

$$1 \text{ in} = 2.54 \text{ cm}$$

$$v_f = v_i + a \Delta t$$

$$1 \text{ ft} = 0.3048 \text{ m}$$

$$s_f = s_i + v_i \Delta t + a \Delta t^2 / 2$$

$$1 \text{ mile} = 1609.34 \text{ m}$$

$$v_f^2 = v_i^2 + 2 a \Delta s$$

$$1 \text{ kg} = 2.205 \text{ lb}$$

$$v = R \omega$$

$$1 \text{ hour} = 60 \text{ min} = 3600 \text{ s}$$

$$\omega_f = \omega_i + \alpha \Delta t$$

$$g = 9.80 \text{ m/s}^2$$

$$\theta_f = \theta_i + \omega_i \Delta t + \alpha \Delta t^2 / 2$$

$$360^\circ = 2 \pi \text{ rad}$$

$$\omega_f^2 = \omega_i^2 + 2 \alpha \Delta \theta$$

$$L = 2 \pi R \text{ (circumference of a circle)}$$

$$\omega = 2 \pi / T, \quad f = 1 / T$$

$$S = R^2 \pi \text{ (surface area of a circle)}$$

$$a_c = v^2 / R = \omega^2 R$$

$$\text{Quadratic equation: if } a x^2 + b x + c = 0, \text{ then } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}, \quad A = \sqrt{A_x^2 + A_y^2 + A_z^2}, \quad \tan \phi = A_y / A_x$$

$$\text{Cosine law: } c^2 = a^2 + b^2 - 2 a b \cos \theta, \text{ where } \theta \text{ is the angle between sides } a \text{ and } b.$$

Projectile motion (positive y up):

$$x_f = x_i + v_{xi} \Delta t, \quad y_f = y_i + v_{yi} \Delta t - g \Delta t^2 / 2; \quad v_{xf} = v_{xi}, \quad v_{yf} = v_{yi} - g \Delta t$$

$$\text{Relative motion: } \vec{v}_{AB} = \vec{v}_{AC} + \vec{v}_{CB}, \quad \vec{v}_{AB} = - \vec{v}_{BA}$$

$$\text{Newton's second law: } \vec{F}_{NET} = m \vec{a}, \quad \vec{F}_{NET} = \vec{F}_1 + \vec{F}_2 + \cdots + \vec{F}_N$$

$$\text{Weight in non-inertial reference frames: } w = mg(1 + a_y/g)$$

$$\text{Kinetic friction: } f_k = \mu_k N, \text{ opposite to the direction of motion}$$

$$\text{Static friction: } f_s^{(\max)} = \mu_s N, \text{ direction as necessary to prevent motion}$$

$$\text{Newton's third law: } \vec{F}_{A \rightarrow B} = - \vec{F}_{B \rightarrow A}.$$

Momentum: $\vec{p} = m \vec{v}$.

Impulse – momentum theorem: $\Delta \vec{p} = \vec{J}$, where $\vec{J} = \int_{t_i}^{t_f} \vec{F} dt$.

Conservation of momentum: $\vec{p}_i = \vec{p}_f$, where $\vec{p} = \sum_k \vec{p}_k = \sum_k m_k \vec{v}_k$.

Kinetic energy: $K = \frac{1}{2} m v^2 = \frac{1}{2m} p^2$.

Potential energy in gravitational field: $U_G = m g h$.

Potential energy of a spring: $U_S = \frac{1}{2} k (\Delta s)^2$. Hooke's law: $\vec{F} = -k \Delta \vec{s}$.

Conservation of mechanical energy: $K_i + U_i = K_f + U_f$.

Work: $W = \int \vec{F} d\vec{r}$. Work-kinetic energy theorem: $W = \Delta K$.

$W_{NC} = \Delta E_{MECH}; \Delta K + \Delta U + \Delta E_{TH} = W_{EXT}$.

Power: $P = \frac{dE_{SYS}}{dt}$; $P = \vec{F} \vec{v}$

Elastic collision, with mass m_2 initially at rest:

$$v_{1F} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i}, \quad v_{2F} = \frac{2 m_1}{m_1 + m_2} v_{1i}$$

Moment of inertia of a system of particles: $I = \sum_i m_i r_i^2$.

Parallel axis theorem: $I = I_{CM} + M d^2$

Moments of inertia of solid bodies through the center of mass:

Rod of mass M length L	$ML^2/12$	Hollow sphere of mass M, radius R	$2 MR^2 / 3$
Cylindrical hoop of mass M, radius R	MR^2	Solid sphere of mass M, radius R	$2 MR^2 / 5$
Solid cylinder of mass M, radius R	$MR^2 / 2$	Solid disk of mass M, radius R	$MR^2 / 2$

Kinetic energy of rotational motion: $K = \frac{1}{2} I \omega^2$

Angular momentum of a solid body: $\vec{L} = I \vec{\omega}, L = I \omega$

Angular momentum of a particle: $\vec{L} = \vec{r} \times \vec{p}, L = r p \sin\theta = m r v \sin\theta$

Torque: $\vec{\tau} = \vec{r} \times \vec{F}, \tau = r F \sin\theta, \tau = I \alpha$

Conservation of angular momentum: $\frac{d\vec{L}}{dt} = \vec{\tau}$, for isolated system $\vec{L} = \text{const.}$

Gravitational force: $= G \frac{m_1 m_2}{d^2}$, where $G = 6.67 * 10^{-11} \text{ N m}^2 / \text{kg}^2$

Gravitational potential energy (zero at infinity): $U = -G \frac{m_1 m_2}{d}$

Gravitational acceleration: $g = G \frac{M}{d^2}$

Orbiting velocity: $v_o = \sqrt{G M / d}$, Escape velocity: $v_e = \sqrt{2 G M / d}$

Kepler's third law: $\frac{d^3}{T^2} = \frac{G M}{4 \pi^2}$

Linear harmonic motion: $x(t) = A \cos(\omega t + \varphi_0), x_{MAX} = A$

$$v(t) = -A \omega \sin(\omega t + \varphi_0), v_{MAX} = A \omega$$

$$a(t) = -A \omega^2 \cos(\omega t + \varphi_0), a_{MAX} = A \omega^2$$

Period of a spring-box oscillator: $T_S = 2\pi \sqrt{m/k}$

Period of a pendulum: $T_P = 2\pi \sqrt{l/g}$

Angular frequency: $\omega = 2 \pi / T$

Mass of the Earth: $M_E = 5.98 * 10^{24} \text{ kg}$, Radius of the Earth: $R_E = 6370 \text{ km}$

Mass of the Sun: $M_S = 1.99 * 10^{30} \text{ kg}$, Radius of the Sun: $R_S = 6.96 * 10^5 \text{ km}$

Earth-Sun distance: $d_{ES} = 149.6 * 10^6 \text{ km}$