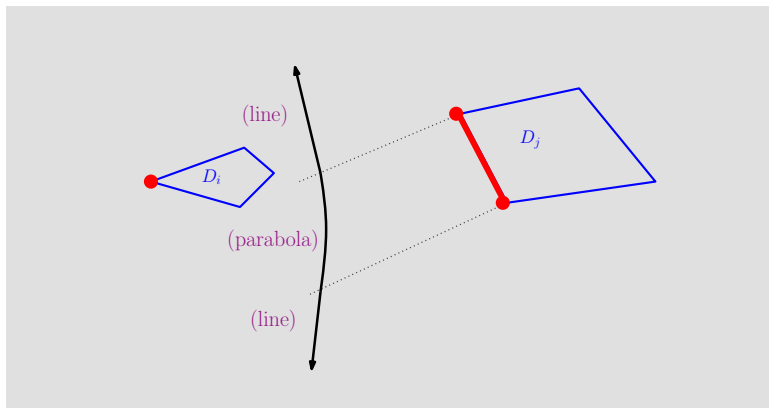


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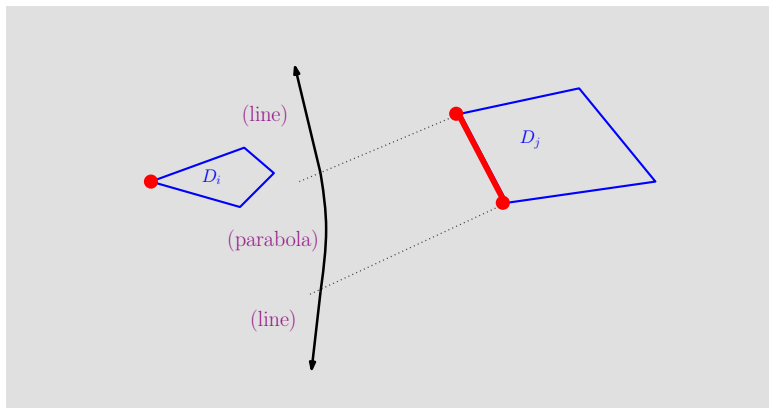
$\langle i, j \rangle$  consists of parabolic arcs  $\langle i^u, j^v \rangle$



