Time Series Analysis in R*

Jeric C. Briones

Department of Mathematics Ateneo de Manila University

1 Preliminaries

Before working with real dataset, we begin by doing preliminary analysis on simulated time series data. Codes used are in OTSA.R, 1LinearModels.R, and 2VolatilityModels.R.

1.1 Loading Simulated Data

We begin by loading the simulated dataset ar2.s and ma1.1.s from the library TSA. This simulated time series data will be used for the succeeding preliminary analyses.

Aside from the loaded simulated data, we also generate another time series data using random standard normal deviates. Standard normal deviates are generated using <code>rnorm()</code>, where the required input is the number of deviates to generate. When unspecified, the default mean and standard deviation are <code>mean=0</code> and <code>sd=1</code>, respectively. The deviates are converted to time series data using the function <code>ts()</code>.

```
# Time-series library
library("TSA")
library("tseries")

# simulated data
data("ar2.s")
data("ma1.1.s")
z = ts(rnorm(120))
```

By default, the parameters of ts() are start=1, end=T, and frequency=1. Here, T refers to the length of the time series data, while frequency refers to the number of observations in a given time step. Commonly used frequencies include frequency=12 to represent monthly data, and frequency=4 to represent quarterly data. These frequencies can easily by changed for a given time series object, as shown below.

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Here, z1 has the same values as z. However, instead of having 120 unit time steps like the latter, the former has $\frac{120}{10} = 12$ unit time steps, where each unit time steps has 10 sub-steps. Similarly, z2 also has the same values as z but with monthly frequency (frequency=12). To indicate that the time series starts December 2012 and ends March 2023, the parameters start=c(2012,12) and end=c(2023,3) are used. It can be noticed that when z, z1, and z2 are plotted, the figures are similar except for the x-axis scale.

1.2 Exploratory Analysis

After loading the dataset, we begin performing exploratory tests to the data: test for autocorrelation and unit-root test. Test for autocorrelation is performed using Box.test(). To specify the portmanteau test used, we use the parameter type. Here, we consider the Ljung-Box Test, specified using type="Ljung". Moreover, by default, this function tests for lag-1 autocorrelation. To test for lag-l autocorrelation, the parameter lag=1 is used. Recall that should there be no autocorrelation, modeling using linear time series model would not be meaningful¹.

```
# check for autocorrelation
# default is lag = 1
Box.test(ar2.s, type="Ljung")
Box.test(ma1.1.s, type="Ljung")
Box.test(z, type="Ljung", lag=3) # test for lag-3 correlation
```

To test for stationarity, we perform unit-root test using augmented Dickey-Fuller Test² (adf.test()). Here, the null hypothesis is the presence of unit root, which means the time series data is not stationary. Thus, if the null hypothesis is rejected, the time series data is considered as stationary. Recall that should the data be non-stationary, preprocessing steps (such as differencing) needs to be performed.

```
1 # test for stationarity (AR)
2 adf.test(ar2.s)
3 adf.test(ma1.1.s)
4 adf.test(z)
```

1.3 Model Building

After checking for autocorrelation and stationarity, we then proceed with time series modelling. We start with lag order selection. This is done by checking the ACF (using acf()) and PACF (using acf()) and adding the parameter type="partial"). Alternatively, pacf() can also be used to check PACF.

```
# compute for ACF
acf(ar2.s)
acf(ma1.1.s)
acf(z)

# compute for PACF
acf(ar2.s, type="partial")
acf(ma1.1.s, type="partial")
acf(z, type="partial")
```

 $^{^1\}mathrm{For}$ illustrative purposes, we continue modelling z despite having no autocorrelation.

²Recall that MA processes are weakly stationary. So, we basically test for stationarity for AR processes. On the other hand, recall that the ADF test assumes an AR model.

Here, notice that based on their respective plots, there is no autocorrelation between the data and its lag-1 value, consistent with earlier results. This is because none of the ACF and PACF values of z are statistically significant. That is, since none of these values exceed the dotted lines, then none of them are statistically different from zero. On the other hand, for ar2.s, ACF values decay while PACF values cut off at lag h = 2 (with another significant ACF value at lag h = 9). For ma1.1.s, ACF values seem to cut off at lag h = 1 (but with other significant ACF value at lags h = 5, 14).

