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Assignment 8

1. The three images below were used to create the final panorama image. The attempt was to capture images to create a planar panorama:



Image Left



Image Middle

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Image Right

2. Below is the final panorama image using overlapping average blending with 40 matches:



Final Panorama

3. **blendedImagePair:**

Two attempts were made for the blendedImagePair implementation. The first was the basic averaging of the overlapped regions. The second an attempt to feather the overlapping edges. The feathering attempt involved creating a step function of the viewable region of the warped image. Once the step function was created it was then blurred using cv2.GaussianBlur with a 75 x 75 kernel. The blurred step function was then normalized and applied to the warped image. The inverted blurred step function was applied to image 2 as show below:

```
Args:
    warped_image (numpy.ndarray): The image provided by cv2.warpPerspective.
    image_2 (numpy.ndarray): The image to insert into the warped image.
    point (numpy.ndarray): The point (x,y) to insert the image at.

Returns:
    image: The warped image with image_2 blended into it.

"""
output_image = np.copy(warped_image)
image_2_copy = np.copy(image_2)
image_2_expanded = np.zeros_like(warped_image)
# REPLACE THIS WITH YOUR BLENDING CODE.
# Feathering attempt
image_2_expanded[point[1]:point[1] + image_2.shape[0],
                  point[0]:point[0] + image_2.shape[1]] = image_2
# Create step functions
step_x = np.zeros_like(warped_image)
step_y = np.zeros_like(warped_image)
step_x[:, :point[0]] = 255
step_y[:point[1], :] = 255

step = step_x + step_y
step[step > 255] = step[step > 255]*0.5

# Blur step function
blurred_step = cv2.GaussianBlur(step, (75,75), 0)

blurred_step = blurred_step*0.00392157 # 1/255

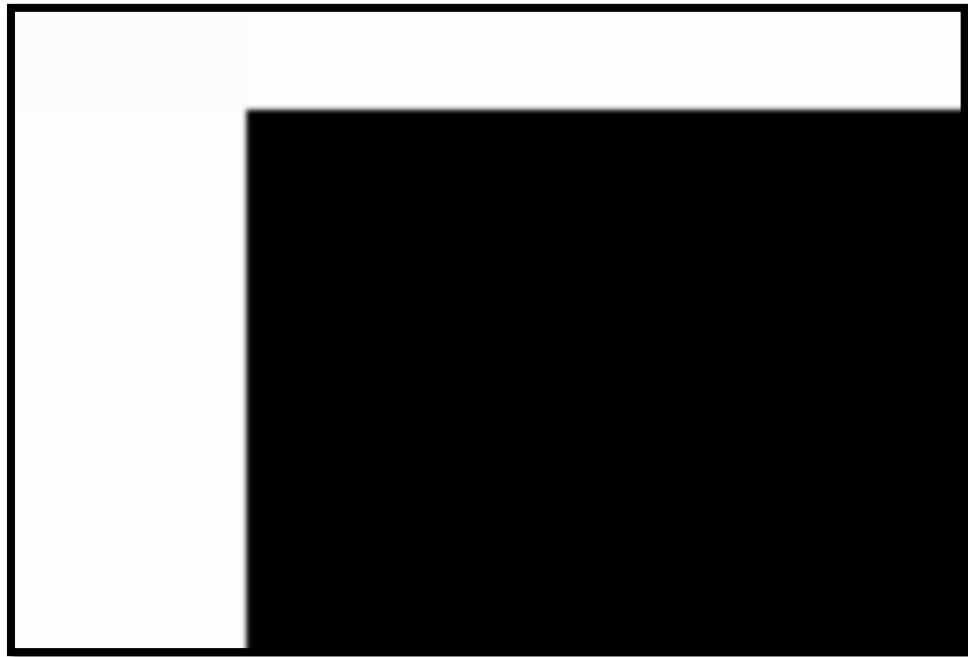
output_image = output_image*blurred_step

image_2_expanded = image_2_expanded*(1 - blurred_step)

output_image = output_image + image_2_expanded
```

Unfortunately the output of this portion caused an error during the second iteration in the findMatchesBetweenImages function. Specifically the sift.detectAndCompute function could not process the blended image. At this point no further attempt was made to process the octaves to complete the feathering algorithm. Below are images of the step function and the output of the first iteration:

