

Introduction to Bayesian inference using Rstan: practical 1 solutions

The aim of this practical is to provide an introduction to the syntax and structure of the Stan programming language and to demonstrate some of the efficiency gains that vectorized operations can provide.

1 Getting started

1.1 Files in Rstudio

- Open Rstudio
- Open a new text file:

File -> New File -> Text File

and type the following Stan programme:

```
data {  
  int<lower=1> N;  
  real<lower=0,upper=1> p;  
}  
model {  
}  
generated quantities {  
  int x[N];  
  for(n in 1:N) {  
    x[n] = bernoulli_rng(p);  
  }  
}
```

Save the text file as `simulation.stan`.

- Open a new R script:

File -> New File -> R Script

and type the following sequence of commands, omitting the comments if you wish:

```
## Load the rstan package:  
library(rstan)  
## Allow rstan to exploit parallel computation:  
rstan_options(auto_write = TRUE)  
options(mc.cores = parallel::detectCores())  
## Set up some constants to pass to Stan:  
constants = list(N=30, p=0.8)  
## Compile and run Stan programme:  
output = stan(file="simulation.stan", data=constants, iter=1,  
              chains=1, algorithm="Fixed_param")  
## Extract simulated data:  
out = as.matrix(output)  
dim(out)  
head(out)  
## Format as vector, removing the log posterior (i.e. "__lp"):
```

```
x = out[1, -length(out)]
## Plot data:
barplot(table(x))
```

Save the R script. Note that Rstudio will correctly add the file extension .R. We can run our R script by sending the commands to the R console. For example, to send one line at a time, press Ctrl + Enter at the end of each line in turn.

1.2 Course R package

Installing the course R package is straightforward. First install drat:

```
install.packages("drat")
```

Then

```
drat::addRepo("jr-packages")
install.packages("jrRstan")
```

This R package contains copies of the practicals, solutions and data sets for the course in addition to some helpful functions that we will use. To load the package, use

```
library("jrRstan")
```

2 Simulating data

In the Stan programme above, we are not attempting to carry out any inference. Instead we're using the generated quantities block to sample some data; in this case a random sample of size 30 from the Bernoulli distribution with probability 0.8. In other words a sequence of 30 0s and 1s where the probability of getting a 1 is 0.8. When we simply want to use Stan to simulate data in this way, notice that the (required) model block is empty. We will learn about the stan function in Chapter 4, but for now, we simply note that the file argument should be the name of the text file where the Stan programme is saved and, if the programme contains a data block, the data argument should be a list with a named element for each variable declared. When it is being used to simulate data, we generally set algorithm="Fixed_param", iter=1 and chains=1.

- What happens if you try to pass values for N or p that violate the constraints in the data block? For example, what happens if:

```
faulty_constants = list(N=30, p=10)
stan(file="simulation.stan", data=faulty_constants, iter=1,
      chains=1, algorithm="Fixed_param")

## failed to create the sampler; sampling not done
```

- Add a transformed data block and include a print statement to check whether the constants, N and p , have been correctly passed.

```
// Modified Stan programme, saved in simulation.stan:
```

```
data {
  int<lower=1> N;
  real<lower=0,upper=1> p;
}
transformed data {
  print("N = ", N, ", p = ", p);
}
model {
}
generated quantities {
  int x[N];
  for(n in 1:N) {
    x[n] = bernoulli_rng(p);
  }
}
```

```
## Compile and run modified Stan programme:
```

```
output = stan(file="simulation.stan", data=constants, iter=1,
              chains=1, algorithm="Fixed_param")
```

```
## N = 30, p = 0.8
```

```
##
```

```
## SAMPLING FOR MODEL 'simulation' NOW (CHAIN 1).
```

```
##
```

```
## Chain 1, Iteration: 1 / 1 [100%] (Sampling)
```

```
## Elapsed Time: 1e-06 seconds (Warm-up)
```

```
## 8e-06 seconds (Sampling)
```

```
## 9e-06 seconds (Total)
```