Based on these lags, we then estimate the model coefficients using arima(). The lag orders are specified using the parameter order=c(p,0,q), where p refers to the AR lag order, while q the MA lag order³. Here, we test AR(2) and AR(9) for ar2.s, and MA(1), MA(5), and MA(14) for ma1.1.s. We also test AR(1) for ar2.s for illustrative purposes.

```
1 # fit ARMA models
2 # order = AR lag, integration, MA lag
3 arima(ar2.s, order=c(1,0,0)) # test AR(1)
4 arima(ar2.s, order=c(2,0,0)) # test AR(2)
5 arima(ar2.s, order=c(9,0,0)) # test AR(9)
6
7 arima(ma1.1.s, order=c(0,0,1)) # test MA(1)
8 arima(ma1.1.s, order=c(0,0,5)) # test MA(5)
9 arima(ma1.1.s, order=c(0,0,14)) # test MA(14)
```

Recall that we can use AIC to determine the best model, with the *best* model having the lowest AIC. Based on the results, the time series data ar2.s is an AR(2) process (AIC of 331.95 vs 451.16 for AR(1) and 339.58 for AR(9)), while ma1.1.s is an MA(1) process (AIC of 363.66 vs 372.58 for MA(5) and 339.58 MA(14)).

2 Fitting Linear Time Series Models

We continue by loading the datasets SP and usd.hkd from the library tseries, and the dataset strikes from the library itsmr. The first dataset is the quarterly S&P composite index, from Quarter 1 of 1936 to Quarter 4 of 1977, the second is the daily USD/HKD exchange rate from January 1, 2005 to March 7, 2006 (with the FOREX rates seen in usd.hkd\$hkrate), while the third is the annual number of USA union strikes from 1951-1980.

2.1 Data: S&P Composite Index

As earlier discussed, after loading the time series data, we begin with the preliminary tests, specifically the test for stationarity using adf.test().

```
# Quarterly S&P Composite Index, 1936Q1 - 1977Q4.
data("SP")

# test for stationarity (AR)
adf.test(SP)
```

Here, we note that the null hypothesis of having a unit root (that is, the data is non-stationary) was not rejected. Hence, preprocessing steps are needed to transform the data into a stationary process. Possible preprocessing steps include log transformation,

³The middle parameter, 0, refers to the order of integration d, where d=0 for ARMA processes.

differencing, and log differencing. In this example, we focus on log differencing, since the data values are quite large. Moreover, we note that log transformation is generally used to handle large-valued data, while differencing is mostly used to remove non-stationarity.

```
# perform pre-processing
SP.ln = log(SP) # take log transformation
SP.ln.d = diff(SP.ln) # take first difference of log
plot(SP.ln.d)

# perform stationarity test for differenced data
adf.test(SP.ln.d)

# check autocorrelation
Box.test(SP.ln.d, type="Ljung")
```

Performing the unit-root test on the transformed data, we note that the resulting time series data is now stationary. Given it is stationary, we then proceed with the test for autocorrelation. Using the Ljung-Box Test, we note that the data has no autocorrelation since the test failed to reject the null hypothesis. As such, further modelling for this time series data will not be pursued.

2.2 Data: USD/HKD FOREX Rate

We begin by converting the current data into a time series object using the function ts(). Then, like earlier, we start with the preliminary tests adf.test() and Box.test().

```
# Daily USD/HKD exchange rate from January 1, 2005 to March 7, 2006

data("usd.hkd")

forex = ts(usd.hkd$hkrate)

# perform initial tests
adf.test(forex)
Box.test(forex, type="Ljung")
```

Here, both tests rejected their respective null hypotheses. Since the data is stationary and serially correlated, we then proceed with (lag) order determination.

```
# check ACF, PACF
acf(forex)
acf(forex, type="partial")
```

Based on the ACF and PACF plots, notice that the ACF plot seems to cut off at lag h = 1, while the PACF plot seems to cut off at lag h = 2. Thus, we test for AR(2), MA(1), and ARMA(2, 1).

```
1 # check models, lower AIC is better
2 arima(forex, order=c(0,0,1)) # test MA(1)
3 arima(forex, order=c(2,0,0)) # test AR(2)
4 arima(forex, order=c(2,0,1)) # test ARMA(2,1)
```

Checking the AIC, the *best* model is ARMA(2,1) with an AIC of -1890.64 (vs -1888.41 for MA(1) and -1889.49 for AR(2)). Thus, usd.hkd\$hkrate follows an ARMA(2,1) process.

