



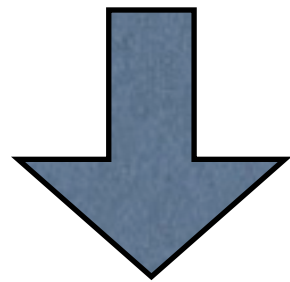
Multiple Coordinate Spaces (Revisited)

CS 355: Interactive Graphics and Image Processing

Forward (Drawing)

- Object Coordinates

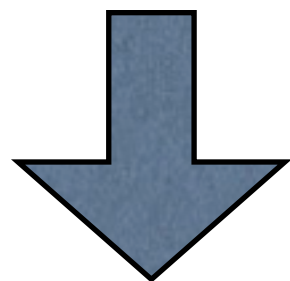
Lab #2



O_i

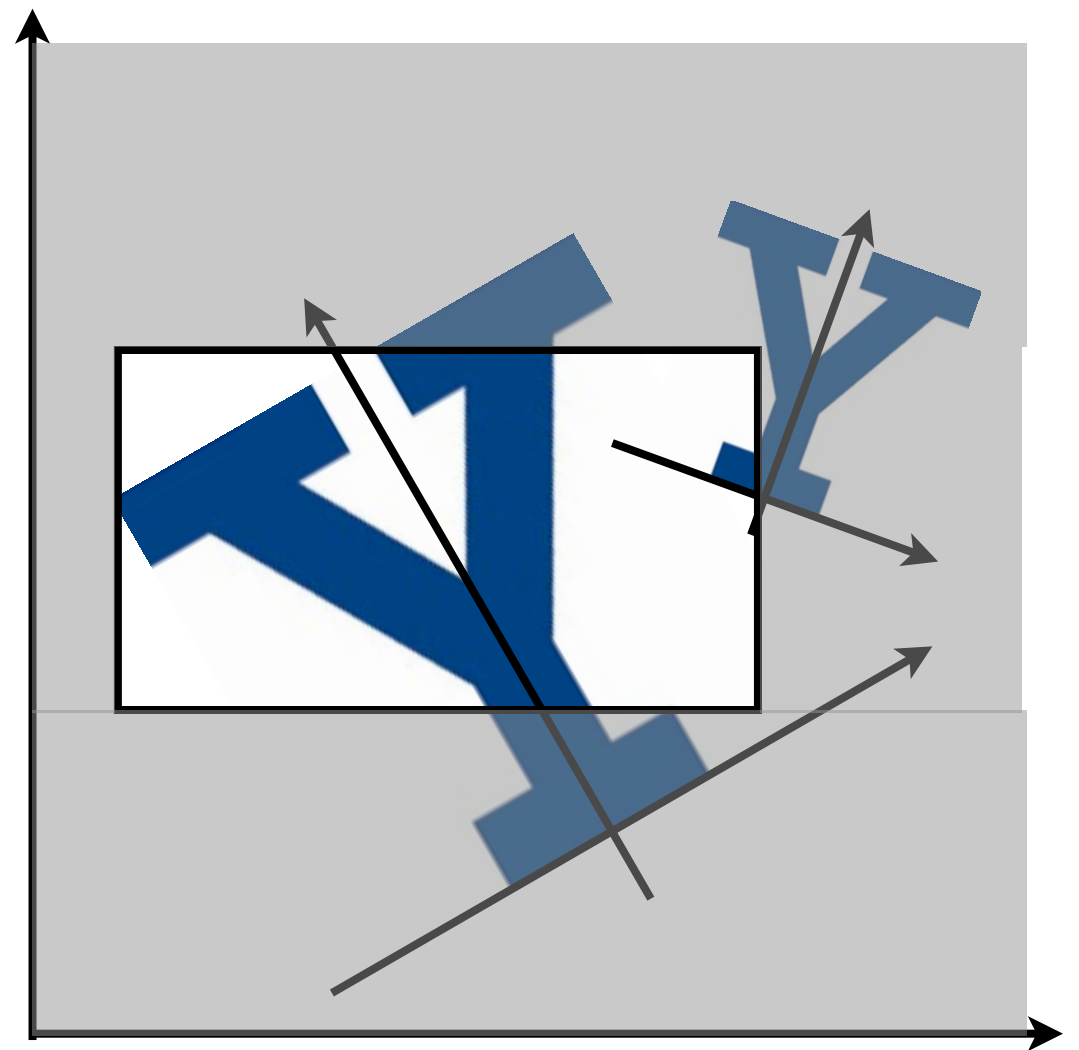
- World Coordinates

Lab #3



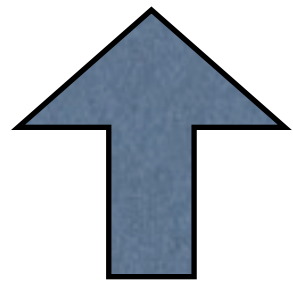
V

- Viewing Coordinates



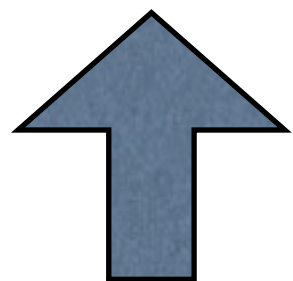
Backward (Selecting)

