

Habitat and fishing control grazing potential on coral reefs

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Supplementary Methods

Region details

In Seychelles, 21 reefs were surveyed in 2008, 2014, and 2017 on two inhabited islands (Mahe, Praslin). Surveys were conducted on the reef slope at 9-12 m depth, and stratified to include carbonate fringing reefs, granitic rocky reefs with coral growth, and patch reef habitats on a sand, rubble, or rock base (Fig. S1B). Surveys were repeated for either 8 (2008) or 16 (2011, 2014, 2017) replicates at each reef, which were located at least 15 m away from each other. To ensure that survey effort was comparable among Seychelles reefs, we only considered surveys from the first 8 replicates (per site per survey year). Overall, the surveys covered up to 0.5 km of reef front and 2,500 m² of reef habitat, including 672 point counts over 4 surveyed years. Reefs were categorised by their exploitation status, with 9 sites in small protected areas and 12 sites supporting artisanal fisheries.

In the Chagos archipelago, 25 reefs were surveyed on four uninhabited atolls in 2010 (Fig. S1B). Surveys were stratified to include sheltered (9) and exposed (9) habitats, and four replicate transects were conducted at each site, resulting in 100 total transects. All reefs were categorised as remote.

In Maldives, 11 reefs were surveyed on one atoll (Huvadhu) in 2013 (Fig. S1B). Surveys were conducted on the reef slope for 4 replicates per reef, resulting in 44 total transects. All reefs were categorised as fished.

In Australia, five reefs were surveyed on the central Great Barrier Reef in 2010 and 2011 (Wheeler, Davies, Rib, Trunk, John Brewer) (Graham et al. 2014) (Fig. S1B). Reefs were stratified to include 3 wave exposed and 3 wave sheltered locations (6 per reef), which were further divided into reef slope (7-9 m depth), reef crest (2-3 m depth), and reef flat (100 m distance from crest). Each location and habitat type was surveyed with four replicate transects. We used data for surveys conducted on the reef slope, which produced a dataset of 24 transects per reef and 120 transects in total. Davies, Rib, Trunk and John Brewer were categorised as fished, and Wheeler was categorised as protected (no-take zone).

Benthic categories

To understand the range of benthic habitat types across the dataset, we categorised reefs according to their benthic regime, using a correlation-based PCA and K-means clustering (Jouffray et al. 2015). The optimal number of clusters was found using an elbow method with $k = 2-15$ range, and then applied to the K-means clustering. For reefs in Seychelles which were surveyed in multiple years, we estimated regimes at each site by averaging cover values over time. Across all reefs, we detected three benthic regimes characterised by 1) hard

coral dominance, 2) high availability of bare substrate, and 3) rubble reefs (Fig. S1B). Coral dominance was the most common regime, detected at 53 reefs across all four regions, whereas bare substrate regimes were only present in Seychelles (14) and Chagos (7). Rubble reefs were only present in Seychelles (6 reefs).

Bite rate models

Cropper function was quantified in terms of potential feeding intensity, the total number of bites per minute, and derived from a predictive model which accounted for species- and genera-specific bite rates (Eqs. 1,2). In our cropper feeding data, bite rates were only weakly correlated with TL (Pearson's $r = -0.18$), and so we assumed bite rates were unrelated to body size.

$$biterate = \text{Gamma}(\mu, \theta) \quad \text{Eq. 1}$$

$$\log(\mu) = \beta_0 + \text{species}_i + \text{genus}_j + \text{dataset}_k \quad \text{Eq. 2}$$

From this model, we generated species- and genera-level posterior predictions of grazing rates and assigned to each individual cropping fish observed in UVCs. Fish belonging to genera which were not present in the feeding observation dataset were assigned average feeding rates irrespective of species and genera (i.e. the model intercept, `\beta_0`). Following Van Rooij et al. (1998), daily carbon intake was linked to body mass (M, grams) as

$$gC = 0.0342.M^{0.816} \quad \text{Eq.3}$$

which we then divided by the predicted number of bites per day to produce an estimate of grams carbon consumed per minute by each individual cropping fish. Our approach accounts for bite size increasing with body size, meaning that larger fish will have greater carbon intakes (Marshall & Mumby 2015). We summed estimates within UVC replicates (i.e. point count or transect) and averaged across replicates to give site-level estimates of potential cropping function.