2.2.1 Parameter Estimates

Given that the data follows an ARMA(2,1), then its functional form is given by

$$X_t = \phi_0 + \phi_1 X_{t-1} + \phi_2 X_{t-2} + W_t + \theta_1 W_{t-1},$$

where $\{X_t\}$ is usd.hkd\$hkrate.

Parameter estimates are included as outputs of arima(). To be specific, estimation is done using the maximum likelihood approach, with the estimates for the coefficients stored in arma21\$coef. Note that the intercept here is not $\hat{\phi}_0$. Rather it is $\hat{\mu}$, the estimate for μ . Using the fact that $\mu = \frac{\phi_0}{1 - \phi_1 - \phi_2}$, we get $\phi_0 = \mu(1 - \phi_1 - \phi_2)$. As such, the functional form of the model is

$$X_t = -0.0004 + 0.2899X_{t-1} - 0.0588X_{t-2} + W_t - 0.4763W_{t-1}$$
.

While the results yielded $\hat{\mu} = -0.0005$, it can be noticed that the confidence interval⁴ for $\hat{\mu}$ is (-0.0014, 0.0004). Since the interval contains 0, it can be argued that $\hat{\mu}$ is not significantly different from 0.

2.2.2 Forecasting

Forecasting for ARMA(p,q) is done using <code>predict()</code>, where the first parameter is the <code>arima()</code> object (in this case, <code>arma21)</code>, while the second parameter is the number of steps ahead <code>n.ahead=m</code>. The forecast values are stored in <code>arma21.p\$pred</code>, while the associated prediction errors are in <code>arma21.p\$se</code>. Values are arranged $\left\{X_{n+1}^{(n)}, X_{n+2}^{(n)}, \ldots, X_{n+m}^{(n)}\right\}$.

```
library(forecast)
# from previous result, use ARMA(2,1)
arma21 = arima(forex, order=c(2,0,1))
arma21$coef
# forecast 5-step ahead
arma21.p = predict(arma21, n.ahead=5)

# alternative function for estimation and forecasting
# forecast() only works when Arima() is used
arma21.2 = Arima(forex, order=c(2,0,1))
arma21.2$coef
arma21.p2 = forecast(arma21.2, h=5)
```

Alternatively, the function Arima() from the library forecast can be used for estimation and forecasting. While both function similarly, the results of Arima() is compatible with the function forecast(). Compared to predict() which only provides the point estimate and prediction error, forecast() also includes prediction intervals as its output, as well as plot compatibility. For this function, the parameter n.ahead=m is replaced with h=m. Moreover, forecast values are stored in arma21.p2\$mean. Additionally, compared to arima() which only outputs the value of the information criterion AIC, Arima() provides the values for the information criteria AIC, BIC, and AICc as well.

2.2.3 Analyzing Residuals

After fitting a time series model, the last step is to check the residuals. Recall that one of the assumptions of time series models discussed is that the residuals are uncorrelated. To check this assumption, we can use the functions tsdiag() and Box.test(), among other

⁴Here, confidence interval is approximated using $\hat{\beta} \pm e$, where e is the associated standard error for the estimate $\hat{\beta}$. For a 95% confidence interval, use $\hat{\beta} \pm 1.96e$.

tests. The tsdiag() provides residual-related plots, including standardized residual plots, ACF plots, and the Ljung-Box test p-value plots⁵. On the other hand, the Ljung-Box test can also be performed again, but using the residuals (stored in arma21\$residuals, or retrieved using the function residuals()) as the input this time.

Depending on the data domain, normality of residuals may also be required. For this, qqnorm() and jarque.bera.test() may be used. Normality of residuals can be checked visually using qqnorm. Moreover, the Jarque-Bera test can be used to check if the residuals are normal by checking for its kurtosis and skewness.

```
# residual diagnostics
# Ljung-Box have issues with degrees of freedom
# jarque.bera.test() is used to check for skewness/kurtosis
tsdiag(arma21)
jarque.bera.test(residuals(arma21))
```

Based on the results, it was observed that while the residuals were uncorrelated, they are not normally distributed. Since the only lag that exceeded the bands in the ACF plot is lag 0, then the residuals are uncorrelated. Moreover, since the null hypothesis that the data are from normal distribution was rejected for the Jarque-Bera test, then the residuals are white noise (but not Gaussian white noise).