- Rather than passing the constants N and p through the data block, we can alternatively omit the data block and declare and assign values to these variables in the transformed data block. We can then omit the data argument in the call to the stan function in R. Write a new Stan programme of this form called simulation_v2.stan then compile and run the programme in R.

```
// New Stan programme, saved in simulation_v2.stan:
```

```
transformed data {
  int<lower=1> N = 30;
  real<lower=0,upper=1> p = 0.8;
}
model {
}
generated quantities {
  int x[N];
  for(n in 1:N) {
    x[n] = bernoulli_rng(p);
  }
}
```

```
## Compile and run new Stan programme:
output_v2 = stan(file="simulation_v2.stan", iter=1, chains=1,
                 algorithm="Fixed_param")
```

- In R, we can generate uniform random numbers using the `runif` function. For example:

```
runif(5, min=-3, max=3)

## [1] -0.1596925 -0.2342325 -1.0333105 -1.4535651 -1.2428872
```

Use the `lookup` function to find a corresponding function in Stan.

```
lookup("runif")

##      StanFunction      Arguments Return Type Page
## 670 uniform_rng (real alpha, real beta)      real 529
```

- Augment your programme `simulation_v2.stan` to additionally simulate 30 uniform random numbers in a vector `z` with lower bound -3 and upper bound 3 . Call the new programme `simulation_v3.stan`. Compile and run it in R and check that the output looks reasonable.

```
// Modified Stan programme, saved in simulation_v3.stan:
transformed data {
  int<lower=1> N = 30;
  real<lower=0,upper=1> p = 0.8;
  real a = -3;
  real b = 3;
}
model {
}
generated quantities {
  int x[N];
  vector[N] z;
  for(n in 1:N) {
    x[n] = bernoulli_rng(p);
    z[n] = uniform_rng(a, b);
  }
}
```

```
## Compile and run modified Stan programme:
output_v3 = stan(file="simulation_v3.stan", iter=1, chains=1,
                 algorithm="Fixed_param")
```

```
## Extract simulated data:
out_v3 = as.matrix(output_v3)
colnames(out_v3)

## [1] "x[1]" "x[2]" "x[3]" "x[4]" "x[5]" "x[6]" "x[7]" "x[8]"
## [9] "x[9]" "x[10]" "x[11]" "x[12]" "x[13]" "x[14]" "x[15]" "x[16]"
## [17] "x[17]" "x[18]" "x[19]" "x[20]" "x[21]" "x[22]" "x[23]" "x[24]"
## [25] "x[25]" "x[26]" "x[27]" "x[28]" "x[29]" "x[30]" "z[1]" "z[2]"
```

```
## [33] "z[3]" "z[4]" "z[5]" "z[6]" "z[7]" "z[8]" "z[9]" "z[10]"
## [41] "z[11]" "z[12]" "z[13]" "z[14]" "z[15]" "z[16]" "z[17]" "z[18]"
## [49] "z[19]" "z[20]" "z[21]" "z[22]" "z[23]" "z[24]" "z[25]" "z[26]"
## [57] "z[27]" "z[28]" "z[29]" "z[30]" "lp__"

x = out_v3[1, 1:30]
z = out_v3[1, 31:60]
## Plot data:
par(mfrow=c(1,2))
barplot(table(x), main="Barplot of x")
hist(z)
par(mfrow=c(1,1))
```

- Modify simulation_v3.stan, saving the file as simulation_v4.stan, so that instead of representing x and z as separate objects, you represent them as a length-2 array of vectors called xz.

```
/* The generated quantities block of simulation_v3.stan
   should change as follows, with the result saved in
   simulation_v4.stan: */
generated quantities {
  vector[N] xz[2];
  for(n in 1:N) {
    xz[1][n] = bernoulli_rng(p);
    xz[2][n] = uniform_rng(a, b);
  }
}
```

