

ROVISP 2016

Density-based Denoising of Point Cloud

Faisal Zaman

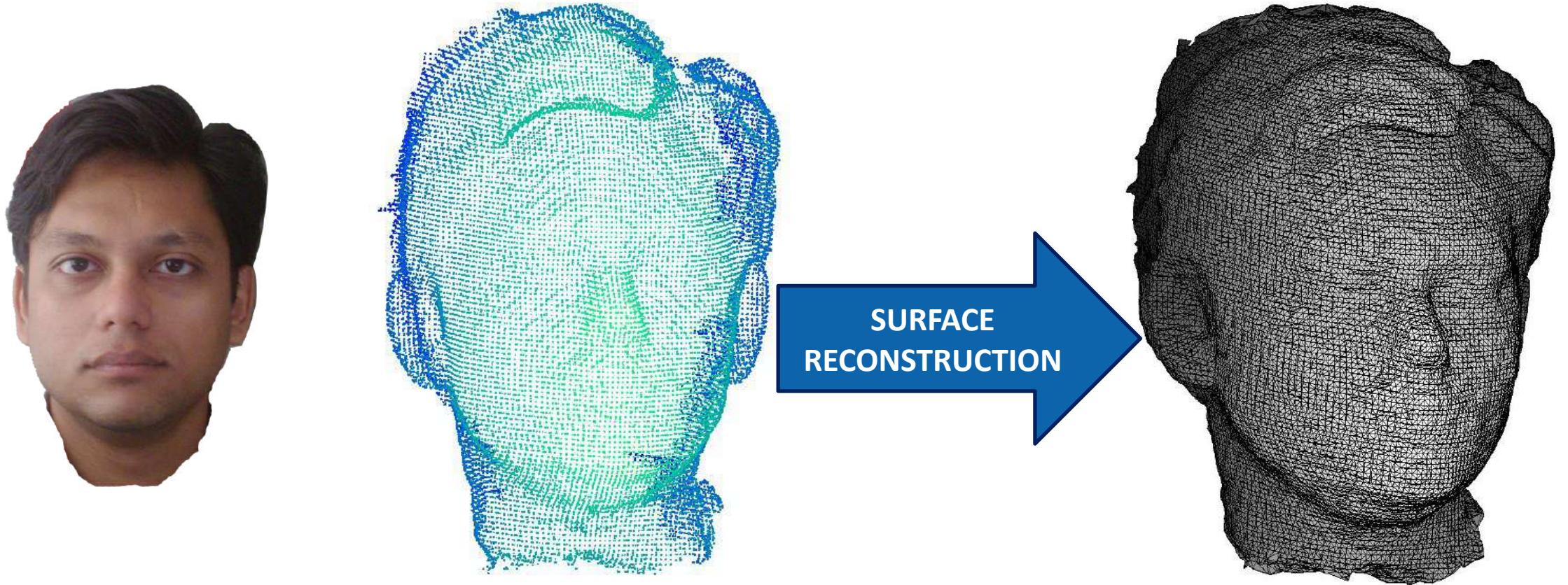
Wong Ya Ping

Ng Boon Yian

Introduction

What is Surface Reconstruction?

The process of producing polygonal meshes from point cloud.



INPUT: Point cloud from object surface

OUTPUT: Polygonal mesh

Introduction

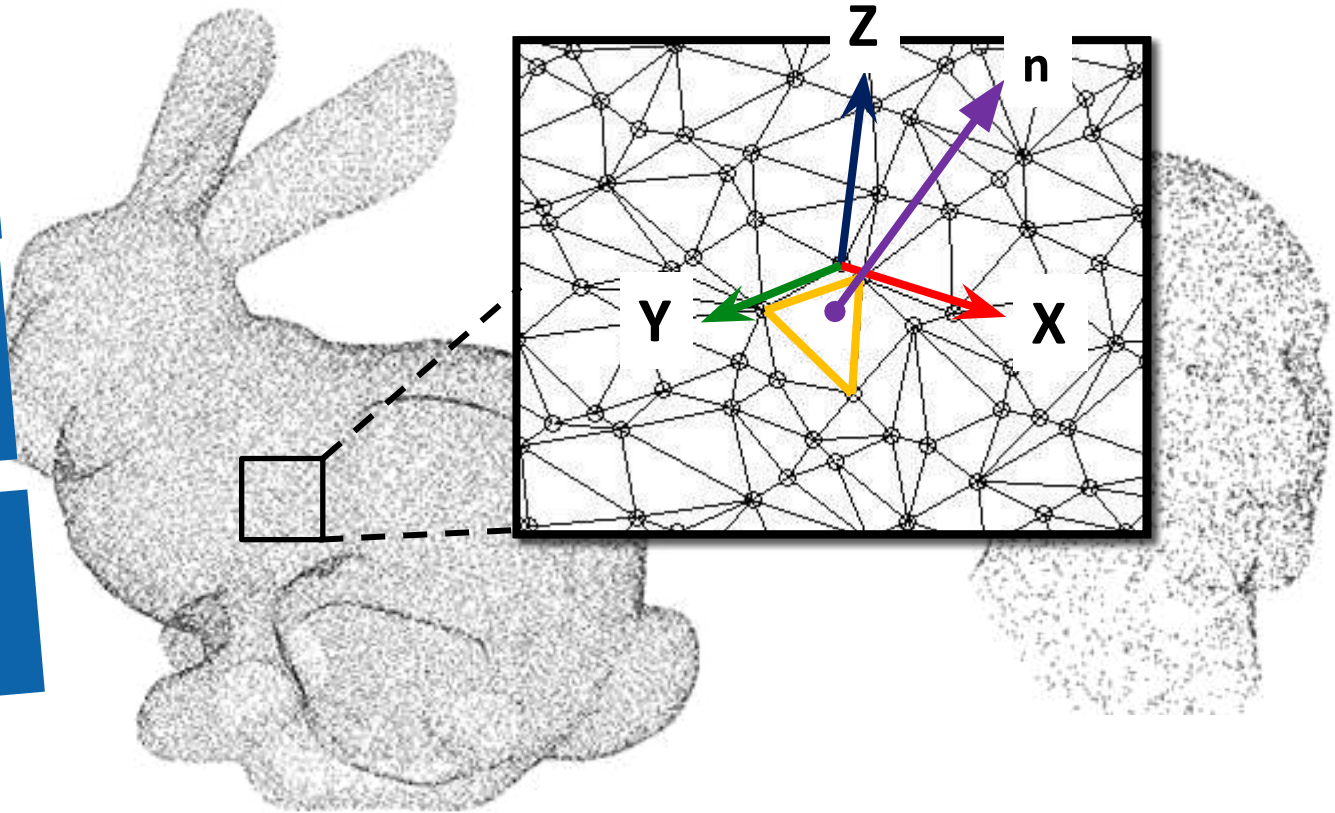
Point Cloud

Set of points sampled from a surface.

Location of the points

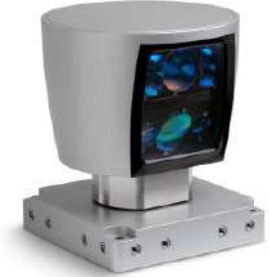
Connectivity Information

Normal



Introduction

How to get Point cloud?