2.3 Data: Strikes

Similar to previous datasets, we perform preprocessing steps and preliminary tests.

```
library(itsmr)
# annual number of USA union strikes, 1951-1980
# perform initial tests and transformations
strikes.l = log(ts(strikes))
strikes.l.d = diff(strikes.l)
strikes.l.d2 = diff(strikes.l.d)
Box.test(strikes.l.d2, type="Ljung-Box")
adf.test(strikes.l.d2)
# determine order using ACF/PACF
acf(strikes.l.d2)
pacf(strikes.l.d2)
```

Note that the data strikes had to be differenced twice to make it stationary. Based on the ACF and PACF plots, candidate models include AR(2), MA(1), and ARMA(1, 1). The model with the best AIC is the AR(2) model.

Note that the middle parameter in $\operatorname{order=c(p,d,q)}$ refers to the order of integration d. As such, depending on d and the input data, there are several ways to use $\operatorname{Arima()}$. If d=0 (that is, using $\operatorname{order=c(2,0,0)}$), then the input data must be the **differenced** data (which is $\operatorname{strikes.1.d2}$). On the other hand, if d>0 (that is, using $\operatorname{order=c(2,2,0)}$), then the input data must be the original data (which is $\operatorname{strikes.1}$). It should also be noted that in the absence of differencing (that is, if d=0), $\operatorname{Arima()}$ assumes non-zero mean and provides an estimate for it (as seen in mean^6). On the other hand, if $\operatorname{ARIMA}(p,d,q)$ is fitted, with d>0, then $\operatorname{Arima()}$ assumes zero mean, and mean

 $^{^5}$ Some textbooks argue that the Ljung-Box test results in the function are problematic since there are issues with the degrees of freedom used in the test.

⁶For arima(), this is the intercept.

is omitted in the estimation. As such, there will be differences in the coefficient estimates depending on the choice of $\operatorname{order=c(p,d,q)}$. If estimated mean $\hat{\mu}$ is statistically zero (based on the resulting prediction interval), then the estimated coefficients should not differ that much. If we wish to exclude the mean from estimation, the parameter $\operatorname{include.mean=F}$ should be used.

```
# estimate coefficients
# methods: ARMA, ARIMA, Yule-Walker
# note that ARMA estimates a mean, while ARIMA assumes zero-mean
# ar2 = Arima(strikes.1.d2, order=c(2,0,0))
# ari2 = Arima(strikes.1, order=c(2,2,0))
# ar2.nomean = Arima(strikes.1.d2, order=c(2,0,0), include.mean=F)
# ar2.yw = ar.yw(strikes.1.d2, order=2)
```

Based from the results, it can be seen that estimates for ϕ_1 and ϕ_2 are close for the three approaches considered (-1.1397 vs -1.1401 vs -1.1401 for ϕ_1 , -0.7796 vs -0.7800 vs -0.7800 for ϕ_2). Here, the first estimate used d=0, the second d=2, while the third d=0 but with include.mean=F. On the other hand, if we are interested in estimation using Yule-Walker equations, the function ar.yw(), with AR(2) specified using the parameter order=2. Note that estimates using Yule-Walker equations may be different those obtained using MLE approach.

In functional form, if X_t is the number of strikes, $Y_t = \nabla^2 X_t$ the twice-differenced data, then using the results of ari2\$coef,

```
Y_t = -1.1401Y_{t-1} - 0.7800Y_{t-2} + W_t
Y_t + 1.1401Y_{t-1} + 0.7800Y_{t-2} = W_t
(1 + 1.1401B + 0.7800B^2)Y_t = W_t
(1 + 1.1401B + 0.7800B^2)(1 - B)^2X_t = W_t.
```

As mentioned earlier, using <code>forecast()</code> allows us to plot the point estimate and prediction intervals for the forecast. It should be noted that the resulting forecast and its plot follows the input data. For example, the forecast for <code>ar2</code> (given by <code>ar2.p</code>) is for the twice differenced data. If the original log-transformed forecast is desired, the forecast must be <code>undifferenced</code>. On the other hand, since the input for <code>ari2</code> is the original log-transformed data, the results for its forecast would be for the log-transformed data.

```
# forecast 5-step ahead, differenced data
ar2.p = forecast(ar2, h=5)
plot(ar2.p)

# forecast 5-step ahead, original data
ar2.p2 = forecast(ari2, h=5)
plot(ar2.p2)

# residual diagnostics
tsdiag(ar2)
jarque.bera.test(residuals(ar2))
```

For the forecast plot, note that the original data is in black, the forecast values are in blue, 80% prediction intervals in grey shade, and 95% prediction intervals in bluish grey shade. Moreover, residual diagnostics are again performed. Here, the residuals are uncorrelated (since only ρ_0 is significant) and normally distributed (since p-value was large).