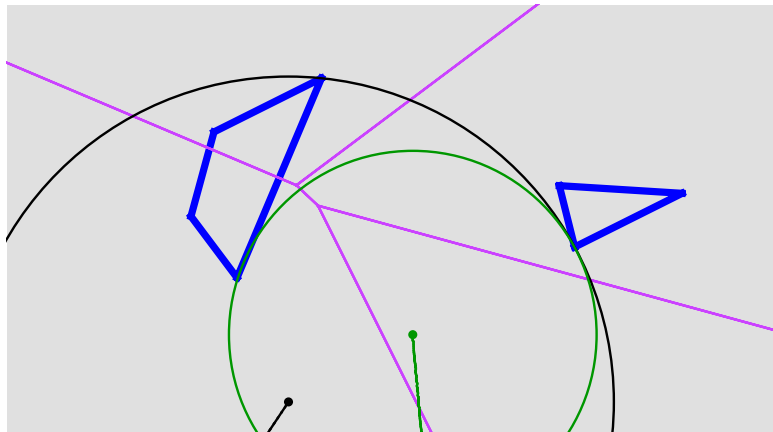
# Uncertain polygons

$i^u$  is farthest vertex of  $R_{\langle i \rangle}$

$j^v$  is nearest vertex or edge of  $R_{\langle j \rangle}$

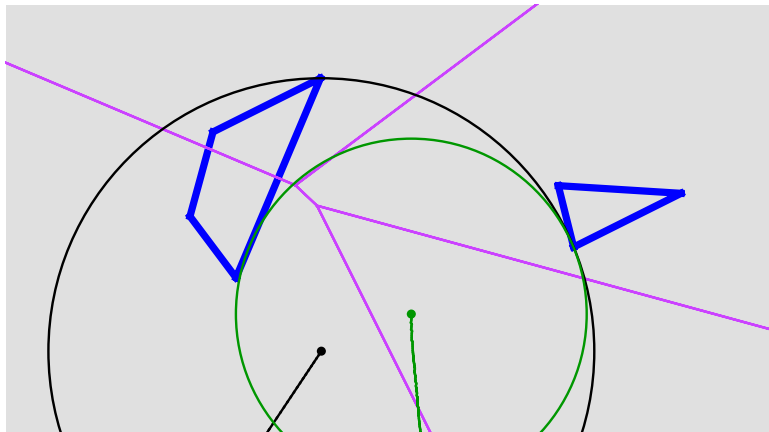


# Uncertain polygons: Complexity

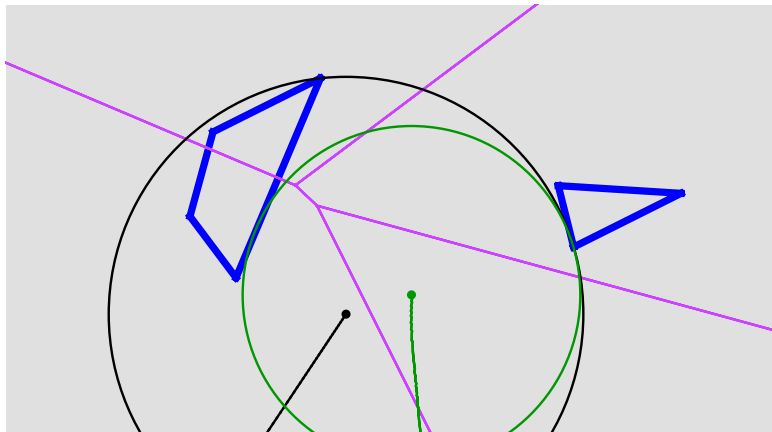




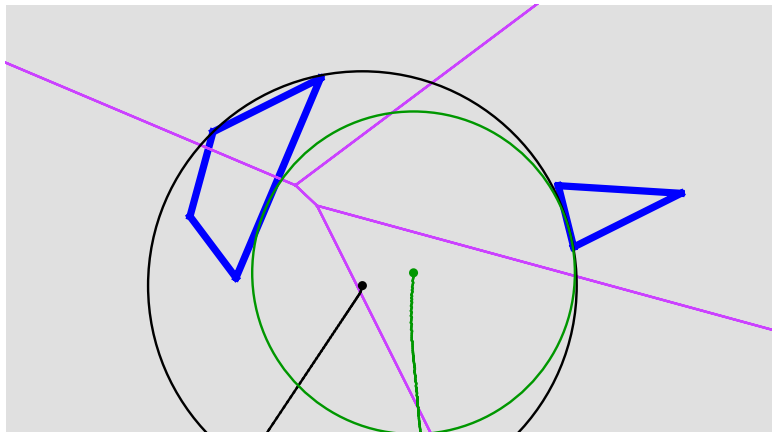
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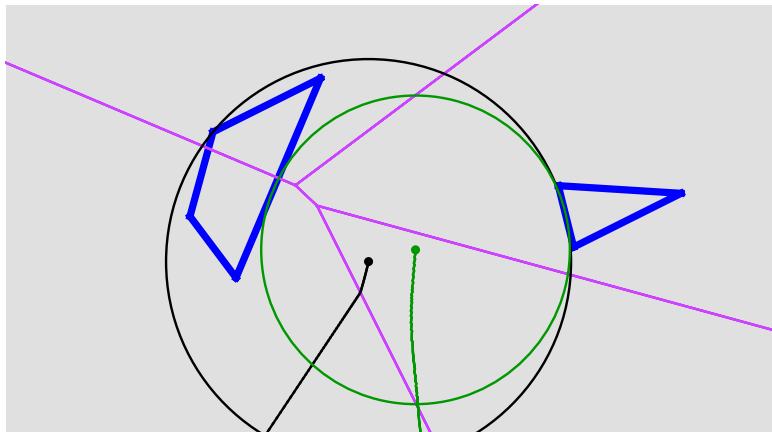