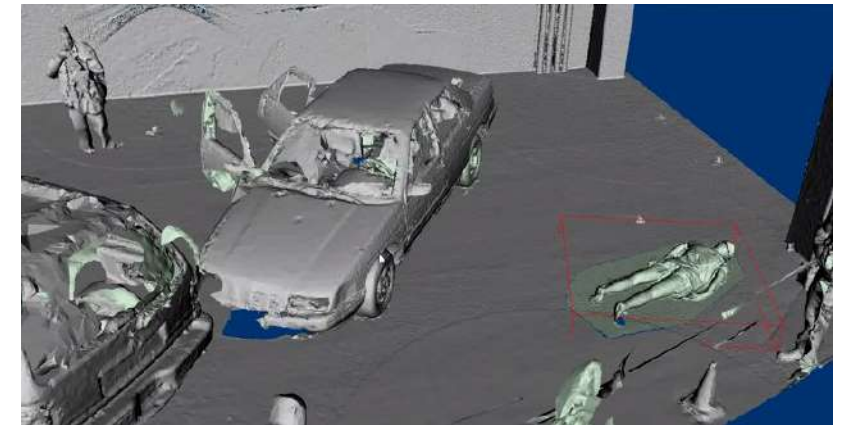


*First ever 3D-printed presidential portrait
by Smithsonian-led team of 3-D digital imaging specialists (Dec, 2014)*

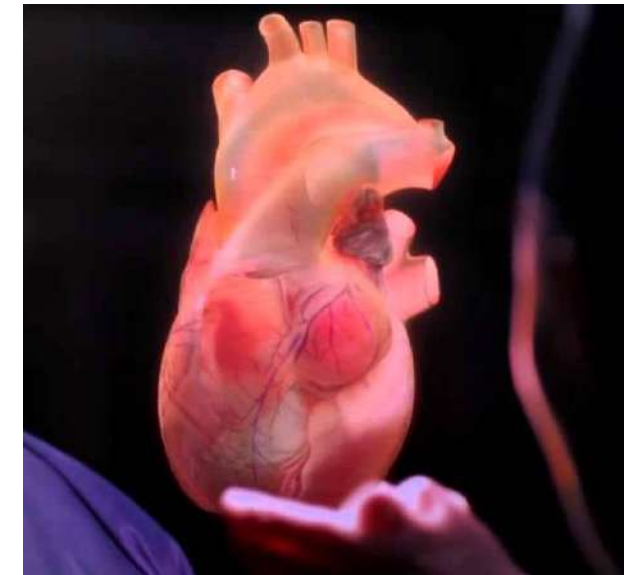
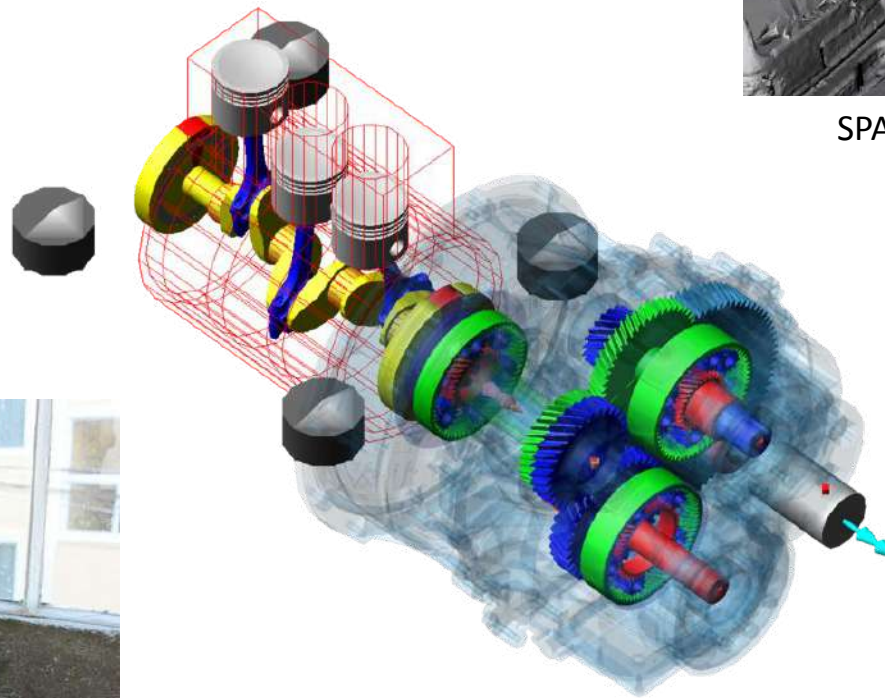
Introduction

Applications

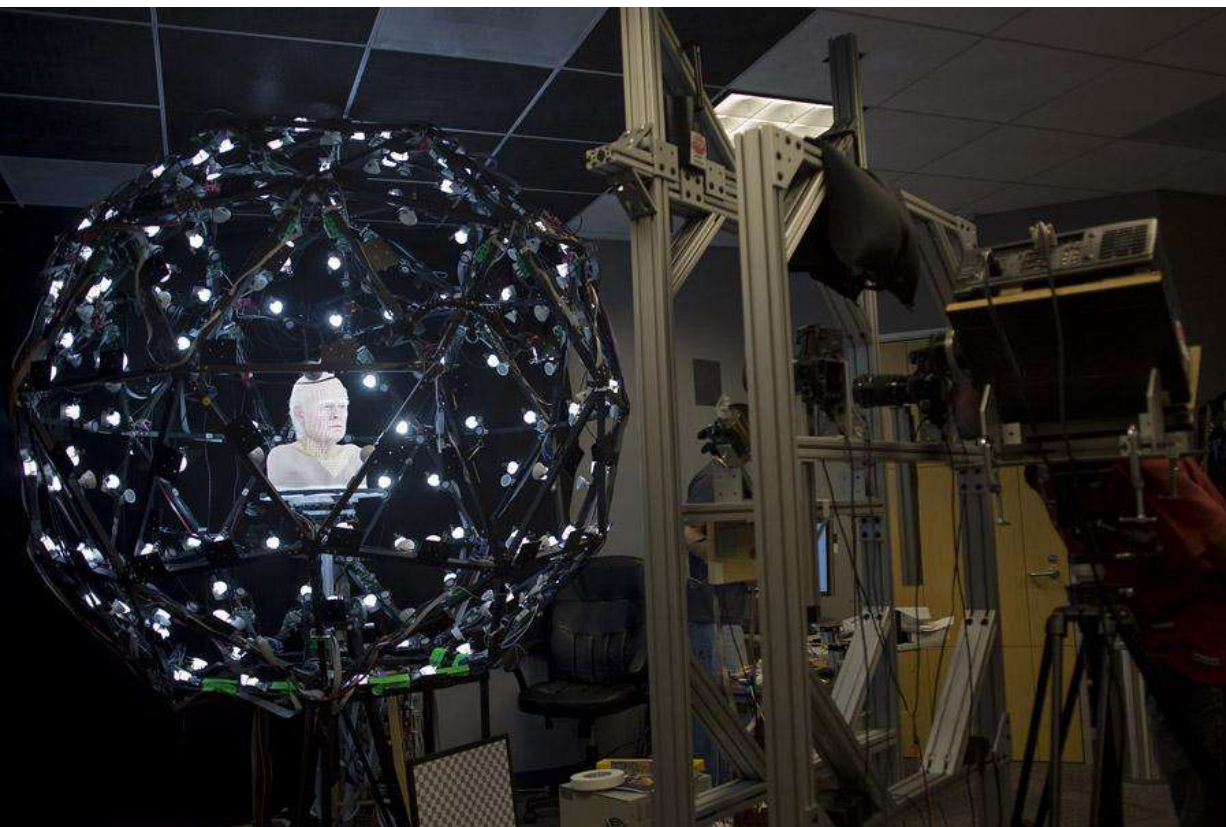
- Crime Scene Reconstruction
- Medical Imaging
- Industrial Design
- Prototyping
- Movie Industry