3 Fitting Seasonal Models

We continue by loading the built-in dataset AirPassengers. This dataset is the monthly airline passenger numbers from 1949-1960. That is, the dataset has a frequency of 12.

3.1 Exploratory Analysis

We begin by performing preprocessing steps and preliminary tests.

```
# Monthly Airline Passenger Numbers 1949-1960
air = AirPassengers

# perform initial transformations
air.l = log(air)
air.l.d = diff(air.l)
plot(cbind(air, air.l,air.l.d))

# perform initial tests
Box.test(air.l.d,type="Ljung")
adf.test(air.l.d)
```

Based on the plots, it is clear that the data has trend and seasonality. However, results from adf.test() suggest that the data is already stationary. This result highlights how the ADF test is not as effective for detecting non-stationarity caused by seasonality.

Seasonal differencing can be done using diff() by setting the second parameter as the seasonal integration order D. For example, if we are interested with $\nabla_{12}X_t$ for seasonal differencing, then we code this as diff(Xt, 12).

```
# do seasonal differencing
# use default frequency as s
air.l.d.12 = diff(air.l.d,12)
plot(cbind(air.l,air.l.d, air.l.d.12))

# determine order
# note that lag 1 = step 12
acf(air.l.d)
acf(air.l.d, lag=100)
pacf(air.l.d, lag=100)
```

Using the parameter lag=100 in acf() and pacf() allows us to see more lags, which is useful when determining lag order for seasonal data. Based on the ACF and PACF plots, $sAR(1)_{12}$ is a candidate model. This is because the PACF plot cuts off after lag Ps=12, and the ACF plot tails off at lags 12k. However, notice that there are non-zero values for lags that are not of the form 12k. As such, mixed seasonal ARIMA model should be considered. For simplicity, the non-seasonal components for the model considered would be AR(1), MA(1), and ARMA(1,1) only.

3.2 Model Building

In estimating the coefficients, instead of using air.1.d as input, we use air.1 and set d = 1. That is, the parameters order=c(1,1,1), order=c(0,1,1), and order=c(1,1,0) are used for the non-seasonal component of Arima(). On the other hand, the seasonal component is indicated by the parameter seasonal=list(order=c(P,D,Q), period=s). If period=s is dropped, the frequency of the ts() object is used by default. In this case,

the seasonal component parameter becomes seasonal=order(P,D,Q). For this dataset, $sAR(1)_{12}$ is coded as seasonal=list(order=c(1,1,0), period=12). Based on the resulting AIC, $sARIMA(0,1,1) \times (1,1,0)_{12}$ is the *best* model (-475.4664 vs -477.4053 vs -474.8188).

As previously mentioned, the mixed seasonal model can be implemented in different ways. To provide different plots for the forecast, three different variations for coding $sARIMA(0,1,1) \times (1,1,0)_{12}$ are considered:

- sarima.model uses air.1 as input. As such d = 1 and D = 1. Since the input is the log-transformed data, the forecast sfor is log forecasts.
- sarima.model.d uses air.1.d as input. As such d=0 and D=1. Since the input is the differenced log-transformed data, the forecast sfor2 is differenced log forecasts.
- sarima.model.d.12 uses air.l.d.12 as input. As such d=0 and D=0. Since the input is the season-differenced and first-differenced log-transformed data, the forecast sfor3 also underwent the same transformation. To make the estimates comparable, include.mean=F was also used.

```
# fit using Arima, the forecast
2 # if period is omitted, default is frequency
sarima.model = Arima(air.1,order=c(0,1,1),seasonal=list(order=c(1,1,0),
     period=12))
4 sfor = forecast(sarima.model, h=12)
5 plot(sfor)
6 sfor$mean
8 # input is differenced data
9 sarima.model.d = Arima(air.l.d, order=c(0,0,1), season=c(1,1,0))
sfor2 = forecast(sarima.model.d, h=12)
plot(sfor2)
13 # input is seasonal differenced data
14 sarima.model.d.12 = Arima(air.l.d.12, order=c(0,0,1), season=c(1,0,0),
     include.mean=F)
sfor3 = forecast(sarima.model.d.12, h=12)
plot(sfor3)
```

