

Generalized Linear Latent and Mixed Model:

method, bayesian estimation, advantages, and
applications to educational data.

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Dedication

To Manuel, for being my friend and father.
To Margarita, Karina, Susan, and Marysu, for their relentless encouragement.
To Ana, for showing me the value of family, here in this moorland.
To both of you, as you are always in my mind.
And to all that knowingly or not, help me to get here.
I am lucky due to all of you.
I hope I make you all proud.

A Manuel, por ser mi amigo y mi padre.
A Margarita, Karina, Susan y Marysu, por su incansable aliento.
A Ana, por mostrarme el valor de la familia, aquí en este páramo.
A ustedes dos, que siempre las tengo en mente.
Y a todos los que sabiendolo o no, me ayudaron a llegar aquí.
Soy un suertudo gracias todos ustedes.
Espero llenarlos de orgullo.

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Abstract

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Abbreviations

ACF	Auto-correlation function.
BUGS	Bayesian Inference Using Gibbs Sampling.
CFA	Confirmatory Factor Analysis.
CLT	Central Limit Theorem.
CP	Centered Parametrization.
DAG	Directed Acyclic Graph.
DDM	Dual Dependence Models.
EFA	Exploratory Factor Analysis.
FOLV	First-order Latent Variable.
GLLAMM	Generalized Linear Latent and Mixed Model.
GLM	Generalized Linear Model.
GLMM	Generalized Linear Mixed Model.
HMC	Hamiltonian Monte Carlo.
ICC	Item Characteristic Curve.
IIF	Item Information Function.
iHMC	Interleaved Hamiltonian Monte Carlo.
JAGS	Just Another Gibbs Sampler.
IRT	Item Response Theory.
MCMC	Markov Chain Monte Carlo.
ML	Maximum Likelihood.
MSEM	Multilevel Structural Equation Model.
NCP	Non-centered Parametrization.
RMSE	Root Mean Squared Error.
SEM	Structural Equation Model.
SOLV	Second-order Latent Variable.
UVI	Unit Variance Identification.
VI	Variational Inference.

Chapter 1

Introduction

1.1 Preliminär considerations

Local independence is one of the key assumptions of Item Response Theory (IRT) models, and it is comprised of two parts: (i) local item independence and (ii) local individual independence [3, 27]. In the former case, the assumption entails that the individual's response to an item does not affect the probability of endorsing another item, after conditioning on the individual's ability. While in the case of the latter, the assumption considers that an individual's response to an item, is independent of another person's response to that same item [64].

The literature has shown that IRT models are not robust to the violation of local independence. The transgression of the assumption affects model parameter estimates, inflates measurement reliabilities and test information, and underestimates standard errors (see Yen [76], Chen and Thissen [10], and Jiao et al. [32]).

However, item response data arising from educational assessments often display several types of dependencies, violating the local item and/or individual independence, e.g. testlets, where items are constructed around a common stimulus [74]; the measurement of multiple latent traits within individuals [64]; cluster effects, where correlation among individuals results from the sampling and measurement mechanism used to gather the data [63]; among others. A good motivating example, that will permeate this research, is the reading comprehension sub-test, from the Peruvian public teaching career national assessment. The test is designed to measure three hierarchically nested sub-dimensions of reading comprehension: literal, inferential, and reflective abilities. Furthermore, the items are bundled together in testlets related to a common text or passage. Finally, multiple cluster effects are present, e.g. at the region, and district level, just to mention a few.

Recent studies have proposed IRT Dual Dependency Models (DDM) to deal with the testlets and individual clustering dependencies observed in the data [17, 16, 15, 32, 13, 14, 64, 8]. The majority of these representations have been developed under the Bayesian framework, and they are similar in parametrization to multilevel models. On the other hand, an almost independent line of research, the Generalized Linear Latent and Mixed Models (GLLAMM) [57, 59, 69, 60], have extended the capabilities of hierarchical models on the estimation of multiple latent traits at different hierarchical levels. These developments have been motivated mostly under the frequentist framework, and they are similar in parametrization to a Multilevel Structural Equation Model (MSEM).

While the initial sense is that both developments are independent of each other, follow-

ing their literature, one can easily notice that they share more than a resemblance. Both follow a multilevel/hierarchical multidimensional approach to account for the clustering of persons within samples and/or items within bundles (DDM), or the latent structures within the individuals (GLLAMM). However, it is important to point out that in some cases the model parametrization between the two developments differs in a way, that some of them appear to be useful only under their specific contexts. Fortunately, their integration under the Bayesian framework is not only trivial, but it can be motivated under either type of model.

The benefits of the integration revolve around two facts: (i) educational data often presents all of the aforementioned dependencies and more, as in the motivating example; and (ii) as it was hinted in the second paragraph, to reach appropriate conclusions from the parameter estimates, IRT models need to account for all of these dependencies. The latter is particularly important as, more often than not, a researcher is interested in producing inferences at the structural level of the model, i.e. how a different set of manifest variables explain the variability in the latent variables, or how the latent variables explain other manifest or latent variables, at different levels. As an example, one might be interested in finding evidence if the latent “abilities” of the teachers are explained by their initial educational conditions, i.e. if they were educated in an institute, university, or both. The main purpose of this would be to identify the type of teacher that might benefit more from the in-service training¹, offered by the national educational authorities, making the intervention cost-effective.

From the previous description, one can infer that the proposed IRT representation would be complex and highly dimensional. Moreover, as educational assessments are usually scored in a binary way (the individual either endorse or not the item), and because not all individuals are assessed by all items, the model will be estimated with sparse data. From the modeling perspective, neither of the previous points presents a challenge for the bayesian framework. However, it has long been recognized that complex parametrizations, that allow this powerful modeling schemes, introduce pathologies that make Markov Chain Monte Carlo methods (MCMC) face performance challenges [18, 19, 50, 51, 6], e.g. not achieving stationarity and/or not making a proper exploration of the posterior sampling space. This is highly relevant because, in order to make inferences about the posterior distribution of the parameters, the chains need to achieve a requirement highly related to the performance of the method: ergodicity [45], i.e. stationarity, convergence, and good mixing [44].

Throughout the bayesian IRT literature, one often finds that four solutions are offered to ensure the fulfillment of the previous requirements, and they can be classified into two broad groups: (i) solutions that involve changing the settings of the MCMC method, and (ii) solutions that involve readjusting the Bayesian model.

In the first category, we find two proposals: (a) increasing the number of iterations per chain, with large burn-in and thinning processes, and (b) designing model-specific MCMC algorithms. The easiest to implement and more prevalent in the literature is the former, e.g. Fujimoto [16] used chains with 60,000 iterations, where 15,000 were discarded and the remaining were thinned in jumps of 3; while Fujimoto [15] used 225,000 iterations, with burn-in of 30,000 and thinning with jumps of 15. Among the drawbacks of this solution are the large computational times; the user involvement in deciding the specific

¹Intervention designed with the purpose of potentiating specific abilities in teachers that are currently part of the public teaching career.

setting for the process, which could be different for different parameters in the same model; and finally, the lack of confidence that larger chain iterations actually produce a proper posterior investigation. On the other hand, several authors have developed high-tech MCMC algorithms that aim to optimize their performance within a particular class of models [51]. In these cases, the developers re-evaluate not only the use of the programming language, with the purpose of speeding and improving performance (e.g. Fujimoto [16]); but also the inclusion of ad-hoc model assumptions, like prior conjugacy² for specific parameters or highly regularizing priors (see next paragraph), to mention a few. Examples of this solutions are in staple software developments like Mplus [47] or Stata [58]. It is clear from the previous that this solution is not accessible to all researchers, either because of the lack of programming skills, or the restrictive cost of access involved in acquiring the software. But more importantly, these solutions are not always applicable to a wider framework of similar models [51].

In the second category, we also find two proposed solutions: (a) re-write the model in an alternative parametrization, and (b) encode prior information through the prior distributions, i.e. use regularizing priors. On both solutions, the purpose is to ensure the identification of the parameters within the model, which helps to stabilize the MCMC procedure [22]. An example of the former is Fujimoto [16], who decomposed the items' discriminatory parameters into overall and specific item discriminations. For the latter, Fujimoto [17] used informative priors also for the items' discrimination parameters.

More often than not, researchers use two or more of the aforementioned solutions to reach an acceptable performance in the chains. However, as point out by Betancourt and Girolami [6], even the most simple hierarchical models present formidable pathologies, that no simple correction can be performed to visit the posterior distribution properly. This is true no matter the rotation/rescaling of the parameter, or the amount of data. In this context, several authors [18, 19, 50, 51, 6] showed that prior information can be included in the model, not only through the prior distributions, but also by encoding it in the model itself, changing the posterior sampling geometries, i.e. removing the dependence of the parameters on other sampled parameters, therefore favoring the performance of MCMC chains.

Given all of the above, the present research will focus on showing how easy it is to account for all of the dependencies that educational data often display, under the GLLAMM framework. Furthermore, given that only the literature related to gaussian hierarchical models have shown the benefits of changing the posterior sampling geometries, through the use of the non-centered parameterization [18, 19, 50, 51, 6], it seems sensible to provide a similar assessment for nonlinear hierarchical models, and in particular, the ones with latent stochastic processes like IRT [51]. Finally, the research will apply the newfound knowledge to data coming from a large Teacher's standardized educational assessments from Peru.

1.2 Objectives

As mentioned in the previous section, the present research has a three-fold purpose:

1. Motivate the Bayesian GLLAMM for binary outcomes [57, 59, 69, 60]. The rep-

²when the prior and posterior distribution belong to the same parametric family.

resentation will emphasize the modeling of multiple hierarchical latent structures and testlets. This, in turn, will effectively blur the division between the GLLAMM framework and IRT models.

2. Empirically evaluate the benefits of changing the posterior sampling geometry, in the context of the Bayesian GLLAMM for binary outcomes. The emphasis here will be on comparing the centered and non-centered parametrizations [18, 19] in terms of performance of the chains, the parameter's recovery capacity, the retrodictive accuracy, and the ability of the model to produce appropriate inferences.
3. Apply the model and its parametrization to a real data setting. Here the emphasis will be to assess the conclusions arrived from the application of the model, and what they could imply for the educational authorities.

Given the aforementioned goals, the researcher believes the master's thesis contributes to the literature in two aspects:

1. In a theoretical and methodological sense, as the research is focused on describing a model that effectively controls for the multiple dependencies usually observed in educational data sets; and
2. In a more practical sense, as the study will provide empirical evidence if changing the sampling posterior geometries could (could not) benefit the performance of MCMC methods and therefore the inferences, under IRT models.

Finally, it is important to mention, that the computational implementation of the method will be developed in **Stan** [72] and **R** [54, 71].

1.3 Organization

Chapter 2 will motivate the GLLAMM for dichotomous outcomes, and define its components. Chapter 3 will describe the Bayesian framework, its benefits and shortcomings. Furthermore, it will outline the evidence behind the change in posterior sampling geometries, and the computational implementation of the model. Chapter 4 will show the results of an empirical simulation study designed to assess the benefits of the re-parametrization, proposed in the previous chapter. Chapter 5 will describe the instruments, the data collection process, and scales under analysis, for a large standardized educational assessment. In addition, the chapter will show the conclusions achieved by the application of the model in the said data. Finally, Chapter 6, will discuss the conclusion for the research, and it will outline the path of future research topics that can be derived from the present effort.