Scraping function was quantified terms of potential area of substrata cleared per minute. Feeding observations provided estimates of bite rates, which we modelled as a function of body size (TL, cm; $r = -0.43$) according to species- and genera-specific grazing rates, for gamma distributed errors (Eqs. 4, 5).

$$biterate = \text{Gamma}(\mu, \theta) \quad \text{Eq. 4}$$

$$\log(\mu) = \beta_0 + \beta_1 * TL + \text{species}_i + \text{genus}_j + \text{dataset}_k \quad \text{Eq. 5}$$

To account for potential differences in scraping action among species and across body sizes, we used a second underwater feeding observation dataset of scraper bite areas. Bite scar area (cm²) was modelled as a function of body size (TL, cm; $r = 0.83$), for Gamma distributed errors (Eqs. 6,7).

$$scarsize = \text{Gamma}(\mu, \theta) \quad \text{Eq. 6}$$

$$\log(\mu) = \beta_0 + \beta_1 * TL \quad \text{Eq. 7}$$

By including size (TL) as an explanatory covariate, models accounted for scar area increasing with body size (Fig. S2A) and bite rates decreasing with body size (Fig. S2B). For each

observed scraper in the UVC dataset, we generated posterior predictions for bite rate and scar size according to its species identity and body size. Species which were not observed in feeding observations were assigned genera-level bite rates. These predictions were converted to area scraped per minute (bite rate x scar size = area scraped) ($\text{m}^2 \text{ ha}^{-1} \text{ min}^{-1}$), summed within surveys and averaged to give site-level estimates of potential scraping function.

All models fitted to feeding data were fitted with weakly informative priors (Table S2) using Markov Chain Monte Carlo sampling implemented in Stan. We sampled three chains of 3,000 iterations (warmup = 1,500) each for model checks, and one long chain of 5,000 iterations (warmup = 1,500) for generating grazing predictions. Model convergence was assessed by inspecting posterior predictions, Gelman-Rubin diagnostic (Rhat), and the number of effective samples (Table S2).

References

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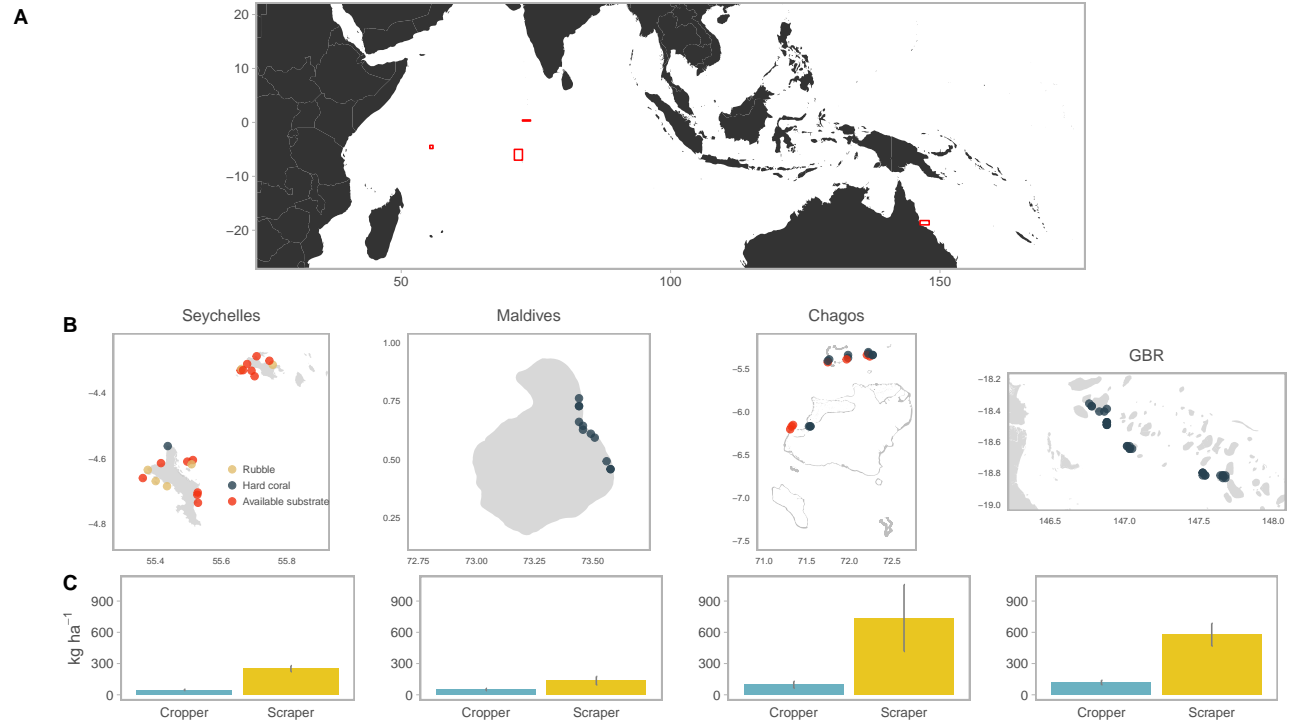


Figure S1 | Map of study sites with benthic habitat regimes (B) and herbivore biomass levels (C). Survey sites are coloured by regimes identified in k-cluster analysis (coral = blue, substrate = red, rubble = yellow), and bar plots show mean grazing biomass (± 2 standard errors) for croppers and scrapers.