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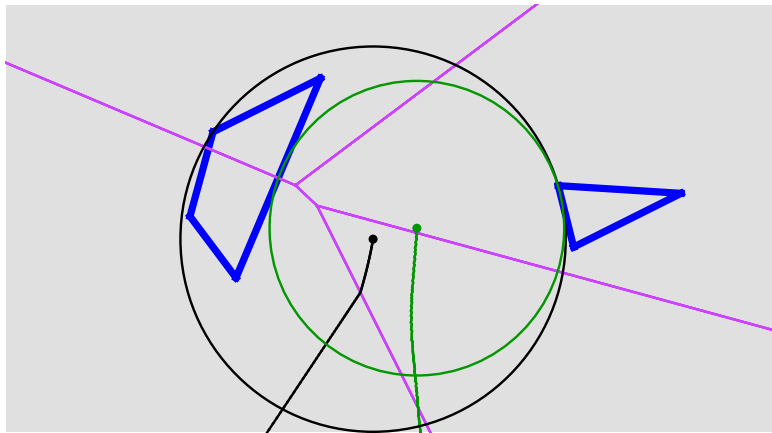
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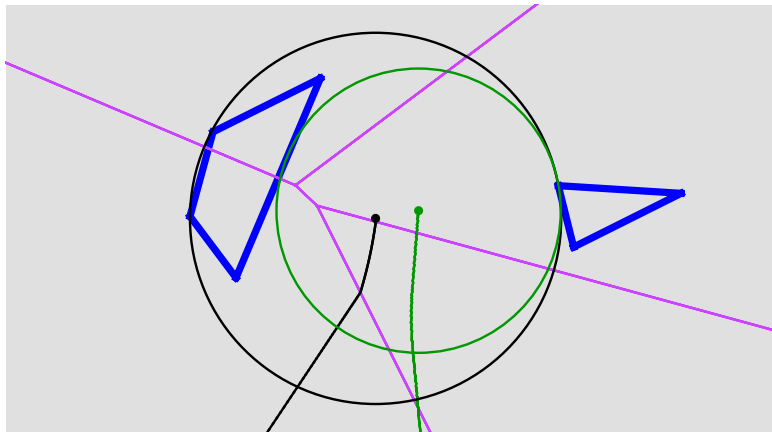
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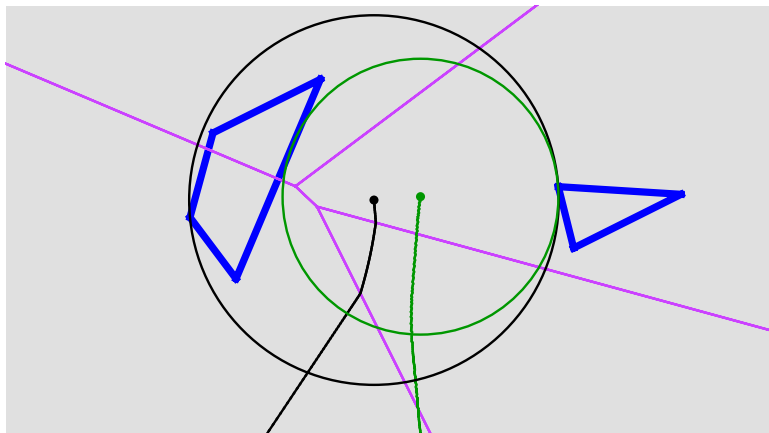
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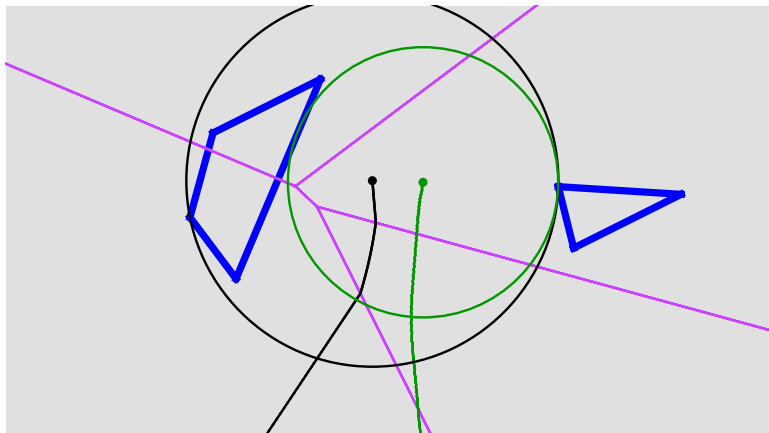
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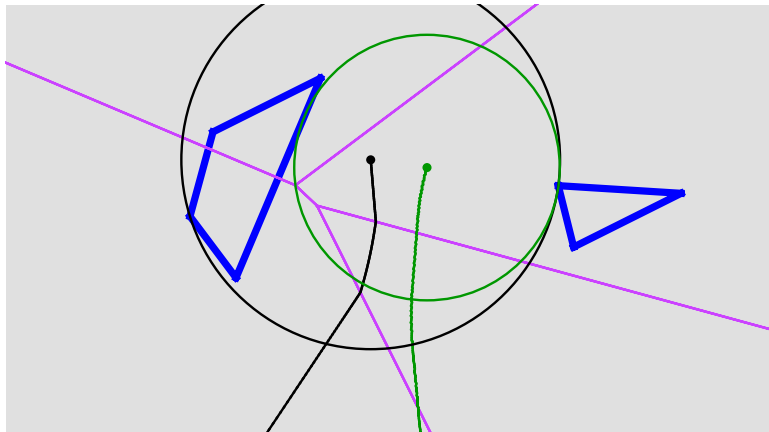