SPAR International 2014 posts Conference



RealView Imaging Ltd



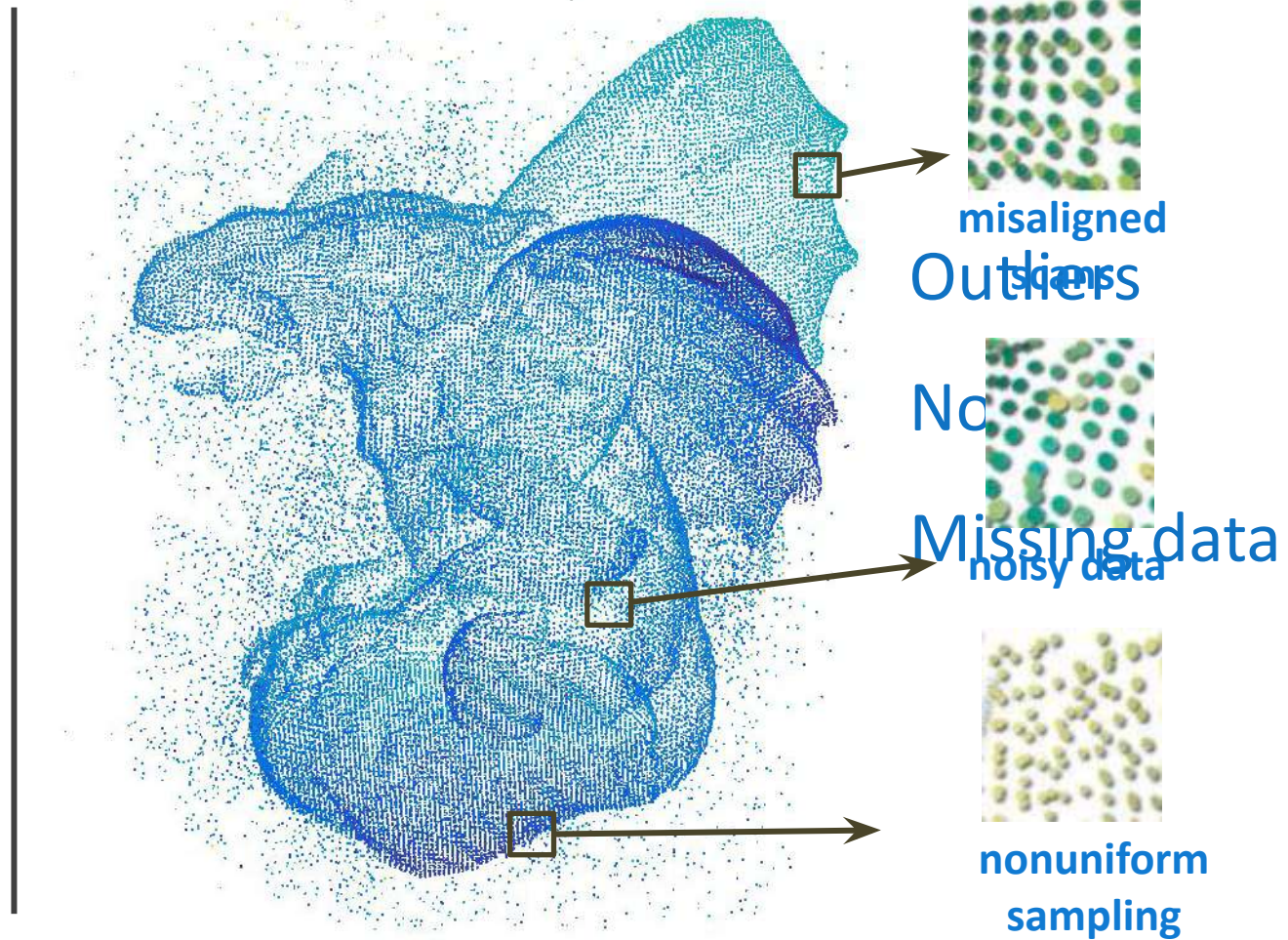
Light Stage 5



The Curious Case of Benjamin Button

Technology based on: A Lighting Reproduction Approach to Live-Action Compositing

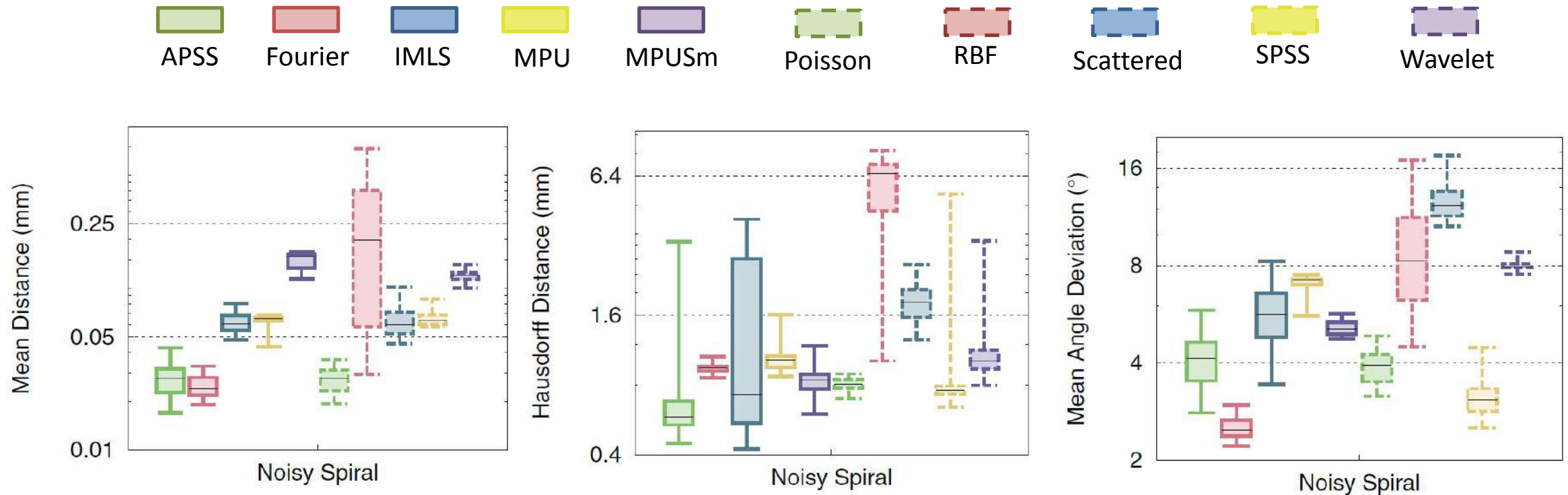
Challenges



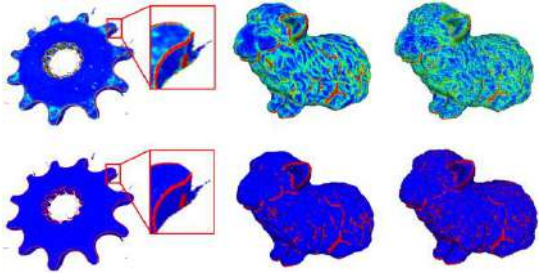
Filter out uncertain and noisy data points

