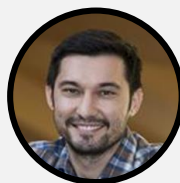


# Plug-and-Play Priors for Reconstruction-based Placental Image Registration (PnP-RR)

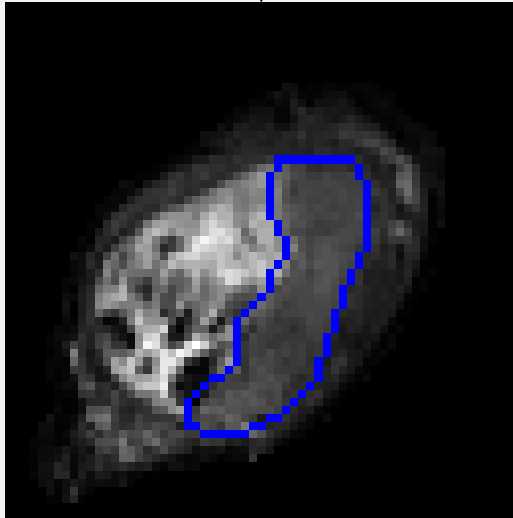
Jiarui Xing, Ulugbek Kamilov,  
Wenjie Wu, Yong Wang,  
and Miaomiao Zhang



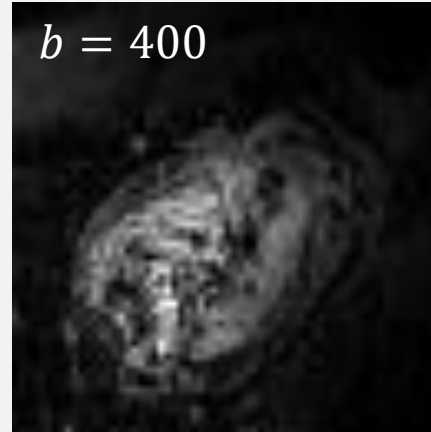
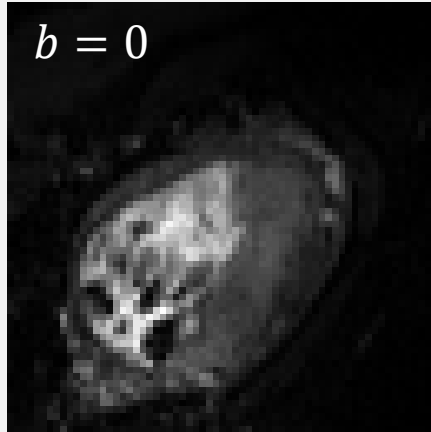
# Monitoring Pregnancy Health through Diffusion-weighted MRI (DW-MRI)



DW-MRI

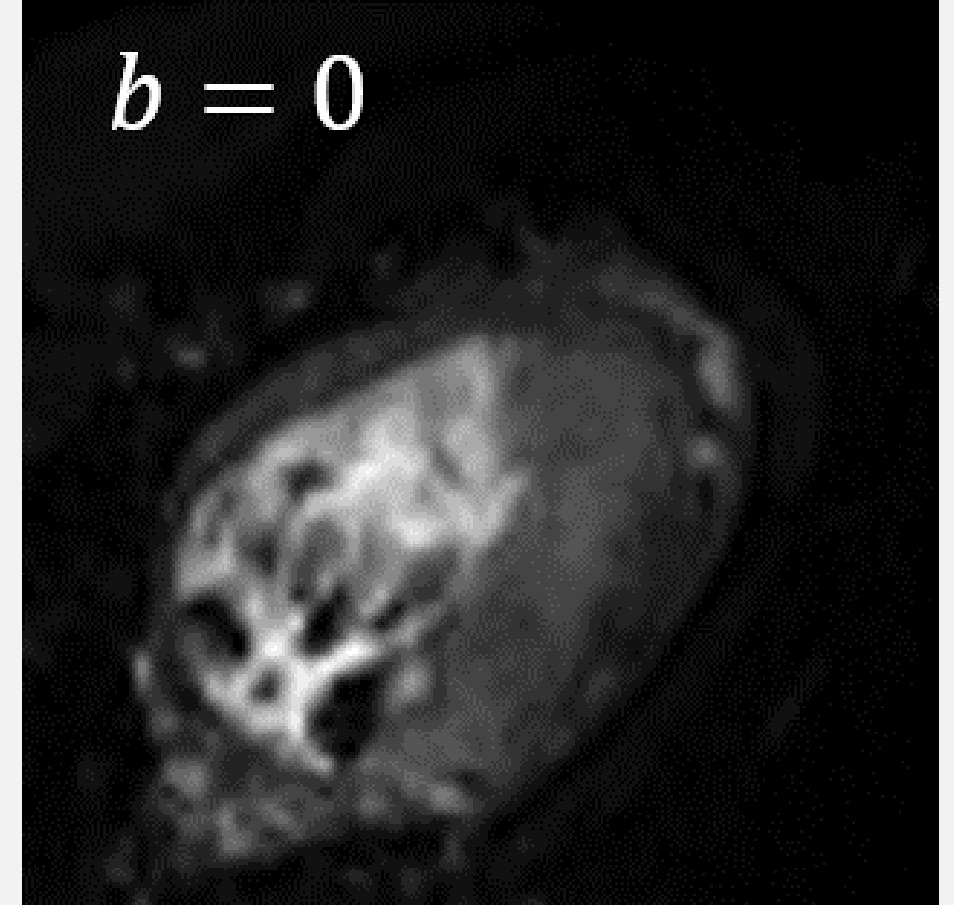
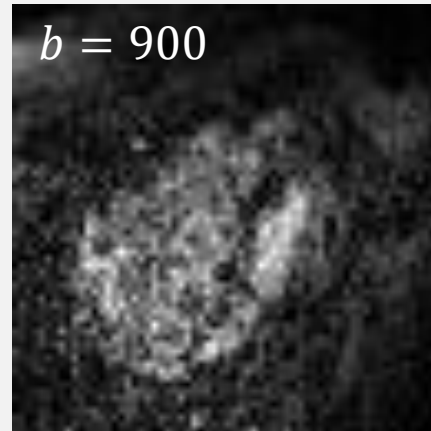
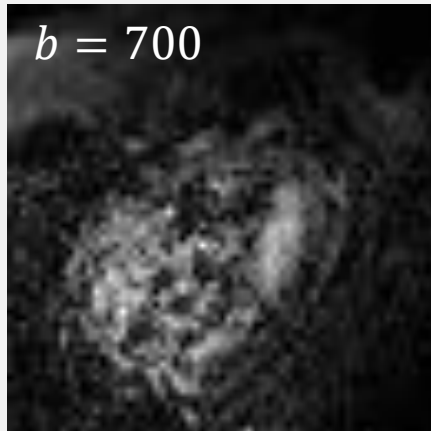
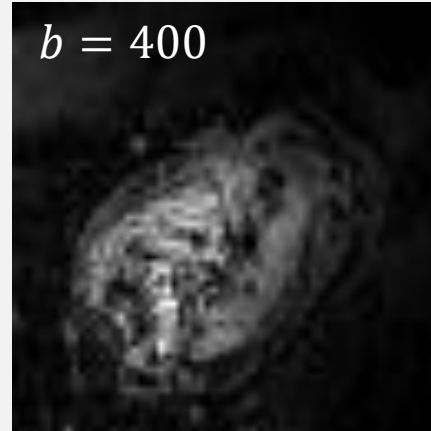
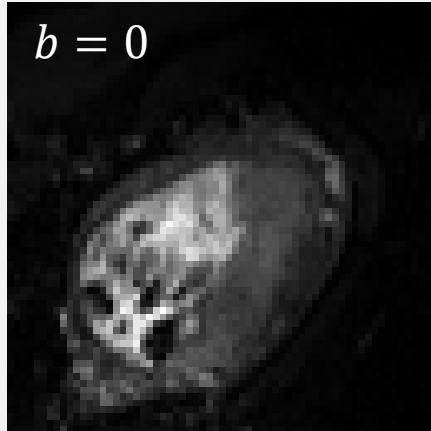


