

Micro-Econometrics

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Contents

1	Linear Regressions	7
1.1	Hypotheses	7
1.2	Least square estimation	11
1.3	Common pitfalls in linear regressions	26
1.4	Instrumental Variables	28
1.5	General Regression Model (GRM) and robust covariance matrices	34
1.6	Shrinkage methods	47
2	Panel regressions	53
2.1	Specification and notations	53
2.2	Three standard cases	56
2.3	Estimation of Fixed-Effects Models	56
2.4	Estimation of random effects models	61
2.5	Dynamic Panel Regressions	66
2.6	Introduction to program evaluation	72
3	Estimation Methods	79
3.1	Generalized Method of Moments (GMM)	79
3.2	Maximum Likelihood Estimation	85
3.3	Bayesian approach	97
4	Binary-choice models	105
4.1	Interpretation in terms of latent variable, and utility-based models	107
4.2	Alternative-Varying Regressors	109
4.3	Estimation	111

4.4	Marginal effects	112
4.5	Goodness of fit	112
4.6	Predictions and ROC curves	117
5	Multiple Choice Models	119
5.1	Ordered case	119
5.2	General multinomial logit model	122
5.3	Nested logits	128
6	Tobit and sample-selection models	133
6.1	Tobit models	133
6.2	Sample Selection Models	142
7	Models of Count Data	149
7.1	Poisson model	149
7.2	Negative binomial model	150
7.3	Hurdle model	154
7.4	Zero-inflated model	154
8	Appendix	159
8.1	Linear algebra: definitions and results	159
8.2	Statistical analysis: definitions and results	161
8.3	Some properties of Gaussian variables	167
8.4	Proofs	169
8.5	Additional codes	173
8.6	Statistical Tables	174

Micro-Econometrics

In microeconomic models, the variables of interest often feature restricted distributions—for instance with discontinuous support—which necessitates specific models. Typical examples are discrete-choice models (binary, multinomial, ordered outcomes), sample selection models (censored or truncated outcomes), and count-data models (integer outcomes). The course describes the estimation and interpretation of these models. It also shows how the discrete-choice models can emerge from (structural) random-utility frameworks.

This course has been developed by Jean-Paul Renne. It is illustrated by R codes using various packages that can be obtained from CRAN. This AEC package is available on GitHub. To install it, one needs to employ the `devtools` library:

```
install.packages("devtools") # in case this library has not been loaded yet
library(devtools)
install_github("jrenne/AEC")
library(AEC)
```

Useful (R) links:

- Download R:
 - R software: <https://cran.r-project.org> (the basic R software)
 - RStudio: <https://www.rstudio.com> (a convenient R editor)
- Tutorials:
 - Rstudio: <https://dss.princeton.edu/training/RStudio101.pdf> (by Oscar Torres-Reyna)
 - R: https://cran.r-project.org/doc/contrib/Paradis-rdebuts_en.pdf (by Emmanuel Paradis)
 - My own tutorial: https://jrenne.shinyapps.io/Rtuto_publiShiny/

Chapter 1

Linear Regressions

Definition 1.1. A linear regression model is of the form:

$$y_i = \beta' \mathbf{x}_i + \varepsilon_i, \quad (1.1)$$

where $\mathbf{x}_i = [x_{i,1}, \dots, x_{i,K}]'$ is a vector of dimension $K \times 1$.

For entity i , the $x_{i,k}$'s, for $k \in \{1, \dots, K\}$, are explanatory variables, regressors, or covariates. The variable of interest, y_i , is often called dependent variable, or regressand. The last term of the specification, namely ε_i , is called error, or disturbance.

The researcher is usually interested in the components of vector β , denoted by β_k , $k \in \{1, \dots, K\}$. She usually aims at estimating these coefficients based on observations of $\{y_i, \mathbf{x}_i\}$, $i \in \{1, \dots, n\}$, which constitutes a *sample*. In the following, we will denote the sample length by n .

To have an intercept in the specification (1.1), one has to set $x_{i,1} = 1$ for all i ; β_1 then corresponds to the intercept.

1.1 Hypotheses

In this section, we introduce different assumptions regarding the covariates and/or the errors. The properties of the estimators used by the researcher depend on which of these assumptions are satisfied.

Hypothesis 1.1 (Full rank). There is no exact linear relationship among the independent variables (the $x_{i,k}$'s, for a given $i \in \{1, \dots, n\}$).

Intuitively, when Hypothesis 1.1 is satisfied, then the estimation of the model parameters is unfeasible since, for any value of β , some changes in the explanatory variables will be exactly compensated by other changes in another set of explanatory variables, preventing the identification of these effects.

Let us denote by \mathbf{X} the matrix containing all explanatory variables, of dimension $n \times K$. (That is, row i of \mathbf{X} is \mathbf{x}'_i .) The following hypothesis concerns the relationship between the errors (gathered in ε , a n -dimensional vector) and the explanatory variables \mathbf{X} :

Hypothesis 1.2 (Conditional mean-zero assumption).

$$\mathbb{E}(\varepsilon|\mathbf{X}) = 0. \quad (1.2)$$

Hypothesis 1.2 has important implications:

Proposition 1.1. *Under Hypothesis 1.2:*

- i. $\mathbb{E}(\varepsilon_i) = 0$;
- ii. The x_{ij} 's and the ε_i 's are uncorrelated, i.e. $\forall i, j \quad \text{Corr}(x_{ij}, \varepsilon_i) = 0$.

Proof. Let us prove (i) and (ii):

- i. By the law of iterated expectations:

$$\mathbb{E}(\varepsilon) = \mathbb{E}(\mathbb{E}(\varepsilon|\mathbf{X})) = \mathbb{E}(0) = 0.$$

- ii. $\mathbb{E}(x_{ij}\varepsilon_i) = \mathbb{E}(\mathbb{E}(x_{ij}\varepsilon_i|\mathbf{X})) = \mathbb{E}(x_{ij} \underbrace{\mathbb{E}(\varepsilon_i|\mathbf{X})}_{=0}) = 0$.

□

The next two hypotheses (1.3 and 1.4) concern the stochastic properties of the errors ε_i :

Hypothesis 1.3 (Homoskedasticity).

$$\forall i, \quad \text{Var}(\varepsilon_i|\mathbf{X}) = \sigma^2.$$

The following lines of code generate a figure comparing two situations: Panel (a) of Figure 1.1 corresponds to a situation of homoskedasticity, and Panel (b) corresponds to a situation of heteroskedasticity. Let us be more specific. In the two plots, we have $X_i \sim \mathcal{N}(0, 1)$ and $\varepsilon_i^* \sim \mathcal{N}(0, 1)$. In Panel (a) (homoskedasticity):

$$Y_i = 2 + 2X_i + \varepsilon_i^*.$$

In Panel (b) (heteroskedasticity):

$$Y_i = 2 + 2X_i + \left(2\mathbb{1}_{\{X_i < 0\}} + 0.2\mathbb{1}_{\{X_i \geq 0\}}\right) \varepsilon_i^*$$


```

N <- 200
X <- rnorm(N); eps <- rnorm(N)
par(mfrow=c(1,2),plt=c(.2,.95,.2,.8))
Y <- 2 + 2*X + eps
plot(X,Y,pch=19,main="(a) Homoskedasticity",
     las=1,cex.lab=.8,cex.axis=.8,cex.main=.8,)
Y <- 2 + 2*X + eps*( (X<0)*2 + (X>=0)*.2 )
plot(X,Y,pch=19,main="(b) Heteroskedasticity",
     las=1,cex.lab=.8,cex.axis=.8,cex.main=.8,)

```

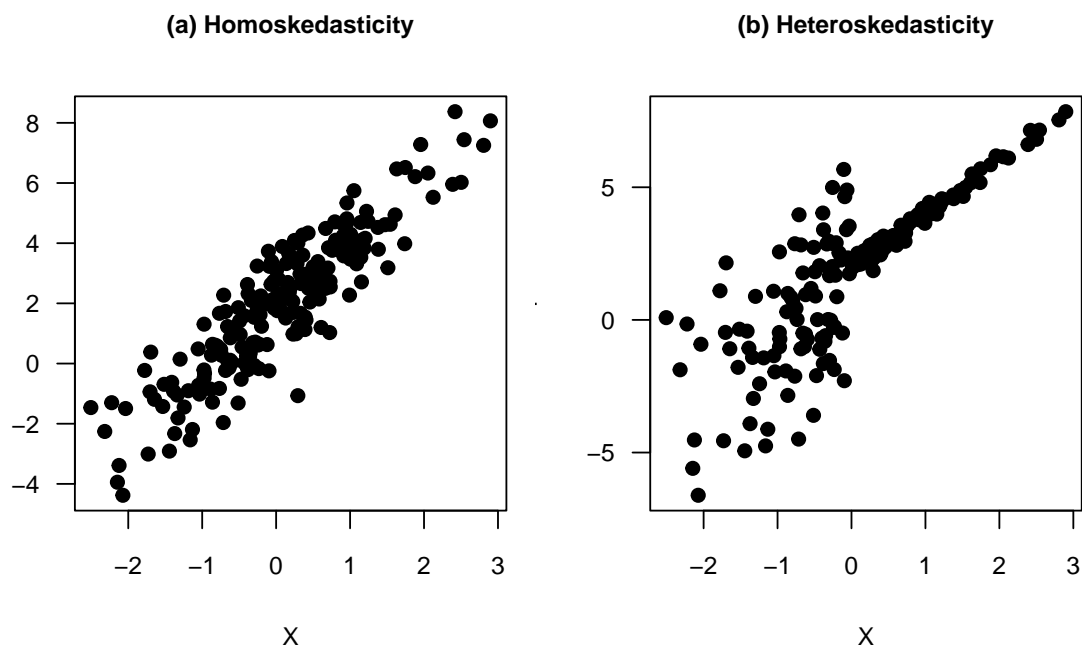


Figure 1.1: Homoskedasticity vs heteroskedasticity. See text for the exact specifications.

Figure 1.2 shows a real-data situation of heteroskedasticity, based on data taken from the Swiss Household Panel. The sample is restricted to persons (i) that are younger than 35 year in 2019, and (ii) that have completed at least 19 years of study. The figure shows that the dispersion of yearly income increases with age.

```

library(AEC)
table(shp$edyear19)

```

```

##
##      8      9     10     12     13     14     16     19     21
##    70   325   350  1985   454   117   990  1263   168

```

```
shp_higherEd <- subset(shp, (edyear19>18)&age19<35)
plot(i19wyg/1000~age19, data=shp_higherEd, pch=19, las=1,
     xlab="Age", ylab="Yearly work income")
abline(lm(i19wyg/1000~age19, data=shp_higherEd), col="red", lwd=2)
```

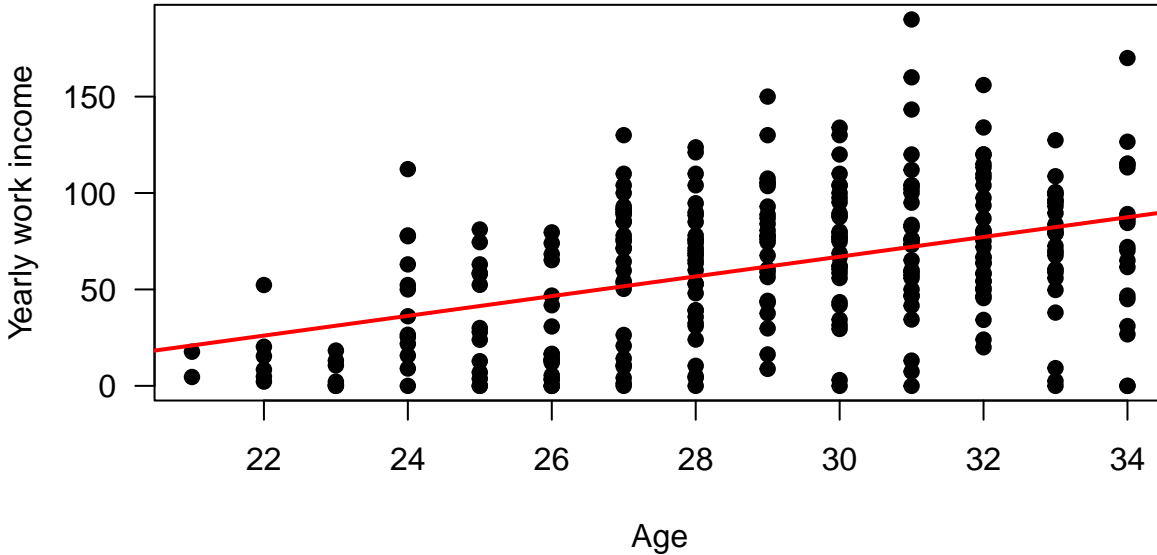


Figure 1.2: Income versus age. Data are from the Swiss Household Panel. The sample is restricted to persons that have completed at least 19 years of study. The figure shows that the dispersion of yearly income increases with age.

The next assumption concerns the correlation of the errors across entities.

Hypothesis 1.4 (Uncorrelated errors).

$$\forall i \neq j, \quad \text{Cov}(\varepsilon_i, \varepsilon_j | \mathbf{X}) = 0.$$

We will often need to work with the covariance matrix of the errors. Proposition 1.2 give the specific form of the covariance matrix of the errors —conditional on \mathbf{X} — when both Hypotheses 1.3 and 1.4 are satisfied:

Proposition 1.2. *If Hypotheses 1.3 and 1.4 hold, then:*

$$\text{Var}(\varepsilon | \mathbf{X}) = \sigma^2 \text{Id},$$

where Id is the $n \times n$ identity matrix.

We will sometimes assume that errors are Gaussian—or normal. We will then invoke Hypothesis 1.5:

Hypothesis 1.5 (Normal distribution).

$$\forall i, \quad \varepsilon_i \sim \mathcal{N}(0, \sigma^2).$$

1.2 Least square estimation

1.2.1 Derivation of the OLS formula

In this section, we will present and study the properties of the most popular estimation approach, namely the **Ordinary Least Squares (OLS)** approach. As suggested by its name, the OLS estimator of β is defined as the vector \mathbf{b} that minimizes the sum of squared residuals. (The *residuals* are the estimates of the *errors* ε_i .)

For a given vector of coefficients $\mathbf{b} = [b_1, \dots, b_K]'$, the sum of squared residuals is:

$$f(\mathbf{b}) = \sum_{i=1}^n \left(y_i - \sum_{j=1}^K x_{i,j} b_j \right)^2 = \sum_{i=1}^n (y_i - \mathbf{x}_i' \mathbf{b})^2.$$

Minimizing this sum amounts to minimizing:

$$f(\mathbf{b}) = (\mathbf{y} - \mathbf{X}\mathbf{b})'(\mathbf{y} - \mathbf{X}\mathbf{b}).$$

Since:¹

$$\frac{\partial f}{\partial \mathbf{b}}(\mathbf{b}) = -2\mathbf{X}'\mathbf{y} + 2\mathbf{X}'\mathbf{X}\mathbf{b},$$

it comes that a necessary first-order condition (FOC) is:

$$\mathbf{X}'\mathbf{X}\mathbf{b} = \mathbf{X}'\mathbf{y}. \quad (1.3)$$

Under Assumption 1.1, $\mathbf{X}'\mathbf{X}$ is invertible. Hence:

$$\boxed{\mathbf{b} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}.}$$

Vector \mathbf{b} minimizes the sum of squared residuals. (f is a non-negative quadratic function, it therefore admits a minimum.)

We have:

$$\mathbf{y} = \underbrace{\mathbf{X}\mathbf{b}}_{\text{fitted values } (\hat{\mathbf{y}})} + \underbrace{\mathbf{e}}_{\text{residuals}}$$

The estimated residuals are:

$$\mathbf{e} = \mathbf{y} - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} = \mathbf{M}\mathbf{y}, \quad (1.4)$$

where $\mathbf{M} := Id - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$ is called the **residual maker** matrix.

Moreover, the fitted values $\hat{\mathbf{y}}$ are given by:

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} = \mathbf{P}\mathbf{y}, \quad (1.5)$$

where $\mathbf{P} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$ is a **projection matrix**.

These matrices \mathbf{M} and \mathbf{P} are such that:

¹see Proposition 8.7.

- $\mathbf{MX} = \mathbf{0}$: if one regresses one of the explanatory variables on \mathbf{X} , the residuals are null.
- $\mathbf{My} = \mathbf{M}\varepsilon$ (because $\mathbf{y} = \mathbf{X}\beta + \varepsilon$ and $\mathbf{MX} = \mathbf{0}$).

Here are some additional properties of \mathbf{M} and \mathbf{P} :

- \mathbf{M} is symmetric ($\mathbf{M} = \mathbf{M}'$) and idempotent ($\mathbf{M} = \mathbf{M}^2 = \mathbf{M}^k$ for $k > 0$).
- \mathbf{P} is symmetric and idempotent.
- $\mathbf{PX} = \mathbf{X}$.
- $\mathbf{PM} = \mathbf{MP} = \mathbf{0}$.
- $\mathbf{y} = \mathbf{Py} + \mathbf{My}$ (decomposition of \mathbf{y} into two orthogonal parts).

It is easily checked that $\mathbf{X}'\mathbf{e} = \mathbf{0}$. Each column of \mathbf{X} is therefore orthogonal to \mathbf{e} . In particular, if an intercept is included in the regression ($x_{i,1} \equiv 1$ for all i 's, i.e., the first column of \mathbf{X} is filled with ones), the average of the residuals is null.

Example 1.1 (Bivariate case). Consider a bivariate situation, where we regress y_i on a constant and an explanatory variable w_i . We have $K = 2$, and \mathbf{X} is a $n \times 2$ matrix whose i^{th} row is $[x_{i,1}, x_{i,2}]$, with $x_{i,1} = 1$ (to account for the intercept) and with $w_i = x_{i,2}$ (say).

We have:

$$\begin{aligned} \mathbf{X}'\mathbf{X} &= \begin{bmatrix} n & \sum_i w_i \\ \sum_i w_i & \sum_i w_i^2 \end{bmatrix}, \\ (\mathbf{X}'\mathbf{X})^{-1} &= \frac{1}{n \sum_i w_i^2 - (\sum_i w_i)^2} \begin{bmatrix} \sum_i w_i^2 & -\sum_i w_i \\ -\sum_i w_i & n \end{bmatrix}, \\ (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} &= \frac{1}{n \sum_i w_i^2 - (\sum_i w_i)^2} \begin{bmatrix} \sum_i w_i^2 \sum_i y_i - \sum_i w_i \sum_i w_i y_i \\ -\sum_i w_i \sum_i y_i + n \sum_i w_i y_i \end{bmatrix} \\ &= \frac{1}{\frac{1}{n} \sum_i (w_i - \bar{w})^2} \begin{bmatrix} \frac{\bar{y}}{n} \sum_i w_i^2 - \frac{\bar{w}}{n} \sum_i w_i y_i \\ \frac{1}{n} \sum_i (w_i - \bar{w})(y_i - \bar{y}) \end{bmatrix}. \end{aligned}$$

It can be seen that the second element of $\mathbf{b} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$ is:

$$b_2 = \frac{\overline{\text{Cov}(W, Y)}}{\overline{\text{Var}(W)}},$$

where $\overline{\text{Cov}(W, Y)}$ and $\overline{\text{Var}(W)}$ are sample estimates.

Since there is a constant in the regression, we have $b_1 = \bar{y} - b_2\bar{w}$.

1.2.2 Properties of the OLS estimate (small sample)

The OLS properties stated in Proposition 1.3 are valid for any sample size n :

Proposition 1.3 (Properties of the OLS estimator). *We have:*

- i. Under Assumptions 1.1 and 1.2, the OLS estimator is linear and unbiased.
- ii. Under Hypotheses 1.1 to 1.4, the conditional covariance matrix of \mathbf{b} is: $\mathbb{V}ar(\mathbf{b}|\mathbf{X}) = \sigma^2(\mathbf{X}'\mathbf{X})^{-1}$.

Proof. Under Hypothesis 1.1, $\mathbf{X}'\mathbf{X}$ can be inverted. We have:

$$\mathbf{b} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} = \beta + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\boldsymbol{\varepsilon}.$$

- i. Let us consider the expectation of the last term, i.e. $\mathbb{E}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\boldsymbol{\varepsilon})$. Using the law of iterated expectations, we obtain:

$$\mathbb{E}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\boldsymbol{\varepsilon}) = \mathbb{E}(\mathbb{E}[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\boldsymbol{\varepsilon} | \mathbf{X}]) = \mathbb{E}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}[\boldsymbol{\varepsilon} | \mathbf{X}]).$$

By Hypothesis 1.2, we have $\mathbb{E}[\boldsymbol{\varepsilon} | \mathbf{X}] = \mathbf{0}$. Hence $\mathbb{E}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\boldsymbol{\varepsilon}) = \mathbf{0}$ and result (i) follows.

- ii. $\mathbb{V}ar(\mathbf{b}|\mathbf{X}) = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}(\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}'|\mathbf{X})\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}$. By Prop. 1.2, if 1.3 and 1.4 hold, then we have $\mathbb{E}(\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}'|\mathbf{X}) = \mathbb{V}ar(\boldsymbol{\varepsilon}|\mathbf{X}) = \sigma^2 Id$.

□

Together, Hypotheses 1.1 to 1.4 form the so-called Gauss-Markov set of assumptions. Under these assumptions, the OLS estimator feature the lowest possible variance within the family of linear unbiased estimates of β :

Theorem 1.1 (Gauss-Markov Theorem). *Under Assumptions 1.1 to 1.4, for any vector w , the minimum-variance linear unbiased estimator of $w'\beta$ is $w'\mathbf{b}$, where \mathbf{b} is the least squares estimator. (BLUE: Best Linear Unbiased Estimator.)*

Proof. Consider $\mathbf{b}^* = C\mathbf{y}$, another linear unbiased estimator of β . Since it is unbiased, we must have $\mathbb{E}(C\mathbf{y}|\mathbf{X}) = \mathbb{E}(C\mathbf{X}\beta + C\boldsymbol{\varepsilon}|\mathbf{X}) = \beta$. We have $\mathbb{E}(C\boldsymbol{\varepsilon}|\mathbf{X}) = C\mathbb{E}(\boldsymbol{\varepsilon}|\mathbf{X}) = \mathbf{0}$ (by 1.2). Therefore \mathbf{b}^* is unbiased if $\mathbb{E}(C\mathbf{X})\beta = \beta$. This has to be the case for any β , which implies that we must have $C\mathbf{X} = Id$. Let us compute $\mathbb{V}ar(\mathbf{b}^*|\mathbf{X})$. For this, we introduce $D = C - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$, which is such that $D\mathbf{y} = \mathbf{b}^* - \mathbf{b}$. The fact that $C\mathbf{X} = Id$ implies that $D\mathbf{X} = \mathbf{0}$. We have $\mathbb{V}ar(\mathbf{b}^*|\mathbf{X}) = \mathbb{V}ar(C\mathbf{y}|\mathbf{X}) = \mathbb{V}ar(C\boldsymbol{\varepsilon}|\mathbf{X}) = \sigma^2 CC'$ (by Assumptions 1.3 and 1.4, see Prop. 1.2). Using $C = D + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$ and exploiting the fact that $D\mathbf{X} = \mathbf{0}$ leads to:

$$\mathbb{V}ar(\mathbf{b}^*|\mathbf{X}) = \sigma^2 [(D + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')(D + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')'] = \mathbb{V}ar(\mathbf{b}|\mathbf{X}) + \sigma^2 \mathbf{D}\mathbf{D}'.$$

Therefore, we have

$$\begin{aligned} \mathbb{V}ar(w'\mathbf{b}^*|\mathbf{X}) &= w'\mathbb{V}ar(\mathbf{b}|\mathbf{X})w + \sigma^2 w'\mathbf{D}\mathbf{D}'w \\ &\geq w'\mathbb{V}ar(\mathbf{b}|\mathbf{X})w = \mathbb{V}ar(w'\mathbf{b}|\mathbf{X}). \end{aligned}$$

□

The Frish-Waugh theorem (Theorem 1.2) reveals the relationship between the OLS estimator and the notion of partial correlation coefficient. Consider the linear least square regression of \mathbf{y} on \mathbf{X} . We introduce the notations:

- $\mathbf{b}^{\mathbf{y}/\mathbf{X}}$: OLS estimates of β ,
- $\mathbf{M}^{\mathbf{X}}$: residual-maker matrix of any regression on \mathbf{X} (given by $Id - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$),
- $\mathbf{P}^{\mathbf{X}}$: projection matrix of any regression on \mathbf{X} (given by $\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$).

Let us split the set of explanatory variables into two: $\mathbf{X} = [\mathbf{X}_1, \mathbf{X}_2]$. With obvious notations: $\mathbf{b}^{\mathbf{y}/\mathbf{X}} = [\mathbf{b}_1', \mathbf{b}_2']'$.

Theorem 1.2 (Frisch-Waugh Theorem). *We have:*

$$\mathbf{b}_2 = \mathbf{b}^{\mathbf{M}^{\mathbf{X}_1}\mathbf{y}/\mathbf{M}^{\mathbf{X}_1}\mathbf{X}_2}.$$

Proof. The minimization of the least squares leads to (these are first-order conditions, see Eq. (1.3)):

$$\begin{bmatrix} \mathbf{X}_1'\mathbf{X}_1 & \mathbf{X}_1'\mathbf{X}_2 \\ \mathbf{X}_2'\mathbf{X}_1 & \mathbf{X}_2'\mathbf{X}_2 \end{bmatrix} \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{X}_1'\mathbf{y} \\ \mathbf{X}_2'\mathbf{y} \end{bmatrix}.$$

Use the first-row block of equations to solve for \mathbf{b}_1 first; it comes as a function of \mathbf{b}_2 . Then use the second set of equations to solve for \mathbf{b}_2 , which leads to:

$$\begin{aligned} \mathbf{b}_2 &= [\mathbf{X}_2'\mathbf{X}_2 - \mathbf{X}_2'\mathbf{X}_1(\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1'\mathbf{X}_2]^{-1}\mathbf{X}_2'(Id - \mathbf{X}_1(\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1')\mathbf{y} \\ &= [\mathbf{X}_2'\mathbf{M}^{\mathbf{X}_1}\mathbf{X}_2]^{-1}\mathbf{X}_2'\mathbf{M}^{\mathbf{X}_1}\mathbf{y}. \end{aligned}$$

Using the fact that $\mathbf{M}^{\mathbf{X}_1}$ is idempotent and symmetric leads to the result. \square

This suggests a second way of estimating \mathbf{b}_2 :

1. Regress Y on X_1 , regress X_2 on X_1 .
2. Regress the residuals associated with the former regression on those associated with the latter regressions.

This is illustrated by the following code, where we run different regressions involving the number of Google searches for “parapluie” (*umbrella* in French). In the broad specification, we regress it on French precipitations and month dummies. Next, we deseasonalize both the dependent variable and the precipitations by regressing them on the month dummies. As stated by Theorem 1.2, regressing deseasonalized Google searches on deseasonalized precipitations give the same coefficient as in the baseline regression.

```
library(AEC)
dummies <- as.matrix(parapluie[,4:14])
eq_all <- lm(parapluie~dummies+precip,data=parapluie)
deseas_parapluie <- lm(parapluie~dummies,data=parapluie)$residuals
deseas_precip <- lm(precip~dummies,data=parapluie)$residuals
eq_frac <- lm(deseas_parapluie~deseas_precip-1)
stargazer::stargazer(eq_all,eq_frac,omit=c(1:11,"Constant"),type="text",
                      omit.stat = c("f","ser"),digits=5,
                      add.lines=list(c('Monthly dummy','Yes','No')))
```

```
##
## =====
##                Dependent variable:
##                -----
##                parapluie  deseas_parapluie
##                (1)        (2)
## -----
## precip            0.13001***
##                  (0.03594)
##
## deseas_precip            0.13001***
##                          (0.03277)
##
## -----
## Monthly dummy    Yes        No
## Observations     72         72
## R2               0.51793     0.18148
## Adjusted R2      0.41988     0.16995
## =====
## Note:            *p<0.1; **p<0.05; ***p<0.01
```

When b_2 is scalar (and then \mathbf{X}_2 is of dimension $n \times 1$), Theorem 1.2 gives the expression of the **partial regression coefficient** b_2 :

$$b_2 = \frac{\mathbf{X}_2' M \mathbf{X}_1 \mathbf{y}}{\mathbf{X}_2' M \mathbf{X}_1 \mathbf{X}_2}.$$

1.2.3 Goodness of fit

Define the total variation in y as the sum of squared deviations (from the sample mean):

$$TSS = \sum_{i=1}^n (y_i - \bar{y})^2.$$

We have:

$$\mathbf{y} = \mathbf{X}\mathbf{b} + \mathbf{e} = \hat{\mathbf{y}} + \mathbf{e}$$

In the following, we assume that the regression includes a constant (i.e. for all i , $x_{i,1} = 1$). Denote by \mathbf{M}^0 the matrix that transforms observations into deviations from sample means. Using that $\mathbf{M}^0\mathbf{e} = \mathbf{e}$ and that $\mathbf{X}'\mathbf{e} = 0$, we have:

$$\begin{aligned} \underbrace{\mathbf{y}'\mathbf{M}^0\mathbf{y}}_{\text{Total sum of sq.}} &= (\mathbf{X}\mathbf{b} + \mathbf{e})'\mathbf{M}^0(\mathbf{X}\mathbf{b} + \mathbf{e}) \\ &= \underbrace{\mathbf{b}'\mathbf{X}'\mathbf{M}^0\mathbf{X}\mathbf{b}}_{\text{"Explained" sum of sq.}} + \underbrace{\mathbf{e}'\mathbf{e}}_{\text{Sum of sq. residuals}} \\ TSS &= Expl.SS + SSR. \end{aligned}$$

We can now define the coefficient of determination:

$$\text{Coefficient of determination} = \frac{Expl.SS}{TSS} = 1 - \frac{SSR}{TSS} = 1 - \frac{\mathbf{e}'\mathbf{e}}{\mathbf{y}'\mathbf{M}^0\mathbf{y}}.$$

(1.6)

It can be shown (Greene (2003), Section 3.5) that:

$$\text{Coefficient of determination} = \frac{[\sum_{i=1}^n (y_i - \bar{y})(\hat{y}_i - \bar{y})]^2}{\sum_{i=1}^n (y_i - \bar{y})^2 \sum_{i=1}^n (\hat{y}_i - \bar{y})^2}.$$

That is, the R^2 is the sample squared correlation between \mathbf{y} and the (regression-implied) \mathbf{y} 's predictions.

The higher the R^2 , the higher the goodness of fit of a model. One however has to be cautious with R^2 . Indeed, it is easy to increase it: it suffices to add explanatory variables. As stated by Proposition 1.5, adding an explanatory variable (even if it does not truly relate to the dependent variable) mechanically results in an increase in the R^2 . In the limit, taking any set of n non-linearly-dependent explanatory variables (i.e., variables satisfying Hypothesis 1.1) results in a R^2 equal to one.

Proposition 1.4 (Change in SSR when a variable is added). *We have:*

$$\mathbf{u}'\mathbf{u} = \mathbf{e}'\mathbf{e} - c^2(\mathbf{z}^{*'}\mathbf{z}^*) \quad (\leq \mathbf{e}'\mathbf{e}) \quad (1.7)$$

where (i) \mathbf{u} and \mathbf{e} are the residuals in the regressions of \mathbf{y} on $[\mathbf{X}, \mathbf{z}]$ and of \mathbf{y} on \mathbf{X} , respectively, (ii) c is the regression coefficient on \mathbf{z} in the former regression and where \mathbf{z}^* are the residuals in the regression of \mathbf{z} on \mathbf{X} .

Proof. The OLS estimates $[\mathbf{d}', c']'$ in the regression of \mathbf{y} on $[\mathbf{X}, \mathbf{z}]$ satisfies (first-order cond., Eq. (1.3)):

$$\begin{bmatrix} \mathbf{X}'\mathbf{X} & \mathbf{X}'\mathbf{z} \\ \mathbf{z}'\mathbf{X} & \mathbf{z}'\mathbf{z} \end{bmatrix} \begin{bmatrix} \mathbf{d} \\ c \end{bmatrix} = \begin{bmatrix} \mathbf{X}'\mathbf{y} \\ \mathbf{z}'\mathbf{y} \end{bmatrix}.$$

Hence, in particular $\mathbf{d} = \mathbf{b} - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{z}c$, where \mathbf{b} is the OLS of \mathbf{y} on \mathbf{X} . Substituting in $\mathbf{u} = \mathbf{y} - \mathbf{X}\mathbf{d} - \mathbf{z}c$, we get $\mathbf{u} = \mathbf{e} - \mathbf{z}^*c$. We therefore have:

$$\mathbf{u}'\mathbf{u} = (\mathbf{e} - \mathbf{z}^*c)(\mathbf{e} - \mathbf{z}^*c) = \mathbf{e}'\mathbf{e} + c^2(\mathbf{z}^{*\prime}\mathbf{z}^*) - 2c\mathbf{z}^{*\prime}\mathbf{e}. \quad (1.8)$$

Now $\mathbf{z}^{*\prime}\mathbf{e} = \mathbf{z}^{*\prime}(\mathbf{y} - \mathbf{X}\mathbf{b}) = \mathbf{z}^{*\prime}\mathbf{y}$ because \mathbf{z}^* are the residuals in an OLS regression on \mathbf{X} . Since $c = (\mathbf{z}^{*\prime}\mathbf{z}^*)^{-1}\mathbf{z}^{*\prime}\mathbf{y}^*$ (by an application of Theorem 1.2), we have $(\mathbf{z}^{*\prime}\mathbf{z}^*)c = \mathbf{z}^{*\prime}\mathbf{y}^*$ and, therefore, $\mathbf{z}^{*\prime}\mathbf{e} = (\mathbf{z}^{*\prime}\mathbf{z}^*)c$. Inserting this in Eq. (1.8) leads to the results. \square

Proposition 1.5 (Change in the coefficient of determination when a variable is added). Denoting by R_W^2 the coefficient of determination in the regression of \mathbf{y} on some variable \mathbf{W} , we have:

$$R_{\mathbf{X},\mathbf{z}}^2 = R_{\mathbf{X}}^2 + (1 - R_{\mathbf{X}}^2)(r_{yz}^{\mathbf{X}})^2,$$

where $r_{yz}^{\mathbf{X}}$ is the coefficient of partial correlation (see Definition 8.5).

Proof. Let's use the same notations as in Prop. 1.4. Theorem 1.2 implies that $c = (\mathbf{z}^{*\prime}\mathbf{z}^*)^{-1}\mathbf{z}^{*\prime}\mathbf{y}^*$. Using this in Eq. (1.7) gives $\mathbf{u}'\mathbf{u} = \mathbf{e}'\mathbf{e} - (\mathbf{z}^{*\prime}\mathbf{y}^*)^2/(\mathbf{z}^{*\prime}\mathbf{z}^*)$. Using the definition of the partial correlation (Eq. (8.1)), we get $\mathbf{u}'\mathbf{u} = \mathbf{e}'\mathbf{e}(1 - (r_{yz}^{\mathbf{X}})^2)$. The results is obtained by dividing both sides of the previous equation by $\mathbf{y}'\mathbf{M}_0\mathbf{y}$. \square

Figure 1.3, below, illustrates the fact that one can obtain an R^2 of one by regressing a sample of length n on any set of n linearly-independent variables.

```
n <- 30; Y <- rnorm(n); X <- matrix(rnorm(n^2), n, n)
all_R2 <- NULL; all_adjR2 <- NULL
for(j in 0:(n-1)){
  if(j==0){eq <- lm(Y~1)} else {eq <- lm(Y~X[,1:j])}
  all_R2 <- c(all_R2, summary(eq)$r.squared)
  all_adjR2 <- c(all_adjR2, summary(eq)$adj.r.squared)
}
par(plt=c(.15,.95,.25,.95))
plot(all_R2, pch=19, ylim=c(min(all_adjR2, na.rm = TRUE), 1),
     xlab="number of regressors", ylab="R2")
points(all_adjR2, pch=3); abline(h=0, col="light grey", lwd=2)
legend("topleft", c("R2", "Adjusted R2"),
     lty=NaN, col=c("black"), pch=c(19, 3), lwd=2)
```

In order to address the risk of adding irrelevant explanatory variables, measures of **adjusted** R^2 have been proposed. Compared to the standard R^2 , these measures add penalties that depend on the number of covariates employed in the regression. A common adjusted R^2 measure, denoted by \bar{R}^2 , is the following:

$$\bar{R}^2 = 1 - \frac{\mathbf{e}'\mathbf{e}/(n-K)}{\mathbf{y}'\mathbf{M}^0\mathbf{y}/(n-1)} = 1 - \frac{n-1}{n-K}(1 - R^2).$$

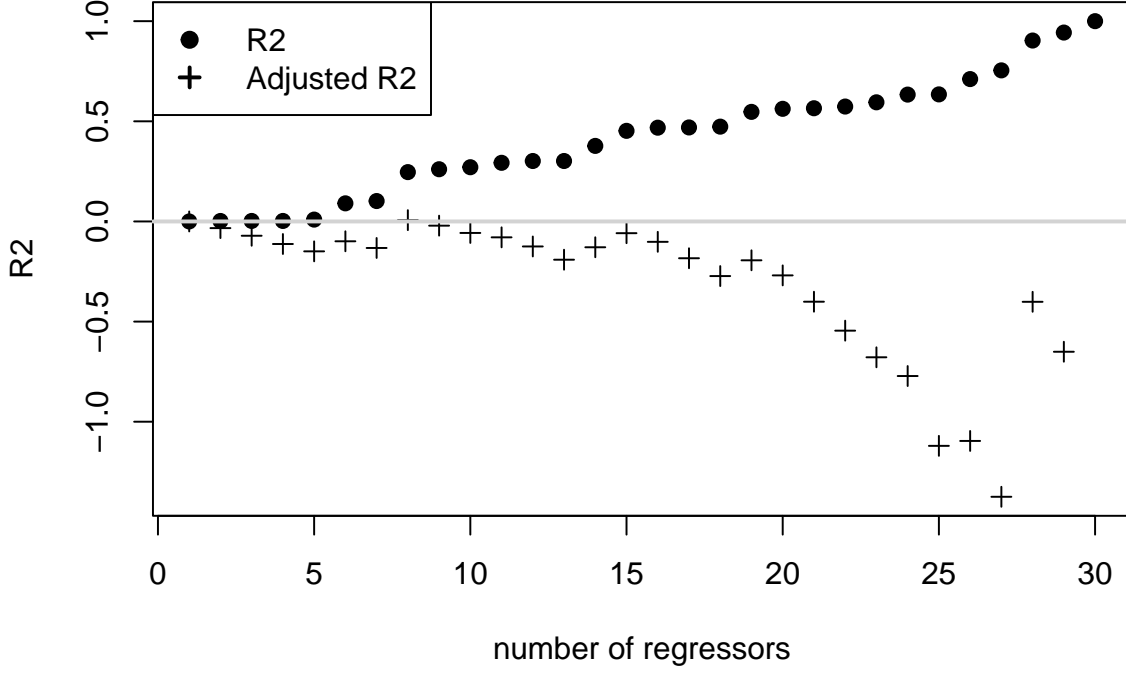


Figure 1.3: This figure illustrates the monotonous increase in the R^2 as a function of the number of explanatory variables. In the true model, there is no explanatory variables, i.e., $y_i = \varepsilon_i$. We then take (independent) regressors and regress y on the latter, progressively increasing the set of regressors.

1.2.4 Inference and confidence intervals (in small sample)

Under the normality assumption (Assumption 1.5), we know the distribution of \mathbf{b} (conditional on \mathbf{X}). Indeed, $\mathbf{b} = \beta + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\varepsilon$. Therefore, conditional on \mathbf{X} , vector \mathbf{b} is an affine combination of Gaussian variables—the components of ε . As a result, it is also Gaussian. Its distribution is therefore completely characterized by its mean and variance, and we have:

$$\mathbf{b}|\mathbf{X} \sim \mathcal{N}(\beta, \sigma^2(\mathbf{X}'\mathbf{X})^{-1}). \quad (1.9)$$

Eq. (1.9) can be used to conduct inference and tests. However, in practice, we do not know σ^2 (which is a population parameter). The following proposition gives an unbiased estimate of σ^2 .

Proposition 1.6. *Under 1.1 to 1.4, an unbiased estimate of σ^2 is given by:*

$$s^2 = \frac{\mathbf{e}'\mathbf{e}}{n - K}. \quad (1.10)$$

(It is sometimes denoted by σ_{OLS}^2 .)

Proof. We have:

$$\begin{aligned} \mathbb{E}(\mathbf{e}'\mathbf{e}|\mathbf{X}) &= \mathbb{E}(\varepsilon'\mathbf{M}\varepsilon|\mathbf{X}) = \mathbb{E}(\text{Tr}(\varepsilon'\mathbf{M}\varepsilon)|\mathbf{X}) \\ &= \text{Tr}(\mathbf{M}\mathbb{E}(\varepsilon\varepsilon'|\mathbf{X})) = \sigma^2\text{Tr}(\mathbf{M}). \end{aligned}$$

(Note that we have $\mathbb{E}(\varepsilon\varepsilon'|\mathbf{X}) = \sigma^2 Id$ by Assumptions 1.3 and 1.4, see Prop. 1.2.) Moreover:

$$\begin{aligned}\text{Tr}(\mathbf{M}) &= n - \text{Tr}(\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}') \\ &= n - \text{Tr}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{X}) = n - \text{Tr}(Id_{K \times K}),\end{aligned}$$

which leads to the result. \square

Two results will prove important to produce inference:

- i. We know the conditional distribution of s^2 (Prop. 1.7).
- ii. s^2 and \mathbf{b} are independent random variables (Prop. 1.8).

Proposition 1.7. *Under 1.1 to 1.5, we have: $\frac{s^2}{\sigma^2}|\mathbf{X} \sim \frac{1}{n-K}\chi^2(n-K)$.*

Proof. We have $\mathbf{e}'\mathbf{e} = \varepsilon'\mathbf{M}\varepsilon$. \mathbf{M} is an idempotent symmetric matrix. Therefore it can be decomposed as PDP' where D is a diagonal matrix and P is an orthogonal matrix. As a result $\mathbf{e}'\mathbf{e} = (P'\varepsilon)'D(P'\varepsilon)$, i.e. $\mathbf{e}'\mathbf{e}$ is a weighted sum of independent squared Gaussian variables (the entries of $P'\varepsilon$ are independent because they are Gaussian —under 1.5— and uncorrelated). The variance of each of these i.i.d. Gaussian variable is σ^2 . Because \mathbf{M} is an idempotent symmetric matrix, its eigenvalues are either 0 or 1, and its rank equals its trace (see Propositions 8.3 and 8.4). Further, its trace is equal to $n - K$ (see proof of Eq. (1.10)). Therefore D has $n - K$ entries equal to 1 and K equal to 0. Hence, $\mathbf{e}'\mathbf{e} = (P'\varepsilon)'D(P'\varepsilon)$ is a sum of $n - K$ squared independent Gaussian variables of variance σ^2 . Therefore $\frac{\mathbf{e}'\mathbf{e}}{\sigma^2} = (n - K)\frac{s^2}{\sigma^2}$ is a sum of $n - k$ squared i.i.d. standard normal variables. The result follows by the definition of the chi-square distribution (see Def. 8.13). \square

Proposition 1.8. *Under Hypotheses 1.1 to 1.5, \mathbf{b} and s^2 are independent.*

Proof. We have $\mathbf{b} = \beta + [\mathbf{X}'\mathbf{X}]^{-1}\mathbf{X}'\varepsilon$ and $s^2 = \varepsilon'\mathbf{M}\varepsilon/(n - K)$. Hence \mathbf{b} is an affine combination of ε and s^2 is a quadratic combination of the same Gaussian shocks. One can write s^2 as $s^2 = (\mathbf{M}\varepsilon)'\mathbf{M}\varepsilon/(n - K)$ and \mathbf{b} as $\beta + \mathbf{T}\varepsilon$. Since $\mathbf{T}\mathbf{M} = 0$, $\mathbf{T}\varepsilon$ and $\mathbf{M}\varepsilon$ are independent (because two uncorrelated Gaussian variables are independent), therefore \mathbf{b} and s^2 , which are functions of two sets of independent variables, are independent. \square

Consistently with Eq. (1.9), under Hypotheses 1.1 to 1.5, the k^{th} entry of \mathbf{b} satisfies:

$$b_k|\mathbf{X} \sim \mathcal{N}(\beta_k, \sigma^2 v_k),$$

where v_k is the k^{th} component of the diagonal of $(\mathbf{X}'\mathbf{X})^{-1}$.

Moreover, we have (Prop. 1.7):

$$\frac{(n - K)s^2}{\sigma^2}|\mathbf{X} \sim \chi^2(n - K).$$

As a result (using Propositions 1.7 and 1.8), we have:

$$t_k = \frac{\frac{b_k - \beta_k}{\sqrt{\sigma^2 v_k}}}{\sqrt{\frac{(n-K)s^2}{\sigma^2(n-K)}}} = \frac{b_k - \beta_k}{\sqrt{s^2 v_k}} \sim t(n-K), \quad (1.11)$$

where $t(n-K)$ denotes a Student t distribution with $n-K$ degrees of freedom (see Def. 8.12).²

Note that $s^2 v_k$ is not exactly the conditional variance of b_k : The variance of b_k conditional on \mathbf{X} is $\sigma^2 v_k$. However $s^2 v_k$ is an unbiased estimate of $\sigma^2 v_k$ (by Prop. 1.6).

The previous result (Eq. (1.11)) can be extended to any linear combinations of elements of \mathbf{b} . (Eq. (1.11) is for its k^{th} component only.) Let us consider $\alpha' \mathbf{b}$, the OLS estimate of $\alpha' \beta$. From Eq. (1.9), we have:

$$\alpha' \mathbf{b} | \mathbf{X} \sim \mathcal{N}(\alpha' \beta, \sigma^2 \alpha' (\mathbf{X}' \mathbf{X})^{-1} \alpha).$$

Therefore:

$$\frac{\alpha' \mathbf{b} - \alpha' \beta}{\sqrt{\sigma^2 \alpha' (\mathbf{X}' \mathbf{X})^{-1} \alpha}} | \mathbf{X} \sim \mathcal{N}(0, 1).$$

Using the same approach as the one used to derive Eq. (1.11), one can show that Props. 1.7 and 1.8 also imply that:

$$\frac{\alpha' \mathbf{b} - \alpha' \beta}{\sqrt{s^2 \alpha' (\mathbf{X}' \mathbf{X})^{-1} \alpha}} \sim t(n-K). \quad (1.12)$$

What precedes is widely exploited for statistical inference in the context of linear regressions. Indeed, Eq. (1.11) gives a sense of the distances between b_k and β_k that can be deemed as “likely” (or, conversely, “unlikely”). For instance, it implies that, if $\sqrt{v_k s^2}$ is equal to 1 (say), then the probability to obtain b_k smaller than $\beta_k - 4.587 \times \sqrt{v_k s^2}$ or larger than $\beta_k + 4.587 \times \sqrt{v_k s^2}$ is equal to 0.1% when $n-K=10$.

That means for instance that, under the assumption that $\beta_k = 0$, it would be extremely unlikely to have obtained $b_k / \sqrt{v_k s^2}$ smaller than -4.587 or larger than 4.587. More generally, this shows that the **t-statistic**, i.e., the ratio $b_k / \sqrt{v_k s^2}$, is the test statistic associated with the null hypothesis:

$$H_0 : \beta_k = 0.$$

Under the null hypothesis, the test statistic follows a Student-t distribution with $n-K$ degrees of freedom. The **t-statistic** is therefore of particular importance, and, as a result, it is routinely reported in regression outputs (see Example 1.2).

Example 1.2 (Education and income). Consider regression that aims at determining covariates of households’ income. This example makes use of data from the Swiss Household Panel (SHP); `edyear19` is the number of years of education and `age19` is the age of the respondent, as of 2019.

²We have $\frac{b_k - \beta_k}{\sqrt{\sigma^2 v_k}} | \mathbf{X} \sim \mathcal{N}(0, 1)$ and $\frac{(n-K)s^2}{\sigma^2} | \mathbf{X} \sim \chi^2(n-K)$. These two distributions do not depend on $\mathbf{X} \Rightarrow$ the *marginal distribution* of t_k is also t .

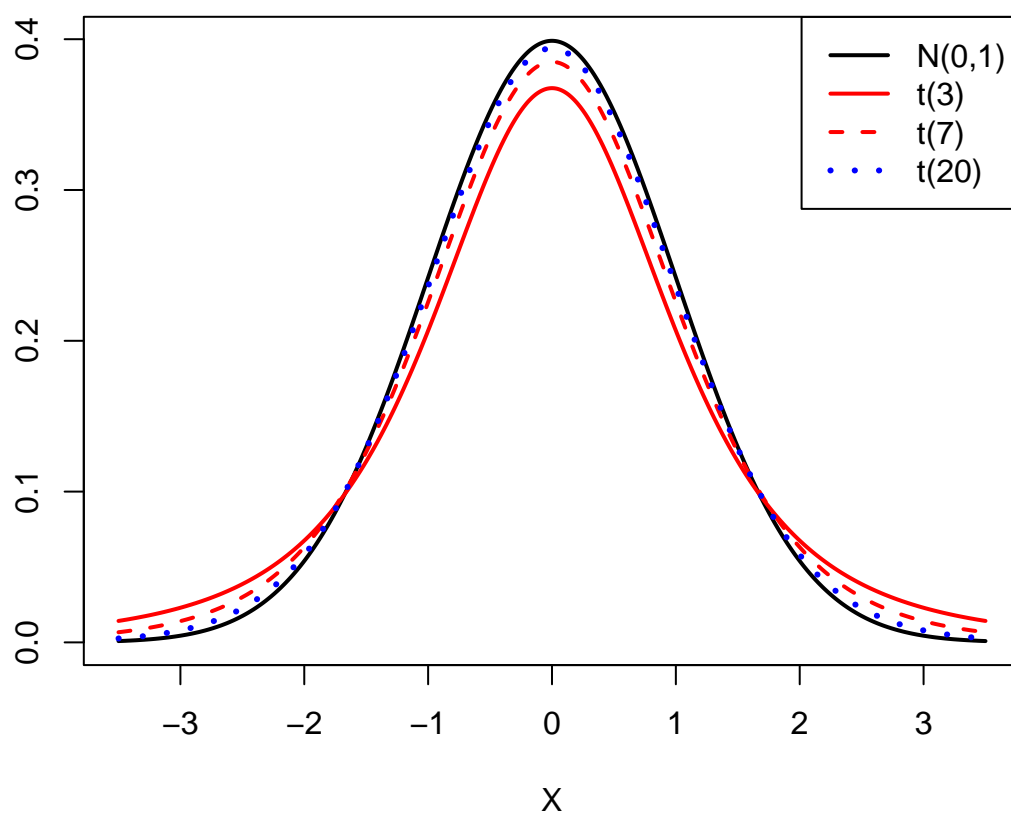


Figure 1.4: The higher the degree of freedom, the closer the distribution of $t(\nu)$ gets to the normal distribution. (Convergence in distribution.)

```

library(AEC)
library(sandwich)
shp$income <- shp$i19ptotn/1000
shp$female <- 1*(shp$sex19==2)
eq <- lm(income ~ edyear19 + age19 + I(age19^2) + female,data=shp)
lmtest::coeftest(eq)

##
## t test of coefficients:
##
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept) -71.9738073    5.7082456 -12.609 < 2.2e-16 ***
## edyear19      4.8442661    0.2172320  22.300 < 2.2e-16 ***
## age19         3.2386215    0.2183812  14.830 < 2.2e-16 ***
## I(age19^2)   -0.0289498    0.0020915 -13.842 < 2.2e-16 ***
## female       -31.8089006    1.4578004 -21.820 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

The last two columns of the previous table give the t-statistic and the p-values associated with t-tests, whose size- α critical region is:

$$\left] -\infty, -\Phi_{t(n-K)}^{-1} \left(1 - \frac{\alpha}{2} \right) \right] \cup \left[\Phi_{t(n-K)}^{-1} \left(1 - \frac{\alpha}{2} \right), +\infty \right[.$$

We recall that the **p-value** is defined as the probability that $|Z| > |t|$, where t is the (computed) t-statistics and where $Z \sim t(n-K)$. That is, in the context of the t-test, the p-value is given by $2(1 - \Phi_{t(n-K)}(|t_k|))$. See this webpage for details regarding the link between critical regions, p-value, and test outcomes.

Now, suppose we want to compute a (symmetrical) *confidence interval* $[I_{d,1-\alpha}, I_{u,1-\alpha}]$ that is such that $\mathbb{P}(\beta_k \in [I_{d,1-\alpha}, I_{u,1-\alpha}]) = 1 - \alpha$. That is, we want to have: $\mathbb{P}(\beta_k < I_{d,1-\alpha}) = \frac{\alpha}{2}$ and $\mathbb{P}(\beta_k > I_{u,1-\alpha}) = \frac{\alpha}{2}$. Let us focus on $I_{d,1-\alpha}$ to start with. Using Eq. (1.11), i.e., $t_k = \frac{b_k - \beta_k}{\sqrt{s^2 v_k}} \sim t(n-K)$, we have:

$$\begin{aligned}
\mathbb{P}(\beta_k < I_{d,1-\alpha}) &= \frac{\alpha}{2} \Leftrightarrow \\
\mathbb{P} \left(\frac{b_k - \beta_k}{\sqrt{s^2 v_k}} > \frac{b_k - I_{d,1-\alpha}}{\sqrt{s^2 v_k}} \right) &= \frac{\alpha}{2} \Leftrightarrow \mathbb{P} \left(t_k > \frac{b_k - I_{d,1-\alpha}}{\sqrt{s^2 v_k}} \right) = \frac{\alpha}{2} \Leftrightarrow \\
1 - \mathbb{P} \left(t_k \leq \frac{b_k - I_{d,1-\alpha}}{\sqrt{s^2 v_k}} \right) &= \frac{\alpha}{2} \Leftrightarrow \frac{b_k - I_{d,1-\alpha}}{\sqrt{s^2 v_k}} = \Phi_{t(n-K)}^{-1} \left(1 - \frac{\alpha}{2} \right),
\end{aligned}$$

where $\Phi_{t(n-K)}(\alpha)$ is the c.d.f. of the $t(n-K)$ distribution (Table 8.2).

Doing the same for $I_{u,1-\alpha}$, we obtain:

$$[I_{d,1-\alpha}, I_{u,1-\alpha}] = \left[b_k - \Phi_{t(n-K)}^{-1} \left(1 - \frac{\alpha}{2} \right) \sqrt{s^2 v_k}, b_k + \Phi_{t(n-K)}^{-1} \left(1 - \frac{\alpha}{2} \right) \sqrt{s^2 v_k} \right].$$

Using the results presented in Example 1.2, we can compute lower and upper bounds of 95% confidence intervals for the estimated parameters as follows:

```
n <- length(eq$residuals); K <- length(eq$coefficients)
lower.b <- eq$coefficients + qt(.025,df=n-K)*sqrt(diag(vcov(eq)))
upper.b <- eq$coefficients + qt(.975,df=n-K)*sqrt(diag(vcov(eq)))
cbind(lower.b,upper.b)
```