Surface Reconstruction Benchmark

M. Berger 2013, created a benchmark for comparing several state-of-the-art surface reconstruction techniques

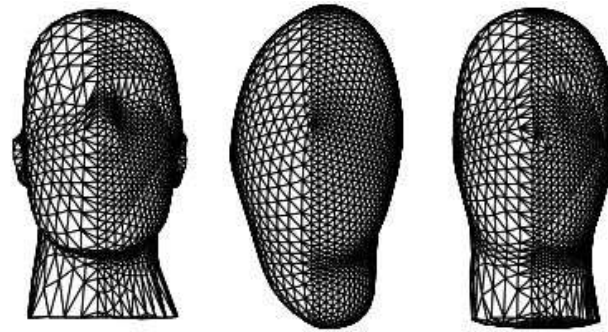


Previous Work



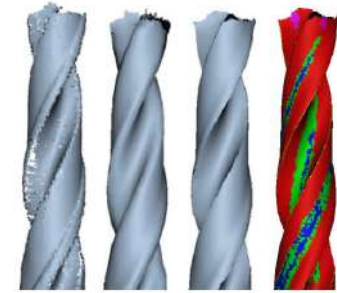
Majority Voting System^{a b c}
Y. Wang et al. (2015)

high computation cost
Infeasible for large datasets



Mean Curvature Flow
Desbrun et al. (2000)

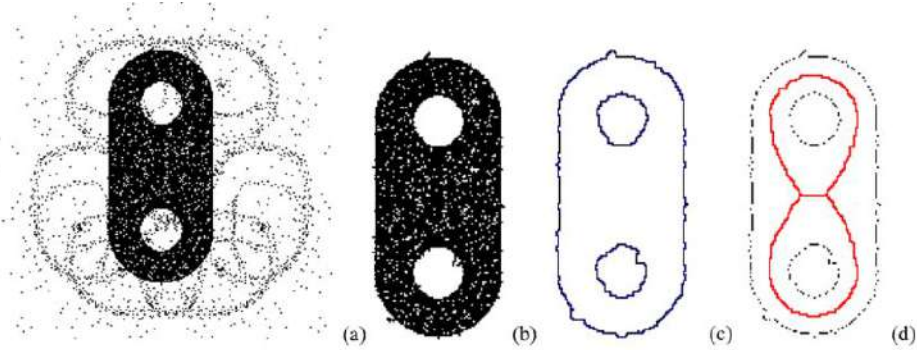
sensitive against large number of outliers
and over smooth the data points



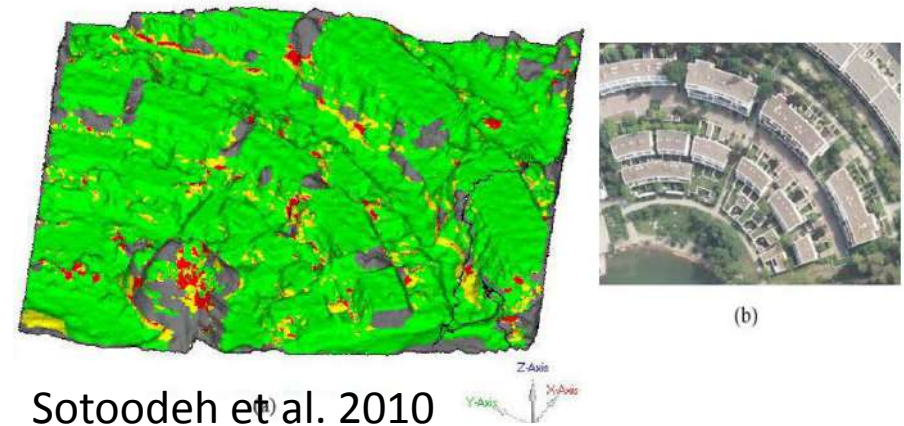
Moving Least Square
Fleishman et al. (2005)

Previous Work

Data Clustering



Y Song et al. 2010

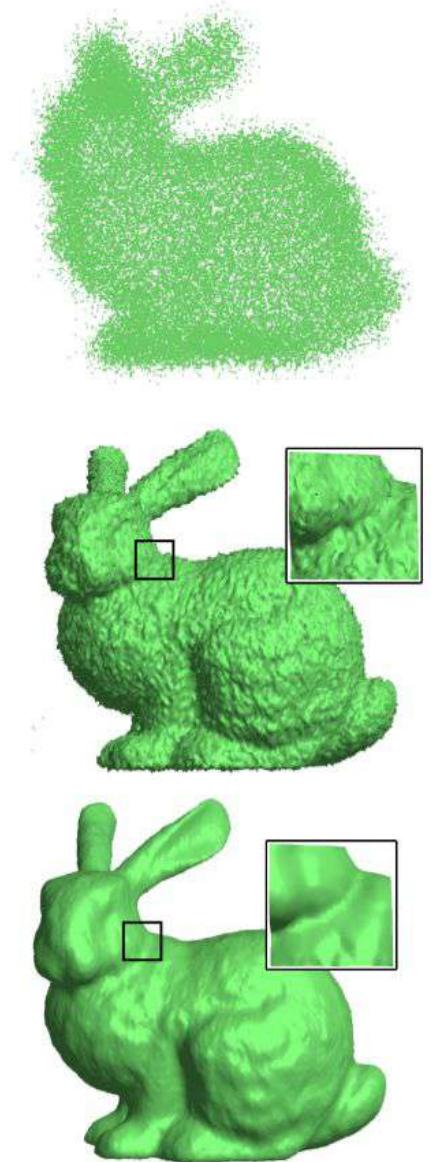


Sotoodeh et al. 2010

require prior knowledge about the input objects

The Density-based Method

- We propose a method to find the optimal bandwidth of Kernel Density Estimation using PSO.
- Mean-shift based clustering technique is used to remove outliers through a thresholding scheme.
- Bilateral mesh filtering is applied to smooth the remaining points.