# Motion Correction for DW-MRI



⋮

# Motion Correction for DW-MRI



Higher b-value -> stronger noise

# Goal

- Motion Correction for placental DW-MR images containing severe noise

# Goal

- Motion Correction for placental DW-MR images containing severe noise
- Develop a noise-robust registration framework

# Challenges

- Traditional registration methods fail due to severe noises

# Challenges

- Traditional registration methods fail due to severe noises
- Explicit **objective function** for optimization is **unclear**



# Outline

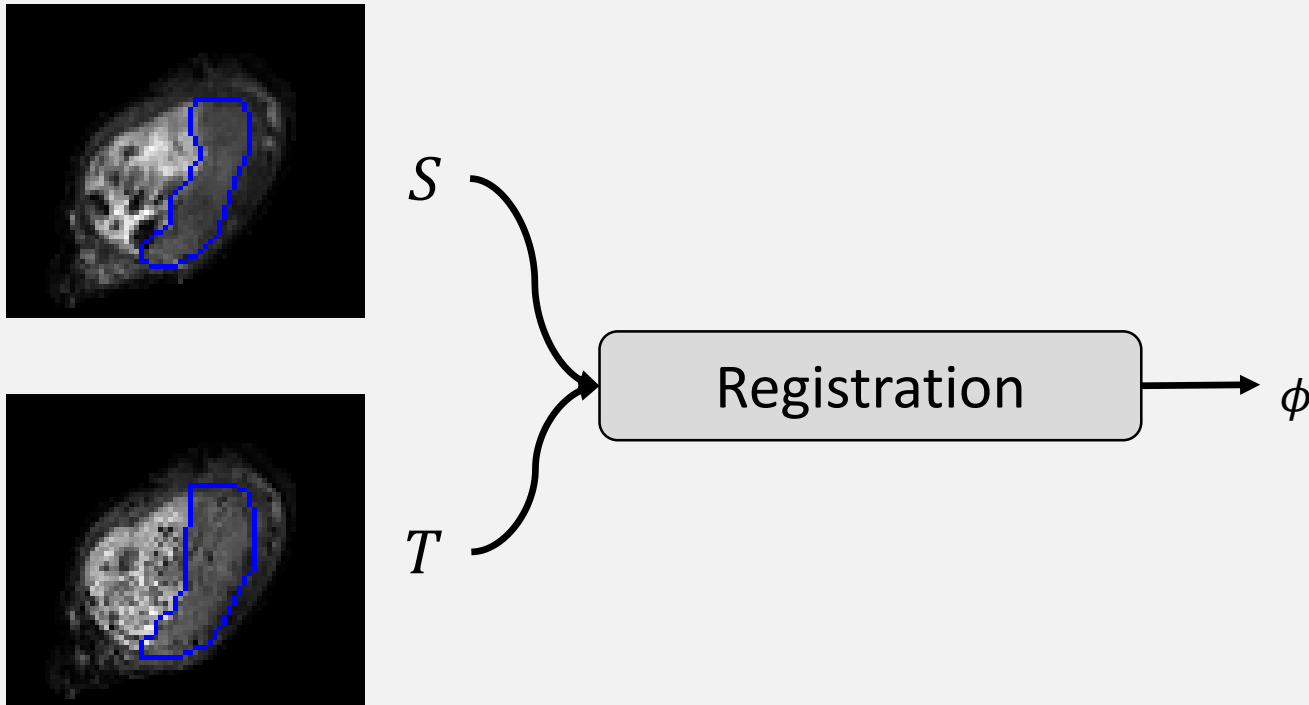
- Background: Image registration
- Related Work
- Proposed Method: Plug-and-play Reconstruction-registration (PnP-RR)
- Experiments and results
- Conclusion

# Outline

- Background: Image registration
- Related Work
- Proposed Method: Plug-and-play Reconstruction-registration (PnP-RR)
- Experiments and results
- Conclusion

