



Welcome to Intro Physics I!

You have successfully found your way to Phys 221!

- Important things to keep in mind:
 - Labs **are** meeting this week. Make sure you attend!
 - Homework is starting right away. Your first problem is due by midnight on Wednesday
 - Will be submitted through WebWork
 - Username is the first portion of your email
 - Initial password is your student id number, and **then change it!**
- To-Do's:
 - Check out the class webpage (WISE and... otherWISE)
 - Take a closer read through my syllabus to understand what you are getting into
 - Consider getting some form of the book (or soon to have)
 - Remember your phone or computer for polling on Wednesday
 - Get crack-a-lacking on the first homework



Matter

Interactions



Identifying Interactions

Take a few minutes to discuss with your neighbors how you could determine whether a particular object is interacting with another object. Assume that you could **ONLY** see the object in question, nothing else!



Changes in Motion

- Most interactions can be boiled down to a change in motion
 - Speeding up or slowing down
 - Changing direction
- Many other apparent interactions also boil down to these same interactions on a microscopic level
 - Changes in temperature for example
 - Or changes in shape / volume
- Means we need methods to quantify and describe “motion”



Quantifying Position

How could you unambiguously describe my position at the front of the room?

$U=3$
 $U=2$
 $U=A$

$E_3 = 3E_1$
 $E_2 = 4E_1$
 E_1

d

$h^2 = u^2 + E_1^2$

$ma_g \downarrow$
 $ma_g \rightarrow v_1$

$d\vec{r} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$
 $d\vec{r} = \frac{2}{4\pi\epsilon_0} \frac{dx}{r^2}$

$dE_y = \frac{2}{4\pi\epsilon_0} \frac{dx}{r^2} \frac{y}{r}$
 $dE_x = \frac{2}{4\pi\epsilon_0} \frac{dx}{r^2} \frac{x}{r}$

$\Delta P = \epsilon_0 A (T_1 - T_0)$

$U = F_e r = F_r \sin \theta = F_L$
 $v = v_0 \sin \theta$

$F_n \cdot x + F_g \cdot x = ma$
 $F_n \cdot x = 0; F_g \cdot x = F_n \sin \theta = mg \sin \theta$
 $a_x = g \sin \theta$

$U_1, U_2 = X \cdot d$
 $U = \frac{U_g}{2}$
 $U = \sqrt{E^2 + X^2}$

Upcoming:

Vectors

$|U|^2 = A^2 \exp(-\frac{x^2}{2\sigma^2})$
 $B(x) = \frac{\sqrt{x}}{\sqrt{\pi}} e^{-\sigma^2(x-x_0)^2}$

$\psi(\psi) = A \cos(k_0 x - \omega t)$

$|F| = \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
 $= \frac{mv^2}{r}$

$U_H = -\int \vec{B} \cdot (d\vec{r})$
 $U_H = E_H b = v d B b$
 $J = \frac{n}{V} q v d A$
 $b \frac{U}{V} = \frac{1}{A q v b} \int b d v d$
 $= -\int \vec{B} \cdot d\vec{U}_H$

$\lambda_1 = \frac{U_1}{f}; \lambda_2 = \frac{U_2}{f}$
 $\sin \theta_2 = \frac{\lambda_1}{AB'}$
 $\frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_2}{\lambda_1} = \frac{U_1}{U_2} = \frac{v_1}{v_2}$

$\frac{1}{s} = \frac{1}{s} + \frac{1}{s'}$

$E_{pot} = -\frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
 $E_{kin} = \frac{1}{2} m v^2 = \frac{1}{2} \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
 $E_{pot} = -2 E_{kin}$

$E_{pot} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r}$
 $= \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$

$\frac{A'B'}{AB} = \frac{s'}{s}$

$\vec{F}_2 = \frac{F_L}{2u}$
 $E = F_2 \cdot s = \frac{F_L}{u} \cdot u \cdot h = F_L \cdot h = m \cdot g \cdot h$
 $s = u \cdot h$

$\vec{F}_2 = 33\% FL$
 $E = F_2 \cdot s$
 $= \frac{F_L}{u} \cdot u \cdot h = F_L \cdot h = m \cdot g \cdot h$
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 $s = u \cdot h$



Important Concept!