```
##               lower.b      upper.b
## (Intercept) -83.16413225 -60.78348237
## edyear19      4.41840914   5.27012310
## age19         2.81051152   3.66673148
## I(age19^2)   -0.03304986  -0.02484977
## female       -34.66674188 -28.95105932
```

1.2.5 Testing a set of linear restrictions

We sometimes want to test if a set of restrictions are *jointly* consistent with the data at hand. Let us formalize such a set of (J) linear restrictions:

$$\begin{aligned} r_{1,1}\beta_1 + \cdots + r_{1,K}\beta_K &= q_1 \\ &\vdots \\ r_{J,1}\beta_1 + \cdots + r_{J,K}\beta_K &= q_J. \end{aligned} \tag{1.13}$$

In matrix form, we get:

$$\mathbf{R}\beta = \mathbf{q}. \tag{1.14}$$

Define the *discrepancy vector* $\mathbf{m} = \mathbf{R}\mathbf{b} - \mathbf{q}$. Under the null hypothesis:

$$\begin{aligned} \mathbb{E}(\mathbf{m}|\mathbf{X}) &= \mathbf{R}\beta - \mathbf{q} = 0 \quad \text{and} \\ \mathbb{V}ar(\mathbf{m}|\mathbf{X}) &= \mathbf{R}\mathbb{V}ar(\mathbf{b}|\mathbf{X})\mathbf{R}'. \end{aligned}$$

With these notations, the assumption to test is:

$$\boxed{H_0 : \mathbf{R}\beta - \mathbf{q} = 0 \text{ against } H_1 : \mathbf{R}\beta - \mathbf{q} \neq 0.} \tag{1.15}$$

Under Hypotheses 1.1 to 1.4, we have $\mathbb{V}ar(\mathbf{m}|\mathbf{X}) = \sigma^2 \mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'$ (see Prop. 1.3). If we add the normality assumption (Hypothesis 1.5), we have:

$$W = \mathbf{m}'\mathbb{V}ar(\mathbf{m}|\mathbf{X})^{-1}\mathbf{m} \sim \chi^2(J). \tag{1.16}$$

If σ^2 was known, we could then conduct a *Wald test* (directly exploiting Eq. (1.16)). But this is not the case in practice and we cannot compute W . We can, however, approximate it by replacing σ^2 by s^2 (given in Eq. (1.10)). The distribution of this new statistic is not $\chi^2(J)$ any more; it is an \mathcal{F} *distribution* (whose quantiles are shown in Table 8.4), and the test is called *F test*.

Proposition 1.9. *Under Hypotheses 1.1 to 1.5 and if Eq. (1.15) holds, we have:*

$$F = \frac{W}{J} \frac{\sigma^2}{s^2} = \frac{\mathbf{m}'(\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}')^{-1}\mathbf{m}}{s^2 J} \sim \mathcal{F}(J, n-K), \quad (1.17)$$

where \mathcal{F} is the distribution of the *F-statistic* (see Def. 8.11).

Proof. According to Eq. (1.16), $W/J \sim \chi^2(J)/J$. Moreover, the denominator (s^2/σ^2) is $\sim \chi^2(n-K)/(n-K)$. Therefore, F is the ratio of a r.v. distributed as $\chi^2(J)/J$ and another distributed as $\chi^2(n-K)/(n-K)$. It remains to verify that these r.v. are independent. Under H_0 , we have $\mathbf{m} = \mathbf{R}(\mathbf{b} - \beta) = \mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\varepsilon$. Therefore $\mathbf{m}'(\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}')^{-1}\mathbf{m}$ is of the form $\varepsilon'\mathbf{T}\varepsilon$ with $\mathbf{T} = \mathbf{D}'\mathbf{C}\mathbf{D}$ where $\mathbf{D} = \mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$ and $\mathbf{C} = (\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}')^{-1}$. Under Hypotheses 1.1 to 1.4, the covariance between $\mathbf{T}\varepsilon$ and $\mathbf{M}\varepsilon$ is $\sigma^2\mathbf{T}\mathbf{M} = \mathbf{0}$. Therefore, under 1.5, these variables are Gaussian variables with 0 covariance. Hence they are independent. \square

For large $n-K$, the $\mathcal{F}_{J, n-K}$ distribution converges to $\mathcal{F}_{J, \infty} = \chi^2(J)/J$. This implies that, in large samples, the *F-statistic* approximately has a χ^2 distribution. In other words, one can approximately employ Eq. (1.16) to perform a *Wald test* (one just has to replace σ^2 with s^2 when computing $\text{Var}(\mathbf{m}|\mathbf{X})$).

The following proposition proposes another equivalent computation of the *F-statistic*, based on the R^2 of the restricted and unrestricted linear models.

Proposition 1.10. *The F-statistic defined by Eq. (1.17) is also equal to:*

$$F = \frac{(R^2 - R_*^2)/J}{(1 - R^2)/(n-K)} = \frac{(SSR_{restr} - SSR_{unrestr})/J}{SSR_{unrestr}/(n-K)}, \quad (1.18)$$

where R_*^2 is the coef. of determination (Eq. (1.6)) of the “restricted regression” (SSR: sum of squared residuals.)

Proof. Let's denote by $\mathbf{e}_* = \mathbf{y} - \mathbf{X}\mathbf{b}_*$ the vector of residuals associated to the *restricted regression* (i.e. $\mathbf{R}\mathbf{b}_* = \mathbf{q}$). We have $\mathbf{e}_* = \mathbf{e} - \mathbf{X}(\mathbf{b}_* - \mathbf{b})$. Using $\mathbf{e}'\mathbf{X} = 0$, we get $\mathbf{e}_*\mathbf{e}_* = \mathbf{e}'\mathbf{e} + (\mathbf{b}_* - \mathbf{b})'\mathbf{X}'\mathbf{X}(\mathbf{b}_* - \mathbf{b}) \geq \mathbf{e}'\mathbf{e}$.

By Proposition 8.5 (in Appendix 8.1), we have: $\mathbf{b}_* - \mathbf{b} = -(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'\{\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'\}^{-1}(\mathbf{R}\mathbf{b} - \mathbf{q})$. Therefore:

$$\mathbf{e}_*\mathbf{e}_* - \mathbf{e}'\mathbf{e} = (\mathbf{R}\mathbf{b} - \mathbf{q})'[\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}']^{-1}(\mathbf{R}\mathbf{b} - \mathbf{q}).$$

This implies that the *F statistic* defined in Prop. 1.9 is also equal to:

$$\frac{(\mathbf{e}_*\mathbf{e}_* - \mathbf{e}'\mathbf{e})/J}{\mathbf{e}'\mathbf{e}/(n-K)},$$

which leads to the result. \square

The null hypothesis H_0 (Eq. (1.15)) of the F-test is rejected if F —defined by Eq. (1.17) or (1.18)—is higher than $\mathcal{F}_{1-\alpha}(J, n-K)$. (Hence, this test is a one-sided test.)

1.2.6 Large Sample Properties

Even if we relax the normality assumption (Hypothesis 1.5), we can approximate the finite-sample behavior of the estimators by using *large-sample* or *asymptotic properties*.

To begin with, we proceed under Hypothesis 1.1 to 1.4. (We will see, later on, how to deal with —partial— relaxations of Hypothesis 1.3 and 1.4.)

Under regularity assumptions, and under Hypotheses 1.1 to 1.4, even if the residuals are not normally-distributed, the least square estimators can be *asymptotically normal* and inference can be performed in the same way as in small samples when Hypotheses 1.1 to 1.5 hold. This derives from Prop. 1.11 (below). The F-test (Prop. 1.10) and the t-test (Eq. (1.11)) can then be performed.

Proposition 1.11. *Under Assumptions 1.1 to 1.4, and assuming further that:*

$$Q = \text{plim}_{n \rightarrow \infty} \frac{\mathbf{X}'\mathbf{X}}{n}, \quad (1.19)$$

and that the $(\mathbf{x}_i, \varepsilon_i)$'s are independent (across entities i), we have:

$$\sqrt{n}(\mathbf{b} - \beta) \xrightarrow{d} \mathcal{N}(0, \sigma^2 Q^{-1}). \quad (1.20)$$

Proof. Since $\mathbf{b} = \beta + \left(\frac{\mathbf{X}'\mathbf{X}}{n}\right)^{-1} \left(\frac{\mathbf{X}'\boldsymbol{\varepsilon}}{n}\right)$, we have: $\sqrt{n}(\mathbf{b} - \beta) = \left(\frac{\mathbf{X}'\mathbf{X}}{n}\right)^{-1} \left(\frac{1}{\sqrt{n}}\right) \mathbf{X}'\boldsymbol{\varepsilon}$. Since $f : A \rightarrow A^{-1}$ is a continuous function (for $A \neq \mathbf{0}$), $\text{plim}_{n \rightarrow \infty} \left(\frac{\mathbf{X}'\mathbf{X}}{n}\right)^{-1} = \mathbf{Q}^{-1}$ (see Prop. 8.12). Let us denote by V_i the vector $\mathbf{x}_i \varepsilon_i$. Because the $(\mathbf{x}_i, \varepsilon_i)$'s are independent, the V_i 's are independent as well. Their covariance matrix is $\sigma^2 \mathbb{E}(\mathbf{x}_i \mathbf{x}_i') = \sigma^2 Q$. Applying the multivariate central limit theorem on vectors V_i gives $\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \varepsilon_i\right) = \left(\frac{1}{\sqrt{n}}\right) \mathbf{X}'\boldsymbol{\varepsilon} \xrightarrow{d} \mathcal{N}(0, \sigma^2 Q)$. An application of Slutsky's theorem (Prop. 8.12) then leads to the results. \square

In practice, σ^2 is approximated by $s^2 = \frac{\mathbf{e}'\mathbf{e}}{n-K}$ (Eq. (1.10)) and \mathbf{Q}^{-1} by $\left(\frac{\mathbf{X}'\mathbf{X}}{n}\right)^{-1}$. That is, the covariance matrix of the estimator is approximated by:

$$\widehat{\text{Var}}(\mathbf{b}) = s^2 (\mathbf{X}'\mathbf{X})^{-1}. \quad (1.21)$$

Eqs. (1.19) and (1.20) respectively correspond to convergences in probability and in distribution (see Definitions 8.16 and 8.19, respectively).

1.3 Common pitfalls in linear regressions

1.3.1 Multicollinearity

Consider the model: $y_i = \beta_1 x_{i,1} + \beta_2 x_{i,2} + \varepsilon_i$, where all variables are zero-mean and $\text{Var}(\varepsilon_i) = \sigma^2$. We have:

$$\mathbf{X}'\mathbf{X} = \begin{bmatrix} \sum_i x_{i,1}^2 & \sum_i x_{i,1}x_{i,2} \\ \sum_i x_{i,1}x_{i,2} & \sum_i x_{i,2}^2 \end{bmatrix},$$

therefore:

$$(\mathbf{X}'\mathbf{X})^{-1} = \frac{1}{\sum_i x_{i,1}^2 \sum_i x_{i,2}^2 - (\sum_i x_{i,1}x_{i,2})^2} \begin{bmatrix} \sum_i x_{i,2}^2 & -\sum_i x_{i,1}x_{i,2} \\ -\sum_i x_{i,1}x_{i,2} & \sum_i x_{i,1}^2 \end{bmatrix}.$$

The inverse of the upper-left parameter of $(\mathbf{X}'\mathbf{X})^{-1}$ is:

$$\sum_i x_{i,1}^2 - \frac{(\sum_i x_{i,1}x_{i,2})^2}{\sum_i x_{i,2}^2} = \sum_i x_{i,1}^2 (1 - \text{correl}_{1,2}^2), \quad (1.22)$$

where $\text{correl}_{1,2}$ is the sample correlation between \mathbf{x}_1 and \mathbf{x}_2 .

Hence, the closer to one $\text{correl}_{1,2}$, the higher the variance of b_1 (recall that the variance of b_1 is the upper-left component of $\sigma^2(\mathbf{X}'\mathbf{X})^{-1}$). That is, if some of our regressors are close to a linear combination of the other ones, then the confidence intervals will tend to be wide, which typically reduces the power of the t-test (we tend to fail to reject the null hypothesis that the coefficients are different from zero).

1.3.2 Omitted variables

Consider the following model (the “True model”):

$$\mathbf{y} = \underbrace{\mathbf{X}_1}_{n \times K_1} \underbrace{\beta_1}_{K_1 \times 1} + \underbrace{\mathbf{X}_2}_{n \times K_2} \underbrace{\beta_2}_{K_2 \times 1} + \varepsilon$$

If one computes \mathbf{b}_1 by regressing \mathbf{y} on \mathbf{X}_1 only, one gets:

$$\mathbf{b}_1 = (\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1'\mathbf{y} = \beta_1 + (\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1'\mathbf{X}_2\beta_2 + (\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1'\varepsilon.$$

This results in the omitted-variable formula:

$$\mathbb{E}(\mathbf{b}_1|\mathbf{X}) = \beta_1 + \underbrace{(\mathbf{X}_1'\mathbf{X}_1)^{-1}(\mathbf{X}_1'\mathbf{X}_2)}_{K_1 \times K_2} \beta_2.$$

(Each column of $(\mathbf{X}_1'\mathbf{X}_1)^{-1}(\mathbf{X}_1'\mathbf{X}_2)$ are the OLS regressors obtained when regressing the columns of \mathbf{X}_2 on \mathbf{X}_1 .) Unless the variables included in \mathbf{X}_1 are orthogonal to those in \mathbf{X}_2 , we obtain a bias. A way to address this potential pitfall is to introduce “controls” in the specification.

Example 1.3. Let us use the California Test Score dataset (in the package `AER`). Assume we want to measure the effect of the students-to-teacher ratio (`str`) on student test scores (`testscr`). The following regressions show that the effect is lower when controls are added.

```
library(AER); data("CASchools")
CASchools$str <- CASchools$students/CASchools$teachers
CASchools$testscr <- .5 * (CASchools$math + CASchools$read)
eq1 <- lm(testscr~str,data=CASchools)
eq2 <- lm(testscr~str+lunch,data=CASchools)
eq3 <- lm(testscr~str+lunch+english,data=CASchools)
stargazer::stargazer(eq1,eq2,eq3,type="text",
                      no.space = TRUE,omit.stat=c("f","ser"))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               testscr
##                               (1)      (2)      (3)
## -----
## str          -2.280***  -1.117***  -0.998***
##              (0.480)    (0.240)    (0.239)
## lunch                -0.600***  -0.547***
##                   (0.017)    (0.022)
## english                        -0.122***
##                             (0.032)
## Constant      698.933***  702.911***  700.150***
##              (9.467)    (4.700)    (4.686)
## -----
## Observations    420        420        420
## R2              0.051      0.767      0.775
## Adjusted R2     0.049      0.766      0.773
## =====
## Note:          *p<0.1; **p<0.05; ***p<0.01
```

1.3.3 Irrelevant variable

Consider the *true model*:

$$\mathbf{y} = \mathbf{X}_1\beta_1 + \varepsilon,$$

while the *estimated model* is:

$$\mathbf{y} = \mathbf{X}_1\beta_1 + \mathbf{X}_2\beta_2 + \varepsilon$$

The estimates are unbiased. However, adding irrelevant explanatory variables increases the variance of the estimate of β_1 (compared to the case where one uses the correct explanatory variables). This is the case unless the correlation between \mathbf{X}_1 and \mathbf{X}_2 is null, see Eq. (1.22).

In other words, the estimator is *inefficient*, i.e., there exists an alternative consistent estimator whose variance is lower. The inefficiency problem can have serious consequences when testing hypotheses such as $H_0 : \beta_1 = 0$. Due to the loss of power, we might wrongly infer that the \mathbf{X}_1 variables are not “relevant” (*Type-II error, False Negative*).

1.4 Instrumental Variables

The conditional mean zero assumption (Hypothesis 1.2), according to which $\mathbb{E}(\varepsilon|\mathbf{X}) = 0$ —which implies in particular that \mathbf{x}_i and ε_i are uncorrelated—is sometimes not consistent with the considered economic framework. When it is the case, the parameters of interest may still be estimated consistently by resorting to instrumental variable techniques.

Consider the following model:

$$y_i = \mathbf{x}_i' \beta + \varepsilon_i, \quad \text{where } \mathbb{E}(\varepsilon_i) = 0 \text{ and } \mathbf{x}_i \not\perp \varepsilon_i. \quad (1.23)$$

Let us illustrate how this situation may result in biased OLS estimate. Consider for instance the situation where:

$$\mathbb{E}(\varepsilon_i) = 0 \quad \text{and} \quad \mathbb{E}(\varepsilon_i \mathbf{x}_i) = \gamma, \quad (1.24)$$

in which case we have $\mathbf{x}_i \not\perp \varepsilon_i$ (consistently with Eq. (1.23)).

By the law of large numbers, $\text{plim}_{n \rightarrow \infty} \mathbf{X}'\varepsilon/n = \gamma$. If $\mathbf{Q}_{xx} := \text{plim } \mathbf{X}'\mathbf{X}/n$, the OLS estimator is not consistent because

$$\mathbf{b} = \beta + (\mathbf{X}'\mathbf{X})^{-1} \mathbf{X}'\varepsilon \xrightarrow{p} \beta + \mathbf{Q}_{xx}^{-1} \gamma \neq \beta.$$

Let us now introduce the notion of instruments.

Definition 1.2 (Instrumental variables). The L -dimensional random variable \mathbf{z}_i is a valid set of instruments if:

- a. \mathbf{z}_i is correlated to \mathbf{x}_i ;
- b. we have $\mathbb{E}(\varepsilon|\mathbf{Z}) = 0$ and
- c. the orthogonal projections of the \mathbf{x}_i 's on the \mathbf{z}_i 's are not multicollinear.

Point c implies in particular that the dimension of \mathbf{z}_i has to be at least as large as that of \mathbf{x}_i . If \mathbf{z}_i is a valid set of instruments, we have:

$$\text{plim} \left(\frac{\mathbf{Z}'\mathbf{y}}{n} \right) = \text{plim} \left(\frac{\mathbf{Z}'(\mathbf{X}\beta + \varepsilon)}{n} \right) = \text{plim} \left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right) \beta.$$

Indeed, by the law of large numbers, $\frac{\mathbf{Z}'\varepsilon}{n} \xrightarrow{p} \mathbb{E}(\mathbf{z}_i\varepsilon_i) = 0$.

If $L = K$, the matrix $\frac{\mathbf{Z}'\mathbf{X}}{n}$ is of dimension $K \times K$ and we have:

$$\left[\text{plim} \left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right) \right]^{-1} \text{plim} \left(\frac{\mathbf{Z}'\mathbf{y}}{n} \right) = \beta.$$

By continuity of the inverse function (everywhere but at 0): $\left[\text{plim} \left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right) \right]^{-1} = \text{plim} \left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right)^{-1}$. The Slutsky Theorem (Prop. 8.12) further implies that:

$$\text{plim} \left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right)^{-1} \text{plim} \left(\frac{\mathbf{Z}'\mathbf{y}}{n} \right) = \text{plim} \left(\left(\frac{\mathbf{Z}'\mathbf{X}}{n} \right)^{-1} \frac{\mathbf{Z}'\mathbf{y}}{n} \right).$$

Hence \mathbf{b}_{iv} is consistent if it is defined by:

$$\boxed{\mathbf{b}_{iv} = (\mathbf{Z}'\mathbf{X})^{-1}\mathbf{Z}'\mathbf{y}.}$$

Proposition 1.12 (Asymptotic distribution of the IV estimator). *If \mathbf{z}_i is a L -dimensional random variable that constitutes a valid set of instruments (see Def. 1.2) and if $L = K$, then the asymptotic distribution of \mathbf{b}_{iv} is:*

$$\mathbf{b}_{iv} \xrightarrow{d} \mathcal{N} \left(\beta, \frac{\sigma^2}{n} [\mathbf{Q}_{xz}\mathbf{Q}_{zz}^{-1}\mathbf{Q}_{zx}]^{-1} \right)$$

where $\text{plim } \mathbf{Z}'\mathbf{Z}/n =: \mathbf{Q}_{zz}$, $\text{plim } \mathbf{Z}'\mathbf{X}/n =: \mathbf{Q}_{zx}$, $\text{plim } \mathbf{X}'\mathbf{Z}/n =: \mathbf{Q}_{xz}$.

Proof. The proof is very similar to that of Prop. 1.11, the starting point being that $\mathbf{b}_{iv} = \beta + (\mathbf{Z}'\mathbf{X})^{-1}\mathbf{Z}'\varepsilon$. \square

When $L = K$, we have:

$$[\mathbf{Q}_{xz}\mathbf{Q}_{zz}^{-1}\mathbf{Q}_{zx}]^{-1} = \mathbf{Q}_{zx}^{-1}\mathbf{Q}_{zz}\mathbf{Q}_{xz}^{-1}.$$

In practice, to estimate $\text{Var}(\mathbf{b}_{iv}) = \frac{\sigma^2}{n}\mathbf{Q}_{zx}^{-1}\mathbf{Q}_{zz}\mathbf{Q}_{xz}^{-1}$, we replace σ^2 by:

$$s_{iv}^2 = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{x}_i'\mathbf{b}_{iv})^2.$$

What about when $L > K$? In this case, we proceed as follows:

1. Regress \mathbf{X} on the space spanned by \mathbf{Z} and
2. Regress \mathbf{y} on the fitted values $\hat{\mathbf{X}} := \mathbf{Z}(\mathbf{Z}'\mathbf{Z})^{-1}\mathbf{Z}'\mathbf{X}$.

These two-step approach is called **Two-Stage Least Squares (2SLS)**. It results in:

$$\mathbf{b}_{iv} = [\mathbf{X}'\mathbf{Z}(\mathbf{Z}'\mathbf{Z})^{-1}\mathbf{Z}'\mathbf{X}]^{-1}\mathbf{X}'\mathbf{Z}(\mathbf{Z}'\mathbf{Z})^{-1}\mathbf{Z}'\mathbf{Y}. \quad (1.25)$$

In this case, Prop. 1.12 still holds, with \mathbf{b}_{iv} given by Eq. (1.25).

If the instruments do not properly satisfy Condition (a) in Def. 1.2 (i.e. if \mathbf{x}_i and \mathbf{z}_i are only loosely related), the instruments are said to be **weak** (see, e.g., Stock and Yogo (2005), available here or Andrews et al. (2019)). A simple standard way to test for weak instruments consist in looking at the F-statistic associated with the first stage of the estimation. The easier it is to reject the null hypothesis (large test statistic), the less weak—or the stronger—the instruments.

The Durbin-Wu-Hausman test (Durbin (1954), Wu (1973), Hausman (1978)) can be used to test if IV necessary. (IV techniques are required if $\text{plim}_{n \rightarrow \infty} \mathbf{X}'\varepsilon/n \neq 0$.) Hausman (1978) proposes a test of the efficiency of estimators. Under the null hypothesis two estimators, \mathbf{b}_0 and \mathbf{b}_1 , are consistent but \mathbf{b}_0 is (asymptotically) efficient relative to \mathbf{b}_1 . Under the alternative hypothesis, \mathbf{b}_1 (IV in the present case) remains consistent but not \mathbf{b}_0 (OLS in the present case). That is, when we reject the null hypothesis, it means that the OLS estimator is not consistent, potentially due to endogeneity issue.

The test statistic is:

$$H = (\mathbf{b}_1 - \mathbf{b}_0)' MPI(\text{Var}(\mathbf{b}_1) - \text{Var}(\mathbf{b}_0))(\mathbf{b}_1 - \mathbf{b}_0),$$

where MPI is the Moore-Penrose pseudo-inverse. Under the null hypothesis, $H \sim \chi^2(q)$, where q is the rank of $\text{Var}(\mathbf{b}_1) - \text{Var}(\mathbf{b}_0)$.

Example 1.4 (Estimation of price elasticity). See e.g. WHO and estimation of tobacco price elasticity of demand.

We want to estimate what is the effect on demand of an *exogenous increase* in prices of cigarettes (say).

The model is:

$$\begin{aligned} \underbrace{q_t^d}_{\text{log(demand)}} &= \alpha_0 + \alpha_1 \underbrace{\times p_t}_{\text{log(price)}} + \alpha_2 \underbrace{\times w_t}_{\text{income}} + \varepsilon_t^d \\ \underbrace{q_t^s}_{\text{log(supply)}} &= \gamma_0 + \gamma_1 \times p_t + \gamma_2 \underbrace{\times \mathbf{y}_t}_{\text{cost factors}} + \varepsilon_t^s, \end{aligned}$$

where $\mathbf{y}_t, w_t, \varepsilon_t^s \sim \mathcal{N}(0, \sigma_s^2)$ and $\varepsilon_t^d \sim \mathcal{N}(0, \sigma_d^2)$ are independent.

Equilibrium: $q_t^d = q_t^s$. This implies that prices are **endogenous**:

$$p_t = \frac{\alpha_0 + \alpha_2 w_t + \varepsilon_t^d - \gamma_0 - \gamma_2 \mathbf{y}_t - \varepsilon_t^s}{\gamma_1 - \alpha_1}.$$

In particular we have $\mathbb{E}(p_t \varepsilon_t^d) = \frac{\sigma_d^2}{\gamma_1 - \alpha_1} \neq 0 \Rightarrow$ Regressing by OLS q_t^d on p_t gives biased estimates (see Eq. (1.24)).

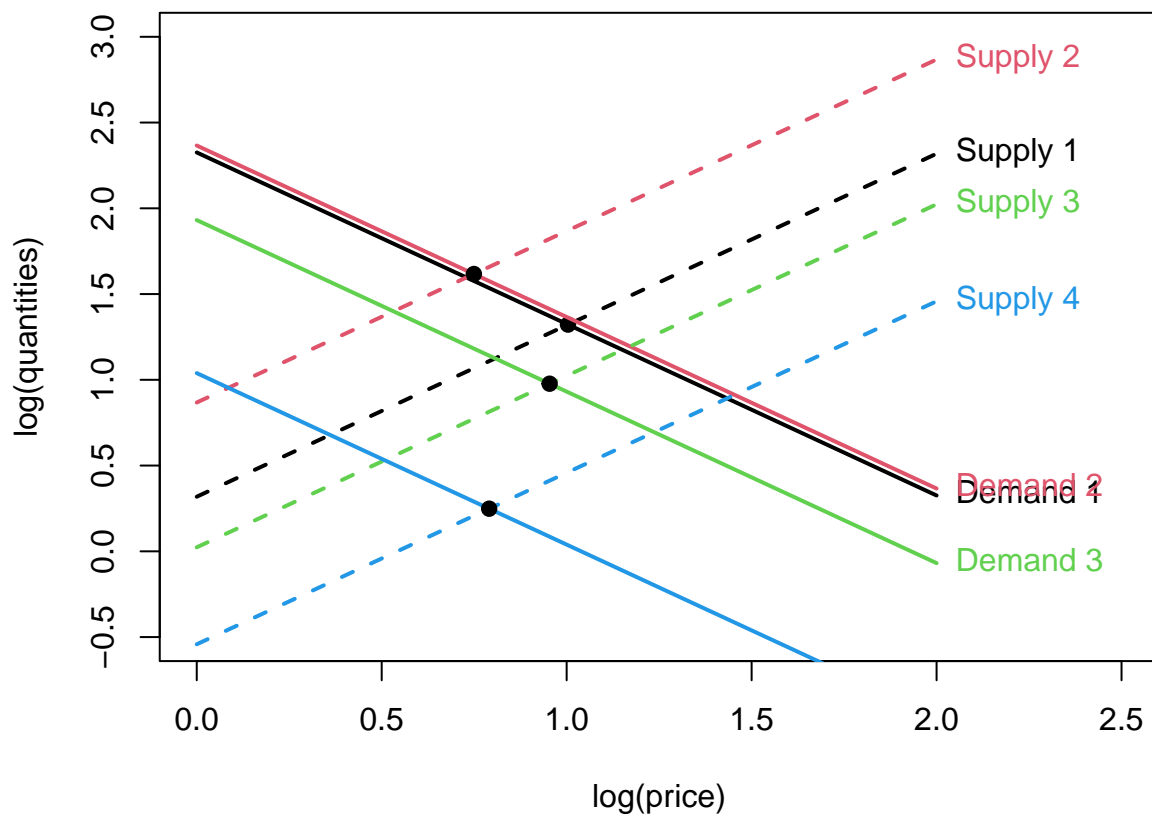


Figure 1.5: This figure illustrates the situation prevailing when estimating a price-elasticity (and the price is endogenous).

Let us use IV regressions to estimate the price elasticity of cigarette demand. For that purpose, we use the `CigarettesSW` dataset of package `AER` (these data are used by Stock and Watson (2003)). This panel dataset documents cigarette consumption for the 48 continental US States from 1985–1995. The instrument is the real tax on cigarettes arising from the state’s general sales tax. The rationale is that larger general sales tax drives cigarette prices up, but the general tax is not determined by other forces affecting ε_t^d .

```
data("CigarettesSW", package = "AER")
CigarettesSW$rprice <- with(CigarettesSW, price/cpi)
CigarettesSW$rincome <- with(CigarettesSW, income/population/cpi)
CigarettesSW$tdiff <- with(CigarettesSW, (taxs - tax)/cpi)

## model
eq.IV1 <- ivreg(log(packs) ~ log(rprice) + log(rincome) |
                log(rincome) + tdiff + I(tax/cpi),
                data = CigarettesSW, subset = year == "1995")
eq.IV2 <- ivreg(log(packs) ~ log(rprice) | tdiff,
                data = CigarettesSW, subset = year == "1995")
eq.no.IV <- lm(log(packs) ~ log(rprice) + log(rincome),
               data = CigarettesSW, subset = year == "1995")
stargazer::stargazer(eq.no.IV, eq.IV1, eq.IV2, type="text", no.space = TRUE,
                     omit.stat=c("f", "ser"))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               log(packs)
##                               OLS          instrumental
##                               (1)          (2)          (3)
##                               variable
## -----
## log(rprice)  -1.407*** -1.277*** -1.084***
##              (0.251)  (0.263)  (0.317)
## log(rincome)   0.344    0.280
##              (0.235)  (0.239)
## Constant     10.342***  9.895***  9.720***
##              (1.023)  (1.059)  (1.514)
## -----
## Observations    48        48        48
## R2              0.433     0.429     0.401
## Adjusted R2     0.408     0.404     0.388
## =====
## Note:           *p<0.1; **p<0.05; ***p<0.01
```



```
summary(eq.IV1,diagnostics = TRUE)$diagnostics
```

```
##              df1 df2  statistic      p-value
## Weak instruments    2  44 244.7337536 1.444054e-24
## Wu-Hausman         1  44   3.0678163 8.682505e-02
## Sargan              1  NA   0.3326221 5.641191e-01
```

The last three tests are interpreted as follows:

- Since the p-value of the first test is small, we reject the null hypothesis according to which the instrument is weak.
- The small p-value of the Wu-Hausman test implies that we reject the null hypothesis according to which the OLS estimates are consistent (at the 10% level only, though).
- No over-identification (misspecification) is detected by the Sargan test (large p-value).

Example 1.5 (Education and wage). In this example, we make use of another dataset proposed by Stock and Watson (2003), namely the `CollegeDistance` dataset.³ the objective is to estimate the effect of education on wages. Education choice is suspected to be an endogenous variable, which calls for an IV strategy. The instrumental variable is the distance to college (see, e.g., Dee (2004)).

```
library(sem)
data("CollegeDistance", package = "AER")
eq.1st.stage <- lm(education ~ urban + gender + ethnicity + unemp + distance,
                  data = CollegeDistance)
CollegeDistance$ed.pred<- predict(eq.1st.stage)
eq.2nd.stage <- lm(wage ~ urban + gender + ethnicity + unemp + ed.pred,
                  data = CollegeDistance)
eqOLS <- lm(wage ~ urban + gender + ethnicity + unemp + education,
            data=CollegeDistance)
eq2SLS <- ivreg(wage ~ urban + gender + ethnicity + unemp + education|
               urban + gender + ethnicity + unemp + distance,
               data=CollegeDistance)
stargazer::stargazer(eq.1st.stage,eq.2nd.stage,eq2SLS,eqOLS,
                    type="text",no.space = TRUE,omit.stat = c("f","ser"))
```

```
##
## =====
##                               Dependent variable:
##                               -----
```

³Cross-section data from the High School and Beyond survey conducted by the Department of Education in the 80s. The survey includes students from approximately 1,100 high schools.

##	education		wage	
##	OLS	OLS	instrumental	OLS
##			variable	
##	(1)	(2)	(3)	(4)
## -----				
## urbanyes	-0.092	0.046	0.046	0.070
##	(0.065)	(0.045)	(0.060)	(0.045)
## genderfemale	-0.025	-0.071*	-0.071	-0.085**
##	(0.052)	(0.037)	(0.050)	(0.037)
## ethnicityafam	-0.524***	-0.227***	-0.227**	-0.556***
##	(0.072)	(0.073)	(0.099)	(0.052)
## ethnicityhispanic	-0.275***	-0.351***	-0.351***	-0.544***
##	(0.068)	(0.057)	(0.077)	(0.049)
## unemp	0.010	0.139***	0.139***	0.133***
##	(0.010)	(0.007)	(0.009)	(0.007)
## distance	-0.087***			
##	(0.012)			
## ed.pred		0.647***		
##		(0.101)		
## education			0.647***	0.005
##			(0.136)	(0.010)
## Constant	14.061***	-0.359	-0.359	8.641***
##	(0.083)	(1.412)	(1.908)	(0.157)
## -----				
## Observations	4,739	4,739	4,739	4,739
## R2	0.023	0.117	-0.612	0.110
## Adjusted R2	0.022	0.116	-0.614	0.109
## =====				
## Note:			*p<0.1; **p<0.05; ***p<0.01	

1.5 General Regression Model (GRM) and robust covariance matrices

The statistical inference presented above relies on strong assumptions regarding the stochastic properties of the errors. Namely, they are assumed to be mutually uncorrelated (Hypothesis 1.4) and homoskedastic (Hypothesis 1.3).

The objective of this section is to present approaches aimed at adjusting the estimate of the covariance matrix of the OLS estimator ($((\mathbf{X}'\mathbf{X})^{-1}s^2$, see Eq. (1.21)), when the previous hypotheses do not hold.

1.5.1 Presentation of the General Regression Model (GRM)

It will prove useful to introduce the following notation:

$$\text{Var}(\varepsilon|\mathbf{X}) = \mathbb{E}(\varepsilon\varepsilon'|\mathbf{X}) = \Sigma. \quad (1.26)$$

Note that Eq. (1.26) is more general than Hypothesis 1.3 and 1.4 because the diagonal entries of Σ may be different (as opposed to under Hypothesis 1.3), and the non-diagonal entries of Σ can be non-null (as opposed to under Hypothesis 1.4).

Definition 1.3 (General Regression Model (GRM)). Hypothesis 1.1 and 1.2, together with Eq. (1.26), form the General Regression Model (GRM) framework.

Naturally, a regression model where Hypotheses 1.1 to 1.4 hold is a specific case of the GRM framework.

The GRM context notably encompasses situations of heteroskedasticity and autocorrelation:

- Heteroskedasticity:

$$\Sigma = \begin{bmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & \sigma_n^2 \end{bmatrix}. \quad (1.27)$$

- Autocorrelation:

$$\Sigma = \sigma^2 \begin{bmatrix} 1 & \rho_{2,1} & \dots & \rho_{n,1} \\ \rho_{2,1} & 1 & & \vdots \\ \vdots & & \ddots & \rho_{n,n-1} \\ \rho_{n,1} & \rho_{n,2} & \dots & 1 \end{bmatrix}. \quad (1.28)$$

Example 1.6 (Auto-regressive processes). Autocorrelation is common in time-series contexts (see Section ??). In a time-series context, subscript i refers to a date.

Assume for instance that:

$$y_i = \mathbf{x}_i' \beta + \varepsilon_i \quad (1.29)$$

with

$$\varepsilon_i = \rho \varepsilon_{i-1} + v_i, \quad v_i \sim \mathcal{N}(0, \sigma_v^2). \quad (1.30)$$

In this case, we are in the GRM context, with:

$$\Sigma = \frac{\sigma_v^2}{1 - \rho^2} \begin{bmatrix} 1 & \rho & \dots & \rho^{n-1} \\ \rho & 1 & & \vdots \\ \vdots & & \ddots & \rho \\ \rho^{n-1} & \rho^{n-2} & \dots & 1 \end{bmatrix}. \quad (1.31)$$

In some cases—in particular when one assumes a parametric formulation for Σ —one can determine a better (more accurate) estimator than the OLS one. This approach is called Generalized Least Squares (GLS), which we present below.

1.5.2 Generalized Least Squares

Assume Σ is known (“feasible GLS”). Because Σ is symmetric positive, it admits a spectral decomposition of the form $\Sigma = \mathbf{C}\Lambda\mathbf{C}'$, where \mathbf{C} is an orthogonal matrix (i.e. $\mathbf{C}\mathbf{C}' = Id$) and Λ is a diagonal matrix (the diagonal entries are the eigenvalues of Σ).

We have $\Sigma = (\mathbf{P}\mathbf{P}')^{-1}$ with $\mathbf{P} = \mathbf{C}\Lambda^{-1/2}$. (We also have $\mathbf{P} = \Sigma^{-1/2}$.) Consider the transformed model:

$$\mathbf{P}'\mathbf{y} = \mathbf{P}'\mathbf{X}\beta + \mathbf{P}'\varepsilon \quad \text{or} \quad \mathbf{y}^* = \mathbf{X}^*\beta + \varepsilon^*.$$

The variance of ε^* is the identity matrix Id . In the transformed model, OLS is BLUE (Gauss-Markow Theorem 1.1).

The **Generalized least squares** estimator of β is:

$$\boxed{\mathbf{b}_{GLS} = (\mathbf{X}'\Sigma^{-1}\mathbf{X})^{-1}\mathbf{X}'\Sigma^{-1}\mathbf{y}.} \quad (1.32)$$

We have:

$$\mathbb{V}ar(\mathbf{b}_{GLS}|\mathbf{X}) = (\mathbf{X}'\Sigma^{-1}\mathbf{X})^{-1}.$$

However, in general, Σ is unknown. The GLS estimator is then said to be *infeasible*. Some structure is required. Assume Σ admits a parametric form $\Sigma(\theta)$. The estimation becomes *feasible* (FGLS) if one replaces $\Sigma(\theta)$ by $\Sigma(\hat{\theta})$, where $\hat{\theta}$ is a consistent estimator of θ . In that case, the FGLS is asymptotically efficient (see Example 1.7).

When Σ has no obvious structure: the OLS (or IV) is the only estimator available. Under regularity assumptions, it remains unbiased, consistent, and asymptotically normally distributed, but not efficient. Standard inference procedures are no longer appropriate.

Example 1.7 (GLS in the auto-correlation case). Consider the case presented in Example 1.6. Because the OLS estimate \mathbf{b} of β is consistent, the estimates e_i of the ε_i ’s also are. Consistent estimators of ρ and σ_v are then obtained by regressing the e_i ’s on the e_{i-1} ’s. Using these estimates in Eq. (1.31) provides a consistent estimate of Σ . Applying these steps recursively gives an efficient estimator of β (Cochrane and Orcutt (1949)).

1.5.3 Asymptotic properties of the OLS estimator in the GRM framework

Since $\mathbf{b} = \beta + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\varepsilon$ and $\mathbb{V}ar(\varepsilon|\mathbf{X}) = \Sigma$, we have:

$$\mathbb{V}ar(\mathbf{b}|\mathbf{X}) = \frac{1}{n} \left(\frac{1}{n}\mathbf{X}'\mathbf{X} \right)^{-1} \left(\frac{1}{n}\mathbf{X}'\Sigma\mathbf{X} \right) \left(\frac{1}{n}\mathbf{X}'\mathbf{X} \right)^{-1}. \quad (1.33)$$

Therefore, the conditional covariance matrix of the OLS estimator is not $\sigma^2(\mathbf{X}'\mathbf{X})^{-1}$ any longer, and using $s^2(\mathbf{X}'\mathbf{X})^{-1}$ for inference may be misleading. Below, we will see how to construct appropriate estimates of the covariance matrix of \mathbf{b} . Before that, let us prove that the OLS estimator remains consistent in the GRM framework.

Proposition 1.13 (Consistency of the OLS estimator in the GRM framework). *If $\text{plim} (\mathbf{X}'\mathbf{X}/n)$ and $\text{plim} (\mathbf{X}'\Sigma\mathbf{X}/n)$ are finite positive definite matrices, then $\text{plim} (\mathbf{b}) = \beta$.*

Proof. We have $\text{Var}(\mathbf{b}) = \mathbb{E}[\text{Var}(\mathbf{b}|\mathbf{X})] + \text{Var}[\mathbb{E}(\mathbf{b}|\mathbf{X})]$. Since $\mathbb{E}(\mathbf{b}|\mathbf{X}) = \beta$, $\text{Var}[\mathbb{E}(\mathbf{b}|\mathbf{X})] = 0$. Eq. (1.33) implies that $\text{Var}(\mathbf{b}|\mathbf{X}) \rightarrow 0$. Hence \mathbf{b} converges in mean square, and therefore in probability (see Prop. 8.13). \square

Prop. 1.14 gives the asymptotic distribution of the OLS estimator in the GRM framework.

Proposition 1.14 (Asymptotic distribution of the OLS estimator in the GRM framework). *If $Q_{xx} = \text{plim} (\mathbf{X}'\mathbf{X}/n)$ and $Q_{x\Sigma x} = \text{plim} (\mathbf{X}'\Sigma\mathbf{X}/n)$ are finite positive definite matrices, then:*

$$\sqrt{n}(\mathbf{b} - \beta) \xrightarrow{d} \mathcal{N}(0, Q_{xx}^{-1} Q_{x\Sigma x} Q_{xx}^{-1}).$$

The IV estimator also features a normal asymptotic distribution:

Proposition 1.15 (Asymptotic distribution of the IV estimator in the GRM framework). *If regressors and IV variables are “well-behaved”, then:*

$$\mathbf{b}_{iv} \overset{a}{\sim} \mathcal{N}(\beta, \mathbf{V}_{iv}),$$

where

$$\mathbf{V}_{iv} = \frac{1}{n}(\mathbf{Q}^*) \text{plim} \left(\frac{1}{n} \mathbf{Z}'\Sigma\mathbf{Z} \right) (\mathbf{Q}^*)',$$

with

$$\mathbf{Q}^* = [\mathbf{Q}_{xz} \mathbf{Q}_{zz}^{-1} \mathbf{Q}_{zx}]^{-1} \mathbf{Q}_{xz} \mathbf{Q}_{zz}^{-1}.$$

For practical purposes, one needs to have estimates of Σ in Props. 1.14 or 1.15. The complication comes from the fact that Σ is of dimension $n \times n$, and its estimation—based on a sample of length n —is therefore infeasible in the general case. Notwithstanding, looking at Eq. (1.33), it appears that one can focus on the estimation of $Q_{x\Sigma x} = \text{plim} (\mathbf{X}'\Sigma\mathbf{X}/n)$ (or $\text{plim} (\frac{1}{n} \mathbf{Z}'\Sigma\mathbf{Z})$ in the IV case). This matrix being of dimension $K \times K$, its estimation is easier.

We have:

$$\frac{1}{n} \mathbf{X}'\Sigma\mathbf{X} = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^n \sigma_{i,j} \mathbf{x}_i \mathbf{x}_j'. \quad (1.34)$$

The so-called **robust covariance matrices** are estimates of the previous matrix. Their computation is based on the fact that if \mathbf{b} is consistent, then the e_i 's are consistent estimators of the ε_i 's.

In the following sections (1.5.4 and 1.5.5), we present two types of robust covariance matrices.

1.5.4 HAC-robust covariance matrices

When only heteroskedasticity prevails, i.e., when matrix Σ is as in Eq. (1.27), then one can use the formula proposed by White (1980) to estimate $\frac{1}{n}\mathbf{X}'\Sigma\mathbf{X}$ (see Example 1.8). When the residuals feature both heteroskedasticity and auto-correlation, then one can use the Newey and West (1987) approach (see Example 1.9).

Example 1.8 (Heteroskedasticity). This is the case of Eq. (1.27). We have $\sigma_{i,j} = 0$ for $i \neq j$. Hence, in this case, we then need to estimate $\frac{1}{n} \sum_{i=1}^n \sigma_i^2 \mathbf{x}_i \mathbf{x}_i'$. White (1980) has shown that, under general conditions:

$$\text{plim} \left(\frac{1}{n} \sum_{i=1}^n \sigma_i^2 \mathbf{x}_i \mathbf{x}_i' \right) = \text{plim} \left(\frac{1}{n} \sum_{i=1}^n e_i^2 \mathbf{x}_i \mathbf{x}_i' \right). \quad (1.35)$$

The estimator of $\frac{1}{n}\mathbf{X}'\Sigma\mathbf{X}$ therefore is:

$$M_{HC0} = \frac{1}{n} \mathbf{X}' \begin{bmatrix} e_1^2 & 0 & \dots & 0 \\ 0 & e_2^2 & & \\ \vdots & & \ddots & 0 \\ 0 & \dots & 0 & e_n^2 \end{bmatrix} \mathbf{X}. \quad (1.36)$$

where the e_i are the OLS residuals of the regression. The previous estimator is often called **HC0**. The **HC1** estimator, due to MacKinnon and White (1985), is obtained by applying an adjustment factor $n/(n-K)$ for the number of degrees of freedom (as in Prop. 1.6). That is:

$$M_{HC1} = \frac{n}{n-K} M_{HC0}. \quad (1.37)$$

We can illustrate the influence of heteroskedasticity using simulations. Consider the following model:

$$y_i = x_i + \varepsilon_i, \quad \varepsilon_i \sim \mathcal{N}(0, x_i^2),$$

where the x_i 's are i.i.d. $t(6)$.

Here is a simulated sample ($n = 200$) of this model:

```
n <- 200
x <- rt(n,df=6)
y <- x + x*rnorm(n)
par(plt=c(.1,.95,.1,.95))
plot(x,y,pch=19)
```

We simulate 1000 samples of the same model with $n = 200$. For each sample, we compute the OLS estimate of β ($= 1$). For each of the 1000 OLS estimations, we employ (a) the standard OLS variance formula ($s^2(\mathbf{X}'\mathbf{X})^{-1}$) and (b) the White formula to estimate the variance of b . For each formula, we compute the average of the 1000 resulting standard deviations and compare these with the standard deviation of the 1000 OLS estimate of β .

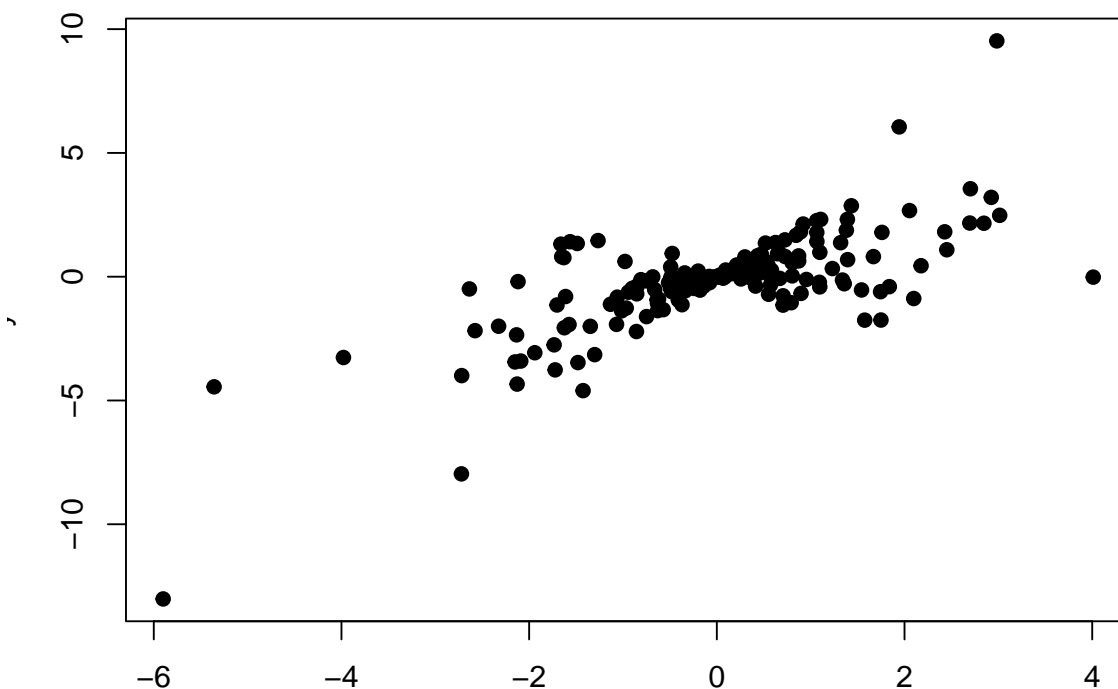


Figure 1.6: Situation of heteroskedasticity. The model is $y_i = x_i + \varepsilon_i$, $\varepsilon_i \sim \mathcal{N}(0, x_i^2)$, where the x_i 's are i.i.d. $t(6)$.

```
n <- 200 # sample size
N <- 1000 # number of simulated samples
XX <- matrix(rt(n*N,df=6),n,N)
YY <- matrix(XX + XX*rnorm(n),n,N)
all_b      <- NULL;all_V_OLS  <- NULL;all_V_White <- NULL
for(j in 1:N){
  Y <- matrix(YY[,j],ncol=1)
  X <- matrix(XX[,j],ncol=1)
  b <- solve(t(X)%*%X) %*% t(X)%*%Y
  e <- Y - X %*% b
  S <- 1/n * t(X) %*% diag(c(e^2)) %*% X
  V_OLS <- solve(t(X)%*%X) * var(e)
  V_White <- 1/n * (solve(1/n*t(X)%*%X)) %*% S %*% (solve(1/n*t(X)%*%X))
  all_b      <- c(all_b,b)
  all_V_OLS  <- c(all_V_OLS,V_OLS)
  all_V_White <- c(all_V_White,V_White)
}
c(sd(all_b),mean(sqrt(all_V_OLS)),mean(sqrt(all_V_White)))
```

```
## [1] 0.14024423 0.06748804 0.13973431
```

The results show that the White formula yields, on average, an estimated standard deviation that is much closer to the “true” value than the standard OLS formula. The latter

underestimate the standard deviation of b .

In the following example, we regress GDP growth rates from the Jordà et al. (2017) database on a systemic financial crisis dummy. We compute the HC0- and HC1-based standard deviations of the parameter estimate, and compare it to the one based on the standard OLS formula. The adjusted standard deviations are close to the one provided by the non-adjusted OLS formula.

```
library(lmtest)
library(sandwich)
nT <- dim(JST)[1]
JST$growth <- NaN
JST$growth[2:nT] <- log(JST$rgdpbarro[2:nT]/JST$rgdpbarro[1:(nT-1)])
JST.red <- subset(JST, year > 1950)
JST.red$iso <- as.factor(JST.red$iso)
JST.red$year <- as.factor(JST.red$year)
eq <- lm(growth ~ crisisJST + iso + year, data = JST.red)
vcovHC0 <- vcovHC(eq, type = "HC0")
vcovHC1 <- vcovHC(eq, type = "HC1")
stargazer::stargazer(eq, eq, eq, type = "text",
                      column.labels = c("No HAC", "HC0", "HC1"),
                      omit = c("iso", "year"), no.space = TRUE, keep.stat = "n",
                      se = list(NULL, sqrt(diag(vcovHC0)), sqrt(diag(vcovHC1))))
```

```
##
## =====
##               Dependent variable:
##      -----
##               growth
##           No HAC      HC0      HC1
##           (1)        (2)      (3)
## -----
## crisisJST    -0.015*** -0.015*** -0.015***
##              (0.005)  (0.005)  (0.006)
## Constant     0.042***  0.042***  0.042***
##              (0.005)  (0.007)  (0.007)
## -----
## Observations  1,258    1,258    1,258
## =====
## Note:          *p<0.1; **p<0.05; ***p<0.01
```

Example 1.9 (Heteroskedasticity and Autocorrelation (HAC)). Newey and West (1987) have proposed a formula to address both heteroskedasticity and auto-correlation of the residuals (Eqs. (1.27) and (1.28)). They show that, if the correlation between terms i and j gets

sufficiently small when $|i - j|$ increases:

$$\begin{aligned} \text{plim} \left(\frac{1}{n} \sum_{i=1}^n \sum_{j=1}^n \sigma_{i,j} \mathbf{x}_i \mathbf{x}_j' \right) &\approx \\ \text{plim} \left(\frac{1}{n} \sum_{t=1}^n e_t^2 \mathbf{x}_t \mathbf{x}_t' + \frac{1}{n} \sum_{\ell=1}^L \sum_{t=\ell+1}^n w_\ell e_t e_{t-\ell} (\mathbf{x}_t \mathbf{x}_{t-\ell}' + \mathbf{x}_{t-\ell} \mathbf{x}_t') \right), \end{aligned} \quad (1.38)$$

where $w_\ell = 1 - \ell/(L + 1)$ (with L large).

Let us illustrate the influence of autocorrelation using simulations. We consider the following model:

$$y_i = x_i + \varepsilon_i, \quad \varepsilon_i \sim \mathcal{N}(0, x_i^2), \quad (1.39)$$

where the x_i 's and the ε_i 's are such that:

$$x_i = 0.8x_{i-1} + u_i \quad \text{and} \quad \varepsilon_i = 0.8\varepsilon_{i-1} + v_i, \quad (1.40)$$

where the u_i 's and the v_i 's are i.i.d. $\mathcal{N}(0, 1)$.

We simulate 500 samples of the same model with $n = 200$. For each sample, we compute the OLS estimate of β ($=1$). For each of the 1000 OLS estimations, we employ (a) the standard OLS variance formula ($s^2(\mathbf{X}'\mathbf{X})^{-1}$), (b) the White formula, and (c) the Newey-West formula to estimate the variance of b . For each formula, we compute the average of the 500 resulting standard deviations and compare these with the standard deviation of the 500 OLS estimate of β .

```
library(AEC)
n <- 100 # sample length
nb.sim <- 500 # number of simulated samples
all.b <- NULL; all.OLS.stdv.b <- NULL
all.Whi.stdv.b <- NULL; all.NW.stdv.b <- NULL
for(i in 1:nb.sim){
  eps <- rnorm(n); x <- rnorm(n)
  for(i in 2:n){
    eps[i] <- eps[i] + .8*eps[i-1]
    x[i] <- x[i] + .8*x[i-1]
  }
  y <- x + eps
  eq <- lm(y~x)
  all.b <- c(all.b, eq$coefficients[2])
  all.OLS.stdv.b <- c(all.OLS.stdv.b, summary(eq)$coefficients[2,2])
  X <- cbind(rep(1,n), x)
  XX <- t(X) %*% X; XX_1 <- solve(XX)
  E2 <- diag(eq$residuals^2)
  White.V <- XX_1 %*% (t(X) %*% E2 %*% X) %*% XX_1
  all.Whi.stdv.b <- c(all.Whi.stdv.b, sqrt(White.V[2,2]))
}
```

```

# HAC:
U <- X * cbind(eq$residuals,eq$residuals)
XSigmaX <- NW.LongRunVariance(U,5)
NW.V <- 1/n * (n*XX_1) %*% XSigmaX %*% (n*XX_1)
all.NW.stdv.b <- c(all.NW.stdv.b,sqrt(NW.V[2,2]))
}
cbind(sd(all.b),mean(all.OLS.stdv.b),
      mean(all.Whi.stdv.b),mean(all.NW.stdv.b))

```

```

##           [,1]      [,2]      [,3]      [,4]
## [1,] 0.201172 0.1013048 0.0962689 0.146974

```

The results show that the Newey-West formula yields, on average, an estimated standard deviation that is closer to the “true” value than the standard OLS formula. The latter underestimate the standard deviation of b .

What precedes suggest that, when the residuals feature autocorrelation, it is important to use appropriately adjusted covariance matrices to make statistical inference. How to detect autocorrelation in residuals? A popular test has been proposed by Durbin and Watson (1950) and Durbin and Watson (1951). The Durbin-Watson test statistic is:

$$DW = \frac{\sum_{i=2}^n (e_i - e_{i-1})^2}{\sum_{i=1}^n e_i^2} = 2(1 - r) - \underbrace{\frac{e_1^2 + e_n^2}{\sum_{i=1}^n e_i^2}}_{\xrightarrow{p} 0},$$

where r is the slope in the regression of the e_i 's on the e_{i-1} 's, i.e.:

$$r = \frac{\sum_{i=2}^n e_i e_{i-1}}{\sum_{i=1}^{n-1} e_i^2}.$$

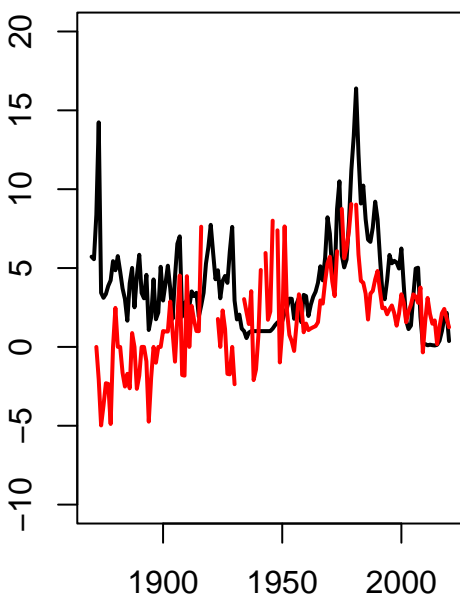
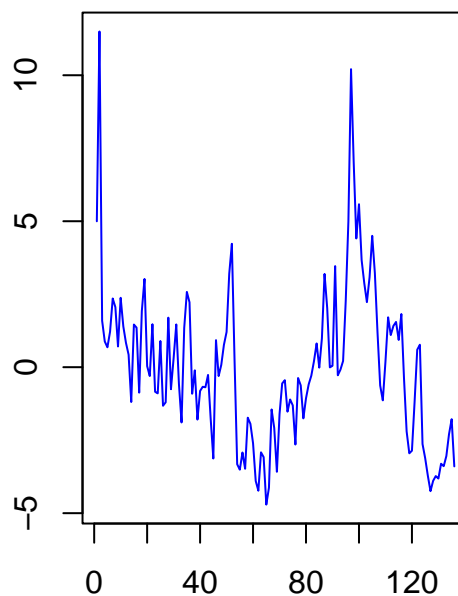
(r is a consistent estimator of $\text{Cor}(\varepsilon_i, \varepsilon_{i-1})$, i.e. ρ in Eq. (1.30).)

The one-sided test for $H_0: \rho = 0$ against $H_1: \rho > 0$ is carried out by comparing DW to values $d_L(T, K)$ and $d_U(T, K)$:

$$\begin{cases} \text{If } DW < d_L, & \text{the null hypothesis is rejected;} \\ \text{if } DW > d_U, & \text{the hypothesis is not rejected;} \\ \text{If } d_L \leq DW \leq d_U, & \text{no conclusion is drawn.} \end{cases}$$

Example 1.10 (Durbin-Watson test). We regress the short-term nominal US interest rate on inflation. We then employ the Durbin-Watson test to see whether the residuals are auto-correlated (which is quite obviously the case).