- Object Coordinates



$$\mathbf{O}_i^{-1}$$

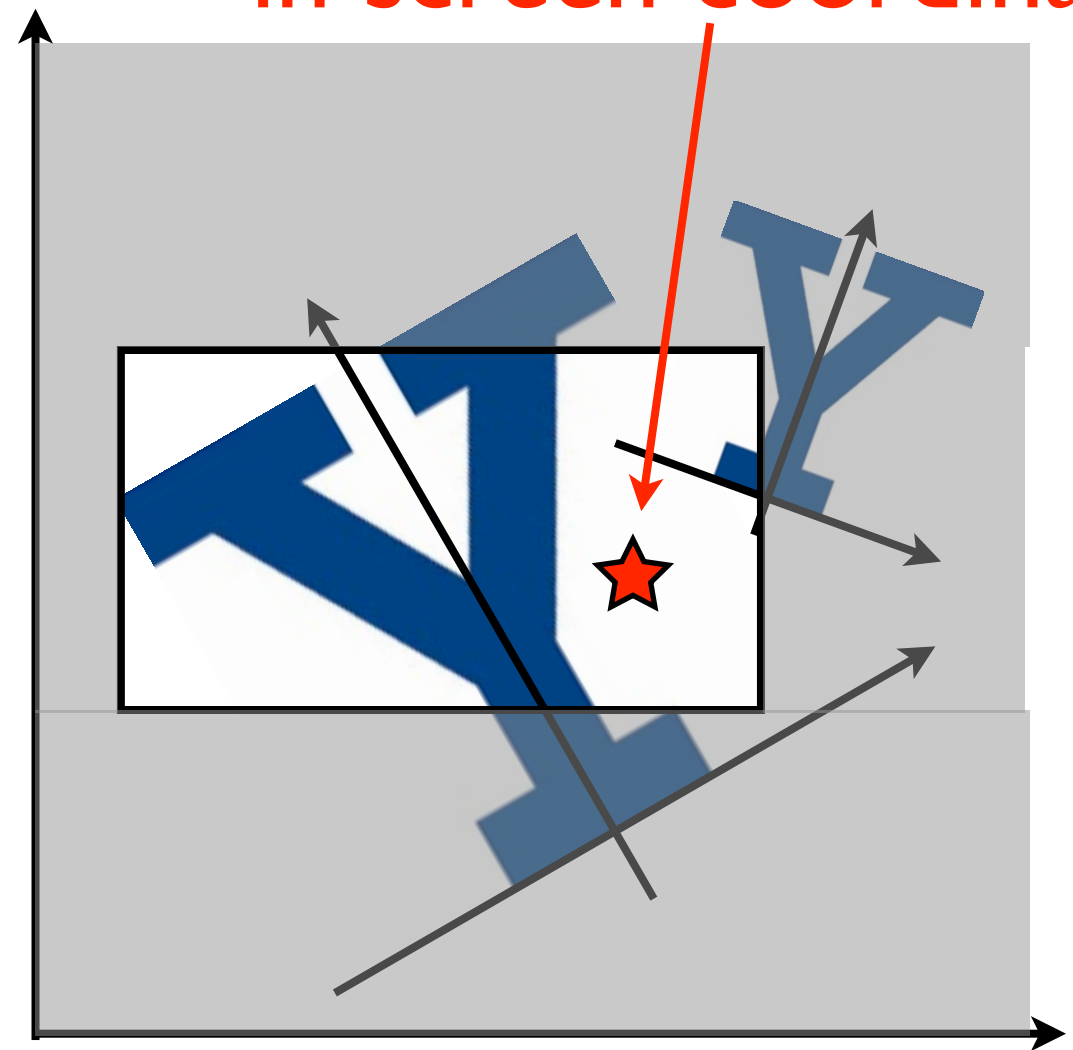
- World Coordinates



$$\mathbf{V}^{-1}$$

- Viewing Coordinates

Mouse click
in screen coordinates



Object to World

- To transform a point from object space to the world space:
- **Rotate** to orientation
- **Translate** to position

$$\mathbf{O}_i = \overset{\text{order} \leftarrow}{\mathbf{T}(\mathbf{c}_i) \mathbf{R}(\theta_i)}$$