- Modify simulation_v4.stan, saving the file as simulation_v5.stan, to additionally simulate 30 normal random variables in a vector y where $y[n]$ has mean $2.5 * x[n] + 1.5 * z[n]$ and standard deviation 0.1. Compile and run your Stan programme in R and check that the output looks reasonable.

```
/* The generated quantities block of simulation_v4.stan
   should change as follows, with the result saved in
   simulation_v5.stan: */
generated quantities {
  vector[N] y;
  vector[N] xz[2];
  for(n in 1:N) {
    xz[1][n] = bernoulli_rng(p);
    xz[2][n] = uniform_rng(a, b);
    y[n] = normal_rng(2.5 * xz[1][n] + 1.5 * xz[2][n], 0.1);
  }
}
```

```
## Compile and run Stan programme:
output_v5 = stan(file="simulation_v5.stan", iter=1, chains=1,
                 algorithm="Fixed_param")
```

```
## Extract simulated data:
out_v5 = as.matrix(output_v5)
colnames(out_v5)
```

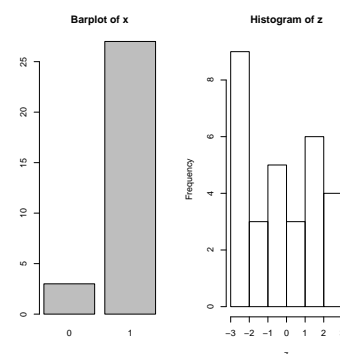


Figure 1: Simulated data.

```
## [1] "y[1]"      "y[2]"      "y[3]"      "y[4]"      "y[5]"      "y[6]"
## [7] "y[7]"      "y[8]"      "y[9]"      "y[10]"     "y[11]"     "y[12]"
## [13] "y[13]"     "y[14]"     "y[15]"     "y[16]"     "y[17]"     "y[18]"
## [19] "y[19]"     "y[20]"     "y[21]"     "y[22]"     "y[23]"     "y[24]"
## [25] "y[25]"     "y[26]"     "y[27]"     "y[28]"     "y[29]"     "y[30]"
## [31] "xz[1,1]"   "xz[2,1]"   "xz[1,2]"   "xz[2,2]"   "xz[1,3]"   "xz[2,3]"
## [37] "xz[1,4]"   "xz[2,4]"   "xz[1,5]"   "xz[2,5]"   "xz[1,6]"   "xz[2,6]"
## [43] "xz[1,7]"   "xz[2,7]"   "xz[1,8]"   "xz[2,8]"   "xz[1,9]"   "xz[2,9]"
## [49] "xz[1,10]"  "xz[2,10]"  "xz[1,11]"  "xz[2,11]"  "xz[1,12]"  "xz[2,12]"
## [55] "xz[1,13]"  "xz[2,13]"  "xz[1,14]"  "xz[2,14]"  "xz[1,15]"  "xz[2,15]"
## [61] "xz[1,16]"  "xz[2,16]"  "xz[1,17]"  "xz[2,17]"  "xz[1,18]"  "xz[2,18]"
## [67] "xz[1,19]"  "xz[2,19]"  "xz[1,20]"  "xz[2,20]"  "xz[1,21]"  "xz[2,21]"
## [73] "xz[1,22]"  "xz[2,22]"  "xz[1,23]"  "xz[2,23]"  "xz[1,24]"  "xz[2,24]"
## [79] "xz[1,25]"  "xz[2,25]"  "xz[1,26]"  "xz[2,26]"  "xz[1,27]"  "xz[2,27]"
## [85] "xz[1,28]"  "xz[2,28]"  "xz[1,29]"  "xz[2,29]"  "xz[1,30]"  "xz[2,30]"
## [91] "lp__"
```

```
y = out_v5[1, 1:30]
x = out_v5[1, seq(31, 90, 2)]
z = out_v5[1, seq(32, 90, 2)]
## Plot:
plot(z, y, main="Scatter plot of z vs y")
```

- If you wanted your Stan programme to return only y and not xz how could you modify your code?

```
/* The generated quantities block of simulation_v5.stan
   should become: */
generated quantities {
  vector[N] y;
  for(n in 1:N) {
    /* Define xz in a block so that it becomes a
       local variable that will not be printed */
    real xz[2];
    xz[1] = bernoulli_rng(p);
    xz[2] = uniform_rng(a, b);
    y[n] = normal_rng(2.5 * xz[1] + 1.5 * xz[2], 0.1);
  }
}
```

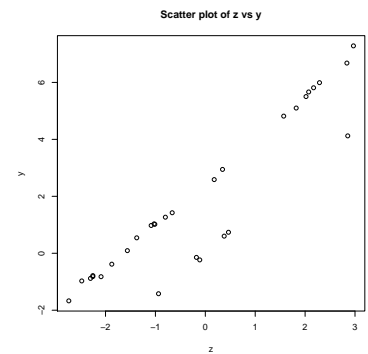


Figure 2: Scatter plot of simulated data.