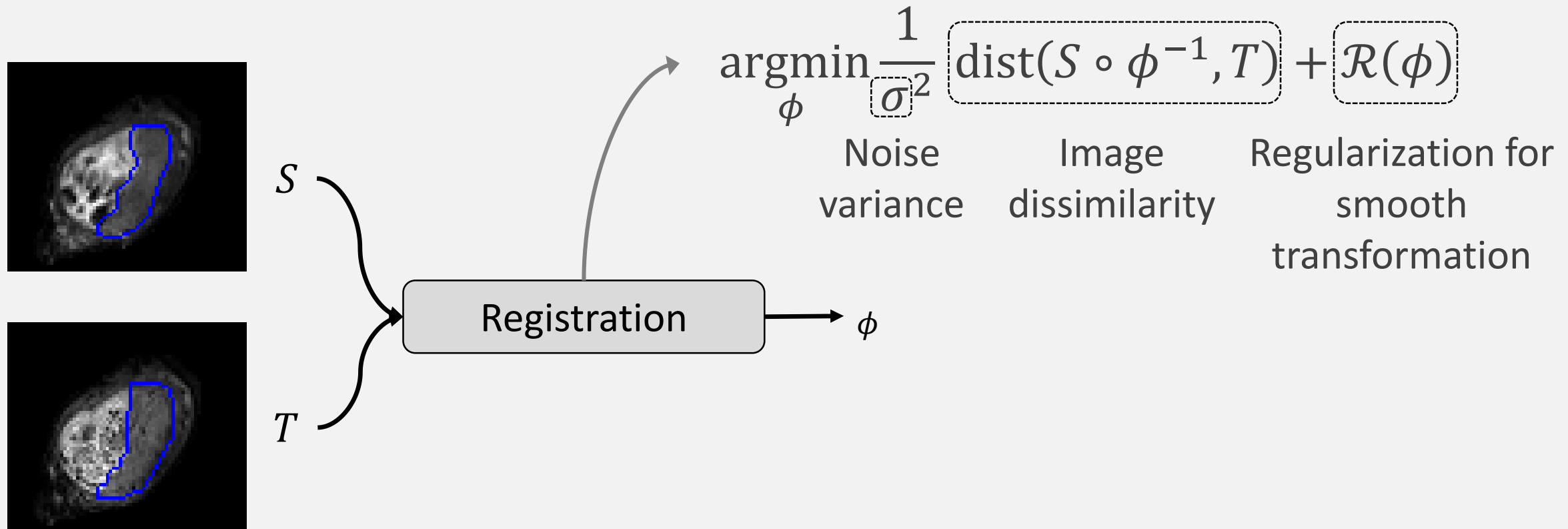
## Background: Image registration

- Task: find the deformation  $\phi$  between a source Image  $S$  and a target image  $T$



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# Outline

- Background: Image registration
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- Experiments and results
- Discussion and conclusion

