1. **Review** For vector spaces V and W, the function $f:V\to W$ is called a *homomorphism* or *linear map* if

 $f(r_1\vec{v}_1+r_2\vec{v}_2)=r_1f(\vec{v}_1)+r_2f(\vec{v}_2)$ for all $r_1,r_2\in\mathbb{R}$, $\vec{v}_1,\vec{v}_2\in\mathbb{V}$.

2. (Some preliminary terminology) Assume $f: V \to W$, $S \subseteq V$, and $T \subseteq W$.

image: for $v \in V$, the image of V is f(v), the image of S, denoted $f(S) = \{f(S) : S \in S\}$ inverse image:

(preimage)

So range of $f = \mathcal{R}(f) = f(V)$

for $w \in W$, the inverse image of w is $f^{-1}(w) = \{v \in V : h(v) = w\}$ inverse function:

f-1 is a function so that f-1(fcx)=x and f(fcx)=x.

- · For any function f, we can find f'(s) but f'(x) may not be a function. (We need f to be 1-1 for f' to be a function.
 - 3. (Lemma 2.1, Definition 2.2, and some notation) Assume $f: V \to W$ is a linear map between vector spaces V and W and assume V' is a subspace of V.
- . f(v') is a subspace of W.
- . f(V) is a subspace of W.
- · range space of f is R(f) w/ inherited vector operation from W.
- . dimension of (R(f)) = dimensial(f(V)) = dim. of range space = the rank of the mapf

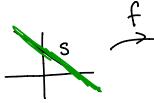
- 4. (Lemma 2.10, Definition 2.11, and some notation) Assume $f:V\to W$ is a linear map between vector spaces V and W and assume W' is a subspace of W.
- . f-1(W') is a subspace of V
- . f-1 ({ Ow}) is a subspace of V called the null space (or <u>kernel</u>) of f. Denoted N(f).
- · dim(N(f)) is the nullity of f.
- 5. (Theorem 2.14 and Corollary 2.17) Assume $f: V \to W$ is a linear map between vector spaces Vand W.
 - · dim V = rank (f) + nullity (f)
 - · rank f < dim V
 - · rankf=dimV (=> nullity (f)=0
 - · nullity(f)=0 (=> f:V → R(V) is an isomorphism
- 6. (Theorem 2.20) Assume $f: V \to W$ is a linear map between vector spaces V and W and dim(V) =n. The following are equivalent statements.
- Of is 1-1
- 2) f-1: f(v) = V is a function
- (5) rank (f)=n
 - 4 nullity (f)=0 lie. N(f)=\delta \vec{0}{v}\delta
- 5) If (b, , b, , ..., b,) is a basis of V, then

Examples:

1.
$$f: \mathbb{R}^2 \to \mathbb{R}$$
 defined as $f\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = x + y$

• Find the image of
$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$
 . $f(\begin{bmatrix} 1 \\ 2 \end{bmatrix}) = 1+2=3$

· Find the image of
$$S = \{ [x] : x \in \mathbb{R} \}$$
. $f([x]) = 10$

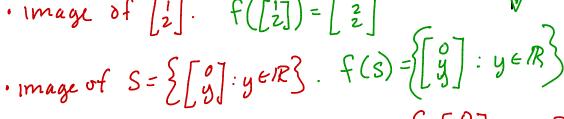


• Find the inverse image of 10.
$$S = \frac{10}{5} \left[\frac{x}{10 - x} \right] : x \in \mathbb{R}^{3}$$

• Find the inverse image of 10.
• Find the inverse image of 0.
$$S = \{ \begin{bmatrix} x \\ -x \end{bmatrix} : x \in \mathbb{R} \} = \{ x \in \mathbb{R} \} =$$

2.
$$f: \mathbb{R}^2 \to \mathbb{R}^3$$
 defined as $f\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x \\ y \\ y \end{bmatrix}$

· Image of
$$\begin{bmatrix} 1\\2 \end{bmatrix}$$
. $f(\begin{bmatrix} 1\\2 \end{bmatrix}) = \begin{bmatrix} 1\\2\\2 \end{bmatrix}$



$$\cdot R(f) = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x, y \in \mathbb{R} \right\} = \left\{ x \begin{bmatrix} z \\ z \end{bmatrix} + y \begin{bmatrix} z \\ z \end{bmatrix} : x, y \in \mathbb{R} \right\}$$

(R(F) is a plane determined by point dimension = 2. ((1,1,0) lus (0,0,1), (0,0,0)

UAF Linear
$$\mathcal{N}(f) = \{ [3] \}$$
 nullty = \mathbb{D} .