3 Vectorized operations

In this part of the practical we will investigate the efficiency gains we can realise through the vectorized operations discussed in Chapter 3.

- Copy the Stan programme from Figure 3.1 into a text file and save it as `figure3_1.stan`.
- Create a revised version of this programme which exploits the vectorization tricks described later in the Chapter. Save it as `figure3_1.v2.stan`. Note that in lectures we considered optimising only the model block. It is also possible to make the functions and generated quantities blocks more efficient.

```

functions {
  real deviance(vector y, matrix X, vector beta, real sigma_sq) {
    vector[num_elements(y)] eta = X * beta; /* Single matrix-vector
                                              calculation */
    real dev = (-2) * normal_lpdf(y | eta, sqrt(sigma_sq)); /*
                                                              Vectorized form of the normal
                                                              probability function */

    return dev;
  }
}

data {
  int<lower=1> K;           // No. columns in design matrix
  int<lower=1> N;           // Sample size
  matrix[N, K] X;          // Design matrix
  vector[N] y;             // Response variables
  row_vector[K] x_pred;    // Design matrix for prediction
  real m_beta[K];          // Prior means for beta[k]
  real m_sigma_sq;         // Prior mean for log(sigma_sq)
  real<lower=0> s_beta[K];  // Prior std. devs for beta[k]
  real<lower=0> s_sigma_sq; // Prior std. dev for log(sigma_sq)
}

parameters {
  real<lower=0> sigma_sq;
  vector[K] beta;
}

model {
  // Likelihood:
  vector[N] eta = X * beta; /* Single matrix-vector calculation
  y ~ normal(eta, sqrt(sigma_sq)); /* Vectorized form of the normal
                                   probability function */

  // Prior:
  beta ~ normal(m_beta, s_beta); /* Vectorized form of the normal
                                   probability function */

  sigma_sq ~ lognormal(m_sigma_sq, s_sigma_sq);
}

generated quantities {
  real y_pred; // Predicted response
  real dev; // Deviance
  // Sample from predictive distribution:
  {
    // Predicted mean, defined in local block so not stored:
    real eta_pred = x_pred * beta; /* Single matrix-vector
                                     calculation */

    y_pred = normal_rng(eta_pred, sqrt(sigma_sq));
  }
  dev = deviance(y, X, beta, sigma_sq);
}

```

- Load the data to pass to the Stan function. For convenience in this practical, the list that we will construct in Chapter 4 has been saved in a data set called `practical1_data` which can be loaded through:

```

## Load data to pass to stan function:
data(practical1_data)

```

We can now compile and run each programme by executing the following code:

```
## Run the programme from Figure 3.1:
fig3_1 = stan("figure3.1.stan", data=practical1_data)
## Run the revised programme:
fig3_1_v2 = stan("figure3.1_v2.stan", data=practical1_data)
```

We will consider the `stan` function and its usage in Chapter 4. For now, simply make a note of the time taken to run each programme. (You can access this by passing the object returned by the `stan` function to the `get_elapsed_time` function). How much speed-up do you gain by using the revised programme?

```
## I get a substantial speed up on my machine:
get_elapsed_time(fig3_1)

##           warmup   sample
## chain:1 1.499192 0.320963
## chain:2 1.255483 0.346918
## chain:3 1.613902 0.350561
## chain:4 1.277692 0.338422

get_elapsed_time(fig3_1_v2)

##           warmup   sample
## chain:1 0.349930 0.075796
## chain:2 0.346703 0.094286
## chain:3 0.416585 0.101875
## chain:4 0.433729 0.101080
```

Solutions

Solutions are available as a vignette:

```
library("jrRstan")
vignette("solutions1", package="jrRstan")
```