## Related Work

- Traditional Image Registration



→ FAIL for  
SEVERE NOISE-CORRUPTED images

## Related Work

- Traditional Image Registration



→ FAIL for  
SEVERE NOISE-CORRUPTED images

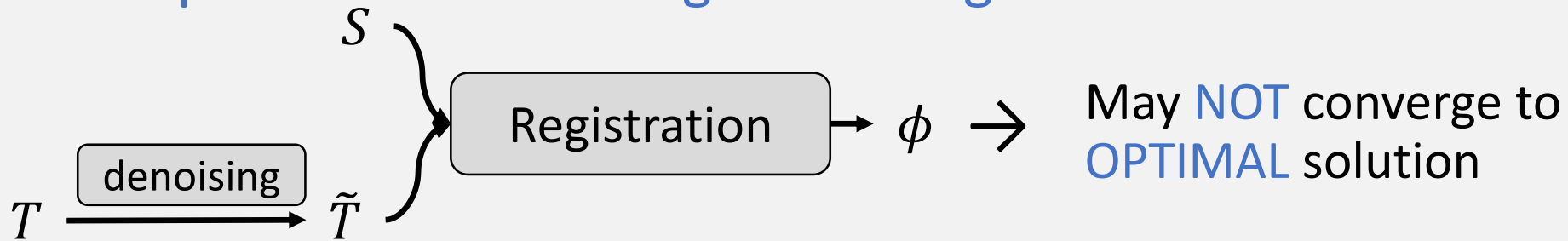
- Idea: Denoising + Registration

# Related Work

- Traditional Image Registration



- Two-step Method: denoising before registration



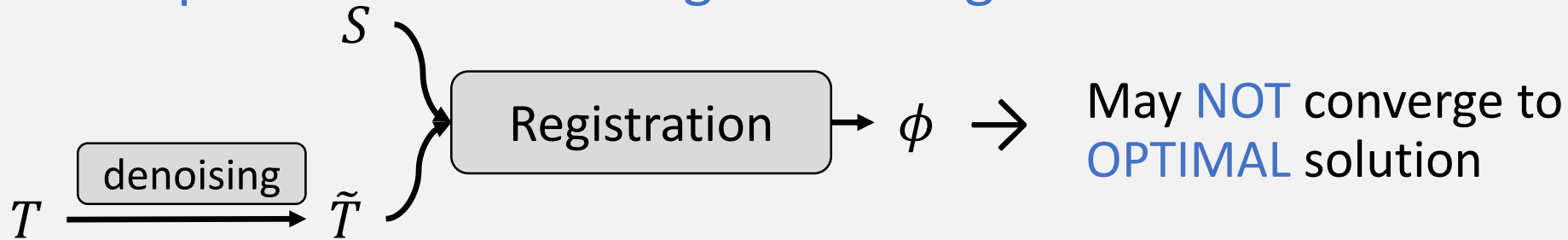


# Related Work

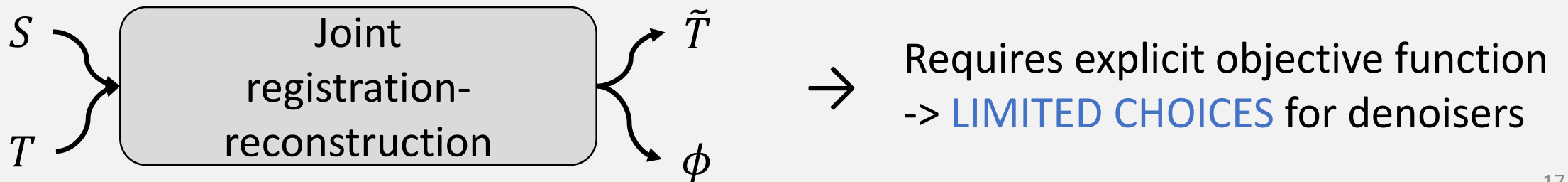
- Traditional Image Registration



- Two-step Method: denoising before registration



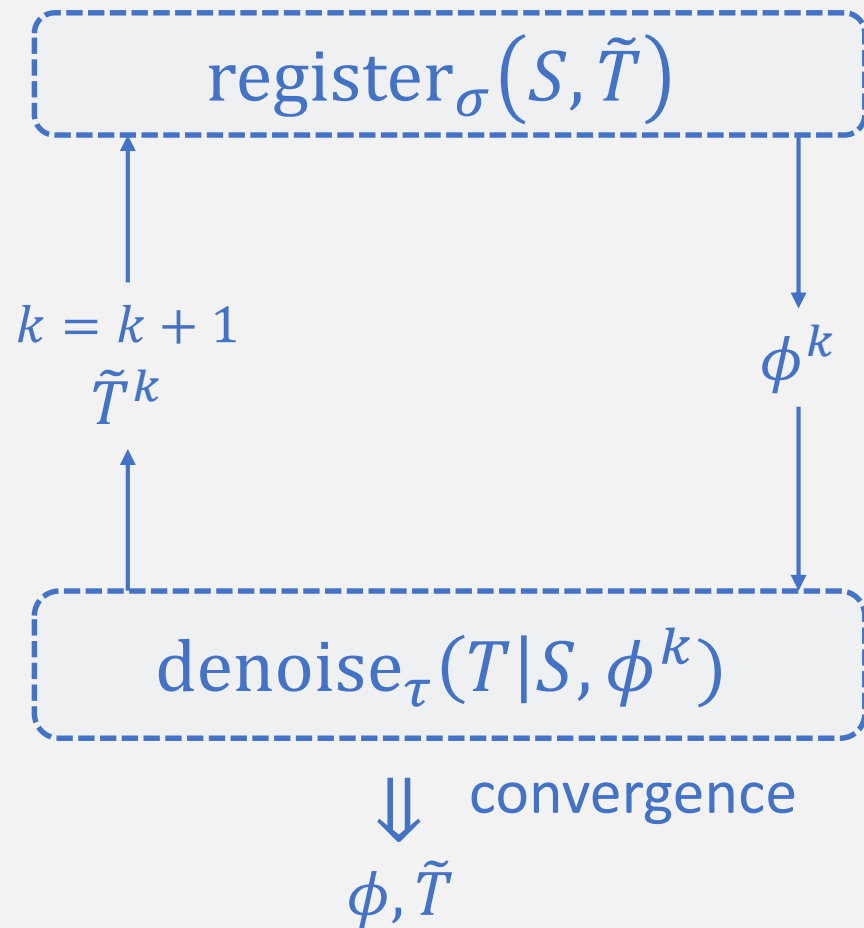
- Joint Optimization Method



# Outline

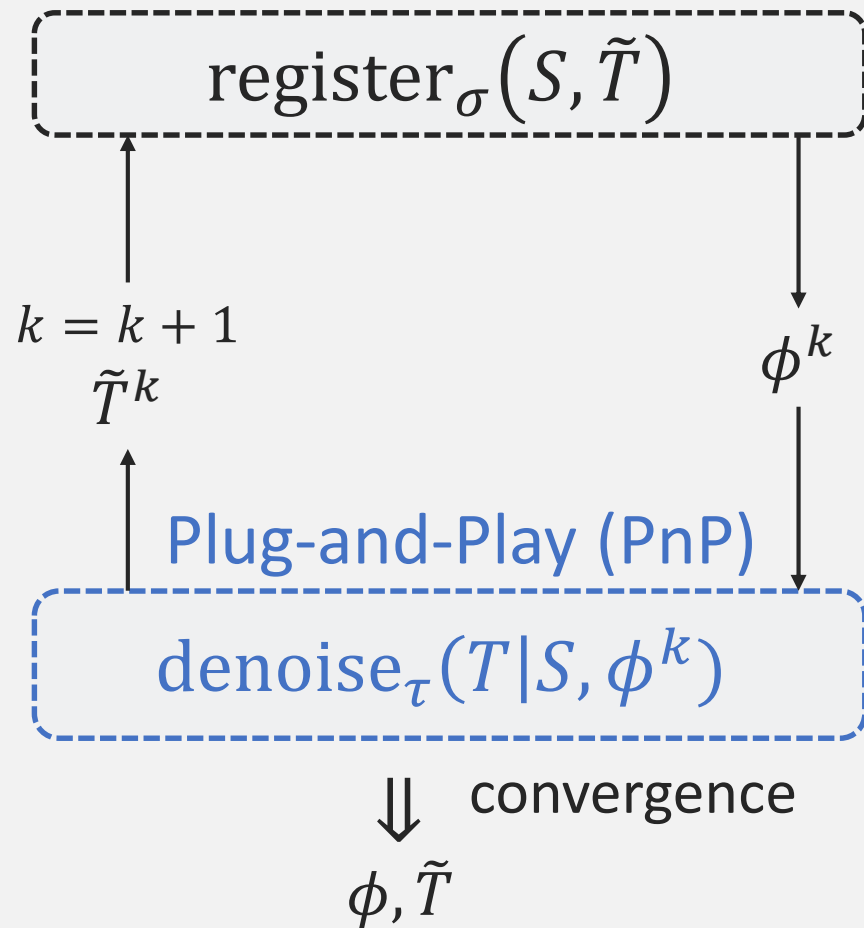
- Background: Image registration
- Related Work
- Proposed Method: Plug-and-play Reconstruction-registration (PnP-RR)
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# Proposed method: PnP-RR



