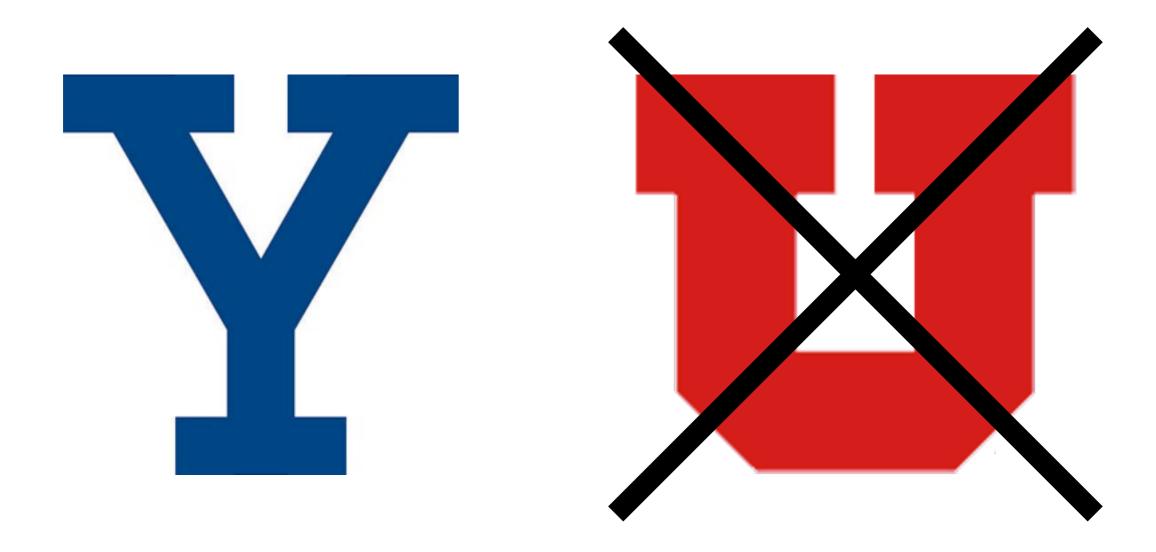
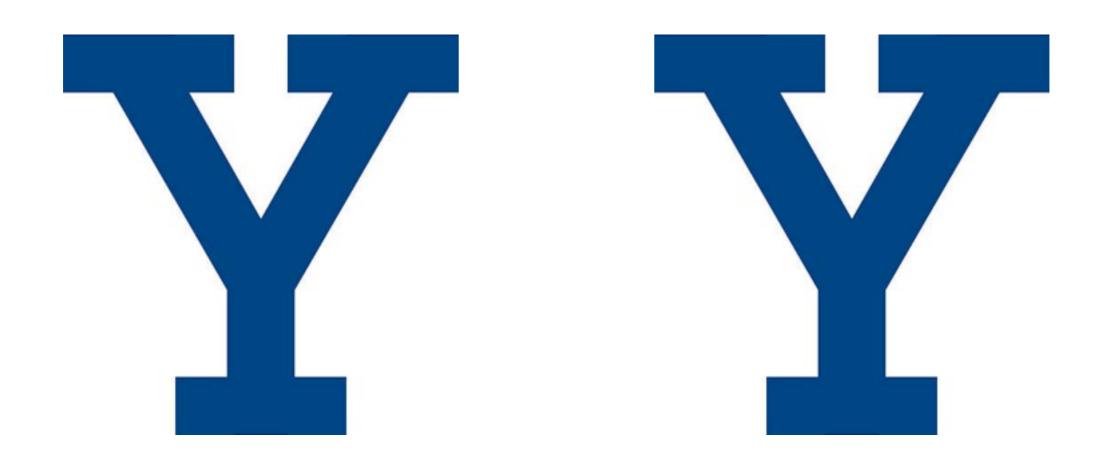