Kernel Density Estimation

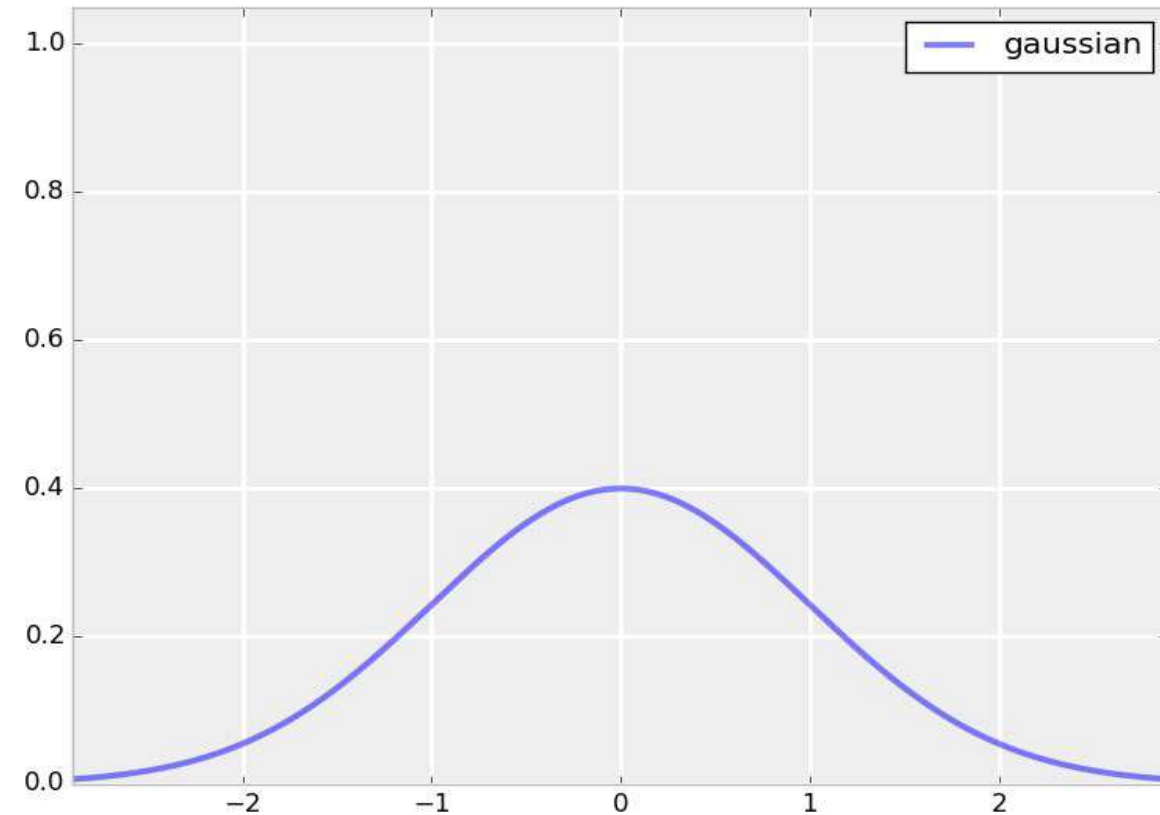
$$\mathbf{X} = (x_1, x_2, \dots, x_N)^T$$

$$\hat{f}_H(x) = n^{-1} \sum_{i=1}^N K_H(x - X_i)$$

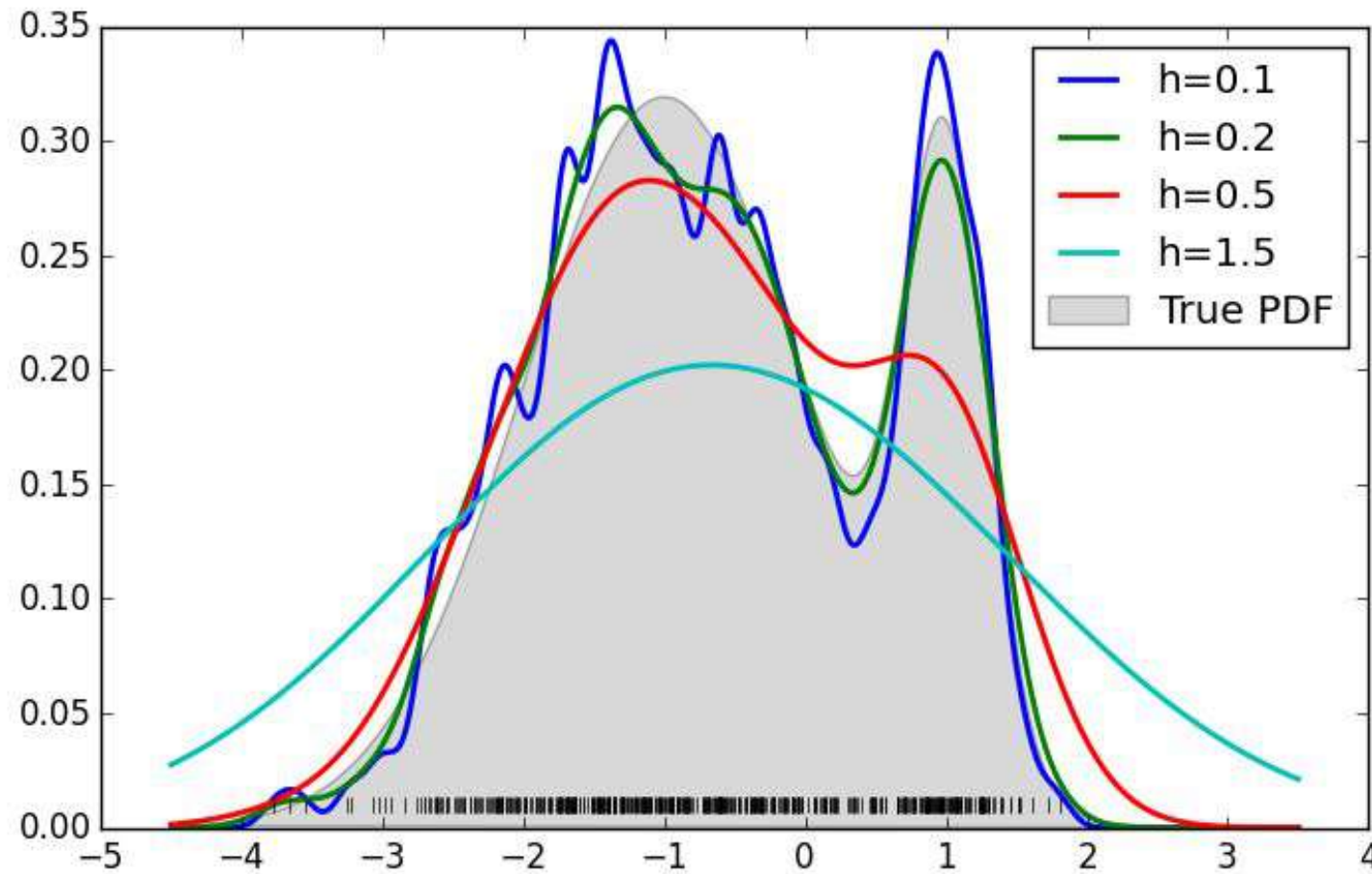
$$\hat{f}(x) = n^{-1} \sum_{i=1}^N h^{-1} K\left(\frac{x - X_i}{h}\right)$$