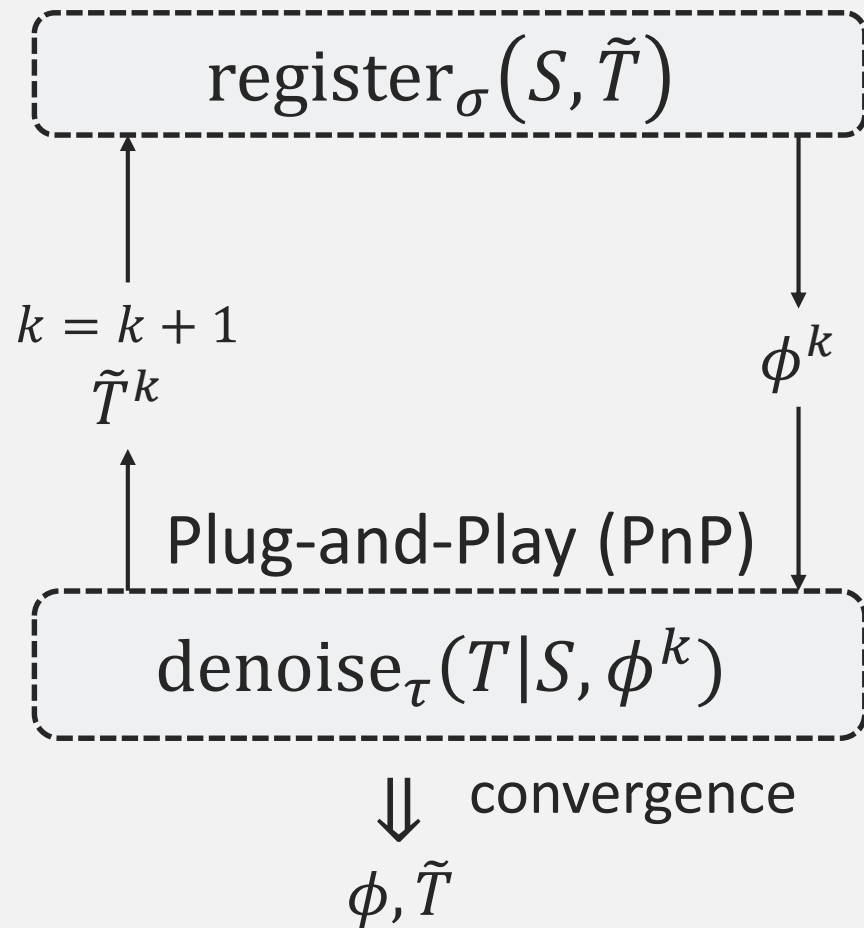
$S$ : Source image     $T$ : Target image  
 $\tilde{T}$ : denoised target images  
 $\phi$ : deformation

## Proposed method: PnP-RR



$S$ : Source image     $T$ : Target image  
 $\tilde{T}$ : denoised target images  
 $\phi$ : deformation

# Proposed method: PnP-RR



$S$ : Source image     $T$ : Target image  
 $\tilde{T}$ : denoised target images  
 $\phi$ : deformation

## • Advantages

- TV ✓
- TGV ✓
- BM3D ✓
- Neural Network ✓

Flexible to  
CHOOSE DENOISER

Better  
PERFORMANCE



Simple to  
IMPLEMENT



Easy to  
TUNE

# Proposed method: PnP-RR

- Mathematical View
- **JOINT**  
denoising-registration  
objective function

$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \\ + \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2$$

# Proposed method: PnP-RR

- Mathematical View
- **JOINT**  
denoising-registration  
objective function

$$\operatorname{argmin}_{\phi, \tilde{T}} \left\{ \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \right\} \text{--- Registration}$$
$$+ \left\{ \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2 \right\} \text{--- Denoising}$$

# Proposed method: PnP-RR

- Mathematical View

- **JOINT**

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$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \\ + \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2$$

- **SPLIT**

Formulated as  
proximal algorithm

$$\text{register}_{\sigma}(S, \tilde{T}^k) \rightarrow \phi^k$$

$$\text{denoise}_{\tau}(\tilde{T}^k | S, \phi^k) \rightarrow \tilde{T}^{k+1}$$



# Proposed method: PnP-RR

- Mathematical View

- **JOINT**

denoising-registration  
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$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \\ + \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2$$

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} Iteratively  
repeat until  
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- Mathematical View

- **JOINT**

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$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \\ + \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2$$

- **SPLIT**

Formulated as  
proximal algorithm

register<sub>σ</sub>

denoise<sub>τ</sub>

→  
Replace with  
arbitrary  
denoiser

- **REPLACE**

Formulated as  
PnP algorithm

register<sub>σ</sub>

denoise'<sub>τ</sub>

# Proposed method: PnP-RR

- Mathematical View

- **JOINT**

denoising-registration  
objective function

$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi) \\ + \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2$$

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Formulated as  
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- Mathematical View

- **JOINT**

denoising-registration  
objective function

$$\operatorname{argmin}_{\phi, \tilde{T}} \frac{1}{\sigma^2} \|S \circ \phi^{-1} - \tilde{T}\|_{L2}^2 + \mathcal{R}_{\text{reg}}(\phi)$$

$$+ \left[ \lambda_1 \mathcal{R}_{\text{denoising}}(\tilde{T}) + \lambda_2 \|T - \tilde{T}\|_{L2}^2 \right]$$

- **SPLIT**

Formulated as  
proximal algorithm

register<sub>σ</sub>

[denoise<sub>τ</sub>]