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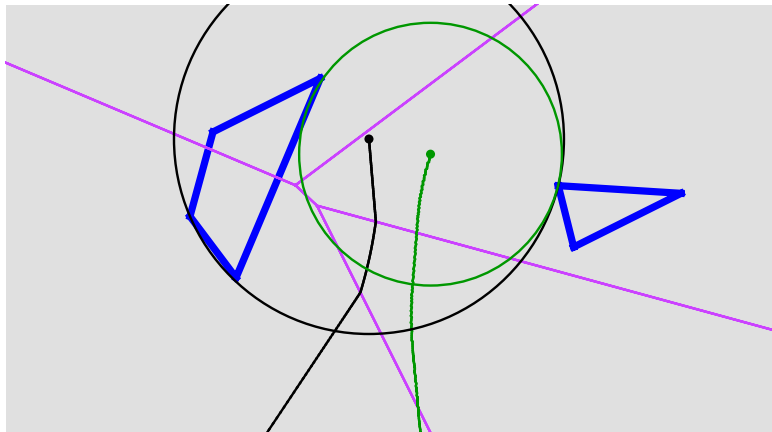




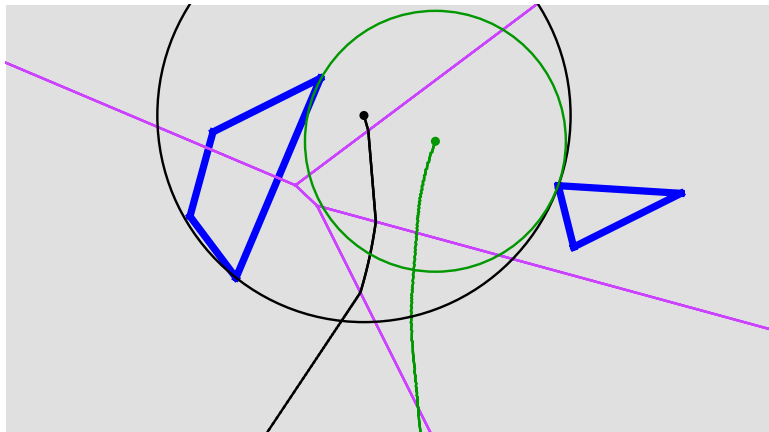
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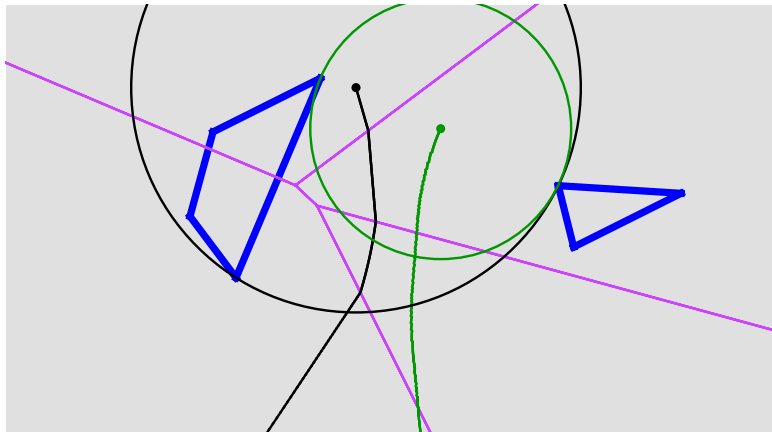
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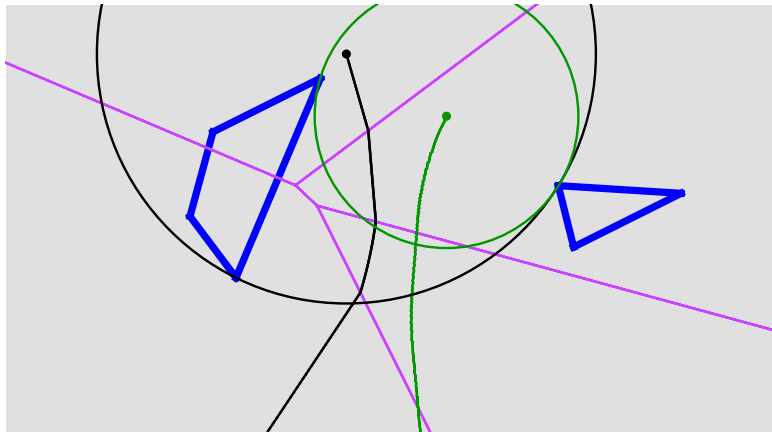
