

Introduction to work on 'Computer'

Chapman's job - algorithm, Complexity, Monitors,
Parallelism, Dynamic Database
Programs, and their
Implementation. It is offered in the first of three parts
for important Advances
in the use of Dynamic Data.
Numerous Problems, and Automatic Program
and their solutions, are given

~~Copyright~~
The theory of Parallel Algorithms,
Parallel Computing, Dynamic Database
Computing, and their
Interactions.

The Theory of Complexity
of
Dynamic Changes in Database,
Parallel Retiring Algorithms, Automation
Computer Programs and their
Solve Interactions 118

7.2 → The Π -Projection

This section will introduce the concept of the Π -projection.

The purpose of that projection

will be to help us simplify

an initial $e(x,y)$ predicate expressions

by removing some of ~~the~~

its atomic predicates. The concept

of the Π -project is important

because it will be used in

Sections 7.3 and 7.6

The definition of

the Π -projection is somewhat

complicated. Our discussion will

therefore begin by introducing

preliminary notation

because it will be used in

Sections 7.3 and 7.6, the definitions

Throughout this chapter, the

symbols of \bar{x} , \bar{y} , x and y

will have the same meanings,
as they had elsewhere in this thesis.

Thus, the first two symbols will ~~be~~

denote fixed elements that belongs

to the respective R_x and R_y relations,

and the latter two symbols will ~~similarly~~

denote variables that belong

to those two relations.

Also in this chapter, a
very different meaning will be attached to
the symbols of $e(x, y)$ and

$e(\bar{x}, \bar{y})$. The

~~new~~ The former term will designate

some predicate-expressions." The latter term

will denote the truth-value

which this predicate assumes when

the fixed elements of \bar{X} and

\bar{Y} are substituted into it.

Let e_1 and e_2 denote two
distinct predicates. In several parts

of this chapter we will wish to

know whether the equalities

of " $e_1(\bar{x}, \bar{y}) = e_2(\bar{x}, \bar{y})$ " or the

" $e_1(x, y) = e_2(x, y)$ " are satisfied

These two equalities will have

very different meanings. The first

equality will be defined to hold when

the $e_1(\bar{x}, \bar{y})$ and $e_2(\bar{x}, \bar{y})$

terms possess the same

truth-value. The second equality

will have a different meaning

①

meaning because

" $e_1(x,y) = e_2(x,y)$ " are satisfied

These two equalities will have

very different meanings. The first

equality will be defined to hold when

the $e_1(\bar{x}, \bar{y})$ and $e_2(\bar{x}, \bar{y})$

terms possess the same

truth-value. The second equality

will have a different meaning

~~meaning because~~

because it describes a condition between
two variables rather than
two fixed elements. The

" $e_1(x, y) = e_2(x, y)$ " equality

will ~~not~~ be defined to
hold only when the e_1 and e_2
predicates are sufficiently similar
to guarantee that all
elements

will be defined to hold whenever

the logical conditions

of " $\forall x \forall y \ e_1(x, y) = e_2(x, y)$ "

is satisfied.

~~most necessarily be~~

~~Sections 7.3 and 7.6~~

will use the concepts of

Π -projections to help them

~~perform~~

The preceding concepts
will be used in our definitions
of the Π and $\overline{\Pi}$ projections.

The remaining parts of this
section will be devoted to defining
and giving examples of those
two projections.

≡

Definition 7.2.A: Let $e(x, y)$

denote a predicate expression

- which is built out of the

atomic predicates of $A_1(x,y), A_2(x,y), \dots, A_L(x,y)$

Let $A_1(x,y), A_2(x,y), \dots, A_K(x,y)$

denote a subset of K of

these L predicates. Also, let

$b_1 b_2 \dots b_K$ denote a collection

of K boolean values.

The $\prod(e; \underbrace{b_1}_{A_1} \underbrace{b_2}_{A_2} \dots \underbrace{b_K}_{A_K})$ projection

will be defined to be that

~~• predicate which is bagotten by~~

~~repla~~

predicate which is identical

to $e(x, y)$ except that

the $A_1(x, y) A_2(x, y) \dots A_k(x, y)$

atomic predicates have been replaced

by the $b_1 b_2 \dots b_k$ boolean values.