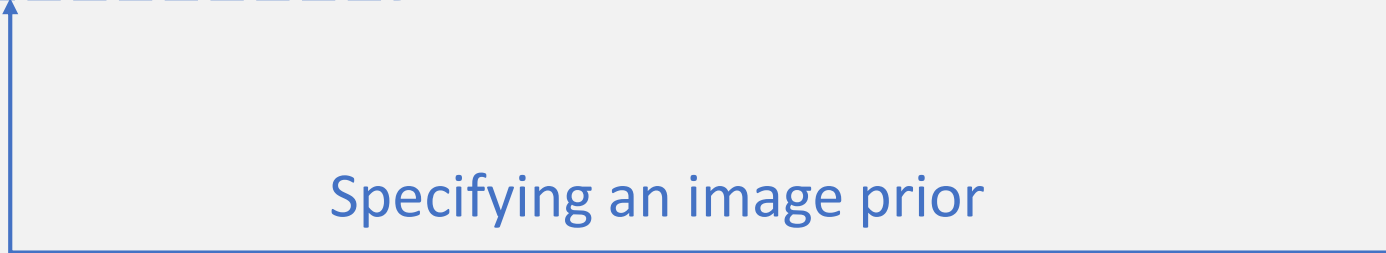
- **REPLACE**

Formulated as  
PnP algorithm

register<sub>σ</sub>

[denoise'<sub>τ</sub>]

Specifying an image prior



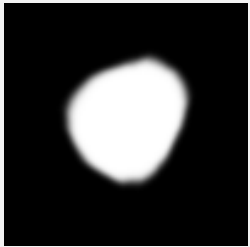
# Outline

- Background: Image registration
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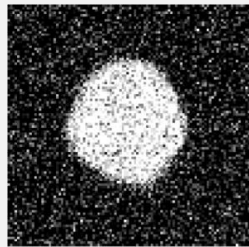
# Experiments

- Data

- 2D synthetic images



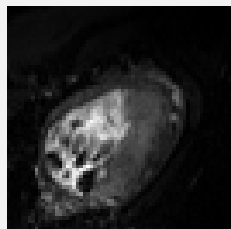
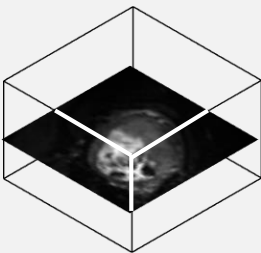
Source  $S$



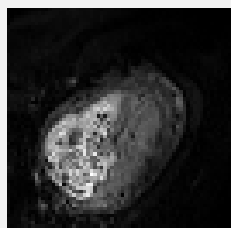
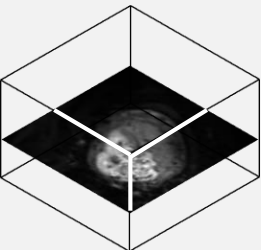
Target  $T$

- 3D placental DW-MR images

Source  $S$



Target  $T$



- Algorithm Setting

- Registration

- Fourier-approximated Lie Algebras for Shooting (FLASH)<sup>[1]</sup>

- Denoising

- Total variation (TV)<sup>[2]</sup>
    - Total generalized variation (TGV)<sup>[3]</sup>
    - Block-matching and 3D filtering (BM3D)<sup>[4]</sup>

[1] Zhang, et al., IPMI, 2017

[2] Rudin, Leonid I. et al., Physica D: nonlinear phenomena 60.1-4 (1992)

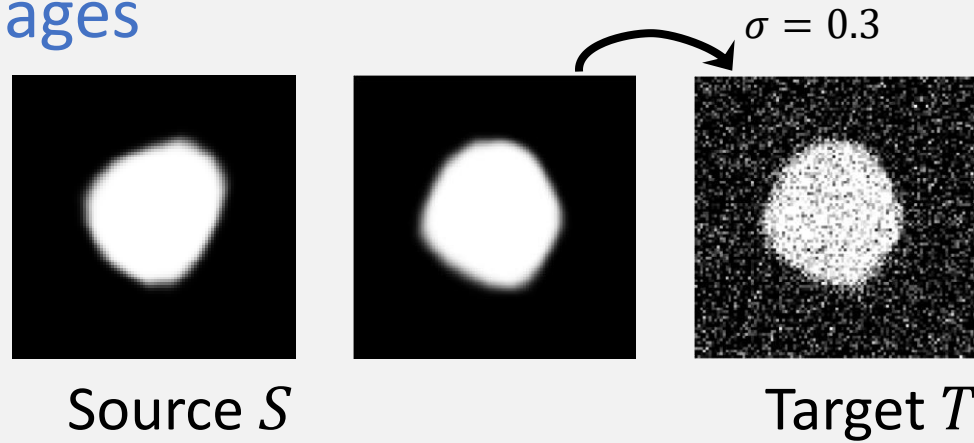
[3] Bredies et al., SIAM Journal on Imaging Sciences 3.3 (2010)

[4] Dabov et al. Image Processing: Algorithms and Systems, Neural Networks, and Machine Learning. Vol. 6064. (2006)