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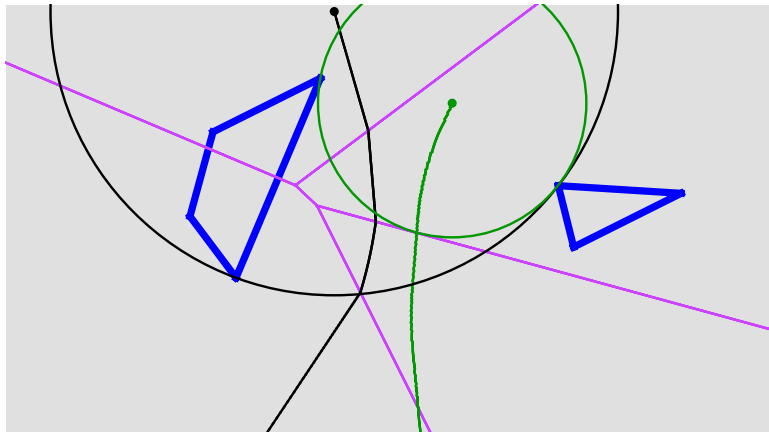
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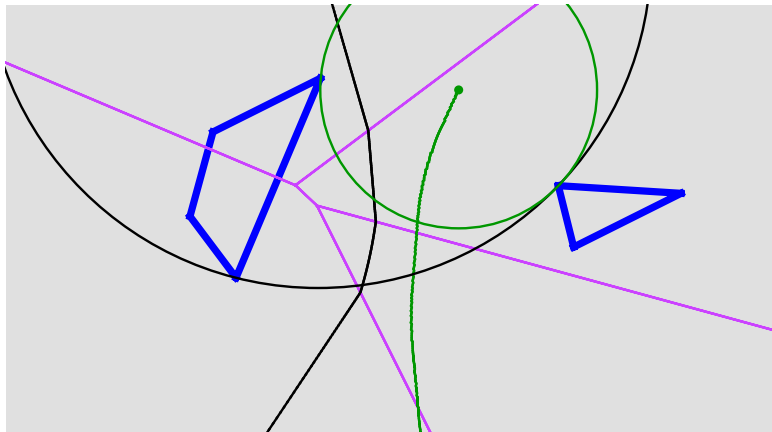
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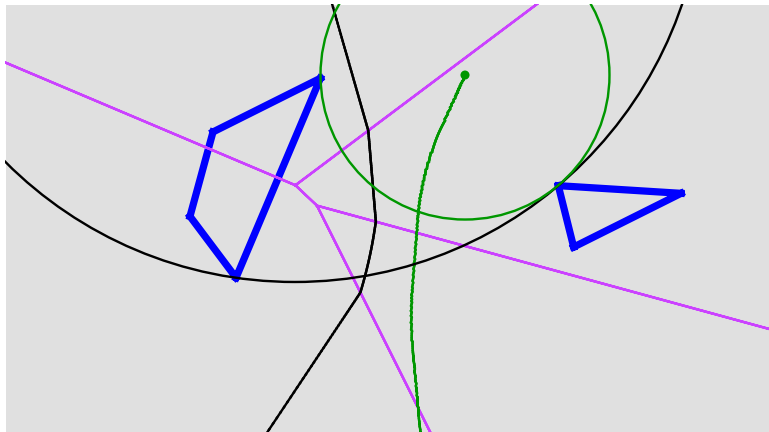
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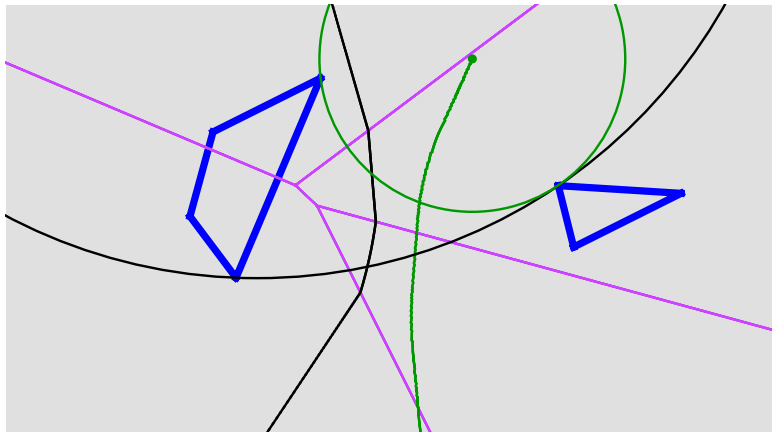