Vectors allow us to unambiguously quantify something's position.

- Unambiguous: Everyone will agree on that object's position
- Quantify: Assign numbers to a certain position
- Graphically they look like arrows



Laying the Foundation

- You have some object you want to describe





Laying the Foundation

- You have some object you want to describe
- You decide the zero point!





Laying the Foundation

- You have some object you want to describe
- You decide the zero point!



Here be Zero



Laying the Foundation

- You have some object you want to describe
- You decide the zero point!
- Arrow extends from zero to the object of interest

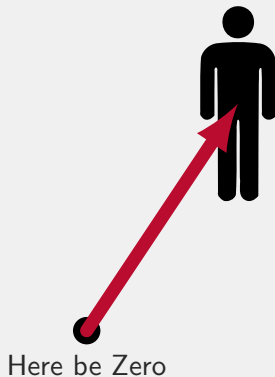


Here be Zero



Laying the Foundation

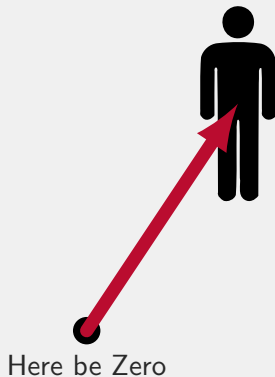
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Laying the Foundation

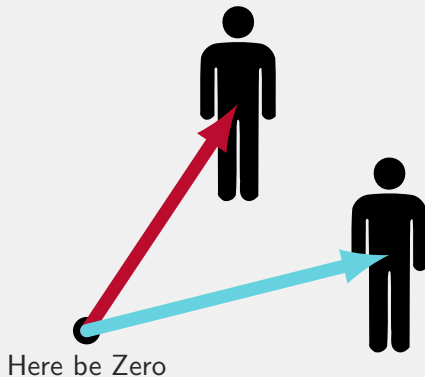
- You have some object you want to describe
- You decide the zero point!
- Arrow extends from zero to the object of interest
- Can describe other objects with more arrows





Laying the Foundation

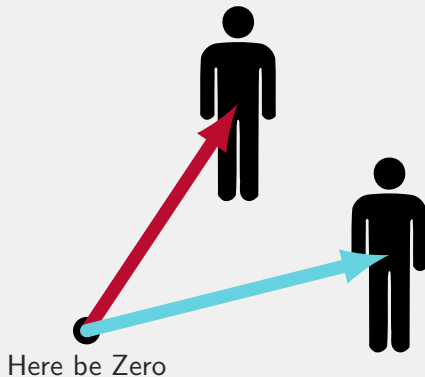
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Laying the Foundation

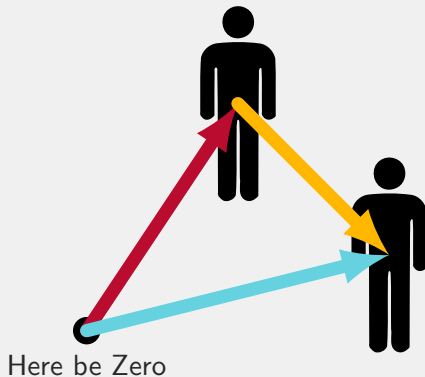
- You have some object you want to describe
- You decide the zero point!
- Arrow extends from zero to the object of interest
- Can describe other objects with more arrows
- Can describe relative positioning with another vector!