Chapter 2

The GLLAMM for dichotomous outcomes

The Generalized Linear Latent and Mixed Model (GLLAMM) is a framework that unifies a wide range of latent variable models. Developed by Rabe-Hesketh and colleagues [57, 59, 58, 69, 60], the method was motivated by the need of a Multilevel Structural Equation Model (MSEM) that accommodated for unbalanced data, noncontinuous responses and cross-level effects among latent variables. The authors focused its development mainly from the frequentist perspective, however, they offered a general guidance on implementing the model under the bayesian framework (see Skrondal and Rabe-Hesketh [69]).

2.1 Model motivation

Consider a large standardized assessment composed of three sub-test designed to evaluate the reading comprehension, mathematical reasoning, and pedagogical knowledge of teachers; where each sub-test has several dichotomously scored items.

Focusing on the first sub-test, the items were designed to measure only one of the three hierarchically nested sub-dimensions of reading comprehension: literal, inferential, and reflective abilities. Furthermore, it is assumed the three sub-dimensions are all that is needed to measure the reading comprehension ability, effectively making this scale, the highest level latent variable in the model, similar to a hierarchical Confirmatory Factor Analysis (CFA). Finally, the items were bundled in groups of five to a common text or passage, i.e. testlets, that provided the stimulus over which the individual is assessed. Figure 2.1 shows the path diagram of the hypothesized dimensional structure, for the hierarchical cross-classified IRT model corresponding with the instrument. The figure represents the responses of one person on 12 items.

With the purpose of providing an easier motivation of the model, we will not consider yet the cluster effects; however, later in the presentation we will show how easy it is to introduce them in the model. Just for future reference, under this example, one expects to observe clustering effects, because individuals from different regions did not have the same educational opportunities, effectively causing differences among them at a regional level.

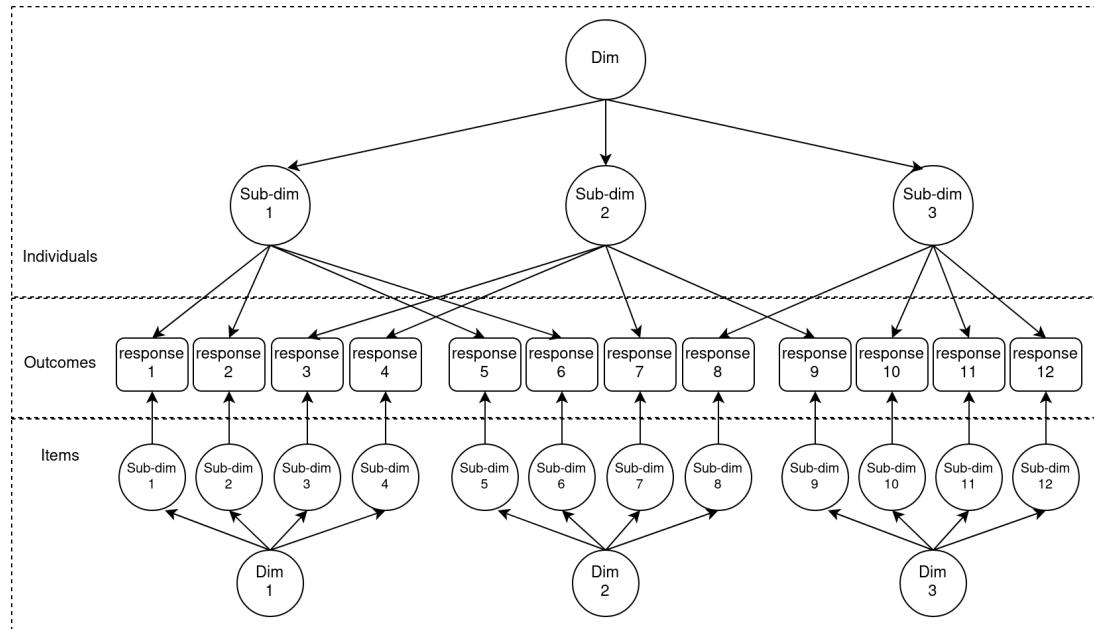


Figure 2.1: Path diagram of the dimensional structure for a hierarchical cross-classified IRT model. Squares represent dichotomous manifest variables, and circles represent latent variables. The figure is based on a reduced set of items, while the errors and scales of the latent variables are not represented. Different sub-dimensions at the individuals block represent the literal, inferential and reflective abilities, while at the items blocks represent the items' difficulties. The dimensions at the individuals block represent the reading comprehension ability, while at the items block represent the multiple testlets.

2.2 Model definition

Following Rabe-Hesketh et al. [57, 59], we continue defining the GLLAMM in two parts: (i) the response model, and (ii) the latent structure.

In case the reader is interested in outcomes different than the dichotomous case, refer to Rabe-Hesketh et al. [57, 59, 58], Skrondal and Rabe-Hesketh [69], and Rabe-Hesketh et al. [60].

2.2.1 Response model

Conditional to all regression parameters β , loadings Λ , latent variables Θ , and structural parameters Ψ and Γ , i.e. $\Omega = \{\beta, \Lambda, \Theta, \Psi, \Gamma\}$; and the “stacked” vector of covariates for the first level (\mathbf{X}) and the structural part (\mathbf{W}); the response model can be represented by a Generalized Linear Model (GLM) [49, 43] with a distributional and a systematic part. The latter composed of a linear predictor and a link function.

For the distributional part, the outcome y_{jkd} is modeled at the first level (level-1) by a Bernoulli probability mass function $f(\cdot)$, in the following form:

$$f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \Omega) = \pi_{jkd}^n (1 - \pi_{jkd})^{1-n} \quad (2.1)$$

where individuals are indexed by $j = 1, \dots, J$, with J representing the total number of individuals in the sample; the items are indexed by k , with d being the dimension the

items are set to measure; and n denotes the endorsement of the item in the Bernoulli trial. On the other hand, for the systematic part, the probability of endorsing the item π_{jkd} is linked to a linear predictor v_{jkd} through an inverse-link function $h(\cdot)$, in the following form:

$$P(y_{jkd} = 1 \mid \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \pi_{jkd} = h(\tau_k + v_{jkd}) \quad (2.2)$$

where τ_k is k 'th item threshold, assumed to be zero for the binary case [57], while the inverse-link function can be defined in three ways:

$$h(x) = \begin{cases} \exp(x)[1 + \exp(x)]^{-1} \\ \Phi(x) \\ \exp(-\exp(x)) \end{cases} \quad (2.3)$$

corresponding to the logistic, standard normal $\Phi(x)$, and Gumbel (extreme value type I) cumulative distributions, respectively. It is usual to report the last in terms of link functions $g(\cdot) = h^{-1}(\cdot)$. In that case, these corresponds to the well known logit, probit and complementary log-log, respectively. Finally, the linear predictor is defined by:

$$v_{jkd} = \sum_{p=1}^P x_{jp} \beta_p + \sum_{m=2}^{M+1} \sum_{k=1}^{K_{(m)}} \eta_k^{(m)} \alpha_k^{(m)} + \sum_{l=2}^{L+1} \sum_{d=1}^{D_{(l)}} \theta_{jd}^{(l)} \lambda_d^{(l)} \quad (2.4)$$

where β_p denotes regression parameter for the x_{jp} explanatory variable with $p = 1, \dots, P$, and P denoting the total number of level-1 response explanatory variables, e.g. time to answer the item, the number of alternatives, among others. $\eta_k^{(m)}$ is the k th item latent dimension at level m with loading $\alpha_k^{(m)}$, where $k = 1, \dots, K_{(m)}$, $K_{(m)}$ denotes the number of dimensions at level $m = 2, \dots, M + 1$, and M represents the number of levels in the items block. It is important to keep in mind, the model also contemplates that not all the item are set to measure all the individual's dimension; however, we decided to not to show such information in the form of an index in equation (2.4), to avoid making the notation heavier. Nevertheless, equation (2.5) is more clear on this detail, as the design block matrices specification show. $\theta_{jd}^{(l)}$ denotes the individual's d th latent dimension at level l with loading $\lambda_d^{(l)}$, where $d = 1, \dots, D_{(l)}$, $D_{(l)}$ represents the number of dimensions at level $l = 2, \dots, L + 1$, and L denotes the number of levels in the individuals block. Notice that since the responses are modeled at the first level, the hierarchies for the latent dimensions need to start from the second level onward.

Additionally, equation (2.4) can be re-written in matrix form in the following way:

$$v_{jkd} = \mathbf{X}_j \boldsymbol{\beta} + \sum_{m=2}^{M+1} \boldsymbol{\eta}^{(m)} \boldsymbol{\alpha}^{(m)} \mathbf{A}_j^{(m)} + \sum_{l=2}^{L+1} \boldsymbol{\theta}_j^{(l)} \boldsymbol{\lambda}^{(l)} \mathbf{B}_j^{(l)} \quad (2.5)$$

where \mathbf{X}_j represents the individual's design matrix of explanatory variables that maps the parameter vector $\boldsymbol{\beta}$ to the linear predictor; and $\mathbf{X} = [\mathbf{X}_1^T, \dots, \mathbf{X}_J^T]^T$ the “stacked” design matrix of \mathbf{X}_j . Moreover, $\boldsymbol{\eta}^{(m)} = [\eta_1^{(m)}, \dots, \eta_{K_{(m)}}^{(m)}]^T$, and $\boldsymbol{\alpha}^{(m)} = [\alpha_1^{(m)}, \dots, \alpha_{K_{(m)}}^{(m)}]^T$ are the vectors of the item's latent dimensions with corresponding loadings at level m , mapped by a block matrix $\mathbf{A}_j^{(m)}$. Similarly, $\boldsymbol{\theta}_j^{(l)} = [\theta_{j1}^{(l)}, \dots, \theta_{jD_{(l)}}^{(l)}]^T$, and $\boldsymbol{\lambda}^{(l)} = [\lambda_1^{(l)}, \dots, \lambda_{D_{(l)}}^{(l)}]^T$ are

the vectors of the individual's latent dimensions with corresponding loadings at level l , mapped by a block matrix $\mathbf{B}_j^{(l)}$.

Finally, in order to have a more concise representation of the model, we can re-express equation (2.5) in the following way:

$$\begin{aligned} v_{jkd} &= \mathbf{X}_j \boldsymbol{\beta} + \boldsymbol{\eta} \boldsymbol{\alpha} \mathbf{A}_j + \boldsymbol{\theta} \boldsymbol{\lambda} \mathbf{B}_j \\ &= \mathbf{X}_j \boldsymbol{\beta} + \boldsymbol{\Theta} \boldsymbol{\Lambda} \mathbf{H}_j \end{aligned} \quad (2.6)$$

where $\boldsymbol{\alpha} = [\boldsymbol{\alpha}^{(2)T}, \dots, \boldsymbol{\alpha}^{(M+1)T}]^T$ and $\boldsymbol{\lambda} = [\boldsymbol{\lambda}^{(1)T}, \dots, \boldsymbol{\lambda}^{(L+1)T}]^T$ represent all the loadings corresponding to the items and individuals dimensions at all levels; whereas $\boldsymbol{\eta} = [\boldsymbol{\eta}^{(2)T}, \dots, \boldsymbol{\eta}^{(M+1)T}]^T$ and $\boldsymbol{\theta} = [\boldsymbol{\theta}^{(2)T}, \dots, \boldsymbol{\theta}^{(L+1)T}]^T$ represent the latent dimensions and sub-dimensions of items and individuals at all levels, respectively. Consequently, \mathbf{A}_j and \mathbf{B}_j are their mapping block matrices. Furthermore, $\boldsymbol{\Lambda} = [\boldsymbol{\alpha}^T, \boldsymbol{\lambda}^T]^T$ and $\boldsymbol{\Theta} = [\boldsymbol{\eta}^T, \boldsymbol{\theta}^T]^T$ to represent the “stacked” vector of loadings, and dimensions, respectively; and \mathbf{H}_j its mapping block matrix.