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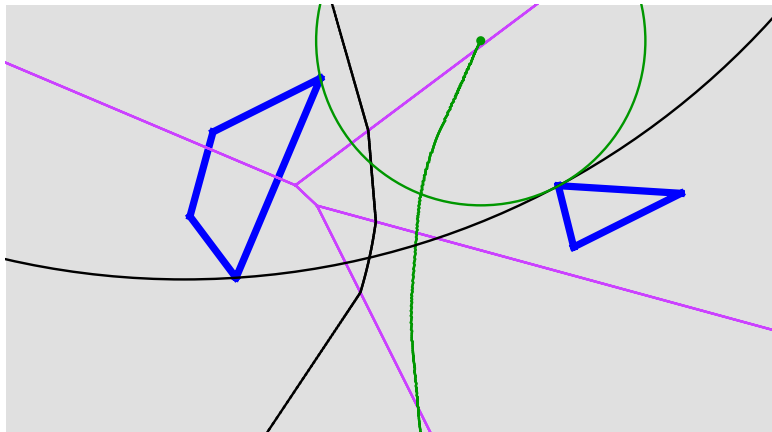




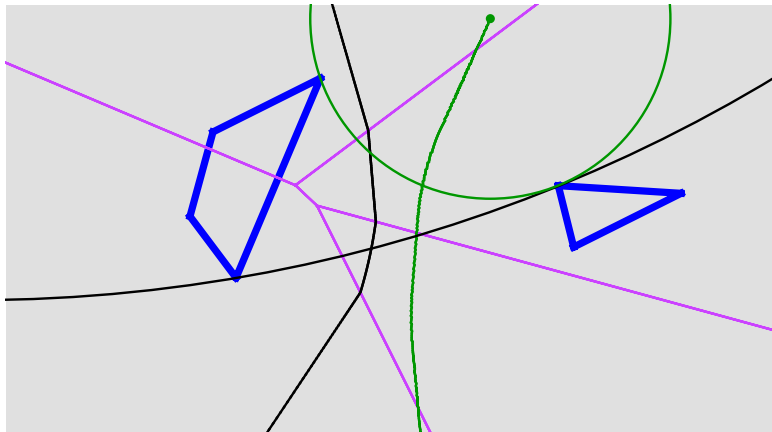
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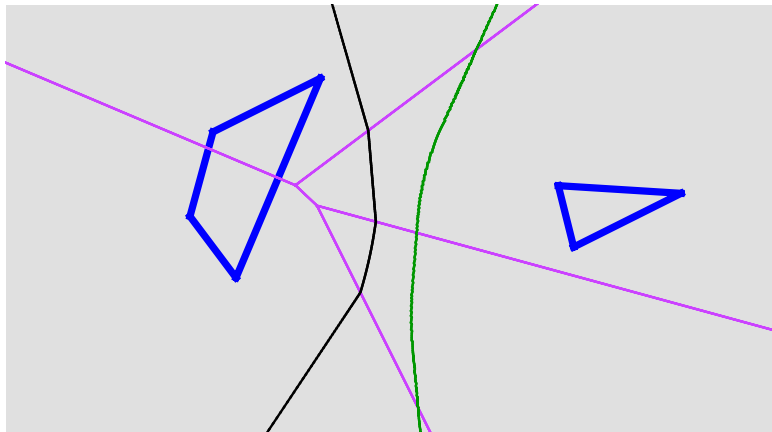
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linear [Kirkpatrick, '79] ...

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- ... plus  $2\times$  that of **farthest point Voronoi diagram**, linear...