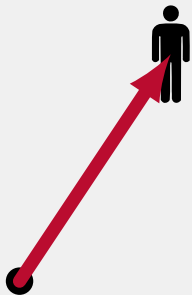
Laying the Foundation

- You have some object you want to describe
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- Can describe other objects with more arrows
- Can describe relative positioning with another vector!





Quantifying Things



Here be Zero



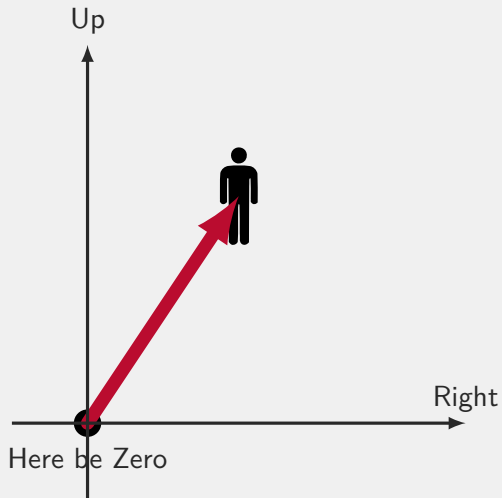
Quantifying Things



- Draw in perpendicular axes



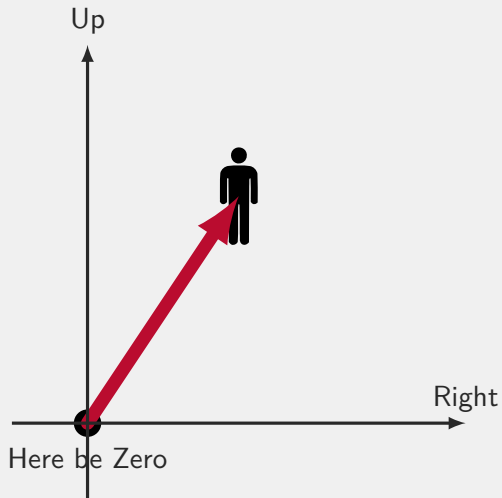
Quantifying Things



- Draw in perpendicular axes



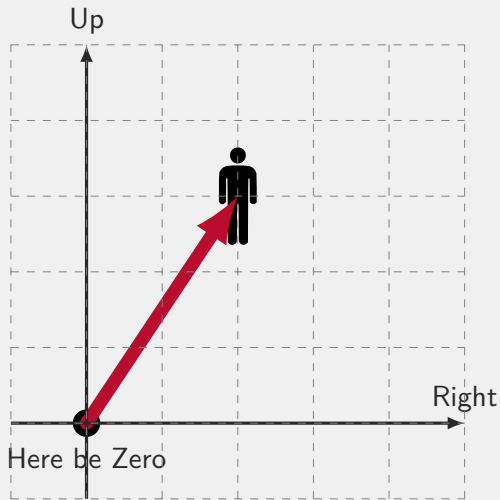
Quantifying Things



- Draw in perpendicular axes
- Decide primary unit of measurement (*usually meters*)



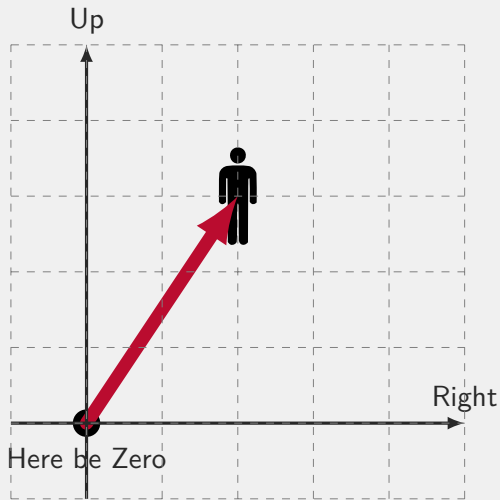
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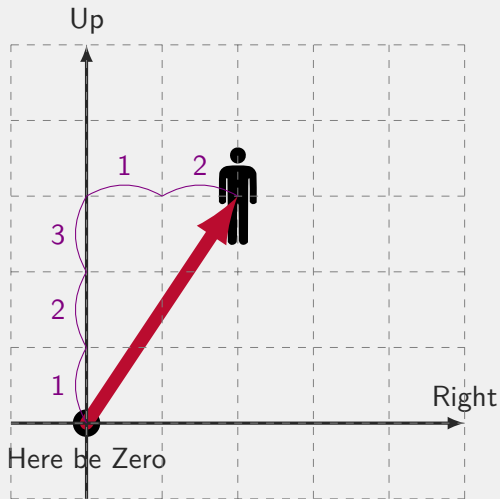
Quantifying Things