Considering figure 2.1 as reference, we would have an empty level-1 covariates matrix \mathbf{X}_j , as we do not have any response explanatory variable ($P = 0$). Moreover, we have $M = 2$ levels at the items block, with $K_2 = 12$ and $K_3 = 3$. Consequently, $\boldsymbol{\eta}^{(2)} = [\eta_1^{(2)}, \dots, \eta_{12}^{(2)}]^T$ and $\boldsymbol{\eta}^{(3)} = [\eta_1^{(3)}, \eta_2^{(3)}, \eta_3^{(3)}]^T$ denotes the items' difficulties and testlet effects, respectively. As stated in previous paragraphs, to avoid the use of even heavier notation, the item's indexes do not reflect that not all the items are set to measure all the individual's dimensions; however, the reader needs to keep that in mind. On the other hand, we have $L = 2$ levels in the individuals block, with $D_2 = 3$ and $D_3 = 1$. Therefore, $\boldsymbol{\theta}^{(2)} = [\theta_1^{(2)}, \theta_2^{(2)}, \theta_3^{(2)}]^T$ which denotes the literal, inferential and reflective abilities; whereas $\boldsymbol{\theta}^{(3)} = \theta_1^{(3)}$ represent the reading comprehension latent variable. Furthermore, since we are trying to express an IRT model, it makes sense to put some restrictions to the parameter set. In this case, we establish $\boldsymbol{\alpha}^{(2)} = -\boldsymbol{\lambda}^{(2)}$ with $\boldsymbol{\lambda}^{(2)} = [\lambda_1^{(2)}, \dots, \lambda_{12}^{(2)}]^T$ representing the item's discriminatory parameter, where $\boldsymbol{\lambda}^{(2)} > \mathbf{0}$. This resemble to a multidimensional generalization of the linear predictor observed in the archetypical Rasch [62], or 2PL [39] models, i.e. $\lambda_d^{(2)}(\theta_{jd}^{(2)} - \eta_k^{(2)})$, where $|\lambda_d^{(2)}| = |\alpha_k^{(2)}|$ denotes the discriminatory power of item k , $\eta_k^{(2)}$ its difficulty, and $\theta_{jd}^{(2)}$ the ability of the individual at dimension d . In addition, $\boldsymbol{\lambda}^{(3)} = [\lambda_1^{(3)}, \lambda_2^{(3)}, \lambda_3^{(3)}]^T$ would represent the loadings from reading comprehension to their respective sub-dimensions; whereas $\boldsymbol{\alpha}^{(3)} = [\alpha_1^{(3)}, \alpha_2^{(3)}, \alpha_3^{(3)}]^T$ would represent the item-specific loadings from the testlets, usually set as $[1, 1, 1]^T$, indicating they explain directly the items difficulties at the lower level.

Finally, notice that through the use of \mathbf{A}_j and \mathbf{B}_j design block matrices, and more generally with \mathbf{H}_j , the model departs from the traditional multivariate framework for formulating structural models, i.e. a wide data format; and adopts a univariate approach, i.e. a long data format. The former stores the subject's repeated outcomes in a single row, with multiple response vectors and explanatory variables appended column-wise to the outcome data. The later stores the subject's repeated outcomes in a single “stacked” response vector with as many rows as there are repeated measurements, and explanatory variables appended column-wise to the outcome data, distinguished from each other, by a design block matrix.

Cluster effects

Considering the previous, we can see that modeling individual clustering just involves the addition of more random effects, to the linear predictor defined in equation (2.4):

$$\begin{aligned} v_{jkdc} &= v_{jkd} + \sum_{c=1}^C \delta_c \\ &= v_{jkd} + \boldsymbol{\delta Z}_j \end{aligned} \quad (2.7)$$

where $c = 1, \dots, C$, which denotes the number of clusters, v_{jkd} is defined as in equation (2.4), and \mathbf{Z}_j is a design block matrix.

2.2.2 Latent structure

The structural model for the latent variables is represented in the following form:

$$\boldsymbol{\Theta} = \boldsymbol{\Psi} \boldsymbol{\Theta} + \boldsymbol{\Gamma} \mathbf{W} + \boldsymbol{\zeta} \quad (2.8)$$

where $S = K + D$, $K = \sum_m K_m$, and $D = \sum_l D_l$. Furthermore, $\boldsymbol{\Psi}$ and $\boldsymbol{\Gamma}$ are parameter matrices that map the relationship between the latent variables $\boldsymbol{\Theta}$, and the “stacked” vector of covariates \mathbf{W} , respectively; while $\boldsymbol{\zeta}$ is a vector of errors or disturbances. It is important to indicate that \mathbf{W} considers a different set of covariates from \mathbf{X} , as we hypothesize they explain the variability in the latent variables at different levels.

Notice equation (2.8) is the generalization of a single-level Structural Equation Models (SEM) to a multilevel setting, however, the main difference in the GLLAMM representation is that the latent variables may vary at different levels.

Additionally, considering that $\boldsymbol{\Theta}$ has no feedback effects, is permuted, and sorted according to the levels of interest, then $\boldsymbol{\Psi}$ will be a strictly upper triangular matrix. In this regard, (i) the absence of feedback loops imply the method deals with non-recursive models, i.e. none of the latent variables are specified as both causes and effects of each other [36]; and (ii) the strictly upper triangular structure reveals the GLLAMM does not allow latent variables to be regressed on lower level latent or observed variables, implying the method deals with reflective measurement¹[5]. For a more detailed explanation on the topic see Edwards and Bagozzi [12].

However, notice that because in the IRT framework $\boldsymbol{\eta}$ and $\boldsymbol{\theta}$ should be orthogonal to each other by design, we can further decompose equation (2.8) in the following form:

$$\boldsymbol{\eta} = \boldsymbol{\Psi}_\eta \boldsymbol{\eta} + \boldsymbol{\Gamma}_\eta \mathbf{W}_\eta + \boldsymbol{\zeta}_\eta \quad (2.9)$$

$$\boldsymbol{\theta} = \boldsymbol{\Psi}_\theta \boldsymbol{\theta} + \boldsymbol{\Gamma}_\theta \mathbf{W}_\theta + \boldsymbol{\zeta}_\theta \quad (2.10)$$

where $\boldsymbol{\Psi}_\eta$, $\boldsymbol{\Psi}_\theta$, $\boldsymbol{\Gamma}_\eta$, and $\boldsymbol{\Gamma}_\theta$ are the dimension-specific parameter matrices that map the relationship between the corresponding latent variables $\boldsymbol{\eta}$ and $\boldsymbol{\theta}$; with $\boldsymbol{\zeta}_\eta$ and $\boldsymbol{\zeta}_\theta$ being the dimension-specific vector of disturbances. Finally, the matrices \mathbf{W}_η and \mathbf{W}_θ would be the dimension-specific covariates.

¹A latent variable is considered reflective when it is thought to be the cause of the lower level latent or manifest variables.

Considering figure 2.1 as reference, we did not specified any structural relationships Ψ ; nor declare any additional covariates \mathbf{W} . However, chapter 4 and 5 will show an implementation where we hypothesized a set of covariates explain the variability on some of the latent variables.

2.3 Model assumptions

Following Skrondal and Rabe-Hesketh [69], the framework has two main assumptions: (i) complete latent space, and (ii) local or conditional independence.

(M1) Complete latent space. The latent space is considered complete if all the latent variables, that we hypothesize affect the outcomes, are considered in the model [26]. In the GLLAMM representation, these would be all latent variables Θ at levels $l > 1$ and $m > 1$, as the outcomes are modeled at the first level.

(M2) Local Independence, also known as conditional independence, is defined in the following form:

$$f(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \prod_{j=1}^J \prod_{d=1}^D \prod_{k=1}^K f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \quad (2.11)$$

where $f(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega})$ denotes the level-1 conditional likelihood, and \mathbf{y} the vector of all responses at the first level.

Notice the approach also assumes local or conditional independence, as their non-hierarchical IRT model counterparts. Nevertheless, its independence is conditional on all the latent dimensions and covariates, at different hierarchical levels; effectively modeling all the observed dependencies.

Finally, it is important to point out that equation (2.11) results from the union of two more specific assumptions, local item and individual independence [64, 3, 27]:

(a) **Local item independence**, which entails the individual's response to an item does not affect the probability of endorsing another item, after conditioning on the individual's ability. This is expressed in the following mathematical form:

$$f(y_{j..} = 1 | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \prod_{d=1}^D \prod_{k=1}^K f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \quad (2.12)$$

where $y_{j..} = [y_{j1}, \dots, y_{jKD}]$ is the vector of all items for individual j and, as previously defined, $K = \sum_m K_m$ and $D = \sum_l D_l$.

(b) **Local individual independence**, which entails that an individual's response to an item is independent of another person's response to that same item. The assumption is expressed in the following form:

$$f(y_{.kd} = 1 | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \prod_{j=1}^J f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \quad (2.13)$$

where $y_{.kd} = [y_{1kd}, \dots, y_{Jkd}]$ is the vector of all individuals endorsing item k from dimension d .

Chapter 3

Bayesian estimation

The practical use the GLLAMM developed in chapter 2 requires the estimation of all of the items and individuals' dimensions, loadings, regression and structural parameters. These can be obtained within two frameworks: the frequentist and bayesian.

The current chapter center its attention on describing the bayesian estimation procedure, using the Markov Chain Monte Carlo method (MCMC). For a full development of GLLAMM under the frequentist framework refer to Rabe-Hesketh and colleagues [57, 59, 69, 60].

3.1 Benefits and shortcomings

3.1.1 Why Bayesian?

The reasons on why bayesian statistics is attractive to perform the parameters' estimation of any model, and especially for the GLLAMM developed in chapter 2, are:

1. It is built on a simulation-based estimation method, therefore, it can handle all kinds of priors and data-generating processes [14]. This is especially useful with highly complex and over-parameterized models, where other methods are unfeasible or work poorly [2, 35].
2. While the likelihood functions are used to define the posterior sampling distributions, they can also be used in a generative way. The likelihood for the data, and priors for the parameters, form the basis to produce samples from the posterior distribution. However, they can also be used to simulate observations, allowing us to test the ability of the method/data to recover the parameters of interest [44].
3. The bayesian estimates are at least as good as its frequentist counterparts [2, 75, 30]. This is true when the method uses uninformative 'flat' priors. However, because the procedure allow us to integrate prior knowledge about the parameters, beyond the observed responses, it can produce results even in scenarios where the Maximum Likelihood methods (ML) have issues of non-convergence or improper estimation [69, 14, 44]. Examples of such are:
 - (a) when we have small sample sizes.

