MAE 5930 Optimization Homework 2

Purpose: The problems assigned help develop your ability to

- implement numerical algorithms for unconstrained optimization.
- solve unconstrained problems using MATLAB's pinv, quadprog, and fminunc.
- solve unconstrained problems using gradient descent and Newton's Method.
- calculate derivatives of vector functions.
- solve linear programming problems graphically and with MATLAB's linprog.

NOTE: You are welcome to program in MATLAB or Python.

Problem 1: Program the backtracking algorithm as described by Boyd on page 464. (Note that Boyd considers gradient vectors to be column vectors instead of row vectors.)

- (a) Inputs to the function are the objective function, gradient function evaluated at x, the point x, and the descent direction v.
- (b) Within the function, set $\alpha = 0.20$ and $\beta = 0.50$.

Problem 2. Program the gradient descent method as described by Boyd on page 466. (Note that Boyd considers gradient vectors to be column vectors instead of row vectors.)

- (a) Inputs to the function are the objective, gradient, and starting point.
- (b) Within the function, set $\eta = 1e-6$.

Problem 3. Program Newton's Method as described by Boyd on page 487. (Note that Boyd considers gradient vectors to be column vectors instead of row vectors.)

- (a) Inputs to the function are the objective, gradient, Hessian, and starting point.
- (b) Within the function, set $\epsilon = 1e-6$.

Problem 4. Consider the least squares estimation problem wherein we are trying to find the $x \in \mathbb{R}^n$ that minimizes the error in the linear equation Ax = b. The matrix $A \in \mathbb{R}^{m \times n}$ and the vector $b \in \mathbb{R}^m$. Assume that m > n and that $\operatorname{rank}(A) = n$.

After defining the error as e = Ax - b, we can write the optimization problem as

$$\min_{x} f(x) = \frac{1}{2}e^{T}e = \frac{1}{2}(Ax - b)^{T}(Ax - b)$$

- (a) Expand the objective function so that it has three terms. Identify the quadratic term, linear term, and constant term.
- (b) Calculate the gradient vector with respect to x.
- (c) Calculate the Hessian matrix with respect to x.
- (d) Use the first-order necessary condition to find all candidates for a local minimum. Check if the second-order necessary condition is satisfied. Explain.
- (e) Use the first and second-order sufficient condition to check if the candidate is indeed a local minimum. Explain.

Problem 5. In MATLAB, create a random A and b for the problem above.

```
>> A = rand(100,3);
>> b = rand(100,1);
```

- (a) Solve the problem using your analytical solution from Problem 4.
- (b) Solve the problem using MATLAB's pinv command.
- (c) Solve the problem using MATLAB's quadprog command.
- (d) Solve the problem using MATLAB's fminunc command.
- (e) Solve the problem using your gradient descent program from Problem 2.
- (f) Solve the problem using your Newton's method program from Problem 3.
- (g) Try different initial guesses and document your observations/thoughts.

Problem 6. Consider the following function $f(x,y) = (\alpha - x)^2 + \beta(y - x^2)^2$ with $\alpha = 1$ and $\beta = 100$.

- (a) Calculate the gradient vector.
- (b) Calculate the Hessian matrix.
- (c) Use the first-order necessary condition to find all candidates for a local minimum.
- (d) Compute the eigenvalues of the Hessian matrix evaluated at the candidate points using MATLAB's eig command. Is the matrix positive semidefinite or positive definite or something else?
- (e) Use the first and second-order sufficient condition to check if the candidate is indeed a local minimum. Explain.

Problem 7. For the optimization problem described in Problem 6:

- (a) Solve the problem using MATLAB's fminunc command.
- (b) Solve the problem using your gradient descent program from Problem 2.
- (c) Solve the problem using your Newton's method program from Problem 3.
- (d) Try the initial guesses $[1 1]^T$ and $[100 1]^T$. Document your observations.

Problem 8. Consider the linear programming (LP) problem with objective

minimize
$$x_1 - x_2$$

subj. to $x_1 + x_2 \le 1$
 $-x_1 + 2x_2 \le 2$
 $x_1 \ge -1$
 $-x_1 + 3x_2 \ge -3$

- (a) Plot the level curves (lines) of the objective on an x_1 - x_2 graph. Identify the direction of decreasing objective value.
- (b) Identify the feasible region by plotting the constraints on the same graph.
- (c) Graphically identify the minimum point using your graph.
- (d) Convert the problem to standard form and solving using MATLAB's linprog.