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Feathering Step Function

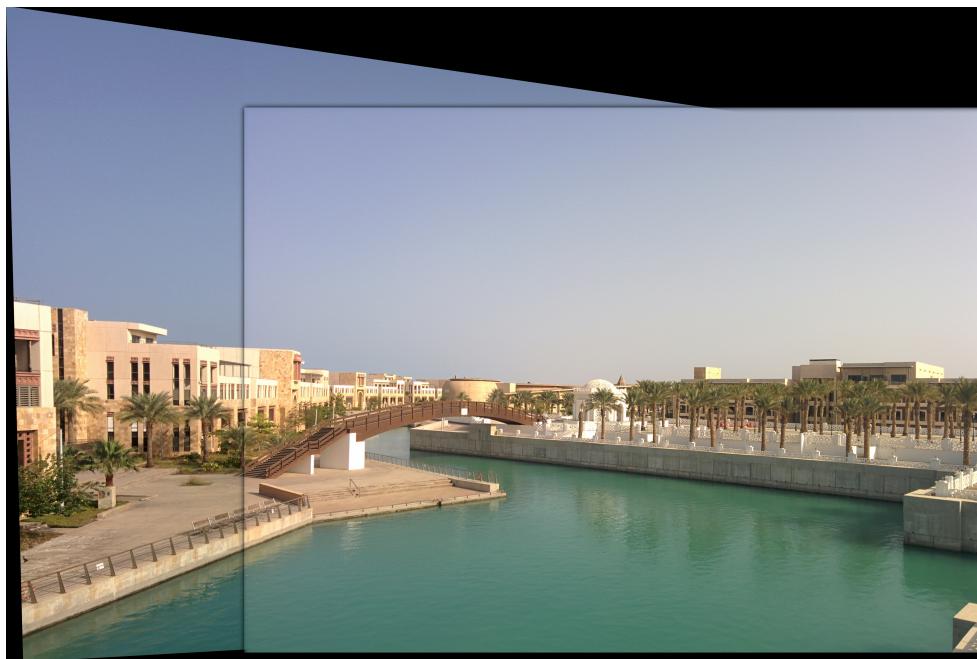


Image 1 and Image 2 “Feathered”

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This resulted in falling back to the overlapping average implementation. For this implementation the overlapping regions were sliced and scaled using NumPy. Once the overlapping regions are calculated and scaled the scaled copy of image_2 is expanded and added to the scaled copy of the warped image as seen in the code below:

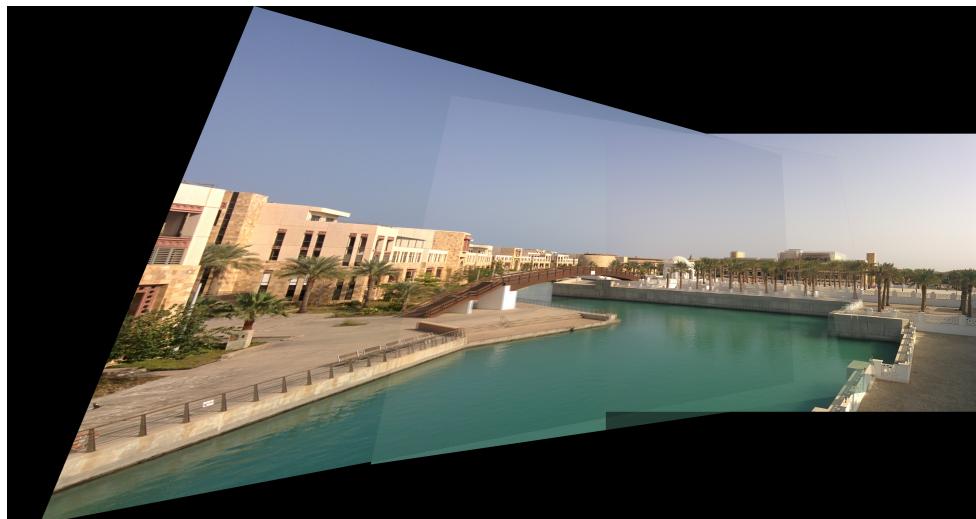
```
output_image = np.copy(warped_image)
image_2_copy = np.copy(image_2)
# Create a copy of image_2
image_2_expanded = np.zeros_like(warped_image)
# Average of overlap
warped_overlap = output_image[point[1]:warped_image.shape[0], point[0]:warped_image.shape[1]]
image_2_overlap = warped_overlap[:image_2.shape[0], :]
# Boolean mask for overlap
boolean_overlap = image_2_overlap > 0
# Create a copy of output_image
output_image[point[1]:warped_image.shape[0], point[0]:warped_image.shape[1]] = \
    warped_image[point[1]:warped_image.shape[0], point[0]:warped_image.shape[1]] * 0.5
# Scale image_2_copy by 0.5
image_2_copy[boolean_overlap] = image_2_copy[boolean_overlap] * 0.5
# Create a copy of image_2_expanded
image_2_expanded = np.zeros_like(warped_image)
# Add image_2_copy to image_2_expanded
image_2_expanded[point[1]:point[1] + image_2_copy.shape[0], \
    point[0]:point[0] + image_2_copy.shape[1]] = image_2_copy
# Add image_2_expanded to output_image
output_image = output_image + image_2_expanded
# END OF FUNCTION
```

