

Input layer: have a 4×4 matrix of pixel values, X_{ij}

$$X = \begin{bmatrix} X_{11} & X_{12} & X_{13} & X_{14} \\ X_{21} & \dots & \dots & \vdots \\ X_{31} & \dots & \dots & \vdots \\ X_{41} & \dots & \dots & X_{44} \end{bmatrix}$$

Apply filters
 2×2 , stride of 1,
 w, h

$$W = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{bmatrix}$$

Conv. layer:
a 3×3 matrix of
input layer convolved
w/ filter, V_{ij}

$$V = \begin{bmatrix} V_{11} & V_{12} & V_{13} \\ V_{21} & V_{22} & V_{23} \\ V_{31} & V_{32} & V_{33} \end{bmatrix}$$

Max-pooled layer:
applied 2×2 max-pooling
to 3×3 conv. layer (stride 1)

$$M = \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix}$$

Output layer:
a 2×1 vector in
the case of binary
response.

Convolutional error:

- Big change here relative to typical backprop: we look at each value in the original conv layer and use an indicator f_{ctr} to identify if that max value is present in that "window", moving L-to-R across and shifting down to start of next row. This gives a square matrix, call it (w_{pool}) , of dim. cardinality (max-pool matrix).

EX: Say orig conv. matrix V is

$$V = \begin{bmatrix} 3 & 2 & 5 \\ 4 & 1 & 7 \\ 3 & 5 & 0 \end{bmatrix}$$

max-pooled matrix M

$$M = \begin{bmatrix} 4 & 7 \\ 5 & 7 \end{bmatrix}$$

reverse max-pool for each

Submatrix ("window")

$$\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

- For $\sigma'(z^{conv})$, z^{conv} will be a vector, where z^{conv}_i is one of the max-pooled values in the max-pool matrix M . In other words, turn M into a column vector and apply σ' to each element of z^{conv} to get $\sigma'(z^{conv})$.

FINALLY:

$$S^{conv} = \left[(w^{pool})^T (S^{pool}) \right] \odot \left[\sigma'(z^{conv}) \right]$$

4×4 4×4 4×1 4×1

Max-Pool Error:

- Same as for a FF-Net, but we recharacterize the weights connecting each m_{ij} and the output nodes. Thus:
- # rows in $W^L = 4 =$ # elements in M .
- # cols in $W^L = 2 =$ # nodes in output layer.

Output error:

$$S^L = \left[\nabla_{a^L} C \right] \odot \left[\sigma'(z^L) \right]$$

2×1 2×1 2×1

FINALLY:

$$S^{pool} = \left[(W^L)^T (S^L) \right] \odot \left[\sigma'(z^{pool}) \right]$$

4×1 4×2 2×1 4×1

NOTE: if we turn the 2×2 filter into a 4×1 vector we see that $[\dim(\text{filter}) = 4 \times 1] == [\dim(S^{conv}) = 4 \times 1]$. Dimensions align!