## Theorem 7

**Guaranteed Voronoi Diagram** for polygons has linear complexity

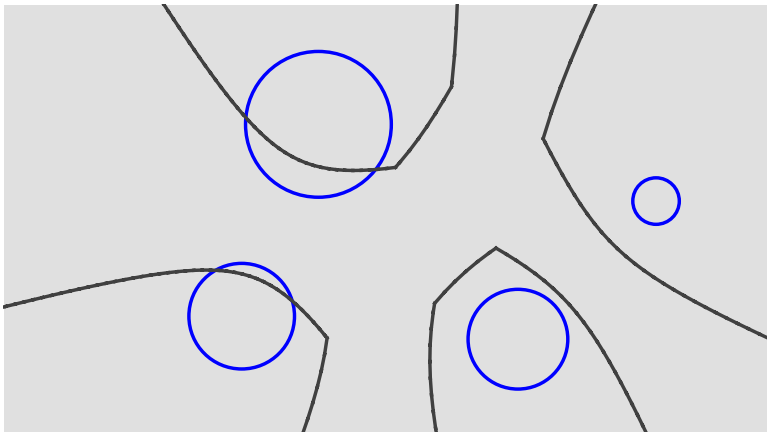


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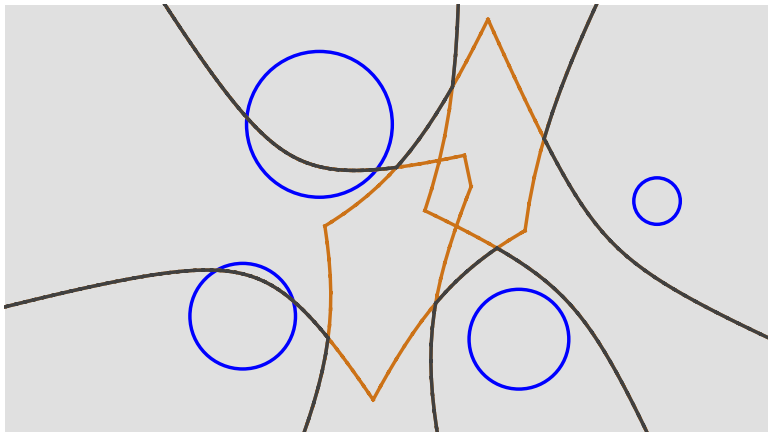
# Guaranteed Subset Voronoi Diagrams: $V^{\{\cdot\}}(\mathcal{D})$

Much of  $\mathbb{R}^2$  falls in 'neutral zone': no guaranteed closest site



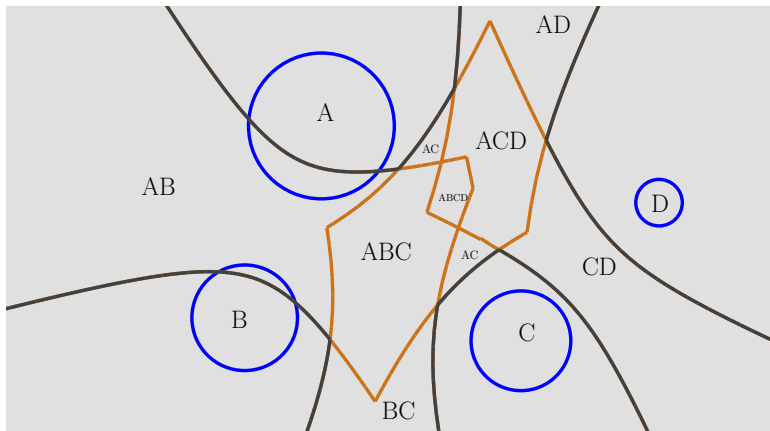
# Guaranteed Subset Voronoi Diagrams: $V^{\{\cdot\}}(\mathcal{D})$

Modify guarantee to involve **subsets** of sites



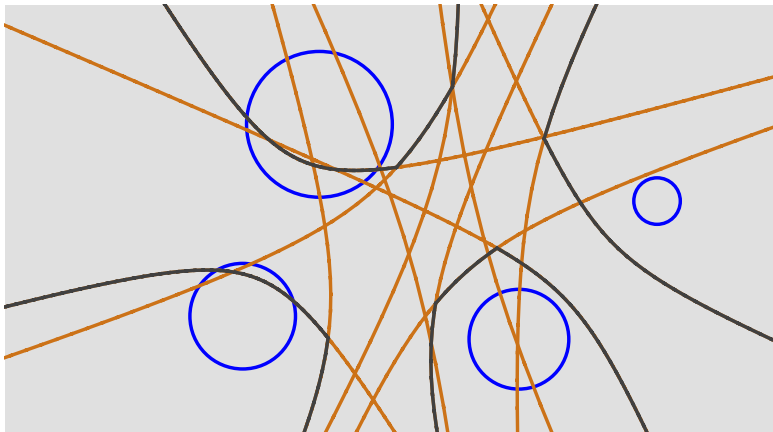
# Guaranteed Subset Voronoi Diagrams: $V^{\{\cdot\}}(\mathcal{D})$

Guarantee:  $p$  closest to some  $D_i \in \mathcal{S}$  than to any  $D_i \in \overline{\mathcal{S}}$