```
library(car)
data <- subset(JST,iso=="USA");T <- dim(data)[1]
data$infl <- c(NaN,100*log(data$cpi[2:T]/data$cpi[1:(T-1)]))
data$infl[(data$infl< -5)|(data$infl>10)] <- NaN
par(mfrow=c(1,2))
plot(data$year,data$stir,ylim=c(-10,20),type="l",lwd=2,xlab="",
      ylab="",main="Nominal rate and inflation")
lines(data$year,data$infl,col="red",lwd=2)
eq <- lm(stir~infl,data=data)
plot(eq$residuals,type="l",col="blue",main="Residuals",xlab="",ylab="")
```

Nominal rate and inflation**Residuals**

```
durbinWatsonTest(eq)
```

```
## lag Autocorrelation D-W Statistic p-value
## 1 0.7321902 0.4984178 0
## Alternative hypothesis: rho != 0
```

1.5.5 Cluster-robust covariance matrices

The present section is based on MacKinnon et al. (2022); another useful reference is Cameron and Miller (2014). We will see how one can approximate $Q_{x\Sigma x} = \text{plim} (\mathbf{X}'\Sigma\mathbf{X}/n)$ (see Prop. 1.14) when the dataset can be decomposed into *clusters*. These clusters constitute a partition of the sample, and they are such that the error terms may be correlated within a given cluster, but not across different clusters. A cluster may, e.g., gathers entities from a given geographical area, from the same industry, or same age cohort.

The OLS estimator satisfies:

$$\mathbf{b} = \beta + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\varepsilon. \quad (1.41)$$

Consider a set $\{n_1, n_2, \dots, n_G\}$ s.t. $n = \sum_g n_g$, on which is based the following decomposition of \mathbf{X} :

$$\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \\ \vdots \\ \mathbf{X}_G \end{bmatrix}.$$

With these notations, Eq. (1.41) rewrites:

$$\mathbf{b} - \beta = \left(\sum_{g=1}^G \mathbf{X}'_g \mathbf{X}_g \right)^{-1} \sum_{g=1}^G \mathbf{s}_g, \quad (1.42)$$

where

$$\mathbf{s}_g = \mathbf{X}'_g \varepsilon_g \quad (1.43)$$

denotes the score vector (of dimension $K \times 1$) associated with the g^{th} cluster.

If the model is correctly specified then $\mathbb{E}(\mathbf{s}_g) = 0$ for all clusters g . Note that Eq. (1.42) is valid for any partition of $\{1, \dots, n\}$. Dividing the sample into clusters becomes meaningful if we further assume that the following hypothesis holds:

Hypothesis 1.6 (Clusters). We have:

$$(i) \mathbb{E}(\mathbf{s}_g \mathbf{s}'_g) = \Sigma_g, \quad (ii) \mathbb{E}(\mathbf{s}_g \mathbf{s}'_q) = 0, \quad g \neq q,$$

where \mathbf{s}_g is defined in Eq. (1.43).

The real assumption here is (ii); the first one simply gives a notation for the covariance matrix of the score associated with the g^{th} cluster. Remark that these covariance matrices can differ across clusters. That is, *cluster-based inference is robust against both heteroskedasticity and intra-cluster dependence without imposing any restrictions on the (unknown) form of either of them*.

Naturally, matrix Σ_g depends on the covariance structure of the ε 's. In particular, if $\Omega_g = \mathbb{E}(\varepsilon_g \varepsilon'_g | \mathbf{X}_g)$, then we have $\Sigma_g = \mathbb{E}(\mathbf{X}'_g \Omega_g \mathbf{X}_g)$.

Under Hypothesis 1.6, it comes that the conditional covariance matrix of \mathbf{b} is:

$$(\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{g=1}^G \Sigma_g \right) (\mathbf{X}'\mathbf{X})^{-1} \quad (1.44)$$

Let us denote by $\varepsilon_{g,i}$ the error associated with the i^{th} component of vector ε_g . Consider the special case where $\mathbb{E}(\varepsilon_{g,i} \varepsilon_{g,j} | \mathbf{X}_g) = \sigma^2 \mathbb{I}_{\{i=j\}}$, then Eq. (1.44) gives the standard expression $\sigma^2 (\mathbf{X}'\mathbf{X})^{-1}$ (see Eq. (1.9)).

If we have $\mathbb{E}(\varepsilon_{gi}\varepsilon_{gj}|\mathbf{X}_g) = \sigma_{gi}^2 \mathbb{I}_{\{i=j\}}$, then we fall in the case addressed by the White formula (see Example 1.8). That is, in this case, the conditional covariance matrix of \mathbf{b} is:

$$(\mathbf{X}'\mathbf{X})^{-1} \left(\mathbf{X}' \begin{bmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & \sigma_n^2 \end{bmatrix} \mathbf{X} \right) (\mathbf{X}'\mathbf{X})^{-1}.$$

As in White (1980), the natural way to approach the conditional covariance given in Eq. (1.44) consists in replacing the Σ_g matrices by their sample equivalent, i.e. $\widehat{\Sigma}_g = \mathbf{X}'_g \mathbf{e}_g \mathbf{e}'_g \mathbf{X}_g$. Adding corrections for the number of degrees of freedom, this leads to the following estimate of the covariance matrix of \mathbf{b} :

$$\frac{G(n-1)}{(G-1)(n-K)} (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{g=1}^G \widehat{\Sigma}_g \right) (\mathbf{X}'\mathbf{X})^{-1}. \quad (1.45)$$

The previous estimate is CRCV1 in MacKinnon et al. (2022). Note that we indeed find the White-MacKinnon estimator (Eq. (1.37)) when $G = n$.

Remark that if there was only one cluster ($G = 1$), and neglecting the degree-of-freedom correction, we would have:

$$(\mathbf{X}'\mathbf{X})^{-1} (\mathbf{X}'\mathbf{e}\mathbf{e}'\mathbf{X}) (\mathbf{X}'\mathbf{X})^{-1} = 0$$

because $\mathbf{X}'\mathbf{e} = 0$. Hence, having large clusters does not necessarily increase variance.

Often, when working with panel data (see Chapter 2), we want to cluster in different dimensions. A typical case is when the data are indexed by both individuals (i) and time (t). In that case, we may indeed suspect that: (a) the residuals are correlated across clusters of dates (e.g., with monthly data, a cluster may be one year) and (b) the residuals are correlated across clusters of individuals (e.g., with data at the county level a cluster may be a state). In this case, one can employ **two-way clustering**.

Formally, consider two distinct partitions of the data: one through index g , with $g \in \{1, \dots, G\}$, and the other through index h , with $h \in \{1, \dots, H\}$. Accordingly, we denote by $\mathbf{X}_{g,h}$ the submatrix of \mathbf{X} that contains the explanatory variables corresponding to clusters g and h (e.g., the firms of a given country g at a given date h). We also denote by $\mathbf{X}_{g,\bullet}$ (respectively $\mathbf{X}_{\bullet,h}$) the submatrix of \mathbf{X} containing all explanatory variables pertaining to cluster g , for all possible values of h (resp. to cluster h , for all possible values of g).

We will make the following assumption:

Hypothesis 1.7 (Two-way clusters). We have:

$$\begin{aligned} \mathbb{E}(\mathbf{s}_{g,\bullet} \mathbf{s}'_{g,\bullet}) &= \Sigma_g, & \mathbb{E}(\mathbf{s}_{\bullet,h} \mathbf{s}'_{\bullet,h}) &= \Sigma_h^*, & \mathbb{E}(\mathbf{s}_{g,h} \mathbf{s}'_{g,h}) &= \Sigma_{g,h}, \\ \mathbb{E}(\mathbf{s}_{g,h} \mathbf{s}'_{q,k}) &= 0 \text{ if } g \neq q \text{ and } h \neq k. \end{aligned}$$

Proposition 1.16 (Covariance of scores in the two-way-cluster setup). *Under this assumption, the matrix of covariance of the scores is given by:*

$$\Sigma = \sum_{g=1}^G \Sigma_g + \sum_{h=1}^H \Sigma_h^* - \sum_{g=1}^G \sum_{h=1}^H \Sigma_{g,h}.$$

(The last term on the right-hand side must be subtracted in order to avoid double counting.)

Proof. We have:

$$\begin{aligned} \Sigma &= \sum_{g=1}^G \sum_{q=1}^G \sum_{h=1}^H \sum_{k=1}^H \mathbf{s}_{g,h} \mathbf{s}'_{q,k} \\ &= \sum_{g=1}^G \underbrace{\left(\sum_{h=1}^H \sum_{k=1}^H \mathbf{s}_{g,h} \mathbf{s}'_{g,k} \right)}_{=\Sigma_g} + \sum_{h=1}^H \underbrace{\left(\sum_{g=1}^G \sum_{q=1}^G \mathbf{s}_{g,h} \mathbf{s}'_{q,h} \right)}_{=\Sigma_h^*} - \sum_{g=1}^G \sum_{h=1}^H \mathbf{s}_{g,h} \mathbf{s}'_{g,h}, \end{aligned}$$

which gives the result. \square

The asymptotic theory can be based on two different approaches: (i) large number of clusters (common case), and (ii) fixed number of clusters but large number of observations in each cluster (see Subsections 4.1 and 4.2 in MacKinnon et al. (2022)). The more variable the N_g 's (clusters' sizes are heterogeneous in terms of size), the less reliable asymptotic inference based on Eq. (1.45), especially when a very few clusters are unusually large, or when the distribution of the data is heavy-tailed. These issues are somehow mitigated when the clusters have an approximate factor structure.

In practice, Σ is estimated by:

$$\widehat{\Sigma} = \sum_{g=1}^G \widehat{\mathbf{s}}_{g,\bullet} \widehat{\mathbf{s}}'_{g,\bullet} + \sum_{h=1}^H \widehat{\mathbf{s}}_{\bullet,h} \widehat{\mathbf{s}}'_{\bullet,h} - \sum_{g=1}^G \sum_{h=1}^H \widehat{\mathbf{s}}_{g,h} \widehat{\mathbf{s}}'_{g,h},$$

and we use:

$$\widehat{\mathbb{V}ar}(\mathbf{b}) = (\mathbf{X}'\mathbf{X})^{-1} \widehat{\Sigma} (\mathbf{X}'\mathbf{X})^{-1}.$$

As an alternative to the asymptotic approximation to the distribution of a statistic of interest, one can resort to bootstrap approximation (see Section 5 of MacKinnon et al. (2022)). In R, the package `fwildclusterboot` allows to implement such approaches.⁴

Let us come back to the analysis of the effect of systemic financial crises on GDP growth. Clustering the data at the country level and, further, at both the country and time levels gives the following:

⁴See, e.g., this tutorial by Alexander Fischer.

```
eq <- lm(growth~crisisJST+iso+year,data=JST.red)
vcov1 <- vcovHC(eq, type = "HC1")
vcov2 <- vcovCL(eq, cluster = JST.red[, c("iso")])
vcov3 <- vcovCL(eq, cluster = JST.red[, c("iso","year")])
stargazer::stargazer(eq, eq, eq, eq,type = "text",
                      column.labels = c("No HAC", "Heterosk.",
                                         "1-way Clust.", "1-way Clust."),
                      omit = c("iso","year"),no.space = TRUE,keep.stat = "n",
                      se = list(NULL,sqrt(diag(vcov1)),
                                sqrt(diag(vcov2)),sqrt(diag(vcov3)))))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               growth
##                               No HAC   Heterosk. 1-way Clust. 1-way Clust.
##                               (1)      (2)      (3)      (4)
## -----
## crisisJST    -0.015*** -0.015*** -0.015*** -0.015**
##              (0.005)  (0.006)  (0.006)  (0.007)
## Constant     0.042***  0.042***  0.042***  0.042***
##              (0.005)  (0.007)  (0.007)  (0.002)
## -----
## Observations  1,258    1,258    1,258    1,258
## =====
## Note:                               *p<0.1; **p<0.05; ***p<0.01
```

1.6 Shrinkage methods

Choosing the appropriate explanatory variables is often complicated, especially in the presence of many potentially relevant covariates. Keeping a large number of covariates results in large standard deviations for the estimated parameters (see Section 1.3.3). In order to address this issue, shrinkage methods have been designed. The objective of these methods is to help select a limited number of variables by shrinking the regression coefficients of the less useful variables towards zero. The two best-known shrinkage techniques are **ridge regression** and the **lasso** approach.⁵ In both cases (ridge and lasso), the OLS minimization problem (see Section 1.2), i.e.,

$$\mathbf{b} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^n (y_i - \mathbf{x}_i' \beta)^2 \quad (1.46)$$

⁵See Tibshirani (2011) for a review of the lasso approach. See also Section 6.2 of James et al. (2013).

is replaced with the following:

$$\mathbf{b}_\lambda = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^n (y_i - \mathbf{x}_i' \beta)^2 + \lambda f(\beta), \quad (1.47)$$

where $\lambda f(\beta)$ is a penalty term that positively depends on the “size” of the components of β . This term is called the *shrinkage penalty* term.

Specifically, assuming that the vector \mathbf{x}_i of potential covariates is of dimension $K \times 1$, we have:

$$\begin{aligned} f(\beta) &= \sum_{j=1}^K \beta_j^2 \quad \text{in the ridge case } (\ell_2 \text{ norm}), \\ f(\beta) &= \sum_{j=1}^K |\beta_j| \quad \text{in the lasso case } (\ell_1 \text{ norm}). \end{aligned}$$

In most cases, we do not want to involve the intercept in the set of parameters to shrink, and the preceding equations are respectively replaced with:

$$\begin{aligned} f(\beta) &= \sum_{j=2}^K \beta_j^2 \quad (\text{ridge}), \\ f(\beta) &= \sum_{j=2}^K |\beta_j| \quad (\text{lasso}). \end{aligned}$$

The nature of the penalty —based on either the ℓ_1 or the ℓ_2 norm— implies a different behaviour of the parameter estimates when λ —the *tuning parameter*— grows. In the ridge regression, coefficient estimates go to zero (shrinkage); in the lasso case, some coefficients reach zero when λ reach some values. In other words, while ridge regression achieve shrinkage, lasso regressions achieve shrinkage *and* variable selection.

Parameter λ has to be determined separately from the minimization problem of Eq. (1.47). One can combine standard criteria (e.g., BIC or Akaike) for this purpose.

In R, one can use the `glmnet` package to run ridge and lasso regressions. In the following example, we employ this package to model interest rates proposed to debtors, using data extracted from the Lending Club platform.

To begin with, let us define the variables we want to consider:

```
library(AEC)
library(glmnet)
credit$owner <- 1*(credit$home_ownership=="OWN")
credit$renter <- 1*(credit$home_ownership=="MORTGAGE")
credit$verification_status <- 1*(credit$verification_status=="Not Verified")
credit$emp_length_10 <- 1*(credit$emp_length_10)
```



```

credit$log_annual_inc <- log(credit$annual_inc)
credit$log_funded_amnt <- log(credit$funded_amnt)
credit$annual_inc2 <- (credit$annual_inc)^2
credit$funded_amnt2 <- (credit$funded_amnt)^2
x <- subset(credit,
            select = c(delinq_2yrs,annual_inc,annual_inc2,log_annual_inc,
                       dti,installment,funded_amnt,
                       funded_amnt2,log_funded_amnt,pub_rec,emp_length_10,
                       owner,renter,pub_rec_bankruptcies,revol_util,revol_bal))

```

Let us standardize the data:

```

y <- scale(credit$int_rate)
x <- scale(x)
indic_complete_cases <- complete.cases(x)
y <- y[indic_complete_cases] # to remove observations with NaN's
x <- x[indic_complete_cases,] # to remove observations with NaN's

```

Next, we define the set of λ we will use, and run the ridge and lasso regressions:

```

grid.lambda <- seq(0,.2,by=.005)
result.ridge <- glmnet(x, y, alpha = 0, lambda = grid.lambda)
result.lasso <- glmnet(x, y, alpha = 1, lambda = grid.lambda)

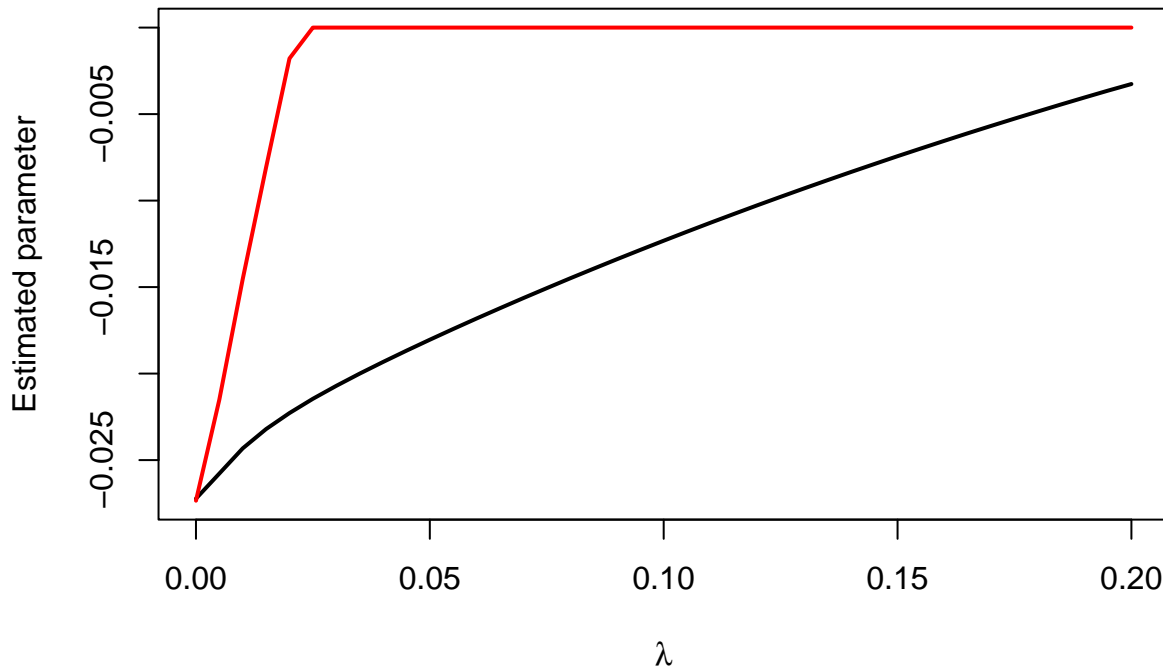
```

The following figure shows how estimated parameters depend on λ :

```

variab <- 6
plot(result.ridge$lambda,coef(result.ridge)[variab,],type="l",
     ylim=c(min(coef(result.ridge)[variab,],coef(result.lasso)[variab,]),
            max(coef(result.ridge)[variab,],coef(result.lasso)[variab,])),
     xlab=expression(lambda),ylab="Estimated parameter",lwd=2)
lines(result.lasso$lambda,coef(result.lasso)[variab,],col="red",lwd=2)

```



Let us take two values of λ and see the associated estimated parameters in the context of lasso regressions:

```
i <- 20; j <- 40
cbind(result.lasso$lambda[i], result.lasso$lambda[j])
```

```
##      [,1] [,2]
## [1,] 0.105 0.005
```

```
cbind(coef(result.lasso)[,i], coef(result.lasso)[,j])
```

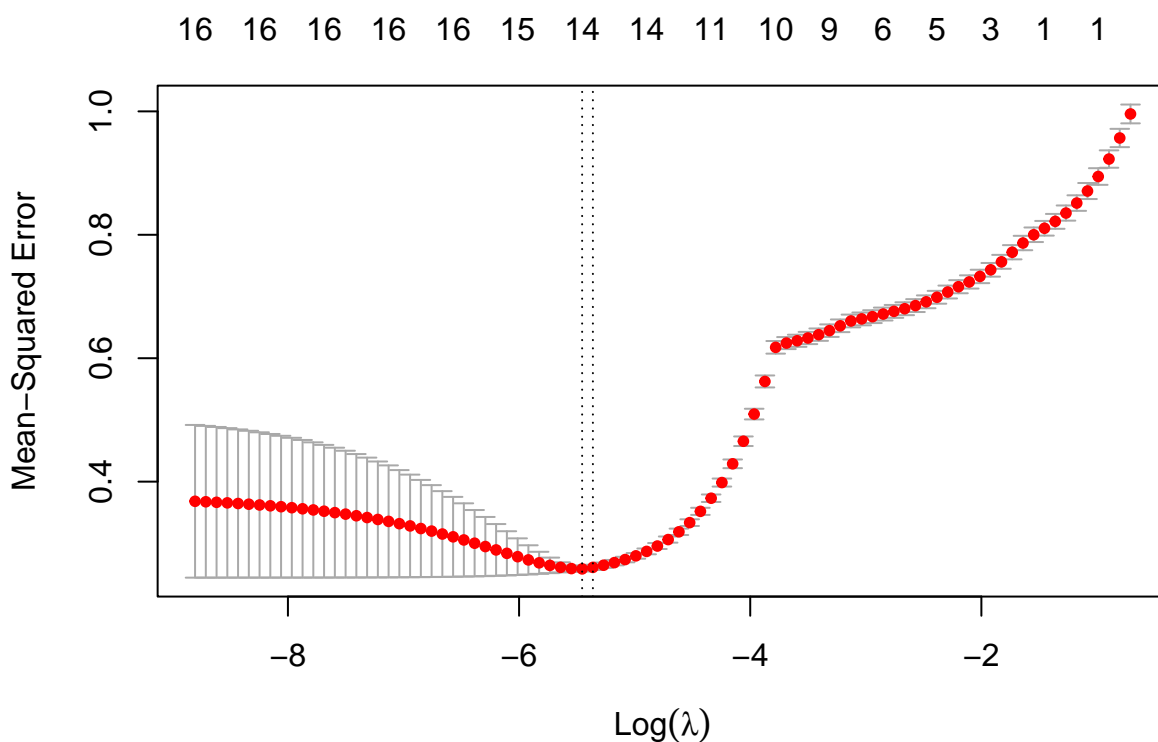
```
##              [,1]      [,2]
## (Intercept) -0.003183346 -0.002290639
## delinq_2yrs  0.086457831  0.096538222
## annual_inc  0.000000000  0.009288932
## annual_inc2  0.000000000  0.000000000
## log_annual_inc 0.000000000 -0.052405808
## dti         0.000000000 -0.021505827
## installment 0.100715553  7.017150265
## funded_amnt  0.000000000 -6.307245657
## funded_amnt2 0.000000000 -0.328837450
## log_funded_amnt 0.000000000 -0.175860616
## pub_rec     0.000000000  0.046974246
## emp_length_10 0.000000000 -0.020078967
## owner       0.000000000 -0.007930234
## renter     -0.007220882 -0.043264994
```

```
## pub_rec_bankruptcies 0.000000000 0.000000000
## revol_util          0.379766899 0.249451915
## revol_bal           0.000000000 -0.024474673
```

```
# Compute values of y predicted by the model, for all lambdas:
pred1 <- predict(result.lasso,as.matrix(x))
# Compute values of y predicted by the model, for a specific value:
pred2 <- predict(result.lasso,as.matrix(x),s=0.085)
```

The `glmnet` package (see Hastie et al. (2021)) also offers tools to implement cross-validation:

```
# cross validation (cv):
cvglmnet <- cv.glmnet(as.matrix(x),y)
plot(cvglmnet)
```



```
# lambda.min: lambda that gives minimum mean cross-validated error
cvglmnet$lambda.min
```

```
## [1] 0.004277307
```

```
# lambda.1se: largest lambda s.t. cost within the one-std-dev cv-based band
cvglmnet$lambda.1se
```

```
## [1] 0.004694339
```

```
coef(cvglmnet, s = "lambda.min") # associated parameters
```

```
## 17 x 1 sparse Matrix of class "dgCMatrix"
```

```
##              s1
## (Intercept)  -0.002262204
## delinq_2yrs   0.093465307
## annual_inc    0.010181514
## annual_inc2    .
## log_annual_inc -0.052917617
## dti           -0.022498219
## installment   7.289164713
## funded_amnt   -6.542070431
## funded_amnt2  -0.359156943
## log_funded_amnt -0.183939650
## pub_rec       0.045755394
## emp_length_10 -0.019706751
## owner         -0.008752887
## renter        -0.042208229
## pub_rec_bankruptcies .
## revol_util    0.241530260
## revol_bal     -0.024248623
```

```
# predicted values of y for specific values of x:
```

```
predict(cvglmnet, newx = as.matrix(x)[1:5,], s = "lambda.min")
```

```
##      lambda.min
## 21529 0.3218125
## 21547 -0.1873492
## 21579 0.6810101
## 21583 -0.2687087
## 21608 -0.2072584
```

Chapter 2

Panel regressions

2.1 Specification and notations

A standard panel situation is as follows: the sample covers a lot of “entities”, indexed by $i \in \{1, \dots, n\}$, with n large, and, for each entity, we observe different variables over a small number of periods $t \in \{1, \dots, T\}$. This is a *longitudinal dataset*.

The linear panel regression model is:

$$y_{i,t} = \underbrace{\mathbf{x}'_{i,t}}_{K \times 1} \underbrace{\beta}_{\text{Individual effects}} + \varepsilon_{i,t}. \quad (2.1)$$

When running panel regressions, the usual objective is to estimate β .

Figure 2.1 illustrates a panel-data situation. The model is $y_i = \alpha_i + \beta x_{i,t} + \varepsilon_{i,t}$, $t \in \{1, 2\}$. On Panel (b), blue dots are for $t = 1$, red dots are for $t = 2$. The lines relate the dots associated with the same entity i . What is remarkable in the simulated model is that, while the unconditional correlation between y and x is negative, the conditional correlation (conditional on α_i) is positive. Indeed, the sign of this conditional correlation is the sign of β , which is positive in the simulated example ($\beta = 5$). In other words, if one did not know the panel nature of the data, that would be tempting to say that $\beta < 0$, but this is not the case, due to **fixed effects** (the α_i 's) that are negatively correlated to the x_i 's.

```
T <- 2; n <- 12 # 2 periods and 12 entities
alpha <- 5*rnorm(n) # draw fixed effects
x.1 <- rnorm(n) - .5*alpha # note: x_i's correlate to alpha_i's
x.2 <- rnorm(n) - .5*alpha
beta <- 5; sigma <- .3
y.1 <- alpha + x.1 + sigma*rnorm(n); y.2 <- alpha + x.2 + sigma*rnorm(n)
x <- c(x.1,x.2) # pooled x
y <- c(y.1,y.2) # pooled y
par(mfrow=c(1,2))
```

```

plot(x,y,col="black",pch=19,xlab="x",ylab="y",main="(a)")
plot(x,y,col="black",pch=19,xlab="x",ylab="y",main="(b)")
points(x.1,y.1,col="blue",pch=19);points(x.2,y.2,col="red",pch=19)
for(i in 1:n){lines(c(x.1[i],x.2[i]),c(y.1[i],y.2[i]))}

```

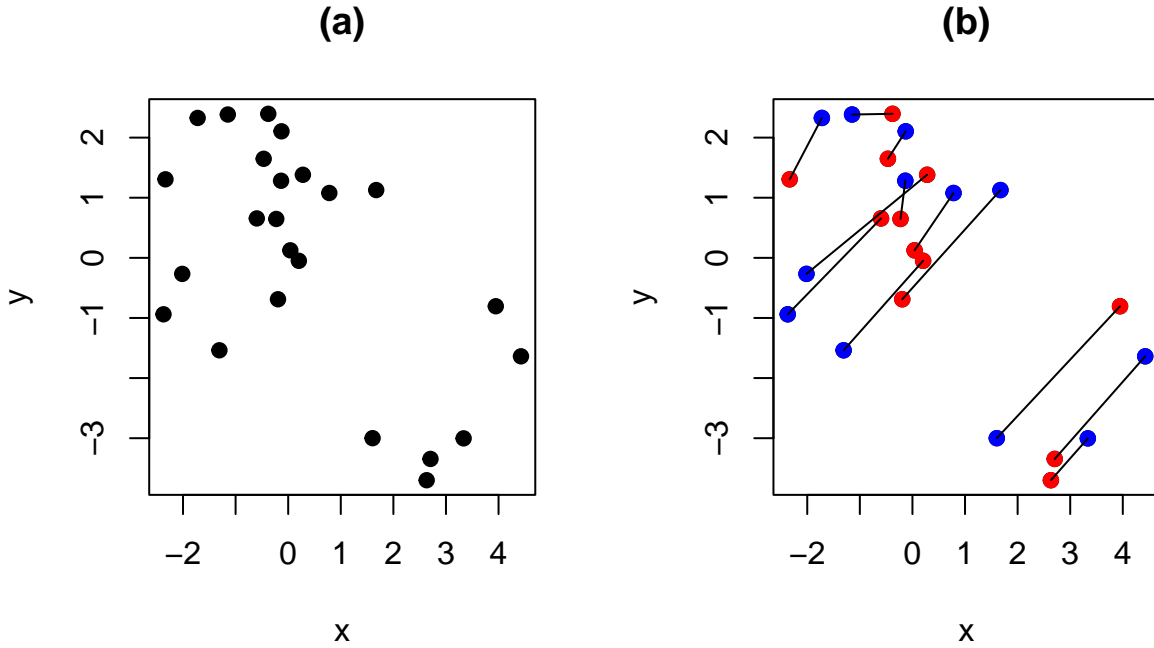


Figure 2.1: The data are the same for both panels. On Panel (b), blue dots are for $t = 1$, red dots are for $t = 2$. The lines relate the dots associated to the same entity i .

Figure 2.2 presents the same type of plot based on the Cigarette Consumption Panel dataset (*CigarettesSW* dataset, used in Stock and Watson (2003)). This dataset documents the average consumption of cigarettes in 48 continental US states for two dates (1985 and 1995).

We will make use of the following notations:

$$\begin{aligned}
 \mathbf{y}_i &= \underbrace{\begin{bmatrix} y_{i,1} \\ \vdots \\ y_{i,T} \end{bmatrix}}_{T \times 1}, \quad \boldsymbol{\varepsilon}_i = \underbrace{\begin{bmatrix} \varepsilon_{i,1} \\ \vdots \\ \varepsilon_{i,T} \end{bmatrix}}_{T \times 1}, \quad \mathbf{x}_i = \underbrace{\begin{bmatrix} \mathbf{x}'_{i,1} \\ \vdots \\ \mathbf{x}'_{i,T} \end{bmatrix}}_{T \times K}, \quad \mathbf{X} = \underbrace{\begin{bmatrix} \mathbf{x}_1 \\ \vdots \\ \mathbf{x}_n \end{bmatrix}}_{(nT) \times K}. \\
 \tilde{\mathbf{y}}_i &= \begin{bmatrix} y_{i,1} - \bar{y}_i \\ \vdots \\ y_{i,T} - \bar{y}_i \end{bmatrix}, \quad \tilde{\boldsymbol{\varepsilon}}_i = \begin{bmatrix} \varepsilon_{i,1} - \bar{\varepsilon}_i \\ \vdots \\ \varepsilon_{i,T} - \bar{\varepsilon}_i \end{bmatrix}, \\
 \tilde{\mathbf{x}}_i &= \begin{bmatrix} \mathbf{x}'_{i,1} - \bar{\mathbf{x}}'_i \\ \vdots \\ \mathbf{x}'_{i,T} - \bar{\mathbf{x}}'_i \end{bmatrix}, \quad \tilde{\mathbf{X}} = \begin{bmatrix} \tilde{\mathbf{x}}_1 \\ \vdots \\ \tilde{\mathbf{x}}_n \end{bmatrix}, \quad \tilde{\mathbf{Y}} = \begin{bmatrix} \tilde{\mathbf{y}}_1 \\ \vdots \\ \tilde{\mathbf{y}}_n \end{bmatrix},
 \end{aligned}$$

where

$$\bar{y}_i = \frac{1}{T} \sum_{t=1}^T y_{i,t}, \quad \bar{\varepsilon}_i = \frac{1}{T} \sum_{t=1}^T \varepsilon_{i,t} \quad \text{and} \quad \bar{\mathbf{x}}_i = \frac{1}{T} \sum_{t=1}^T \mathbf{x}_{i,t}.$$

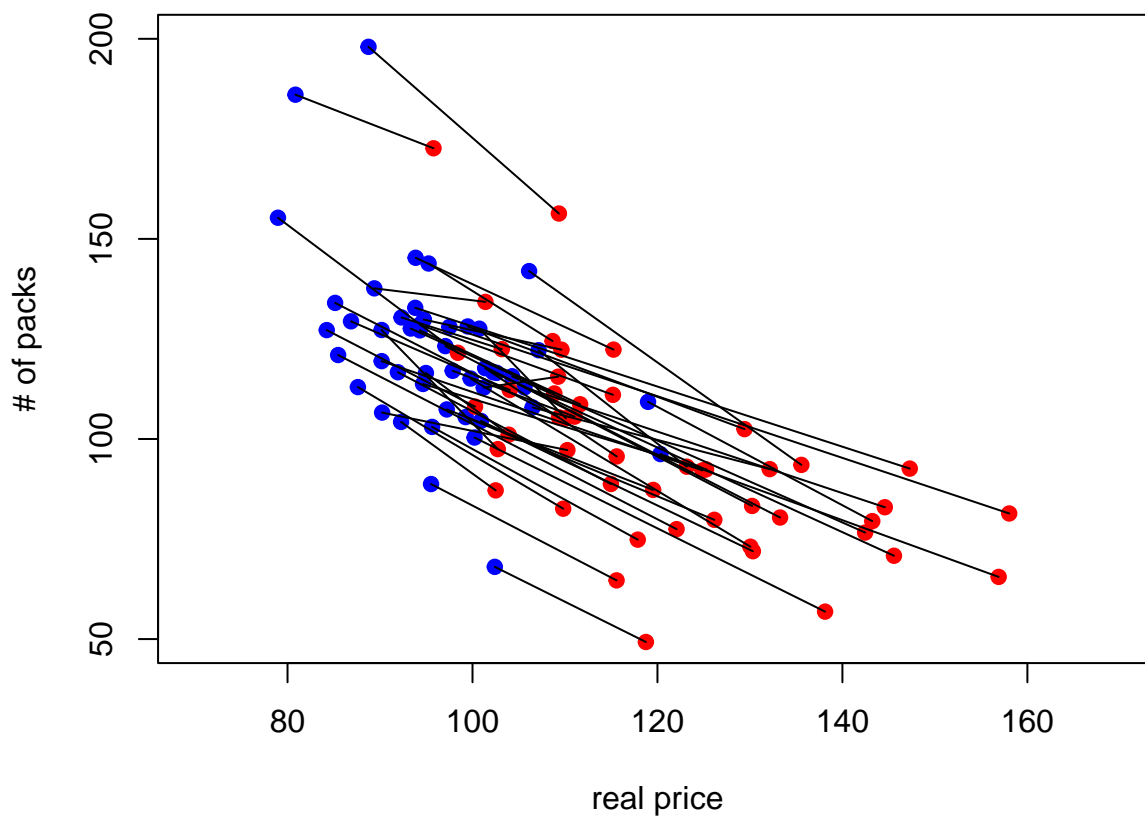


Figure 2.2: Cigarette consumption versus real price in the CigarettesSW panel dataset.

2.2 Three standard cases

There are three typical situations:

- **Pooled regression:** $\mathbf{z}_i \equiv 1$. This case amounts to the case studied in Chapter 1.
- **Fixed Effects** (Section 2.3): \mathbf{z}_i is unobserved, but correlates with $\mathbf{x}_i \Rightarrow \mathbf{b}$ is biased and inconsistent in the OLS regression of \mathbf{y} on \mathbf{X} (omitted variable, see Section 1.3.2).
- **Random Effects** (Section 2.4): \mathbf{z}_i is unobserved, but uncorrelated with \mathbf{x}_i . The model writes:

$$y_{i,t} = \mathbf{x}'_{i,t}\beta + \alpha + \underbrace{u_i + \varepsilon_{i,t}}_{\text{compound error}},$$

where $\alpha = \mathbb{E}(\mathbf{z}'_i\alpha)$ and $u_i = \mathbf{z}'_i\alpha - \mathbb{E}(\mathbf{z}'_i\alpha) \perp \mathbf{x}_i$. In that case, the OLS is consistent, but not efficient. GLS can be used to gain efficiencies over OLS (see Section 1.5.2 for a presentation of the GLS approach).

2.3 Estimation of Fixed-Effects Models

Hypothesis 2.1 (Fixed-effect model). We assume that:

- There is no perfect multicollinearity among the regressors.
- $\mathbb{E}(\varepsilon_{i,t}|\mathbf{X}) = 0$, for all i, t .
- We have:

$$\mathbb{E}(\varepsilon_{i,t}\varepsilon_{j,s}|\mathbf{X}) = \begin{cases} \sigma^2 & \text{if } i = j \text{ and } s = t, \\ 0 & \text{otherwise.} \end{cases}$$

These assumptions are analogous to those introduced in the standard linear regression:

- (i) \leftrightarrow Hyp. 1.1, (ii) \leftrightarrow Hyp. 1.2, (iii) \leftrightarrow Hyp. 1.3 + 1.4.

In matrix form, for a given i , the model writes:

$$\mathbf{y}_i = \mathbf{x}_i\beta + \mathbf{1}_T\alpha_i + \varepsilon_i,$$

where $\mathbf{1}_T$ is a T -dimensional vector of ones.

This is the **Least Square Dummy Variable (LSDV)** model:

$$\mathbf{y} = [\mathbf{X} \quad \mathbf{D}] \begin{bmatrix} \beta \\ \alpha \end{bmatrix} + \varepsilon, \quad (2.2)$$

with:

$$\mathbf{D} = \underbrace{\begin{bmatrix} \mathbf{1}_T & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{1}_T & \dots & \mathbf{0} \\ & & \ddots & \\ \mathbf{0} & \mathbf{0} & \dots & \mathbf{1}_T \end{bmatrix}}_{(nT \times n)}.$$

The linear regression (Eq. (2.2)) —with the dummy variables— satisfies the Gauss-Markov conditions (Theorem 1.1). Hence, in this context, the OLS estimator is the *best linear unbiased estimator* (BLUE).

Denoting by \mathbf{Z} the matrix $[\mathbf{X} \quad \mathbf{D}]$, and by \mathbf{b} and \mathbf{a} the respective OLS estimates of β and of α , we have:

$$\begin{bmatrix} \mathbf{b} \\ \mathbf{a} \end{bmatrix} = [\mathbf{Z}'\mathbf{Z}]^{-1}\mathbf{Z}'\mathbf{y}. \quad (2.3)$$

The asymptotical distribution of $[\mathbf{b}', \mathbf{a}']'$ derives from the standard OLS context: Prop. 1.11 can be used after having replaced \mathbf{X} by $\mathbf{Z} = [\mathbf{X} \quad \mathbf{D}]$.

We have:

$$\begin{bmatrix} \mathbf{b} \\ \mathbf{a} \end{bmatrix} \xrightarrow{d} \mathcal{N} \left(\begin{bmatrix} \beta \\ \alpha \end{bmatrix}, \sigma^2 \frac{Q^{-1}}{nT} \right), \quad (2.4)$$

where

$$Q = \text{plim}_{nT \rightarrow \infty} \frac{1}{nT} \mathbf{Z}'\mathbf{Z},$$

assuming the previous limit exists.

In practice, an estimator of the covariance matrix of $[\mathbf{b}', \mathbf{a}']'$ is:

$$s^2 (\mathbf{Z}'\mathbf{Z})^{-1} \quad \text{with} \quad s^2 = \frac{\mathbf{e}'\mathbf{e}}{nT - K - n},$$

where \mathbf{e} is the $(nT) \times 1$ vector of OLS residuals.

There is an alternative way of expressing the LSDV estimators. It involves the residual-maker matrix $\mathbf{M}_D = Id - \mathbf{D}(\mathbf{D}'\mathbf{D})^{-1}\mathbf{D}'$ (see Eq. (1.4)), which acts as an operator that removes entity-specific means, i.e.:

$$\tilde{\mathbf{Y}} = \mathbf{M}_D \mathbf{Y}, \quad \tilde{\mathbf{X}} = \mathbf{M}_D \mathbf{X} \quad \text{and} \quad \tilde{\varepsilon} = \mathbf{M}_D \varepsilon.$$

With these notations, using the Frisch-Waugh theorem (Theorem 1.2), we get another expression for the estimator \mathbf{b} appearing in Eq. (2.3):

$$\mathbf{b} = [\mathbf{X}'\mathbf{M}_D\mathbf{X}]^{-1}\mathbf{X}'\mathbf{M}_D\mathbf{y}. \quad (2.5)$$

This amounts to regressing the $\tilde{y}_{i,t}$'s ($= y_{i,t} - \bar{y}_i$) on the $\tilde{\mathbf{x}}_{i,t}$'s ($= \mathbf{x}_{i,t} - \bar{\mathbf{x}}_i$).

The estimate of α is given by:

$$\mathbf{a} = (\mathbf{D}'\mathbf{D})^{-1}\mathbf{D}'(\mathbf{y} - \mathbf{X}\mathbf{b}), \quad (2.6)$$

which is obtained by developing the second row of

$$\begin{bmatrix} \mathbf{X}'\mathbf{X} & \mathbf{X}'\mathbf{D} \\ \mathbf{D}'\mathbf{X} & \mathbf{D}'\mathbf{D} \end{bmatrix} \begin{bmatrix} \mathbf{b} \\ \mathbf{a} \end{bmatrix} = \begin{bmatrix} \mathbf{X}'\mathbf{Y} \\ \mathbf{D}'\mathbf{Y} \end{bmatrix},$$

which are the first-order conditions resulting from the least squares problem (see Eq. (1.3)). One can use different types of fixed effects in the same regression. Typically, one can have time and entity fixed effects. In that case, the model writes:

$$y_{i,t} = \mathbf{x}'_{i,t}\beta + \alpha_i + \gamma_t + \varepsilon_{i,t}.$$

The LSDV approach (Eq. (2.2)) can still be resorted to. It suffices to extend the \mathbf{Z} matrix with additional columns (then called *time dummies*):

$$\mathbf{y} = [\mathbf{X} \quad \mathbf{D} \quad \mathbf{C}] \begin{bmatrix} \beta \\ \alpha \\ \gamma \end{bmatrix} + \varepsilon, \quad (2.7)$$

with:

$$\mathbf{C} = \begin{bmatrix} \delta_1 & \delta_2 & \dots & \delta_{T-1} \\ \vdots & \vdots & & \vdots \\ \delta_1 & \delta_2 & \dots & \delta_{T-1} \end{bmatrix},$$

where the T -dimensional vector δ_t (the *time dummy*) is

$$[0, \dots, 0, \underset{t^{th} \text{ entry}}{\underset{\sim}{1}}, 0, \dots, 0]'$$

Using state and year fixed effects in the CigarettesSW panel dataset yields the following results:

```
data("CigarettesSW", package = "AER")
CigarettesSW$rprice <- with(CigarettesSW, price/cpi) # compute real price
CigarettesSW$rincome <- with(CigarettesSW, income/population/cpi)
eq.pooled <- lm(log(packs)~log(rprice)+log(rincome),data=CigarettesSW)
eq.LSDV <- lm(log(packs)~log(rprice)+log(rincome)+state,
              data=CigarettesSW)
CigarettesSW$year <- as.factor(CigarettesSW$year)
eq.LSDV2 <- lm(log(packs)~log(rprice)+log(rincome)+state+year,
              data=CigarettesSW)
stargazer::stargazer(eq.pooled,eq.LSDV,eq.LSDV2,type="text",no.space = TRUE,
                    omit=c("state","year"),
                    add.lines=list(c('State FE','No','Yes','Yes'),
                                   c('Year FE','No','No','Yes')),
                    omit.stat=c("f","ser"))
```

```
##
## =====
##               Dependent variable:
##               -----
```

```
##                               log(packs)
##                               (1)      (2)      (3)
## -----
## log(rprice)  -1.334*** -1.210*** -1.056***
##              (0.135)  (0.114)  (0.149)
## log(rincome) 0.318**   0.121    0.497
##              (0.136)  (0.190)  (0.304)
## Constant     10.067*** 9.954*** 8.360***
##              (0.516)  (0.264)  (1.049)
## -----
## State FE     No       Yes      Yes
## Year FE      No       No       Yes
## Observations 96       96       96
## R2           0.552    0.966    0.967
## Adjusted R2  0.542    0.929    0.931
## =====
## Note:        *p<0.1; **p<0.05; ***p<0.01
```

Example 2.1 (Housing prices and interest rates). In this example, we want to estimate the effect of short and long-term interest rate on housing prices. The data come from the Jordà et al. (2017) dataset (see this website).

```
library(AEC);library(sandwich)
data(JST); JST <- subset(JST,year>1950);N <- dim(JST)[1]
JST$hpreal <- JST$hpnom/JST$cpi # real house price index
JST$dhpreal <- 100*log(JST$hpreal/c(NaN,JST$hpreal[1:(N-1)]))
# Put NA's when change in country:
JST$dhpreal[c(0,JST$iso[2:N]!=JST$iso[1:(N-1)])] <- NaN
JST$dhpreal[abs(JST$dhpreal)>30] <- NaN # remove extreme price change
JST$YEAR <- as.factor(JST$year) # to have time fixed effects
eq1_noFE <- lm(dhpreal ~ stir + ltrate,data=JST)
eq1_FE   <- lm(dhpreal ~ stir + ltrate + iso + YEAR,data=JST)
eq2_noFE <- lm(dhpreal ~ I(ltrate-stir),data=JST)
eq2_FE   <- lm(dhpreal ~ I(ltrate-stir) + iso + YEAR,data=JST)
stargazer::stargazer(eq1_noFE, eq1_FE, eq2_noFE, eq2_FE, type = "text",
                      column.labels = c("no FE", "with FE", "no FE","with FE"),
                      omit = c("iso","YEAR","Constant"),keep.stat = "n",
                      add.lines=list(c('Country FE','No','Yes','No','Yes'),
                                     c('Year FE','No','Yes','No','Yes')))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               dhpreal
```

```
##              no FE      with FE      no FE      with FE
##              (1)       (2)       (3)       (4)
## -----
## stir          0.485***   0.532***
##              (0.114)   (0.134)
##
## ltrate        -0.690***  -0.384***
##              (0.127)   (0.145)
##
## I(ltrate - stir)                -0.476*** -0.475***
##                                (0.115)  (0.125)
##
## -----
## Country FE      No        Yes        No        Yes
## Year FE         No        Yes        No        Yes
## Observations    1,141     1,141     1,141     1,141
## =====
## Note:                               *p<0.1; **p<0.05; ***p<0.01
```

If we suspect heteroskedasticity and autocorrelation (HAC) in the residuals, we can apply cluster corrections (see Section 1.5.5):

```
vcov_cluster1_noFE <- vcovCL(eq1_noFE, cluster = JST[, c("iso","YEAR")])
vcov_cluster1_FE   <- vcovCL(eq1_FE, cluster = JST[, c("iso","YEAR")])
vcov_cluster2_noFE <- vcovCL(eq2_noFE, cluster = JST[, c("iso","YEAR")])
vcov_cluster2_FE   <- vcovCL(eq2_FE, cluster = JST[, c("iso","YEAR")])
robust_se_FE1_noFE <- sqrt(diag(vcov_cluster1_noFE))
robust_se_FE1_FE   <- sqrt(diag(vcov_cluster1_FE))
robust_se_FE2_noFE <- sqrt(diag(vcov_cluster2_noFE))
robust_se_FE2_FE   <- sqrt(diag(vcov_cluster2_FE))
stargazer::stargazer(eq1_noFE, eq1_FE, eq2_noFE, eq2_FE, type = "text",
  column.labels = c("no FE", "with FE", "no FE", "with FE"),
  omit = c("iso","YEAR","Constant"), keep.stat = "n",
  add.lines=list(c('Country FE','No','Yes','No','Yes'),
    c('Year FE','No','Yes','No','Yes')),
  se = list(robust_se_FE1_noFE, robust_se_FE1_FE,
    robust_se_FE2_noFE, robust_se_FE2_FE))
```

```
##
## =====
##              Dependent variable:
##              -----
##              dhpreal
##              no FE    with FE    no FE    with FE
```

##	(1)	(2)	(3)	(4)
## -----				
## stir	0.485*	0.532**		
##	(0.271)	(0.240)		
##				
## ltrate	-0.690**	-0.384*		
##	(0.269)	(0.200)		
##				
## I(ltrate - stir)			-0.476*	-0.475**
##			(0.255)	(0.213)
##				
## -----				
## Country FE	No	Yes	No	Yes
## Year FE	No	Yes	No	Yes
## Observations	1,141	1,141	1,141	1,141
## =====				
## Note:	*p<0.1; **p<0.05; ***p<0.01			

2.4 Estimation of random effects models

Here, the individual effects are assumed to be not correlated to other variables (the \mathbf{x}_i 's). In that context, the OLS estimator is consistent. However, it is not efficient. The GLS approach can be employed to gain efficiency.

Random-effect models write:

$$y_{i,t} = \mathbf{x}'_{it}\beta + (\alpha + \underbrace{u_i}_{\text{Random heterogeneity}}) + \varepsilon_{i,t},$$

with

$$\begin{aligned} \mathbb{E}(\varepsilon_{i,t}|\mathbf{X}) &= \mathbb{E}(u_i|\mathbf{X}) = 0, \\ \mathbb{E}(\varepsilon_{i,t}\varepsilon_{j,s}|\mathbf{X}) &= \begin{cases} \sigma_\varepsilon^2 & \text{if } i = j \text{ and } s = t, \\ 0 & \text{otherwise.} \end{cases} \\ \mathbb{E}(u_i u_j|\mathbf{X}) &= \begin{cases} \sigma_u^2 & \text{if } i = j, \\ 0 & \text{otherwise.} \end{cases} \\ \mathbb{E}(\varepsilon_{i,t} u_j|\mathbf{X}) &= 0 \quad \text{for all } i, j \text{ and } t. \end{aligned}$$

Introducing the notations $\eta_{i,t} = u_i + \varepsilon_{i,t}$ and $\eta_i = [\eta_{i,1}, \dots, \eta_{i,T}]'$, we have $\mathbb{E}(\eta_i|\mathbf{X}) = \mathbf{0}$ and $\text{Var}(\eta_i|\mathbf{X}) = \Gamma$, where

$$\Gamma = \begin{bmatrix} \sigma_\varepsilon^2 + \sigma_u^2 & \sigma_u^2 & \sigma_u^2 & \dots & \sigma_u^2 \\ \sigma_u^2 & \sigma_\varepsilon^2 + \sigma_u^2 & \sigma_u^2 & \dots & \sigma_u^2 \\ \vdots & & \ddots & & \vdots \\ \sigma_u^2 & \sigma_u^2 & \sigma_u^2 & \dots & \sigma_\varepsilon^2 + \sigma_u^2 \end{bmatrix} = \sigma_\varepsilon^2 Id_T + \sigma_u^2 \mathbf{1}_T \mathbf{1}_T',$$

where Id_T is the identity matrix of dimension $T \times T$, and $\mathbf{1}_T$ is a T -dimensional vector of ones.

Denoting by Σ the covariance matrix of $\eta = [\eta'_1, \dots, \eta'_n]'$, we have:

$$\Sigma = Id_n \otimes \Gamma,$$

where Id_n is the identity matrix of dimension $n \times n$.

If we knew Σ , we would apply (feasible) GLS (Eq. (1.32), in Section 1.5.2):

$$\beta = (\mathbf{X}'\Sigma^{-1}\mathbf{X})^{-1}\mathbf{X}'\Sigma^{-1}\mathbf{y}.$$

(As explained in Section 1.5.2, this amounts to regressing $\Sigma^{-1/2'}\mathbf{y}$ on $\Sigma^{-1/2'}\mathbf{X}$.)

It can be checked that $\Sigma^{-1/2} = Id_n \otimes (\Gamma^{-1/2})$ where

$$\Gamma^{-1/2} = \frac{1}{\sigma_\varepsilon} \left(Id_T - \frac{\theta}{T} \mathbf{1}_T \mathbf{1}_T' \right), \quad \text{with} \quad \theta = 1 - \frac{\sigma_\varepsilon}{\sqrt{\sigma_\varepsilon^2 + T\sigma_u^2}}.$$

Hence, if we knew Σ , we would transform the data as follows:

$$\Gamma^{-1/2}\mathbf{y}_i = \frac{1}{\sigma_\varepsilon} \begin{bmatrix} y_{i,1} - \theta\bar{y}_i \\ y_{i,2} - \theta\bar{y}_i \\ \vdots \\ y_{i,T} - \theta\bar{y}_i \end{bmatrix}.$$

What about when Σ is unknown? One can take deviations from group means to remove heterogeneity:

$$y_{i,t} - \bar{y}_i = [\mathbf{x}_{i,t} - \bar{\mathbf{x}}_i]' \beta + (\varepsilon_{i,t} - \bar{\varepsilon}_i). \quad (2.8)$$

The previous equation can be consistently estimated by OLS. (Although the residuals are correlated across t 's for the observations pertaining to a given entity, the OLS remain consistent; see Prop. 1.13.)

We have $\mathbb{E} \left[\sum_{t=1}^T (\varepsilon_{i,t} - \bar{\varepsilon}_i)^2 \right] = (T-1)\sigma_\varepsilon^2$.

The $\varepsilon_{i,t}$'s are not observed but \mathbf{b} , the OLS estimator of β in Eq. (2.8), is a consistent estimator of β . Using an adjustment for the degrees of freedom, we can approximate their variance with:

$$\hat{\sigma}_e^2 = \frac{1}{nT - n - K} \sum_{i=1}^n \sum_{t=1}^T (e_{i,t} - \bar{e}_i)^2.$$

What about σ_u^2 ? We can exploit the fact that OLS are consistent in the pooled regression:

$$\text{plim } s_{pooled}^2 = \text{plim } \frac{\mathbf{e}'\mathbf{e}}{nT - K - 1} = \sigma_u^2 + \sigma_\varepsilon^2,$$

and therefore use $s_{pooled}^2 - \hat{\sigma}_e^2$ as an approximation to σ_u^2 .

Let us come back to Example 2.1 (relationship between changes in housing prices and interest rates). In the following, we use the random effect specification; and compare the results with those obtained with the pooled regression and with the fixed-effect model. For that, we use the function `plm` of the package of the same name. (Note that `eq.FE` is similar to `eq1` in Example 2.1.)

```
library(plm);library(stargazer)
eq.RE <- plm(dhpreal ~ stir + ltrate,data=JST,index=c("iso","YEAR"),
             model="random",effect="twoways")
eq.FE <- plm(dhpreal ~ stir + ltrate,data=JST,index=c("iso","YEAR"),
             model="within",effect="twoways")
eq0 <- plm(dhpreal ~ stir + ltrate,data=JST,index=c("iso","YEAR"),
           model="pooling")
stargazer(eq0, eq.RE, eq.FE, type = "text",no.space = TRUE,
          column.labels=c("Pooled","Random Effect","Fixed Effects"),
          add.lines=list(c('State FE','No','Yes','Yes'),
                        c('Year FE','No','Yes','Yes')),
          omit.stat=c("f","ser"))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               dhpreal
##                               Pooled   Random Effect Fixed Effects
##                               (1)       (2)       (3)
## -----
## stir           0.485***    0.456***    0.532***
##                (0.114)    (0.019)    (0.134)
## ltrate         -0.690***   -0.541***   -0.384***
##                (0.127)    (0.020)    (0.145)
## Constant       4.103***    3.341***
##                (0.421)    (0.096)
## -----
## State FE       No         Yes         Yes
## Year FE        No         Yes         Yes
## Observations   1,141     1,141     1,141
## R2             0.027     0.024     0.015
## Adjusted R2    0.025     0.022    -0.067
## =====
## Note:          *p<0.1; **p<0.05; ***p<0.01
```

One can run an Hausman (1978) test in order to check whether or not the fixed-effect model is needed. Indeed, if this is not the case (i.e., if the covariates are not correlated to the

disturbances), then it is preferable to use the random-effect estimation as the latter is more efficient.

```
phtest(eq.FE,eq.RE)
```

```
##
## Hausman Test
##
## data:  dhpreal ~ stir + ltrate
## chisq = 3.8386, df = 2, p-value = 0.1467
## alternative hypothesis: one model is inconsistent
```

The p-value being high, we do not reject the null hypothesis according to which the covariates and the errors are uncorrelated. We should therefore prefer the random-effect model.

Example 2.2 (Spatial data). This example makes use of Airbnb prices (Zürich, 22 June 2017), collected from Tom Slee’s website. The covariates are the number of bedrooms and the number of people that can be accommodated. We consider the use of district fixed effects. Figure 2.3 shows the price to explain (the size of the circles is proportional to the prices). The white lines delineate the 12 districts of the city.

Let us regress prices on the covariates as well as on district dummies:

```
eq_noFE <- lm(price~bedrooms+accommodates,data=airbnb)
eq_FE   <- lm(price~bedrooms+accommodates+neighborhood,data=airbnb)
# Adjust standard errors:
cov_FE   <- vcovHC(eq_FE, cluster = airbnb[, c("neighborhood")])
robust_se_FE <- sqrt(diag(cov_FE))
cov_noFE <- vcovHC(eq_noFE, cluster = airbnb[, c("neighborhood")])
robust_se_noFE <- sqrt(diag(cov_noFE))
stargazer::stargazer(eq_FE, eq_noFE, eq_FE, eq_noFE, type = "text",
                      column.labels = c("FE (no HAC)", "No FE (no HAC)",
                                          "FE (with HAC)", "No FE (with HAC)"),
                      omit = c("neighborhood"),no.space = TRUE,
                      omit.labels = c("District FE"),keep.stat = "n",
                      se = list(NULL, NULL, robust_se_FE, robust_se_noFE))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               price
## FE (no HAC) No FE (no HAC) FE (with HAC) No FE (with HAC)
##              (1)          (2)          (3)          (4)
```

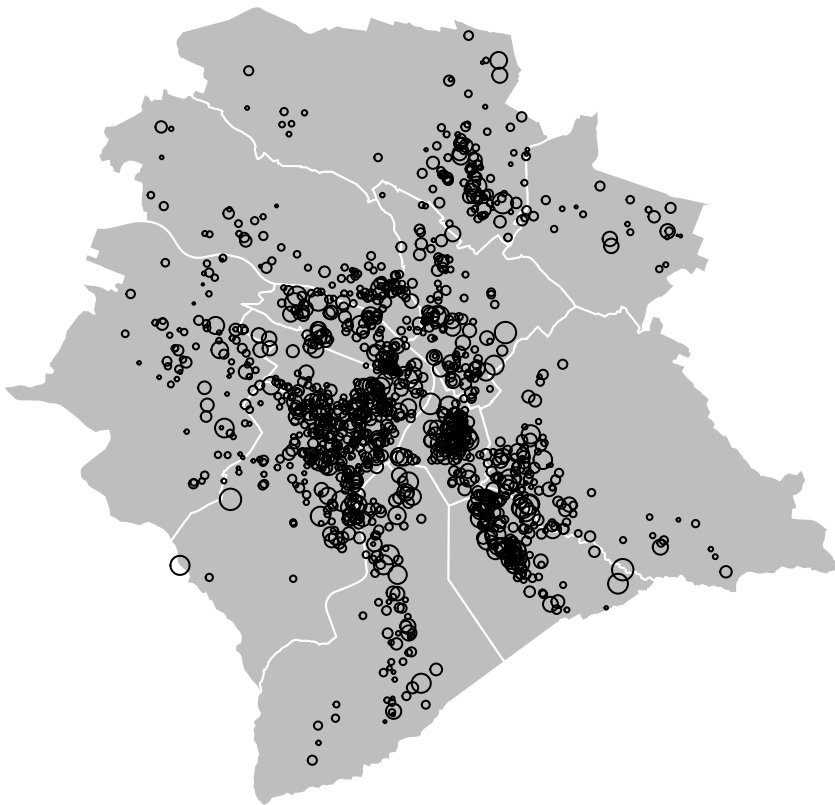



Figure 2.3: Airbnb prices for the Zurich area, 22 June 2017. The size of the circles is proportional to the prices. White lines delineate the 12 districts of the city.