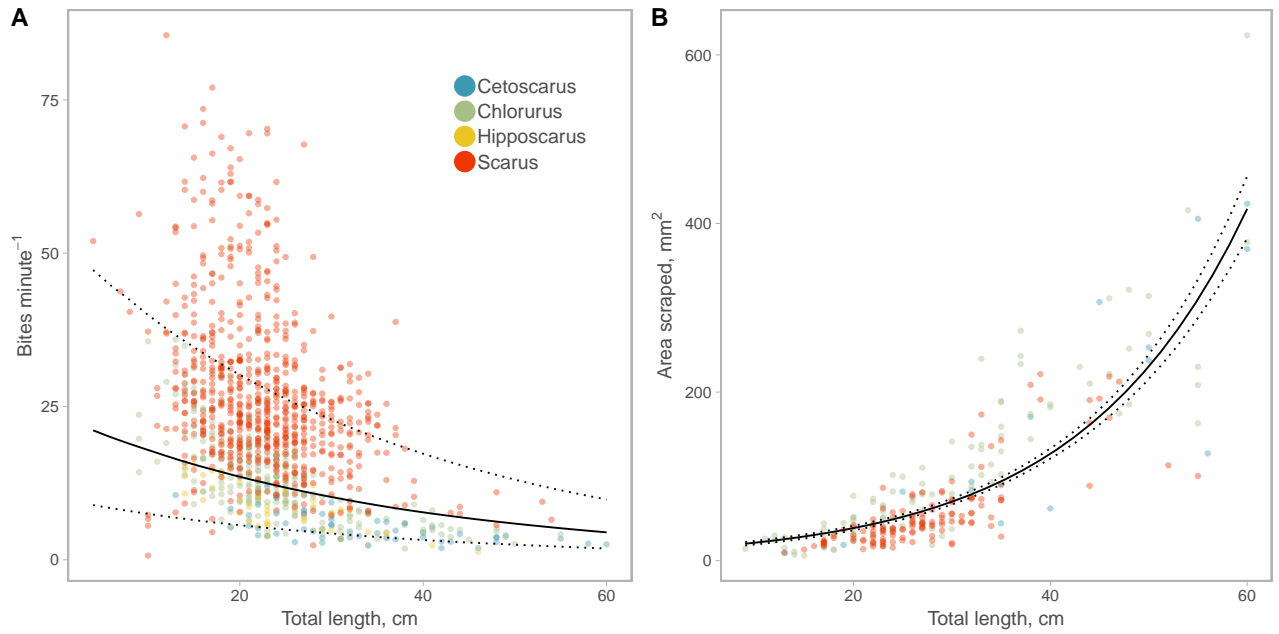


Figure S2 | Size effects on scraper bite rates (A) and bite area (B). Lines indicate median posterior predictions with 95% certainty intervals, excluding species and genera effects, across the range of observed body sizes (total length, cm). Points are observed bite rates or bite areas coloured by genera.

