

ARM Introduction

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1. Basic Knowledge (1 points) Click to report a problem How many integer registers are there on the Raspberry Pi given that it's in 32-bit mode? Some of the registers are special and cannot be used as general registers. For example register r15 is the PC , r14 is the SP , and r13 is LR .
2. Overflow (1 points) Click to report a problem Given that the maximum value for a 16 bit unsigned number is 65535 uint16_t x = 65533; x += 3; The result in x is o A value is being computed: int seconds = age * 365 * 24 * 60 * 60; How might you detect that overflow is occurring? Vanswer is negative Vanswer grows smaller with increasing number Vanswer ends in a digit that is not zero answer contains the digit 6 .
3. Basic Instructions (1 points) Click to report a problem After each of the following assembler instruction show the values in the registers as 8 hex digits. (Do not put in 0x) For the pc put in the last two digits 000102b4: mov r0, #4 @r0=00000004 pc=000102b8 output pc=000102b8 pc=000102bc: add r0, #5 @r0=mmm pc=000102bc pc=000102c0 pc=000102c0 4. Parameters (1 points) Click to report a problem Given the following function prototype, identify what register is used for each parameter and return value

int f(int a, int b);

parameter a uses ro

parameter b uses [1] return value uses ro 5. calling functions (1 points) Click to report a problem In ARM assembler, the bl (branch and link) instruction is used to call a function and bx (branch and exchange) instruction are used to return. 000104c8: mov r0, #0 @r0=00000000 pc=000104 cc 000104cc: add r0, #4 @r0=0000004 pc=000104 do 000104d0: sub r0, #3 @r0=00000001 pc=000104 d4 000104d4: bl 000104f0 pc=000104 fo @1r=000104d8 pc=000104 e0 000104d8: bl 000104e0 @1r=000104dc {pc} @*** your code ends here*** 000104dc: pop pc=000104 e4 000104e0: mul r0, #3 @r0=00000003 1r 000104e4: bx pc=000104 dc r1, =0xFFAB 000104e8: ldr 000104ec: ldr r2, =16384000104f0: add r0, #1 @r0=00000001 000104f4: bx lr pc=000104 d8

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