```
## -----
## bedrooms      7.229***      5.629**      7.229***      5.629***
##              (2.135)      (2.194)      (2.052)      (2.073)
## accommodates  16.426***     17.449***     16.426***     17.449***
##              (1.284)      (1.323)      (1.431)      (1.428)
## Constant      95.118***     68.417***     95.118***     68.417***
##              (5.323)      (3.223)      (5.664)      (3.527)
## -----
## District FE   Yes          No          Yes          No
## -----
## Observations  1,321        1,321        1,321        1,321
## =====
## Note:                                     *p<0.1; **p<0.05; ***p<0.01
```

Figure 2.4 compares the residuals with and without fixed effects. The sizes of the circles are proportional to the absolute values of the residuals, the color indicates the sign (blue for positive).

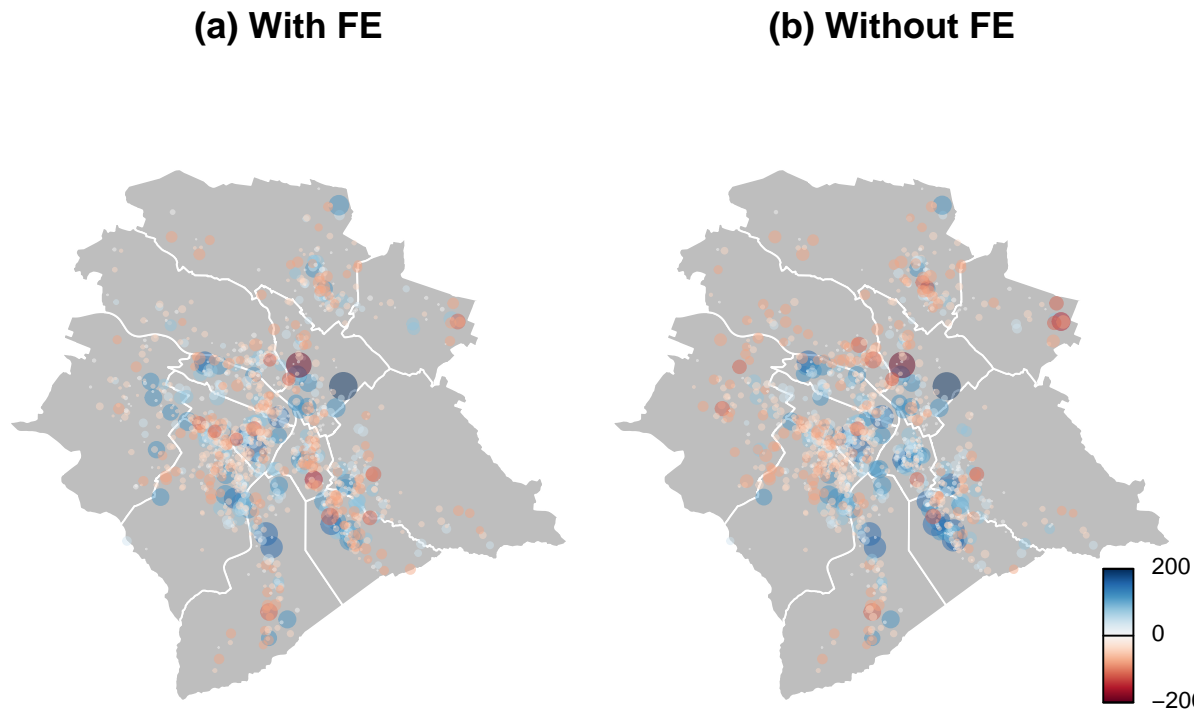


Figure 2.4: Regression residuals. The sizes of the circles are proportional to the absolute values of the residuals, the color indicates the sign (blue for negative).

With fixed effects, the colors are better balanced within each district.

2.5 Dynamic Panel Regressions

In what precedes, it has been assumed that there is no correlation between the observations indexed by (i, t) and those indexed by (j, s) as long as $j \neq i$ or $t \neq s$. If one suspects that the errors $\varepsilon_{i,t}$ are correlated (across entities i for a given date t , or across dates for a given entity, or both), then one should employ a robust covariance matrix (see Section 1.5.5).

In several cases, auto-correlation in the variable of interest may stem from an auto-regressive specification. That is, Eq. (2.1) is then replaced by:

$$y_{i,t} = \rho y_{i,t-1} + \underbrace{\mathbf{x}'_{i,t} \beta}_{K \times 1} + \underbrace{\alpha_i}_{\text{Individual effects}} + \varepsilon_{i,t}. \quad (2.9)$$

In that case, even if the explanatory variables $\mathbf{x}_{i,t}$ are uncorrelated to the errors $\varepsilon_{i,t}$, we have that the additional *explanatory variable* $y_{i,t-1}$ correlates to the errors $\varepsilon_{i,t-1}, \varepsilon_{i,t-2}, \dots, \varepsilon_{i,1}$. As a result, the LSDV estimate of the model parameters $\{\rho, \beta\}$ may be biased, even if n is large. To see this, notice that the LSDV regression amounts to regressing $\tilde{\mathbf{y}}$ on $\tilde{\mathbf{X}}$ (see Eq. (2.5)), where the elements of $\tilde{\mathbf{X}}$ are the explanatory variables from which we subtract their within-sample means. In particular, we have:

$$\tilde{y}_{i,t-1} = y_{i,t-1} - \frac{1}{T} \sum_{s=1}^T y_{i,s-1},$$

which correlates to the corresponding error, that is:

$$\tilde{\varepsilon}_{i,t} = \varepsilon_{i,t} - \frac{1}{T} \sum_{s=1}^T \varepsilon_{i,s}.$$

The previous equation shows that the *within-group* estimator (LSDV) introduces all realizations of the $\varepsilon_{i,t}$ errors into the transformed error term ($\tilde{\varepsilon}_{i,t}$). As a result, in large- n fixed- T panels, it is consistent only if all the right-hand-side variables of the regression are strictly exogenous (i.e., do not correlate to past, present, and future errors $\varepsilon_{i,t}$).¹ This is not the case when there are lags of $y_{i,t}$ on the right-hand side of the regression formula.

The following simulation illustrate this bias. The x -coordinates of the dots are the fixed effects α_i 's, and the y -coordinates are their LSDV estimates. The blue line is the 45-degree line.

```
n <- 400; T <- 10
rho <- 0.8; sigma <- .5
alpha <- rnorm(n)
y <- alpha / (1-rho) + sigma^2 / (1 - rho^2) * rnorm(n)
all_y <- y
for(t in 2:T){
```

¹Although the bias may vanish for large T 's, it does not if n only goes to infinity.

```

y <- rho * y + alpha + sigma * rnorm(n)
all_y <- rbind(all_y,y)
}
y <- c(all_y[2:T,]); y_1 <- c(all_y[1:(T-1),])
D <- diag(n) %x% rep(1,T-1)
Z <- cbind(c(y_1),D)
b <- solve(t(Z) %*% Z) %*% t(Z) %*% y
a <- b[2:(n+1)]
plot(alpha,a)
lines(c(-10,10),c(-10,10),col="blue")

```

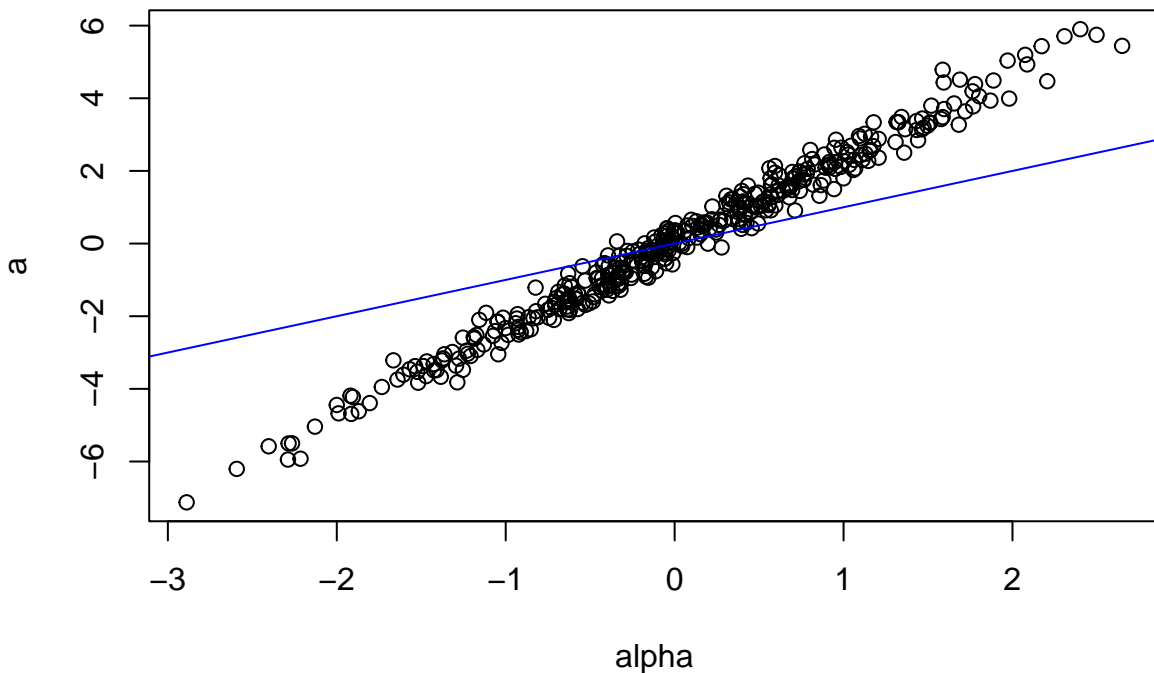


Figure 2.5: illustration of the bias pertaining to the LSDV estimation approach in the presence of auto-correlation of the depend variable.

In the previous example, the estimate of ρ (whose true value is 0.8) is 0.531.

To address this, one can resort to instrumental-variable regressions. Anderson and Hsiao (1982) have, in particular, proposed a first-differenced Two Stage Least Squares (2SLS) estimator (see Eq. (1.25) in Section 1.4). This estimation is based on the following transformation of the model:

$$\Delta y_{i,t} = \rho \Delta y_{i,t-1} + (\Delta \mathbf{x}_{i,t})' \beta + \Delta \varepsilon_{i,t}. \quad (2.10)$$

The OLS estimates of the parameters are biased because $\varepsilon_{i,t-1}$ —which is part of the error $\Delta \varepsilon_{i,t}$ — is correlated to $y_{i,t-1}$ —which is part of the “explanatory variable”, namely $\Delta y_{i,t-1}$. But consistent estimates can be obtained using 2SLS with instrumental variables that are correlated with $\Delta y_{i,t}$ but orthogonal to $\Delta \varepsilon_{i,t}$. One can for instance use $\{y_{i,t-2}, \mathbf{x}_{i,t-2}\}$ as

instruments. Note that this approach can be implemented only if there are more than 3 time observations per entity i .

If the explanatory variables $\mathbf{x}_{i,t}$ are assumed to be predetermined (i.e., do not contemporaneously correlate with the errors $\varepsilon_{i,t}$), then $\mathbf{x}_{i,t-1}$ can be added to the instruments associated with $\Delta y_{i,t}$. Further, if these variables (the $\mathbf{x}_{i,t}$'s) are exogenous (i.e., do not contemporaneously correlate with any of the errors $\varepsilon_{i,s}$, $\forall s$), then $\mathbf{x}_{i,t}$ also constitute a valid instrument.

Using the previous (simulated) example, this approach consists in the following steps:

```
Dy <- c(all_y[3:T,]) - c(all_y[2:(T-1),])
Dy_1 <- c(all_y[2:(T-1),]) - c(all_y[1:(T-2),])
y_2 <- c(all_y[1:(T-2),])
Z <- matrix(y_2, ncol=1)
Pz <- Z %*% solve(t(Z) %*% Z) %*% t(Z)
Dy_1hat <- Pz %*% Dy_1
rho_2SLS <- solve(t(Dy_1hat) %*% Dy_1hat) %*% t(Dy_1hat) %*% Dy
```

While the OLS estimate of ρ (whose true value is 0.8) was 0.531, we obtain here `rho_2SLS` = 0.89.

Let us come back to the general case (with covariates $\mathbf{x}_{i,k}$'s). For $t = 3$, $y_{i,1}$ (and $\mathbf{x}_{i,1}$) is the only possible instrument. However, for $t = 4$, one could use $y_{i,2}$ and $y_{i,1}$ (as well as $\mathbf{x}_{i,2}$ and $\mathbf{x}_{i,1}$). More generally, defining matrix Z_i as follows:

$$Z_i = \begin{bmatrix} \mathbf{z}'_{i,1} & 0 & \dots & & & & & \\ 0 & \mathbf{z}'_{i,1} & \mathbf{z}'_{i,2} & 0 & \dots & & & \\ 0 & 0 & 0 & \mathbf{z}_{i,1} & \mathbf{z}'_{i,2} & \mathbf{z}'_{i,3} & 0 & \dots \\ \vdots & & & & & & & \\ 0 & \dots & & & & & 0 & \mathbf{z}'_{i,1} \dots \mathbf{z}'_{i,T-2} \end{bmatrix},$$

where $\mathbf{z}_{i,t} = [y_{i,t}, \mathbf{x}'_{i,t}]'$, we have the moment conditions:²

$$\mathbb{E}(Z'_i \Delta \varepsilon_i) = 0,$$

with $\Delta \varepsilon_i = [\Delta \varepsilon_{i,3}, \dots, \Delta \varepsilon_{i,T}]'$.

These restrictions are used in the GMM approach employed by Arellano and Bond (1991). Specifically, a GMM estimator of the model parameters is given by:

$$\operatorname{argmin} \left(\frac{1}{n} \sum_{i=1}^n Z'_i \Delta \varepsilon_i \right)' W_n \left(\frac{1}{n} \sum_{i=1}^n Z'_i \Delta \varepsilon_i \right),$$

using the weighting matrix

$$W_n = \left(\frac{1}{n} \sum_{i=1}^n \widehat{Z'_i \Delta \varepsilon_i \Delta \varepsilon_i'} Z_i \right)^{-1},$$

²If $\mathbf{x}_{i,t}$ is predetermined (exogenous), we can use $\mathbf{z}_{i,t} = [y_{i,t}, \mathbf{x}_{i,t+1}, \mathbf{x}'_{i,t}]'$ (respectively $\mathbf{z}_{i,t} = [y_{i,t}, \mathbf{x}_{i,t+2}, \mathbf{x}_{i,t+1}, \mathbf{x}'_{i,t}]'$).

where the $\widehat{\Delta\varepsilon_i}$'s are consistent estimates of the $\Delta\varepsilon_i$'s that result from a preliminary estimation. In this sense, this estimator is a two-step GMM one.

If the disturbances are homoskedastic, then it can be shown that an asymptotically equivalent (efficient) GMM estimator can be obtained by using:

$$W_{1,n} = \left(\frac{1}{n} Z_i' H Z_i \right)^{-1},$$

where H is is $(T - 2) \times (T - 2)$ matrix of the form:

$$H = \begin{bmatrix} 2 & -1 & 0 & \dots & 0 \\ -1 & 2 & -1 & & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & & -1 & 2 & -1 \\ 0 & \dots & 0 & -1 & 2 \end{bmatrix}.$$

It is straightforward to extend these GMM methods to cases where there is more than one lag of the dependent variable on the right-hand side of the equation or in cases where disturbances feature limited moving-average serial correlation.

The `pdynmc` package allows to run these GMM approaches (see Fritsch et al. (2019)). The following lines of code allow to replicate the results of Arellano and Bond (1991):

```
library(pdynmc)
data(EmplUK, package = "plm")
dat <- EmplUK
dat[,c(4:7)] <- log(dat[,c(4:7)])
m1 <- pdynmc(dat = dat, # name of the dataset
             varname.i = "firm", # name of the cross-section identifier
             varname.t = "year", # name of the time-series identifiers
             use.mc.diff = TRUE, # use moment conditions from equations in differences?
             use.mc.lev = FALSE, # use moment conditions from equations in levels?
             use.mc.nonlin = FALSE, # use nonlinear (quadratic) moment conditions?
             include.y = TRUE, # instruments should be derived from the lags of the
             varname.y = "emp", # name of the dependent variable in the dataset
             lagTerms.y = 2, # number of lags of the dependent variable
             fur.con = TRUE, # further control variables (covariates) are included?
             fur.con.diff = TRUE, # include further control variables in equations in differences?
             fur.con.lev = FALSE, # include further control variables in equations in levels?
             varname.reg.fur = c("wage", "capital", "output"), # covariate(s) -in the dataset-
             lagTerms.reg.fur = c(1,2,2), # number of lags of the further controls
             include.dum = TRUE, # A logical variable indicating whether dummy variables are included?
             dum.diff = TRUE, # A logical variable indicating whether dummy variables are included in differences?
             dum.lev = FALSE, # A logical variable indicating whether dummy variables are included in levels?
             varname.dum = "year",
```

```

w.mat = "iid.err", # One of the character strings c('"iid.err"', '"identit
std.err = "corrected",
estimation = "onestep", # One of the character strings c('"onestep"', '"tw
opt.meth = "none" # numerical optimization procedure. When no nonlinear mo
)
summary(m1,digits=3)

```

```

##
## Dynamic linear panel estimation (onestep)
## GMM estimation steps: 1
##
## Coefficients:
##      Estimate Std.Err.rob z-value.rob Pr(>|z.rob|)
## L1.emp      0.686226   0.144594    4.746    < 2e-16 ***
## L2.emp     -0.085358   0.056016   -1.524    0.12751
## L0.wage     -0.607821   0.178205   -3.411    0.00065 ***
## L1.wage      0.392623   0.167993    2.337    0.01944 *
## L0.capital   0.356846   0.059020    6.046    < 2e-16 ***
## L1.capital  -0.058001   0.073180   -0.793    0.42778
## L2.capital  -0.019948   0.032713   -0.610    0.54186
## L0.output    0.608506   0.172531    3.527    0.00042 ***
## L1.output   -0.711164   0.231716   -3.069    0.00215 **
## L2.output    0.105798   0.141202    0.749    0.45386
## 1979         0.009554   0.010290    0.929    0.35289
## 1980         0.022015   0.017710    1.243    0.21387
## 1981        -0.011775   0.029508   -0.399    0.68989
## 1982        -0.027059   0.029275   -0.924    0.35549
## 1983        -0.021321   0.030460   -0.700    0.48393
## 1976        -0.007703   0.031411   -0.245    0.80646
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## 41 total instruments are employed to estimate 16 parameters
## 27 linear (DIF)
## 8 further controls (DIF)
## 6 time dummies (DIF)
##
## J-Test (overid restrictions): 70.82 with 25 DF, pvalue: <0.001
## F-Statistic (slope coeff): 528.06 with 10 DF, pvalue: <0.001
## F-Statistic (time dummies): 14.98 with 6 DF, pvalue: 0.0204

```

We generate novel results (m2) by replacing “onestep” with “twostep” (in the estimation field). The resulting estimated coefficients are:

```
##      L1.emp      L2.emp      L0.wage      L1.wage      L0.capital      L1.capital
##  0.62870890 -0.06518800 -0.52575951  0.31128961  0.27836190  0.01409950
##  L2.capital      L0.output      L1.output      L2.output      1979      1980
## -0.04024847  0.59192286 -0.56598515  0.10054264  0.01121551  0.02306871
##      1981      1982      1983      1976
## -0.02135806 -0.03111604 -0.01799335 -0.02336762
```

Arellano and Bond (1991) have proposed a specification test. If the model is correctly specified, then the errors of Eq. (2.10) —that is the first-difference equation— should feature non-zero first-order auto-correlations, but zero higher-order autocorrelations.

Function `mtest.fct` of package `pdynmc` implements this test. Here is its result in the present case:

```
mtest.fct(m1,order=3)
```

```
##
##  Arellano and Bond (1991) serial correlation test of degree 3
##
## data:  1step GMM Estimation
## normal = 0.045945, p-value = 0.9634
## alternative hypothesis: serial correlation of order 3 in the error terms
```

One can also implement the Hansen J-test of the over-identifying restrictions (see Section 3.1.3):

```
jtest.fct(m1)
```

```
##
##  J-Test of Hansen
##
## data:  1step GMM Estimation
## chisq = 70.82, df = 25, p-value = 2.905e-06
## alternative hypothesis: overidentifying restrictions invalid
```

```
jtest.fct(m2)
```

```
##
##  J-Test of Hansen
##
## data:  2step GMM Estimation
## chisq = 31.381, df = 25, p-value = 0.1767
## alternative hypothesis: overidentifying restrictions invalid
```


2.6 Introduction to program evaluation

This section briefly introduces the econometrics of program evaluation. Program evaluation refer to the analysis of the causal effects of some “treatments” in a broad sense. These treatment can, e.g., correspond to the implementation (or announcement) of policy measures. A comprehensive review is proposed by Abadie and Cattaneo (2018). A seminal book on the subject is that of Angrist and Pischke (2008).

2.6.1 Presentation of the problem

To begin with, let us consider a single entity. To simplify notations, we drop the entity index (i). Let us denote by Y the outcome variable (for the variable of interest), by W is a binary variable indicating whether the considered entity has received treatment ($W = 1$) or not ($W = 0$), and by X a vector of covariates, assumed to be predetermined relative to the treatment. That is, W and X could be correlated, but the values of X have been determined before that of W (in such a way that the realization of W does not affect X). Typically, X contains characteristics of the considered entity.

We are interested in the effect of the treatment, that is:

$$Y_1 - Y_0,$$

where Y_1 correspond to the outcome obtained under treatment, while Y_0 is the outcome obtained without it. Notice that we have:

$$Y = (1 - W)Y_0 + WY_1.$$

The problem is that observing (Y, W, X) is not sufficient to observe the treatment effect $Y_1 - Y_0$. Additional assumptions are needed to estimate it, or, more precisely, its expectations (*average treatment effect*):

$$ATE = \mathbb{E}(Y_1 - Y_0).$$

Importantly, ATE is different from the following quantity:

$$\alpha = \underbrace{\mathbb{E}(Y|W = 1)}_{=\mathbb{E}(Y_1|W=1)} - \underbrace{\mathbb{E}(Y|W = 0)}_{=\mathbb{E}(Y_0|W=0)},$$

that is easier to estimate. Indeed, a consistent estimate of α is the difference between the means of the outcome variables in two sub-samples: one containing only the treated entities (this gives an estimate of $\mathbb{E}(Y_1|W = 1)$) and the other containing only the non-treated entities (this gives an estimate of $\mathbb{E}(Y_0|W = 0)$). Coming back to ATE , the problem is that we won't have direct information regarding $\mathbb{E}(Y_0|W = 1)$ and $\mathbb{E}(Y_1|W = 0)$. However, these two conditional expectations are part of ATE . Indeed, $ATE = \mathbb{E}(Y_1) - \mathbb{E}(Y_0)$, and:

$$\mathbb{E}(Y_1) = \mathbb{E}(Y_1|W = 0)\mathbb{P}(W = 0) + \mathbb{E}(Y_1|W = 1)\mathbb{P}(W = 1) \quad (2.11)$$

$$\mathbb{E}(Y_0) = \mathbb{E}(Y_0|W = 0)\mathbb{P}(W = 0) + \mathbb{E}(Y_0|W = 1)\mathbb{P}(W = 1). \quad (2.12)$$

2.6.2 Randomized controlled trials (RCTs)

In the context of Randomized controlled trials (RCTs), entities are randomly assigned to receive the treatment. As a result, we have $\mathbb{E}(Y_1) = \mathbb{E}(Y_1|W = 0) = \mathbb{E}(Y_1|W = 1)$ and $\mathbb{E}(Y_0) = \mathbb{E}(Y_0|W = 0) = \mathbb{E}(Y_0|W = 1)$. Using this into Eqs. (2.11) and (2.12) yields $ATE = \alpha$.

Therefore, in this context, estimating $\mathbb{E}(Y_1 - Y_0)$ amounts to computing the difference between two sample means, namely (a) the sample mean of the subset of Y_i 's corresponding to the entities for which $W_i = 1$, and (b) the one for which $W_i = 0$.

More accurate estimates can be obtained through regressions. Assume that the model reads:

$$Y_i = W_i\beta_1 + X_i'\beta_z + \varepsilon_i,$$

where $\mathbb{E}(\varepsilon_i|X_i) = 0$ (and W_i is independent from X_i and ε_i). In this case, we obtain a consistent estimate of β_1 by regressing \mathbf{y} on $\mathbf{Z} = [\mathbf{w}, \mathbf{X}]$.

2.6.3 Difference-in-Difference (DiD) approach

The DiD approach is a popular methodology implemented in cases where W cannot be considered as an independent variable. It exploits two dimensions: entities (i), and time (t). To simplify the exposition, we consider only two periods here ($t = 0$ and $t = 1$).

Consider the following model:

$$Y_{i,t} = W_{i,t}\beta_1 + \mu_i + \delta_t + \varepsilon_{i,t} \quad (2.13)$$

The parameter of interest is β_1 , which is the treatment effect (recall that $W_{i,t} \in \{0, 1\}$). Usually, for all entities i , we have $W_{i,t=0} = 0$. But only some of them are treated on date 1, i.e., $W_{i,1} \in \{0, 1\}$.

The disturbance $\varepsilon_{i,t}$ affects the outcome, but we assume that it does not relate to the selection for treatment; therefore, $\mathbb{E}(\varepsilon_{i,t}|W_{i,t}) = 0$. By contrast, we do not exclude some correlation between $W_{i,t}$ (for $t = 1$) and μ_i ; hence, μ_i may constitute a *confounder*. Finally, we suppose that the micro-variables W_i do not affect the time fixed effects δ_t , such that $\mathbb{E}(\delta_t|W_{i,t}) = \mathbb{E}(\delta_t)$.

We have:

$$\begin{aligned} \mathbb{E}(Y_{i,1}|W_{i,1} = 1) &= \beta_1 + \mathbb{E}(\mu_i|W_{i,1} = 1) + \mathbb{E}(\delta_1|W_{i,1} = 1) + \mathbb{E}(\varepsilon_{i,1}) \\ \mathbb{E}(Y_{i,0}|W_{i,1} = 1) &= \mathbb{E}(\mu_i|W_{i,1} = 1) + \mathbb{E}(\delta_0|W_{i,1} = 1) + \mathbb{E}(\varepsilon_{i,0}) \\ \mathbb{E}(Y_{i,1}|W_{i,1} = 0) &= \mathbb{E}(\mu_i|W_{i,1} = 0) + \mathbb{E}(\delta_1|W_{i,1} = 0) + \mathbb{E}(\varepsilon_{i,1}) \\ \mathbb{E}(Y_{i,0}|W_{i,1} = 0) &= \mathbb{E}(\mu_i|W_{i,1} = 0) + \mathbb{E}(\delta_0|W_{i,1} = 0) + \mathbb{E}(\varepsilon_{i,0}). \end{aligned}$$

and, under our assumptions, it can be checked that:

$$\beta_1 = \mathbb{E}(\Delta Y_{i,1}|W_{i,1} = 1) - \mathbb{E}(\Delta Y_{i,1}|W_{i,1} = 0),$$

where $\Delta Y_{i,1} = Y_{i,1} - Y_{i,0}$. Therefore, in this context, the treatment effect appears to be a difference (of two conditionnal expectations) of difference (of the outcome variable, through time).

This is illustrated by Figure 2.6, which represents the generic DiD framework.

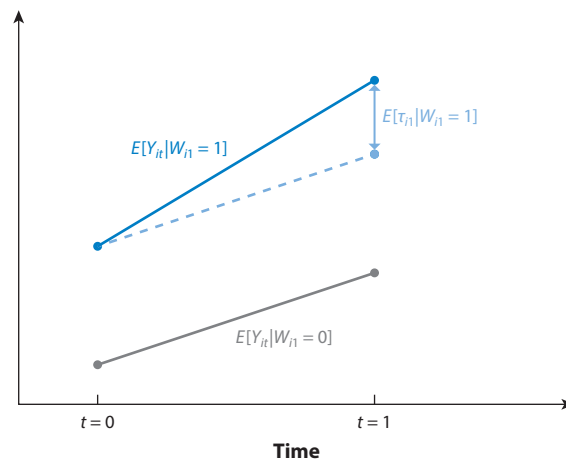


Figure 5

Identification in a difference-in-differences model. The dashed line represents the outcome that the treated units would have experienced in the absence of the treatment.

Figure 2.6: Source: Abadie et al., (1998).

In practice, implementing this approach consists in running a linear regression of the type of Eq. (2.13). These regressions often use time-invariant characteristics as controls instead of the fixed effects μ_i . As illustrated in the next subsection, the parameter of interest (β_1) is often associated with an interaction term.

Example 2.3 (Workers' compensation for injury on time out of work). This example is based on the data used in Meyer et al. (1995). This dataset is part of the `wooldridge` package. This paper examines the effect of workers' compensation for injury on time out of work. It exploits a **natural experiment** approach of comparing individuals injured before and after increases in the maximum weekly benefit amount. Specifically, in 1980, the cap on weekly earnings covered by worker's compensation was increased in Kentucky and Michigan. This can be exploited to check whether this new policy was followed by an increase in the amount of time workers spent unemployed (for example, higher compensation may reduce workers' incentives to avoid injury).

As shown in Figure 2.7, the measure has only affected high-earning workers. The idea exploited by Meyer et al. (1995) was to compare the increase in time out of work before-after 1980 for higher-earnings workers on the one hand (entities who received the treatment) and low-earnings workers on the other hand (control group).

The next lines of codes replicate some of their results. The dependent variable is the logarithm of the duration of benefits. For more information use `?injury`, after having loaded the `wooldridge` library.

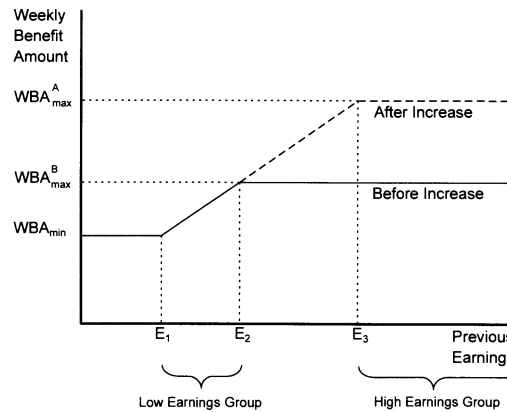


FIGURE 1. TEMPORARY TOTAL BENEFIT SCHEDULE BEFORE AND AFTER AN INCREASE IN THE MAXIMUM WEEKLY BENEFIT

Figure 2.7: Source: Meyer et al., (1995).

In the table of results below, the parameter of interest is the one associated with the interaction term `afchnge:highearn`. Columns 2 and 3 correspond to the first two column of Table 6 in Meyer et al. (1995).

```
library(wooldridge)
data(injury)
injury <- subset(injury, ky==1)
injury$indust <- as.factor(injury$indust)
injury$injtype <- as.factor(injury$injtype)
#names(injury)
eq1 <- lm(log(durat) ~ afchnge + highearn + afchnge*highearn, data=injury)
eq2 <- lm(log(durat) ~ afchnge + highearn + afchnge*highearn +
           lprewage*highearn + male + married + lage + ltotmed + hosp +
           indust + injtype, data=injury)
eq3 <- lm(log(durat) ~ afchnge + highearn + afchnge*highearn +
           lprewage*highearn + male + married + lage + indust +
           injtype, data=injury)
stargazer::stargazer(eq1, eq2, eq3, type="text",
                     omit=c("indust", "injtype", "Constant"), no.space = TRUE,
                     add.lines = list(c("industry dummy", "no", "yes", "yes"),
                                       c("injury dummy", "no", "yes", "yes")),
                     order = c(1, 2, 18, 3:17, 19, 20), omit.stat = c("f", "ser"))
```

```
##
## =====
##               Dependent variable:
##            -----
##                   log(durat)
```

##	(1)	(2)	(3)
## -----			
## afchnge	0.008	-0.004	0.016
##	(0.045)	(0.038)	(0.045)
## highearn	0.256***	-0.595	-1.522
##	(0.047)	(0.930)	(1.099)
## afchnge:highearn	0.191***	0.162***	0.215***
##	(0.069)	(0.059)	(0.069)
## lprewage		0.207**	0.258**
##		(0.088)	(0.104)
## male		-0.070*	-0.072
##		(0.039)	(0.046)
## married		0.055	0.051
##		(0.035)	(0.041)
## lage		0.244***	0.252***
##		(0.044)	(0.052)
## ltotmed		0.361***	
##		(0.011)	
## hosp		0.252***	
##		(0.044)	
## highearn:lprewage		0.065	0.232
##		(0.158)	(0.187)
## -----			
## industry dummy	no	yes	yes
## injury dummy	no	yes	yes
## Observations	5,626	5,347	5,347
## R2	0.021	0.319	0.049
## Adjusted R2	0.020	0.316	0.046
## =====			
## Note:	*p<0.1; **p<0.05; ***p<0.01		

Chapter 3

Estimation Methods

This chapter presents three approaches to estimate parametric models: the General Method of Moments (GMM), the Maximum Likelihood approach (ML), and the Bayesian approach. The general context is the following: You observe a sample $\mathbf{y} = \{y_1, \dots, y_n\}$, you assume that these data have been generated by a model parameterized by $\theta \in \mathbb{R}^K$, and you want to estimate this vector θ_0 .

3.1 Generalized Method of Moments (GMM)

3.1.1 Definition of the GMM estimator

We denote by y_i a $p \times 1$ vector of variables; by θ an $K \times 1$ vector of parameters, and by $h(y_i; \theta)$ a continuous $r \times 1$ vector-valued function.

We denote by θ_0 the true value of θ and we assume that θ_0 satisfies:

$$\mathbb{E}[h(y_i; \theta_0)] = \mathbf{0}.$$

We denote by \underline{y}_i the information contained in the current and past observations of y_i , that is: $\underline{y}_i = \{y_i, y_{i-1}, \dots, y_1\}$. We denote by $g(\underline{y}_n; \theta)$ the sample average of the $h(y_i; \theta)$ vectors, i.e.:

$$g(\underline{y}_n; \theta) = \frac{1}{n} \sum_{i=1}^n h(y_i; \theta).$$

The intuition behind the GMM estimator is the following: choose θ so as to make the sample moment as close as possible to their population values, that is 0.

Definition 3.1. A GMM estimator of θ_0 is given by:

$$\hat{\theta}_n = \operatorname{argmin}_{\theta} \quad g(\underline{y}_n; \theta)' W_n g(\underline{y}_n; \theta),$$

where W_n is a positive definite matrix (that may depend on \underline{y}_n).

In the specific case where $K = r$ (the dimension of θ is the same as that of $h(y_i; \theta)$ —or of $g(\underline{y}_n; \theta)$ — then $\hat{\theta}_n$ satisfies:

$$g(\underline{y}_n; \hat{\theta}_n) = \mathbf{0}.$$

Under regularity and identification conditions, this estimator is consistent, that is $\hat{\theta}_n$ converges towards θ_0 in probability, which we denote by:

$$\text{plim}_n \hat{\theta}_n = \theta_0, \quad \text{or} \quad \hat{\theta}_n \xrightarrow{p} \theta_0, \quad (3.1)$$

i.e. $\forall \varepsilon > 0, \lim_{n \rightarrow \infty} \mathbb{P}(|\hat{\theta}_n - \theta_0| > \varepsilon) = 0$ (this is Definition 8.16).

Definition 3.1 involves a positive definite matrix W_n . While one can take any positive definite matrix to have consistency (Eq. (3.1)), it can be shown that the GMM estimator achieves the minimum asymptotic variance when W_n is the inverse of matrix S , the latter being defined by:

$$S = \text{Asy.Var} \left(\sqrt{n} g(\underline{y}_n; \hat{\theta}_n) \right).$$

In this case, W_n is said to be the *optimal weighting matrix*.

The intuition behind this result is the same that underlies Generalized Least Squares (see Section 1.5.2), that is: it is beneficial to use a criterion in which the weights are inversely proportional to the variances of the moments.

If $h(x_i; \theta_0)$ is not correlated to $h(x_j; \theta_0)$, for $i \neq j$, then we have:

$$S = \text{Var}(h(x_i; \theta_0)),$$

which can be approximated by

$$\hat{\Gamma}_{0,n} = \frac{1}{n} \sum_{i=1}^n h(x_i; \hat{\theta}_n) h(x_i; \hat{\theta}_n)'$$

In a time series context, we often have correlation between x_i and x_{i+k} , especially for small k 's. In this case, and if the time series $\{y_i\}$ is covariance stationary, then we have:

$$S := \sum_{\nu=-\infty}^{\infty} \Gamma_{\nu},$$

where $\Gamma_{\nu} := \mathbb{E}[h(x_i; \theta_0) h(x_{i-\nu}; \theta_0)']$. Matrix S is called the *long-run variance* of process $\{y_i\}$.

For $\nu \geq 0$, let us define $\hat{\Gamma}_{\nu,n}$ by:

$$\hat{\Gamma}_{\nu,n} = \frac{1}{n} \sum_{i=\nu+1}^n h(x_i; \hat{\theta}_n) h(x_{i-\nu}; \hat{\theta}_n)',$$

then S can be approximated by the Newey and West (1987) formula:

$$\hat{\Gamma}_{0,n} + \sum_{\nu=1}^q \left[1 - \frac{\nu}{q+1} \right] (\hat{\Gamma}_{\nu,n} + \hat{\Gamma}_{\nu,n}'). \quad (3.2)$$

3.1.2 Asymptotic distribution of the GMM estimator

We have:

$$\boxed{\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \mathcal{N}(0, V)}, \quad (3.3)$$

where $V = (DS^{-1}D')^{-1}$, with

$$D := \mathbb{E} \left(\frac{\partial h(x_i; \theta)}{\partial \theta'} \right) \Big|_{\theta=\theta_0}.$$

Matrix V can be approximated by

$$\hat{V}_n = (\hat{D}_n \hat{S}_n^{-1} \hat{D}_n')^{-1}, \quad (3.4)$$

where \hat{S}_n is given by Eq. (3.2) and

$$\hat{D}_n' := \frac{\partial g(\underline{y}_n; \theta)}{\partial \theta'} \Big|_{\theta=\hat{\theta}_n}.$$

In practice, the previous matrix is computed numerically.

3.1.3 Testing hypotheses in the GMM framework

A first important test is the one concerning the validity of the moment restrictions (Sargan-Hansen test; Sargan (1958) and Hansen (1982)). Assume that the number of restrictions imposed is larger than the number of parameters to estimate ($r > K$). In this case, the restrictions are said to be over-identifying.

Under correct specification, we asymptotically have:

$$\sqrt{n}g(\underline{y}_n; \theta_0) \sim \mathcal{N}(0, S).$$

As a result, it comes that:

$$J_n = \left(\sqrt{n}g(\underline{y}_n; \theta_0) \right)' S^{-1} \left(\sqrt{n}g(\underline{y}_n; \theta_0) \right) \quad (3.5)$$

asymptotically follows a χ^2 distribution. The number of degrees of freedom is equal to $r - K$. (Note that, for $r = K$, we have, as expected, $J = 0$.) That is, asymptotically:

$$J_n \sim \chi^2(r - K).$$

The GMM framework also allows to easily test linear restrictions on the parameters. First, given Eq. (3.3), Wald tests (see Eq. (1.16) in Section 1.2.5) are readily available. Second, one can also resort to a test equivalent to the *likelihood ratio tests* (see Definition 3.8). More precisely, consider an unconstrained model and a constrained version of this model, the number of restrictions being equal to k . If the two models are estimated by considering the same moment constraints, and the same weighting matrix —using Eq. (3.4), based on the unrestricted model—, then we have that:

$$n \left[(g(\underline{y}_n; \hat{\theta}_n^*) - g(\underline{y}_n; \hat{\theta}_n)) \right] \sim \chi^2(k),$$

where $\hat{\theta}_n^*$ is the constrained estimate of θ_0 .

3.1.4 Example: Estimation of the Stochastic Discount Factor (s.d.f.)

Under the no-arbitrage assumption, there exists a random variable $\mathcal{M}_{t,t+1}$ (a s.d.f.) such that

$$\mathbb{E}_t(\mathcal{M}_{t,t+1}R_{t+1}) = 1$$

for any (gross) asset return R_t . In the following, R_t denotes a n_r -dimensional vector of gross returns.

We consider the following specification of the s.d.f.:

$$\mathcal{M}_{t,t+1} = 1 - \mathbf{b}'_M(F_{t+1} - \mathbb{E}_t(F_{t+1})), \quad (3.6)$$

where F_t is a vector of factors. Eq. (3.6) then reads:

$$\mathbb{E}_t([1 - \mathbf{b}'_M(F_{t+1} - \mathbb{E}_t(F_{t+1}))]R_{t+1}) = 1.$$

Assume that the date- t information set is $\mathcal{J}_t = \{\mathbf{z}_t, \mathcal{J}_{t-1}\}$, where \mathbf{z}_t is a vector of variables observed on date t . (We then have $\mathbb{E}_t(\bullet) \equiv \mathbb{E}(\bullet|\mathcal{J}_t)$.)

We can use \mathbf{z}_t as an instrument. Indeed, we have:

$$\begin{aligned} & \mathbb{E}(z_{i,t}[\mathbf{b}'_M\{F_{t+1} - \mathbb{E}_t(F_{t+1})\}R_{t+1} - R_{t+1} + 1]) \\ &= \mathbb{E}(\mathbb{E}_t\{z_{i,t}[\mathbf{b}'_M\{F_{t+1} - \mathbb{E}_t(F_{t+1})\}R_{t+1} - R_{t+1} + 1]\}) \\ &= \mathbb{E}(z_{i,t} \underbrace{\mathbb{E}_t\{\mathbf{b}'_M\{F_{t+1} - \mathbb{E}_t(F_{t+1})\}R_{t+1} - R_{t+1} + 1\}}_{1 - \mathbb{E}_t(\mathcal{M}_{t,t+1}R_{t+1})=0}) = 0. \end{aligned} \quad (3.7)$$

We have then converted a conditional moment condition into a unconditional one (which we need to implement the GMM approach described above). However, at that stage, we can still not directly use the GMM formulas because of the conditional expectation $\mathbb{E}_t(F_{t+1})$ that appears in $\mathbb{E}(z_{i,t}[\mathbf{b}'_M\{F_{t+1} - \mathbb{E}_t(F_{t+1})\}R_{t+1} - R_{t+1} + 1]) = 0$.

To go further, let us assume that:

$$\mathbb{E}_t(F_{t+1}) = \mathbf{b}_F \mathbf{z}_t.$$

We can then easily estimate matrix \mathbf{b}_F (of dimension $n_F \times n_z$) by OLS. Note here that these OLS can be seen as a special GMM case. Indeed, as was done in Eq. (3.7), we can show that, for the j^{th} component of F_t , we have:

$$\mathbb{E}([F_{j,t+1} - \mathbf{b}_{F,j}\mathbf{z}_t]\mathbf{z}_t) = 0,$$

where $\mathbf{b}_{F,j}$ denotes the j^{th} row of \mathbf{b}_F . This yields the OLS formula.

Equipped with \mathbf{b}_F , we rely on the following moment restrictions to estimate \mathbf{b}_M :

$$\mathbb{E}(z_{i,t}[\mathbf{b}'_M\{F_{t+1} - \mathbf{b}_F \mathbf{z}_t\}R_{t+1} - R_{t+1} + 1]) = 0.$$

Specifically, the number of restrictions is $n_R \times n_z$. Let us implement this approach in the U.S. context, using data extracted from the FRED database. In factor F_t , we use the changes in the VIX and in the personal consumption expenditures. The returns (R_t) are based on the Wilshire 5000 Price Index (a stock price index) and on the ICE BofA BBB US Corporate Index Total Return Index (a bond return index).

```
library(fredr)
fredr_set_key("df65e14c054697a52b4511e77fcfa1f3")
start_date <- as.Date("1990-01-01"); end_date <- as.Date("2022-01-01")
f <- function(ticker){
  fredr(series_id = ticker,
        observation_start = start_date, observation_end = end_date,
        frequency = "m", aggregation_method = "avg")
}
vix <- f("VIXCLS") # VIX
pce <- f("PCE") # Personal consumption expenditures
sto <- f("SPASTT01USM661N") # Stock price index
bdr <- f("BAMLCC0A4BBBTRIV") # ICE BofA BBB US Corp. Index Tot. Return
T <- dim(vix)[1]
dvix <- c(vix$value[3:T]/vix$value[2:(T-1)]) # change in VIX t+1
dpce <- c(pce$value[3:T]/pce$value[2:(T-1)]) # change in PCE t+1
dsto <- c(sto$value[3:T]/sto$value[2:(T-1)]) # return t+1
dbdr <- c(bdr$value[3:T]/bdr$value[2:(T-1)]) # return t+1
dvix_1 <- c(vix$value[2:(T-1)]/vix$value[1:(T-2)]) # change in VIX t
dpce_1 <- c(pce$value[2:(T-1)]/pce$value[1:(T-2)]) # change in PCE t
dsto_1 <- c(sto$value[2:(T-1)]/sto$value[1:(T-2)]) # return t
dbdr_1 <- c(bdr$value[2:(T-1)]/bdr$value[1:(T-2)]) # return t
```

Define the matrices containing the F_{t+1} , z_t , and R_{t+1} vectors:

```
F_tp1 <- cbind(dvix, dpce)
Z <- cbind(1, dvix_1, dpce_1, dsto_1, dbdr_1)
b_F <- t(solve(t(Z) %*% Z) %*% t(Z) %*% F_tp1)
F_innov <- F_tp1 - Z %*% t(b_F)
R_tp1 <- cbind(dsto, dbdr)
n_F <- dim(F_tp1)[2]; n_R <- dim(R_tp1)[2]; n_z <- dim(Z)[2]
```

Function `f_aux` compute the $h(x_t; \theta)$ and the $g(\underline{y}_T; \theta)$; function `f2beMin` is the function to be minimized.

```
f_aux <- function(theta){
  b_M <- matrix(theta[1:n_F], ncol=1)
  R_aux <- matrix(F_innov %*% b_M, T-2, n_R) * R_tp1 - R_tp1 + 1
  H <- (R_aux %x% matrix(1,1,n_z)) * (matrix(1,1,n_R) %x% Z)
```

```

g <- matrix(apply(H,2,mean),ncol=1)
return(list(g=g,H=H))
}
f2beMin <- function(theta,W){# function to be minimized
  res <- f_aux(theta)
  return(t(res$g) %*% W %*% res$g)
}

```

Now, let's minimize this function, using use the BFGS numerical algorithm (part of the optim wrapper). We run 5 iterations (where W is updated).

```

library(AEC)
theta <- c(rep(0,n_F)) # inital value
for(i in 1:10){# recursion on W
  res <- f_aux(theta)
  W <- solve(NW.LongRunVariance(res$H,q=6))
  res.optim <- optim(theta,f2beMin,W=W,
                    method="BFGS", # could be "Nelder-Mead"
                    control=list(trace=FALSE,maxit=200),hessian=TRUE)
  theta <- res.optim$par
}

```

Finally, let's compute the standard deviation of the parameter estimates, using Eq. (3.4):

```

eps <- .0001
g0 <- f_aux(theta)$g
D <- NULL
for(i in 1:length(theta)){
  theta.i <- theta
  theta.i[i] <- theta.i[i] + eps
  gi <- f_aux(theta.i)$g
  D <- cbind(D,(gi-g0)/eps)
}
V <- 1/T * solve(t(D) %*% W %*% D)
std.dev <- sqrt(diag(V));t.stud <- theta/std.dev
cbind(theta,std.dev,t.stud)

```

```

##           theta    std.dev    t.stud
## [1,]  -1.352152  0.9725812 -1.390272
## [2,] -80.373739 48.2598742 -1.665436

```

The Hansen statistic can be used to test the model (see Eq. (3.5)). If the model is correct, we have:

$$Tg(\underline{y}_T; \theta)' S^{-1} g(\underline{y}_T; \theta) \sim i.i.d. \chi^2(J - K),$$

where J is the number of moment constraints ($n_z \times n_r$ here) and K is the number of estimated parameters ($= n_F$ here).

```
g <- f_aux(theta)$g
Hansen_stat <- T * t(g) %*% W %*% g
pvalue <- pchisq(q = Hansen_stat, df = n_R*n_z - n_F)
pvalue
```

```
##           [,1]
## [1,] 0.3133884
```

3.2 Maximum Likelihood Estimation

3.2.1 Intuition

Intuitively, the *Maximum Likelihood Estimation (MLE)* consists in looking for the value of θ that is such that the probability of having observed \mathbf{y} (the sample at hand) is the highest possible.

To set an example, assume that the time periods between the arrivals of two customers in a shop, denoted by y_i , are i.i.d. and follow an exponential distribution, i.e. $y_i \sim i.i.d. \mathcal{E}(\lambda)$. You have observed these arrivals for some time, thereby constituting a sample $\mathbf{y} = \{y_1, \dots, y_n\}$. You want to estimate λ (i.e. in that case, the vector of parameters is simply $\theta = \lambda$).

The density of Y (one observation) is $f(y; \lambda) = \frac{1}{\lambda} \exp(-y/\lambda)$. Fig. 3.1 represents such density functions for different values of λ .

Your 200 observations are reported at the bottom of Fig. 3.1 (red bars). You build the histogram and display it on the same chart.

What is your estimate of λ ? Intuitively, one is led to take the λ for which the (theoretical) distribution is the closest to the histogram (that can be seen as an “empirical distribution”). This approach is consistent with the idea of picking the λ for which the probability of observing the values included in \mathbf{y} is the highest.

Let us be more formal. Assume that you have only four observations: $y_1 = 1.1$, $y_2 = 2.2$, $y_3 = 0.7$ and $y_4 = 5.0$. What was the probability of jointly observing:

- $1.1 - \varepsilon \leq Y_1 < 1.1 + \varepsilon$,
- $2.2 - \varepsilon \leq Y_2 < 2.2 + \varepsilon$,
- $0.7 - \varepsilon \leq Y_3 < 0.7 + \varepsilon$, and
- $5.0 - \varepsilon \leq Y_4 < 5.0 + \varepsilon$?

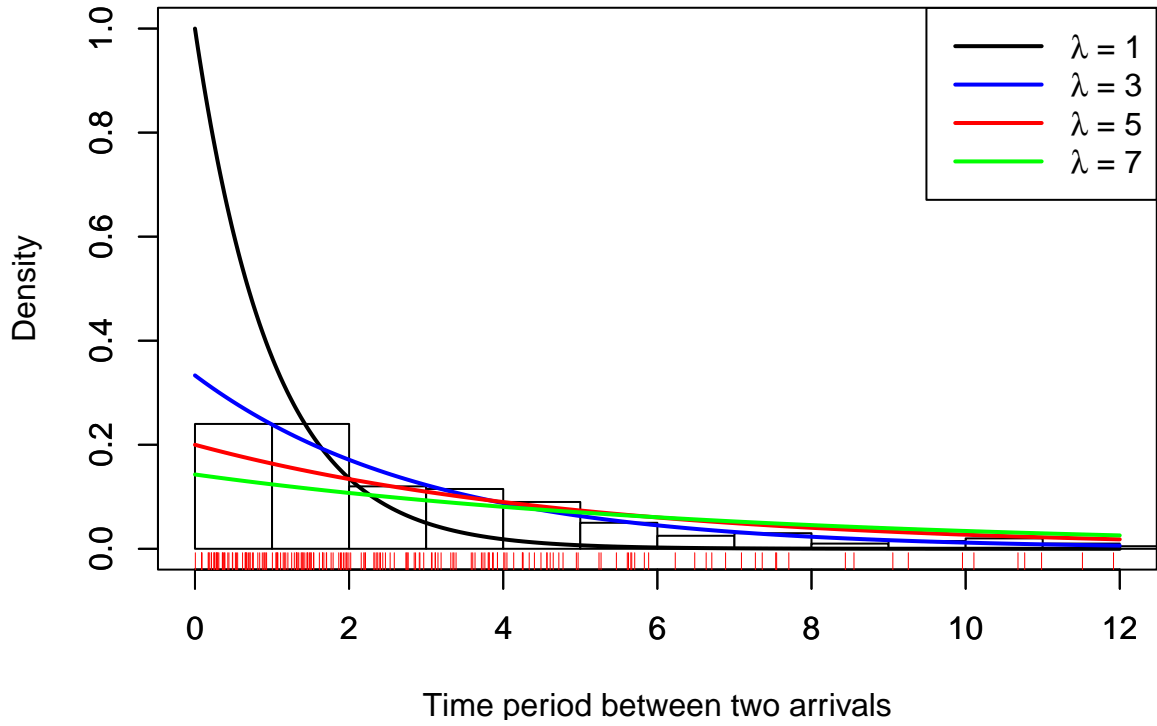


Figure 3.1: The red ticks, at the bottom, indicate observations (there are 200 of them). The histogram is based on these 200 observations

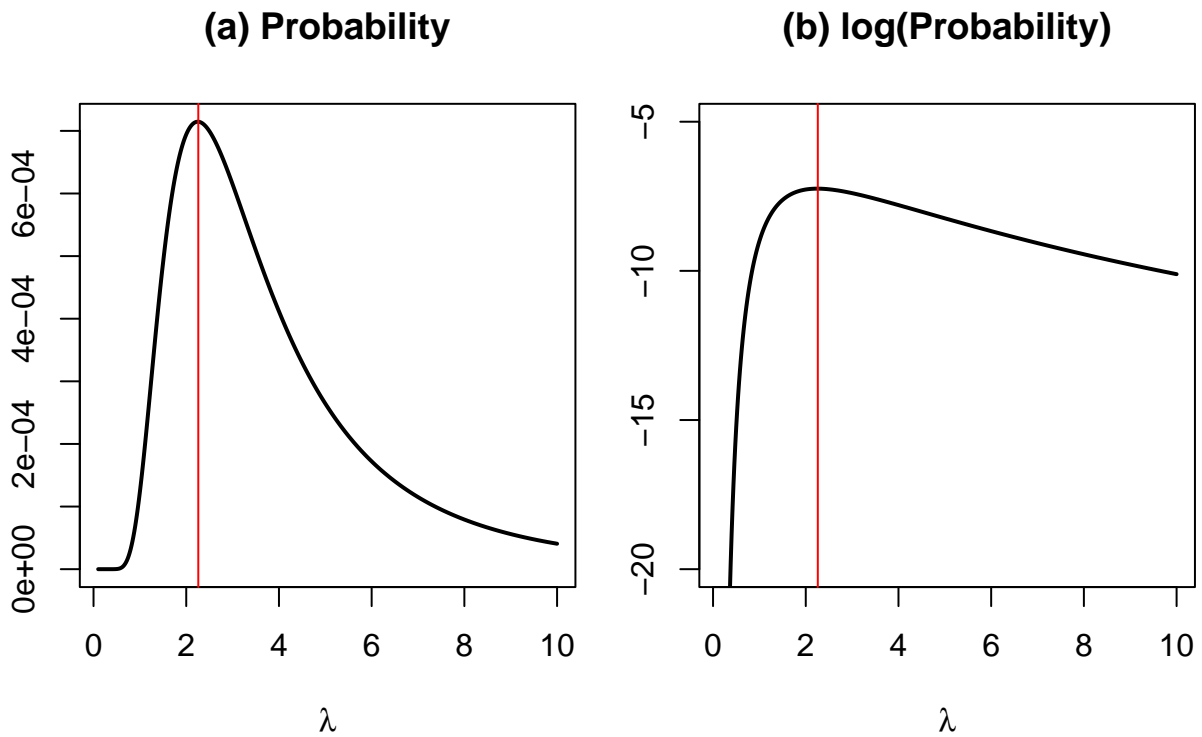


Figure 3.2: Proba. that $y_i - \varepsilon \leq Y_i < y_i + \varepsilon$, $i \in \{1, 2, 3, 4\}$. The vertical red line indicates the maximum of the function.

Because the y_i 's are i.i.d., this probability is $\prod_{i=1}^4 (2\varepsilon f(y_i, \lambda))$. The next plot shows the probability (divided by $16\varepsilon^4$, which does not depend on λ) as a function of λ .

The value of λ that maximizes the probability is 2.26.

Let us come back to the example with 200 observations:

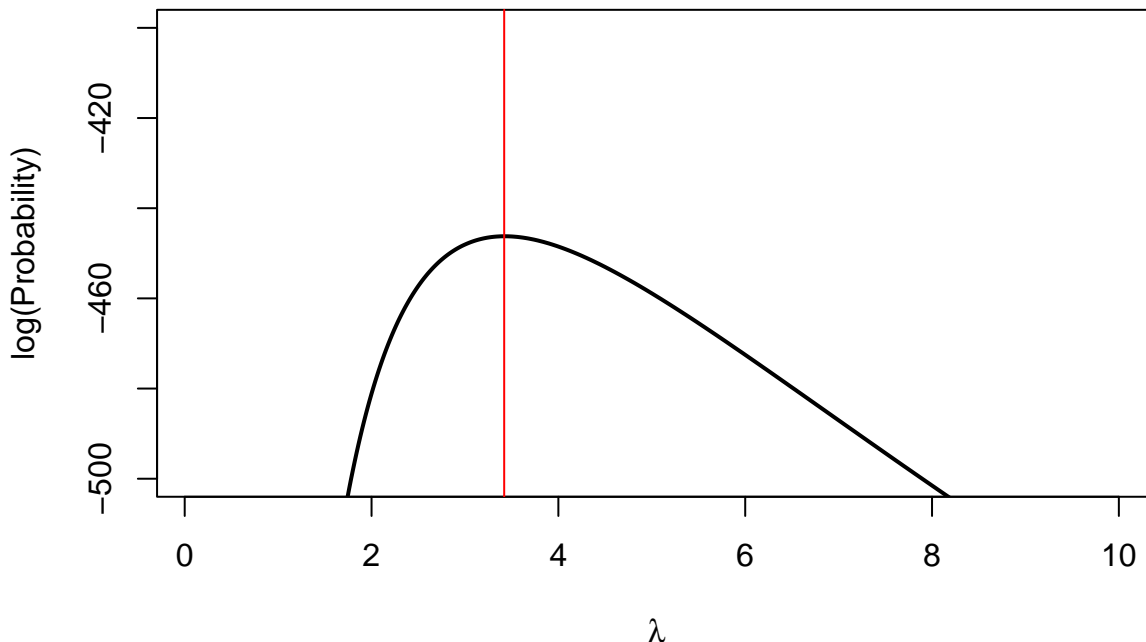


Figure 3.3: Log-likelihood function associated with the 200 i.i.d. observations. The vertical red line indicates the maximum of the function.

In that case, the value of λ that maximizes the probability is 3.42.

3.2.2 Definition and properties

$f(y; \theta)$ denotes the probability density function (p.d.f.) of a random variable Y which depends on a set of parameters θ . The density of n independent and identically distributed (i.i.d.) observations of Y is given by:

$$f(\mathbf{y}; \theta) = \prod_{i=1}^n f(y_i; \theta),$$

where \mathbf{y} denotes the vector of observations; $\mathbf{y} = \{y_1, \dots, y_n\}$.

Definition 3.2 (Likelihood function). The likelihood function is:

$$\mathcal{L} : \theta \rightarrow \mathcal{L}(\theta; \mathbf{y}) = f(\mathbf{y}; \theta) = f(y_1, \dots, y_n; \theta).$$

We often work with $\log \mathcal{L}$, the **log-likelihood function**.

Example 3.1 (Gaussian distribution). If $y_i \sim \mathcal{N}(\mu, \sigma^2)$, then

$$\log \mathcal{L}(\theta; \mathbf{y}) = -\frac{1}{2} \sum_{i=1}^n \left(\log \sigma^2 + \log 2\pi + \frac{(y_i - \mu)^2}{\sigma^2} \right).$$

Definition 3.3 (Score). The score $S(y; \theta)$ is given by $\frac{\partial \log f(y; \theta)}{\partial \theta}$.

If $y_i \sim \mathcal{N}(\mu, \sigma^2)$ (Example 3.1), then

$$\frac{\partial \log f(y; \theta)}{\partial \theta} = \begin{bmatrix} \frac{\partial \log f(y; \theta)}{\partial \mu} \\ \frac{\partial \log f(y; \theta)}{\partial \sigma^2} \end{bmatrix} = \begin{bmatrix} \frac{y - \mu}{\sigma^2} \\ \frac{1}{2\sigma^2} \left(\frac{(y - \mu)^2}{\sigma^2} - 1 \right) \end{bmatrix}.$$

Proposition 3.1 (Score expectation). *The expectation of the score is zero.*

Proof. We have:

$$\begin{aligned} \mathbb{E} \left(\frac{\partial \log f(Y; \theta)}{\partial \theta} \right) &= \int \frac{\partial \log f(y; \theta)}{\partial \theta} f(y; \theta) dy \\ &= \int \frac{\partial f(y; \theta) / \partial \theta}{f(y; \theta)} f(y; \theta) dy = \frac{\partial}{\partial \theta} \int f(y; \theta) dy \\ &= \partial 1 / \partial \theta = 0, \end{aligned}$$

which gives the result. \square

Definition 3.4 (Fisher information matrix). The information matrix is (minus) the expectation of the second derivatives of the log-likelihood function:

$$\mathcal{J}_Y(\theta) = -\mathbb{E} \left(\frac{\partial^2 \log f(Y; \theta)}{\partial \theta \partial \theta'} \right).$$

Proposition 3.2. *We have*

$$\mathcal{J}_Y(\theta) = \mathbb{E} \left[\left(\frac{\partial \log f(Y; \theta)}{\partial \theta} \right) \left(\frac{\partial \log f(Y; \theta)}{\partial \theta} \right)' \right] = \text{Var}[S(Y; \theta)].$$

Proof. We have $\frac{\partial^2 \log f(Y; \theta)}{\partial \theta \partial \theta'} = \frac{\partial^2 f(Y; \theta)}{\partial \theta \partial \theta'} \frac{1}{f(Y; \theta)} - \frac{\partial \log f(Y; \theta)}{\partial \theta} \frac{\partial \log f(Y; \theta)}{\partial \theta'}$. The expectation of the first right-hand side term is $\partial^2 1 / (\partial \theta \partial \theta') = \mathbf{0}$, which gives the result. \square

Example 3.2. If $y_i \sim i.i.d. \mathcal{N}(\mu, \sigma^2)$, let $\theta = [\mu, \sigma^2]'$ then

$$\frac{\partial \log f(y; \theta)}{\partial \theta} = \begin{bmatrix} \frac{y - \mu}{\sigma^2} & \frac{1}{2\sigma^2} \left(\frac{(y - \mu)^2}{\sigma^2} - 1 \right) \end{bmatrix}',$$

and

$$\mathcal{J}_Y(\theta) = \mathbb{E} \left(\frac{1}{\sigma^4} \begin{bmatrix} \sigma^2 & y - \mu \\ y - \mu & \frac{(y - \mu)^2}{\sigma^2} - \frac{1}{2} \end{bmatrix} \right) = \begin{bmatrix} 1/\sigma^2 & 0 \\ 0 & 1/(2\sigma^4) \end{bmatrix}.$$

Proposition 3.3 (Additive property of the Information matrix). *The information matrix resulting from two independent experiments is the sum of the information matrices:*

$$\mathcal{I}_{X,Y}(\theta) = \mathcal{I}_X(\theta) + \mathcal{I}_Y(\theta).$$

Proof. Directly deduced from the definition of the information matrix (Def. 3.4), using that the expectation of a product of independent variables is the product of the expectations. \square

Theorem 3.1 (Frechet-Darmois-Cramer-Rao bound). *Consider an unbiased estimator of θ denoted by $\hat{\theta}(Y)$. The variance of the random variable $\omega' \hat{\theta}$ (which is a linear combination of the components of $\hat{\theta}$) is larger than:*

$$(\omega' \omega)^2 / (\omega' \mathcal{I}_Y(\theta) \omega).$$

Proof. The Cauchy-Schwarz inequality implies that $\sqrt{\text{Var}(\omega' \hat{\theta}(Y)) \text{Var}(\omega' S(Y; \theta))} \geq |\omega' \text{Cov}[\hat{\theta}(Y), S(Y; \theta)] \omega|$. Now, $\text{Cov}[\hat{\theta}(Y), S(Y; \theta)] = \int_y \hat{\theta}(y) \frac{\partial \log f(y; \theta)}{\partial \theta} f(y; \theta) dy = \frac{\partial}{\partial \theta} \int_y \hat{\theta}(y) f(y; \theta) dy = \mathbf{I}$ because $\hat{\theta}$ is unbiased. Therefore $\text{Var}(\omega' \hat{\theta}(Y)) \geq \text{Var}(\omega' S(Y; \theta))^{-1} (\omega' \omega)^2$. Prop. 3.2 leads to the result. \square

Definition 3.5 (Identifiability). The vector of parameters θ is identifiable if, for any other vector θ^* :

$$\theta^* \neq \theta \Rightarrow \mathcal{L}(\theta^*; \mathbf{y}) \neq \mathcal{L}(\theta; \mathbf{y}).$$

Definition 3.6 (Maximum Likelihood Estimator (MLE)). The maximum likelihood estimator (MLE) is the vector θ that maximizes the likelihood function. Formally:

$$\theta_{MLE} = \arg \max_{\theta} \mathcal{L}(\theta; \mathbf{y}) = \arg \max_{\theta} \log \mathcal{L}(\theta; \mathbf{y}). \quad (3.8)$$

Definition 3.7 (Likelihood equation). A necessary condition for maximizing the likelihood function (under regularity assumption, see Hypotheses 3.1) is:

$$\frac{\partial \log \mathcal{L}(\theta; \mathbf{y})}{\partial \theta} = \mathbf{0}. \quad (3.9)$$

Hypothesis 3.1 (Regularity assumptions). We have:

- i. $\theta \in \Theta$ where Θ is compact.
- ii. θ_0 is identified.
- iii. The log-likelihood function is continuous in θ .
- iv. $\mathbb{E}_{\theta_0}(\log f(Y; \theta))$ exists.
- v. The log-likelihood function is such that $(1/n) \log \mathcal{L}(\theta; \mathbf{y})$ converges almost surely to $\mathbb{E}_{\theta_0}(\log f(Y; \theta))$, uniformly in $\theta \in \Theta$.
- vi. The log-likelihood function is twice continuously differentiable in an open neighborhood of θ_0 .
- vii. The matrix $\mathbf{I}(\theta_0) = -\mathbb{E}_0 \left(\frac{\partial^2 \log \mathcal{L}(\theta; \mathbf{y})}{\partial \theta \partial \theta'} \right)$ —the Fisher Information matrix— exists and is nonsingular.

Proposition 3.4 (Properties of MLE). *Under regularity conditions (Assumptions 3.1), the MLE is:*

- a. **Consistent:** $\text{plim } \theta_{MLE} = \theta_0$ (θ_0 is the true vector of parameters).
- b. **Asymptotically normal:**

$$\boxed{\sqrt{n}(\theta_{MLE} - \theta_0) \xrightarrow{d} \mathcal{N}(0, \mathcal{I}_Y(\theta_0)^{-1})}. \quad (3.10)$$

- c. **Asymptotically efficient:** θ_{MLE} is asymptotically efficient and achieves the Freechet-Darmois-Cramer-Rao lower bound for consistent estimators.
- d. **Invariant:** The MLE of $g(\theta_0)$ is $g(\theta_{MLE})$ if g is a continuous and continuously differentiable function.

Proof. See Appendix 8.4. □

Since $\mathcal{I}_Y(\theta_0) = \frac{1}{n}\mathbf{I}(\theta_0)$, the asymptotic covariance matrix of the MLE is $[\mathbf{I}(\theta_0)]^{-1}$, that is:

$$[\mathbf{I}(\theta_0)]^{-1} = \left[-\mathbb{E}_0 \left(\frac{\partial^2 \log \mathcal{L}(\theta; \mathbf{y})}{\partial \theta \partial \theta'} \right) \right]^{-1}.$$

A direct (analytical) evaluation of this expectation is often out of reach. It can however be estimated by, either:

$$\hat{\mathbf{I}}_1^{-1} = \left(-\frac{\partial^2 \log \mathcal{L}(\theta_{MLE}; \mathbf{y})}{\partial \theta \partial \theta'} \right)^{-1}, \quad (3.11)$$

$$\hat{\mathbf{I}}_2^{-1} = \left(\sum_{i=1}^n \frac{\partial \log \mathcal{L}(\theta_{MLE}; y_i)}{\partial \theta} \frac{\partial \log \mathcal{L}(\theta_{MLE}; y_i)}{\partial \theta'} \right)^{-1}. \quad (3.12)$$

Asymptotically, we have $(\hat{\mathbf{I}}_1^{-1})\hat{\mathbf{I}}_2 = Id$, that is, the two formulas provide the same result.

In case of (suspected) misspecification, one can use the so-called *sandwich estimator* of the covariance matrix.¹ This covariance matrix is given by:

$$\hat{\mathbf{I}}_3^{-1} = \hat{\mathbf{I}}_2^{-1} \hat{\mathbf{I}}_1 \hat{\mathbf{I}}_2^{-1}. \quad (3.13)$$

3.2.3 To sum up – MLE in practice

To implement MLE, we need:

- A parametric model (depending on the vector of parameters θ whose “true” value is θ_0) is specified.

¹For more details, see, e.g., Charles Geyer’s lectures notes.

- i.i.d. sources of randomness are identified.
- The density associated to one observation y_i is computed analytically (as a function of θ): $f(y; \theta)$.
- The log-likelihood is $\log \mathcal{L}(\theta; \mathbf{y}) = \sum_i \log f(y_i; \theta)$.
- The MLE estimator results from the optimization problem (this is Eq. (3.8)):

$$\theta_{MLE} = \arg \max_{\theta} \log \mathcal{L}(\theta; \mathbf{y}). \quad (3.14)$$

- We have: $\theta_{MLE} \sim \mathcal{N}(\theta_0, \mathbf{I}(\theta_0)^{-1})$, where $\mathbf{I}(\theta_0)^{-1}$ is estimated by means of Eq. (3.11), Eq. (3.12), or Eq. (3.13). Most of the time, this computation is numerical.

3.2.4 Example: MLE estimation of a mixture of Gaussian distribution

Consider the returns of the Swiss Market Index (SMI). Assume that these returns are independently drawn from a mixture of Gaussian distributions. The p.d.f. $f(x; \theta)$, with $\theta = [\mu_1, \sigma_1, \mu_2, \sigma_2, p]'$, is given by:

$$p \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(-\frac{(x - \mu_1)^2}{2\sigma_1^2}\right) + (1 - p) \frac{1}{\sqrt{2\pi\sigma_2^2}} \exp\left(-\frac{(x - \mu_2)^2}{2\sigma_2^2}\right).$$

(See p.d.f. of mixtures of Gaussian distributions.)