- (b) when individuals have null scores or aberrant response patterns [27, 1]. The latter happens when examinees answer some relatively difficult and discriminating items correctly, while answering some of the easiest incorrectly.
- (c) when parameters need to be confined to a permitted space, e.g. the estimation of positive unique factors variances [42].
- (d) when we need to estimate parameters under sparse data, where the asymptotic theory is unlikely to hold [14];

3.1.2 Are you sure there's nothing wrong?

Off course the bayesian framework has shortcomings, among them:

1. It exposes the user to somewhat-arbitrary decisions about the running of the chains, in order to ensure a proper performance, e.g. how many iterates does the chain need to achieve precise estimates?, what is the right size for the burn-in and warm-up phases?, how should the thinning procedure be performed, if any?, should we follow the same procedure for all parameters of interest?, among others [69].
2. The user can include all type of information through the priors distributions, making their elicitation convenient for manipulation.
3. Multiple options are available to evaluate the performance of the method, and most of them are visual, making it hard to assess if a proper posterior investigation have been made [23]. More specifically, the user has multiple options to assess if the chain achieves the three requirements of a good performance: stationarity, convergence, and good mixing [44].
4. The procedure makes it hard to discover parameters' lack of identification [69]. Inadequate mixing of the chain could lead us to think unidentified parameters have been estimated with precision, when in fact what we have are 'flat' posteriors [33].
5. Oftentimes the posterior sampling geometry of the model makes it hard to find proper solutions for the parameter space, no matter the rotation/rescaling of the parameter, or the amount of data [6]. This is especially true in complex hierarchical models.
6. The greater the complexity of the model, the harder it is to communicate/share the implementation with other scientist. This is especially true, when researcher re-parameterize the model to solve the previous shortcoming [44].
7. The procedure usually requires more time to achieve a proper solution, compared to the classical methods. This is especially true in models with high complexity [73, 65].

Although some of the previous shortcomings have made the Bayesian procedure a "controversial" implementation, most of them already have acceptable solutions.

For the first point, a popular approach is to use a large number of iterates, burn-in and thinning processes. This is mostly applicable under the Metropolis-Hastings and Gibbs sampling algorithms. However, recent solutions, like the Hamiltonian Monte Carlo

(HMC) [6], is less reliant on selecting these features, as it implements a different sampling mechanism (see section 3.3.1).

On the second point, the literature has indicated that priors can be used to reflect subjective beliefs¹. However, as McElreath [44] indicated, because the priors can be considered a part of the model assumptions, they can be chosen, evaluated, and revised as any other component of the model, through the use of prior predictive simulations and/or sensitivity analysis (see section 3.3.5).

About the third point, the literature on bayesian analysis acknowledge that the visual assessment of stationarity and convergence is easier, and these procedures usually has additional support from statistics like `Rhat` [22]. On the contrary, a visual evaluation of ‘good’ mixing remains as a hard task. Recent approaches have taken a more proactive stance on the latter, seeking to increase the possibility of a well mixed chain by changing the posterior sampling geometry of the model [50, 51, 6, 44] (see section 3.4).

On the fourth point, the most common solution is to use regularizing priors, i.e. priors that are more ‘skeptical’ of wider parameter spaces [44]. However, it is important to mention, there are scenarios where one achieves poor parameter estimates, even in the presence of ‘enough’ data and regularizing priors, but this shortcoming is also applicable to the classical estimation procedures, e.g. the estimation of the variance parameters in random effects models [69].

About the fifth point, as it was mentioned in previous paragraphs, a recent approach to solve the issue is to change the posterior sampling geometry of the model. This means to re-parameterize the model in a way that removes the dependence of the parameters on other sampled parameters; or even, produce sample mechanisms located in a continuous between a centered (CP) and non-centered parametrization (NCP), e.g. Interleaved HMC (iHMC) and/or Variational Inference (VI) [18, 19, 50, 51, 6, 25] (see section 3.4).

Finally, the sixth and seventh points can be considered the ‘price’ a scientist has to pay, to be able to fit models that conforms better with the observed data generating processes. Although, recent developments are striving to improve upon reducing the latter, i.e. the required running time.

3.2 Bayesian GLLAMM for dichotomous outcomes

3.2.1 Posterior distribution

Denoting \mathbf{Y} as the observed data and $\boldsymbol{\Omega} = \{\boldsymbol{\beta}, \boldsymbol{\Lambda}, \boldsymbol{\Theta}, \boldsymbol{\Psi}, \boldsymbol{\Gamma}\}$, i.e. all the parameters declared in section 2.2.1 and 2.2.2, the posterior distribution is obtained using the Bayes theorem, in the following way:

$$P(\boldsymbol{\Omega} | \mathbf{Y}) = \frac{P(\mathbf{Y} | \boldsymbol{\Omega}) P(\boldsymbol{\Omega})}{\int P(\mathbf{Y} | \boldsymbol{\Omega}) P(\boldsymbol{\Omega}) d\boldsymbol{\Omega}} \quad (3.1)$$

this is possible since the Bayesian approach makes no distinction between latent variables and parameters. All of them are considered random quantities [69]. Furthermore, since inference only requires representing the likelihood of the data $P(\mathbf{Y} | \boldsymbol{\Omega})$ and the prior

¹see McElreath [44] (Chapter 2, pp. 36), Rethinking section “Prior, prior pants on fire”, for an interesting stance contrary to this statement.

distribution $P(\Omega)$; and because the denominator is just a (hard to calculate) constant, the posterior can be determined up to a normalizing constant, without loss of generality:

$$P(\Omega | \mathbf{Y}) \propto P(\mathbf{Y} | \Omega) P(\Omega) \quad (3.2)$$

3.2.2 Prior distributions

Similar to Patz and Junker [52], we use an independent distributional structure for the joint priors of the parameters. Therefore, at the highest level of the GLLAMM we have:

$$\begin{aligned} P(\Omega) &= P(\beta, \Lambda, \Theta, \Psi, \Gamma) \\ &= P(\beta) P(\Lambda) P(\Theta) P(\Psi) P(\Gamma) \\ &= P(\beta) [P(\alpha) P(\lambda)] [P(\eta) P(\theta)] [P(\Psi_\eta) P(\Psi_\theta)] [P(\Gamma_\eta) P(\Gamma_\theta)] \end{aligned} \quad (3.3)$$

However, giving the hierarchical and cross-classified structure of the model, the lower level priors will also depend on further parameters², e.g. variances and covariances of the latent variables. These are known as *hyper-parameters*, and their prior distributions as *hyper-priors*. Because of the previous, we are not going to detail their lower level representation, as they are highly dependent on the specifics of the model.

Section 3.3.5 details the process of prior predictive investigation for prior elicitation. On the other hand, chapter 4 and 5 will show the elicitation of priors, in the context of a simulated and real data set, respectively.

3.2.3 Likelihood

Following Rabe-Hesketh et al. [57], the likelihood function is build in a recursive way. First, we replace the structural model (2.8) into the linear predictor (2.6):

$$v_{jkd} = \mathbf{X}_j \beta + (\mathbf{I} - \Psi)^{-1} [\Gamma \mathbf{W} + \zeta] \Lambda \mathbf{H}_j \quad (3.4)$$

Second, the linear predictor and inverse-link function (2.3) are used to construct the systematic part of the response (2.2), i.e. its expected value. Here we use a logit link for pedagogical purposes:

$$\pi_{jkd} = \frac{\exp(\tau_k + v_{jkd})}{1 + \exp(\tau_k + v_{jkd})} = \frac{\exp(v_{jkd})}{1 + \exp(v_{jkd})} \quad (3.5)$$

Third, the expected value is used in the distributional part (2.1), in the following form:

$$f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \Omega) = \pi_{jkd}^n (1 - \pi_{jkd})^{1-n} \quad (3.6)$$

Fourth, considering assumptions (M1) and (M2) described in section 2.3, we produce the level-1 likelihood:

$$f(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \Omega) = \prod_{j=1}^J \prod_{d=1}^D \prod_{k=1}^K f(y_{jkd} = 1 | \mathbf{X}, \mathbf{W}, \Omega) \quad (3.7)$$

²Because of this sequential model specification, it is said the priors also have a “hierarchical” structure.

Fifth, we define the marginal likelihood at levels l and m , conditional on the latent variables at levels $l + 1$ and $m + 1$, in the following form:

$$f_{(m)}^{(l)}(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \int \left[\prod f_{(m-1)}^{(l-1)}(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \right] P(\boldsymbol{\Theta}_{(m)}^{(l)}) d\boldsymbol{\Theta}_{(m)}^{(l)} \quad (3.8)$$

where the product inside the brackets is over all units in level $(l - 1)$ and $(m - 1)$, the first level is defined as in equation (3.7), and $P(\boldsymbol{\Theta}_{(m)}^{(l)})$ are the prior distributions for the latent variables at level l and m , with $\boldsymbol{\Theta}_{(m)}^{(l)} = [\boldsymbol{\eta}^{(m)}, \boldsymbol{\theta}^{(l)}]$. Finally, we define the likelihood as:

$$\mathcal{L}(\mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \prod_{m=2}^{M+1} \prod_{l=2}^{L+1} f_{(m)}^{(l)}(\mathbf{y} = \mathbf{1} | \mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \quad (3.9)$$

and the log-likelihood as:

$$\ell(\mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) = \log \mathcal{L}(\mathbf{X}, \mathbf{W}, \boldsymbol{\Omega}) \quad (3.10)$$

3.2.4 Model identification

As indicated by Rabe-Hesketh et al. [57], in order to fully specify the model and provide a scale for the latent variables, we have to make assumptions for either the distribution of the disturbances $\boldsymbol{\zeta}$, or the distribution of one or more of the latent variables $\boldsymbol{\Theta}$. On the other hand, as point out by Fujimoto [15] and several others authors, we could also set restrictions for one or more of the loadings in $\boldsymbol{\Lambda}$. The last is more prevalent in frequentist software packages like Winsteps [38].

Furthermore, as it is hinted by equation (3.9), it is assumed the latent variables at different levels are independent from each other, whereas latent variables at the same level may present dependency. Therefore, when the assumption is coherent under the context of a model, we will presume the latent variables at the same level have a multivariate normal distribution with a mean and covariance structure determined by equations (2.9) and (2.10). In the case of the covariance matrices, these are determined by the covariance of the specific disturbances $\boldsymbol{\zeta}$.

Chapter 4 and 5 will show the model identification strategy in the context of a simulated and real data set, respectively.

3.3 Computational implementation

3.3.1 Hamiltonian Monte Carlo

For years the state-of-the-art platform for Bayesian statistical modeling have been the BUGS³ project, with its WinBUGS and OpenBUGS implementations [41, 40]. However, a more recent participant JAGS⁴ [53] has gain traction, due to its cross-platform capabilities. In any case, both platforms are not that different from each other. Both use two of the most popular and successful algorithms for performing MCMC: the Metropolis-Hastings [45, 28] and Gibbs Sampling [24] algorithms.

³Bayesian inference Using Gibbs Sampling

⁴Just Another Gibbs Sampler

In general lines, the Metropolis algorithm follows a two-step procedure: (i) it produces a new proposal for a parameter’s value, and (ii) it evaluates the proposal against the current, accepting the new value if it is more likely under the posterior distribution. On the other hand, the Gibbs sampling uses a similar procedure, but it gains efficiency by exploiting the knowledge behind the target distribution. The latter improvement catapulted the Gibbs sampler into the workhorse of high dimensional Bayesian computing.