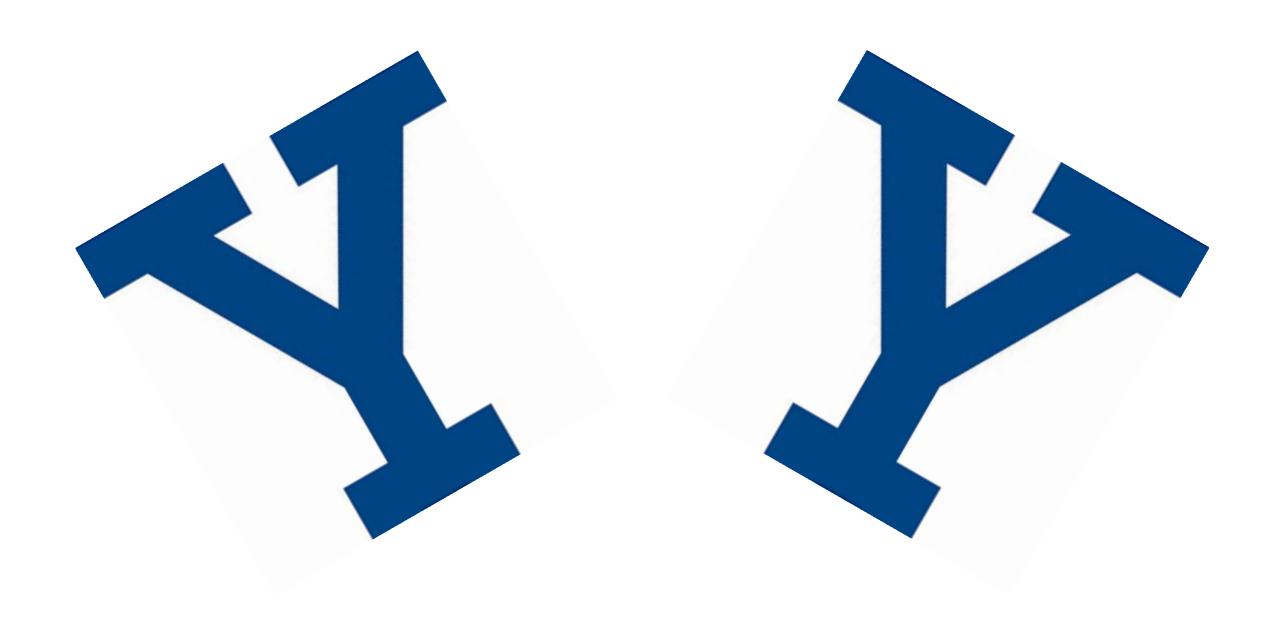