- Draw in perpendicular axes
- Decide primary unit of measurement (*usually meters*)
- Determine how many units it travels in each direction:



Quantifying Things



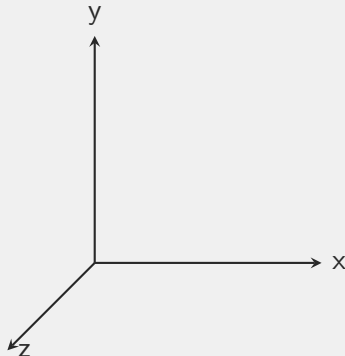
- Draw in perpendicular axes
- Decide primary unit of measurement (*usually meters*)
- Determine how many units it travels in each direction:

3 Up and 2 Right



A Notational Note

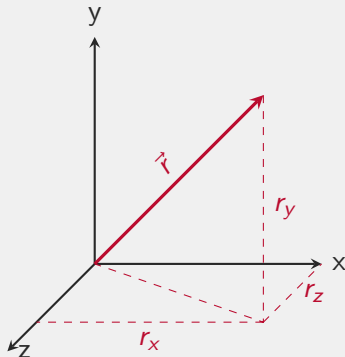
- When we have 3 dimensions, we'll adopt a convention where the z-axis comes out toward us





A Notational Note

- When we have 3 dimensions, we'll adopt a convention where the z-axis comes out toward us
- Vector **components** describe how far the vector travels in each axis direction

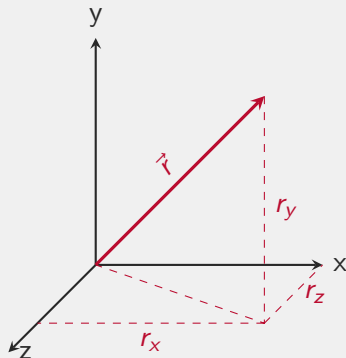




A Notational Note

- When we have 3 dimensions, we'll adopt a convention where the z-axis comes out toward us
- Vector **components** describe how far the vector travels in each axis direction
- We'll use the notation:

$$\vec{r} = \langle r_x, r_y, r_z \rangle$$



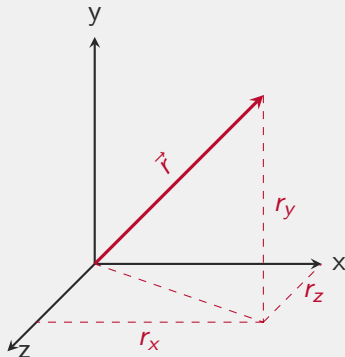


A Notational Note

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- Vector **components** describe how far the vector travels in each axis direction
- We'll use the notation:

$$\vec{r} = \langle r_x, r_y, r_z \rangle$$

- This notation would describe *any* vector with those lengths, regardless of where it started!