However, both methods remain as highly random procedures, and because of it, they still have important limitations. The most important of them all is that they do not yield independent and identically distributed samples (*iid*). This in turn means, the exploration of the posterior is made through a series of (sometimes highly dependent) values, causing the MCMC chain to converge to the target distribution only in the long run, i.e. when the number of iterations approach infinity ($t \rightarrow \infty$) [22]. It is important to mention that while the non-fulfillment of *iid* samples is a critic of all simulation based method, in no algorithms is more relevant than in the previous two.

In this context, multiple approaches have been proposed to ensure an appropriate exploration of the posterior distribution, even in the face of non-*iid* samples, and often-times, the aforementioned software packages use them in conjunction. The first consist on improving the sampling mechanism by using a Hybrid MCMC method. A good example of this is the “Metropolis-within-Gibbs” algorithm [46]. The second consist on setting a warm-up phase, that seeks to adapt the proposal distributions to favor the exploration of the posterior. Finally, the third consist on defining the number of iterates, burn-in and thinning processes in a way, that it reduces the serial dependencies in the samples.

Nevertheless, the aforementioned solutions, while useful, do not solve all issues related to the MCMC chain’s performance, as these can remain biased in subtle ways, that are more harder to identify [44]. Therefore, researchers have decided instead to propose new improved algorithms.

Is in this context were the Hamiltonian Monte Carlo or Hybrid Monte Carlo (HMC) was proposed by Duane et al. [11]. While the full representation of method is out of the scope of this research, we can still make a high-level description of its process, with purpose of point out its benefits and shortcomings.

Assuming we have continuous distributions and the partial derivatives of the log-density function (the gradient) exists, the method iterates between the updating of two vector spaces of a “particle” [48, 44]. First, it samples new values for the particle’s momentum vector, independent of the current values of its position vector, i.e. it gives the particle a random “flick”. In the second iteration, using Hamiltonian dynamics, a Metropolis update is performed to propose a new position vector for the particle. In this sense, one can say the HMC runs a small physics simulation, where the position of the particle denotes the current parameter values in the Markov chain, the momentum denotes the proposed path to a new set of values, and the log-posterior provides the “friction-less” surface over which the particle moves, where the gradient defines its curvature [44].

In principle, because HMC produce “more informed” proposals, it will accept all of them. In practice, however, HMC uses a rejection procedure that inform us when the method was not able to maintain the “energy” of the system, producing a bad numeric approximation, i.e. a divergent transition (see section 3.4 for an example). For more on the background theory on Hamiltonian Dynamics and specifics about the HMC algorithm refer to Neal [48], and Betancourt and Girolami [6].

All of this just tells us that HMC is a highly complex algorithm. However, as McEl-

reath [44] pointed out, the Gibbs strategy got its improvement over the Metropolis-Hastings by being less random, not more. And in that sense, HMC pushes this principle to a greater length, but manages to improve the efficiency of the MCMC procedure. This is especially true in cases where ordinary Metropolis or Gibbs sampling cannot make a proper exploration of the parameter space, e.g. with highly correlated parameters or with models with hundreds or thousands of parameters, like complex hierarchical models. Moreover, as HCM is more efficient, it requires less number of iterations to make a proper posterior investigation [44, 22]

Off course, this comes with a cost. The methods is more computationally intensive than the previous. However, because of the efficiency improvement and the need of less number of iterations, the method requires less computer time in total, even when each individual sample needs more.

3.3.2 Where can I find this magical software?

Stan [72] is the software package that will provide us with the machinery of HMC. Furthermore, the results produced from the software will be analyzed with **R** [54, 71], and its integration packages.

3.3.3 What about burn-in and thinning?

Since HMC uses a different approach and produces more informative proposals, setting specific burn-in and thinning processes are no longer necessary.

However, the method does require to perform a warm-up procedure to adapt sampling, and to tune in two parameters of the algorithm: the number of steps (`leapfrogs`), and the `step size` [72]. These parameters are used to make a discrete approximation of the momentum vector, i.e. the path of the particle [48, 6].

Notice, this phase is similar to a procedure performed in JAGS, where the proposal distribution gets “tuned-up” to improve the posterior investigation. However, the similarities end there. The warm-up samples in HMC are not representative of the target posterior distribution, no matter how long the iterations continue [44]. Finally, after the warm-up is finished, and assuming the adaption was successful, the method will sample directly from the target distribution.

In the current research, we will use a total 3,000 effective iterations, coming from 3 chains of 2,000 iterations each, where 1,000 of them will be spend on warm-up, and no thinning procedure will be performed. Notice this departs (by far) from most of the literature on bayesian IRT models, e.g. Fujimoto [16] used chains with 60,000 iterations, where 15,000 were discarded and the remaining were thinned in jumps of 3; while Fujimoto [15] used 225,000 iterations, with burn-in of 30,000 and thinning with jumps of 15; just to mention a few.

3.3.4 Initial starts

Since the method requires starting values for the parameters, the author decided to allow the software to sample these from the priors defined in the model.

3.3.5 Prior elicitation

Multiple studies have pointed out the benefits of using mildly informative priors to reduce over-fitting, while allowing the model to learn regular features of the data, e.g. McElreath [44], Gelman et al. [21] and Jaynes [31]. In contrast, the literature has emphasized the unintended consequences on the posterior, resulting from using highly uninformative priors, e.g. Seaman et al. [66], and Gelman [20].

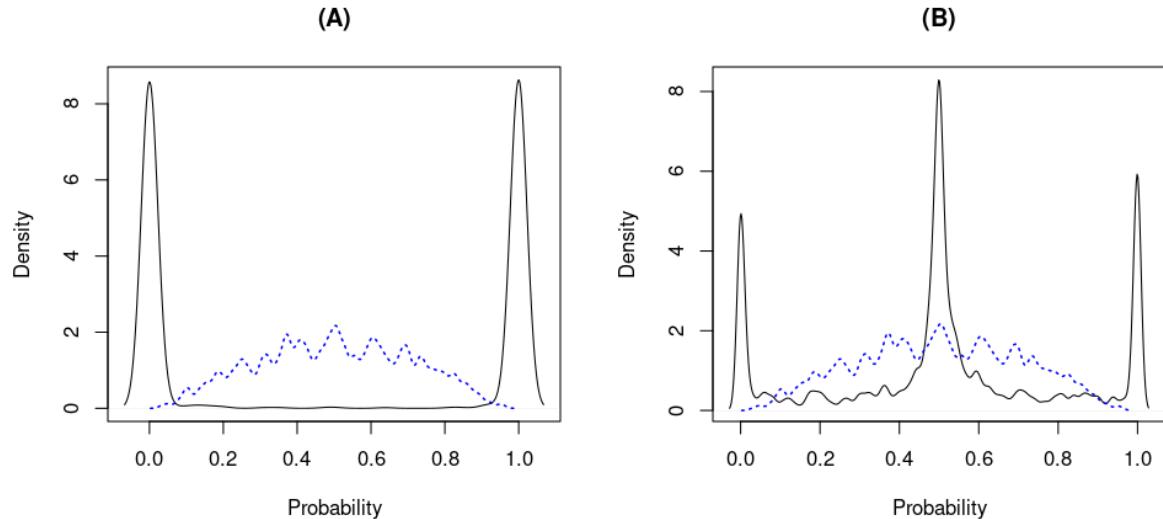


Figure 3.1: Prior predictive simulation. Examples of uninformative and mildly informative priors. The panels show the density for the probability of a binary outcome under: (A) uninformative prior on equation (3.11) and mildly informative prior on equation (3.13); and (B) uninformative prior on equation (3.12) and mildly informative prior on equation (3.14). Uninformative (black continuous lines), and mildly informative (blue discontinuous lines).

In our case, as stated in section 3.1.2, because priors can be considered a part of the model assumptions, they can be chosen, evaluated, and revised as any other component of the model [44]. In that sense, we motivate the use of mildly informative priors through a simple illustration. Consider an example similar to one outlined by Seaman et al. [66] and McElreath [44], where a simple latent variable model is defined as follows:

$$\begin{aligned} \theta &\sim N(0, 100) \\ \text{logit}(p) &= \theta \end{aligned} \tag{3.11}$$

where θ denotes a latent dimension, and p denotes the probability of a binary outcome, defined by the logit-link function. For pedagogical purposes, we did not declare the distribution of the response, as we wanted to assess what the prior implied for its expected value/probability.

Panel (A) from figure 3.1 shows that the uninformative prior in equation (3.11) forces an unintended assumption onto the expected value of the outcome (black continuous line). The model is now highly ‘skeptical’ of probabilities that are not zero or one. This means

that we are effectively using highly regularizing priors, but opposite on how they are supposed to be used, i.e. to avoid visiting non-likely parameter spaces.

The scenario gets equally bad with the presence of hyper-parameters, and even less extreme assumptions. Consider the following example:

$$\begin{aligned} v &\sim \log N(0, 3) \\ \theta &\sim N(0, v) \\ \text{logit}(p) &= \theta \end{aligned} \tag{3.12}$$

where v is distributed as a log-normal distribution ($v > 0$). Panel (B) from figure 3.1 shows that the uninformative priors in equation (3.12) forces another unintended assumption on the expected value of the outcome (black solid line). The model is now highly ‘skeptical’ of probabilities that are not $p = \{0, 0.5, 1\}$. Again is like using regularizing priors but “in reverse”.

Luckily, these extreme priors can be overcome with enough data. However, that does not discard the need to address the issue, as much of the time, researchers do not have a clear definition of how much is “enough” data.

In that sense, mildly informative priors can help alleviate the concern. Mildly/weakly informative priors are prior distributions that are not supplying any controversial information, are consistent with the likelihood, and are strong enough to pull the data away from inappropriate inferences [22]. To illustrate its use, consider a mildly informative prior on equation (3.11):

$$\begin{aligned} \theta &\sim N(0, 1) \\ \text{logit}(p) &= \theta \end{aligned} \tag{3.13}$$

Notice now θ has a prior that is consistent with common IRT applications, and its distribution does not force the expected value of the outcome to be as extreme, as in the uninformative case. Panel (A) from figure 3.1 shows the prior probability of the outcome can now be in the full $[0, 1]$ range, where extreme probability values are assumed less likely (blue discontinuous line vs black solid line).

Similarly, in the presence of hyper-parameters we can set mildly informative priors in the following form:

$$\begin{aligned} v &\sim \log N(0, 0.5) \\ \theta &\sim N(0, v) \\ \text{logit}(p) &= \theta \end{aligned} \tag{3.14}$$

where the blue discontinuous line on panel (B) of figure 3.1 shows its transformation into the expected value of the outcome.

One can imagine the procedure of prior elicitation will get more complicated with a larger number of parameter and hyper-parameters. Therefore, the use of prior predictive simulation will be a tool of high value for complex models, as in our current implementation. See section 4.4.2 for an example on the use of prior predictive investigation, under simulated data.

3.4 To center or not to center

As pointed out by Betancourt and Girolami [6], even the most simple hierarchical models present formidable pathologies, that no simple correction can be performed to visit the posterior distribution properly. This is true no matter the rotation/rescaling of the parameter, or the amount of data.

A great example of this is what McElreath [44] dubbed the Devil's funnel (depicted in figure 3.3), where the author shows that you do not need a complex model to start observing these issues. Consider the following joint distribution:

$$\begin{aligned} v &\sim N(0, 3) \\ \theta &\sim N(0, \exp(v)) \end{aligned} \tag{3.15}$$

where v is the *hyper-parameter* of θ , and θ is dependent on the samples of v . The latter is what the literature dubbed as the centered parametrization (CP).