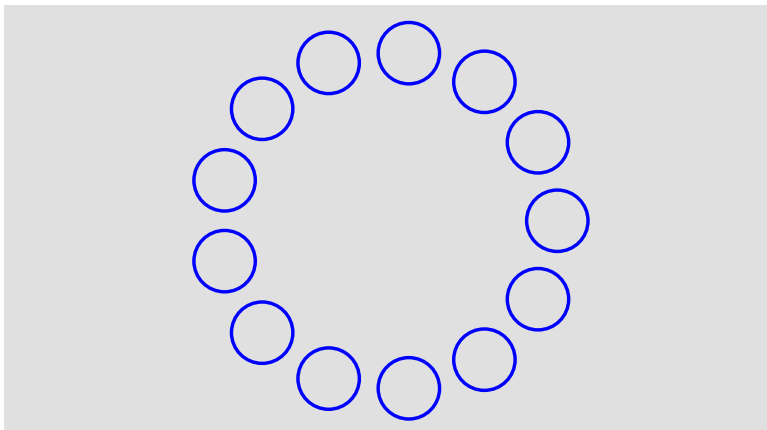
# Guaranteed Subset Voronoi Diagrams: $V^{\{\cdot\}}(\mathcal{D})$

**Lemma 8:** Complexity is  $O(n^4)$



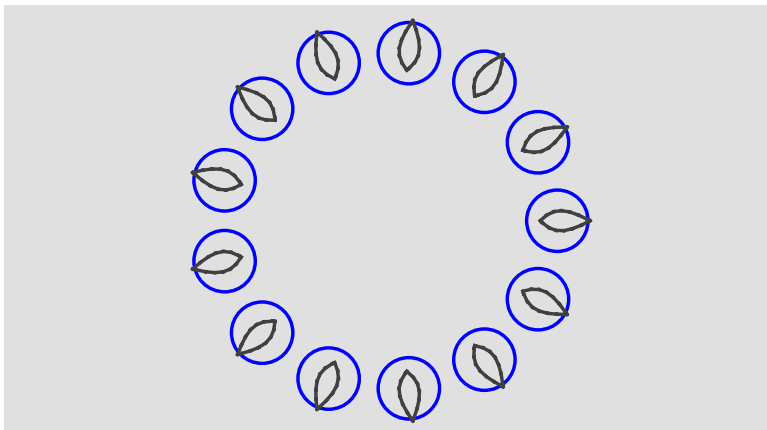
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Complexity is  $\Omega(n^2)$



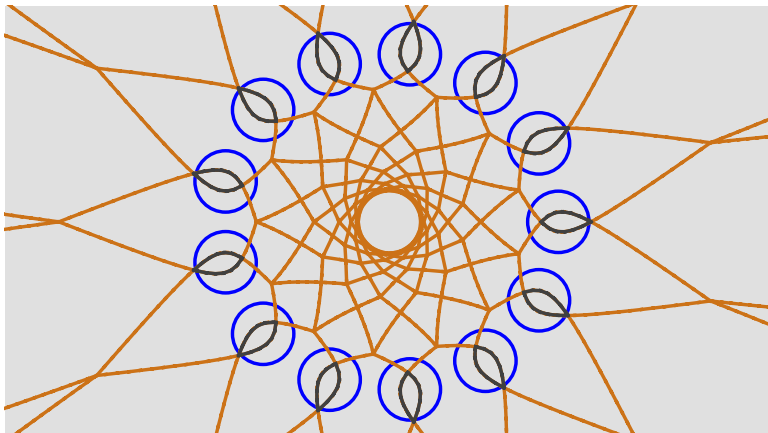
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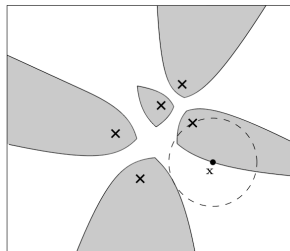
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## Related work

- uncertain sites, probabilistic view: expected closest, probably closest  
[Aurenhammer et al., '91]

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- uncertain sites, probabilistic view: **expected closest**, **probably closest**  
[Aurenhammer et al., '91]
- 'neutral zone' similar to **zone diagrams**



[Asano et al., '07]

# Future work

- efficient algorithm for generating  $V(\mathcal{D})$  (polygons)

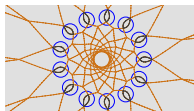


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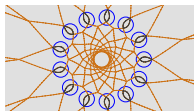


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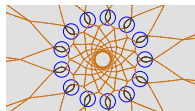
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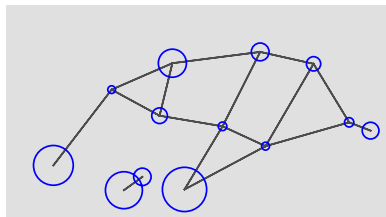


- tighten bound for complexity of  $V^{\{\}}(\mathcal{D})$



- efficient algorithm for generating  $V^{\{\}}(\mathcal{D})$

- investigate dual of  $V(\mathcal{D})$



# Resources

Java applet available at: [www.cs.ubc.ca/~jpsemer](http://www.cs.ubc.ca/~jpsemer)