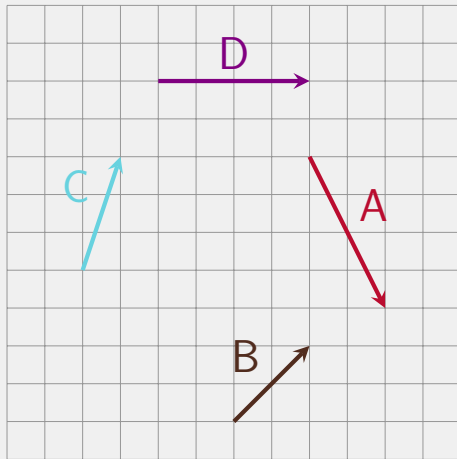




Understanding Check (Unofficial)

If you have an internet capable device,
navigate to `rembold-class.ddns.net`

Which of the arrows to the right could
represent the vector $\langle 2, 2, 0 \rangle$?



$U=3$
 $U=2$
 $U=1$

$E_3 = 3E_1$
 $E_2 = 4E_1$
 E_1

d

$h^2 = u^2 + E_1^2$

$ma_g \downarrow$
 $ma_g \rightarrow v_1$

$d\vec{r} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$
 $d\vec{r} = \frac{2}{4\pi\epsilon_0} \frac{dx}{r^2}$

$d\vec{r} = \frac{2}{4\pi\epsilon_0} \frac{dx}{r^2}$

$\Delta P = c\sigma A(T_1 - T_2)$

$U = F_e r = F_r \sin \theta = F_L$
 $v = v_0 \sin \theta$

$F_n \cdot x + F_g \cdot x = ma$
 $F_n \cdot x = 0; F_g \cdot x = F_g \sin \theta = mg \sin \theta$
 $a_x = g \sin \theta$

$U_1, U_2 = X \cdot \vec{d}$
 $U = \frac{U_g}{2}$
 $U = \frac{U_g}{2}$

Upcoming:

Manipulating Vectors

$U^2 = A^2 \exp(-\frac{x^2}{2\sigma^2})$
 $B(x) = \frac{\sqrt{x}}{\sqrt{\pi}} e^{-\sigma^2(x-x_0)^2}$

$\psi(\psi) = A \cos(k_0 x - \omega t)$

$|F| = \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
 $= \frac{mv^2}{r}$

$U_H = -\int \vec{B} \cdot (d\vec{r})$
 $U_H = E_H b = v d B b$
 $J = \frac{n}{V} q v d A$
 $b \frac{U}{V} = \frac{1}{A q v b} - \frac{1}{b d e v d}$
 $= -\int \vec{B} \cdot d\vec{r}$

$\frac{1}{s} \frac{1}{s} = \frac{1}{1} - \frac{1}{s^2}$
 $\frac{1}{s} = \frac{1}{s} + \frac{1}{s^2}$

$E_{pot} = -\frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
 $E_{kin} = \frac{1}{2} m v^2 = \frac{1}{2} \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$
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$E_{pot} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r}$
 $= \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$

$\frac{A'B'}{AB} = \frac{s'}{s}$

$F_2 = \frac{F_L}{2u}$
 $E = F_2 \cdot s$
 $= \frac{F_L}{u} \cdot u \cdot h$
 $F_L = F_L \cdot h$
 $= m \cdot g \cdot h$
 $s = u \cdot h$

$\vec{v}_1 \rightarrow \vec{v}_2$
 $m_1 \vec{v}_1 + m_2 \vec{v}_2 = m_1 \vec{v}_1' + m_2 \vec{v}_2'$
 $\frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = \frac{1}{2} m_1 v_1'^2 + \frac{1}{2} m_2 v_2'^2$
 $\tan \theta = \frac{ax}{g}; a = g \tan \theta$
 $F_s = \frac{mg}{\cos \theta}; |F_s| = \frac{mg}{\sin \theta}$



Oh the Possibilities!

- As mathematical constructs, there are a host of things we can do with vectors:
 - Multiply or divide by scalars
 - Find the magnitude
 - Find a unit vector
 - Add and subtract vectors
 - Differentiate vectors
 - Take the dot product
 - Take the cross product



Oh the Possibilities!