```
library(AEC); data(smi)
T <- dim(smi)[1]
h <- 5 # holding period (one week)
smi$r <- c(rep(NA, h),
           100*c(log(smi$Close[(1+h):T]/smi$Close[1:(T-h)])))
indic.dates <- seq(1, T, by=5) # weekly returns
smi <- smi[indic.dates,]
smi <- smi[complete.cases(smi),]
par(mfrow=c(1,1)); par(plt=c(.15, .95, .1, .95))
plot(smi$Date, smi$r, type="l", xlab="", ylab="in percent")
abline(h=0, col="blue")
abline(h=mean(smi$r, na.rm = TRUE)+2*sd(smi$r, na.rm = TRUE), lty=3, col="blue")
abline(h=mean(smi$r, na.rm = TRUE)-2*sd(smi$r, na.rm = TRUE), lty=3, col="blue")
```

Build the log-likelihood function (function `log.f`), and use the numerical BFGS algorithm to maximize it (using the `optim` wrapper):

```
f <- function(theta, y){ # Likelihood function
  mu.1 <- theta[1]; mu.2 <- theta[2]
  sigma.1 <- theta[3]; sigma.2 <- theta[4]
```

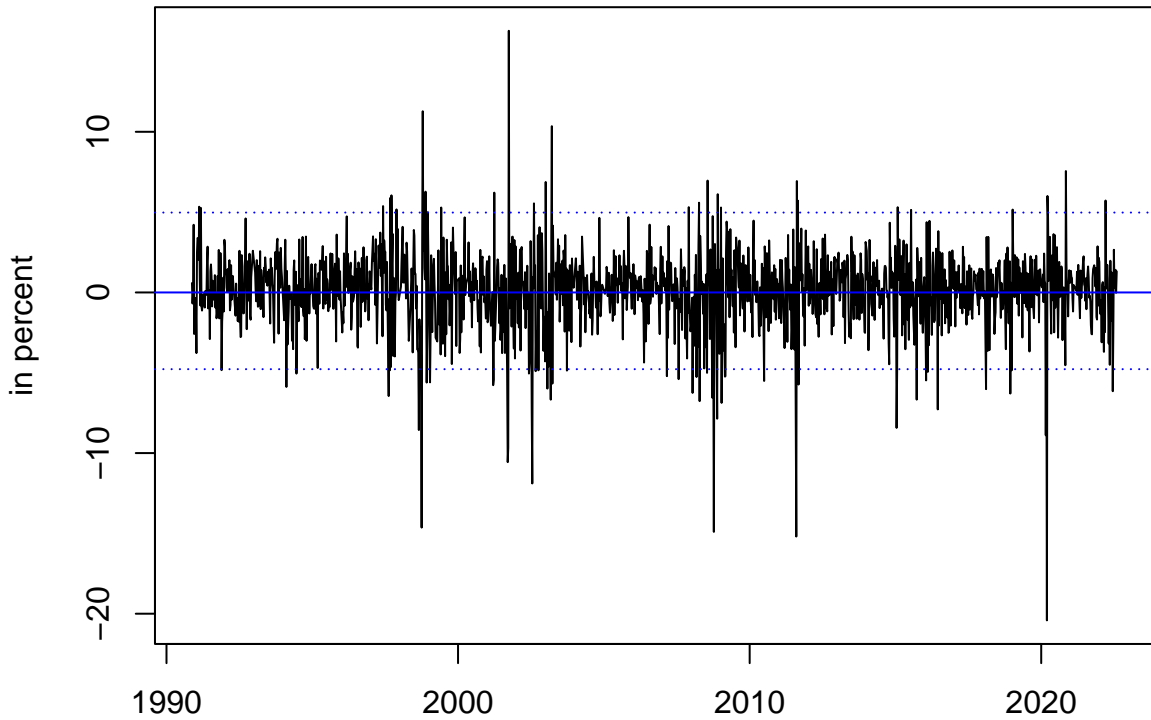


Figure 3.4: Time series of SMI weekly returns (source: Yahoo Finance).

```
p <- exp(theta[5])/(1+exp(theta[5]))
res <- p*1/sqrt(2*pi*sigma.1^2)*exp(-(y-mu.1)^2/(2*sigma.1^2)) +
  (1-p)*1/sqrt(2*pi*sigma.2^2)*exp(-(y-mu.2)^2/(2*sigma.2^2))
return(res)
}
log.f <- function(theta,y){ #log-Likelihood function
  return(-sum(log(f(theta,y))))
}
res.optim <- optim(c(0,0,0.5,1.5,.5),
  log.f,
  y=smi$r,
  method="BFGS", # could be "Nelder-Mead"
  control=list(trace=FALSE,maxit=100),hessian=TRUE)
theta <- res.optim$par
theta
```

```
## [1] 0.3012379 -1.3167476 1.7715072 4.8197596 1.9454889
```

Next, compute estimates of the covariance matrix of the MLE (using Eqs. (3.11), (3.12), and (3.13)), and compare the three sets of resulting standard deviations for the five estimated parameters:

```

# Hessian approach:
I.1 <- solve(res.optim$hessian)
# Outer-product of gradient approach:
log.f.0 <- log(f(theta,smi$r))
epsilon <- .00000001
d.log.f <- NULL
for(i in 1:length(theta)){
  theta.i <- theta
  theta.i[i] <- theta.i[i] + epsilon
  log.f.i <- log(f(theta.i,smi$r))
  d.log.f <- cbind(d.log.f,
                   (log.f.i - log.f.0)/epsilon)
}
I.2 <- solve(t(d.log.f) %*% d.log.f)
# Misspecification-robust approach (sandwich formula):
I.3 <- I.1 %*% solve(I.2) %*% I.1
cbind(diag(I.1),diag(I.2),diag(I.3))

```

```

##           [,1]      [,2]      [,3]
## [1,] 0.003683422 0.003199481 0.00586160
## [2,] 0.226892824 0.194283391 0.38653389
## [3,] 0.005764271 0.002769579 0.01712255
## [4,] 0.194081311 0.047466419 0.83130838
## [5,] 0.092114437 0.040366005 0.31347858

```

According to the first (respectively third) type of estimate for the covariance matrix, a 95% confidence interval for μ_1 is [0.182, 0.42] (resp. [0.151, 0.451]).

Note that we have not directly estimated parameter p but $\nu = \log(p/(1-p))$ (in such a way that $p = \exp(\nu)/(1 + \exp(\nu))$). In order to get an estimate of the standard deviation of our estimate of p , we can implement the **Delta method**. This method is based on the fact that, for a function g that is continuous in the neighborhood of θ_0 and for large n , we have:

$$\text{Var}(g(\hat{\theta}_n)) \approx \frac{\partial g(\hat{\theta}_n)}{\partial \theta'} \text{Var}(\hat{\theta}_n) \frac{\partial g(\hat{\theta}_n)'}{\partial \theta}. \quad (3.15)$$

```

g <- function(theta){
  mu.1 <- theta[1]; mu.2 <- theta[2]
  sigma.1 <- theta[3]; sigma.2 <- theta[4]
  p <- exp(theta[5])/(1+exp(theta[5]))
  return(c(mu.1,mu.2,sigma.1,sigma.2,p))
}
# Computation of g's gradient around estimated theta:
eps <- .00001

```

```

g.theta <- g(theta)
g.gradient <- NULL
for(i in 1:5){
  theta.perturb <- theta
  theta.perturb[i] <- theta[i] + eps
  g.gradient <- cbind(g.gradient, (g(theta.perturb)-g.theta)/eps)
}
Var <- g.gradient %*% I.3 %*% t(g.gradient)
stdv.g.theta <- sqrt(diag(Var))
stdv.theta <- sqrt(diag(I.3))
cbind(theta, stdv.theta, g.theta, stdv.g.theta)

```

```

##           theta stdv.theta      g.theta stdv.g.theta
## [1,]  0.3012379 0.07656108  0.3012379  0.07656108
## [2,] -1.3167476 0.62171850 -1.3167476  0.62171850
## [3,]  1.7715072 0.13085316  1.7715072  0.13085316
## [4,]  4.8197596 0.91176114  4.8197596  0.91176114
## [5,]  1.9454889 0.55989158  0.8749539  0.06125726

```

The previous results show that the MLE estimate of p is 0.8749539, and its standard deviation is approximately equal to 0.0612573.

To finish with, let us draw the estimated parametric p.d.f. (the mixture of Gaussian distribution), and compare it to a non-parametric (kernel-based) estimate of this p.d.f. (using function `density`):

```

x <- seq(-5,5,by=.01)
par(plt=c(.1,.95,.1,.95))
plot(x,f(theta,x),type="l",lwd=2,xlab="returns, in percent",ylab="",
      ylim=c(0,1.4*max(f(theta,x))))
lines(density(smi$r),type="l",lwd=2,lty=3)
lines(x,dnorm(x,mean=mean(smi$r),sd = sd(smi$r)),col="red",lty=2,lwd=2)
rug(smi$r,col="blue")
legend("topleft",
      c("Kernel estimate (non-parametric)",
        "Estimated mixture of Gaussian distr. (MLE, parametric)",
        "Normal distribution"),
      lty=c(3,1,2),lwd=c(2), # line width
      col=c("black","black","red"),pt.bg=c(1),pt.cex = c(1),
      bg="white",seg.len = 4)

```

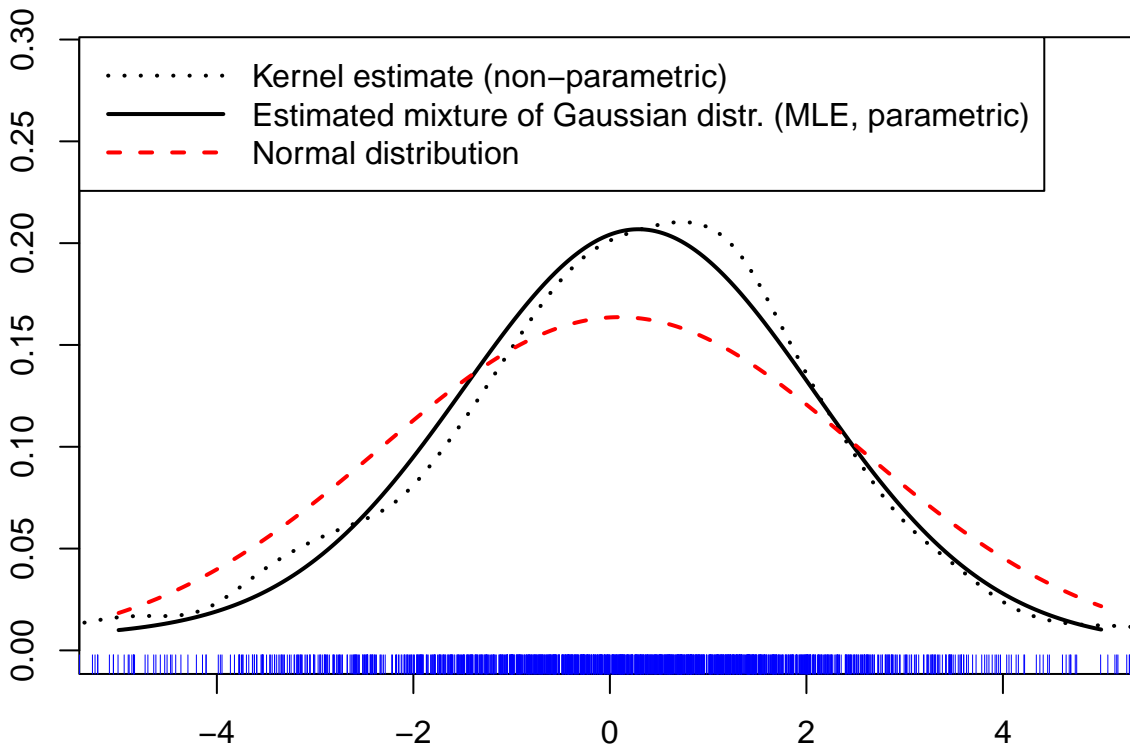


Figure 3.5: Comparison of different estimates of the distribution of returns.

3.2.5 Test procedures

Suppose we want to test the following parameter restrictions:

$$H_0 : \underbrace{h(\theta)}_{r \times 1} = 0. \quad (3.16)$$

In the context of MLE, three tests are largely used:

- Likelihood Ratio (LR) test,
- Wald (W) test,
- Lagrange Multiplier (LM) test.

Here is the rationale behind these three tests:²

- LR: If $h(\theta) = 0$, then imposing this restriction during the estimation (restricted estimator) should not result in a large decrease in the likelihood function (w.r.t the unrestricted estimation).
- Wald: If $h(\theta) = 0$, then $h(\hat{\theta})$ should not be far from 0 (even if these restrictions are not imposed during the MLE).

²An interesting graphical presentation of the tests is proposed in Buse (1982).

- LM: If $h(\theta) = 0$, then the gradient of the likelihood function should be small when evaluated at the restricted estimator.

In terms of implementation, while the LR necessitates to estimate both restricted and unrestricted models, the Wald test requires the estimation of the unrestricted model only, and the LM tests requires the estimation of the restricted model only.

As shown below, the three test statistics associated with these three tests coincide asymptotically. (Therefore, they naturally have the same asymptotic distribution, that are χ^2 .)

Proposition 3.5 (Asymptotic distribution of the Wald statistic). *Under regularity conditions (Assumptions 3.1) and under $H_0 : h(\theta) = 0$, the Wald statistic, defined by:*

$$\xi^W = h(\hat{\theta})' \text{Var}[h(\hat{\theta})]^{-1} h(\hat{\theta}),$$

where

$$\text{Var}[h(\hat{\theta})] = \left(\frac{\partial h(\hat{\theta})}{\partial \theta'} \right) \text{Var}[\hat{\theta}] \left(\frac{\partial h(\hat{\theta})'}{\partial \theta} \right), \quad (3.17)$$

is asymptotically $\chi^2(r)$, where the number of degrees of freedom r corresponds to the dimension of $h(\theta)$. (Note that Eq. (3.17) is the same as the one used in the Delta method, see Eq. (3.15).)

The Wald test, defined by the critical region

$$\{\xi^W \geq \chi_{1-\alpha}^2(r)\},$$

where $\chi_{1-\alpha}^2(r)$ denotes the quantile of level $1 - \alpha$ of the $\chi^2(r)$ distribution, has asymptotic level α and is consistent.³

Proof. See Appendix 8.4. □

In practice, in Eq. (3.17), $\text{Var}[\hat{\theta}]$ is replaced by an estimate given, e.g., by Eq. (3.11), Eq. (3.12), or Eq. (3.13).

Proposition 3.6 (Asymptotic distribution of the LM test statistic). *Under regularity conditions (Assumptions 3.1) and under $H_0 : h(\theta) = 0$, the LM statistic*

$$\xi^{LM} = \left(\frac{\partial \log \mathcal{L}(\theta)}{\partial \theta'} \bigg|_{\theta=\hat{\theta}^0} \right) [\mathbf{I}(\hat{\theta}^0)]^{-1} \left(\frac{\partial \log \mathcal{L}(\theta)}{\partial \theta} \bigg|_{\theta=\hat{\theta}^0} \right), \quad (3.18)$$

(where $\hat{\theta}^0$ is the restricted MLE estimator) is $\chi^2(r)$.

The test defined by the critical region:

$$\{\xi^{LM} \geq \chi_{1-\alpha}^2(r)\}$$

has asymptotic level α and is consistent (see Defs. 8.7 and 8.8). This test is called Score or Lagrange Multiplier (LM) test.

³See Defs. 8.7 and 8.8 for definitions of the asymptotic levels and consistency of tests.

Proof. See Appendix 8.4. □

Definition 3.8 (Likelihood Ratio test statistics). The likelihood ratio associated to a restriction of the form $H_0 : h(\theta) = 0$ is given by:

$$LR = \frac{\mathcal{L}_R(\theta; \mathbf{y})}{\mathcal{L}_U(\theta; \mathbf{y})} \quad (\in [0, 1]),$$

where \mathcal{L}_R (respectively \mathcal{L}_U) is the likelihood function that imposes (resp. that does not impose) the restriction. The likelihood ratio test statistic is given by $-2 \log(LR)$, that is:

$$\xi^{LR} = 2(\log \mathcal{L}_U(\theta; \mathbf{y}) - \log \mathcal{L}_R(\theta; \mathbf{y})).$$

Proposition 3.7 (Asymptotic equivalence of LR, LM, and Wald tests). *Under the null hypothesis H_0 , we have, asymptotically:*

$$\xi^{LM} = \xi^{LR} = \xi^W.$$

Proof. See Appendix 8.4. □

3.3 Bayesian approach

3.3.1 Introduction

An excellent introduction to Bayesian methods is proposed by Martin Haugh, 2017.

As suggested by the name of this approach, the starting point is the Bayes formula:

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \& B)}{\mathbb{P}(B)},$$

where A and B are two “events”. For instance, A may be: parameter α (conceived as something stochastic) lies in interval $[a, b]$. Assume that you are interested in the probability of occurrence of A . Without any specific information (or “unconditionally”), this probability is $\mathbb{P}(A)$. Your evaluation of this probability can only be better if you are provided with any additional form of information. Typically, if the event B tends to occur simultaneously with A , then knowledge of B can be useful. The Bayes formula says how this additional information (on B) can be used to “update” the probability of event A .

In our case, this intuition will work as follows: assume that you know the form of the data-generating process (DGP). That is, you know the structure of the model used to draw some stochastic data; you also know the type of distributions used to generate these data. However, you do not know the numerical values of all the parameters characterizing the DGP. Let us denote by θ the vector of unknown parameters. While these parameters are not known exactly, assume that we have—even without having observed any data—some **priors** on their distribution. Then, as was the case in the example above (with A and B), the observation

of data generated by the model can only reduce the uncertainty associated with θ . Loosely speaking, combining the priors and the observations of data generated by the model should result in “thinner” distributions for the components of θ . The latter distributions are called the **posterior distributions**.⁴

Let us formalize this intuition. Define the prior by $f_\theta(\theta)$ and the model realizations (the “data”) by vector \mathbf{y} . The joint distribution of (\mathbf{y}, θ) is given by:

$$f_{Y,\theta}(\mathbf{y}, \theta) = f_{Y|\theta}(\mathbf{y}, \theta)f_\theta(\theta),$$

and, symmetrically, by

$$f_{Y,\theta}(\mathbf{y}, \theta) = f_{\theta|Y}(\theta, \mathbf{y})f_Y(\mathbf{y}),$$

where $f_{\theta|Y}(\cdot, \mathbf{y})$, the distribution of the parameters conditional on the observations, is the **posterior** distribution.

The last two equations imply that:

$$f_{\theta|Y}(\theta, \mathbf{y}) = \frac{f_{Y|\theta}(\mathbf{y}, \theta)f_\theta(\theta)}{f_Y(\mathbf{y})}. \quad (3.19)$$

Note that f_Y is the marginal (or unconditional) distribution of \mathbf{y} , that can be written:

$$f_Y(\mathbf{y}) = \int f_{Y|\theta}(\mathbf{y}, \theta)f_\theta(\theta)d\theta. \quad (3.20)$$

Eq. (3.19) is sometimes rewritten as follows:

$$f_{\theta|Y}(\theta, \mathbf{y}) \propto f_{\theta,Y}(\theta, \mathbf{y}) := f_{Y|\theta}(\mathbf{y}, \theta)f_\theta(\theta), \quad (3.21)$$

where \propto means, loosely speaking, “*proportional to*”. In rare instances, starting from given priors, one can analytically compute the posterior distribution $f_\theta(\theta, \mathbf{y})$. However, in most cases, this is out of reach. One then has to resort to numerical approaches to compute the posterior distribution. Monte Carlo Markov Chains (MCMC) is one of them.

According to the Bernstein-von Mises Theorem, Bayesian and MLE estimators have the same large sample properties. (In particular, the Bayesian approach also achieve the FDCR bound, see Theorem 3.1.) The intuition behind this result is that the influence of the prior diminishes with increasing sample sizes.

3.3.2 Monte-Carlo Markov Chains

MCMC techniques aim at using simulations to approach a distribution whose distribution is difficult to obtain analytically. Indeed, in some circumstances, one can draw in a distribution even if we do not know its analytical expression.

⁴The output of the Bayesian approach will be the (posterior) distribution of the vector of parameters (θ). When we speak about the *distributions of the components of θ* , we mean the marginal distributions of each component of the vector.

Definition 3.9 (Markov Chain). The sequence $\{z_i\}$ is said to be a (first-order) Markovian process if it satisfies:

$$f(z_i | z_{i-1}, z_{i-2}, \dots) = f(z_i | z_{i-1}).$$

The Metropolis-Hastings (MH) algorithm is a specific MCMC approach that allows to generate samples of θ 's whose distribution approximately corresponds to the posterior distribution of Eq. (3.19).

The MH algorithm is a recursive algorithm. That is, one can draw the i^{th} value of θ , denoted by θ_i , if one has already drawn θ_{i-1} . Assume we have θ_{i-1} . We obtain a value for θ_i by implementing the following steps:

1. Draw $\tilde{\theta}_i$ from the conditional distribution $Q_{\tilde{\theta}|\theta}(\cdot, \theta_{i-1})$, called **proposal distribution**.
2. Draw u in a uniform distribution on $[0, 1]$.
3. Compute

$$\alpha(\tilde{\theta}_i, \theta_{i-1}) := \min \left(\frac{f_{\theta,Y}(\tilde{\theta}_i, \mathbf{y})}{f_{\theta,Y}(\theta_{i-1}, \mathbf{y})} \times \frac{Q_{\tilde{\theta}|\theta}(\theta_{i-1}, \tilde{\theta}_i)}{Q_{\tilde{\theta}|\theta}(\tilde{\theta}_i, \theta_{i-1})}, 1 \right), \quad (3.22)$$

where $f_{\theta,Y}$ is given in Eq. (3.21).

4. If $u < \alpha(\tilde{\theta}_i, \theta_{i-1})$, then take $\theta_i = \tilde{\theta}_i$, otherwise we leave θ_i equal to θ_{i-1} .

It can be shown that, the distribution of the draws converges to the posterior distribution. That is, after a sufficiently large number of iterations, the draws can be considered to be drawn from the posterior distribution.⁵

To get some insights into the algorithm, consider the case of a **symmetric proposal distribution**, that is:

$$Q_{\tilde{\theta}|\theta}(\tilde{\theta}_i, \theta_{i-1}) = Q_{\tilde{\theta}|\theta}(\theta_{i-1}, \tilde{\theta}_i). \quad (3.23)$$

We then have:

$$\alpha(\tilde{\theta}, \theta_{i-1}) = \min \left(\frac{q(\tilde{\theta}, y)}{q(\theta_{i-1}, y)}, 1 \right). \quad (3.24)$$

Remember that, up to the marginal distribution of the data ($f_Y(\mathbf{y})$), $f_{\theta,Y}(\tilde{\theta}, \mathbf{y})$ is the probability of observing \mathbf{y} conditional on having a model parameterized by $\tilde{\theta}$. Then, under Eq. (3.24), it appears that if this probability is larger for $\tilde{\theta}$ than for θ_{i-1} (in which case $\tilde{\theta}$ seems “more consistent with the observations \mathbf{y} ” than θ_{i-1}), we accept θ_i . By contrast, if $f_{\theta,Y}(\tilde{\theta}, \mathbf{y}) < f_{\theta,Y}(\theta_{i-1}, \mathbf{y})$, then we do not necessarily accept the proposed value $\tilde{\theta}$, especially if $f_{\theta,Y}(\tilde{\theta}, \mathbf{y}) \ll f_{\theta,Y}(\theta_{i-1}, \mathbf{y})$ (in which case $\tilde{\theta}$ seems far less consistent with the observations \mathbf{y} than θ_{i-1} , and, accordingly, the acceptance probability, namely $\alpha(\tilde{\theta}, \theta_{i-1})$, is small).

The choice of the **proposal distribution** $Q_{\tilde{\theta}|\theta}$ is crucial to get a rapid convergence of the algorithm. Looking at Eq. (3.22), it is easily seen that the optimal choice would be

⁵The proof of this claim is based on the fact that, if θ_{i-1} is drawn from the posterior distribution, then it is also the case for θ_i .

$Q_{\tilde{\theta}|\theta}(\cdot, \theta_i) = f_{\theta|Y}(\cdot, \mathbf{y})$. In that case, we would have $\alpha(\tilde{\theta}_i, \theta_{i-1}) \equiv 1$ (see Eq. (3.22)). We would then accept all draws from the proposal distribution, as this distribution would directly be the posterior distribution. Of course, this situation is not realistic as the objective of the algorithm is precisely to approximate the posterior distribution.

A common choice for Q is a multivariate normal distribution. If θ is of dimension K , we can for instance use:

$$Q(\tilde{\theta}, \theta) = \frac{1}{(\sqrt{2\pi}\sigma^2)^K} \exp \left(-\frac{1}{2} \sum_{j=1}^K \frac{(\tilde{\theta}_j - \theta_j)^2}{\sigma^2} \right),$$

which is an example of symmetric proposal distribution (see Eq. (3.23)). Equivalently, we then have:

$$\tilde{\theta} = \theta + \varepsilon,$$

where ε is a K -dimensional vector of independent zero-mean normal disturbances of variance σ^2 .⁶ One then has to determine an appropriate value for σ . If it is too low, then α will be close to 1 (as $\tilde{\theta}_i$ will be close to θ_{i-1}), and we will accept very often the proposed value ($\tilde{\theta}_i$). This seems to be a favourable situation. But it may not be. Indeed, it means that it will take a large number of iterations to explore the whole distribution of θ . What if σ is very large? In this case, it is likely that the proposed values ($\tilde{\theta}_i$) will often result in poor likelihoods; The probability of acceptance will then be low and the Markov chain may be blocked at its initial value. Therefore, intermediate values of σ^2 have to be determined. The acceptance rate (i.e., the average value of $\alpha(\tilde{\theta}, \theta_{i-1})$) can be used as a guide for that. Indeed, a literature explores the optimal values for such acceptance rate (in order to obtain the best possible fit of the posterior for a minimum number of algorithm iterations). In particular, following Roberts et al. (1997), people often target acceptance rate of the order of magnitude of 20%.

It is important to note that, to implement this approach, one only has to be able to compute the joint p.d.f. $q(\theta, \mathbf{y}) = f_{Y|\theta}(\mathbf{y}, \theta)f_{\theta}(\theta)$ (Eq. (3.21)). That is, as soon as one can evaluate the likelihood ($f_{Y|\theta}(\mathbf{y}, \theta)$) and the prior ($f_{\theta}(\theta)$), we can employ this methodology.

3.3.3 Example: AR(1) specification

In the following example, we employ MCMC in order to estimate the posterior distributions of the three parameters defining an AR(1) model. The specification is as follows:

$$y_t = \mu + \rho y_{t-1} + \sigma \varepsilon_t, \quad \varepsilon_t \sim i.i.d. \mathcal{N}(0, 1).$$

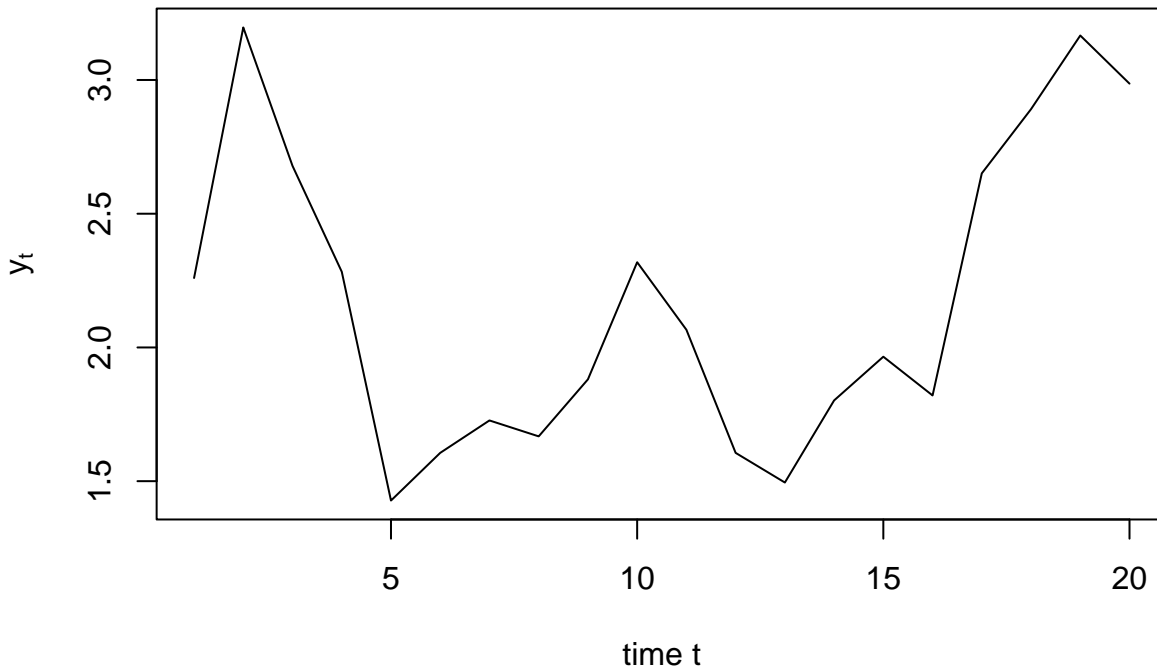
Hence, we have $\theta = [\mu, \rho, \sigma]$. Let us first simulate the process on T periods:

⁶We could also have different variances for the different components of θ . However, this may lead to complicated settings. A useful practice consists in looking for model (re)parametrization –based, e.g., on exponential and/or logistic functions– that are such that the components of θ are all expected to be of the order of magnitude of the unity.

```

mu <- .6; rho <- .8; sigma <- .5 # true model specification
T <- 20 # number of observations
y0 <- mu/(1-rho)
Y <- NULL
for(t in 1:T){
  if(t==1){y <- y0}
  y <- mu + rho*y + sigma * rnorm(1)
  Y <- c(Y,y)}
plot(Y,type="l",xlab="time t",ylab=expression(y[t]))

```



Next, let us write the likelihood function, i.e. $f_{Y|\theta}(\mathbf{y}, \theta)$. For ρ , which is expected to be between 0 and 1, we use a logistic transformation. For σ , that is expected to be positive, we use an exponential transformation.

```

likelihood <- function(param,Y){
  mu <- param[1]
  rho <- exp(param[2])/(1+exp(param[2]))
  sigma <- exp(param[3])
  MU <- mu/(1-rho)
  SIGMA2 <- sigma^2/(1-rho^2)
  L <- 1/sqrt(2*pi*SIGMA2)*exp(-(Y[1]-MU)^2/(2*SIGMA2))
  Y1 <- Y[2:length(Y)]
  Y0 <- Y[1:(length(Y)-1)]
  aux <- 1/sqrt(2*pi*sigma^2)*exp(-(Y1-mu-rho*Y0)^2/(2*sigma^2))
  L <- L * prod(aux)
  return(L)
}

```

Next define function `rQ` that draws from the (Gaussian) proposal distribution, as well as function `Q`, that computes $Q_{\tilde{\theta}|\theta}(\tilde{\theta}, \theta)$:

```
rQ <- function(x,a){
  n <- length(x)
  y <- x + a * rnorm(n)
  return(y)}
Q <- function(y,x,a){
  q <- 1/sqrt(2*pi*a^2)*exp(-(y - x)^2/(2*a^2))
  return(prod(q))}
```

We consider Gaussian priors:

```
prior <- function(param,means_prior,stdv_prior){
  f <- 1/sqrt(2*pi*stdv_prior^2)*exp(-(param -
                                         means_prior)^2/(2*stdv_prior^2))
  return(prod(f))}
```

Function `p_tilde` corresponds to $f_{\theta,Y}$:

```
p_tilde <- function(param,Y,means_prior,stdv_prior){
  p <- likelihood(param,Y) * prior(param,means_prior,stdv_prior)
  return(p)}
```

We can now define function α (Eq. (3.22)):

```
alpha <- function(y,x,means_prior,stdv_prior,a){
  aux <- p_tilde(y,Y,means_prior,stdv_prior)/
    p_tilde(x,Y,means_prior,stdv_prior) * Q(y,x,a)/Q(x,y,a)
  alpha_proba <- min(aux,1)
  return(alpha_proba)}
```

Now, all is set for us to write the MCMC function:

```
MCMC <- function(Y,means_prior,stdv_prior,a,N){
  x <- means_prior
  all_theta <- NULL
  count_accept <- 0
  for(i in 1:N){
    y <- rQ(x,a)
    alph <- alpha(y,x,means_prior,stdv_prior,a)
    #print(alph)
    u <- runif(1)
```

```

if(u < alph){
  count_accept <- count_accept + 1
  x <- y}
all_theta <- rbind(all_theta,x)}
print(paste("Acceptance rate:",toString(round(count_accept/N,3))))
return(all_theta)}

```

Specify the Gaussian priors:

```

true_values <- c(mu,log(rho/(1-rho)),log(sigma))
means_prior <- c(1,0,0) # as if we did not know the true values
stdv_prior <- rep(2,3)
resultMCMC <- MCMC(Y,means_prior,stdv_prior,a=.45,N=20000)

```

```
## [1] "Acceptance rate: 0.098"
```

```

par(mfrow=c(2,3))
for(i in 1:length(means_prior)){
  m <- means_prior[i]
  s <- stdv_prior[i]
  x <- seq(m-3*s,m+3*s,length.out = 100)
  par(mfg=c(1,i))
  aux <- density(resultMCMC[,i])
  par(plt=c(.15,.95,.15,.85))
  plot(x,dnorm(x,m,s),type="l",xlab="",ylab="",main=paste("Parameter",i),
       ylim=c(0,max(aux$y)))
  lines(aux$x,aux$y,col="red",lwd=2)
  abline(v=true_values[i],lty=2,col="blue")
  par(mfg=c(2,i))
  plot(resultMCMC[,i],1:length(resultMCMC[,i]),xlim=c(min(x),max(x)),
       type="l",xlab="",ylab="")
}

```

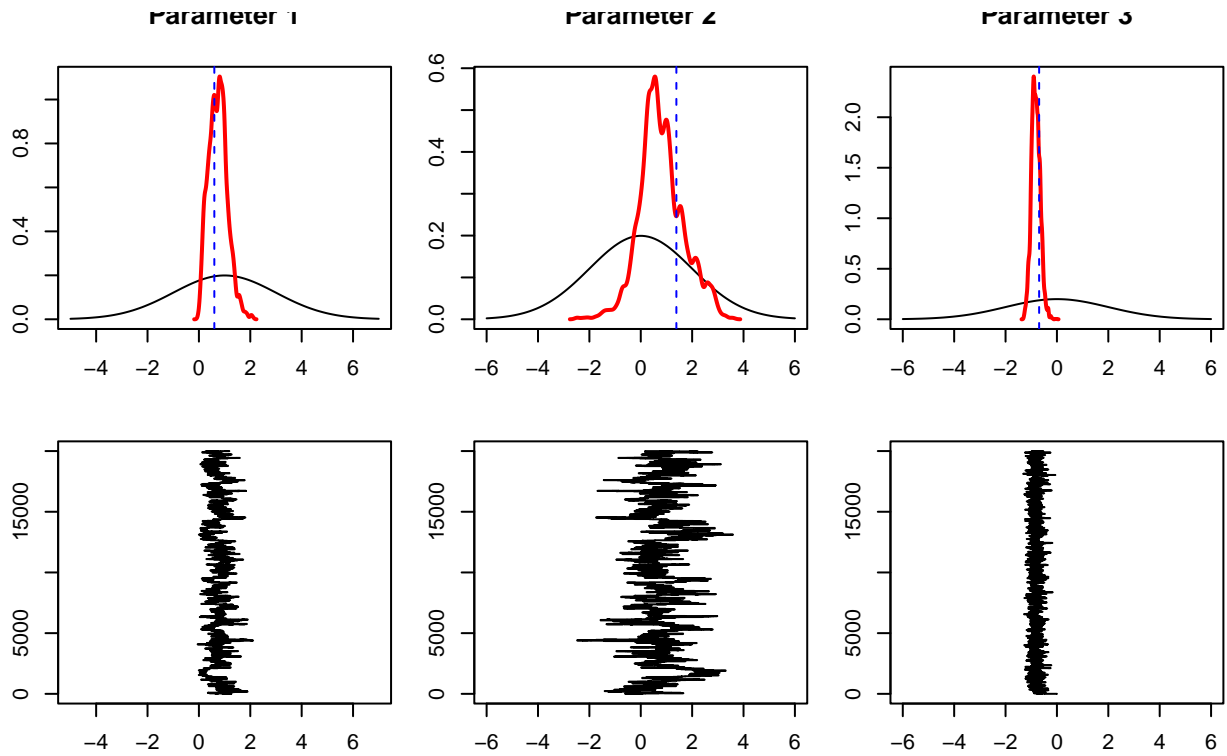


Figure 3.6: The upper line of plot compares prior (black) and posterior (red) distributions. The vertical dashed blue lines indicate the true values of the parameters. The second row of plots show the sequence of θ_i 's generated by the MCMC algorithm. These sequences are the ones used to produce the posterior distributions (red lines) in the upper plots.

Chapter 4

Binary-choice models

In microeconomic models, the variables of interest often feature restricted distributions—for instance with discontinuous support—which necessitates specific models. In many instances, the variables to be explained (the y_i 's) have only two possible values (0 and 1, say). That is, they are binary variables. The probability for them to be equal to either 0 or 1 may depend on independent variables, gathered in vectors \mathbf{x}_i ($K \times 1$).

The spectrum of applications is wide:

- Binary decisions (e.g. in referendums, being owner or renter, living in the city or in the countryside, in/out of the labour force,...),
- Contamination (disease or default),
- Success/failure (exams).

Without loss of generality, the model reads:

$$y_i|\mathbf{X} \sim \mathcal{B}(g(\mathbf{x}_i; \theta)), \quad (4.1)$$

where $g(\mathbf{x}_i; \theta)$ is the parameter of the Bernoulli distribution. In other words, conditionally on \mathbf{X} :

$$y_i = \begin{cases} 1 & \text{with probability } g(\mathbf{x}_i; \theta) \\ 0 & \text{with probability } 1 - g(\mathbf{x}_i; \theta), \end{cases} \quad (4.2)$$

where θ is a vector of parameters to be estimated.

An estimation strategy is to assume that $g(\mathbf{x}_i; \theta)$ can be proxied by $\tilde{\theta}' \mathbf{x}_i$ and to run a linear regression to estimate $\tilde{\theta}$ (a situation called **Linear Probability Model, LPM**):

$$y_i = \tilde{\theta}' \mathbf{x}_i + \varepsilon_i.$$

Notwithstanding the fact that this specification does not exclude negative probabilities or probabilities greater than one, it could be compatible with the *assumption of zero conditional mean* (Hypothesis 1.2) and with the *assumption of non-correlated residuals* (Hypothesis 1.4), but more difficultly with the *homoskedasticity assumption* (Hypothesis 1.3). Moreover, the

ε_i 's cannot be Gaussian (because $y_i \in \{0, 1\}$). Hence, using a linear regression to study the relationship between \mathbf{x}_i and y_i can be consistent but it is inefficient.

Figure 4.1 illustrates the fit resulting from an application of the LPM model to binary (dependent) variables.

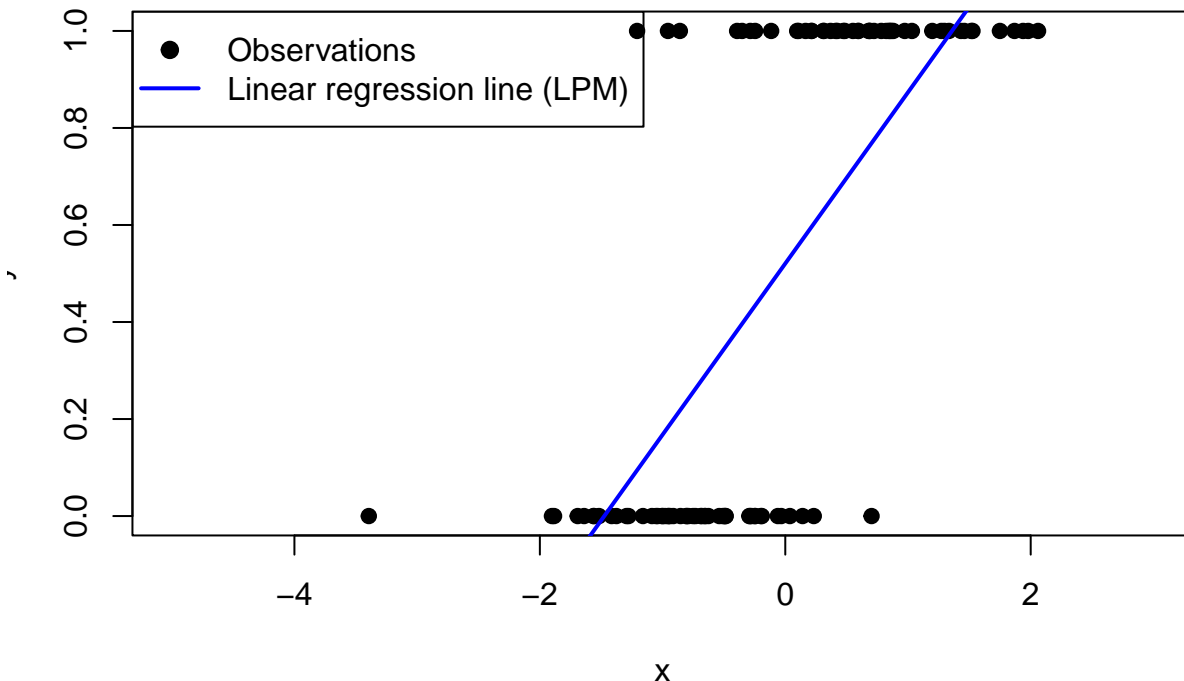


Figure 4.1: Fitting a binary variable with a linear model (Linear Probability Model, LPM). The model is $\mathbb{P}(y_i = 1|x_i) = \Phi(0.5 + 2x_i)$, where Φ is the c.d.f. of the normal distribution and where $x_i \sim i.i.d. \mathcal{N}(0, 1)$.

Except for its last row (LPM case), Table 4.1 provides examples of functions g valued in $[0, 1]$, and that can therefore be used in models of the type: $\mathbb{P}(y_i = 1|\mathbf{x}_i; \theta) = g(\theta' \mathbf{x}_i)$ (see Eq. (4.2)). The “linear” case is given for comparison, but note that it does not satisfy $g(\theta' \mathbf{x}_i) \in [0, 1]$ for any value of $\theta' \mathbf{x}_i$.

Table 4.1: This table provides examples of function g , s.t. $\mathbb{P}(y_i = 1|\mathbf{x}_i; \theta) = g(\theta' \mathbf{x}_i)$. The LPM case (last row) is given for comparison but, again, it does not satisfy $g(\theta' \mathbf{x}_i) \in [0, 1]$ for any value of $\theta' \mathbf{x}_i$.

Model	Function g	Derivative
Probit	Φ	ϕ
Logit	$\frac{\exp(x)}{1 + \exp(x)}$	$\frac{\exp(x)}{(1 + \exp(x))^2}$
log-log	$1 - \exp(-\exp(x))$	$\exp(-\exp(x)) \exp(x)$
linear (LPM)	x	1

Figure 4.2 displays the first three g functions appearing in Table 4.1.

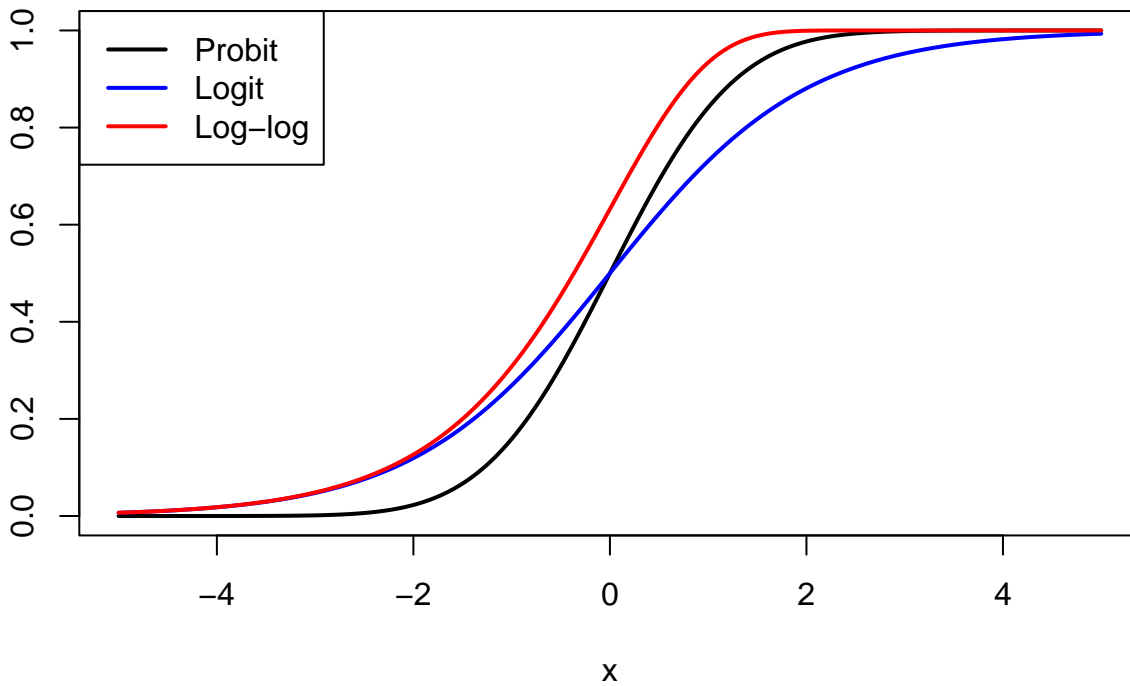


Figure 4.2: Probit, Logit, and Log-log functions.

The **probit** and the **logit** models are popular binary-choice models. In the probit model, we have:

$$g(z) = \Phi(z), \quad (4.3)$$

where Φ is the c.d.f. of the normal distribution. And for the logit model:

$$g(z) = \frac{1}{1 + \exp(-z)}. \quad (4.4)$$

Figure 4.3 shows the conditional probabilities associated with the (probit) model that had been used to generate the data of Figure 4.1.

4.1 Interpretation in terms of latent variable, and utility-based models

The probit model has an interpretation in terms of latent variables, which, in turn, is often exploited in structural models, called **Random Utility Models (RUM)**. In such structural models, it is assumed that the agents that have to take the decision do so by selecting the outcome that provides them with the larger utility (for agent i , two possible outcomes: $y_i = 0$ or $y_i = 1$). Part of this utility is observed by the econometrician—it depends on the covariates \mathbf{x}_i — and part of it is latent.

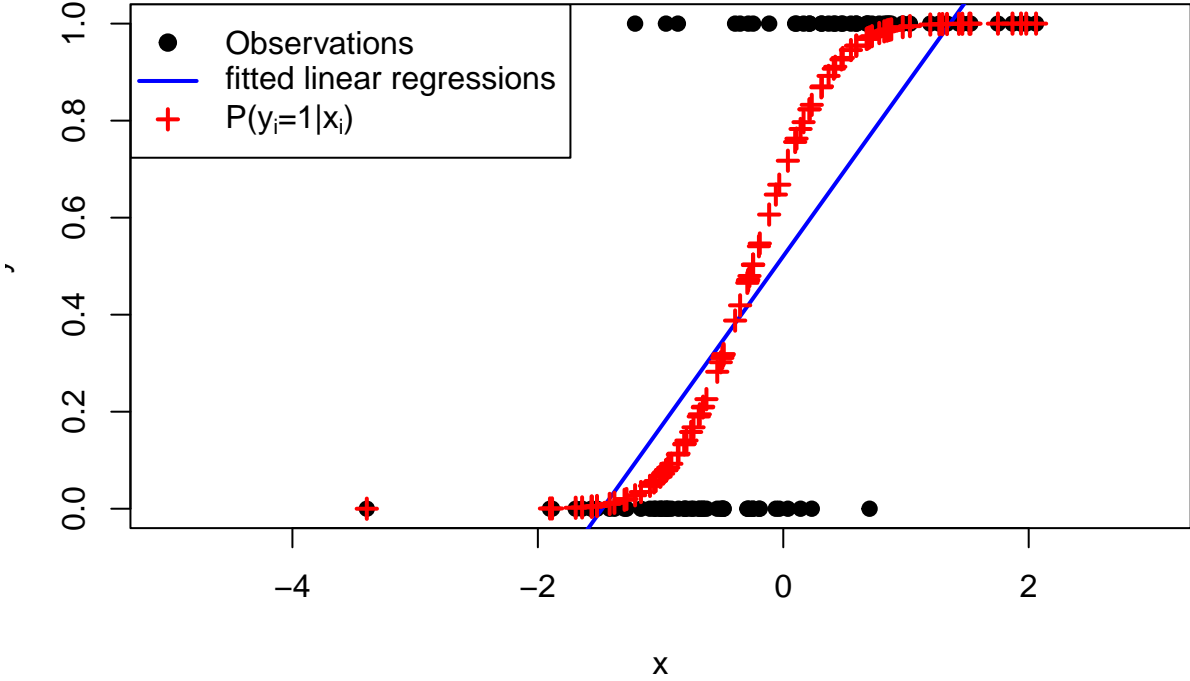


Figure 4.3: The model is $\mathbb{P}(y_i = 1|x_i) = \Phi(0.5 + 2x_i)$, where Φ is the c.d.f. of the normal distribution and where $x_i \sim i.i.d. \mathcal{N}(0, 1)$. Crosses give the model-implied probabilities of having $y_i = 1$ (conditional on x_i).

In the probit model, we have:

$$\mathbb{P}(y_i = 1|\mathbf{x}_i; \theta) = \Phi(\theta' \mathbf{x}_i) = \mathbb{P}(-\varepsilon_i < \theta' \mathbf{x}_i),$$

where $\varepsilon_i \sim \mathcal{N}(0, 1)$. That is:

$$\mathbb{P}(y_i = 1|\mathbf{x}_i; \theta) = \mathbb{P}(0 < y_i^*),$$

where $y_i^* = \theta' \mathbf{x}_i + \varepsilon_i$, with $\varepsilon_i \sim \mathcal{N}(0, 1)$. Variable y_i^* can be interpreted as a (latent) variable that determines y_i (since $y_i = \mathbb{I}_{\{y_i^* > 0\}}$).

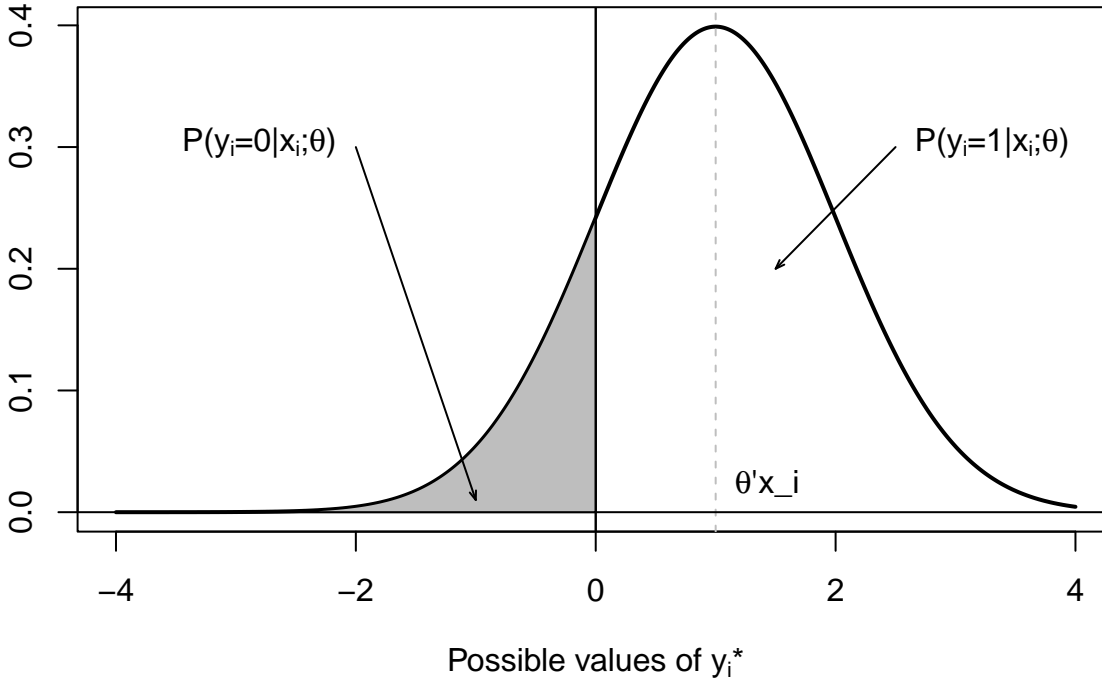
Figure 4.4 illustrates this situation.

Assume that agent (i) chooses $y_i = 1$ if the utility associated with this choice ($U_{i,1}$) is higher than the one associated with $y_i = 0$ (that is $U_{i,0}$). Assume further that the utility of agent i , if she chooses outcome j ($\in \{0, 1\}$), is given by

$$U_{i,j} = V_{i,j} + \varepsilon_{i,j},$$

where $V_{i,j}$ is the deterministic component of the utility associated with choice and where $\varepsilon_{i,j}$ is a random (agent-specific) component. Moreover, posit $V_{i,j} = \theta'_j \mathbf{x}_i$. We then have:

$$\begin{aligned} \mathbb{P}(y_i = 1|\mathbf{x}_i; \theta) &= \mathbb{P}(\theta'_1 \mathbf{x}_i + \varepsilon_{i,1} > \theta'_0 \mathbf{x}_i + \varepsilon_{i,0}) \\ &= F(\theta'_1 \mathbf{x}_i - \theta'_0 \mathbf{x}_i) = F([\theta_1 - \theta_0]' \mathbf{x}_i), \end{aligned} \quad (4.5)$$

Figure 4.4: Distribution of y_i^* conditional on \mathbf{x}_i .

where F is the c.d.f. of $\varepsilon_{i,0} - \varepsilon_{i,1}$.

Note that only the difference $\theta_1 - \theta_0$ is identifiable (as opposed to θ_1 and θ_0). Moreover, replacing U with aU ($a > 0$) gives the same model; this *scaling* issue can be solved by fixing the variance of $\varepsilon_{i,0} - \varepsilon_{i,1}$.

Example 4.1 (Migration and income). The RUM approach has been used by Nakosteen and Zimmer (1980) to study migration choices. Their model is based on the comparison of marginal costs and benefits associated with migration. The main ingredients of their approach are as follows:

- Wage that can be earned at the present location: $y_p^* = \theta_p' \mathbf{x}_p + \varepsilon_p$.
- Migration cost: $C^* = \theta_c' \mathbf{x}_c + \varepsilon_c$.
- Wage earned elsewhere: $y_m^* = \theta_m' \mathbf{x}_m + \varepsilon_m$.

In this context, agents decision to migrate if $y_m^* > y_p^* + C^*$, i.e. if

$$y^* = y_m^* - y_p^* - C^* = \theta' \mathbf{x} + \underbrace{\varepsilon}_{=\varepsilon_m - \varepsilon_c - \varepsilon_p} > 0,$$

where \mathbf{x} is the union of the \mathbf{x}_i s, for $i \in \{p, m, c\}$.

4.2 Alternative-Varying Regressors

In some cases, regressors may depend on the considered alternative (0 or 1). For instance:

- When modeling the decision to participate in the labour force (or not), the wage depends on the alternative. Typically, it is zero if the considered agent has decided not to work (and strictly positive otherwise).
- In the context of the choice of transportation mode, “time cost” depends on the considered transportation mode.

In terms of utility, we then have:

$$V_{i,j} = \theta_j^{(u)'} \mathbf{u}_{i,j} + \theta_j^{(v)'} \mathbf{v}_i,$$

where the $\mathbf{u}_{i,j}$ ’s are regressors associated with agent i , but taking different values for the different choices ($j = 0$ or $j = 1$). In that case, Eq. (4.5) becomes:

$$\mathbb{P}(y_i = 1 | \mathbf{x}_i; \theta) = F \left(\theta_1^{(u)'} \mathbf{u}_{i,1} - \theta_0^{(u)'} \mathbf{u}_{i,0} + [\theta_1^{(v)} - \theta_0^{(v)}]' \mathbf{v}_i \right), \quad (4.6)$$

and, if $\theta_1^{(u)} = \theta_0^{(u)} = \theta^{(u)}$ —as is customary— we get:

$$\mathbb{P}(y_i = 1 | \mathbf{x}_i; \theta) = F \left(\theta_1^{(u)'} (\mathbf{u}_{i,1} - \mathbf{u}_{i,0}) + [\theta_1^{(v)} - \theta_0^{(v)}]' \mathbf{v}_i \right). \quad (4.7)$$

Example 4.2 (Fishing-mode dataset). The fishing-mode dataset used in Cameron and Trivedi (2005) (Chapters 14 and 15) contains alternative-specific variables. Specifically, for each individual, the price and catch rate depend on the fishing model. In the table reported below, lines `price` and `catch` correspond to the prices and catch rates associated with the chosen alternative.