kernel function

Smoothing parameter

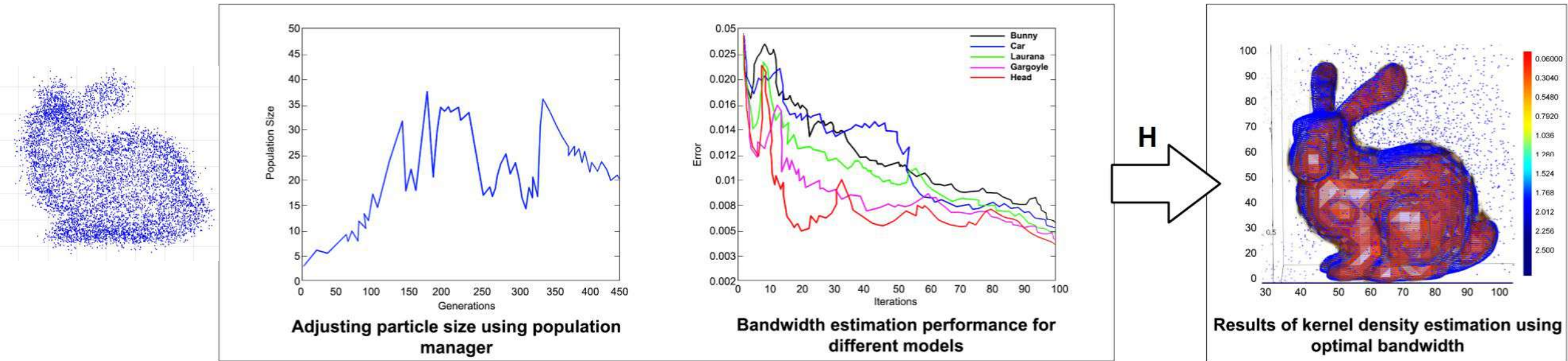


Influence of Bandwidth (h)



Proposed Pipeline

Proposed optimal bandwidth selection criterion using PSO



Optimal H

Error Criteria:

– Minimize the error between

$\hat{f}_H(x)$ (estimated density) and $f(x)$ (true density)

$$MISE(h) = E \left\{ \int [\hat{f}(x) - f(x)]^2 dx \right\}$$

Mean Integrated Square Error

$$ISE(h) = \int [\hat{f}(x) - f(x)]^2 dx$$

Integrated Square Error

Cross-Validation Methods

- Leave-One-Out Cross-Validation (LOOCV)
 - LOOCV to estimate the risk function $R(\hat{f}(x), f(x))$

$$L(H) = \frac{1}{n} \sum_{i=1}^n \log \hat{f}_{H,i}(x_i)$$

The optimal smoothing parameter:

$$H^* = \arg \max \frac{1}{n} L(H)$$

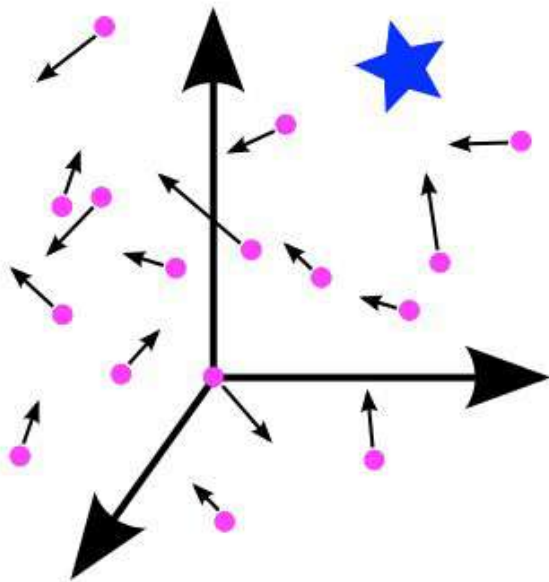
More details in paper!

PSO for Optimal Bandwidth Selection

$$v_{id} = \omega v_{id} + C_c U[0,1](x_{id} - p_{id}) + C_s U[0,1](x_{id} - p_{gd})$$

