## THE LAST OF SECTION 2.3.3: VECTOR SPACES AND LINEAR SYSTEMS

1. Below is a homogeneous system of linear equations, the coefficient matrix A and the reduced echelon form of matrix A, called B. Answer the questions below.

$$\begin{cases} v + 2w + x + 2y + z = 0 \\ -v - 2w + x + y + z = 0 \\ 2v + 4w + y = 0 \\ x + y + z = 0 \end{cases} \qquad A = \begin{pmatrix} 1 & 2 & 1 & 2 & 1 \\ -1 & -2 & 1 & 1 & 1 \\ 2 & 4 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{pmatrix} \qquad B = \begin{pmatrix} 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- (a) What is the rank of A? 3
- (b) Find the set of solutions to the system and express the set in vector form.

$$\begin{array}{l} V+2\omega=0\\ Y=0 \end{array} \begin{pmatrix} V\\ \omega\\ Y\\ Z \end{pmatrix} = \begin{pmatrix} -2\omega\\ \omega\\ -2\\ 0\\ Z \end{pmatrix}, \quad Sol. = \left\{ \omega\begin{pmatrix} -2\\ 1\\ 0\\ 0\\ 0 \end{pmatrix} + Z\begin{pmatrix} 0\\ -1\\ 0\\ 1 \end{pmatrix} : \omega, Z \in \mathbb{R} \right\}$$

(c) Is the set of solutions a vector space? Why or why not?

Yes. Sol. set = Span 
$$\left\{ \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\} \right\}$$
 and span(s) is always a vector span.

(d) What is the *dimension* of the solution set? **2** 

Vectors a, and as span the soln set by definition They are linearly independent b/c they have non zero entries in different positions.

- 2. (Theorem 3.13) Let A be an  $m \times n$  matrix with rank r. What sort of number can r be? If A is the coefficient matrix of a homogeneous system, how many equations and how many unknowns are there? What can you say about the solution set?
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- · [A:0] corresponds to a system of m equations and n unknowns.
- The solution set of the system with matrix form [A:0] must have n-r free variables and there for be a subspace of dimension n-r.

- 3. (Corollary 3.14) Let A be an  $n \times n$  matrix. The following statements are equivalent:
  - (a) A has rank n
  - (b) (what can you say about the rows?) The nrows are linearly independent.
  - (c) (what can you say about the columns?) The n columns are linearly independent.
  - (d) (what can you say about SoLE's with A as a coefficient matrix?) There is always exactly 1 solution.
  - (e) (is A singular or nonsingular?) non Singular.

## Section 3.1.1

1. Let  $V = \mathbb{R}^3$  and  $W = \mathcal{P}_2$ . Give an intuitive argument that these are not really different vector

The place holders (a) (or 1st, 2rd, 3rd coord) feel exactly the same as place holders atbx+Cx2 (called constant, linear, and quadratic coefficients)

2. Definition: V, W vector spaces.

f: V = W is an isomorphism if Of is I-I and onto, Of f(v,+v) = f(v)+f(v) and 3 for all reP, V, eV f(rV) = rf(V)

We say V and W are isomorphic vector spaces.