\equiv

Example 7.3.B: Let $e(x, y)$

denote the predicate expression

~~given in e~~

given below:

$$\textcircled{1} \quad e(x, y) = \{ A_1(x, y) \text{ OR } [A_2(x, y) \text{ AND } A_3(x, y)] \}$$

Some examples of Π -projections

are shown below:

$$\textcircled{2} \quad \Pi(e, \begin{array}{c} \text{TRUE} \\ \downarrow \\ A_2 \end{array}) = \{ A_1(x, y) \text{ OR } [\text{TRUE AND } A_3(x, y)] \} \\ = \{ A_1(x, y) \text{ OR } A_3(x, y) \}$$

$$\textcircled{3} \quad \Pi(e, \begin{array}{c} \text{FALSE} \\ \downarrow \\ A_2 \end{array}) = \{ A_1(x, y) \text{ OR } [\text{FALSE AND } A_3(x, y)] \} \\ = \{ A_1(x, y) \}$$

~~Other examples of Π -projection~~

$$\textcircled{4} \quad \Pi(e, \begin{array}{c} \text{FALSE} & \text{TRUE} \\ \downarrow & \downarrow \\ A_1 & A_2 \end{array}) = \{A_3(x, y)\}$$

$$\textcircled{5} \quad \Pi(e, \begin{array}{c} \text{TRUE} & \text{TRUE} \\ \downarrow & \downarrow \\ A_1 & A_2 \end{array}) = \{\text{TRUE or } A_3(x, y)\} \\ = \text{TRUE}$$

$$\textcircled{6} \quad \Pi(e, \begin{array}{c} \text{FALSE} & \text{FALSE} \\ \downarrow & \downarrow \\ A_1 & A_2 \end{array}) = \text{FALSE}$$

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The Π -projection will

be used in the next section

of this chapter. A slightly,

Example 7.3.6: Sometimes predicate

$e(x, y)$ will possess an

$A_i(x, y)$ atomic predicates which

occurs in several positions

within this predicate. In this case, all

such occurrences of the $A_i(x, y)$ atomic

predicates should be replaced

by the designated boolean value

when the Π -projection is

~~operations, this~~

performed. An example of

such a multiple substitution can be seen

by examining equation 7. Some

Π -projection of this equation are

shown in equations 8 and 9

$$⑦ e(x, y) = \{ [A_1(x, y) \text{ AND } A_2(x, y)] \text{ OR } [(NOT A_1(x, y)) \text{ AND } A_3(x, y)] \}$$

$$⑧ \Pi(e, \underset{A_1}{\downarrow}^{\text{TRUE}}) = \{ A_2(x, y) \}$$

$$⑨ \Pi(e, \underset{A_1}{\downarrow}^{\text{FALSE}}) = \{ A_3(x, y) \}$$

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The π -projections

will be used in the

next section of this

chapter. A slightly

different versions of this ~~example~~

projection will be used

in section 7.6. That section

will employ the " $\overline{\pi}$ over-line"

projection. The definition of

this $\overline{\pi}$ projection is given

below:

\equiv

Definition 7.3.D: Let $e(X, y)$ denote

~~three signs~~ ~~last~~ a

a predicate expression whose

atomic predicates are once

again denoted as $A_1(x,y), A_2(x,y), \dots, A_{L_n}(x,y)$

denote a subset of K of those L

atomic predicates. Let us further

recall that $A_j(\bar{x}, \bar{y})$ denotes

the truth-value which

results when the \bar{x} and \bar{y}

elements are substituted into the

~~the truth values of \bar{x} and \bar{y}~~

~~and substituted into~~

$A_i(\bar{x}, \bar{y})$ predicate. The $\overline{\text{TT}}(e, \bar{x}, \bar{y}; A_1 A_2 \dots A_k)$

expression will be defined to

be that predicate which is identical to $c(\bar{x}, \bar{y})$ except that this predicate's K distinct $A_i(\bar{x}, \bar{y})$

predicates are replaced by the

$A_i(\bar{x}, \bar{y})$ truth-values.