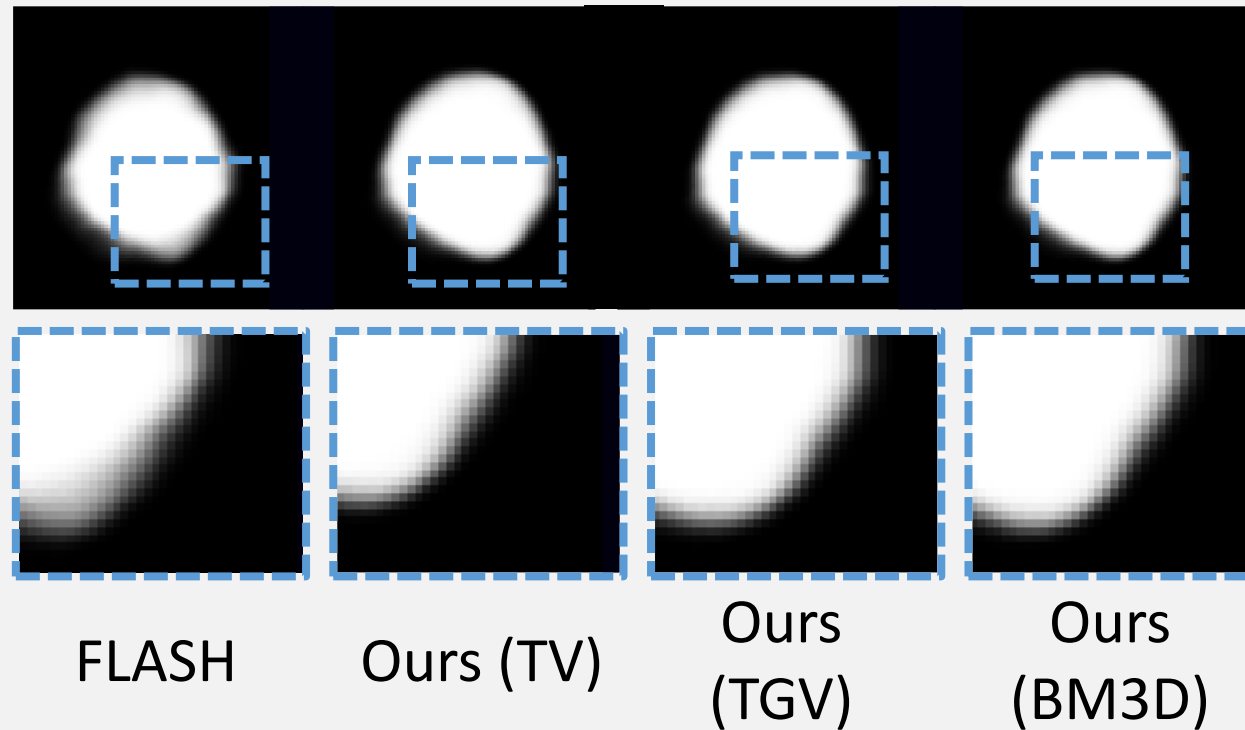
# Results

- 2D synthetic images

Source  
and  
Target

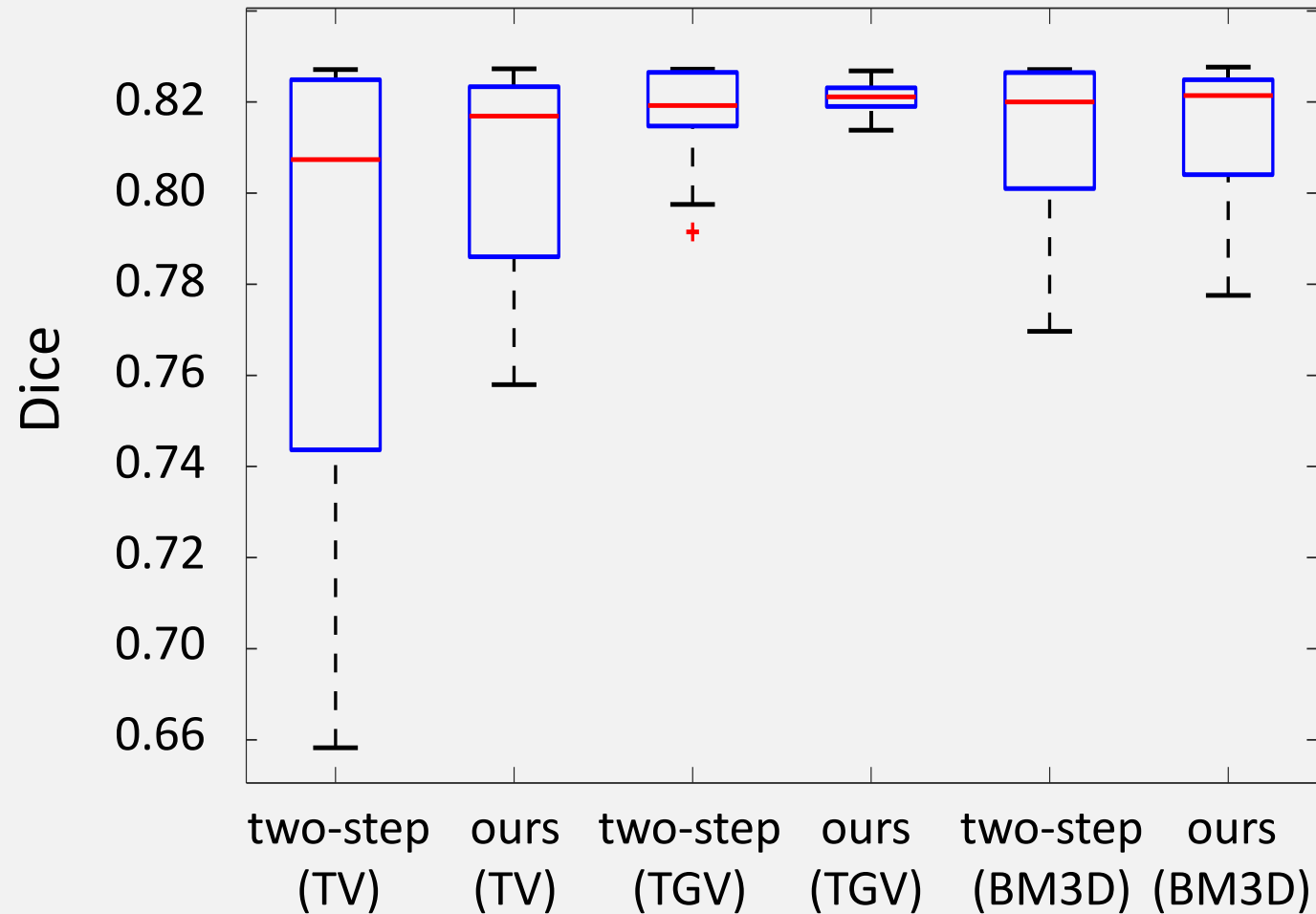


Result  
(deformed  
source)



