

James Queeney

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RESEARCH INTERESTS

I am a fifth-year PhD candidate interested in developing theoretically supported deep reinforcement learning algorithms, with a focus on addressing barriers for real-world deployment. My current work considers the need for robustness, safety, and generalization in deep reinforcement learning.

EDUCATION

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|---|----------------------|
| Boston University | Expected Summer 2023 |
| <i>PhD Candidate in Systems Engineering</i> | |
| Boston University | Jan 2022 |
| <i>MS in Systems Engineering</i> | |
| Colgate University | May 2013 |
| <i>BA in Mathematics and Mathematical Economics</i> | |
| <ul style="list-style-type: none"> • Class of 2013 Valedictorian, Honors in Mathematics, Phi Beta Kappa, Summa Cum Laude | |

RESEARCH EXPERIENCE

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|---|----------------|
| Doctoral Research Fellow | 2019 – Present |
| <i>Boston University – Advisors: Ioannis Paschalidis, Christos Cassandras</i> | |
| <ul style="list-style-type: none"> • Design robust, safe, and efficient deep reinforcement learning algorithms with performance guarantees | |
| Research Intern | Summer 2022 |
| <i>Mitsubishi Electric Research Laboratories – Host: Mouhacine Benosman</i> | |
| <ul style="list-style-type: none"> • Publication: Risk-averse model uncertainty for distributionally robust safe reinforcement learning | |
| Research Assistant | 2017 – 2018 |
| <i>Colgate University – Host: William Cipolli</i> | |
| <ul style="list-style-type: none"> • Implemented Bayesian non-parametric approaches to supervised learning with Polya trees | |

TEACHING AND OUTREACH

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| CISE Graduate Student Workshop Organizer | Jan 2023 |
| <i>Boston University Center for Information & Systems Engineering</i> | |
| <ul style="list-style-type: none"> • Reviewed abstracts, selected speakers, created schedule, and hosted workshop | |
| Graduate Teaching Fellow | Fall 2022 |
| <i>Boston University – Optimization Theory and Methods (SE 674)</i> | |
| <ul style="list-style-type: none"> • Taught weekly recitation section and held office hours for graduate-level engineering course | |
| Research Mentor | Summer 2021 |
| <i>Boston University Research in Science & Engineering Program</i> | |
| <ul style="list-style-type: none"> • Advised high school student in reinforcement learning research project on rodent navigation | |
| Graduate Teaching Fellow | Fall 2019 |
| <i>Boston University – Introduction to Programming for Engineers (EK 125)</i> | |
| <ul style="list-style-type: none"> • Led classes and lab sessions, held office hours, graded assignments, and managed TAs | |

INDUSTRY EXPERIENCE

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| Director of Operations Research <i>Bargain Hunt</i> | 2017 – 2018 |
| Private Equity Associate <i>Thomas H. Lee Partners – Consumer & Healthcare Group</i> | 2015 – 2017 |
| Investment Banking Analyst <i>Bank of America Merrill Lynch – Mergers & Acquisitions Group</i> | 2013 – 2015 |

PUBLICATIONS

- **Queeney, J.**, Ozcan, E. C., Paschalidis, I. C., and Cassandras, C. G. (2023). Optimal transport perturbations for safe reinforcement learning with robustness guarantees. arXiv preprint, arXiv:2301.13375.
- **Queeney, J.** and Benosman, M. (2023). Risk-averse model uncertainty for distributionally robust safe reinforcement learning. arXiv preprint, arXiv:2301.12593.
- Giammarino, V., **Queeney, J.**, Carstensen, L. C., Hasselmo, M. E., and Paschalidis, I. C. (2022). Opportunities and challenges from using animal videos in reinforcement learning for navigation. arXiv preprint, arXiv:2209.12347.
- **Queeney, J.**, Paschalidis, I. C., and Cassandras, C. G. (2022). Generalized policy improvement algorithms with theoretically supported sample reuse. arXiv preprint, arXiv:2206.13714.
- **Queeney, J.**, Paschalidis, I. C., and Cassandras, C. G. (2021). Generalized proximal policy optimization with sample reuse. In *Advances in Neural Information Processing Systems*, volume 34. Curran Associates, Inc.
- **Queeney, J.**, Paschalidis, I. C., and Cassandras, C. G. (2021). Uncertainty-aware policy optimization: A robust, adaptive trust region approach. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 35, pages 9377-9385. AAAI Press.

PRESENTATIONS

- Safe reinforcement learning with robustness guarantees (2023). *Massachusetts Institute of Technology Invited Talk*, Cambridge, MA.
- Balancing stability and efficiency in deep reinforcement learning (2023). *Harvard University Invited Talk*, Cambridge, MA.
- Stable and efficient reinforcement learning with principled sample reuse (2022). *CISE Graduate Student Workshop 8.0*, Boston, MA. **Best Presenter Award**.
- Robust and efficient reinforcement learning from limited data (2021). *Boston University Division of Systems Engineering Presentation*, Boston, MA.
- Generalized proximal policy optimization with sample reuse (2021). *35th Conference on Neural Information Processing Systems (NeurIPS 2021)*, Virtual.
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *CISE Best Student Paper Awards Presentation*, Virtual. **Best Student Paper Award Finalist**.
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *35th AAAI Conference on Artificial Intelligence (AAAI 2021)*, Virtual.

HONORS AND AWARDS

- Doctoral Research Fellow, *Boston University* 2019 – Present
- CISE Best Student Paper Award Finalist, *Boston University* 2022
- CISE Graduate Student Workshop Best Presenter Award, *Boston University* 2022
- CISE Best Student Paper Award Finalist, *Boston University* 2021
- Dean’s Fellowship Award, *Boston University* 2018 – 2019
- Class of 2013 Valedictorian, *Colgate University* 2013
- Osborne Mathematics Prize, *Colgate University* 2013
- Phi Beta Kappa Award, *Colgate University* 2013
- Phi Beta Kappa, *Colgate University* 2013
- Summa Cum Laude, *Colgate University* 2013
- Honors in Mathematics, *Colgate University* 2013
- John T. Mitchell Award, *Colgate University* 2012 – 2013
- Charles A. Dana Scholar, *Colgate University* 2011 – 2013
- Alumni Memorial Scholar, *Colgate University* 2009 – 2013
- Sisson Mathematics Prize, *Colgate University* 2010
- Dodge Prize, *Colgate University* 2010

SKILLS

- **Programming Languages:** Python, MATLAB, R
- **Software:** DeepMind Control Suite, Gurobi, MuJoCo, OpenAI Gym, TensorFlow