In functional form, if X_t is the number of airline passengers, and using the results of sarima.model\$coef, we get

$$(1 + 0.4743B)(1 - B^{12})(1 - B)X_t = (1 - 0.4423B)W_t.$$

4 Fitting Volatility Models

We continue by revisiting the dataset usd.hkd from the library tseries.

4.1 Data: USD/HKD FOREX Rate

Recall that the data usd.hkd\$hkrate follows an ARMA(2,1) process, and that the best linear time series model for this dataset is arma21. We then begin by checking for auto-correlation for the residuals and squared residuals.

```
# get the residuals after fitting ARMA(2,1)
res.arma21 = residuals(arma21)

# check the residuals
acf(res.arma21)
pacf(res.arma21)
Box.test(res.arma21, type="Ljung")

# check the squared residuals
acf(res.arma21^2)
pacf(res.arma21^2)
Box.test(res.arma21^2, type="Ljung")
```

The resulting correlagrams clearly indicate that the residuals are uncorrelated, as there are no lags that exceed the bands. However, the square residuals are serially correlated since there are significant lags. Since lag h = 1 is significant, we continue with ARCH(1).

4.1.1 Two-Pass Estimation Method

We start with the two-pass estimation method where we model the mean and volatility equations separately. Note that we do not use the parameter include.mean=F since we want $\alpha_0 > 0$.

```
# two-pass estimation
vol.ar1 = Arima(res.arma21^2, order=c(1,0,0))
vol.ar1$coef
```

Using this approach, we obtain

$$\begin{cases} Y_t &= \sigma_t \epsilon_t \\ \sigma_t^2 &= 0.0005 + 0.2517 Y_{t-1}^2 \end{cases},$$

where $\hat{\alpha}_0 := \hat{\phi}_0 = 0.0005 = \hat{\mu}(1 - \hat{\phi}_1)$. A quick check with the obtained standard errors shows that the approximate for the confidence intervals for $\hat{\alpha}_0$ and $\hat{\alpha}_1$ do not contain zero.

4.1.2 Initial Joint Model Fitting

We estimate the model coefficients using garchFit(). The volatility model is specified using \sim garch(m,s), where m refers to the order for Y_t^2 while s the order for σ_t^2 . In the absence of a mean equation, ARMA(0,0) is assumed. That is, $X_t = \mu + Y_t$. If the mean equation ARMA(p, q) is known, the parameter becomes \sim arma(p, q)+garch(m,s).

```
1 # fit ARMA(p,q)-ARCH(1) model
2 vol = garchFit(~garch(1,0),data=forex) #arma(0,0)
3 arma21.vol = garchFit(~arma(2,1)+garch(1,0),data=forex) #arma(2,1)
4 summary(vol)
5 summary(arma21.vol)
```

The model vol gives

$$\begin{cases} X_t &= -0.0012 + Y_t \\ Y_t &= \sigma_t \epsilon_t \\ \sigma_t^2 &= 0.0005 + 0.4989 Y_{t-1}^2 \end{cases},$$

while the model arma21.vol yields

$$\begin{cases} X_t &= -0.0004 + 0.3120X_{t-1} - 0.0952X_{t-2} + Y_t - 0.4908Y_{t-1} \\ Y_t &= \sigma_t \epsilon_t \\ \sigma_t^2 &= 0.0004 + 0.4491Y_{t-1}^2 \end{cases}$$

where $\hat{\phi}_0 = -0.0004 = \hat{\mu}(1 - \hat{\phi}_1 - \hat{\phi}_2)$. Notice that while the estimated coefficients for the mean equation obtained using the two-pass and the joint estimation methods are different, it can be argued that they are statistically similar based on their resulting standard errors and confidence intervals⁷.