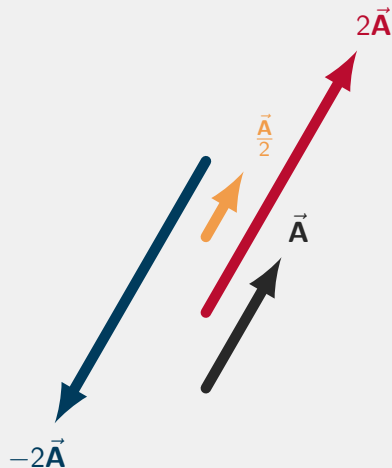
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Multiplying by Scalars

- Scales the vector by the given scalar
- Does **not** change the vector direction
- Negative scalars flip the direction
- Multiplies each component

$$2 \langle 1, 2, 1 \rangle = \langle 2, 4, 2 \rangle$$





Magnitude and Direction

- Magnitude

- How long is your vector?

$$|\vec{w}| = \sqrt{w_x^2 + w_y^2 + w_z^2}$$

- Magnitude is a scalar (not a vector)
- Note: **Magnitude** changes when multiplied by a scalar!

- Direction

- Given by a unit vector (magnitude = 1)

$$\hat{w} = \frac{\vec{w}}{|\vec{w}|}$$

- Unit vectors are indeed vectors (*shocking!*)
- Direction does **not** change when multiplied by a scalar

Important Concept!

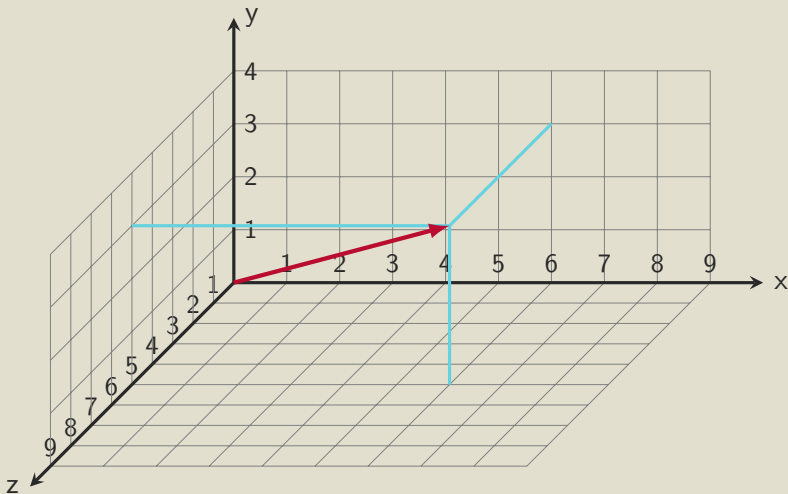
A vector can be written in full as:

$$\vec{w} = |\vec{w}| \cdot \hat{w}$$



Example

Determine the magnitude and direction of the below vector.

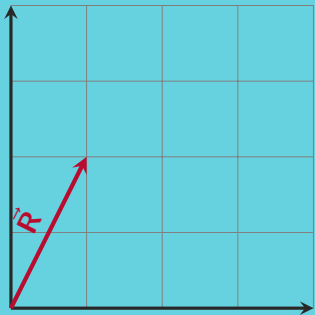




Adding and Subtracting

Graphically

Uses the "head-to-tail" method:

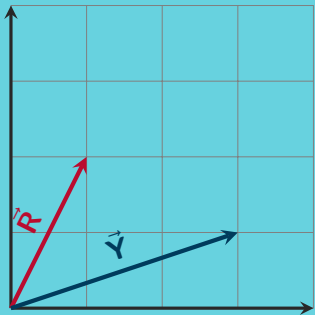




Adding and Subtracting

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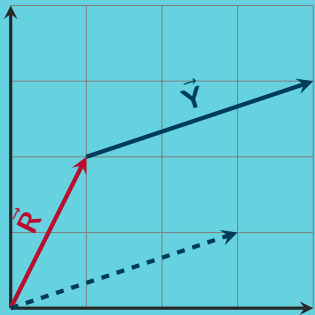