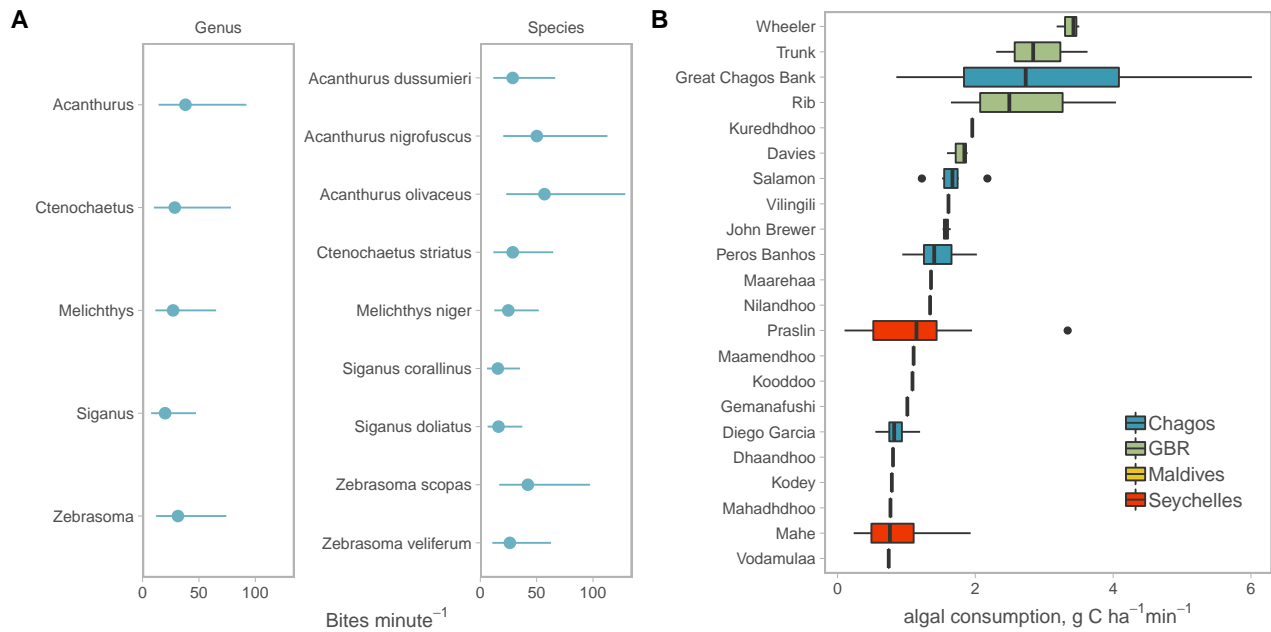


Figure S3 | Cropper bite rate predictions (A) and observed cropper function in UVC (B) Predicted bite rates are median posterior predictions with 95% certainty intervals (A), and boxplots are site-level observed cropping function for each reef, coloured by UVC region.

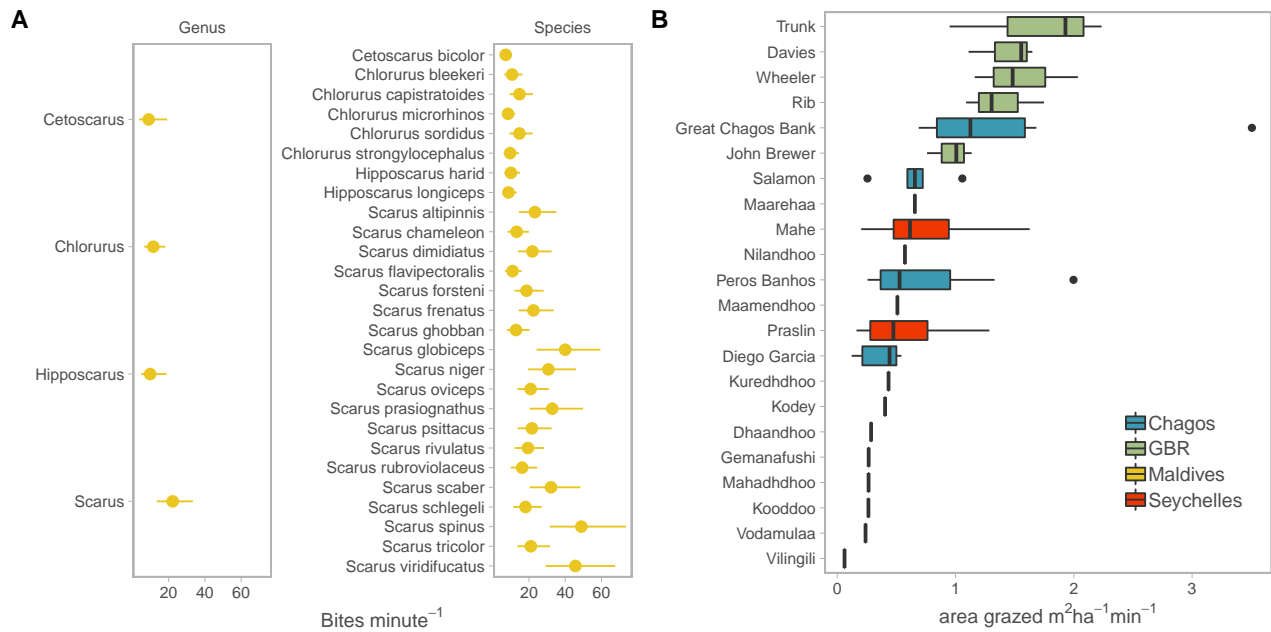


Figure S4 | Scrapper bite rate predictions (A) and observed scraping function in UVC (B) Predicted bite rates are median posterior predictions with 95% certainty intervals (A), and boxplots are site-level observed scraping function for each reef, coloured by UVC region.