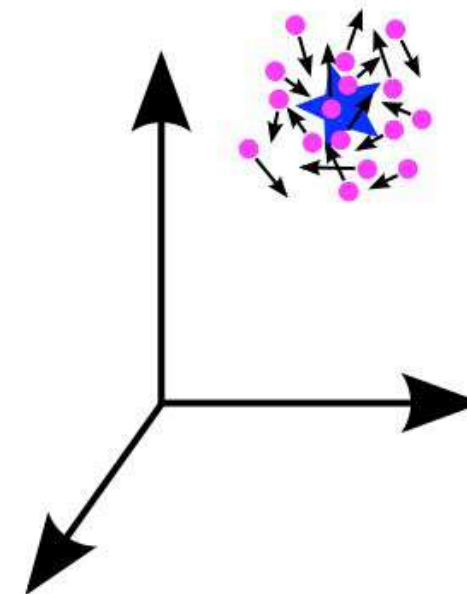
$$x_{id} = x_{id} + v_{id}$$

$$x_{id} = \min(\max(B_{ld}, x_{id}), B_{ud})$$



Iteration # 0

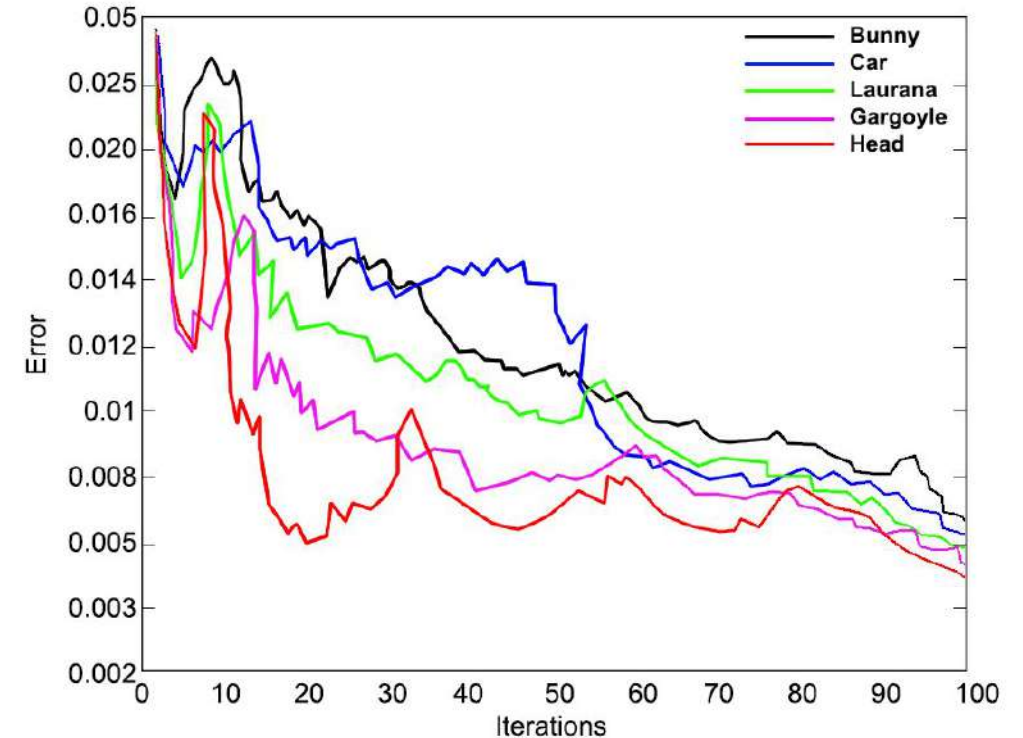
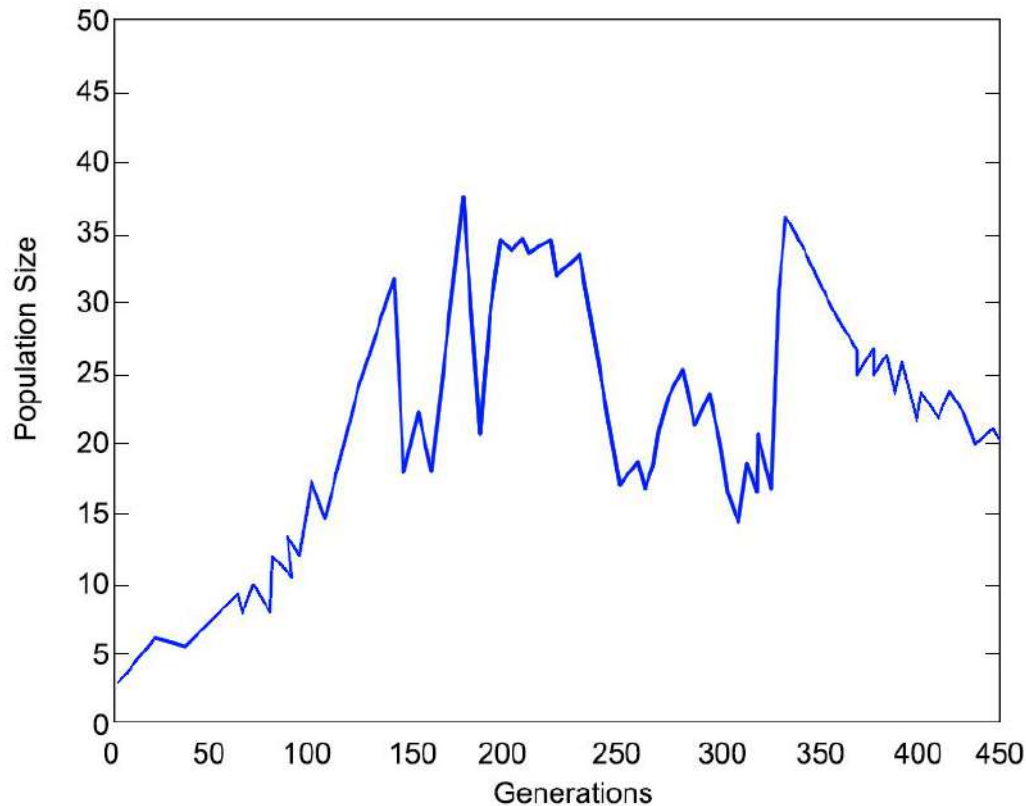
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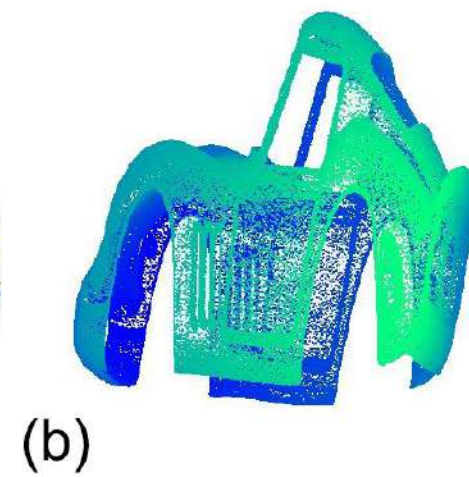
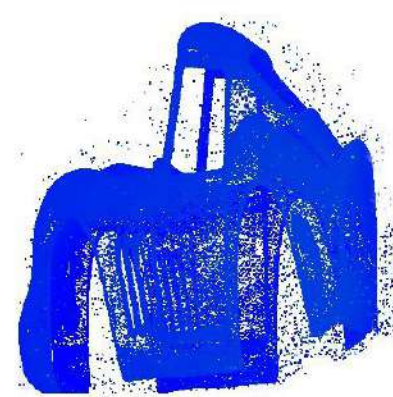
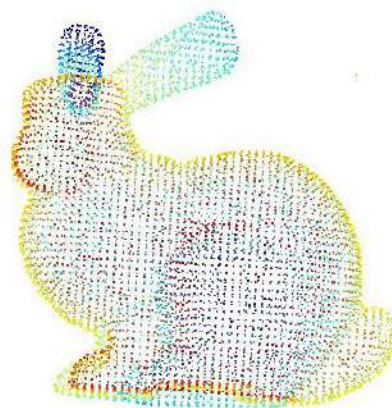
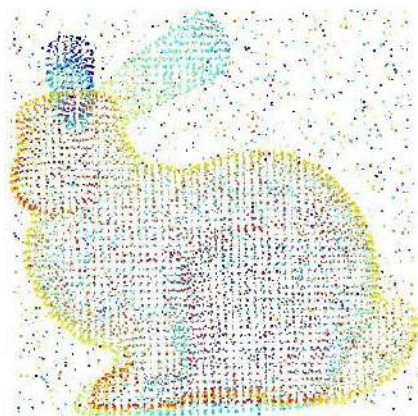
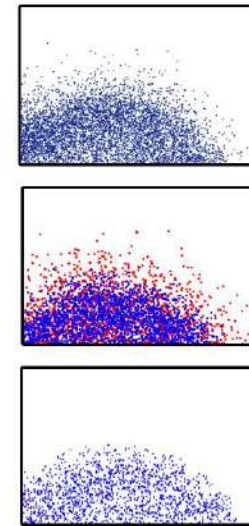
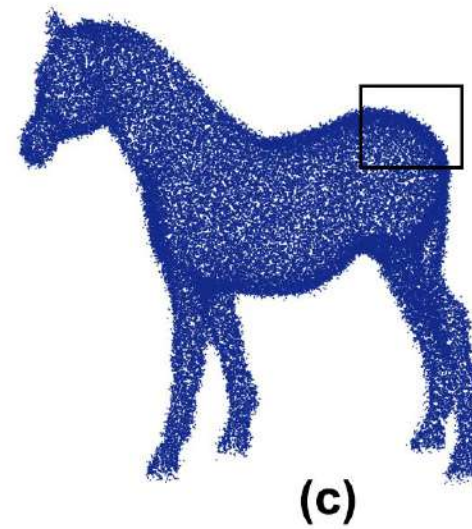
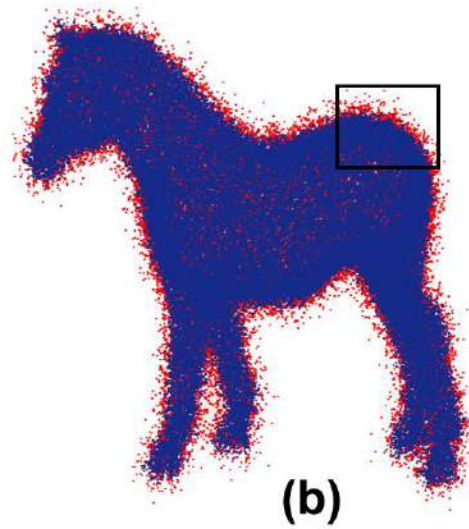
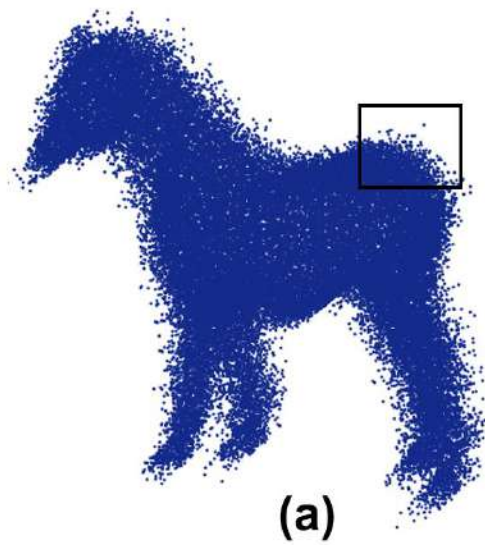
Iteration # N