$$\mathbf{R}(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{T}(\mathbf{c}) = \begin{bmatrix} 1 & 0 & c_x \\ 0 & 1 & c_y \\ 0 & 0 & 1 \end{bmatrix}$$

World to Object

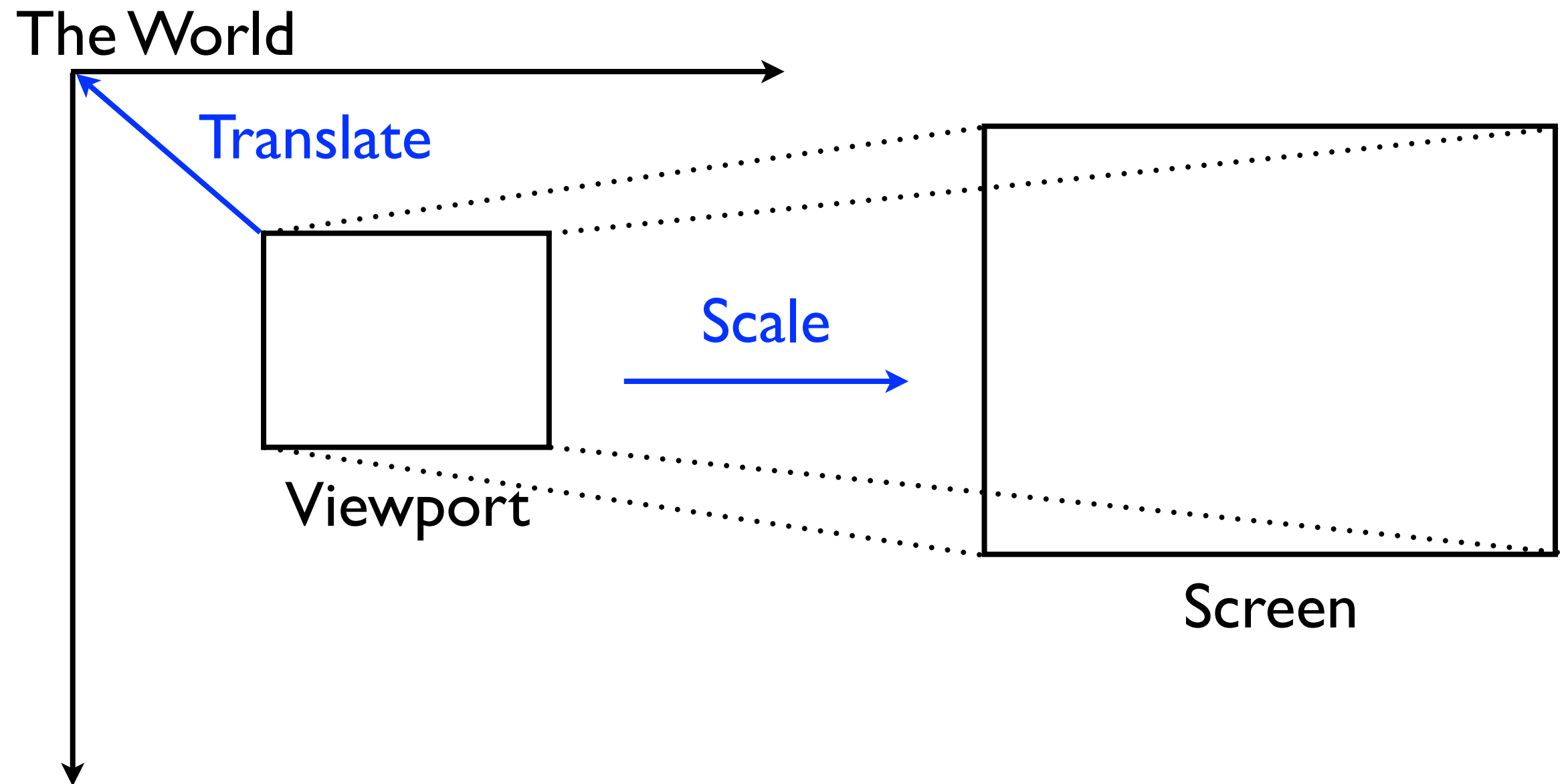
- To transform a point from world space to object space:
- Translate from position to origin
- Rotate back from orientation