```
library(mlogit)
data("Fishing", package="mlogit")
stargazer::stargazer(Fishing, type="text")
```

```
##
## =====
## Statistic      N      Mean    St. Dev.    Min      Max
## -----
## price.beach    1,182   103.422   103.641    1.290    843.186
## price.pier     1,182   103.422   103.641    1.290    843.186
## price.boat     1,182    55.257    62.713     2.290    666.110
## price.charter  1,182    84.379    63.545    27.290    691.110
## catch.beach    1,182     0.241     0.191     0.068     0.533
## catch.pier     1,182     0.162     0.160     0.001     0.452
## catch.boat     1,182     0.171     0.210     0.0002    0.737
## catch.charter  1,182     0.629     0.706     0.002     2.310
## income         1,182  4,099.337  2,461.964  416.667  12,500.000
## -----
```

4.3 Estimation

These models can be estimated by Maximum Likelihood approaches (see Section 3.2).

To simplify the exposition, we consider the \mathbf{x}_i vectors of covariates to be deterministic. Moreover, we assume that the r.v. are independent across entities i . How to write the likelihood in that case? It is easily checked that:

$$f(y_i|\mathbf{x}_i; \theta) = g(\theta' \mathbf{x}_i)^{y_i} (1 - g(\theta' \mathbf{x}_i))^{1-y_i}.$$

Therefore, if the observations (\mathbf{x}_i, y_i) are independent across entities i , we obtain:

$$\log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) = \sum_{i=1}^n y_i \log[g(\theta' \mathbf{x}_i)] + (1 - y_i) \log[1 - g(\theta' \mathbf{x}_i)].$$

The likelihood equation reads (FOC of the optimization program, see Def. 3.7):

$$\frac{\partial \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X})}{\partial \theta} = \mathbf{0},$$

that is:

$$\sum_{i=1}^n y_i \mathbf{x}_i \frac{g'(\theta' \mathbf{x}_i)}{g(\theta' \mathbf{x}_i)} - (1 - y_i) \mathbf{x}_i \frac{g'(\theta' \mathbf{x}_i)}{1 - g(\theta' \mathbf{x}_i)} = \mathbf{0}.$$

This is a nonlinear (multivariate) equation that can be solved numerically. Under regularity conditions (Hypotheses 3.1), we approximately have (Prop. 3.4):

$$\theta_{MLE} \sim \mathcal{N}(\theta_0, \mathbf{I}(\theta_0)^{-1}),$$

where

$$\mathbf{I}(\theta_0) = -\mathbb{E}_0 \left(\frac{\partial^2 \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X})}{\partial \theta \partial \theta'} \right) = n \mathcal{J}_Y(\theta_0).$$

For finite samples, we can e.g. approximate $\mathbf{I}(\theta_0)^{-1}$ by Eq. (3.11):

$$\mathbf{I}(\theta_0)^{-1} \approx - \left(\frac{\partial^2 \log \mathcal{L}(\theta_{MLE}; \mathbf{y}, \mathbf{X})}{\partial \theta \partial \theta'} \right)^{-1}.$$

In the Probit case (see Table 4.1), it can be shown that we have:

$$\begin{aligned} \frac{\partial^2 \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X})}{\partial \theta \partial \theta'} &= - \sum_{i=1}^n g'(\theta' \mathbf{x}_i) [\mathbf{x}_i \mathbf{x}_i'] \times \\ &\left[y_i \frac{g'(\theta' \mathbf{x}_i) + \theta' \mathbf{x}_i g(\theta' \mathbf{x}_i)}{g(\theta' \mathbf{x}_i)^2} + (1 - y_i) \frac{g'(\theta' \mathbf{x}_i) - \theta' \mathbf{x}_i (1 - g(\theta' \mathbf{x}_i))}{(1 - g(\theta' \mathbf{x}_i))^2} \right]. \end{aligned}$$

In the Logit case (see Table 4.1), it can be shown that we have:

$$\frac{\partial^2 \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X})}{\partial \theta \partial \theta'} = - \sum_{i=1}^n g'(\theta' \mathbf{x}_i) \mathbf{x}_i \mathbf{x}_i',$$

where $g'(x) = \frac{\exp(-x)}{(1 + \exp(-x))^2}$.

Remark that, since $g'(x) > 0$, $-\partial^2 \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) / \partial \theta \partial \theta'$ is positive definite.

4.4 Marginal effects

How to measure marginal effects, i.e. the effect on the probability that $y_i = 1$ of a marginal increase of $x_{i,k}$? This object is given by:

$$\frac{\partial \mathbb{P}(y_i = 1 | \mathbf{x}_i; \theta)}{\partial x_{i,k}} = \underbrace{g'(\theta' \mathbf{x}_i)}_{>0} \theta_k,$$

which is of the same sign as θ_k if function g is monotonously increasing.

For agent i , this marginal effect is consistently estimated by $g'(\theta'_{MLE} \mathbf{x}_i) \theta_{MLE,k}$. It is important to see that the marginal effect depends on \mathbf{x}_i : respective increases by 1 unit of $x_{i,k}$ (entity i) and of $x_{j,k}$ (entity j) do not necessarily have the same effect on $\mathbb{P}(y_i = 1 | \mathbf{x}_i; \theta)$ as on $\mathbb{P}(y_j = 1 | \mathbf{x}_j; \theta)$. To address this issue, one can compute some measures of “average” marginal effect. There are two main solutions. For each explanatory variable k :

- i. Denoting by $\hat{\mathbf{x}}$ the sample average of the \mathbf{x}_i s, compute $g'(\theta'_{MLE} \hat{\mathbf{x}}) \theta_{MLE,k}$.
- ii. Compute the average (across i) of $g'(\theta'_{MLE} \mathbf{x}_i) \theta_{MLE,k}$.

4.5 Goodness of fit

There is no obvious version of “ R^2 ” for binary-choice models. Existing measures are called **pseudo- R^2 measures**.

Denoting by $\log \mathcal{L}_0(\mathbf{y})$ the (maximum) log-likelihood that would be obtained for a model containing only a constant term (i.e. with $\mathbf{x}_i = 1$ for all i), the McFadden’s pseudo- R^2 is given by:

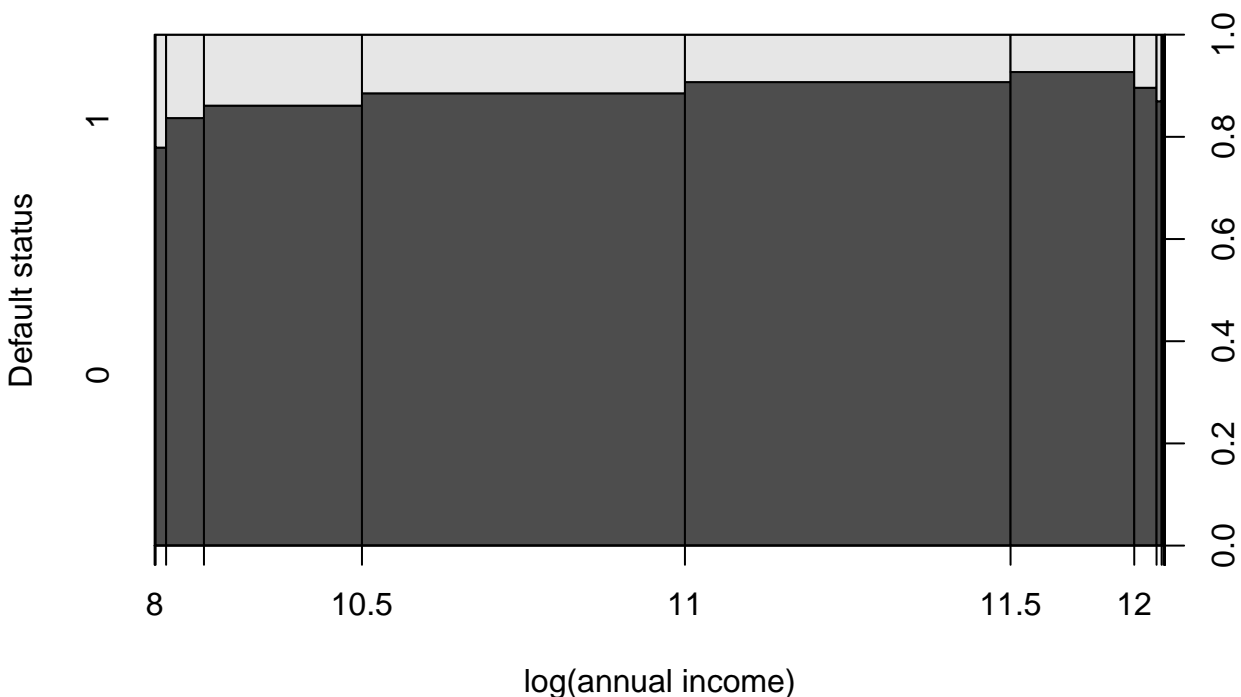
$$R_{MF}^2 = 1 - \frac{\log \mathcal{L}(\theta; \mathbf{y})}{\log \mathcal{L}_0(\mathbf{y})}.$$

Intuitively, $R_{MF}^2 = 0$ if the explanatory variables do not convey any information on the outcome y . Indeed, in this case, the model is not better than the reference model, that simply captures the fraction of y_i ’s that are equal to 1.

Example 4.3 (Credit and defaults (Lending-club dataset)). This example makes use of the `credit` data of package `AEC`. The objective is to model the default probabilities of borrowers.

Let us first represent the relationship between the fraction of households that have defaulted on their loan and their annual income:

```
library(AEC)
credit$Default <- 0
credit$Default[credit$loan_status == "Charged Off"] <- 1
credit$Default[credit$loan_status ==
               "Does not meet the credit policy. Status:Charged Off"] <- 1
credit$amt2income <- credit$loan_amnt/credit$annual_inc
plot(as.factor(credit$Default)~log(credit$annual_inc),
     ylevels=2:1,ylab="Default status",xlab="log(annual income)")
```



The previous figure suggests that the effect of annual income on the probability of default is non-monotonous. We will therefore include a quadratic term in one of our specification (namely `eq1` below).

We consider three specifications. The first one (`eq0`), with no explanatory variables, is trivial. It will just be used to compute the pseudo- R^2 . In the second (`eq1`), we consider a few covariates (loan amount, the ratio between the amount and annual income, The number of more-than-30 days past-due incidences of delinquency in the borrower's credit file for the past 2 years, and a quadratic function of annual income). In the third model (`eq2`), we add a credit rating.

```

eq0 <- glm(Default ~ 1,data=credit,family=binomial(link="probit"))
eq1 <- glm(Default ~ log(loan_amnt) + amt2income + delinq_2yrs +
            log(annual_inc)+ I(log(annual_inc)^2),
            data=credit,family=binomial(link="probit"))
eq2 <- glm(Default ~ grade + log(loan_amnt) + amt2income + delinq_2yrs +
            log(annual_inc)+ I(log(annual_inc)^2),
            data=credit,family=binomial(link="probit"))
stargazer::stargazer(eq0,eq1,eq2,type="text",no.space = TRUE)

```

```

##
## =====
##                               Dependent variable:
##                               -----
##                               Default
##                               (1)      (2)      (3)
## -----
## gradeB                               0.400***
##                               (0.055)
## gradeC                               0.587***
##                               (0.057)
## gradeD                               0.820***
##                               (0.061)
## gradeE                               0.874***
##                               (0.091)
## gradeF                               1.230***
##                               (0.147)
## gradeG                               1.439***
##                               (0.227)
## log(loan_amnt)                      -0.149** -0.194***
##                               (0.060) (0.061)
## amt2income                          1.266*** 1.222***
##                               (0.383) (0.393)
## delinq_2yrs                         0.096*** 0.009
##                               (0.034) (0.035)
## log(annual_inc)                     -1.444** -0.874
##                               (0.569) (0.586)
## I(log(annual_inc)2)                 0.064** 0.038
##                               (0.025) (0.026)
## Constant                           -1.231*** 7.937*** 4.749
##                               (0.017) (3.060) (3.154)
## -----
## Observations                        9,156    9,156    9,156
## Log Likelihood                      -3,157.696 -3,120.625 -2,981.343
## Akaike Inf. Crit.                   6,317.392 6,253.250 5,986.686

```

```
## =====
## Note:                *p<0.1; **p<0.05; ***p<0.01
```

Let us compute the pseudo R2 for the last two models:

```
logL0 <- logLik(eq0); logL1 <- logLik(eq1); logL2 <- logLik(eq2)
pseudoR2_eq1 <- 1 - logL1/logL0 # pseudo R2
pseudoR2_eq2 <- 1 - logL2/logL0 # pseudo R2
c(pseudoR2_eq1, pseudoR2_eq2)
```

```
## [1] 0.01173993 0.05584870
```

Let us now compute the (average) marginal effects, using method ii of Section 4.4:

```
mean(dnorm(predict(eq2)), na.rm=TRUE)*eq2$coefficients
```

```
##      (Intercept)           gradeB           gradeC
##      0.840731198       0.070747353       0.103944305
##           gradeD           gradeE           gradeF
##      0.145089219       0.154773742       0.217702041
##           gradeG      log(loan_amnt)      amt2income
##      0.254722161       -0.034289921       0.216251992
##      delinq_2yrs      log(annual_inc) I(log(annual_inc)^2)
##      0.001574178       -0.154701321       0.006813694
```

There is an issue for the `annual_inc` variable. Indeed, the previous computation does not realize that this variable appears twice among the explanatory variables (through `log(annual_inc)` and `I(log(annual_inc)^2)`). To address this, one can proceed as follows: (1) we construct a new counterfactual dataset where annual incomes are increased by 1%, (2) we use the model to compute model-implied probabilities of default on this new dataset and (3), we subtract the probabilities resulting from the original dataset from these counterfactual probabilities:

```
new_credit <- credit
new_credit$annual_inc <- 1.01 * new_credit$annual_inc
bas_predict_eq2 <- predict(eq2, newdata = credit, type = "response")
# This is equivalent to pnorm(predict(eq2, newdata = credit))
new_predict_eq2 <- predict(eq2, newdata = new_credit, type = "response")
mean(new_predict_eq2 - bas_predict_eq2)
```

```
## [1] -6.562126e-05
```

The negative sign means that, on average across the entities considered in the analysis, a 1% increase in annual income results in a decrease in the default probability. This average effect is however pretty low. To get an economic sense of the size of this effect, let us compute the average effect associated with a unit increase in the number of delinquencies:

```
new_credit <- credit
new_credit$delinq_2yrs <- credit$delinq_2yrs + 1
new_predict_eq2 <- predict(eq2, newdata = new_credit, type = "response")
mean(new_predict_eq2 - bas_predict_eq2)
```

```
## [1] 0.001582332
```

We can employ a likelihood ratio test (see Def. 3.8) to see if the two variables associated with annual income are jointly statistically significant (in the context of eq1):

```
eq1restr <- glm(Default ~ log(loan_amnt) + amt2income + delinq_2yrs,
                 data=credit,family=binomial(link="probit"))
LRstat <- 2*(logL1 - logLik(eq1restr))
pvalue <- 1 - c(pchisq(LRstat,df=2))
```

The computation gives a p-value of 0.0436.

Example 4.4 (Replicating Table 14.2 of Cameron and Trivedi (2005)). The following lines of codes replicate Table 14.2 of Cameron and Trivedi (2005) (see Example 4.2).

```
data.reduced <- subset(Fishing,mode %in% c("charter","pier"))
data.reduced$lnrelp <- log(data.reduced$price.charter/data.reduced$price.pier)
data.reduced$y <- 1*(data.reduced$mode=="charter")
# check first line of Table 14.1:
price.charter.y0 <- mean(data.reduced$pcharter[data.reduced$y==0])
price.charter.y1 <- mean(data.reduced$pcharter[data.reduced$y==1])
price.charter <- mean(data.reduced$pcharter)
# Run probit regression:
reg.probit <- glm(y ~ lnrelp,
                 data=data.reduced,
                 family=binomial(link="probit"))
# Run Logit regression:
reg.logit <- glm(y ~ lnrelp,
                 data=data.reduced,
                 family=binomial(link="logit"))
# Run OLS regression:
reg.OLS <- lm(y ~ lnrelp,
              data=data.reduced)
# Replicates Table 14.2 of Cameron and Trivedi:
stargazer::stargazer(reg.logit, reg.probit, reg.OLS,no.space = TRUE,
                     type="text")
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               y
##                               logistic      probit      OLS
##                               (1)         (2)         (3)
## -----
## lnrelp          -1.823*** -1.056***      -0.243***
##                  (0.145)  (0.075)         (0.010)
## Constant        2.053***  1.194***      0.784***
##                  (0.169)  (0.088)         (0.013)
## -----
## Observations          630          630          630
## R2                                0.463
## Adjusted R2                                0.462
## Log Likelihood      -206.827  -204.411
## Akaike Inf. Crit.    417.654   412.822
## Residual Std. Error                0.330 (df = 628)
## F Statistic                542.123*** (df = 1; 628)
## =====
## Note:                                *p<0.1; **p<0.05; ***p<0.01
```

4.6 Predictions and ROC curves

How to compute model-implied predicted outcomes? As is the case for y_i , predicted outcomes \hat{y}_i need to be valued in $\{0, 1\}$. A natural choice consists in considering that $\hat{y}_i = 1$ if $\mathbb{P}(y_i = 1 | \mathbf{x}_i; \theta) > 0.5$, i.e., in taking a cutoff of $c = 0.5$. There exist, though, situations where doing so is not relevant. For instance, we may have some models where all predicted probabilities are small, but some less than others. In this context, a model-implied probability of 10% (say) could characterize a “high-risk” entity. However, using a cutoff of 50% would not identify this level of riskiness.

The **receiver operating characteristics (ROC)** curve constitutes a more general approach. The idea is to remain agnostic and to consider all possible values of the cutoff c . It works as follows. For each potential cutoff $c \in [0, 1]$, compute (and plot):

- The fraction of $y = 1$ values correctly classified (*True Positive Rate*) against
- The fraction of $y = 0$ values incorrectly specified (*False Positive Rate*).

Such a curve mechanically starts at (0,0) —which corresponds to $c = 1$ — and terminates at (1,1) —situation when $c = 0$.

In the case of no predictive ability (worst situation), the ROC curve is a straight line between (0,0) and (1,1).

Example 4.5 (ROC with the fishing-mode dataset). Figure 4.5 shows the ROC curve associated with the probit model estimated in Example 4.4.

```
library(pROC)
predict_model <- predict.glm(reg.probit,type = "response")
roc(data.reduced$y, predict_model, percent=T,
    boot.n=1000, ci.alpha=0.9, stratified=T, plot=TRUE, grid=TRUE,
    show.thres=TRUE, legacy.axes = TRUE, reuse.auc = TRUE,
    print.auc = TRUE, print.thres.col = "blue", ci=TRUE,
    ci.type="bars", print.thres.cex = 0.7, col = 'red',
    main = paste("ROC curve using", "(N = ", nrow(data.reduced), ")") )
```

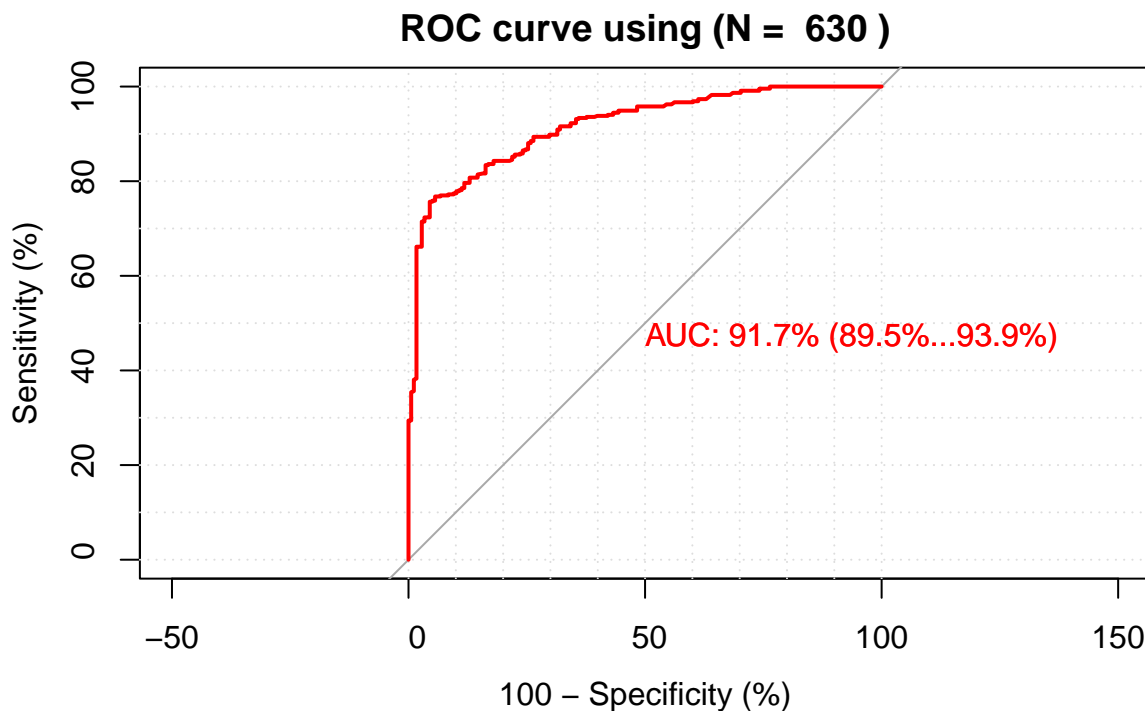


Figure 4.5: Application of the ROC methodology on the fishing-mode dataset.

Chapter 5

Multiple Choice Models

We will now consider cases where the number of possible outcomes (or alternatives) is larger than two. Let us denote by J this number. We have $y_j \in \{1, \dots, J\}$. This situation arise for instance when the outcome variable reflects:

- Opinions: strongly opposed / opposed / neutral / support (ranked choices),
- Occupational field: lawyer / farmer / engineer / doctor / ...,
- Alternative shopping areas,
- Transportation types.

In a few cases, the values associated with the choices will themselves be meaningful, for example, number of accidents per day: $y = 0, 1, 2, \dots$ (count data). In most cases, the values are meaningless.

We assume the existence of covariates, gathered in vector \mathbf{x}_i ($K \times 1$), that are suspected to influence for the probabilities of obtaining the different outcomes ($y_i = j$, $j \in \{1, \dots, J\}$).

In what follows, we will assume that the y_i 's are assumed to be independently distributed, with:

$$y_i = \begin{cases} 1 & \text{with probability } g_1(\mathbf{x}_i; \theta) \\ \vdots & \\ J & \text{with probability } g_J(\mathbf{x}_i; \theta). \end{cases} \quad (5.1)$$

(Of course, for all entities (i), we must have $\sum_{j=1}^J g_j(\mathbf{x}_i; \theta) = 1$.) Our objective is to estimate the vector of population parameters θ given functional forms for the g_j 's.

5.1 Ordered case

Sometimes, there exists a natural order for the different alternatives. This is typically the case where respondents have to choose a level of agreement to a statement, e.g.: (1) Strongly disagree; (2) Disagree; (3) Neither agree nor disagree; (4) Agree; (5) Strongly agree. Another standard case is that of ratings (from A to F, say).

The ordered probit model consists in extending the binary case, considering the latent-variable view of the latter (see Section 4.1). Formally, the model is as follows:

$$\mathbb{P}(y_i = j | \mathbf{x}_i) = \mathbb{P}(\alpha_{j-1} < y_i^* < \alpha_j | \mathbf{x}_i), \quad (5.2)$$

where

$$y_i^* = \theta' \mathbf{x}_i + \varepsilon_i,$$

with $\varepsilon_i \sim i.i.d. \mathcal{N}(0, 1)$. The α_j 's, $j \in \{1, \dots, J-1\}$, are (new) parameters that have to be estimated, on top of θ . Naturally, we have $\alpha_1 < \alpha_2 < \dots < \alpha_{J-1}$. Moreover α_0 is $-\infty$ and α_J is $+\infty$, so that Eq. (5.2) is valid for any $j \in \{1, \dots, J\}$ (including 1 and J).

We have:

$$\begin{aligned} g_j(\mathbf{x}_i; \theta, \alpha) = \mathbb{P}(y_i = j | \mathbf{x}_i) &= \mathbb{P}(\alpha_{j-1} < y_i^* < \alpha_j | \mathbf{x}_i) \\ &= \mathbb{P}(\alpha_{j-1} - \theta' \mathbf{x}_i < \varepsilon_i < \alpha_j - \theta' \mathbf{x}_i) \\ &= \Phi(\alpha_j - \theta' \mathbf{x}_i) - \Phi(\alpha_{j-1} - \theta' \mathbf{x}_i), \end{aligned}$$

where Φ is the c.d.f. of $\mathcal{N}(0, 1)$.

If, for all i , one of the components of \mathbf{x}_i is equal to 1 (which is what is done in linear regression to introduce an intercept in the specification), then one of the α_j ($j \in \{1, \dots, J-1\}$) is not identified. One can then arbitrarily set $\alpha_1 = 0$. This is what is done in the binary logit/probit cases.

This model can be estimated by maximizing the likelihood function (see Section 3.2). This function is given by:

$$\log \mathcal{L}(\theta, \alpha; \mathbf{y}, \mathbf{X}) = \sum_{i=1}^n \sum_{j=1}^J \mathbb{I}_{\{y_i=j\}} \log(g_j(\mathbf{x}_i; \theta, \alpha)). \quad (5.3)$$

Let us stress that we have two types of parameters to estimate: those included in vector θ , and the α_j 's, gathered in vector α .

The estimated values of the θ_j 's are slightly more complicated to interpret (at least in term of sign) than in the binary case. Indeed, we have:

$$\mathbb{P}(y_i \leq j | \mathbf{x}_i) = \Phi(\alpha_j - \theta' \mathbf{x}_i) \Rightarrow \frac{\partial \mathbb{P}(y_i \leq j | \mathbf{x}_i)}{\partial \mathbf{x}_i} = - \underbrace{\Phi'(\alpha_j - \theta' \mathbf{x}_i)}_{>0} \theta.$$

Hence the sign of θ_k indicates whether $\mathbb{P}(y_i \leq j | \mathbf{x}_i)$ increases or decreases w.r.t. $x_{i,k}$ (the k^{th} component of \mathbf{x}_i). By contrast:

$$\frac{\partial \mathbb{P}(y_i = j | \mathbf{x}_i)}{\partial \mathbf{x}_i} = \underbrace{(-\Phi'(\alpha_j + \theta' \mathbf{x}_i) + \Phi'(\alpha_{j-1} + \theta' \mathbf{x}_i))}_A \theta.$$

Therefore the signs of the components of θ are not necessarily those of the marginal effects. (For the sign of A is a priori unknown.)

Example 5.1 (Predicting credit ratings (Lending-club dataset)). Let us use credit dataset again (see Example 4.3), and let us try and model the ratings attributed by the lending-club:

```
library(AEC)
library(MASS)
credit$emp_length_low5y <- credit$emp_length %in%
  c("< 1 year","1 year","2 years","3 years","4 years")
credit$emp_length_high10y <- credit$emp_length=="10+ years"
credit$annual_inc <- credit$annual_inc/1000
credit$loan_amnt <- credit$loan_amnt/1000
credit$income2loan <- credit$annual_inc/credit$loan_amnt
training <- credit[1:20000,] # sample is reduced
training <- subset(training,grade!=c("E","F","G"))
training <- droplevels(training)
training$grade.ordered <- factor(training$grade,ordered=TRUE,
                                levels = c("D","C","B","A"))
model1 <- polr(grade.ordered ~ log(loan_amnt) + log(income2loan) + delinq_2yrs,
               data=training, Hess=TRUE, method="probit")
model2 <- polr(grade.ordered ~ log(loan_amnt) + log(income2loan) + delinq_2yrs +
               emp_length_low5y + emp_length_high10y,
               data=training, Hess=TRUE, method="probit")
stargazer::stargazer(model1,model2,ord.intercepts = TRUE,type="text",
                     no.space = TRUE)
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               grade.ordered
##                               (1)          (2)
## -----
```

## log(loan_amnt)	-0.014	-0.040*
##	(0.022)	(0.022)
## log(income2loan)	0.115***	0.092***
##	(0.022)	(0.022)
## delinq_2yrs	-0.399***	-0.404***
##	(0.025)	(0.025)
## emp_length_low5y		-0.096***
##		(0.027)
## emp_length_high10y		0.088**
##		(0.035)
## D C	-0.937***	-1.073***
##	(0.082)	(0.086)
## C B	-0.160**	-0.295***

```
##                (0.082)          (0.085)
## B| A          0.696***          0.564***
##                (0.082)          (0.086)
## -----
## Observations      8,695          8,695
## =====
## Note:              *p<0.1; **p<0.05; ***p<0.01
```

Predicted ratings (and probabilities of being given a given rating) can be computed as follows:

```
pred.grade <- predict(model1,newdata = training)
# pred.grade = predicted grade, defined as the most likely according model
pred.proba <- predict(model1,newdata = training, type="probs")
```

5.2 General multinomial logit model

This section introduces the general multinomial logit model, which is the natural extension of the binary logit model (see Table 4.1). Its general formulation is as follows:

$$g_j(\mathbf{x}_i; \theta) = \frac{\exp(\theta'_j \mathbf{x}_i)}{\sum_{k=1}^J \exp(\theta'_k \mathbf{x}_i)}. \quad (5.4)$$

Note that, by construction, $g_j(\mathbf{x}_i; \theta) \in [0, 1]$ and $\sum_j g_j(\mathbf{x}_i; \theta) = 1$.

The components of \mathbf{x}_i (regressors, or covariates) may be *alternative-specific* or *alternative invariant* (see also Section 4.2). We may, e.g., organize \mathbf{x}_i as follows:

$$\mathbf{x}_i = [\mathbf{u}'_{i,1}, \dots, \mathbf{u}'_{i,J}, \mathbf{v}'_i]', \quad (5.5)$$

where the notations are as in Section 4.2, that is:

- $\mathbf{u}_{i,j}$ ($j \in \{1, \dots, J\}$): vector of variables associated with agent i and alternative j (alternative-specific regressors). Examples: Travel time per type of transportation (transportation choice), wage per type of work, cost per type of car.
- \mathbf{v}_i : vector of variables associated with agent i but alternative-invariant. Examples: age or gender of agent i ,

When \mathbf{x}_i is as in Eq. (5.5), with obvious notations, θ_j is of the form:

$$\theta_j = [\theta_{1,j}^{(u)'}, \dots, \theta_{J,j}^{(u)'}, \theta_j^{(v)'}]', \quad (5.6)$$

and $\theta = [\theta_1', \dots, \theta_J']'$.

The literature has considered different specific cases of the general multinomial logit model:¹

¹The labelling “CL” and “MNL” —used in the literature— are relatively *ad hoc* (see 15.4.1 in Cameron and Trivedi (2005)).

- **Conditional logit (CL)** with alternative-varying regressors:

$$\theta_j = [\mathbf{0}', \dots, \mathbf{0}', \underset{j^{th} \text{ position}}{\beta'}, \mathbf{0}', \dots]', \quad (5.7)$$

i.e., we have $\beta = \theta_{1,1}^{(u)} = \dots = \theta_{J,J}^{(u)}$ and $\theta_{i,j}^{(u)} = \mathbf{0}$ for $i \neq j$.

- **Multinomial logit (MNL)** with alternative-invariant regressors:

$$\theta_j = [\mathbf{0}', \dots, \mathbf{0}', \theta_j^{(v)'}]'. \quad (5.8)$$

- **Mixed logit:**

$$\theta_j = [\mathbf{0}', \dots, \mathbf{0}', \beta', \mathbf{0}', \dots, \mathbf{0}', \theta_j^{(v)'}]'. \quad (5.9)$$

Example 5.2 (CL and MNL with the fishing-mode dataset). The following lines replicate Table 15.2 in Cameron and Trivedi (2005) (see also Examples 4.2 and 4.4):

```
# Specify data organization:
library(mlogit)
library(stargazer)
data("Fishing", package="mlogit")
Fish <- mlogit.data(Fishing,
                    varying = c(2:9),
                    choice = "mode",
                    shape = "wide")
MNL1 <- mlogit(mode ~ price + catch, data = Fish)
MNL2 <- mlogit(mode ~ price + catch - 1, data = Fish)
MNL3 <- mlogit(mode ~ 0 | income, data = Fish)
MNL4 <- mlogit(mode ~ price + catch | income, data = Fish)
stargazer(MNL1, MNL2, MNL3, MNL4, type="text", no.space = TRUE,
           omit.stat = c("lr"))
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               mode
##                               (1)      (2)      (3)      (4)
## -----
## (Intercept):boat      0.871***           0.739***  0.527**
##                      (0.114)           (0.197)  (0.223)
## (Intercept):charter    1.499***           1.341***  1.694***
##                      (0.133)           (0.195)  (0.224)
## (Intercept):pier      0.307***           0.814***  0.778***
```

```

##              (0.115)              (0.229)   (0.220)
## price      -0.025***  -0.020***              -0.025***
##              (0.002)   (0.001)              (0.002)
## catch      0.377***   0.953***              0.358***
##              (0.110)   (0.089)              (0.110)
## income:boat              0.0001**  0.0001*
##              (0.00004)  (0.0001)
## income:charter              -0.00003  -0.00003
##              (0.00004)  (0.0001)
## income:pier              -0.0001*** -0.0001**
##              (0.0001)  (0.0001)
## -----
## Observations      1,182      1,182      1,182      1,182
## R2                0.178      0.014      0.189
## Log Likelihood    -1,230.784 -1,311.980 -1,477.151 -1,215.138
## =====
## Note:                                *p<0.1; **p<0.05; ***p<0.01

```

ML estimation

General multinomial logit models can be estimated by Maximum Likelihood techniques (see Section 3.2). Consider the general model described in Eq. (5.1). It can be noted that:

$$f(y_i|\mathbf{x}_i; \theta) = \prod_{j=1}^J g_j(\mathbf{x}_i; \theta)^{\mathbb{I}_{\{y_i=j\}}},$$

which leads to

$$\log f(y_i|\mathbf{x}_i; \theta) = \sum_{j=1}^J \mathbb{I}_{\{y_i=j\}} \log(g_j(\mathbf{x}_i; \theta)).$$

The log-likelihood function is therefore given by:

$$\log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) = \sum_{i=1}^n \sum_{j=1}^J \mathbb{I}_{\{y_i=j\}} \log(g_j(\mathbf{x}_i; \theta)). \quad (5.10)$$

Numerical methods have to be employed in order to find the maximum-likelihood estimate of θ . (Standard packages contain fast algorithms.)

Marginal Effects

Let us consider the computation of marginal effects in the general multinomial logit model

(Eq. (5.4)). Using the notation $p_{i,j} \equiv \mathbb{P}(y_i = j | \mathbf{x}_i; \theta)$, we have:

$$\begin{aligned} \frac{\partial p_{i,j}}{\partial x_{i,s}} &= \frac{\theta_{j,s} \exp(\theta'_j \mathbf{x}_i) \sum_{k=1}^J \exp(\theta'_k \mathbf{x}_i)}{(\sum_{k=1}^J \exp(\theta'_k \mathbf{x}_i))^2} \\ &\quad - \frac{\exp(\theta'_j \mathbf{x}_i) \sum_{k=1}^J \theta_{k,s} \exp(\theta'_k \mathbf{x}_i)}{(\sum_{k=1}^J \exp(\theta'_k \mathbf{x}_i))^2} \\ &= \theta_{j,s} p_{i,j} - \sum_{k=1}^J \theta_{k,s} p_{i,j} p_{i,k} \\ &= p_{i,j} \times \left(\theta_{j,s} - \underbrace{\sum_{k=1}^J \theta_{k,s} p_{i,k}}_{=\bar{\theta}_s^{(i)}} \right), \end{aligned}$$

where $\bar{\theta}_s^{(i)}$ does not depend on j . Note that the sign of the marginal effect is not necessarily that of $\theta_{j,s}$.

Random Utility models

The general multinomial logit model may arise as the natural specification arising in structural contexts where agents compare (random) utilities associated with J potential outcomes (see Section 4.1 for the binary situation).

Let's drop the i subscript for simplicity and assume that the utility derived from choosing j is given by $U_j = V_j + \varepsilon_j$, where V_j is deterministic (may depend on observed covariates) and ε_j is stochastic. We have (with obvious notations):

$$\begin{aligned} \mathbb{P}(y = j) &= \mathbb{P}(U_j > U_k, \forall k \neq j) \\ \mathbb{P}(y = j) &= \mathbb{P}(U_k - U_j < 0, \forall k \neq j) \\ \mathbb{P}(y = j) &= \mathbb{P}(\underbrace{\varepsilon_k - \varepsilon_j}_{=:\tilde{\varepsilon}_{k,j}} < \underbrace{V_j - V_k}_{=:-\tilde{V}_{k,j}}, \forall k \neq j). \end{aligned}$$

The last expression is an $(J - 1)$ -variate integral. While it has, in general, no analytical solution, Prop. 5.1 shows that it is the case when employing Gumbel distributions (see Def. 5.1).

Definition 5.1 (Gumbel distribution). The c.d.f. of the Gumbel distribution (\mathcal{W}) is:

$$F(u) = \exp(-\exp(-u)), \quad f(u) = \exp(-u - \exp(u)).$$

Remark: if $X \sim \mathcal{W}$, then $\mathbb{E}(X) = 0.577$ (Euler constant)² and $\mathbb{V}ar(X) = \pi^2/6$.

Proposition 5.1 (Weibull). *In the context of the utility model described above, if $\varepsilon_j \sim i.i.d. \mathcal{W}$, then*

$$\mathbb{P}(y = j) = \frac{\exp(V_j)}{\sum_{k=1}^J \exp(V_k)}.$$

²The Euler constant γ satisfies $\gamma = \lim_{n \rightarrow \infty} (-\ln(n) + \sum_{k=1}^n \frac{1}{k})$.

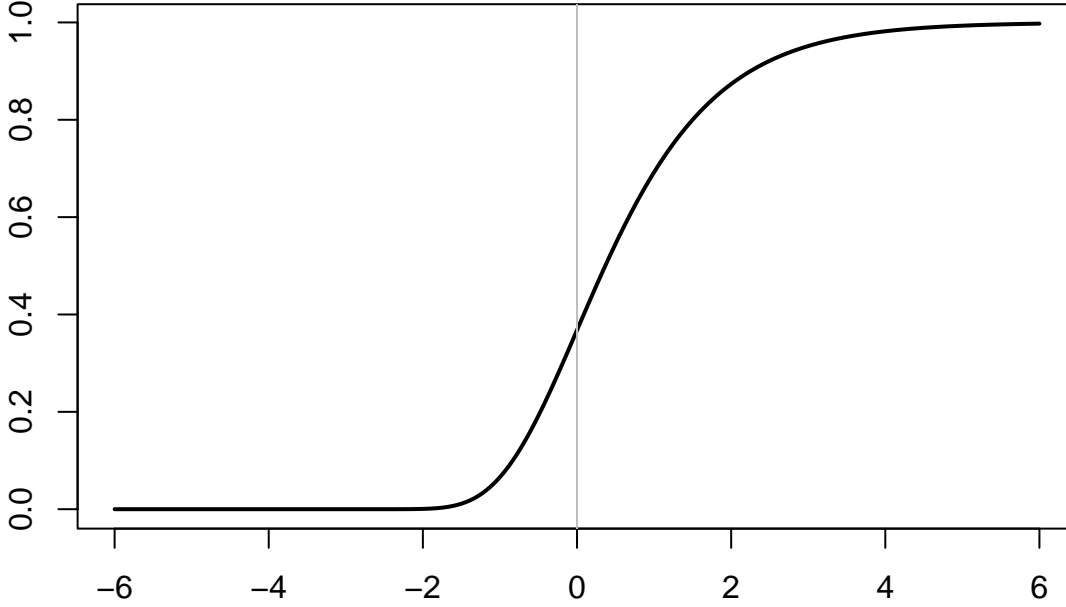


Figure 5.1: C.d.f. of the Gumbel distribution ($F(x) = \exp(-\exp(-x))$).

Proof. We have:

$$\begin{aligned} \mathbb{P}(y = j) &= \mathbb{P}(\forall k \neq j, U_k < U_j) = \mathbb{P}(\forall k \neq j, \varepsilon_k < V_j - V_k + \varepsilon_j) \\ &= \int \prod_{k \neq j} F(V_j - V_k + \varepsilon) f(\varepsilon) d\varepsilon. \end{aligned}$$

After computation, it comes that

$$\prod_{k \neq j} F(V_j - V_k + \varepsilon) f(\varepsilon) = \exp[-\varepsilon - \exp(-\varepsilon + \lambda_j)],$$

where $\lambda_j = \log\left(1 + \frac{\sum_{k \neq j} \exp(V_k)}{\exp(V_j)}\right)$. We then have:

$$\begin{aligned} \mathbb{P}(y = j) &= \int \exp[-\varepsilon - \exp(-\varepsilon + \lambda_j)] d\varepsilon \\ &= \int \exp[-t - \lambda_j - \exp(-t)] d\varepsilon = \exp(-\lambda_j), \end{aligned}$$

which leads to the result. □

Some remarks on identification (see Def. 3.5) are in order.

1. We have:

$$\mathbb{P}(y = j) = \frac{\exp(V_j)}{\sum_{k=1}^J \exp(V_k)} = \frac{\exp(V_j^*)}{1 + \sum_{k=2}^J \exp(V_k^*)},$$

where $V_j^* = V_j - V_1$. We can therefore always assume that $V_1 = 0$. In the case where $V_{i,j} = \theta_j' \mathbf{x}_i = \beta' \mathbf{u}_{i,j} + \theta_j^{(v)'} \mathbf{v}_i$ (see Eqs. (5.5) and (5.9)), we can for instance assume that:

$$\begin{aligned} (A) \quad & \mathbf{u}_{i,1} = 0, \\ (B) \quad & \theta_1^{(v)} = 0. \end{aligned}$$

If (A) does not hold, we can replace $\mathbf{u}_{i,j}$ with $\mathbf{u}_{i,j} - \mathbf{u}_{i,1}$.

2. If $J = 2$ and $j \in \{0, 1\}$ (shift by one unit), we have $\mathbb{P}(y = 1|\mathbf{x}) = \frac{\exp(\theta' \mathbf{x})}{1 + \exp(\theta' \mathbf{x})}$, this is the logit model (Table 4.1).

Limitations of logit models

In a Logit model, we have:

$$\mathbb{P}(y = j|y \in \{k, j\}) = \frac{\exp(\theta_j' \mathbf{x})}{\exp(\theta_j' \mathbf{x}) + \exp(\theta_k' \mathbf{x})}. \quad (5.11)$$

This conditional probability does not depend on other alternatives (i.e., it does not depend on θ_m , $m \neq j, k$). In particular, if $\mathbf{x} = [\mathbf{u}'_1, \dots, \mathbf{u}'_J, \mathbf{v}']'$, then changes in \mathbf{u}_m ($m \neq j, k$) have no impact on the object shown in Eq. (5.11).

That is, a Multinomial Logit can be seen as a series of pairwise comparisons that are unaffected by the characteristics of alternatives. Such a model is said to satisfy the **independence from irrelevant alternatives (IIA)** property. That is, in these models, for any individual, the ratio of probabilities of choosing two alternatives is independent of the availability or attributes of any other alternatives. While this may not sound alarming, there are situations where you would like it not to be the case, this is for instance the case when you want to extrapolate the results of your estimated model to a situation where there is a novel outcome that is highly substitutable to one of the previous ones. This can be illustrated with the famous “red-blue bus” example:

Example 5.3 (Red-blue bus and IIA). Assume one has a logit model capturing the decision to travel using either a car ($y = 1$) or a (red) bus ($y = 2$). Assume you want to augment this model to allow for a third choice ($y = 3$): travel with a blue bus. If a blue bus ($y = 3$) is exactly as a red bus, except for the color, then one would expect to have:

$$\mathbb{P}(y = 3|y \in \{2, 3\}) = 0.5,$$

i.e. $\theta_2 = \theta_3$.

Assume we had $V_1 = V_2$. We expect to have $V_2 = V_3$ (hence $p_2 = p_3$). A multinomial logit model would then imply $p_1 = p_2 = p_3 = 0.33$. It would however seem more reasonable to have $p_1 = p_2 + p_3 = 0.5$ and $p_2 = p_3 = 0.25$.

5.3 Nested logits

Nested Logits are natural extensions of logit models when choices feature a nesting structure. This approach is relevant when it makes sense to group some choices into the same *nest*, also called *limbs*. Intuitively, this framework is consistent with the idea according to which, for each agent, there exist unobserved nest-specific variables.

The setup is as follows: we consider J limbs. For each limb j , we have K_j branches. Let us denote by y_1 the limb choice (i.e., $y_1 \in \{1, \dots, J\}$) and by y_2 the branch choice (with $y_2 \in \{1, \dots, K_j\}$). The utility associated with the pair of choices (j, k) is given by

$$U_{j,k} = V_{j,k} + \varepsilon_{j,k}.$$

We have:

$$\mathbb{P}[(y_1, y_2) = (j, k) | \mathbf{x}] = \mathbb{P}(U_{j,k} > U_{l,m}, (l, m) \neq (j, k) | \mathbf{x}).$$

One usually make the following two assumptions:

- i. The deterministic part of the utility is given by $V_{j,k} = \mathbf{u}'_j \alpha + \mathbf{v}'_{j,k} \beta_j$, where α is common to all nests and the β_j 's are nest-specific.
- ii. The disturbances ε follow the Generalized Extreme Value (GEV) distribution (see Def. 8.15).

The following figure displays simulations of pairs $(\varepsilon_1, \varepsilon_2)$ drawn from GEV distributions for different values of ρ . The simulation approach is based on Bhat. The code used to produce this chart is provided in Appendix 8.5.1.

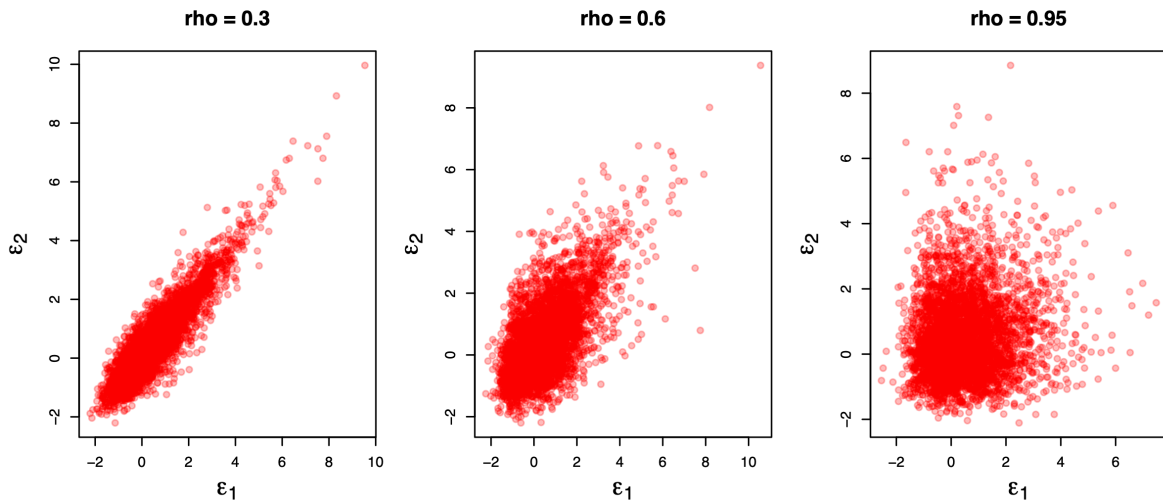


Figure 5.2: GEV simulations.

Under (i) and (ii), we have:

$$\begin{aligned} \mathbb{P}[(y_1, y_2) = (j, k) | \mathbf{x}] &= \frac{\exp(\mathbf{u}'_j \alpha + \rho_j I_j)}{\underbrace{\sum_{m=1}^J \exp(\mathbf{u}'_m \alpha + \rho_m I_m)}_{=\mathbb{P}[y_1=j|\mathbf{x}]} } \times \\ &\quad \frac{\exp(\mathbf{v}'_{j,k} \beta_j / \rho_j)}{\underbrace{\sum_{l=1}^{K_j} \exp(\mathbf{v}'_{j,l} \beta_j / \rho_j)}_{=\mathbb{P}[y_2=k|y_1=j, \mathbf{x}]}}, \end{aligned} \quad (5.12)$$

where I_j 's are called inclusive values (or log sums), given by:

$$I_j = \log \left(\sum_{l=1}^{K_j} \exp(\mathbf{v}'_{j,l} \beta_j / \rho_j) \right).$$

Some remarks are in order:

- a. It can be shown that $\rho_j = \sqrt{1 - \text{Cor}(\varepsilon_{j,k}, \varepsilon_{j,l})}$, for $k \neq l$.
- b. $\rho_j = 1$ implies that $\varepsilon_{j,k}$ and $\varepsilon_{j,l}$ are uncorrelated (we are then back to the multinomial logit case).
- c. When $J = 1$:

$$F([\varepsilon_1, \dots, \varepsilon_K]', \rho) = \exp \left(- \left(\sum_{k=1}^K \exp(-\varepsilon_k / \rho) \right)^\rho \right).$$

- d. We have:

$$I_j = \mathbb{E}(\max_k(U_{j,k})) = \mathbb{E}(\max_k(V_{j,k} + \varepsilon_{j,k})),$$

The inclusive values can therefore be seen as measures of the relative attractiveness of a nest.

This approach allows for some level of correlation across the $\varepsilon_{j,k}$ (for a given j). This can be interpreted as the existence of an (unobserved) *common error component* for the alternatives of a same nest. This component contributes to making the alternatives of a given nest more similar. In other words, this approach can accommodate a higher sensitivity (cross-elasticity) between the alternatives of a given nest.

Note that if the common component is reduced to zero (i.e. $\rho_i = 1$), the model boils down to the multinomial logit model with no covariance of error terms among the alternatives.

Contrary to the general multinomial model, nested logits can solve the Red-Blue problem described in Section 5.2 (see Example 5.3). Assume you have estimated a model specifying $U_1 = V_1 + \varepsilon_1$ (car choice) and $U_2 = V_2 + \varepsilon_2$ (red bus choice). You can then assume that the

blue-bus utility is of the form $U_3 = V_2 + \varepsilon_3$ where ε_3 is perfectly correlated to ε_2 . This is done by redefining the set of choices as follows:

$$\begin{aligned} j = 1 &\Leftrightarrow (j' = 1, k = 1) \\ j = 2 &\Leftrightarrow (j' = 2, k = 1) \\ j = 3 &\Leftrightarrow (j' = 2, k = 2), \end{aligned}$$

and by setting $\rho_2 \rightarrow 0$.

IIA holds within a nest, but not when considering alternatives in different nests. Indeed, using Eq. (5.12):

$$\frac{\mathbb{P}[y_1 = j, y_2 = k_A | \mathbf{x}]}{\mathbb{P}[y_1 = j, y_2 = k_B | \mathbf{x}]} = \frac{\exp(\mathbf{v}'_{j,k_A} \beta_j / \rho_j)}{\exp(\mathbf{v}'_{j,k_B} \beta_j / \rho_j)},$$

i.e. we have IIA in nest j .

By contrast:

$$\begin{aligned} \frac{\mathbb{P}[y_1 = j_A, y_2 = k_A | \mathbf{x}]}{\mathbb{P}[y_1 = j_B, y_2 = k_B | \mathbf{x}]} &= \frac{\exp(\mathbf{u}'_{j_A} \alpha + \rho_{j_A} I_{j_A}) \exp(\mathbf{v}'_{j_A, k_A} \beta_{j_A} / \rho_{j_A})}{\exp(\mathbf{u}'_{j_B} \alpha + \rho_{j_B} I_{j_B}) \exp(\mathbf{v}'_{j_B, k_B} \beta_{j_B} / \rho_{j_B})} \times \\ &\quad \frac{\sum_{l=1}^{K_{j_B}} \exp(\mathbf{v}'_{j_B, l} \beta_{j_B} / \rho_{j_B})}{\sum_{l=1}^{K_{j_A}} \exp(\mathbf{v}'_{j_A, l} \beta_{j_A} / \rho_{j_A})}, \end{aligned}$$

which depends on the expected utilities of all alternatives in nest j_A and j_B . So the IIA does not hold.

Example 5.4 (Travel-mode dataset). Let us illustrate nested logits on the travel-mode dataset used, e.g., by Hensher and Greene (2002) (see also Heiss (2002)).