Particle Selection

- Efficient Population Utilization Strategy for PSO (EPUS-PSO)
 - adopting population manager to significantly improve the efficiency of PSO
[ST Hsieh 2009]

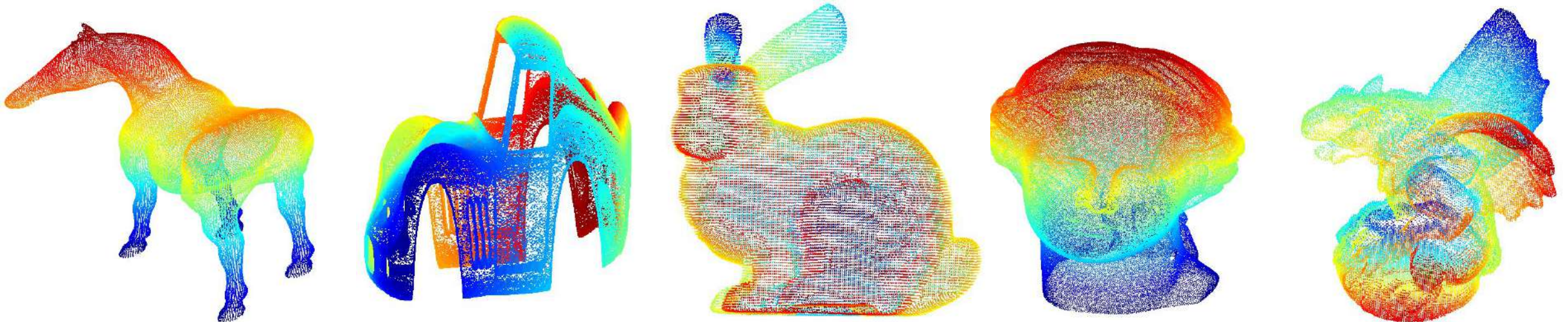


Results

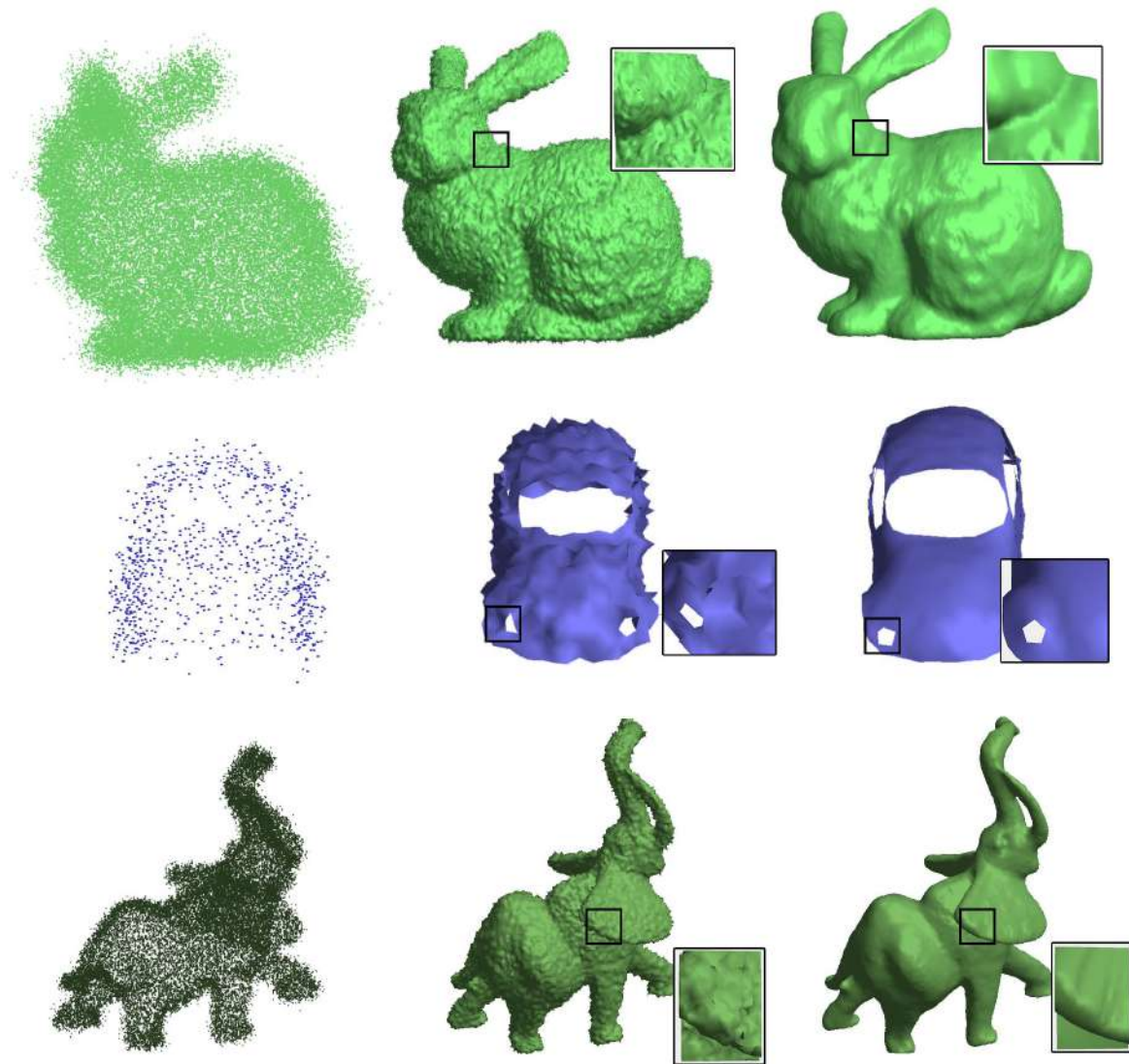


Performance

Data				
Bunny	330 K	324 K	29 s	30 s
Car	720 K	600 K	1 m 45 s	1 m 25 s
Horse	364 K	214 K	44.43 s	18 m 45 s
Gargoyle	2.1 M	796 K	3 m 2 s	4 m 44 s
Head	1.9 M	1.2 M	2 m 5 s	3 m 25 s



Bilateral Mesh Denoising



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Thanks!

Any Questions
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