Adding and Subtracting

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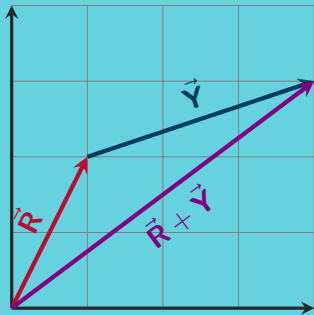




Adding and Subtracting

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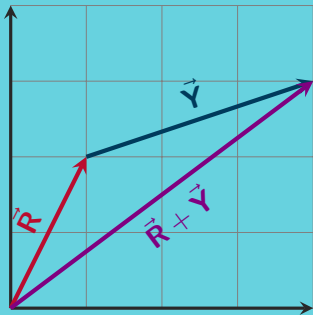




Adding and Subtracting

Graphically

Uses the "head-to-tail" method:



Component-wise

Adding triangles, which is the same as just adding the components!

$$\begin{array}{r} \langle 1, 2, 0 \rangle \\ + \langle 3, 1, 0 \rangle \\ \hline \langle 4, 3, 0 \rangle \end{array}$$

$U=3$
 $U=2$
 $U=1$

$E_3 = 3E_1$
 $E_2 = 4E_1$
 E_1

d

$h^2 = U^2 E_1$

$ma_g \downarrow$

$d\vec{r} = d\vec{r}_1 + d\vec{r}_2$

$d\vec{r}_1 = d\vec{r} \cos \theta$

$d\vec{r}_2 = d\vec{r} \sin \theta$

$d\vec{r}_1 = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$

$d\vec{r}_2 = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$

$d\vec{r}_1 = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$

$d\vec{r}_2 = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2}$

$\Delta P = \epsilon_0 A (T_1 - T_0)$

$U = F_e r = F_r \sin \theta = F_L$

$v = v_0 \sin \theta$

$U_1, U_2 = X \sin \theta$

$F_n, x + F_a, x = ma$

$F_n, x = 0; F_a, x = F_a \sin \theta$

$= mg \sin \theta$

$a_x = g \sin \theta$

$z = \sqrt{r^2 + x^2}$

$v^2 = 2g \sin \theta \Delta x$

$v^2 = 2gh$

$v_s = \sqrt{2gh} \sin \theta$

Upcoming:

Syllabus Highlights

$U^2 = A^2 \exp(-\frac{x^2}{2\sigma^2})$

$B(x) = \frac{\sigma}{\sqrt{\pi}} e^{-\frac{x^2}{2\sigma^2}}$

$\psi(x) = A \cos(k_0 x - \omega t)$

$|F| = \frac{1}{4\pi\epsilon_0} \frac{ze^2}{r}$

$= \frac{mv^2}{r}$

$U_H = -\int \vec{B} \cdot d\vec{r}$

$U_H = E_H b = v d B b$

$J = \frac{n}{V} q v d A$

$b \frac{U}{V} = \frac{1}{A q v b} \int b d v d$

$= -\int \vec{B} \cdot d\vec{r}$

$\frac{1}{s} \frac{d}{dt} = \sqrt{1 - (v/c)^2}$

$P_z^{(A)} = -P_z^{(A)}$

$F_2 = \frac{F_L}{2}$

$E = F_2 \cdot s$

$= \frac{F_L}{2} \cdot u \cdot h$

$F_L = F_L \cdot h$

$= m \cdot g \cdot h$

$s = u \cdot h$

$\frac{1}{s} = \frac{1}{s} + \frac{1}{s'}$

$\frac{A'B'}{AB} = \frac{s'}{s}$

$\frac{s'}{s} = \frac{s' - f}{f}$

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$\frac{A'B'}{AB} = \frac{s' - f}{f}$