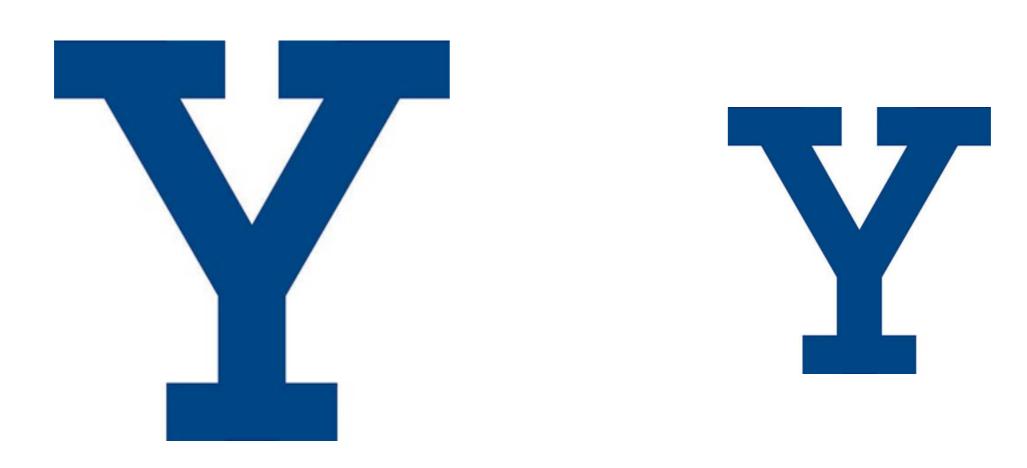
Multiple Coordinate Spaces

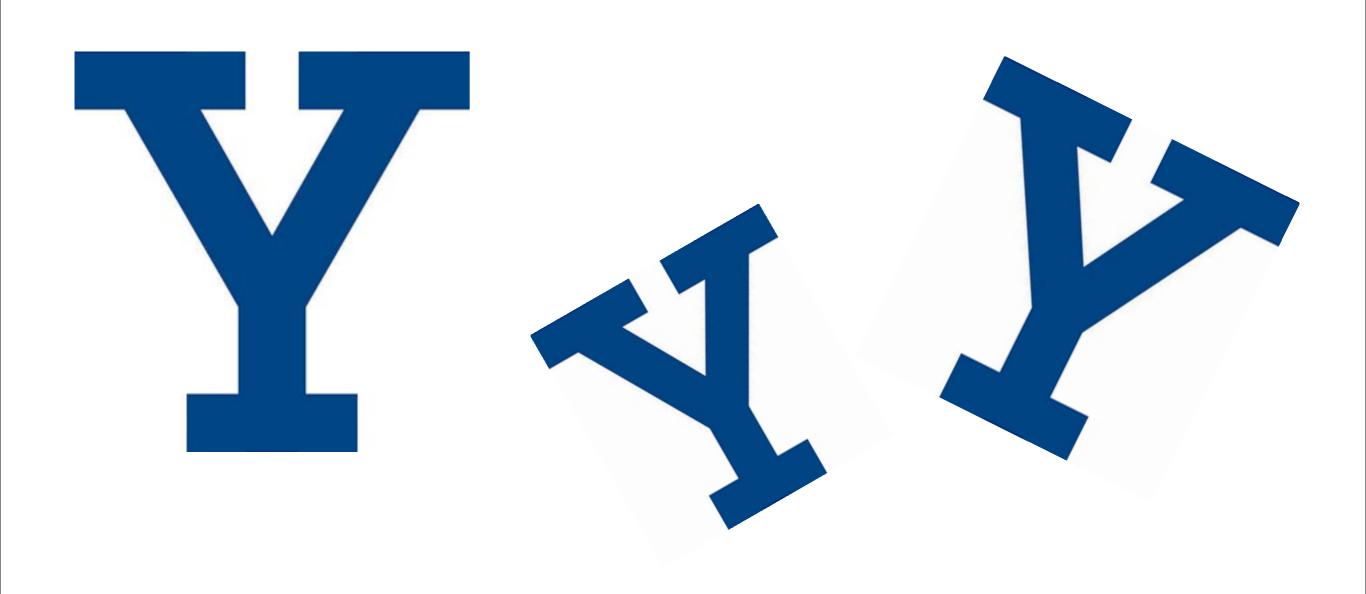
CS 355: Interactive Graphics and Image Processing