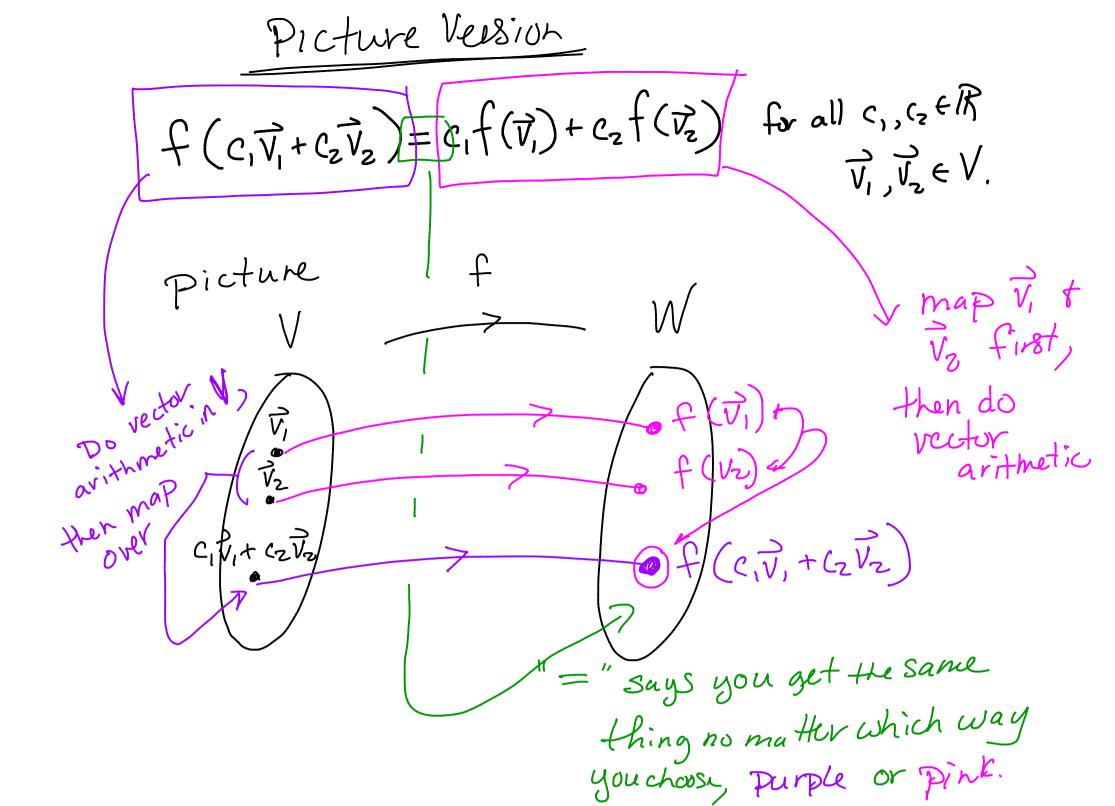
## 150morphic = effectively the same

Instead of showing  $f(\vec{v_1} + \vec{v_2}) = f(\vec{v_1}) + f(v_2)$  AND  $f(r\vec{v_1}) = rf(\vec{v_1})$ 

we can instead show

$$f\left(c_{1}\overrightarrow{V_{1}}+c_{2}\overrightarrow{V_{2}}\right)=c_{1}f\left(\overrightarrow{V_{1}}\right)+c_{2}f\left(\overrightarrow{V_{2}}\right) \quad \text{for all } c_{1},c_{2}\in\mathbb{R}$$

$$\overrightarrow{V_{1}},\overrightarrow{V_{2}}\in\mathbb{V}.$$



Example: Show  $V=R^3$  and  $W=P_2$  are isomorphic.

Pick a correspondence between V and W:  $f(\begin{bmatrix} a \\ b \end{bmatrix}) = a+b\times+cx^2$ .

Show f is I-I: Sppse  $f(\begin{bmatrix} a \\ b \end{bmatrix}) = f(\begin{bmatrix} a' \\ b' \end{bmatrix})$ . Then,  $a+b\times+cx^2 = a'+b'\times+c'\times^2$ .

So a=a',b=b',c=c'. So  $\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} a' \\ b' \end{bmatrix}$ . So f is I-I.

Show f is onto: Let  $a+b\times+cx^2$  be any polynomial in  $P_2$ .

Pick  $\vec{v} = \begin{pmatrix} a \\ b \end{pmatrix} \in R^3$ . Now  $f(\begin{bmatrix} b \\ b \end{pmatrix}) = a+b\times+cx^2$ . So f is onto.

Show f respects vector operations: Let  $c_1, c_2 \in R$  and  $\begin{bmatrix} a \\ b \end{bmatrix}, \begin{bmatrix} a' \\ b' \end{bmatrix} \in V=R^3$ .  $f(c_1 \begin{bmatrix} a \\ b \\ c' \end{bmatrix} + c_2 \begin{bmatrix} a' \\ b' \\ c' \end{bmatrix}) = f(\begin{bmatrix} c_1a+c_2a' \\ c_1b+c_2b' \\ c_1c+c_2c' \end{bmatrix}) = (c_1a+c_2a') + (c_1b+c_2b')\times + (gc+c_2c')\times^2$ These are equal.  $c_1f(\begin{bmatrix} a \\ b \\ c' \end{bmatrix}) + c_2f(\begin{bmatrix} a' \\ b' \\ c' \end{bmatrix}) - c_1(a+b\times+cx^2) + c_2(a+b\times+c'\times^2)$   $= (c_1a+c_2a') + (c_1b+c_2b')\times + (c_1c+c_2c')\times^2$