```
library(mlogit)
library(stargazer)
data("TravelMode", package = "AER")
Prepared.TravelMode <- mlogit.data(TravelMode, chid.var = "individual",
                                   alt.var = "mode", choice = "choice",
                                   shape = "long")

# Fit a multinomial model:
hl <- mlogit(choice ~ wait + travel + vcost, Prepared.TravelMode,
            method = "bfgs", heterosc = TRUE, tol = 10)

## Fit a nested logit model:
TravelMode$avincome <- with(TravelMode, income * (mode == "air"))
TravelMode$time <- with(TravelMode, travel + wait) / 60
TravelMode$timeair <- with(TravelMode, time * I(mode == "air"))
TravelMode$income <- with(TravelMode, income / 10)
# Hensher and Greene (2002), table 1 p.8-9 model 5
TravelMode$incomeother <- with(TravelMode,
                              ifelse(mode %in% c('air', 'car'), income, 0))
```


Chapter 6

Tobit and sample-selection models

6.1 Tobit models

In some situations, the dependent variable is incompletely observed, which may result in a non-representative sample. Typically, in some cases, observations of the dependent variable can have a lower and/or an upper limit, while the “true”, underlying, dependent variable has not. In this case, OLS regression may lead to inconsistent parameter estimates.

Tobit models have been designed to address some of these situations. This approach has been named after James Tobin, who developed this model in the late 50s (see Tobin (1956)).

Figure 6.1 illustrates the situation. The dots (white and black) represent the “true” observations. Now, assume that only the black are observed. If one uses these observations in an OLS regression to estimate the relationship between x and y , then one gets the red line. It is clear that the sensitivity of y to x is then underestimated. The blue line is the line one would obtain if white dots were also observed; the grey line represents the model used to generate the data ($y_i = x_i + \varepsilon_i$).

Assume that the (partially) observed dependent variable follows:

$$y^* = \beta' \mathbf{x} + \varepsilon,$$

with ε is drawn from a distribution characterized by a p.d.f. denoted by f_γ^* and a c.d.f. denoted by F_γ^* ; these functions depend on a vector of parameters γ .

The observed dependent variable is:

$$\begin{aligned} \text{Censored case:} \quad y &= \begin{cases} y^* & \text{if } y^* > L \\ L & \text{if } y^* \leq L, \end{cases} \\ \text{Truncated case:} \quad y &= \begin{cases} y^* & \text{if } y^* > L \\ - & \text{if } y^* \leq L, \end{cases} \end{aligned}$$

where “—” stands for missing observations.

This formulation is easily extended to censoring from above ($L \rightarrow U$), or censoring from both below and above.

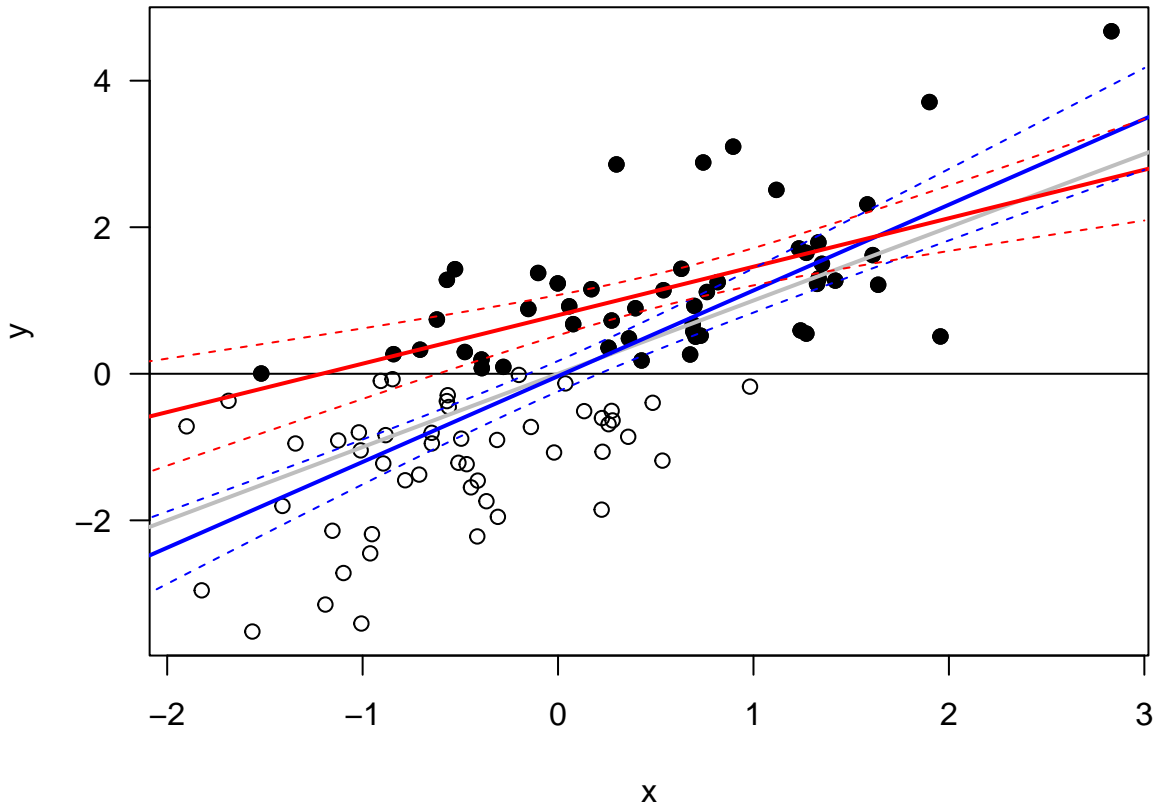


Figure 6.1: Bias in the case of sample selection. The grey line represents the population regression line. The model is $y_i = x_i + \varepsilon_i$, with $\varepsilon_{i,t} \sim \mathcal{N}(0,1)$. The red line is the OLS regression line based on black dots only.

The model parameters are gathered in vector $\theta = [\beta', \gamma']'$. Let us write the conditional p.d.f. of the observed variable:

$$\begin{aligned} \text{Censored case:} \quad f(y|\mathbf{x}; \theta) &= \begin{cases} f_\gamma^*(y - \beta' \mathbf{x}) & \text{if } y > L \\ F_\gamma^*(L - \beta' \mathbf{x}) & \text{if } y = L, \end{cases} \\ \text{Truncated case:} \quad f(y|\mathbf{x}; \theta) &= \frac{f_\gamma^*(y - \beta' \mathbf{x})}{1 - F_\gamma^*(L - \beta' \mathbf{x})} \quad \text{with } y > L. \end{aligned}$$

The (conditional) log-likelihood function is then given by:

$$\log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) = \sum_{i=1}^n \log f(y_i | \mathbf{x}_i; \theta).$$

In the censored case, we have:

$$\begin{aligned} \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) &= \sum_{i=1}^n \left\{ \mathbb{I}_{\{y_i=L\}} \log [F_\gamma^*(L - \beta' \mathbf{x}_i)] + \right. \\ &\quad \left. \mathbb{I}_{\{y_i>0\}} \log [f_\gamma^*(y_i - \beta' \mathbf{x}_i)] \right\}. \end{aligned}$$

The Tobit, or censored/truncated normal regression model, corresponds to the case described above, but with Gaussian errors ε . Specifically:

$$y^* = \beta' \mathbf{x} + \varepsilon,$$

with $\varepsilon \sim i.i.d. \mathcal{N}(0, \sigma^2)$ ($\Rightarrow \gamma = \sigma^2$).

Without loss of generality, we can assume that $L = 0$. (One can shift observed data if necessary.)

- The censored density (with $L = 0$) is given by:

$$f(y) = \left[\frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(y - \beta' \mathbf{x})^2\right) \right]^{\mathbb{I}_{\{y>0\}}} \left[1 - \Phi\left(\frac{\beta' \mathbf{x}}{\sigma}\right) \right]^{\mathbb{I}_{\{y=0\}}}.$$

- The truncated density (with $L = 0$) is given by:

$$f(y) = \frac{1}{\Phi(\beta' \mathbf{x})} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(y - \beta' \mathbf{x})^2\right).$$

Results usually heavily rely on distributional assumptions (more than in uncensored/untruncated case). The framework is easy to extend to an heteroskedastic case, for instance by setting $\sigma_i^2 = \exp(\alpha' \mathbf{x}_i)$. Such a situation is illustrated by Figure 6.2.

Let us consider the conditional means of y in the general case, i.e., for any ε distribution. Assume \mathbf{x} is observed, such that expectations are conditional on \mathbf{x} .

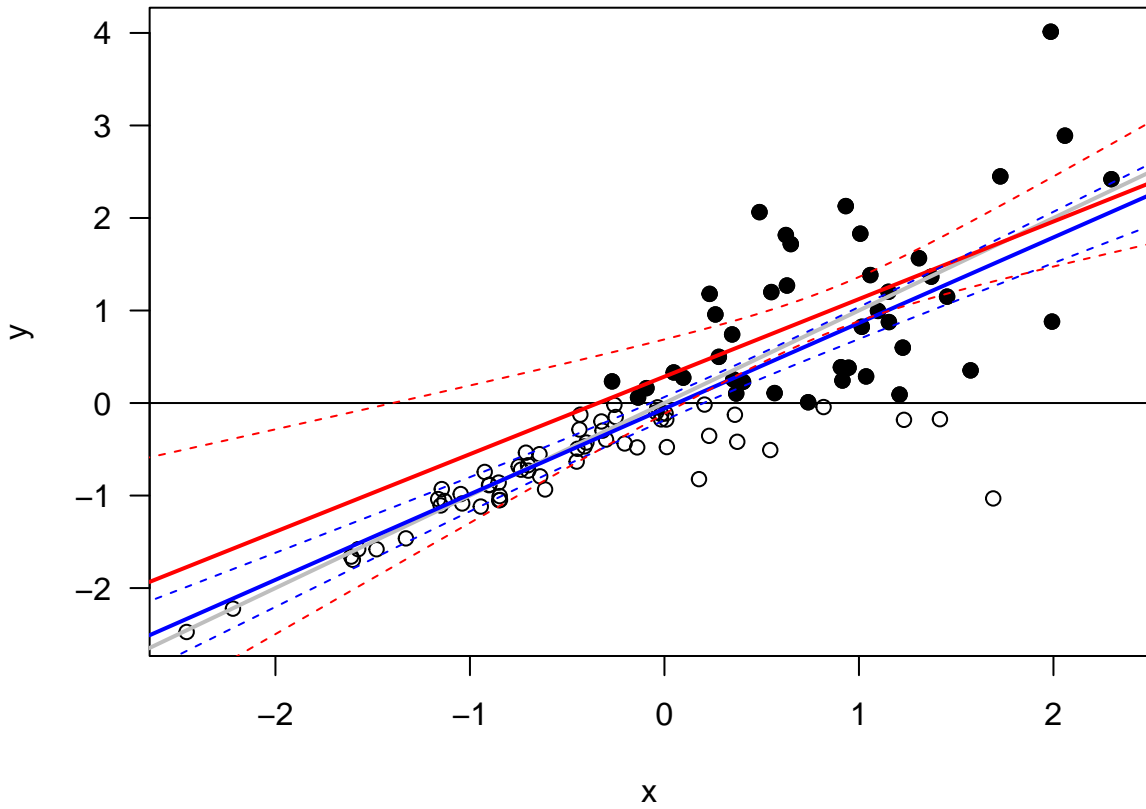


Figure 6.2: Censored dataset with heteroskedasticity. The model is $y_i = x_i + \varepsilon_i$, with $\varepsilon_{i,t} \sim \mathcal{N}(0, \sigma_i^2)$ where $\sigma_i = \exp(-1 + x_i)$.

- For data that are left-truncated at 0, we have:

$$\mathbb{E}(y) = \mathbb{E}(y^*|y^* > 0) = \underbrace{\beta' \mathbf{x}}_{=\mathbb{E}(y^*)} + \underbrace{\mathbb{E}(\varepsilon|\varepsilon > -\beta' \mathbf{x})}_{>0} > \mathbb{E}(y^*).$$

- Consider data that are left-censored at 0. By Bayes, we have:

$$f_{y^*|y^*>0}(u) = \frac{f_{y^*}(u)}{\mathbb{P}(y^* > 0)} \mathbb{I}_{\{u>0\}}.$$

Therefore:

$$\begin{aligned} \mathbb{E}(y^*|y^* > 0) &= \frac{1}{\mathbb{P}(y^* > 0)} \int_{-\infty}^{\infty} u f_{y^*}(u) \mathbb{I}_{\{u>0\}} du \\ &= \frac{1}{\mathbb{P}(y^* > 0)} \underbrace{\mathbb{E}(y^* \mathbb{I}_{\{y^*>0\}})}_{=y}, \end{aligned}$$

and, further:

$$\begin{aligned} \mathbb{E}(y) &= \mathbb{P}(y^* > 0) \mathbb{E}(y^*|y^* > 0) \\ &> \mathbb{E}(y^*) = \mathbb{P}(y^* > 0) \mathbb{E}(y^*|y^* > 0) + \mathbb{P}(y^* < 0) \underbrace{\mathbb{E}(y^*|y^* < 0)}_{<0}. \end{aligned}$$

Now, let us come back to the Tobit (i.e., Gaussian case) case.

- For data that are left-truncated at 0:

$$\begin{aligned} \mathbb{E}(y) &= \beta' \mathbf{x} + \mathbb{E}(\varepsilon|\varepsilon > -\beta' \mathbf{x}) \\ &= \beta' \mathbf{x} + \sigma \underbrace{\frac{\phi(\beta' \mathbf{x}/\sigma)}{\Phi(\beta' \mathbf{x}/\sigma)}}_{=: \lambda(\beta' \mathbf{x}/\sigma)} = \sigma \left(\frac{\beta' \mathbf{x}}{\sigma} + \lambda \left(\frac{\beta' \mathbf{x}}{\sigma} \right) \right). \end{aligned} \quad (6.1)$$

where the penultimate line is obtained by using Eq. (8.3).

- For data that are left-censored at 0:

$$\begin{aligned} \mathbb{E}(y) &= \mathbb{P}(y^* > 0) \mathbb{E}(y^*|y^* > 0) \\ &= \Phi \left(\frac{\beta' \mathbf{x}}{\sigma} \right) \sigma \left(\frac{\beta' \mathbf{x}}{\sigma} + \lambda \left(\frac{\beta' \mathbf{x}}{\sigma} \right) \right). \end{aligned}$$

Heckit regression

The previous formula (Eq. (6.1)) can in particular be used in an alternative estimation approach, namely the Heckman two-step estimation. This approach is based on two steps:¹

¹See 16.10.2 of Cameron and Trivedi (2005) for the derivation of asymptotic standard errors of β .

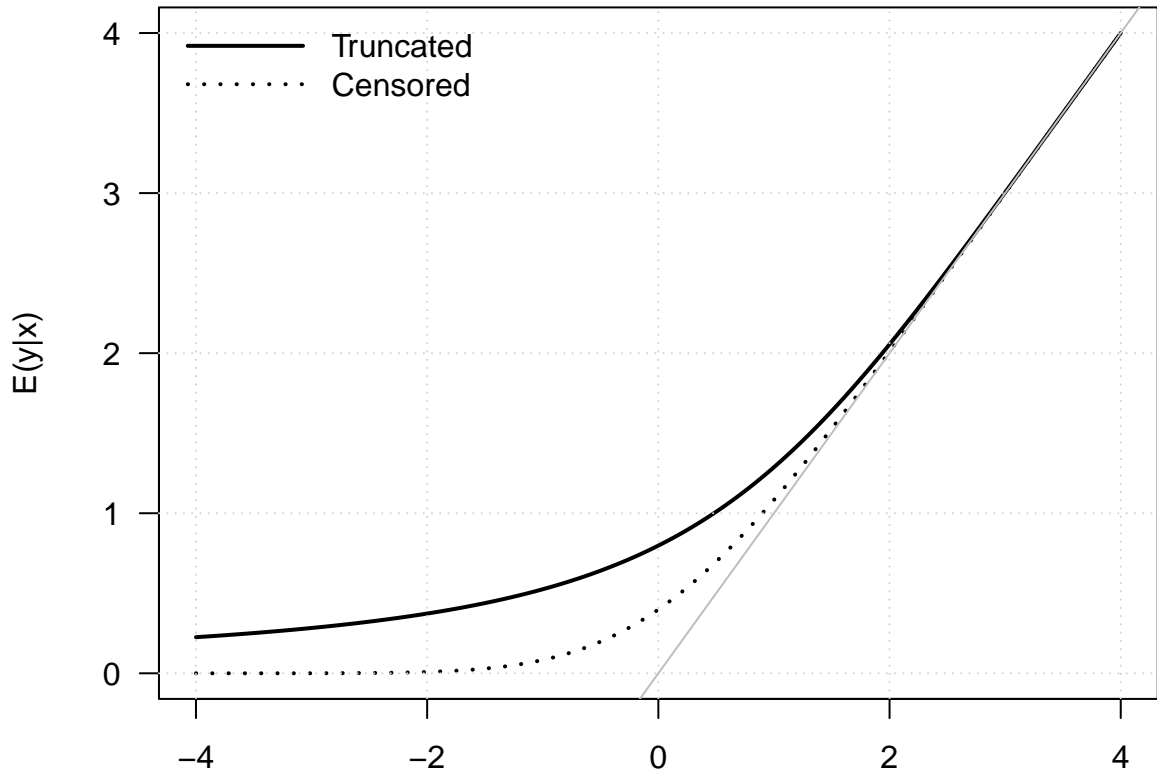


Figure 6.3: Conditional means of y in Tobit models. The model is $y_i = x_i + \varepsilon_i$, with $\varepsilon_i \sim \mathcal{N}(0, 1)$.

1. Using the complete sample, fit a Probit model of $\mathbb{I}_{\{y_i > 0\}}$ on \mathbf{x} . This provides a consistent estimate of $\frac{\beta}{\sigma}$, and therefore of $\lambda(\beta' \mathbf{x}/\sigma)$. (Indeed, if $z_i \equiv \mathbb{I}_{\{y_i > 0\}}$, then $\mathbb{P}(z_i = 1 | \mathbf{x}_i; \beta/\sigma) = \Phi(\beta' \mathbf{x}_i/\sigma)$.)
2. Using the truncated sample only: run an OLS regression of \mathbf{y} on $\{\mathbf{x}, \lambda(\beta' \mathbf{x}/\sigma)\}$ (having Eq. (6.1) in mind). This provides a consistent estimate of (β, σ) .

The underlying specification is of the form:

Conditional mean + disturbance.

where “Conditional mean” comes from Eq. (6.1) and “disturbance” is an error with zero conditional mean.

This approach is also applied to the case of **sample selection models** (Section 6.2).

Example 6.1 (Wage prediction). The present example is based on the dataset used in Mroz (1987) (which is part of the `sampleSelection` package).

```
library(sampleSelection)
library(AER)
data("Mroz87")
Mroz87$lfps.yesno <- NaN
Mroz87$lfps.yesno[Mroz87$lfps==1] <- "yes"
Mroz87$lfps.yesno[Mroz87$lfps==0] <- "no"
Mroz87$lfps.yesno <- as.factor(Mroz87$lfps.yesno)
ols <- lm(wage ~ educ + exper + I( exper^2 ) + city, data=subset(Mroz87,lfps==1))
tobit <- tobit(wage ~ educ + exper + I( exper^2 ) + city,
              left = 0, right = Inf,
              data=Mroz87)
Heckit <- heckit(lfps ~ educ + exper + I( exper^2 ) + city, # selection equation
                wage ~ educ + exper + I( exper^2 ) + city, # outcome equation
                data=Mroz87 )

stargazer(ols,Heckit,tobit,no.space = TRUE,type="text",omit.stat = "f")
```

```
##
## =====
##                               Dependent variable:
##                               -----
##                               wage
##                               Heckman      Tobit
##                               OLS          selection
##                               (1)          (2)          (3)
## -----
```

```

## educ          0.481***      0.759***      0.642***
##              (0.067)      (0.270)      (0.081)
## exper         0.032         0.430         0.461***
##              (0.062)      (0.369)      (0.068)
## I(exper2)     -0.0003      -0.008      -0.009***
##              (0.002)      (0.008)      (0.002)
## city          0.449         0.113         -0.087
##              (0.318)      (0.522)      (0.378)
## Constant     -2.561***     -12.251     -10.395***
##              (0.929)      (8.853)      (1.095)
## -----
## Observations      428          753          753
## R2                0.125        0.128
## Adjusted R2       0.117        0.117
## Log Likelihood                    -1,462.700
## rho                                1.063
## Inverse Mills Ratio                5.165 (4.594)
## Residual Std. Error 3.111 (df = 423)
## Wald Test                                153.892*** (df = 4)
## =====
## Note:                                *p<0.1; **p<0.05; ***p<0.01

```

Figure 6.4 shows that, low wages, the OLS model tends to over-predict wages. The slope between observed and Tobit-predicted wages is closer to one (the adjustment line is closer to the 45-degree line.)

Two-part model

In the standard Tobit framework, the model determining censored —or truncated— data *censoring mechanism* is the same as the one determining non-censored —or observed— data *outcome mechanism*. A two-part model adds flexibility by permitting the zeros and non-zeros to be generated by different densities. The second model characterizes the outcome *conditional on* the outcome being observed.

In a seminal paper, Duan et al. (1983) employ this methodology to account for individual annual hospital expenses. The two models are then as follows:

- 1st model: $\mathbb{P}(hosp = 1|\mathbf{x}) = \Phi(\mathbf{x}'_1\beta_1)$,
- 2nd model: $Expense = \exp(\mathbf{x}'_2\beta_2 + \eta)$, with $\eta \sim i.i.d. \mathcal{N}(0, \sigma_2^2)$.

Specifically:

$$\mathbb{E}(Expense|\mathbf{x}_1, \mathbf{x}_2) = \Phi(\mathbf{x}'_1\beta_1) \exp\left(\mathbf{x}'_2\beta_2 + \frac{\sigma_2^2}{2}\right).$$

In sample-selection models, studied in the next section, one specifies the joint distribution for the censoring and outcome mechanisms (while the two parts are independent here).

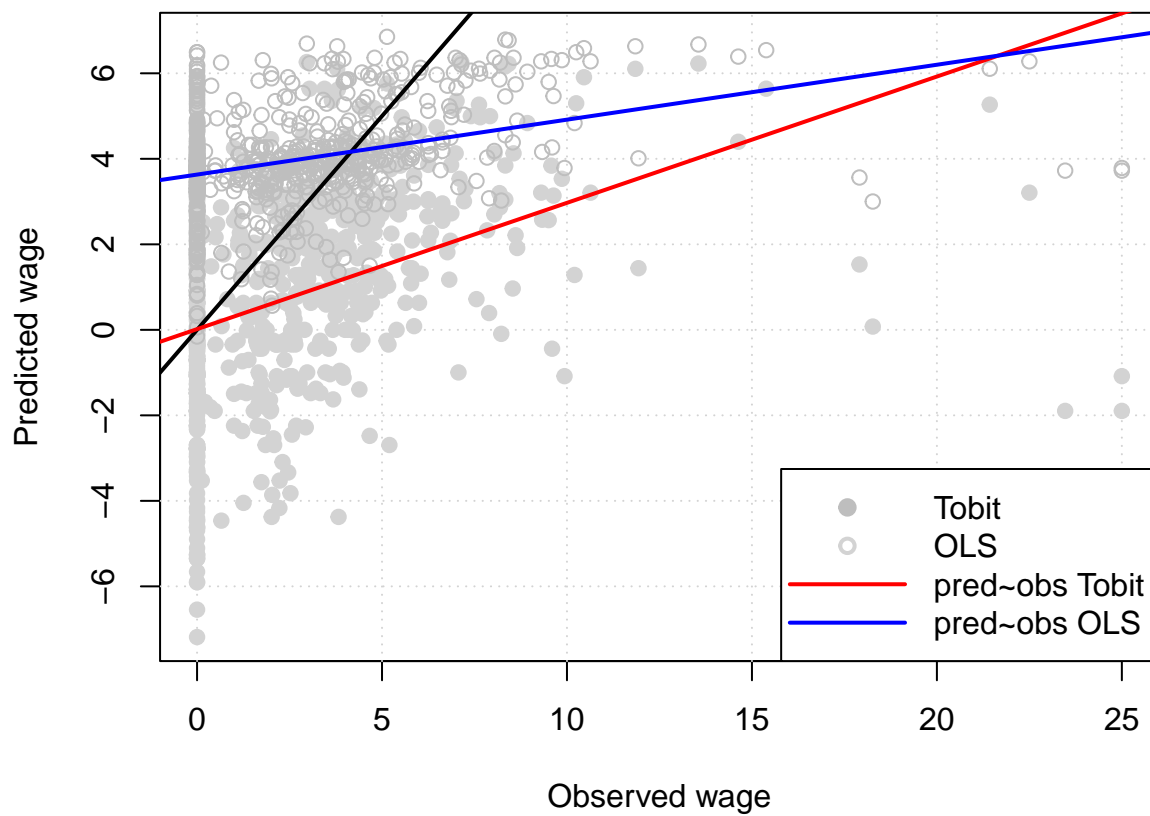


Figure 6.4: Predicted versus observed wages.

6.2 Sample Selection Models

The situation tackled by sample-selection models is the following. The dependent variable of interest, denoted by y_2 , depends on observed variables \mathbf{x}_2 . Observing y_2 , or not, depends on the value of a latent variable (y_1^*) that is correlated to observed variables \mathbf{x}_1 . The difference w.r.t. the two-part model sketched above is that, even conditionally on $(\mathbf{x}_1, \mathbf{x}_2)$, y_1^* and y_2 may be correlated.

As in the Tobit case, even in the simplest case of population conditional mean linear in regressors (i.e. $y_2 = \mathbf{x}_2' \beta_2 + \varepsilon_2$), OLS regression leads to inconsistent parameter estimates because the sample is not representative of the population.

There are two latent variables: y_1^* and y_2^* . We observe y_1 and, if the considered entity “participates”, we also observe y_2 . More specifically:

$$\begin{aligned} y_1 &= \begin{cases} 1 & \text{if } y_1^* > 0 \\ 0 & \text{if } y_1^* \leq 0 \end{cases} \quad (\text{participation equation}) \\ y_2 &= \begin{cases} y_2^* & \text{if } y_1 = 1 \\ - & \text{if } y_1 = 0 \end{cases} \quad (\text{outcome equation}). \end{aligned}$$

Moreover:

$$\begin{aligned} y_1^* &= \mathbf{x}_1' \beta_1 + \varepsilon_1 \\ y_2^* &= \mathbf{x}_2' \beta_2 + \varepsilon_2. \end{aligned}$$

Note that the Tobit model (Section 6.1) is the special case where $y_1^* = y_2^*$.

Usually:

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} 1 & \rho \sigma_2 \\ \rho \sigma_2 & \sigma_2^2 \end{bmatrix} \right).$$

Let us derive the likelihood associated with this model. We have:

$$f(\underbrace{0}_{=y_1}, \underbrace{-}_{=y_2} | \mathbf{x}; \theta) = \mathbb{P}(y_1^* \leq 0) = \Phi(-\mathbf{x}_1' \beta_1) \quad (6.2)$$

$$\begin{aligned} f(1, y_2 | \mathbf{x}; \theta) &= f(y_2^* | \mathbf{x}; \theta) \mathbb{P}(y_1^* > 0 | y_2^*, \mathbf{x}; \theta) \\ &= \frac{1}{\sigma} \phi \left(\frac{y_2 - \mathbf{x}_2' \beta_2}{\sigma} \right) \mathbb{P}(y_1^* > 0 | y_2, \mathbf{x}; \theta). \end{aligned} \quad (6.3)$$

Let us compute $\mathbb{P}(y_1^* > 0 | y_2, \mathbf{x}; \theta)$. By Prop. 8.16 (in Appendix 8.3), applied to $(\varepsilon_1, \varepsilon_2)$, we have:

$$y_1^* | y_2 \sim \mathcal{N} \left(\mathbf{x}_1' \beta_1 + \frac{\rho}{\sigma_2} (y_2 - \mathbf{x}_2' \beta_2), 1 - \rho^2 \right).$$

which leads to

$$\mathbb{P}(y_1^* > 0 | y_2, \mathbf{x}; \theta) = \Phi \left(\frac{\mathbf{x}_1' \beta_1 + \frac{\rho}{\sigma_2} (y_2 - \mathbf{x}_2' \beta_2)}{\sqrt{1 - \rho^2}} \right). \quad (6.4)$$

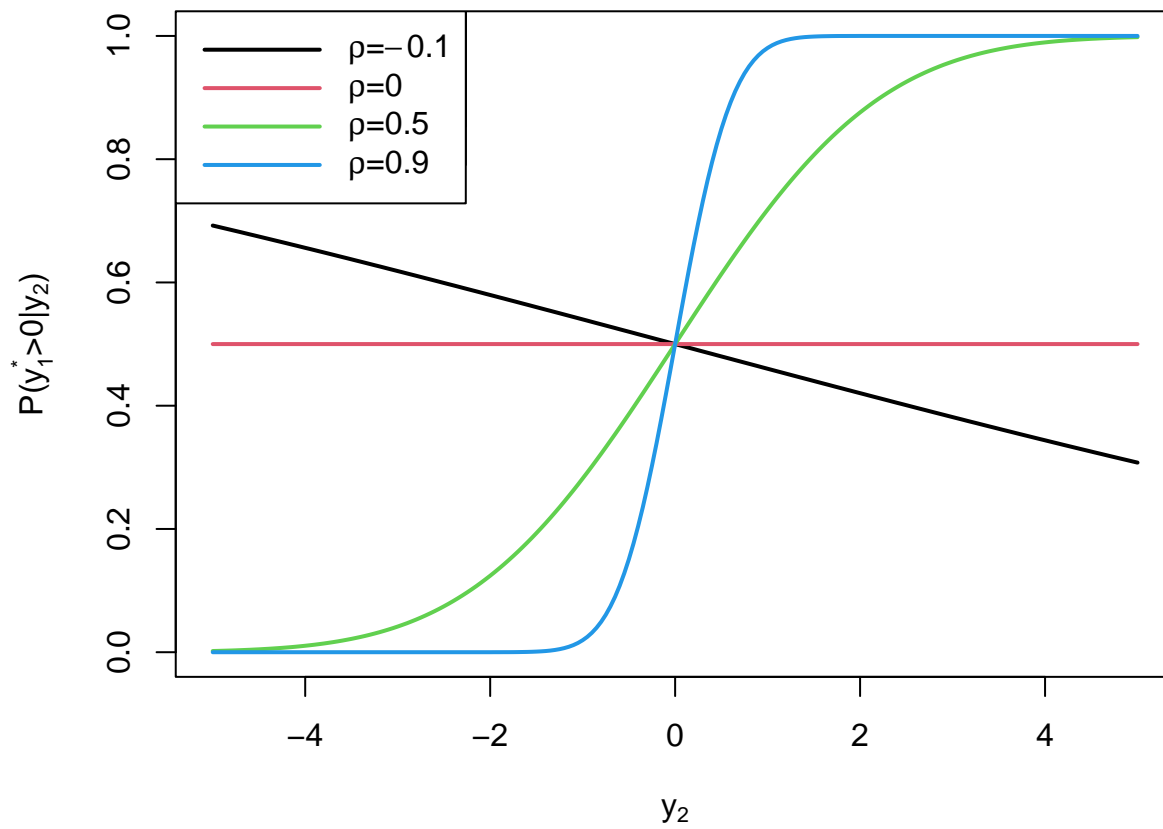


Figure 6.5: Probability of observing y_2 depending on its value, for different values of conditional correlation between y_2 and y_1^* .

Figure 6.5 displays $\mathbb{P}(y_1^* > 0 | y_2, \mathbf{x}; \theta)$ for different values of y_2 and of ρ , in the case where $\beta_1 = \beta_2 = 0$.

Using Eqs. (6.2), (6.3) and (6.4), one gets the log-likelihood function:

$$\begin{aligned} \log \mathcal{L}(\theta; \mathbf{y}, \mathbf{X}) &= \sum_{i=1}^n (1 - y_{1,i}) \log \Phi(-\mathbf{x}'_{1,i} \beta_1) + \\ &\quad \sum_{i=1}^n y_{1,i} \log \left(\frac{1}{\sigma} \phi \left(\frac{y_{2,i} - \mathbf{x}'_{2,i} \beta_2}{\sigma} \right) \right) + \\ &\quad \sum_{i=1}^n y_{1,i} \log \left(\Phi \left(\frac{\mathbf{x}'_{1,i} \beta_1 + \frac{\rho}{\sigma_2} (y_{2,i} - \mathbf{x}'_{2,i} \beta_2)}{\sqrt{1 - \rho^2}} \right) \right). \end{aligned}$$

We can also compute conditional expectations:

$$\begin{aligned} \mathbb{E}(y_2^* | y_1 = 1, \mathbf{x}) &= \mathbb{E}(\mathbb{E}(y_2^* | y_1^*, \mathbf{x}) | y_1 = 1, \mathbf{x}) \\ &= \mathbb{E}(\mathbf{x}'_2 \beta_2 + \rho \sigma_2 (y_1^* - \mathbf{x}'_1 \beta_1) | y_1 = 1, \mathbf{x}) \\ &= \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \underbrace{\mathbb{E}(y_1^* - \mathbf{x}'_1 \beta_1 | \varepsilon_1 > -\mathbf{x}'_1 \beta_1, \mathbf{x})}_{=\varepsilon_1 \sim \mathcal{N}(0,1)} \\ &= \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \frac{\phi(-\mathbf{x}'_1 \beta_1)}{1 - \Phi(-\mathbf{x}'_1 \beta_1)} \\ &= \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \frac{\phi(\mathbf{x}'_1 \beta_1)}{\Phi(\mathbf{x}'_1 \beta_1)} = \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \lambda(\mathbf{x}'_1 \beta_1), \end{aligned} \tag{6.5}$$

and:

$$\begin{aligned} \mathbb{E}(y_2^* | y_1 = 0, \mathbf{x}) &= \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \mathbb{E}(y_1^* - \mathbf{x}'_1 \beta_1 | \varepsilon_1 \leq -\mathbf{x}'_1 \beta_1, \mathbf{x}) \\ &= \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \frac{\phi(-\mathbf{x}'_1 \beta_1)}{1 - \Phi(-\mathbf{x}'_1 \beta_1)} \\ &= \mathbf{x}'_2 \beta_2 - \rho \sigma_2 \frac{\phi(-\mathbf{x}'_1 \beta_1)}{\Phi(-\mathbf{x}'_1 \beta_1)} = \mathbf{x}'_2 \beta_2 - \rho \sigma_2 \lambda(-\mathbf{x}'_1 \beta_1). \end{aligned}$$

Heckman procedure

As for tobit models (Section 6.1), we can use the Heckman procedure to estimate this model. Eq. (6.5) shows that $\mathbb{E}(y_2^* | y_1 = 1, \mathbf{x}) \neq \mathbf{x}'_2 \beta_2$ when $\rho \neq 0$. Therefore, the OLS approach yields biased estimates based when it is employed only on the sub-sample where $y_1 = 1$.

The Heckman two-step procedure (or “Heckit”) consists in replacing $\lambda(\mathbf{x}'_1 \beta_1)$ appearing in Eq. (6.5) with a consistent estimate of it. More precisely:

1. Get an estimate $\widehat{\beta}_1$ of β_1 (probit regression of y_1 on \mathbf{x}_1).

2. Run the OLS regression (using only data associated with $y_1 = 1$):

$$y_2 = \mathbf{x}'_2 \beta_2 + \rho \sigma_2 \lambda(\mathbf{x}'_1 \widehat{\beta}_1) + \varepsilon_2, \quad (6.6)$$

considering $\lambda(\mathbf{x}'_1 \widehat{\beta}_1)$ as a regressor.

How to estimate σ_2^2 ? By Eq. (8.4), we have:

$$\mathbb{V}ar(y_2|y_1^* > 0, \mathbf{x}) = \mathbb{V}ar(\varepsilon_2|\varepsilon_1 > -\mathbf{x}'_1 \beta_1, \mathbf{x}).$$

Using that ε_2 can be decomposed as $\rho \sigma_2 \varepsilon_1 + \xi$, where $\xi \sim \mathcal{N}(0, \sigma_2^2(1 - \rho^2))$ is independent from ε_1 , we get:

$$\mathbb{V}ar(y_2|y_1^* > 0, \mathbf{x}) = \sigma_2^2(1 - \rho^2) + \rho^2 \sigma_2^2 \mathbb{V}ar(\varepsilon_1|\varepsilon_1 > -\mathbf{x}'_1 \beta_1, \mathbf{x}).$$

Using Eq. (8.5), we get:

$$\mathbb{V}ar(\varepsilon_1|\varepsilon_1 > -\mathbf{x}'_1 \beta_1, \mathbf{x}) = 1 - \mathbf{x}'_1 \beta_1 \lambda(\mathbf{x}'_1 \beta_1) - \lambda(\mathbf{x}'_1 \beta_1)^2,$$

which gives

$$\begin{aligned} \mathbb{V}ar(y_2|y_1^* > 0, \mathbf{x}) &= \sigma_2^2(1 - \rho^2) + \rho^2 \sigma_2^2(1 - \mathbf{x}'_1 \beta_1 \lambda(\mathbf{x}'_1 \beta_1) - \lambda(\mathbf{x}'_1 \beta_1)^2) \\ &= \sigma_2^2 - \rho^2 \sigma_2^2 (\mathbf{x}'_1 \beta_1 \lambda(\mathbf{x}'_1 \beta_1) + \lambda(\mathbf{x}'_1 \beta_1)^2), \end{aligned}$$

and, finally:

$$\sigma_2^2 \approx \widehat{\mathbb{V}ar}(y_2|y_1^* > 0, \mathbf{x}) + \widehat{\rho \sigma_2}^2 (\mathbf{x}'_1 \widehat{\beta}_1 \lambda(\mathbf{x}'_1 \widehat{\beta}_1) + \lambda(\mathbf{x}'_1 \widehat{\beta}_1)^2).$$

The Heckman procedure is computationally simple. Although computational costs are no longer an issue, the two-step solution allows certain generalisations more easily than ML, and is more robust in certain circumstances. The computation of parameter standard errors is fairly complicated because of the two steps (see Cameron and Trivedi (2005), Subsection 16.10.2). Bootstrap can be resorted to.

Example 6.2 (Wage prediction). As in Example 6.1, let us use the Mroz (1987) dataset again, with the objective of explaining wage setting.

```
library(sampleSelection)
library(AER)
data("Mroz87")
Mroz87$lfy.yesno <- NaN
Mroz87$lfy.yesno[Mroz87$lfy==1] <- "yes"
Mroz87$lfy.yesno[Mroz87$lfy==0] <- "no"
Mroz87$lfy.yesno <- as.factor(Mroz87$lfy.yesno)
#Logit & Probit (selection equation)
logitW <- glm(lfy ~ age + I( age^2 ) + kids5 + huswage + educ,
```

```

        family = binomial(link = "logit"), data = Mroz87)
probitW <- glm(lfp ~ age + I( age^2 ) + kids5 + huswage + educ,
              family = binomial(link = "probit"), data = Mroz87)
# OLS for outcome:
ols1 <- lm(log(wage) ~ educ+exper+I( exper^2 )+city,data=subset(Mroz87,lfp==1))
# Two-step Heckman estimation
heckvan <-
  hekit( lfp ~ age + I( age^2 ) + kids5 + huswage + educ, # selection equation
        log(wage) ~ educ + exper + I( exper^2 ) + city, # outcome equation
        data=Mroz87 )
# Maximun likelihood estimation of selection model:
ml <- selection(lfp~age+I(age^2)+kids5+huswage+educ,
               log(wage)~educ+exper+I(exper^2)+city, data = Mroz87)
# Print selection-equation estimates:
stargazer(logitW,probitW,heckvan,ml,type = "text",no.space = TRUE,
          selection.equation = TRUE)

```

```

##
## =====
##                               Dependent variable:
##                               -----
##                               lfp
##                               Heckman
##                               selection
##                               selection
##                               (1)      (2)      (3)      (4)
## -----
## age                0.012      0.010      0.010      0.010
##                   (0.114)    (0.069)    (0.069)    (0.069)
## I(age2)            -0.001     -0.0005   -0.0005   -0.0005
##                   (0.001)    (0.001)    (0.001)    (0.001)
## kids5             -1.409***   -0.855*** -0.855*** -0.854***
##                   (0.198)    (0.116)    (0.115)    (0.116)
## huswage           -0.069***   -0.042*** -0.042*** -0.042***
##                   (0.020)    (0.012)    (0.012)    (0.013)
## educ              0.244***    0.148***  0.148***  0.148***
##                   (0.040)    (0.024)    (0.023)    (0.024)
## Constant          -0.938     -0.620   -0.620   -0.615
##                   (2.508)    (1.506)    (1.516)    (1.518)
## -----
## Observations              753      753      753      753
## R2                        0.158
## Adjusted R2              0.148
## Log Likelihood          -459.955 -459.901      -891.177
## Akaike Inf. Crit.       931.910  931.802

```

[illegible]

```
# Print outcome-equation estimates:
```

```
stargazer(ols1,heckvan,ml,type = "text",no.space = TRUE,omit.stat = "f")
```

##	=====		
##	Dependent variable:		
##	-----		
##		log(wage)	
##	OLS	Heckman	selection
##		selection	
##	(1)	(2)	(3)
##	-----		
## educ	0.106***	0.106***	0.106***
##	(0.014)	(0.017)	(0.017)
## exper	0.041***	0.041***	0.041***
##	(0.013)	(0.013)	(0.013)
## I(exper2)	-0.001**	-0.001**	-0.001**
##	(0.0004)	(0.0004)	(0.0004)
## city	0.054	0.053	0.053
##	(0.068)	(0.069)	(0.069)
## Constant	-0.531***	-0.547*	-0.544**
##	(0.199)	(0.289)	(0.272)
##	-----		
## Observations	428	753	753
## R2	0.158	0.158	
## Adjusted R2	0.150	0.148	
## Log Likelihood			-891.177
## rho		0.018	0.014 (0.203)
## Inverse Mills Ratio		0.012 (0.152)	
## Residual Std. Error	0.667 (df = 423)		
##	=====		
## Note:	*p<0.1; **p<0.05; ***p<0.01		

Chapter 7

Models of Count Data

Count-data models aim at explaining dependent variables y_i that take integer values. Typically, one may want to account for the number of doctor visits, of customers, of hospital stays, of borrowers' defaults, of recreational trips, of accidents. Quite often, these data feature large proportion of zeros (see, e.g., Table 20.1 in Cameron and Trivedi (2005)), and/or are skewed to the right.

7.1 Poisson model

The most basic count-data model is the Poisson model. In this model, we have $y \sim \mathcal{P}(\mu)$, i.e.

$$\mathbb{P}(y = k) = \frac{\mu^k e^{-\mu}}{k!},$$

implying $\mathbb{E}(y) = \text{Var}(y) = \mu$.

the Poisson parameter, μ , is then assumed to depend on some observed variables, gathered in vector \mathbf{x}_i for entity i . To ensure that $\mu_i \geq 0$, it is common to take $\mu_i = \exp(\beta' \mathbf{x}_i)$, which gives:

$$y_i \sim \mathcal{P}(\exp[\beta' \mathbf{x}_i]).$$

The Poisson regression is intrinsically heteroskedastic (since $\text{Var}(y_i) = \mu_i = \exp(\beta' \mathbf{x}_i)$).

Under the assumption of independence across entities, the log-likelihood is given by:

$$\log \mathcal{L}(\beta; \mathbf{y}, \mathbf{X}) = \sum_{i=1}^n (y_i \beta' \mathbf{x}_i - \exp[\beta' \mathbf{x}_i] - \ln[y_i!]).$$

The first-order condition to get the MLE is:

$$\sum_{i=1}^n (y_i - \exp[\beta' \mathbf{x}_i]) \mathbf{x}_i = \mathbf{0}_{K \times 1}. \quad (7.1)$$

Eq. (7.1) is equivalent to what would define the **Pseudo Maximum-Likelihood** estimator of β in the (misspecified) model

$$y_i \sim i.i.d. \mathcal{N}(\exp[\beta' \mathbf{x}_i], \sigma^2).$$

That is, Eq. (7.1) also characterizes the (true) ML estimator of β in the previous model.

Since $\mathbb{E}(y_i | \mathbf{x}_i) = \exp(\beta' \mathbf{x}_i)$, we have:

$$y_i = \exp(\beta' \mathbf{x}_i) + \varepsilon_i,$$

with $\mathbb{E}(\varepsilon_i | \mathbf{x}_i) = 0$. This notably implies that the (N)LS estimator of β is consistent.

How to interpret regression coefficients (the components of β)? We have:

$$\frac{\partial \mathbb{E}(y_i | \mathbf{x}_i)}{\partial x_{i,j}} = \beta_j \exp(\beta' \mathbf{x}_i),$$

which depends on the considered individual.

The average estimated response is:

$$\hat{\beta}_j \frac{1}{n} \sum_{i=1}^n \exp(\hat{\beta}' \mathbf{x}_i),$$

which is equal to $\hat{\beta}_j \bar{y}$ if the model includes a constant (e.g., if $x_{1,i} = 1$ for all entities i).

The limitation of the standard Poisson model is that the distribution of y_i conditional on \mathbf{x}_i depends on a single parameter (μ_i). Besides, there is often a tension between fitting the fraction of zeros, i.e. $\mathbb{P}(y_i = 0 | \mathbf{x}_i) = \exp[-\exp(\beta' \mathbf{x}_i)]$, and the distribution of $y_i | \mathbf{x}_i, y_i > 0$. The following models (negative binomial, or NB model, the Hurdle model, and the Zero-Inflated model) have been designed to address these points.

7.2 Negative binomial model

In the negative binomial model, we have:

$$y_i | \lambda_i \sim \mathcal{P}(\lambda_i),$$

but λ_i is now random. Specifically, it takes the form:

$$\lambda_i = \nu_i \times \exp(\beta' \mathbf{x}_i),$$

where $\nu_i \sim i.i.d. \Gamma(\underbrace{\delta}_{\text{shape}}, \underbrace{1/\delta}_{\text{scale}})$. That is, the p.d.f. of ν_i is:

$$g(\nu) = \frac{\nu^{\delta-1} e^{-\nu\delta} \delta^\delta}{\Gamma(\delta)},$$

where $\Gamma : z \mapsto \int_0^{+\infty} t^{z-1} e^{-t} dt$ (and $\Gamma(k+1) = k!$).

This notably implies that:

$$\mathbb{E}(\nu_i) = 1 \quad \text{and} \quad \mathbb{V}ar(\nu) = \frac{1}{\delta}.$$

Hence, the p.d.f. of y_i conditional on μ and δ (with $\mu = \exp(\beta' \mathbf{x}_i)$) is obtained as a mixture of densities:

$$\mathbb{P}(y_i = k | \exp(\beta' \mathbf{x}_i) = \mu; \delta) = \int_0^\infty \frac{e^{-\mu\nu} (\mu\nu)^k}{k!} \frac{\nu^{\delta-1} e^{-\nu\delta} \delta^\delta}{\Gamma(\delta)} d\nu.$$

It can be shown that:

$$\mathbb{E}(y|\mathbf{x}) = \mu \quad \text{and} \quad \mathbb{V}ar(y|\mathbf{x}) = \mu(1 + \alpha\mu),$$

where $\exp(\beta' \mathbf{x}_i) = \mu$ and $\alpha = 1/\delta$.

We have one additional degree of freedom w.r.t. the Poisson model (α).

Note that $\mathbb{V}ar(y|\mathbf{x}) > \mathbb{E}(y|\mathbf{x})$ (which is often called for by the data). Moreover, the conditional variance is quadratic in the mean:

$$\mathbb{V}ar(y|\mathbf{x}) = \mu + \alpha\mu^2.$$

The previous expression is the basis of the so-called **NB2** specification. If δ is replaced with μ/γ , then we get the **NB1** model:

$$\mathbb{V}ar(y|\mathbf{x}) = \mu(1 + \gamma).$$

Example 7.1 (Number of doctor visits). The following example compares different specifications, namely a linear regression model, a Poisson model, and a NB model, to account for the number of doctor visits. The dataset (`randdata`) is the one used in Chapter 20 of Cameron and Trivedi (2005) (available on that page).

```
library(AEC)
library(COUNT)
library(psc1) # for predprob function and hurdle model
par(plt=c(.15,.95,.1,.95))
plot(table(randdata$mdvis))
```

```
c(mean(randdata$mdvis),var(randdata$mdvis))
```

```
## [1] 2.860426 20.289300
```

As shown on the previous line, the variance of the number of visits is much larger than its expectation. This suggests that a Poisson model would be misspecified.

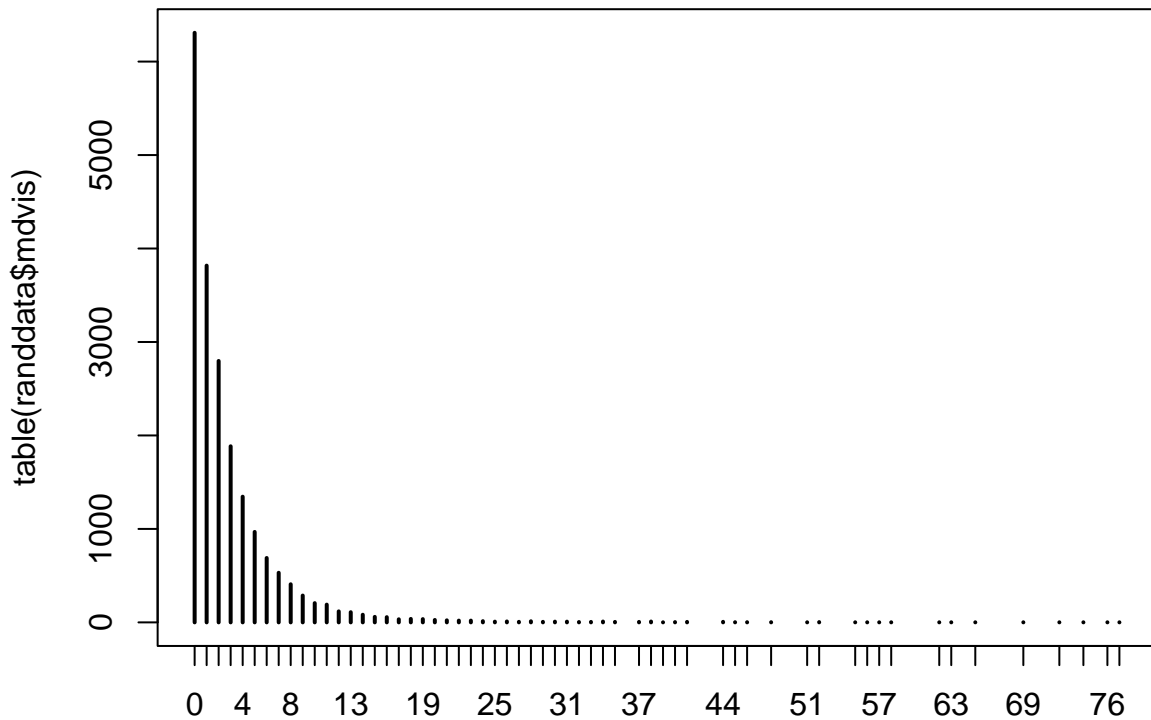


Figure 7.1: Distribution of the number of doctor visits.

```

randdata$LC <- log(1 + randdata$coins)
model.OLS <- lm(mdvis ~ LC + idp + lpi + fmde + physlm + disea + hlthg +
               hlthf + hlthp - 1, data=randdata)
model.poisson <- glm(mdvis ~ LC + idp + lpi + fmde + physlm + disea +
                    hlthg + hlthf + hlthp - 1, data=randdata, family = poisson)
model.neg.bin <- glm.nb(mdvis ~ LC + idp + lpi + fmde + physlm + disea +
                       hlthg + hlthf + hlthp - 1, data=randdata)
model.neg.bin.with.intercept <-
  glm.nb(mdvis ~ LC + idp + lpi + fmde + physlm + disea + hlthg +
         hlthf + hlthp, data=randdata)
stargazer::stargazer(model.OLS, model.poisson, model.neg.bin,
                     model.neg.bin.with.intercept, type="text",
                     no.space = TRUE, omit.stat = c("f", "ser"))

```

```

##
## =====
##                               Dependent variable:
##                               -----
##                               mdvis
##                               OLS      Poisson      negative
##                               (1)      (2)      (3)      binomial
##                               (4)
##

```



```
## -----
## LC          -0.155*** -0.051*** -0.057*** -0.058***
##              (0.020)  (0.003)  (0.006)  (0.006)
## idp         -0.546*** -0.183*** -0.212*** -0.268***
##              (0.075)  (0.011)  (0.023)  (0.023)
## lpi         0.230***  0.095***  0.088***  0.041***
##              (0.012)  (0.002)  (0.004)  (0.004)
## fmde        -0.073*** -0.029*** -0.030*** -0.038***
##              (0.012)  (0.002)  (0.004)  (0.003)
## physlm      0.945***  0.217***  0.229***  0.269***
##              (0.104)  (0.013)  (0.031)  (0.030)
## disea       0.177***  0.050***  0.062***  0.038***
##              (0.004)  (0.0005) (0.001)  (0.001)
## hlthg       0.270***  0.126***  0.068*** -0.044**
##              (0.066)  (0.009)  (0.020)  (0.020)
## hlthf       0.455***  0.149***  0.084**  0.017
##              (0.123)  (0.016)  (0.037)  (0.036)
## hlthp       1.537***  0.197***  0.185**  0.178**
##              (0.263)  (0.027)  (0.076)  (0.074)
## Constant                    0.664***
##                          (0.025)
## -----
## Observations      20,190      20,190      20,190      20,190
## R2                 0.322
## Adjusted R2       0.322
## Log Likelihood          -64,221.340 -43,745.860 -43,384.660
## theta                        0.732*** (0.010) 0.773*** (0.011)
## Akaike Inf. Crit.      128,460.700  87,509.710  86,789.320
## =====
## Note:                                *p<0.1; **p<0.05; ***p<0.01
```

In the previous table, The reported θ is the inverse of α appearing in $\text{Var}(y|\mathbf{x}) = \mu + \alpha\mu^2$ (NB2 specification). That is, the model implies that $\text{Var}(y|\mathbf{x}) = \mu + \mu^2/\theta$.

Models' predictions can be obtained as follows:

```
# prediction of beta'x, equivalent to "model.poisson$fitted.values":
predict_poisson.beta.x <- predict(model.poisson)
# prediction of the number of events (exp(beta'x)):
predict_poisson <- predict(model.poisson, type="response")
predict_NB <- model.neg.bin$fitted.values
```

Let us now compute the model-implied probabilities, and let's compare them with the frequencies observed in the data.

```
prop.table.data <- prop.table(table(randdata$mdvis))
predprob.poisson <- predprob(model.poisson) # part of pscl package
predprob.nb <- predprob(model.neg.bin)
print(rbind(prop.table.data[1:6],
            apply(predprob.poisson[,1:6],2,mean),
            apply(predprob.nb[,1:6],2,mean)))
```

```
##           0           1           2           3           4           5
## [1,] 0.3124319 0.1890540 0.1385339 0.09331352 0.06661714 0.04794453
## [2,] 0.1220592 0.2230328 0.2271621 0.17173478 0.10888940 0.06244353
## [3,] 0.3486824 0.1884640 0.1219340 0.08385899 0.05968603 0.04350209
```

It appears that the NB model is better at capturing the relatively large number of zeros than the Poisson model. This will also be the case for the Hurdle and Zero-Inflation models:

7.3 Hurdle model

The main objective of this model, w.r.t. the Poisson model, is to generate more zeros in the data than predicted by the previous count models. The idea is to separate the modeling of the number of zeros and that of the number of non-zero counts. Specifically, the frequency of zeros is determined by f_1 , the (relative) frequencies of non-zero counts are determined by f_2 :

$$f(y) = \begin{cases} f_1(0) & \text{if } y = 0, \\ \frac{1 - f_1(0)}{1 - f_2(0)} f_2(y) & \text{if } y > 0. \end{cases}$$

Note that we are back to the standard Poisson model if $f_1 \equiv f_2$. This model is straightforwardly estimated by ML.

7.4 Zero-inflated model

The objective is the same as for the Hurdle model, the modeling is slightly different. It is based on a mixture of a binary process B (p.d.f. f_1) and a process Z (p.d.f. f_2). B and Z are independent. Formally:

$$y = BZ,$$

implying:

$$f(y) = \begin{cases} f_1(0) + (1 - f_1(0))f_2(0) & \text{if } y = 0, \\ (1 - f_1(0))f_2(y) & \text{if } y > 0. \end{cases}$$

Typically, f_1 corresponds to a logit model and f_2 is Poisson or negative binomial density. This model is easily estimated by ML techniques.

Example 7.2 (Number of doctor visits). Let us come back to the data used in Example 7.1, and estimate Hurdle and a zero-inflation models:

```
library(stargazer)
model.hurdle <-
  hurdle(mdvis ~ LC + idp + lpi + fmde + physlm + disea + hlthg + hlthf +
    hlthp, data=randdata,
    dist = "poisson", zero.dist = "binomial", link = "logit")
model.zeroinfl <- zeroinfl(mdvis ~ LC + idp + lpi + fmde + physlm +
  disea + hlthg + hlthf + hlthp, data=randdata,
  dist = "poisson", link = "logit")
stargazer(model.hurdle,model.zeroinfl,zero.component=FALSE,
  no.space=TRUE,type="text")
```

```
##
## =====
##               Dependent variable:
##            -----
##                   mdvis
##             hurdle   zero-inflated
##                   count data
##                   (1)         (2)
## -----
```

## LC	-0.015***	-0.015***
##	(0.003)	(0.003)
## idp	-0.085***	-0.086***
##	(0.011)	(0.011)
## lpi	0.010***	0.010***
##	(0.002)	(0.002)
## fmde	-0.021***	-0.021***
##	(0.002)	(0.002)
## physlm	0.231***	0.231***
##	(0.012)	(0.012)
## disea	0.022***	0.022***
##	(0.001)	(0.001)
## hlthg	0.027***	0.026***
##	(0.010)	(0.010)
## hlthf	0.147***	0.146***
##	(0.016)	(0.016)
## hlthp	0.304***	0.303***
##	(0.026)	(0.026)
## Constant	1.133***	1.133***
##	(0.012)	(0.012)
##	-----	-----

```
## Observations      20,190      20,190
## Log Likelihood   -54,772.100   -54,772.550
## =====
## Note:            *p<0.1; **p<0.05; ***p<0.01
```

```
stargazer(model.hurdle,model.zeroinfl,zero.component=TRUE,
           no.space=TRUE,type="text")
```

```
##
## =====
##                      Dependent variable:
##                      -----
##                      mdvis
##                      hurdle      zero-inflated
##                      count data
##                      (1)          (2)
## -----
```

## LC	-0.150***	0.154***
##	(0.010)	(0.011)
## idp	-0.631***	0.637***
##	(0.038)	(0.040)
## lpi	0.102***	-0.105***
##	(0.007)	(0.007)
## fmde	-0.062***	0.060***
##	(0.006)	(0.006)
## physlm	0.239***	-0.203***
##	(0.056)	(0.058)
## disea	0.062***	-0.059***
##	(0.003)	(0.003)
## hlthg	-0.142***	0.158***
##	(0.034)	(0.036)
## hlthf	-0.352***	0.396***
##	(0.062)	(0.064)
## hlthp	-0.181	0.233
##	(0.149)	(0.151)
## Constant	0.411***	-0.528***
##	(0.044)	(0.047)
## -----		
## Observations	20,190	20,190
## Log Likelihood	-54,772.100	-54,772.550
## =====		
## Note:	*p<0.1; **p<0.05; ***p<0.01	

Let us test the importance of LC in the model using a Wald test:

```
# Test whether LC is important in the model:
```

```
model.hurdle.reduced <- update(model.hurdle, ~.-LC)
lmtest::waldtest(model.hurdle, model.hurdle.reduced)
```

```
## Wald test
```

```
##
```

```
## Model 1: mdvis ~ LC + idp + lpi + fmde + physlm + disea + hlthg + hlthf +  
##      hlthp
```

```
## Model 2: mdvis ~ idp + lpi + fmde + physlm + disea + hlthg + hlthf + hlthp
```

```
## Res.Df Df Chisq Pr(>Chisq)
```

```
## 1 20170
```

```
## 2 20172 -2 247.64 < 2.2e-16 ***
```

```
## ---
```

```
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Finally, we compare average model-implied probabilities with the frequencies observed in the data:

```
predprob.hurdle <- predprob(model.hurdle)
predprob.zeroinfl <- predprob(model.zeroinfl)
```

```
print(rbind(prop.table.data[1:6],  
  apply(predprob.poisson[,1:6],2,mean),  
  apply(predprob.nb[,1:6],2,mean),  
  apply(predprob.hurdle[,1:6],2,mean),  
  apply(predprob.zeroinfl[,1:6],2,mean)))
```

```
##           0           1           2           3           4           5  
## [1,] 0.3124319 0.18905399 0.1385339 0.09331352 0.06661714 0.04794453  
## [2,] 0.1220592 0.22303277 0.2271621 0.17173478 0.10888940 0.06244353  
## [3,] 0.3486824 0.18846395 0.1219340 0.08385899 0.05968603 0.04350209  
## [4,] 0.3124319 0.06056959 0.1083120 0.13262624 0.12553899 0.09847017  
## [5,] 0.3124687 0.06053019 0.1082797 0.13262552 0.12556525 0.09850216
```


Chapter 8

Appendix

8.1 Linear algebra: definitions and results

Definition 8.1 (Eigenvalues). The eigenvalues of a matrix M are the numbers λ for which:

$$|M - \lambda I| = 0,$$

where $|\bullet|$ is the determinant operator.