This joint distribution might seem familiar, as bayesian hierarchical model practitioners often use it to ensure the standard deviation remains into the permitted parameter space ($\sigma \geq 0$). Similar types of requirements permeate IRT models. Moreover, it seems that any MCMC procedure would not have any issues exploring the joint distribution of these parameters, as they are normally distributed and there are only two of them, but we would be wrong.

For pedagogical purposes, the example was run without data, as the author wanted to emphasize the pathologies are present even before we feed the data to our model. However, its easy to extrapolate that these issues will remain present when data is available. The reader can find the `stan` and `jags` implementations for these examples in Appendix B.1.1. The `stan` implementation replicates the example stated by Betancourt and Girolami [6] and McElreath [44].

Figure 3.2 show the chains resulting from implementing the model on equation (3.15), through HMC (`stan`). As one can see from the figure, the joint posterior distribution is not explored properly. The chains show no sign of achieving ergodicity [45], i.e. they do not show stationarity or convergence (top panels), nor a good mixing (middle and bottom panels). This is further supported by the `Rhat`, and effective sample sizes estimates `n_eff` [22]. The `Rhat` for all parameters did not properly approach the threshold of one (most of them were even above 1.05), indicating the chains did not achieve convergence: the between-chain variability was larger than the within-chain variability. Furthermore, the effective samples sizes were 34 and 293 for v and θ , respectively; indicating the values of the chains remained highly correlated (see bottom panels). This is striking, as one expects effective sample sizes closer to the effective number of iterations (3,000, coming from 3 chains with 1,000 samples each, after warm-up).

3.4.1 Wasn't HMC the solution to this?

HMC is a powerful MCMC algorithm, and its benefits stand the test of other scenarios, as detailed by multiple authors [44, 22]. However, the issue with this example goes a little bit farther than what the algorithm can actually overcome, and this is true also for the Metropolis and Gibbs sampling algorithms. Nevertheless, we will see HMC still manages to be efficient within the constraints of the problem.

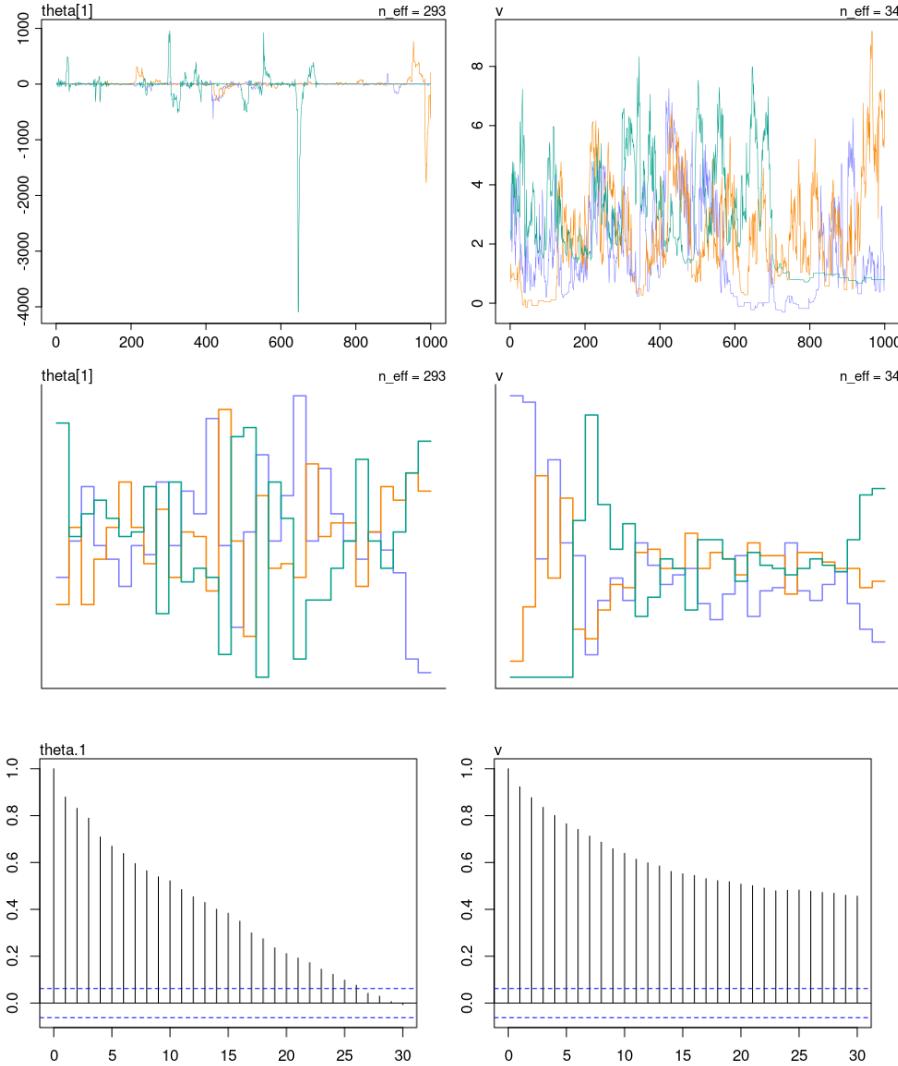


Figure 3.2: The Devil’s funnel. Centered Parametrization. (Top) Trace plots for the iterations on three chains. (Middle) Trank plots for the same data. (Bottom) Auto-correlation Functions (ACF) plot for the iterations.

Figure 3.3 shows the posterior sampling geometry of the model in equation (3.15), for the HMC algorithm (`stan`, left) and Metropolis/Gibbs sampler (`jags`, right), respectively.

The first thing to notice is the complexity of the joint posterior geometry, with a steep funnel shape as the values of v gets smaller and smaller. This makes sense, as the exponential of larger negative values, force the standard deviation of θ to be narrower and narrower around its mean (zero).

The second thing to notice is that HMC (left panel) still manages to successfully explore the steep parameter space of v and θ . This can be observed through the blue points that are scattered in most of the geometry, albeit some parts are less visited (area where $\theta > 0$). This does not happen under the Gibbs sampler. In fact, `jags` did not manage to escape the narrow funnel shape, no matter the number of iterations used in the adaptation, burn-in and sampling procedures⁵ (panel B). Moreover, as shown in figure

⁵`stan` used 3 chains with 1,000 iterations for adaptation, and 1,000 iterations for sampling. `jags`

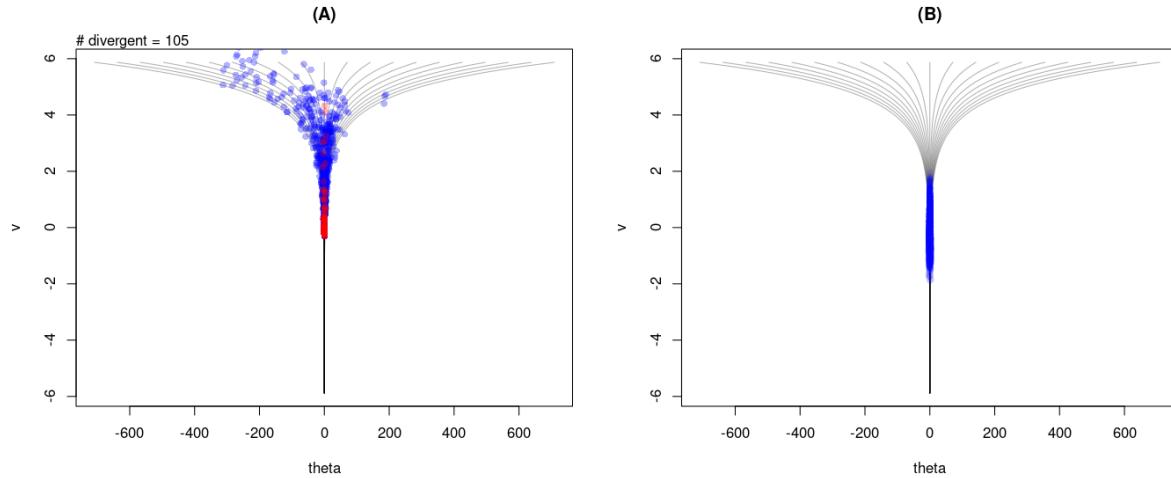


Figure 3.3: Posterior sampling geometry. Centered Parametrization. (A) HMC exploration, blue points are accepted samples, red points denote divergent transitions. (B) Metropolis/Gibbs exploration, blue points are samples.

A.1 (appendix), the traceplots indicate the chains are “healthy”, ignoring the clear lack of exploration of the joint distribution.

Finally, although HMC did not fully explore the joint distribution, at least the method let us know which parts of it did not manage to visit appropriately (see red points indicating divergent transitions). The last is important, because HMC gives us the opportunity to identify where can we improve our parametrization, something that is not available on Metropolis or Gibbs.

3.4.2 So, how can we solve this?

There are three proposed solutions for the previously explained issue: (i) adapt the HMC warm-up, (ii) use regularizing priors, and (iii) change the posterior sampling geometry. This section will explain briefly the first, outline the geometrical perspective of the second (as its results are well studied); and advocate for the benefits of the third, in the context of IRT models.

Adapt warm-up

As explained in previous sections, the HMC requires a warm-up phase to adapt the parameters’ sampling. In it, two meta-parameters are “tuned-in” (`leapfrogs` and `step size`); while a rejection criterion (`adapt_delta`) remains constant. As we recall, HMC follows a rejection procedure that inform us when the method was not able to maintain the “energy” of the system, producing a divergent transition; and in the core of this procedure is the rejection criterion.

used 3 chains with 5,000 iterations for adaptation, 5,000 iterations for burn-in, and 5,000 iterations for sampling.

As it is pointed out by McElreath [44], divergent transitions do not damage directly our posterior distribution approximation, but they do hurt indirectly, as the region where divergent transitions occur is hard to properly explore.

Therefore, to reduce the impact of the divergent transitions, the user can increase the criterion's threshold above the default values (`adapt_delta= 0.95`), resulting in slower but more confident exploration of the posterior distribution.

Finally, in regards to this solution, two important point should be kept in mind. First, the solution is method specific, as HMC is the only algorithm that uses this parameter. And second, the solution forces the method to make a slower posterior investigation, therefore requiring the user to set longer chains to achieve ergodicity.