$$\mathbf{O}_i^{-1} = \mathbf{R}(-\theta_i) \mathbf{T}(-\mathbf{c}_i)$$

$$\mathbf{R}(-\theta) = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{T}(-\mathbf{c}) = \begin{bmatrix} 1 & 0 & -c_x \\ 0 & 1 & -c_y \\ 0 & 0 & 1 \end{bmatrix}$$

Viewports



World to View

- To transform a point from world space to viewing space:
- **Translate** from origin of viewport to origin of the world
- **Scale** by the zoom factor

$$\mathbf{V} = \overset{\text{order} \leftarrow}{\mathbf{S}(f)} \mathbf{T}(-\mathbf{p})$$

$$\mathbf{T}(-\mathbf{p}) = \begin{bmatrix} 1 & 0 & -p_x \\ 0 & 1 & -p_y \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{S}(f) = \begin{bmatrix} f & 0 & 0 \\ 0 & f & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

View to World

- To transform a point from world space to viewing space:
- **Translate** from origin of viewport to origin of the world
- **Scale** by the zoom factor

$$\mathbf{V}^{-1} = \mathbf{T}(\mathbf{p}) \mathbf{S}(1/f)$$

$$\mathbf{T}(\mathbf{p}) = \begin{bmatrix} 1 & 0 & p_x \\ 0 & 1 & p_y \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{S}(1/f) = \begin{bmatrix} 1/f & 0 & 0 \\ 0 & 1/f & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Drawing

- Transform from object space to world space
- Transform from world space to view space

$$\mathbf{M} = \mathbf{V} \mathbf{O}_i$$

← order

$$\mathbf{p}_{\text{view}} = \mathbf{M} \mathbf{p}_{\text{object}}$$

Selecting

- Transform from view space to world space
- Transform from world space to object space

$$\mathbf{M}^{-1} = \overset{\text{order} \leftarrow}{\mathbf{O}_i^{-1}} \mathbf{V}^{-1}$$

$$\mathbf{p}_{\text{object}} = \mathbf{M}^{-1} \mathbf{p}_{\text{view}}$$

Coming up...

- 3D!