While this did create a panorama the blending seemed to have changed how the additional iterations compute the perspective warp compared to test code that pastes the second image into the panorama:

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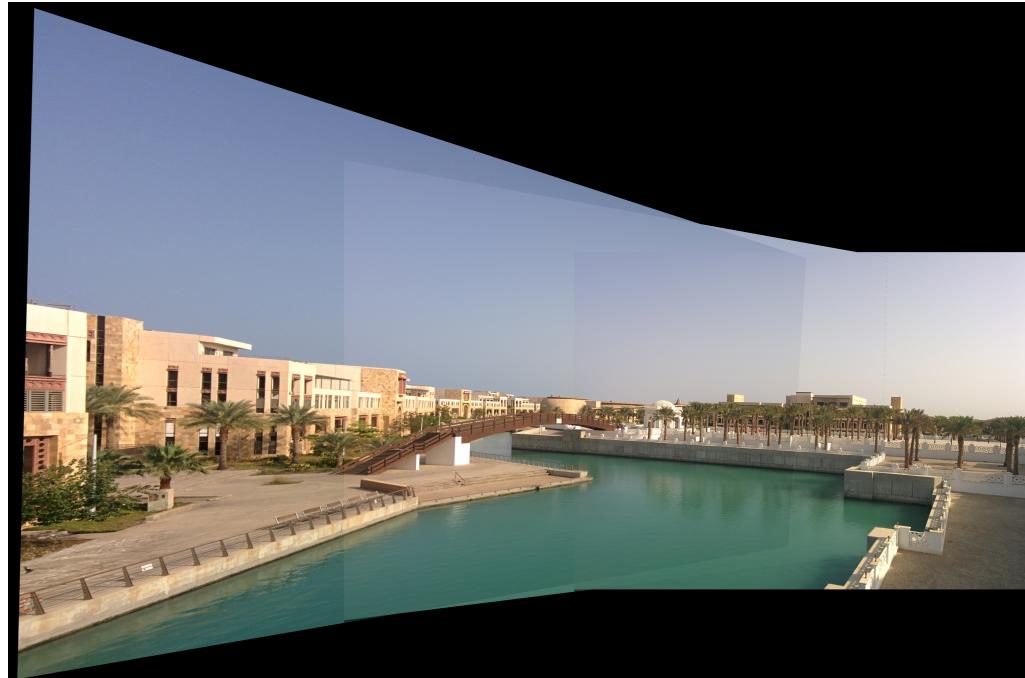
Paste Blending Panorama with 20 matches



Overlapping Average Panorama with 20 matches

The above image seems a bit too warped and has artifacts as well as signs for blurriness. However doubling the number of matches had a positive effect and helped remove some of the blurriness and artifacts:

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Overlapping Average Panorama with 40 matches

In addition, reducing the matches results in no improvement. The blurring and artifacts are still present as well as the warping:



Overlapping Average Panorama with 5 matches

On my final panorama I used 40 matches to get a better quality image using the overlapping average blend.

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I attempted to take a planar panorama as best I could. While my panorama seemed to blend better than the test images I wish I would've been able to implement feather down the seam to eliminate the visible edges between the separate photos.