Regularizing priors

As previously mentioned, several authors have shown the benefits of using weakly regularizing priors in diverse types of models [44, 21, 31]. However, few of them have described how the use of regularizing priors work from a geometrical perspective. Consider the use of a regularizing prior on equation (3.15):

$$\begin{aligned} v &\sim N(0, 1) \\ \theta &\sim N(0, \exp(v)) \end{aligned} \tag{3.16}$$

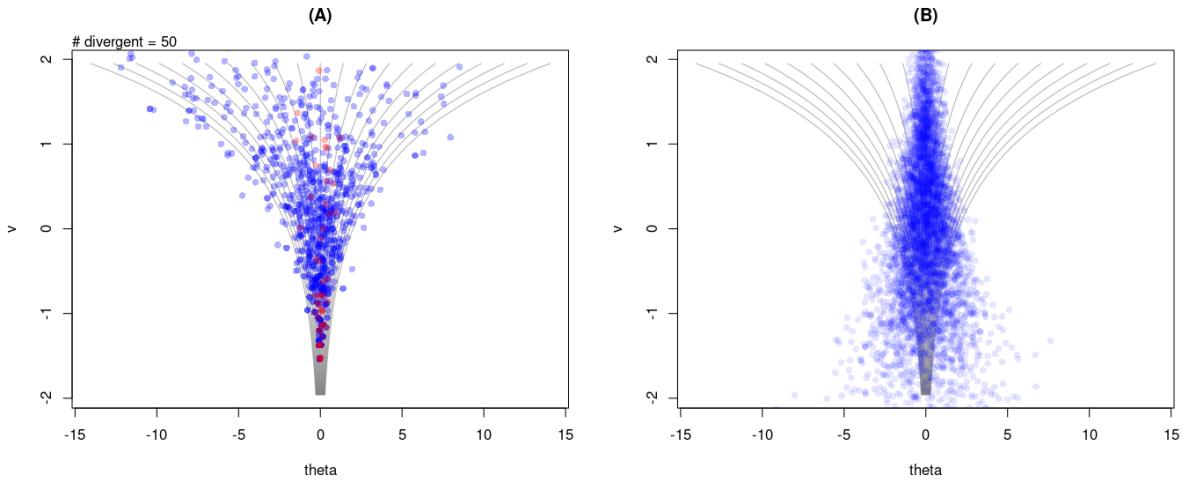


Figure 3.4: Posterior sampling geometry. Centered Parametrization with mildly informative priors. (A) HMC exploration, blue points are accepted samples, red points denote divergent transitions. (B) Metropolis/Gibbs exploration, blue points are samples.

Figure 3.4 shows the joint posterior sampling geometry of equation (3.16), for the HMC algorithm (`stan`, left) and Metropolis/Gibbs sampler (`jags`, right), respectively.

The first thing to notice from the figure is that the geometry available for exploration seems more broad. However, what is actually happening is that by adding information about v , we are “zooming” into the posterior geometry observed in figure 3.3, according to the range of the new priors. This further benefits the exploration of the posterior, as

extreme ranges don't have to be visited from the start, e.g. the narrow funnel in the range $[-6, -2]$ of v from figure 3.3.

The second thing one can notice is that HMC does not “lose time” exploring sections of the posterior distribution that are not needed. Surprisingly in contrast, the Gibbs sampler explore non-useful sections and leaves the useful ones unexplored. Again, this is true no matter the number of iterations used in the adaptation, burn-in and sampling procedures⁶. Moreover, the chains in figure A.2 (appendix) seem to be ergodic, ignoring the clear lack of exploration of the joint distribution, as in the previous example.

Third, we see that using regularizing priors reduced the number of `stan`'s divergent transitions from 150 (in the previous example) to 50. Although we still observe them in the steepest part of the geometry. Such information is not provided by `jags`.

Finally, we notice a mild improvement on the trace, tranks and ACF plots in figure 3.5, compared to figure 3.2 in the previous example.

Non-centered parametrization

It would seem that, increasing the regularizing power of the priors is the answer to get rid of the sampling issues raised by a complex posterior sampling geometry. However, there is a limit on the information a prior can contain, without imposing strong assumptions about the parameters (see section 3.3.5 for an example). Furthermore, sometimes researchers want the information on the data dominates the posterior parameter space. In those cases, imposing even mildly informative priors is a solution that is out of the picture.

In this context, Betancourt and Girolami [6] indicated that prior information can be included in the model, not only through the prior distributions, but also by encoding it in the model itself, taking advantage of the hierarchical structure explicitly, i.e. change the posterior sampling geometries.

Following Papaspiliopoulos et al. [50, 51], and Betancourt and Girolami [6], under the Bayesian framework, a change in geometry consist on a model re-parameterization that seeks to remove the dependence of parameters on other sampled parameters, therefore favoring the performance of the MCMC chains. This is what the literature has dubbed as the non-centered parametrization (NCP).

In light of previous examples, changing the posterior sampling geometry means to modify equation (3.15) in the following way:

$$\begin{aligned} v &\sim N(0, 3) \\ z &\sim N(0, 1) \\ \theta &= \exp(v) z \end{aligned} \tag{3.17}$$

notice v has the original assumed variability, but now θ is defined in a way, that is no longer sample dependent on v , i.e. we no longer sample θ directly but z , and transform it back.

The motivation for this re-parametrization have seeds in the calculation of the standard score (z-score). Notice that if $\theta \sim N(\mu_\theta, \sigma_\theta)$ where $\sigma_\theta = \exp(v)$, then $(\theta - \mu_\theta)/\sigma_\theta = z$ and $z \sim N(0, 1)$. Using this process in reverse, we notice $\theta = \mu_\theta + \sigma_\theta z = \exp(v) z$ when $\mu_\theta = 0$, then $\theta \sim N(0, \exp(v))$. As the previous, there are transformation that can be

⁶the author used the same settings as in the previous example.

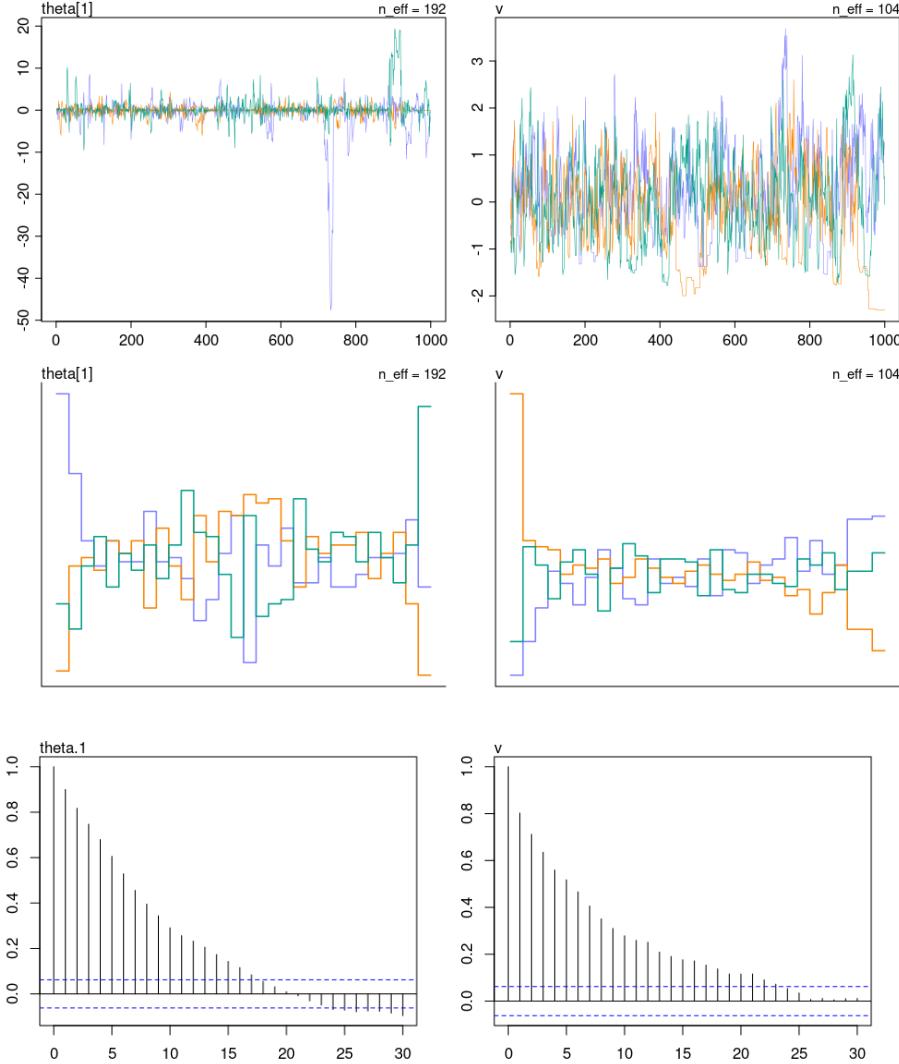


Figure 3.5: The Devil’s funnel. Centered Parametrization with mildly informative priors. (Top) Trace plots for the iterations on three chains. (Middle) Trank plots for the same data. (Bottom) Auto-correlation Functions (ACF) plot for the iterations.

done for other distributions, and they can even be extended to the multivariate normal case, through the use of the Cholesky decomposition [44].

Figure 3.6 show the posterior sampling geometry for the HMC and Gibbs sampler, under the re-parametrization. Notice both algorithms manage to explore more successfully the posterior distribution, although the HMC does it a bit better on the extremes of v . Moreover, the HMC shows no divergent transitions, meaning the posterior is “visited” without issues. Evidence of the latter can be as seen on figure 3.7, where the chains show clear signs of stationarity, convergence and good mixing.

Finally, Papaspiliopoulos et al. [51] indicated that the success of the NCP strategy is largely dependent on the specifics of the model, i.e. neither CP or NCP is more “optimal” than the other. The author pointed out that the natural CP showed better performance when conditional conjugacy was present, i.e. when the posterior distribution belonged to the same parametric family as the likelihood or prior distribution. On the other hand, the

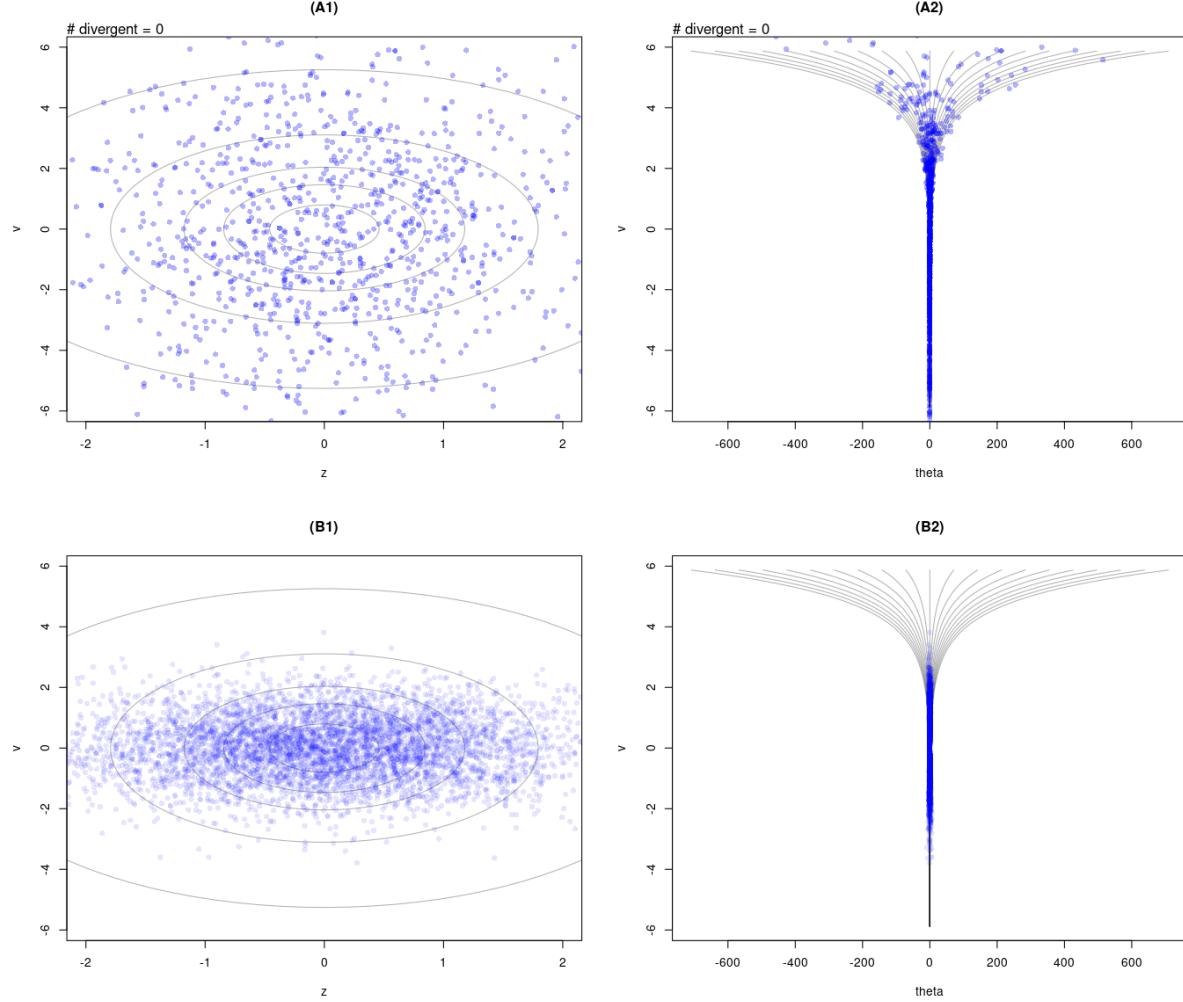


Figure 3.6: Posterior sampling geometry. Non-Centered Parametrization. (A1, B1) geometry defined by the independent parameters v and z . (A2, B2) Original sampling geometry defined by v and θ . (A1, A2) HMC algorithm (`stan`). (B1, B2) Metropolis/Gibbs sampler (`jags`). Blue points are accepted samples. Red points denote divergent transitions.