$\oint \vec{B} \cdot d\vec{r} = \mu_0 I + \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{A}$

$\oint \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} q$

$\oint \vec{B} \cdot d\vec{A} = 0$

$\vec{B} = B_z + \mu_0 \vec{u} = B_z (1 + \chi_m)$

$E = c B$

$m_1 v_{1x} + m_2 v_{2x} = m_1 v_{1x}' + m_2 v_{2x}'$

$\frac{1}{2} m_1 v_{1x}^2 + \frac{1}{2} m_2 v_{2x}^2 = \frac{1}{2} m_1 v_{1x}'^2 + \frac{1}{2} m_2 v_{2x}'^2$

$= \frac{1}{2} m_1 v_{1x}^2 + \frac{1}{2} m_2 v_{2x}^2$

$\tan \theta = \frac{ax}{g}$

$F_s = \frac{mg}{\cos \theta}$

$F_s = \frac{mg}{\cos \theta}$



My Vitals

Name: Jed Rembold

Office: Collins 311 (it's shared)

Office Hours: MW 4:15–5:15pm, TTh 2:00–4:00pm, *and open door*

Email: jjrembold@willamette.edu

Office Phone: (503)-370-6860



Grading

Attendance	Lab	Written HW	Video HW	3 Midterms	Final
5%	15%	15%	10%	30%	25%



Homework

- Online

- Assigned Mon, Wed
- Due Wed, Fri at midnight
- Completed on WebWork, *no penalty for incorrect answers*

- Video

- Assigned Fri
- Due Mon at midnight
- < 4 min video to show objective mastery
 - Objective provided
 - You choose/create problem
 - **Can be a simple video!**
- I'll request permission to post my favorites to the webpage
- One question on each test will pull from those videos



- 3 Midterms
 - First is September 17
 - Get a 3x5 inch index card, one side, handwritten
 - In class, so 1 hour in length
 - Will have about 5 minutes at the start to discuss with peers, but no writing during this time!
 - I will give out old tests and other study materials about a week before each exam
- Final
 - On Friday, December 17
 - Comprehensive
 - Can use previous index cards + 1

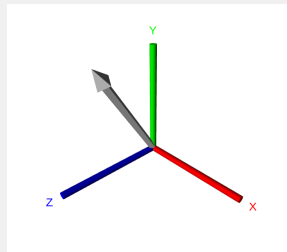


- All labs mixed between sections
- You need to be at lab to receive lab credit
- Let both me and your lab instructor know if you need to miss:
 - Best to make it up at a different lab that week
 - In the worst case, there is 1 potential day old labs can be made up
- **You can not pass the class if you miss more than 4 labs**



Computation

- This course introduces computational skills that are often times ignored in other Intro courses
- The bulk of these will happen during lab
- A few homeworks throughout the semester will rely on these skills, and basic versions could show up on tests.
- Don't neglect them! I can't really think of any scientific discipline in this day of age that could not benefit from applying computational methods in certain cases!
- Lab these first few weeks will focus on teaching you the basics so that you can then start applying them to class concepts





Practice Time

Given that

$$\vec{a} = \langle 1, 3, 5 \rangle, \quad \vec{b} = \langle 2, 4, 6 \rangle, \quad \vec{c} = \langle 4, 1, 0 \rangle, \quad \vec{d} = \langle 2, 4, 0 \rangle$$

can you answer the following?

1. What is $5\vec{a} + \vec{b} + \frac{1}{2}\vec{d}$?
2. Is $\vec{c} + \vec{d}$ the same as $\vec{d} + \vec{c}$? Can you support your claim graphically?
3. Is $\vec{c} - \vec{d}$ the same as $\vec{d} - \vec{c}$? Can you support your claim graphically?
4. What is the magnitude of $\vec{b} - \vec{a}$?
5. Is $\vec{b} - \vec{a}$ a unit vector? If not, what unit vector points in the same direction?