Comment: An perhaps somewhat simpler definition of the $\overline{\text{TT}}(e, \bar{x}, \bar{y}, A_1 A_2 \dots A_k)$

projection can be given if

the $\bar{\Pi}$ projection is used. The

~~$\bar{\Pi}(e, \bar{x}, \bar{y}; A_1, A_2, \dots, A_K)$ projection~~

projections will thus be defined to be flat

special version of the $\bar{\Pi}$ projection given in the following equation!

$$\textcircled{10} \quad \bar{\Pi}(e, \bar{x}, \bar{y}; A_1, A_2, \dots, A_K) = \bar{\Pi} \begin{bmatrix} e & A_1(\bar{x}, \bar{y}) & A_2(\bar{x}, \bar{y}) & \dots & A_K(\bar{x}, \bar{y}) \\ & \downarrow & \downarrow & \dots & \downarrow \\ & A_1(x, y) & A_2(x, y) & \dots & A_K(x, y) \end{bmatrix}$$

\equiv

Example 7.3.D Let us calculate

the $\bar{\Pi}(e, \bar{x}, \bar{y}; "x.9 > y.b_1", "x.9 > y.b_2")$

for the predicate defined is

equivalent to

projection for the $e(x, y)$ predicate, defined
below:

$$① \quad \bar{e}(x, y) = \{(x.q_1 > y.b \text{ AND } x.q_1 > 1) \text{ OR } (x.q_2 > y.b \text{ AND } x.q_2 > 2)\}$$

$$② \quad e(x, y) = \{(x.q > y.b_1 \text{ AND } y.b_1 > 1) \text{ OR } (x.q > y.b_2 \text{ AND } y.b_2 > 2)\}$$

The value of this projection

~~$\bar{e}(x, y)$~~

will depend on the truth-values

of the " $\bar{x}.q > \bar{y}.b_1$ " and " $\bar{x}.q > \bar{y}.b_2$ "

atomic predicates. The following table

illustrates how these two truth-values

govern the results of

the $\overline{\Pi}(e, \bar{X}, \bar{Y}, "x.a > y.b_1", "x.a_2 > y.b_2")$

projection:

<u>"x.a > y.b₁" truth-value</u>	<u>"x.a > y.b₂" truth-value</u>	<u>Resulting $\overline{\Pi}$ Projections</u>
TRUE	TRUE	$y.b_1 > 1 \text{ OR } y.b_2 > 2$
TRUE	FALSE	$y.b_1 > 1$
FALSE	TRUE	$y.b_2 > 2$
FALSE	FALSE	FALSE

Various types of Π -projections

will be discussed in sections 7.3 and 7.6.

This concept is important because it

will help us to simplify our

notation in those discussions.

~~script combination of well-known~~

well-known interpreted-file techniques with

Section 3.2's special hashing

functions.

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Our various database

algorithms will be designed

to process E-S predicates by

making subroutine-calls to

The E-7 algorithms. The

last section's Π -projections

will be used by the process

which reduces ~~an~~ initial E-8 expression to

~~to reduced to a simple~~

simpler E-7 expression. The $e_0 e_1 e_2 \dots e_k$

~~parameters in are eliminated~~

predicates, defined below, will play

a major role in that

reduction process:

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Definition 7.3. E: Let $e(x, y)$

denote an E-3 expression which

possesses the K tabular predicates

of $T_1^{xy} T_2^{xy} \dots T_K^{xy}$. Let i

denote an integer whose

value is between zero and K. Throughout

this section, the symbol $e_i(x, y)$

0)

~~$e_i(x, y)$~~ predicate will be presumed

will be called the i -th reductions
predicates of $e(X, y)$. The definitions which $e_i(X, y)$ will
assume in this section is given below:

$$\textcircled{1} \quad e_i(X, y) = \prod \left(e, \begin{array}{c} \text{FALSE} & \text{FALSE} & \text{FALSE} \\ \downarrow & \downarrow & \downarrow \\ T_1(X, y) & T_2(X, y) & T_i(X, y) \end{array} \right)$$

\equiv

Remark 7.3.P : Note that the

preceding definitions implied

that $e_k(X, y)$ is an $E\rightarrow$

expression (because all K of

e 's tabular predicate are

removed when the $e_k(X, y)$

This note
expression is formed). Also, Definition 7.3.E.,
can be easily shown to imply that (because
 $e(X, Y)$ and $e_0(X, Y)$ are the same predicate).
These two facts will be used by
our E-8 algorithms.

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Definition 7.3.G Let $S_{e_i}^F(X)$ denote the
sum associated with the $e_i(X, Y)$ predicate. During
this section, the symbol

$Z_i^F(X)$ will be an abbreviation for

the following arithmetic