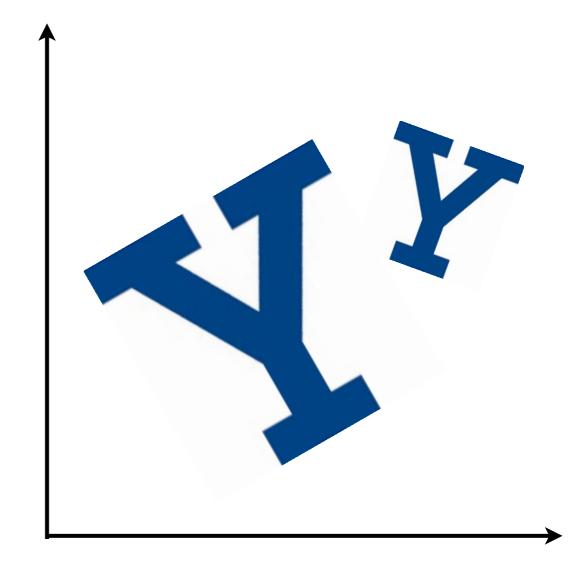






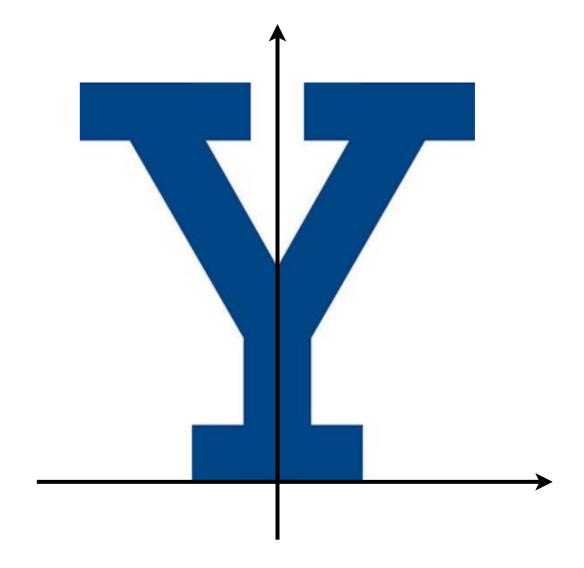
World Space

- The "world space" defines the space in which objects can live
- Choice of origin and coordinate system is arbitrary



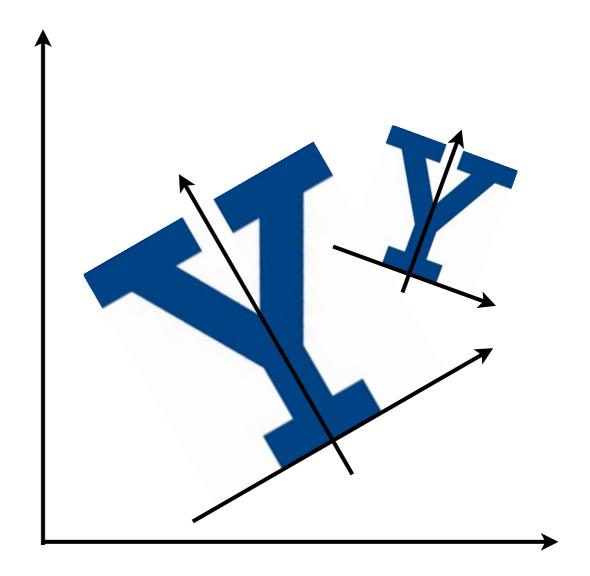
Object Space

- The coordinate system used to define an object
- Choice or origin and coordinate axes also arbitrary
- But usually chosen to make object definition the simplest



Objects in the World

- Placing an object in the world:
 - Location
 - Orientation
 - Size
- These define an object-to-world transformation



Viewing Coordinates

- We don't see the entire world, only a window into it
 - Location
 - Orientation
 - Size
- These define a world-to-view transformation