# Results

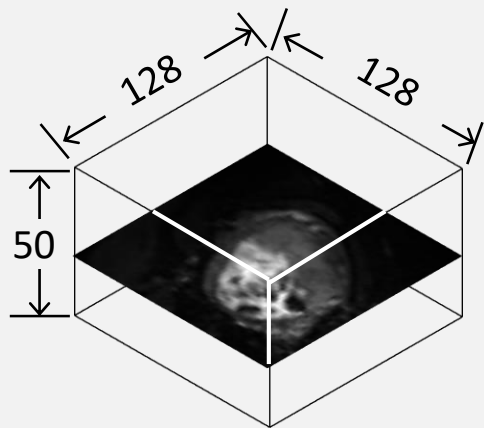
- 2D synthetic images: Dice Evaluation



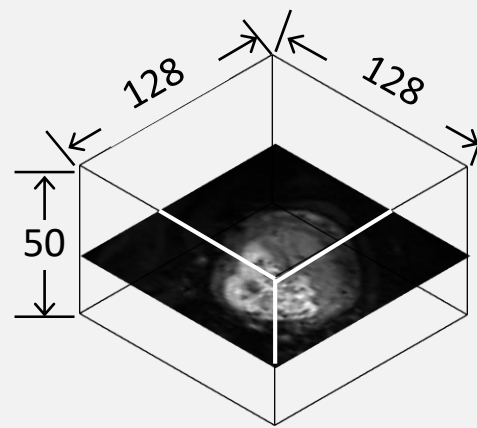


# Results

- 3D placental DW-MR images



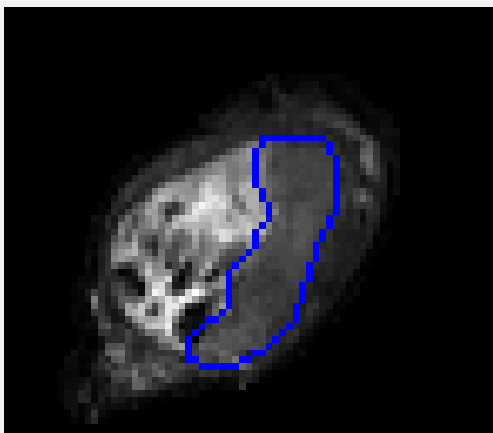
Source  $S$



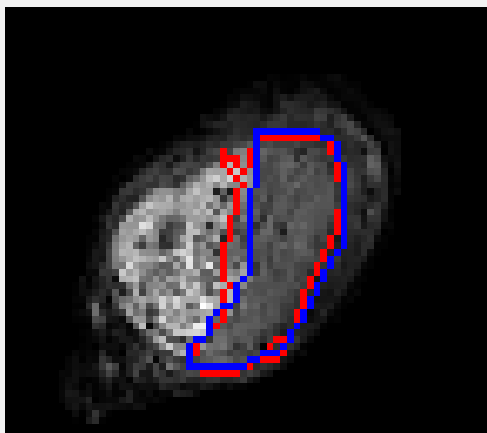
Target  $T$

# Results

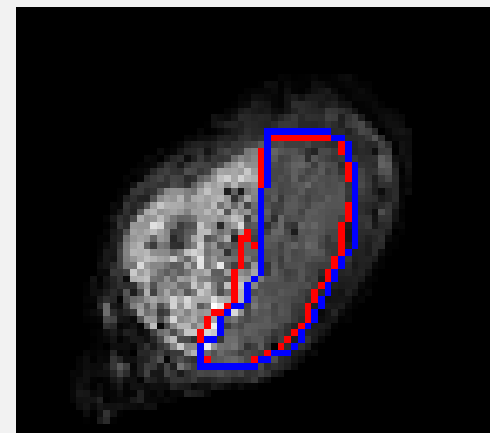
- Propagated placental segments



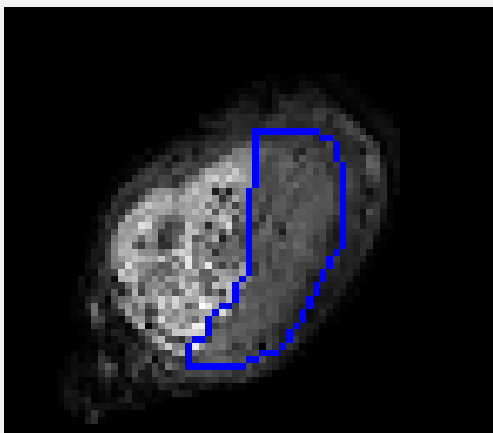
Source



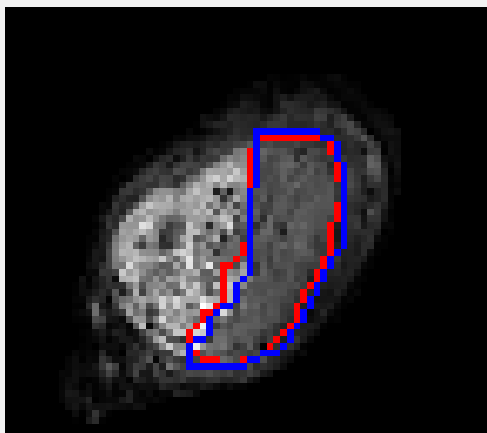
FLASH



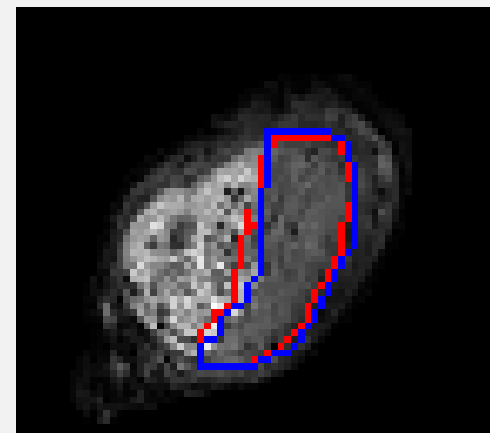
Ours (TGV)



Target



Ours (TV)



Ours (BM3D)

# Outline

- Background: Image registration
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## Conclusion

- Develop a robust registration framework, PnP-RR, that corrects motion for severely noise-corrupted images

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# Conclusion

- Develop a robust registration framework, PnP-RR, that corrects motion for severely noise-corrupted images
- Model has more flexibility to allow arbitrary denoising algorithm integrated with the registration task
- Easy to implement and robust to parameter tuning

Paper



Slides