Note that for the first model, $\hat{\mu}$ was not significant, while $\hat{\alpha}_0$ (labelled omega in the output) and $\hat{\alpha}_1$ are. On the other hand, for the second model, $\hat{\mu}$, $\hat{\phi}_1$, and $\hat{\phi}_2$ were not significant, while $\hat{\theta}_1$, $\hat{\alpha}_0$, and $\hat{\alpha}_1$ are. However, it should be noted that $\hat{\phi}_1$ was significant at the level $\alpha = 0.1$. As such, a possible reduced model to check is ARMA(1,1) + ARCH(1).

4.1.3 Refining the Model

Using the reduced model, we fit the ARMA(1,1) + ARCH(1) into the data.

```
# refine model
2 arma11.vol = garchFit(~arma(1,1)+garch(1,0),data=forex)
3 summary(arma11.vol)
4 arma11.vol@fit$coef
5 arma11.vol@fit$se.coef
```

The point estimates of the coefficients and their corresponding standard errors are stored in armall.vol@fit\$coef and armall.vol@fit\$se.coef, respectively. In functional form, the ARMA(1,1) + ARCH(1) model is given by

$$\begin{cases} X_t &= -0.0002 + 0.3429X_{t-1} + Y_t - 0.5875Y_{t-1} \\ Y_t &= \sigma_t \epsilon_t \\ \sigma_t^2 &= 0.0005 + 0.4331Y_{t-1}^2 \end{cases},$$

with all the estimated coefficients except for $\hat{\mu}$ significant. Moreover, different information criteria for each model⁸ can be seen below:

⁷Using $\hat{\phi}_1 \pm e$, the estimated C.I. for $\hat{\phi}_1$ in arma21 is (0.0900, 0.4898), while in arma21.vol is (0.1312, 0.4928). Since the intervals overlap, then the two estimates for $\hat{\phi}_1$ are arguably similar.

⁸These can be obtained using model@fit\$ics. For example, the information criteria for arma11.vol are stored in arma11@fit\$ics

Model	AIC	BIC	SIC
vol	-4.5239	-4.4956	-4.5239
arma21.vol	-4.5360	-4.4794	-4.5364
arma11.vol	-4.5349	-4.4877	-4.5351

Depending on the choice of information criterion, the *best* model would vary. Interestingly, while arma21.vol had a smaller AIC, arma11.vol had a smaller BIC. For simplicity, we use arma11.vol sa the best model.

4.1.4 Checking Standardized Residuals

After fitting the model, the last step is to check the model residuals. Recall that the resulting standardized residuals must be an iid sequence.

```
# check standardized residuals
fit.vol = volatility(arma11.vol)
fit.vol.sr = residuals(arma11.vol) / volatility(arma11.vol)

plot(fit.vol, type="l")
plot(fit.vol.sr, type="l")

# check standardized residuals
acf(fit.vol.sr)
pacf(fit.vol.sr)
Box.test(fit.vol.sr, type="Ljung", lag=7)

# check standardized squared residuals
acf(fit.vol.sr^2)
pacf(fit.vol.sr^2)
pacf(fit.vol.sr^2)
Box.test(fit.vol.sr^2, type="Ljung")
```

From the correlogram results, except for lag h=7, there seems to be no significant lags for the standardized residual fit.vol.sr. Doing the Ljung-Box test for lag h=7, the null hypothesis that there are no serial correlation is not rejected, with p-value 0.1426. The same conclusion can be reached for the standardized squared residuals.

On the other hand, using the information from summary(garchFit()) regarding the different tests for the standardized residuals, it seems that these residuals are not normal, as supported by the results of the Jarque-Bera Test and Shapiro-Wilk Test⁹. This is because the p-value for these two tests are relatively zero regardless of the model used.

4.1.5 Forecasting

Forecasting for ARMA(p,q)+GARCH(m,s) is done using predict(), where the first parameter is the garchFit() object (in this case, arma11.vol), while the second parameter is the number of steps ahead n.ahead=m. An optional parameter, plot=T, can be included to plot the forecasts. The forecast values for $\{X_t\}$ are stored in forex.p\$meanForecast, while the associated prediction errors are in forex.p\$meanError. On the other hand, forecast values for $\{\sigma_t\}$ are stored in forex.p\$standardDeviation.

```
# forecast values
forex.p = predict(arma11.vol, n.ahead=5, plot=T)
forex.p
```

⁹Recall that the first test checks for normality using skewness and kurtosis, while the second uses order statistics. In both cases, the null hypothesis is that the residuals are normal.