The World

Viewport

All Together

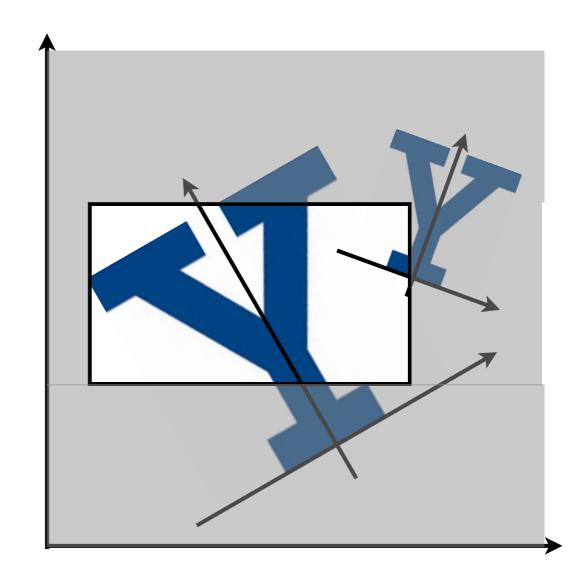
Object Coordinates

Lab #2

World Coordinates

Lab #3

Viewing Coordinates

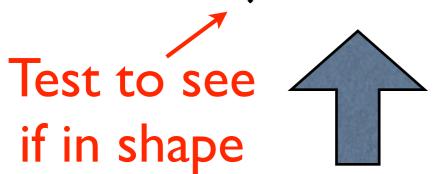


3D Modeling & Rendering

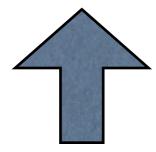
- Define a 3D model in object space
- Place that 3D model in the world (object space to world space)
- Figure out where it is relative to the camera (world space to camera space)
- Project 3D to a virtual camera (and apply perspective if desired)
- Apply a 2D viewport if desired

Going the Other Way

Object Coordinates

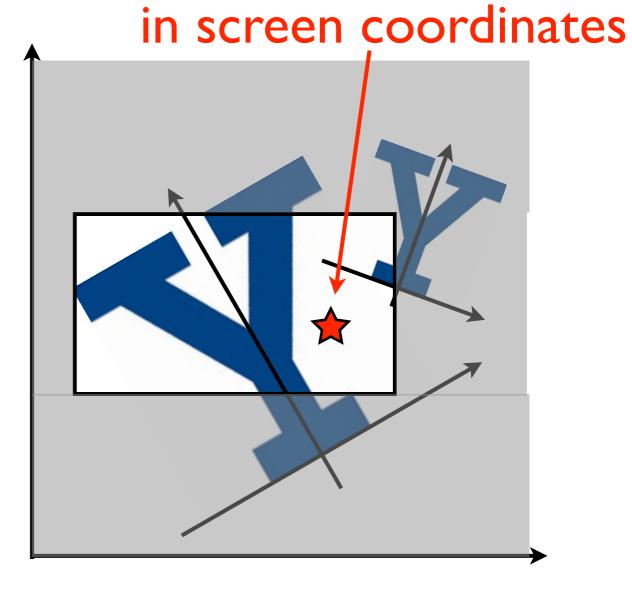


World Coordinates



Viewing Coordinates

Mouse click



Lab #2

- Clicking in a shape selects it
 - Can change its color
 - Display manipulation "handles"
- Dragging shapes
 - Clicking in a shape and dragging the mouse moves the shape
- Resizing shapes
 - Clicking a corner handle and dragging resizes the shape
- Rotating shapes
 - Clicking the rotation handle and dragging rotates the shape

Lab #2

- Parent Shape class:
 - color
 - center
 - rotation angle
- Child subclasses:
 - Shape parameters in object space
 - Exception: lines can stay endpoints in world space

Lab #2

- Java's 2DGraphics drawing supports drawing with transformations
- Supports affine transformations
 - Translation (changing position)
 - Rotation (changing orientation)
 - Scale (changing size)
 - and more we won't need for this lab...

Object to World

- An object has a position and an orientation
 - First: rotate in object space to desired world-space orientation
 - Second: move (translate) to the position in world space



Transformed Drawing

```
Graphics2D g;
// rotate by \pi / 4
g.rotate(Math.PI / 4);
// translate to (100,50)
g.translate(100,50);
g.fillRect(0,0,width,height);
```

Inverse Transformations

- The inverse of a transformation "undoes" that transformation
- If a sequence:
 - do sequence of steps backwards
 - do each step backwards

World to Object

- An object has a <u>position</u> and an <u>orientation</u>
 - First: move (translate) back from the position in world space to object space
 - Second: rotate in object space back from desired world-space orientation

Example

Forward (Drawing)

- Represent as simple rectangle centered at origin
- Rotate by $\pi / 4$
- Translate by (100,50)

Backward (Selecting)

- Translate by (-100,-50)
- Rotate by -π / 4
- Test against simple rectangle centered at origin

Coming up...

- Selection geometry
- Introduction to matrices
- Matrix transformations
 - Forward
 - Inverse