Proposition 8.1 (Properties of the determinant). *We have:*

- $|MN| = |M| \times |N|$.
- $|M^{-1}| = |M|^{-1}$.
- *If M admits the diagonal representation $M = TDT^{-1}$, where D is a diagonal matrix whose diagonal entries are $\{\lambda_i\}_{i=1,\dots,n}$, then:*

$$|M - \lambda I| = \prod_{i=1}^n (\lambda_i - \lambda).$$

Definition 8.2 (Moore-Penrose inverse). If $M \in \mathbb{R}^{m \times n}$, then its Moore-Penrose pseudo inverse (exists and) is the unique matrix $M^* \in \mathbb{R}^{n \times m}$ that satisfies:

- i. $MM^*M = M$
- ii. $M^*MM^* = M^*$
- iii. $(MM^*)' = MM^*$.iv $(M^*M)' = M^*M$.

Proposition 8.2 (Properties of the Moore-Penrose inverse).

- *If M is invertible then $M^* = M^{-1}$.*
- *The pseudo-inverse of a zero matrix is its transpose. **
- ***
- The pseudo-inverse of the pseudo-inverse is the original matrix.*

Definition 8.3 (Idempotent matrix). Matrix M is idempotent if $M^2 = M$.

If M is a symmetric idempotent matrix, then $M'M = M$.

Proposition 8.3 (Roots of an idempotent matrix). *The eigenvalues of an idempotent matrix are either 1 or 0.*

Proof. If λ is an eigenvalue of an idempotent matrix M then $\exists x \neq 0$ s.t. $Mx = \lambda x$. Hence $M^2x = \lambda Mx \Rightarrow (1 - \lambda)Mx = 0$. Either all element of Mx are zero, in which case $\lambda = 0$ or at least one element of Mx is nonzero, in which case $\lambda = 1$. \square

Proposition 8.4 (Idempotent matrix and chi-square distribution). *The rank of a symmetric idempotent matrix is equal to its trace.*

Proof. The result follows from Prop. 8.3, combined with the fact that the rank of a symmetric matrix is equal to the number of its nonzero eigenvalues. \square

Proposition 8.5 (Constrained least squares). *The solution of the following optimisation problem:*

$$\begin{aligned} \min_{\beta} \quad & ||\mathbf{y} - \mathbf{X}\beta||^2 \\ \text{subject to } & \mathbf{R}\beta = \mathbf{q} \end{aligned}$$

is given by:

$$\beta^r = \beta_0 - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'\{\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'\}^{-1}(\mathbf{R}\beta_0 - \mathbf{q}),$$

where $\beta_0 = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$.

Proof. See for instance Jackman, 2007. \square

Proposition 8.6 (Inverse of a partitioned matrix). *We have:*

$$\begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{bmatrix}^{-1} = \begin{bmatrix} (\mathbf{A}_{11} - \mathbf{A}_{12}\mathbf{A}_{22}^{-1}\mathbf{A}_{21})^{-1} & -\mathbf{A}_{11}^{-1}\mathbf{A}_{12}(\mathbf{A}_{22} - \mathbf{A}_{21}\mathbf{A}_{11}^{-1}\mathbf{A}_{12})^{-1} \\ -(\mathbf{A}_{22} - \mathbf{A}_{21}\mathbf{A}_{11}^{-1}\mathbf{A}_{12})^{-1}\mathbf{A}_{21}\mathbf{A}_{11}^{-1} & (\mathbf{A}_{22} - \mathbf{A}_{21}\mathbf{A}_{11}^{-1}\mathbf{A}_{12})^{-1} \end{bmatrix}.$$

Definition 8.4 (Matrix derivatives). Consider a fonction $f : \mathbb{R}^K \rightarrow \mathbb{R}$. Its first-order derivative is:

$$\frac{\partial f}{\partial \mathbf{b}}(\mathbf{b}) = \begin{bmatrix} \frac{\partial f}{\partial b_1}(\mathbf{b}) \\ \vdots \\ \frac{\partial f}{\partial b_K}(\mathbf{b}) \end{bmatrix}.$$

We use the notation:

$$\frac{\partial f}{\partial \mathbf{b}'}(\mathbf{b}) = \left(\frac{\partial f}{\partial \mathbf{b}}(\mathbf{b}) \right)'.$$

Proposition 8.7. *We have:*

- If $f(\mathbf{b}) = A'\mathbf{b}$ where A is a $K \times 1$ vector then $\frac{\partial f}{\partial \mathbf{b}}(\mathbf{b}) = A$.
- If $f(\mathbf{b}) = \mathbf{b}'A\mathbf{b}$ where A is a $K \times K$ matrix, then $\frac{\partial f}{\partial \mathbf{b}}(\mathbf{b}) = 2A\mathbf{b}$.

Proposition 8.8 (Square and absolute summability). *We have:*

$$\underbrace{\sum_{i=0}^{\infty} |\theta_i| < +\infty}_{\text{Absolute summability}} \quad \Rightarrow \quad \underbrace{\sum_{i=0}^{\infty} \theta_i^2 < +\infty}_{\text{Square summability}}.$$

Proof. See Appendix 3.A in Hamilton. Idea: Absolute summability implies that there exist N such that, for $j > N$, $|\theta_j| < 1$ (deduced from Cauchy criterion, Theorem 8.2 and therefore $\theta_j^2 < |\theta_j|$). \square

8.2 Statistical analysis: definitions and results

8.2.1 Moments and statistics

Definition 8.5 (Partial correlation). The **partial correlation** between y and z , controlling for some variables \mathbf{X} is the sample correlation between y^* and z^* , where the latter two variables are the residuals in regressions of y on \mathbf{X} and of z on \mathbf{X} , respectively.

This correlation is denoted by $r_{yz}^{\mathbf{X}}$. By definition, we have:

$$r_{yz}^{\mathbf{X}} = \frac{\mathbf{z}^{*'}\mathbf{y}^*}{\sqrt{(\mathbf{z}^{*'}\mathbf{z}^*)(\mathbf{y}^{*'}\mathbf{y}^*)}}. \quad (8.1)$$

Definition 8.6 (Skewness and kurtosis). Let Y be a random variable whose fourth moment exists. The expectation of Y is denoted by μ .

- The skewness of Y is given by:

$$\frac{\mathbb{E}[(Y - \mu)^3]}{\{\mathbb{E}[(Y - \mu)^2]\}^{3/2}}.$$

- The kurtosis of Y is given by:

$$\frac{\mathbb{E}[(Y - \mu)^4]}{\{\mathbb{E}[(Y - \mu)^2]\}^2}.$$

Theorem 8.1 (Cauchy-Schwarz inequality). *We have:*

$$|\text{Cov}(X, Y)| \leq \sqrt{\text{Var}(X)\text{Var}(Y)}$$

and, if $X \neq 0$ and $Y \neq 0$, the equality holds iff X and Y are the same up to an affine transformation.

Proof. If $\text{Var}(X) = 0$, this is trivial. If this is not the case, then let's define Z as $Z = Y - \frac{\text{Cov}(X, Y)}{\text{Var}(X)}X$. It is easily seen that $\text{Cov}(X, Z) = 0$. Then, the variance of $Y = Z + \frac{\text{Cov}(X, Y)}{\text{Var}(X)}X$ is equal to the sum of the variance of Z and of the variance of $\frac{\text{Cov}(X, Y)}{\text{Var}(X)}X$, that is:

$$\text{Var}(Y) = \text{Var}(Z) + \left(\frac{\text{Cov}(X, Y)}{\text{Var}(X)} \right)^2 \text{Var}(X) \geq \left(\frac{\text{Cov}(X, Y)}{\text{Var}(X)} \right)^2 \text{Var}(X).$$

The equality holds iff $\text{Var}(Z) = 0$, i.e. iff $Y = \frac{\text{Cov}(X, Y)}{\text{Var}(X)}X + cst$. □

Definition 8.7 (Asymptotic level). An asymptotic test with critical region Ω_n has an asymptotic level equal to α if:

$$\sup_{\theta \in \Theta} \lim_{n \rightarrow \infty} \mathbb{P}_\theta(S_n \in \Omega_n) = \alpha,$$

where S_n is the test statistic and Θ is such that the null hypothesis H_0 is equivalent to $\theta \in \Theta$.

Definition 8.8 (Asymptotically consistent test). An asymptotic test with critical region Ω_n is consistent if:

$$\forall \theta \in \Theta^c, \quad \mathbb{P}_\theta(S_n \in \Omega_n) \rightarrow 1,$$

where S_n is the test statistic and Θ^c is such that the null hypothesis H_0 is equivalent to $\theta \notin \Theta$.

Definition 8.9 (Kullback discrepancy). Given two p.d.f. f and f^* , the Kullback discrepancy is defined by:

$$I(f, f^*) = \mathbb{E}^* \left(\log \frac{f^*(Y)}{f(Y)} \right) = \int \log \frac{f^*(y)}{f(y)} f^*(y) dy.$$

Proposition 8.9 (Properties of the Kullback discrepancy). *We have:*

- i. $I(f, f^*) \geq 0$
- ii. $I(f, f^*) = 0$ iff $f \equiv f^*$.

Proof. $x \rightarrow -\log(x)$ is a convex function. Therefore $\mathbb{E}^*(-\log f(Y)/f^*(Y)) \geq -\log \mathbb{E}^*(f(Y)/f^*(Y)) = 0$ (proves (i)). Since $x \rightarrow -\log(x)$ is strictly convex, equality in (i) holds if and only if $f(Y)/f^*(Y)$ is constant (proves (ii)). □

Definition 8.10 (Characteristic function). For any real-valued random variable X , the characteristic function is defined by:

$$\phi_X : u \rightarrow \mathbb{E}[\exp(iuX)].$$

8.2.2 Standard distributions

Definition 8.11 (F distribution). Consider $n = n_1 + n_2$ i.i.d. $\mathcal{N}(0, 1)$ r.v. X_i . If the r.v. F is defined by:

$$F = \frac{\sum_{i=1}^{n_1} X_i^2}{\sum_{j=n_1+1}^{n_1+n_2} X_j^2} \frac{n_2}{n_1}$$

then $F \sim \mathcal{F}(n_1, n_2)$. (See Table 8.4 for quantiles.)

Definition 8.12 (Student-t distribution). Z follows a Student-t (or t) distribution with ν degrees of freedom (d.f.) if:

$$Z = X_0 / \sqrt{\frac{\sum_{i=1}^{\nu} X_i^2}{\nu}}, \quad X_i \sim i.i.d. \mathcal{N}(0, 1).$$

We have $\mathbb{E}(Z) = 0$, and $\text{Var}(Z) = \frac{\nu}{\nu-2}$ if $\nu > 2$. (See Table 8.2 for quantiles.)

Definition 8.13 (Chi-square distribution). Z follows a χ^2 distribution with ν d.f. if $Z = \sum_{i=1}^{\nu} X_i^2$ where $X_i \sim i.i.d. \mathcal{N}(0, 1)$. We have $\mathbb{E}(Z) = \nu$. (See Table 8.3 for quantiles.)

Definition 8.14 (Cauchy distribution).

The probability distribution function of the Cauchy distribution defined by a location parameter μ and a scale parameter γ is:

$$f(x) = \frac{1}{\pi\gamma \left(1 + \left[\frac{x-\mu}{\gamma}\right]^2\right)}.$$

The mean and variance of this distribution are undefined.

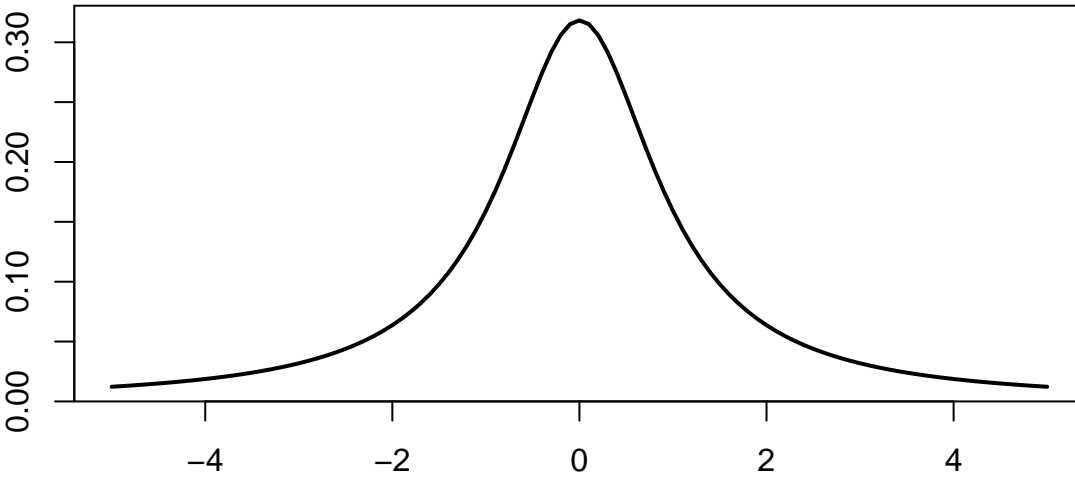


Figure 8.1: Pdf of the Cauchy distribution ($\mu = 0$, $\gamma = 1$).

Proposition 8.10 (Inner product of a multivariate Gaussian variable). Let X be a n -dimensional multivariate Gaussian variable: $X \sim \mathcal{N}(0, \Sigma)$. We have:

$$X' \Sigma^{-1} X \sim \chi^2(n).$$

Proof. Because Σ is a symmetrical definite positive matrix, it admits the spectral decomposition PDP' where P is an orthogonal matrix (i.e. $PP' = Id$) and D is a diagonal matrix with non-negative entries. Denoting by $\sqrt{D^{-1}}$ the diagonal matrix whose diagonal entries are the inverse of those of D , it is easily checked that the covariance matrix of $Y := \sqrt{D^{-1}}P'X$ is Id . Therefore Y is a vector of uncorrelated Gaussian variables. The properties of Gaussian variables imply that the components of Y are then also independent. Hence $Y'Y = \sum_i Y_i^2 \sim \chi^2(n)$.

It remains to note that $Y'Y = X'PD^{-1}P'X = X'\mathbb{V}ar(X)^{-1}X$ to conclude. \square

Definition 8.15 (Generalized Extreme Value (GEV) distribution). The vector of disturbances $\varepsilon = [\varepsilon_{1,1}, \dots, \varepsilon_{1,K_1}, \dots, \varepsilon_{J,1}, \dots, \varepsilon_{J,K_J}]'$ follows the Generalized Extreme Value (GEV) distribution if its c.d.f. is:

$$F(\varepsilon, \rho) = \exp(-G(e^{-\varepsilon_{1,1}}, \dots, e^{-\varepsilon_{J,K_J}}; \rho))$$

with

$$\begin{aligned} G(\mathbf{Y}; \rho) &\equiv G(Y_{1,1}, \dots, Y_{1,K_1}, \dots, Y_{J,1}, \dots, Y_{J,K_J}; \rho) \\ &= \sum_{j=1}^J \left(\sum_{k=1}^{K_j} Y_{jk}^{1/\rho_j} \right)^{\rho_j} \end{aligned}$$

8.2.3 Stochastic convergences

Proposition 8.11 (Chebychev's inequality). *If $\mathbb{E}(|X|^r)$ is finite for some $r > 0$ then:*

$$\forall \varepsilon > 0, \quad \mathbb{P}(|X - c| > \varepsilon) \leq \frac{\mathbb{E}[|X - c|^r]}{\varepsilon^r}.$$

In particular, for $r = 2$:

$$\forall \varepsilon > 0, \quad \mathbb{P}(|X - c| > \varepsilon) \leq \frac{\mathbb{E}[(X - c)^2]}{\varepsilon^2}.$$

Proof. Remark that $\varepsilon^r \mathbb{I}_{\{|X| \geq \varepsilon\}} \leq |X|^r$ and take the expectation of both sides. \square

Definition 8.16 (Convergence in probability). The random variable sequence x_n converges in probability to a constant c if $\forall \varepsilon, \lim_{n \rightarrow \infty} \mathbb{P}(|x_n - c| > \varepsilon) = 0$.

It is denoted as: $\text{plim } x_n = c$.

Definition 8.17 (Convergence in the L^r norm). x_n converges in the r -th mean (or in the L^r -norm) towards x , if $\mathbb{E}(|x_n|^r)$ and $\mathbb{E}(|x|^r)$ exist and if

$$\lim_{n \rightarrow \infty} \mathbb{E}(|x_n - x|^r) = 0.$$

It is denoted as: $x_n \xrightarrow{L^r} c$.

For $r = 2$, this convergence is called **mean square convergence**.

Definition 8.18 (Almost sure convergence). The random variable sequence x_n converges almost surely to c if $\mathbb{P}(\lim_{n \rightarrow \infty} x_n = c) = 1$.

It is denoted as: $x_n \xrightarrow{a.s.} c$.

Definition 8.19 (Convergence in distribution). x_n is said to converge in distribution (or in law) to x if

$$\lim_{n \rightarrow \infty} F_{x_n}(s) = F_x(s)$$

for all s at which F_X —the cumulative distribution of X —is continuous.

It is denoted as: $x_n \xrightarrow{d} x$.

Proposition 8.12 (Rules for limiting distributions (Slutsky)). *We have:*

i. **Slutsky's theorem:** If $x_n \xrightarrow{d} x$ and $y_n \xrightarrow{p} c$ then

$$\begin{aligned} x_n y_n &\xrightarrow{d} xc \\ x_n + y_n &\xrightarrow{d} x + c \\ x_n / y_n &\xrightarrow{d} x/c \quad (\text{if } c \neq 0) \end{aligned}$$

ii. **Continuous mapping theorem:** If $x_n \xrightarrow{d} x$ and g is a continuous function then $g(x_n) \xrightarrow{d} g(x)$.

Proposition 8.13 (Implications of stochastic convergences). *We have:*

$$\begin{array}{ccc} \boxed{L^s} & \xRightarrow{1 \leq r \leq s} & \boxed{L^r} \\ & & \Downarrow \\ \boxed{a.s.} & \Rightarrow & \boxed{p} \Rightarrow \boxed{d} \end{array}$$

Proof. (of the fact that $\left(\xrightarrow{p}\right) \Rightarrow \left(\xrightarrow{d}\right)$). Assume that $X_n \xrightarrow{p} X$. Denoting by F and F_n the c.d.f. of X and X_n , respectively:

$$\begin{aligned} F_n(x) &= \mathbb{P}(X_n \leq x, X \leq x + \varepsilon) + \mathbb{P}(X_n \leq x, X > x + \varepsilon) \\ &\leq F(x + \varepsilon) + \mathbb{P}(|X_n - X| > \varepsilon). \end{aligned}$$

Besides,

$$\begin{aligned} F(x - \varepsilon) &= \mathbb{P}(X \leq x - \varepsilon, X_n \leq x) + \mathbb{P}(X \leq x - \varepsilon, X_n > x) \\ &\leq F_n(x) + \mathbb{P}(|X_n - X| > \varepsilon), \end{aligned}$$

which implies:

$$F(x - \varepsilon) - \mathbb{P}(|X_n - X| > \varepsilon) \leq F_n(x). \quad (8.2)$$

Eqs. (8.2) and (8.2) imply:

$$F(x - \varepsilon) - \mathbb{P}(|X_n - X| > \varepsilon) \leq F_n(x) \leq F(x + \varepsilon) + \mathbb{P}(|X_n - X| > \varepsilon).$$

Taking limits as $n \rightarrow \infty$ yields

$$F(x - \varepsilon) \leq \liminf_{n \rightarrow \infty} F_n(x) \leq \limsup_{n \rightarrow \infty} F_n(x) \leq F(x + \varepsilon).$$

The result is then obtained by taking limits as $\varepsilon \rightarrow 0$ (if F is continuous at x). \square

Proposition 8.14 (Convergence in distribution to a constant). *If X_n converges in distribution to a constant c , then X_n converges in probability to c .*

Proof. If $\varepsilon > 0$, we have $\mathbb{P}(X_n < c - \varepsilon) \xrightarrow{n \rightarrow \infty} 0$ i.e. $\mathbb{P}(X_n \geq c - \varepsilon) \xrightarrow{n \rightarrow \infty} 1$ and $\mathbb{P}(X_n < c + \varepsilon) \xrightarrow{n \rightarrow \infty} 1$. Therefore $\mathbb{P}(c - \varepsilon \leq X_n < c + \varepsilon) \xrightarrow{n \rightarrow \infty} 1$, which gives the result. \square

Example 8.1 (Convergence in probability but not L^r). Let $\{x_n\}_{n \in \mathbb{N}}$ be a series of random variables defined by:

$$x_n = nu_n,$$

where u_n are independent random variables s.t. $u_n \sim \mathcal{B}(1/n)$.

We have $x_n \xrightarrow{p} 0$ but $x_n \not\xrightarrow{L^r} 0$ because $\mathbb{E}(|X_n - 0|) = \mathbb{E}(X_n) = 1$.

Theorem 8.2 (Cauchy criterion (non-stochastic case)). *We have that $\sum_{i=0}^T a_i$ converges ($T \rightarrow \infty$) iff, for any $\eta > 0$, there exists an integer N such that, for all $M \geq N$,*

$$\left| \sum_{i=N+1}^M a_i \right| < \eta.$$

Theorem 8.3 (Cauchy criterion (stochastic case)). *We have that $\sum_{i=0}^T \theta_i \varepsilon_{t-i}$ converges in mean square ($T \rightarrow \infty$) to a random variable iff, for any $\eta > 0$, there exists an integer N such that, for all $M \geq N$,*

$$\mathbb{E} \left[\left(\sum_{i=N+1}^M \theta_i \varepsilon_{t-i} \right)^2 \right] < \eta.$$

8.2.4 Central limit theorem

Theorem 8.4 (Law of large numbers). *The sample mean is a consistent estimator of the population mean.*

Proof. Let's denote by ϕ_{X_i} the characteristic function of a r.v. X_i . If the mean of X_i is μ then the Talyor expansion of the characteristic function is:

$$\phi_{X_i}(u) = \mathbb{E}(\exp(iuX)) = 1 + iu\mu + o(u).$$

The properties of the characteristic function (see Def. 8.10) imply that:

$$\phi_{\frac{1}{n}(X_1+\dots+X_n)}(u) = \prod_{i=1}^n \left(1 + i\frac{u}{n}\mu + o\left(\frac{u}{n}\right)\right) \rightarrow e^{iu\mu}.$$

The facts that (a) $e^{iu\mu}$ is the characteristic function of the constant μ and (b) that a characteristic function uniquely characterises a distribution imply that the sample mean converges in distribution to the constant μ , which further implies that it converges in probability to μ . \square

Theorem 8.5 (Lindberg-Levy Central limit theorem, CLT). *If x_n is an i.i.d. sequence of random variables with mean μ and variance $\sigma^2 \in]0, +\infty[$, then:*

$$\sqrt{n}(\bar{x}_n - \mu) \xrightarrow{d} \mathcal{N}(0, \sigma^2), \quad \text{where} \quad \bar{x}_n = \frac{1}{n} \sum_{i=1}^n x_i.$$

Proof. Let us introduce the r.v. $Y_n := \sqrt{n}(\bar{X}_n - \mu)$. We have $\phi_{Y_n}(u) = \left[\mathbb{E} \left(\exp(i\frac{1}{\sqrt{n}}u(X_1 - \mu)) \right) \right]^n$. We have:

$$\begin{aligned} & \left[\mathbb{E} \left(\exp \left(i\frac{1}{\sqrt{n}}u(X_1 - \mu) \right) \right) \right]^n \\ &= \left[\mathbb{E} \left(1 + i\frac{1}{\sqrt{n}}u(X_1 - \mu) - \frac{1}{2n}u^2(X_1 - \mu)^2 + o(u^2) \right) \right]^n \\ &= \left(1 - \frac{1}{2n}u^2\sigma^2 + o(u^2) \right)^n. \end{aligned}$$

Therefore $\phi_{Y_n}(u) \xrightarrow{n \rightarrow \infty} \exp\left(-\frac{1}{2}u^2\sigma^2\right)$, which is the characteristic function of $\mathcal{N}(0, \sigma^2)$. \square

8.3 Some properties of Gaussian variables

Proposition 8.15. *If \mathbf{A} is idempotent and if \mathbf{x} is Gaussian, \mathbf{Lx} and $\mathbf{x}'\mathbf{Ax}$ are independent if $\mathbf{LA} = \mathbf{0}$.*

Proof. If $\mathbf{LA} = \mathbf{0}$, then the two Gaussian vectors \mathbf{Lx} and \mathbf{Ax} are independent. This implies the independence of any function of \mathbf{Lx} and any function of \mathbf{Ax} . The results then follows from the observation that $\mathbf{x}'\mathbf{Ax} = (\mathbf{Ax})'(\mathbf{Ax})$, which is a function of \mathbf{Ax} . \square

Proposition 8.16 (Bayesian update in a vector of Gaussian variables). *If*

$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} \sim \mathcal{N} \left(0, \begin{bmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{bmatrix} \right),$$

then

$$\begin{aligned} Y_2|Y_1 &\sim \mathcal{N}(\Omega_{21}\Omega_{11}^{-1}Y_1, \Omega_{22} - \Omega_{21}\Omega_{11}^{-1}\Omega_{12}) \\ Y_1|Y_2 &\sim \mathcal{N}(\Omega_{12}\Omega_{22}^{-1}Y_2, \Omega_{11} - \Omega_{12}\Omega_{22}^{-1}\Omega_{21}). \end{aligned}$$

Proposition 8.17 (Truncated distributions). *If X is a random variable distributed according to some p.d.f. f , with c.d.f. F , with infinite support. Then the p.d.f. of $X|a \leq X < b$ is*

$$g(x) = \frac{f(x)}{F(b) - F(a)} \mathbb{I}_{\{a \leq x < b\}},$$

for any $a < b$.

In particular, for a Gaussian variable $X \sim \mathcal{N}(\mu, \sigma^2)$, we have

$$f(X = x|a \leq X < b) = \frac{\frac{1}{\sigma} \phi\left(\frac{x - \mu}{\sigma}\right)}{Z}.$$

with $Z = \Phi(\beta) - \Phi(\alpha)$, where $\alpha = \frac{a - \mu}{\sigma}$ and $\beta = \frac{b - \mu}{\sigma}$.

Moreover:

$$\mathbb{E}(X|a \leq X < b) = \mu - \frac{\phi(\beta) - \phi(\alpha)}{Z} \sigma. \quad (8.3)$$

We also have:

$$\begin{aligned} & \text{Var}(X|a \leq X < b) \\ &= \sigma^2 \left[1 - \frac{\beta \phi(\beta) - \alpha \phi(\alpha)}{Z} - \left(\frac{\phi(\beta) - \phi(\alpha)}{Z} \right)^2 \right] \end{aligned} \quad (8.4)$$

In particular, for $b \rightarrow \infty$, we get:

$$\text{Var}(X|a < X) = \sigma^2 [1 + \alpha \lambda(-\alpha) - \lambda(-\alpha)^2], \quad (8.5)$$

with $\lambda(x) = \frac{\phi(x)}{\Phi(x)}$ is called the **inverse Mills ratio**.

Consider the case where $a \rightarrow -\infty$ (i.e. the conditioning set is $X < b$) and $\mu = 0$, $\sigma = 1$. Then Eq. (8.3) gives $\mathbb{E}(X|X < b) = -\lambda(b) = -\frac{\phi(b)}{\Phi(b)}$, where λ is the function computing the inverse Mills ratio.

Proposition 8.18 (p.d.f. of a multivariate Gaussian variable). *If $Y \sim \mathcal{N}(\mu, \Omega)$ and if Y is a n -dimensional vector, then the density function of Y is:*

$$\frac{1}{(2\pi)^{n/2} |\Omega|^{1/2}} \exp \left[-\frac{1}{2} (Y - \mu)' \Omega^{-1} (Y - \mu) \right].$$

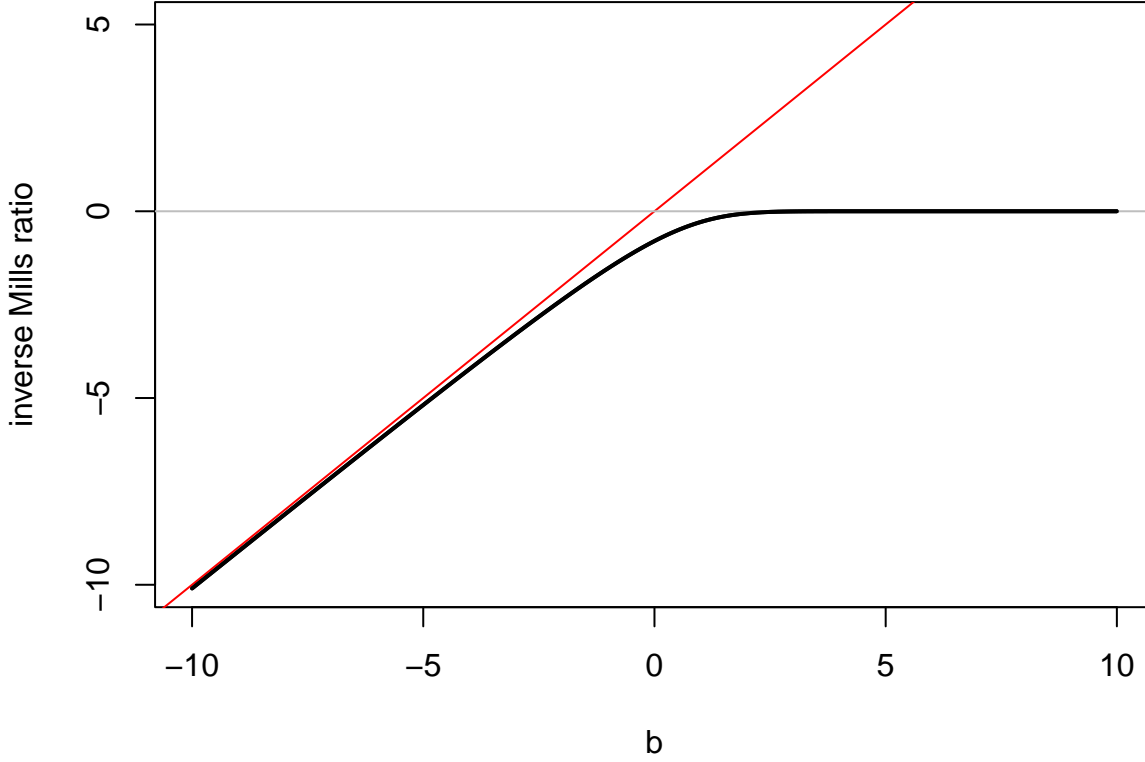


Figure 8.2: $\mathbb{E}(X|X < b)$ as a function of b when $X \sim \mathcal{N}(0, 1)$ (in black).

8.4 Proofs

Proof of Proposition 3.4

Proof. Assumptions (i) and (ii) (in the set of Assumptions 3.1) imply that θ_{MLE} exists ($= \operatorname{argmax}_{\theta} (1/n) \log \mathcal{L}(\theta; \mathbf{y})$).

$(1/n) \log \mathcal{L}(\theta; \mathbf{y})$ can be interpreted as the sample mean of the r.v. $\log f(Y_i; \theta)$ that are i.i.d. Therefore $(1/n) \log \mathcal{L}(\theta; \mathbf{y})$ converges to $\mathbb{E}_{\theta_0}(\log f(Y; \theta))$ – which exists (Assumption iv).

Because the latter convergence is uniform (Assumption v), the solution θ_{MLE} almost surely converges to the solution to the limit problem:

$$\operatorname{argmax}_{\theta} \mathbb{E}_{\theta_0}(\log f(Y; \theta)) = \operatorname{argmax}_{\theta} \int_{\mathcal{Y}} \log f(y; \theta) f(y; \theta_0) dy.$$

Properties of the Kullback information measure (see Prop. 8.9), together with the identifiability assumption (ii) implies that the solution to the limit problem is unique and equal to θ_0 .

Consider a r.v. sequence θ that converges to θ_0 . The Taylor expansion of the score in a neighborhood of θ_0 yields to:

$$\frac{\partial \log \mathcal{L}(\theta; \mathbf{y})}{\partial \theta} = \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} + \frac{\partial^2 \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta \partial \theta'} (\theta - \theta_0) + o_p(\theta - \theta_0)$$

θ_{MLE} converges to θ_0 and satisfies the likelihood equation $\frac{\partial \log \mathcal{L}(\theta; \mathbf{y})}{\partial \theta} = \mathbf{0}$. Therefore:

$$\frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} \approx -\frac{\partial^2 \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta \partial \theta'} (\theta_{MLE} - \theta_0),$$

or equivalently:

$$\frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} \approx \left(-\frac{1}{n} \sum_{i=1}^n \frac{\partial^2 \log f(y_i; \theta_0)}{\partial \theta \partial \theta'} \right) \sqrt{n} (\theta_{MLE} - \theta_0),$$

By the law of large numbers, we have: $\left(-\frac{1}{n} \sum_{i=1}^n \frac{\partial^2 \log f(y_i; \theta_0)}{\partial \theta \partial \theta'} \right) \rightarrow \frac{1}{n} \mathbf{I}(\theta_0) = \mathcal{J}_Y(\theta_0)$.

Besides, we have:

$$\begin{aligned} \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} &= \sqrt{n} \left(\frac{1}{n} \sum_i \frac{\partial \log f(y_i; \theta_0)}{\partial \theta} \right) \\ &= \sqrt{n} \left(\frac{1}{n} \sum_i \left\{ \frac{\partial \log f(y_i; \theta_0)}{\partial \theta} - \mathbb{E}_{\theta_0} \frac{\partial \log f(Y_i; \theta_0)}{\partial \theta} \right\} \right) \end{aligned}$$

which converges to $\mathcal{N}(0, \mathcal{J}_Y(\theta_0))$ by the CLT.

Collecting the preceding results leads to (b). The fact that θ_{MLE} achieves the FDCR bound proves (c). \square

Proof of Proposition 3.5

Proof. We have $\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \mathcal{N}(0, \mathcal{J}(\theta_0)^{-1})$ (Eq. (3.10)). A Taylor expansion around θ_0 yields to:

$$\sqrt{n}(h(\hat{\theta}_n) - h(\theta_0)) \xrightarrow{d} \mathcal{N} \left(0, \frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h(\theta_0)'}{\partial \theta} \right). \quad (8.6)$$

Under H_0 , $h(\theta_0) = 0$ therefore:

$$\sqrt{n}h(\hat{\theta}_n) \xrightarrow{d} \mathcal{N} \left(0, \frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h(\theta_0)'}{\partial \theta} \right). \quad (8.7)$$

Hence

$$\sqrt{n} \left(\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h(\theta_0)'}{\partial \theta} \right)^{-1/2} h(\hat{\theta}_n) \xrightarrow{d} \mathcal{N}(0, Id).$$

Taking the quadratic form, we obtain:

$$nh(\hat{\theta}_n)' \left(\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h(\theta_0)'}{\partial \theta} \right)^{-1} h(\hat{\theta}_n) \xrightarrow{d} \chi^2(r).$$

The fact that the test has asymptotic level α directly stems from what precedes. **Consistency of the test:** Consider $\theta_0 \in \Theta$. Because the MLE is consistent, $h(\hat{\theta}_n)$ converges to $h(\theta_0) \neq 0$. Eq. (8.6) is still valid. It implies that ξ_n^W converges to $+\infty$ and therefore that $\mathbb{P}_\theta(\xi_n^W \geq \chi_{1-\alpha}^2(r)) \rightarrow 1$. \square

Proof of Proposition 3.6

Proof. Notations: “ \approx ” means “equal up to a term that converges to 0 in probability”. We are under H_0 . $\hat{\theta}^0$ is the constrained ML estimator; $\hat{\theta}$ denotes the unconstrained one.

We combine the two Taylor expansion: $h(\hat{\theta}_n) \approx \frac{\partial h(\theta_0)}{\partial \theta'}(\hat{\theta}_n - \theta_0)$ and $h(\hat{\theta}_n^0) \approx \frac{\partial h(\theta_0)}{\partial \theta'}(\hat{\theta}_n^0 - \theta_0)$ and we use $h(\hat{\theta}_n^0) = 0$ (by definition) to get:

$$\sqrt{n}h(\hat{\theta}_n) \approx \frac{\partial h(\theta_0)}{\partial \theta'}\sqrt{n}(\hat{\theta}_n - \hat{\theta}_n^0). \quad (8.8)$$

Besides, we have (using the definition of the information matrix):

$$\frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \approx \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} - \mathcal{J}(\theta_0)\sqrt{n}(\hat{\theta}_n^0 - \theta_0) \quad (8.9)$$

and:

$$0 = \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\hat{\theta}_n; \mathbf{y})}{\partial \theta} \approx \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} - \mathcal{J}(\theta_0)\sqrt{n}(\hat{\theta}_n - \theta_0). \quad (8.10)$$

Taking the difference and multiplying by $\mathcal{J}(\theta_0)^{-1}$:

$$\sqrt{n}(\hat{\theta}_n - \hat{\theta}_n^0) \approx \mathcal{J}(\theta_0)^{-1} \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \mathcal{J}(\theta_0). \quad (8.11)$$

Eqs. (8.8) and (8.11) yield to:

$$\sqrt{n}h(\hat{\theta}_n) \approx \frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta}. \quad (8.12)$$

Recall that $\hat{\theta}_n^0$ is the MLE of θ_0 under the constraint $h(\theta) = 0$. The vector of Lagrange multipliers $\hat{\lambda}_n$ associated to this program satisfies:

$$\frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} + \frac{\partial h'(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \hat{\lambda}_n = 0. \quad (8.13)$$

Substituting the latter equation in Eq. (8.12) gives:

$$\begin{aligned} \sqrt{n}h(\hat{\theta}_n) &\approx -\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h'(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \frac{\hat{\lambda}_n}{\sqrt{n}} \\ &\approx -\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h'(\theta_0; \mathbf{y})}{\partial \theta} \frac{\hat{\lambda}_n}{\sqrt{n}}, \end{aligned}$$

which yields:

$$\frac{\hat{\lambda}_n}{\sqrt{n}} \approx - \left(\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h'(\theta_0; \mathbf{y})}{\partial \theta} \right)^{-1} \sqrt{n}h(\hat{\theta}_n). \quad (8.14)$$

It follows, from Eq. (8.7), that:

$$\frac{\hat{\lambda}_n}{\sqrt{n}} \xrightarrow{d} \mathcal{N} \left(0, \left(\frac{\partial h(\theta_0)}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial h'(\theta_0; \mathbf{y})}{\partial \theta} \right)^{-1} \right).$$

Taking the quadratic form of the last equation gives:

$$\frac{1}{n} \hat{\lambda}_n' \frac{\partial h(\hat{\theta}_n^0)}{\partial \theta'} \mathcal{J}(\hat{\theta}_n^0)^{-1} \frac{\partial h'(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \hat{\lambda}_n \xrightarrow{d} \chi^2(r).$$

Using Eq. (8.13), it appears that the left-hand side term of the last equation is ξ^{LM} as defined in Eq. (3.18). Consistency: see Remark 17.3 in Gouriéroux and Monfort (1995). \square

Proof of Proposition 3.7

Proof. Let us first demonstrate the asymptotic equivalence of ξ^{LM} and ξ^{LR} .

The second-order Taylor expansions of $\log \mathcal{L}(\hat{\theta}_n^0, \mathbf{y})$ and $\log \mathcal{L}(\hat{\theta}_n, \mathbf{y})$ are:

$$\begin{aligned} \log \mathcal{L}(\hat{\theta}_n, \mathbf{y}) &\approx \log \mathcal{L}(\theta_0, \mathbf{y}) + \frac{\partial \log \mathcal{L}(\theta_0, \mathbf{y})}{\partial \theta'} (\hat{\theta}_n - \theta_0) \\ &\quad - \frac{n}{2} (\hat{\theta}_n - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n - \theta_0) \\ \log \mathcal{L}(\hat{\theta}_n^0, \mathbf{y}) &\approx \log \mathcal{L}(\theta_0, \mathbf{y}) + \frac{\partial \log \mathcal{L}(\theta_0, \mathbf{y})}{\partial \theta'} (\hat{\theta}_n^0 - \theta_0) \\ &\quad - \frac{n}{2} (\hat{\theta}_n^0 - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n^0 - \theta_0). \end{aligned}$$

Taking the difference, we obtain:

$$\begin{aligned} \xi_n^{LR} &\approx 2 \frac{\partial \log \mathcal{L}(\theta_0, \mathbf{y})}{\partial \theta'} (\hat{\theta}_n - \hat{\theta}_n^0) + n (\hat{\theta}_n^0 - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n^0 - \theta_0) \\ &\quad - n (\hat{\theta}_n - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n - \theta_0). \end{aligned}$$

Using $\frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\theta_0; \mathbf{y})}{\partial \theta} \approx \mathcal{J}(\theta_0) \sqrt{n} (\hat{\theta}_n - \theta_0)$ (Eq. (8.10)), we have:

$$\begin{aligned} \xi_n^{LR} &\approx 2n (\hat{\theta}_n - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n - \hat{\theta}_n^0) + n (\hat{\theta}_n^0 - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n^0 - \theta_0) \\ &\quad - n (\hat{\theta}_n - \theta_0)' \mathcal{J}(\theta_0) (\hat{\theta}_n - \theta_0). \end{aligned}$$

In the second of the three terms in the sum, we replace $(\hat{\theta}_n^0 - \theta_0)$ by $(\hat{\theta}_n^0 - \hat{\theta}_n + \hat{\theta}_n - \theta_0)$ and we develop the associated product. This leads to:

$$\xi_n^{LR} \approx n (\hat{\theta}_n^0 - \hat{\theta}_n)' \mathcal{J}(\theta_0)^{-1} (\hat{\theta}_n^0 - \hat{\theta}_n). \quad (8.15)$$

The difference between Eqs. (8.9) and (8.10) implies:

$$\frac{1}{\sqrt{n}} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \approx \mathcal{J}(\theta_0) \sqrt{n} (\hat{\theta}_n - \hat{\theta}_n^0),$$

which, associated to Eq. (8.10), gives:

$$\xi_n^{LR} \approx \frac{1}{n} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta'} \mathcal{J}(\theta_0)^{-1} \frac{\partial \log \mathcal{L}(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \approx \xi_n^{LM}.$$

Hence ξ_n^{LR} has the same asymptotic distribution as ξ_n^{LM} .

Let's show that the LR test is consistent. For this, note that:

$$\begin{aligned} \frac{\log \mathcal{L}(\hat{\theta}, \mathbf{y}) - \log \mathcal{L}(\hat{\theta}^0, \mathbf{y})}{n} &= \frac{1}{n} \sum_{i=1}^n [\log f(y_i; \hat{\theta}_n) - \log f(y_i; \hat{\theta}_n^0)] \\ &\rightarrow \mathbb{E}_0[\log f(Y; \theta_0) - \log f(Y; \theta_\infty)], \end{aligned}$$

where θ_∞ , the pseudo true value, is such that $h(\theta_\infty) \neq 0$ (by definition of H_1). From the Kullback inequality and the asymptotic identifiability of θ_0 , it follows that $\mathbb{E}_0[\log f(Y; \theta_0) - \log f(Y; \theta_\infty)] > 0$. Therefore $\xi_n^{LR} \rightarrow +\infty$ under H_1 .

Let us now demonstrate the equivalence of ξ^{LM} and ξ^W .

We have (using Eq. (8.14)):

$$\xi_n^{LM} = \frac{1}{n} \hat{\lambda}'_n \frac{\partial h(\hat{\theta}_n^0)}{\partial \theta'} \mathcal{J}(\hat{\theta}_n^0)^{-1} \frac{\partial h'(\hat{\theta}_n^0; \mathbf{y})}{\partial \theta} \hat{\lambda}_n.$$

Since, under H_0 , $\hat{\theta}_n^0 \approx \hat{\theta}_n \approx \theta_0$, Eq. (8.14) therefore implies that:

$$\xi^{LM} \approx n h(\hat{\theta}_n)' \left(\frac{\partial h(\hat{\theta}_n)}{\partial \theta'} \mathcal{J}(\hat{\theta}_n)^{-1} \frac{\partial h'(\hat{\theta}_n; \mathbf{y})}{\partial \theta} \right)^{-1} h(\hat{\theta}_n) = \xi^W,$$

which gives the result. □

8.5 Additional codes

8.5.1 Simulating GEV distributions

The following lines of code have been used to generate Figure 5.2.

```

n.sim <- 4000
par(mfrow=c(1,3),
    plt=c(.2,.95,.2,.85))
all.rhos <- c(.3,.6,.95)
for(j in 1:length(all.rhos)){
  theta <- 1/all.rhos[j]
  v1 <- runif(n.sim)
  v2 <- runif(n.sim)
  w <- rep(.000001,n.sim)
  # solve for f(w) = w*(1 - log(w)/theta) - v2 = 0
  for(i in 1:20){
    f.i <- w * (1 - log(w)/theta) - v2
    f.prime <- 1 - log(w)/theta - 1/theta
    w <- w - f.i/f.prime
  }
  u1 <- exp(v1^(1/theta) * log(w))
  u2 <- exp((1-v1)^(1/theta) * log(w))

  # Get eps1 and eps2 using the inverse of
  # the Gumbel distribution's cdf:
  eps1 <- -log(-log(u1))
  eps2 <- -log(-log(u2))
  cbind(cor(eps1,eps2),1-all.rhos[j]^2)
  plot(eps1,eps2,pch=19,col="#FF000044",
       main=paste("rho = ",toString(all.rhos[j]),sep=""),
       xlab=expression(epsilon[1]),
       ylab=expression(epsilon[2]),
       cex.lab=2,cex.main=1.5)
}

```

8.6 Statistical Tables

Table 8.1: Quantiles of the $\mathcal{N}(0, 1)$ distribution. If a and b are respectively the row and column number; then the corresponding cell gives $\mathbb{P}(0 < X \leq a + b)$, where $X \sim \mathcal{N}(0, 1)$.

	0	0.01	0.02	0.03	0.04	0.05	0.06	0.07	0.08	0.09
0	0.5000	0.6179	0.7257	0.8159	0.8849	0.9332	0.9641	0.9821	0.9918	0.9965
0.1	0.5040	0.6217	0.7291	0.8186	0.8869	0.9345	0.9649	0.9826	0.9920	0.9966
0.2	0.5080	0.6255	0.7324	0.8212	0.8888	0.9357	0.9656	0.9830	0.9922	0.9967
0.3	0.5120	0.6293	0.7357	0.8238	0.8907	0.9370	0.9664	0.9834	0.9925	0.9968
0.4	0.5160	0.6331	0.7389	0.8264	0.8925	0.9382	0.9671	0.9838	0.9927	0.9969
0.5	0.5199	0.6368	0.7422	0.8289	0.8944	0.9394	0.9678	0.9842	0.9929	0.9970
0.6	0.5239	0.6406	0.7454	0.8315	0.8962	0.9406	0.9686	0.9846	0.9931	0.9971
0.7	0.5279	0.6443	0.7486	0.8340	0.8980	0.9418	0.9693	0.9850	0.9932	0.9972
0.8	0.5319	0.6480	0.7517	0.8365	0.8997	0.9429	0.9699	0.9854	0.9934	0.9973
0.9	0.5359	0.6517	0.7549	0.8389	0.9015	0.9441	0.9706	0.9857	0.9936	0.9974
1	0.5398	0.6554	0.7580	0.8413	0.9032	0.9452	0.9713	0.9861	0.9938	0.9974
1.1	0.5438	0.6591	0.7611	0.8438	0.9049	0.9463	0.9719	0.9864	0.9940	0.9975
1.2	0.5478	0.6628	0.7642	0.8461	0.9066	0.9474	0.9726	0.9868	0.9941	0.9976
1.3	0.5517	0.6664	0.7673	0.8485	0.9082	0.9484	0.9732	0.9871	0.9943	0.9977
1.4	0.5557	0.6700	0.7704	0.8508	0.9099	0.9495	0.9738	0.9875	0.9945	0.9977
1.5	0.5596	0.6736	0.7734	0.8531	0.9115	0.9505	0.9744	0.9878	0.9946	0.9978
1.6	0.5636	0.6772	0.7764	0.8554	0.9131	0.9515	0.9750	0.9881	0.9948	0.9979
1.7	0.5675	0.6808	0.7794	0.8577	0.9147	0.9525	0.9756	0.9884	0.9949	0.9979
1.8	0.5714	0.6844	0.7823	0.8599	0.9162	0.9535	0.9761	0.9887	0.9951	0.9980
1.9	0.5753	0.6879	0.7852	0.8621	0.9177	0.9545	0.9767	0.9890	0.9952	0.9981
2	0.5793	0.6915	0.7881	0.8643	0.9192	0.9554	0.9772	0.9893	0.9953	0.9981
2.1	0.5832	0.6950	0.7910	0.8665	0.9207	0.9564	0.9778	0.9896	0.9955	0.9982
2.2	0.5871	0.6985	0.7939	0.8686	0.9222	0.9573	0.9783	0.9898	0.9956	0.9982
2.3	0.5910	0.7019	0.7967	0.8708	0.9236	0.9582	0.9788	0.9901	0.9957	0.9983
2.4	0.5948	0.7054	0.7995	0.8729	0.9251	0.9591	0.9793	0.9904	0.9959	0.9984
2.5	0.5987	0.7088	0.8023	0.8749	0.9265	0.9599	0.9798	0.9906	0.9960	0.9984
2.6	0.6026	0.7123	0.8051	0.8770	0.9279	0.9608	0.9803	0.9909	0.9961	0.9985
2.7	0.6064	0.7157	0.8078	0.8790	0.9292	0.9616	0.9808	0.9911	0.9962	0.9985
2.8	0.6103	0.7190	0.8106	0.8810	0.9306	0.9625	0.9812	0.9913	0.9963	0.9986
2.9	0.6141	0.7224	0.8133	0.8830	0.9319	0.9633	0.9817	0.9916	0.9964	0.9986

Table 8.2: Quantiles of the Student- t distribution. The rows correspond to different degrees of freedom (ν , say); the columns correspond to different probabilities (z , say). The cell gives q that is s.t. $\mathbb{P}(-q < X < q) = z$, with $X \sim t(\nu)$.

	0.05	0.1	0.75	0.9	0.95	0.975	0.99	0.999
1	0.079	0.158	2.414	6.314	12.706	25.452	63.657	636.619
2	0.071	0.142	1.604	2.920	4.303	6.205	9.925	31.599
3	0.068	0.137	1.423	2.353	3.182	4.177	5.841	12.924
4	0.067	0.134	1.344	2.132	2.776	3.495	4.604	8.610
5	0.066	0.132	1.301	2.015	2.571	3.163	4.032	6.869
6	0.065	0.131	1.273	1.943	2.447	2.969	3.707	5.959
7	0.065	0.130	1.254	1.895	2.365	2.841	3.499	5.408
8	0.065	0.130	1.240	1.860	2.306	2.752	3.355	5.041
9	0.064	0.129	1.230	1.833	2.262	2.685	3.250	4.781
10	0.064	0.129	1.221	1.812	2.228	2.634	3.169	4.587
20	0.063	0.127	1.185	1.725	2.086	2.423	2.845	3.850
30	0.063	0.127	1.173	1.697	2.042	2.360	2.750	3.646
40	0.063	0.126	1.167	1.684	2.021	2.329	2.704	3.551
50	0.063	0.126	1.164	1.676	2.009	2.311	2.678	3.496
60	0.063	0.126	1.162	1.671	2.000	2.299	2.660	3.460
70	0.063	0.126	1.160	1.667	1.994	2.291	2.648	3.435
80	0.063	0.126	1.159	1.664	1.990	2.284	2.639	3.416
90	0.063	0.126	1.158	1.662	1.987	2.280	2.632	3.402
100	0.063	0.126	1.157	1.660	1.984	2.276	2.626	3.390
200	0.063	0.126	1.154	1.653	1.972	2.258	2.601	3.340
500	0.063	0.126	1.152	1.648	1.965	2.248	2.586	3.310

Table 8.3: Quantiles of the χ^2 distribution. The rows correspond to different degrees of freedom; the columns correspond to different probabilities.

	0.05	0.1	0.75	0.9	0.95	0.975	0.99	0.999
1	0.004	0.016	1.323	2.706	3.841	5.024	6.635	10.828
2	0.103	0.211	2.773	4.605	5.991	7.378	9.210	13.816
3	0.352	0.584	4.108	6.251	7.815	9.348	11.345	16.266
4	0.711	1.064	5.385	7.779	9.488	11.143	13.277	18.467
5	1.145	1.610	6.626	9.236	11.070	12.833	15.086	20.515
6	1.635	2.204	7.841	10.645	12.592	14.449	16.812	22.458
7	2.167	2.833	9.037	12.017	14.067	16.013	18.475	24.322
8	2.733	3.490	10.219	13.362	15.507	17.535	20.090	26.124
9	3.325	4.168	11.389	14.684	16.919	19.023	21.666	27.877
10	3.940	4.865	12.549	15.987	18.307	20.483	23.209	29.588
20	10.851	12.443	23.828	28.412	31.410	34.170	37.566	45.315
30	18.493	20.599	34.800	40.256	43.773	46.979	50.892	59.703
40	26.509	29.051	45.616	51.805	55.758	59.342	63.691	73.402
50	34.764	37.689	56.334	63.167	67.505	71.420	76.154	86.661
60	43.188	46.459	66.981	74.397	79.082	83.298	88.379	99.607
70	51.739	55.329	77.577	85.527	90.531	95.023	100.425	112.317
80	60.391	64.278	88.130	96.578	101.879	106.629	112.329	124.839
90	69.126	73.291	98.650	107.565	113.145	118.136	124.116	137.208
100	77.929	82.358	109.141	118.498	124.342	129.561	135.807	149.449
200	168.279	174.835	213.102	226.021	233.994	241.058	249.445	267.541
500	449.147	459.926	520.950	540.930	553.127	563.852	576.493	603.446

Table 8.4: Quantiles of the \mathcal{F} distribution. The columns and rows correspond to different degrees of freedom (resp. n_1 and n_2). The different panels correspond to different probabilities (α) The corresponding cell gives z that is s.t. $\mathbb{P}(X \leq z) = \alpha$, with $X \sim \mathcal{F}(n_1, n_2)$.

	1	2	3	4	5	6	7	8	9	10
alpha = 0.9										
5	4.060	3.780	3.619	3.520	3.453	3.405	3.368	3.339	3.316	3.297
10	3.285	2.924	2.728	2.605	2.522	2.461	2.414	2.377	2.347	2.323
15	3.073	2.695	2.490	2.361	2.273	2.208	2.158	2.119	2.086	2.059
20	2.975	2.589	2.380	2.249	2.158	2.091	2.040	1.999	1.965	1.937
50	2.809	2.412	2.197	2.061	1.966	1.895	1.840	1.796	1.760	1.729
100	2.756	2.356	2.139	2.002	1.906	1.834	1.778	1.732	1.695	1.663
500	2.716	2.313	2.095	1.956	1.859	1.786	1.729	1.683	1.644	1.612
alpha = 0.95										
5	6.608	5.786	5.409	5.192	5.050	4.950	4.876	4.818	4.772	4.735
10	4.965	4.103	3.708	3.478	3.326	3.217	3.135	3.072	3.020	2.978
15	4.543	3.682	3.287	3.056	2.901	2.790	2.707	2.641	2.588	2.544
20	4.351	3.493	3.098	2.866	2.711	2.599	2.514	2.447	2.393	2.348
50	4.034	3.183	2.790	2.557	2.400	2.286	2.199	2.130	2.073	2.026
100	3.936	3.087	2.696	2.463	2.305	2.191	2.103	2.032	1.975	1.927
500	3.860	3.014	2.623	2.390	2.232	2.117	2.028	1.957	1.899	1.850
alpha = 0.99										
5	16.258	13.274	12.060	11.392	10.967	10.672	10.456	10.289	10.158	10.051
10	10.044	7.559	6.552	5.994	5.636	5.386	5.200	5.057	4.942	4.849
15	8.683	6.359	5.417	4.893	4.556	4.318	4.142	4.004	3.895	3.805
20	8.096	5.849	4.938	4.431	4.103	3.871	3.699	3.564	3.457	3.368
50	7.171	5.057	4.199	3.720	3.408	3.186	3.020	2.890	2.785	2.698
100	6.895	4.824	3.984	3.513	3.206	2.988	2.823	2.694	2.590	2.503
500	6.686	4.648	3.821	3.357	3.054	2.838	2.675	2.547	2.443	2.356

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