NCP worked as its complement, excelling when the previous requirement was not present. Therefore, due to this complementary behavior, it makes sense that recent advancements on the topic are focused on producing sample mechanisms located in a continuous between CP and NCP, as greater performance improvements can be obtained by leveraging on both, e.g. Interleaved HMC (iHMC) or Variational Inference (VI) [18, 19, 50, 51, 25].

Chapter 4 and 5 will show the application of NCP in the context of an IRT model.

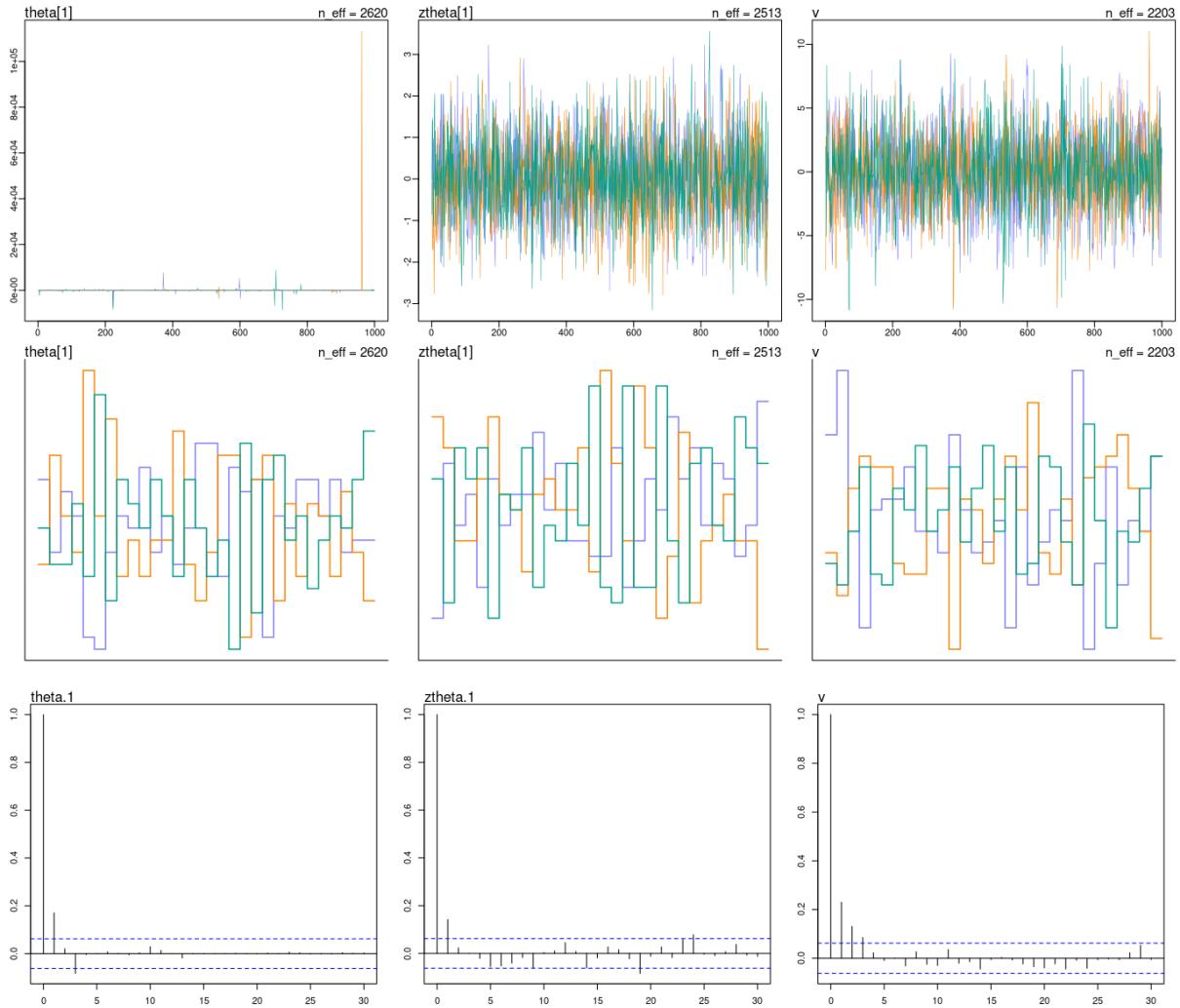


Figure 3.7: The Devil's funnel. Non-centered Parametrization. (Top) Trace plots for the iterations on three chains. (Middle) Rank plots for the same data. (Bottom) Auto-correlation Functions (ACF) plots for the iterations.

Chapter 4

Simulation Study

4.1 Objectives

The simulation study was conducted to assess three attributes of the bayesian implementation of the GLLAMM for dichotomous outcomes:

1. **Performance.** The study assessed the performance of the MCMC chains in terms of achieving ergodicity, under the centered (CP) and non-centered parametrization (NCP), respectively.
2. **Recovery capacity.** The study evaluated the capacity to recover the parameters of interest, e.g. regression parameters, latent variables and loadings. However, it centered its focus on the recovery of the regression parameters, as they are highly relevant for making appropriate inferences at the individual level.
3. **Retrodictive accuracy.** The study appraised the capacity of the implementation to retrodict the data of interest, according to a set of aggregating dimensions.

4.2 Conditions

The full factorial design of the conditions available to investigate the previous three objectives is large (48 experimental conditions). The factorial design would consider 2 levels related to the value of the rejection criteria (default `adapt_delta= 0.95` or `adapt_delta= 0.99`), 2 levels related to the use/no use of regularizing priors, 2 levels for the parametrization of the model (CP and NCP), 3 simulated sample sizes of interest (500, 250, and 100), and 2 levels related to the models of interest.

However, because bayesian practitioners usually use the CP in conjunction with other solutions to reach an acceptable MCMC performance (and the practice is fairly extended in the literature), we believe a large set of the aforementioned conditions can be trimmed out in favor of a more realistic comparison. Therefore, we decided to use a fully crossed design with $3 \times 2 \times 2 = 12$ experimental conditions, where only the sample sizes, parametrization, and models of interest were manipulated. On the other hand, we decided to maintain the remaining two experimental factors on levels close to realistic implementations, i.e. we use weakly regularizing priors with `adapt_delta= 0.99`. The former substantively justified in sections 3.3.5 and 3.4.2.

Consequently, the author used three different samples sizes to generate the data under analysis: 500, 250, and 100. The literature on IRT models present several implementations with samples sizes above 250, however, few present samples lower than that. The author decided to use a sample size of a 100 to fill in this gap. Moreover, the decision was also supported by the notion that the change of the posterior sampling geometries could benefit the performance and recovery capacity of the implementation, under this setting.

Second, as expected, the author used two parametrization of the models: CP and NCP. To the author's knowledge, the IRT literature has not evaluated the change of posterior sampling geometries, as an alternative to improve the performance of the bayesian implementation of said models. The study will fill part of this gap.

Third, the author evaluated the performance, recovery capacity and retrodictive accuracy of a first- and second-order latent variable models (FOLV and SOLV, respectively). The selected models were motivated from our specific subject knowledge of the teacher's standardized assessments in Peru.

Consequently, ten (10) data sets were generated for each study condition, following the algorithm in section 4.3. Each data set resembled responses to 25 binary scored items, conforming to the SOLV model defined in figure 4.2. The model was motivated by the hypothesized structure of the reading comprehension sub-test, from the Peruvian public teaching career national assessment (see chapter 5). The latent structure, regression parameters, and loadings remained unchanged throughout the simulation replicas, to reduce experimental error [34].

4.3 Algorithm

Each data replication was simulated following a six-step procedure. First, the author randomly simulated a collection of pseudo-covariates $\mathbf{W}_\theta = [W_1, W_2, W_3, W_4]$, motivated by a similar information set present in the reading comprehension sub-test. The generated covariates were: (i) a binary “gender” variable (W_1), describing males and females, (ii) an integer “age” variable (W_2) with range [30, 65], the latter corresponding to the age of retirement, (iii) a three-level categorical “education” variable (W_3), indicating the type of education the individual received: institute only, university only, or both; and finally (iv) a four-level categorical “experience” variable (W_4), denoting the individual’s years of work experience, where the higher the category, the higher the years of experience. Associated with these, the author defined their regression parameters $\boldsymbol{\Gamma}_\theta = [\Gamma_0, \Gamma_1, \Gamma_2, \Gamma_3, \Gamma_4]$ where: (i) $\Gamma_0 = 0$, indicating the absence of an intercept; (ii) $\Gamma_1 = [\gamma_m, \gamma_f] = [0, 0.5]$, for males and females, respectively; (iii) $\Gamma_2 = -0.02$, indicating the individuals loose ability with age, in a linear manner; (iv) $\Gamma_3 = [\gamma_{io}, \gamma_{uo}, \gamma_b] = [-0.5, 0.5, 0]$, assuming individuals with university degree have better ability levels, followed by individuals with both educations, and individuals with institute degrees; and lastly (v) $\Gamma_4 = [\gamma_{0y}, \gamma_{5y}, \gamma_{10y}, \gamma_{11+y}] = [-0.5, 0, 0.35, 0.5]$, implying experience has decreasing returns on abilities.

Second, the study simulated the second- and first-order latent variables, corresponding to the reading comprehension ability and its three sub-dimensions: literal, inferential and reflective. Reading comprehension ($\theta_j^{(3)}$) was generated from a normal distribution $N(\mu_j^{(3)}, \sigma_\theta^{(3)})$, with $\mu_j^{(3)} = \boldsymbol{\Gamma}_\theta \mathbf{W}_\theta$, i.e. the linear combination of the simulated covariates and its corresponding regression parameters, and $\sigma_\theta^{(3)} = 0.5$. On the other hand, the three sub-dimensions were generated from a multivariate normal distribution $MVN(\boldsymbol{\mu}_j^{(2)}, \boldsymbol{\Sigma}^{(2)})$,

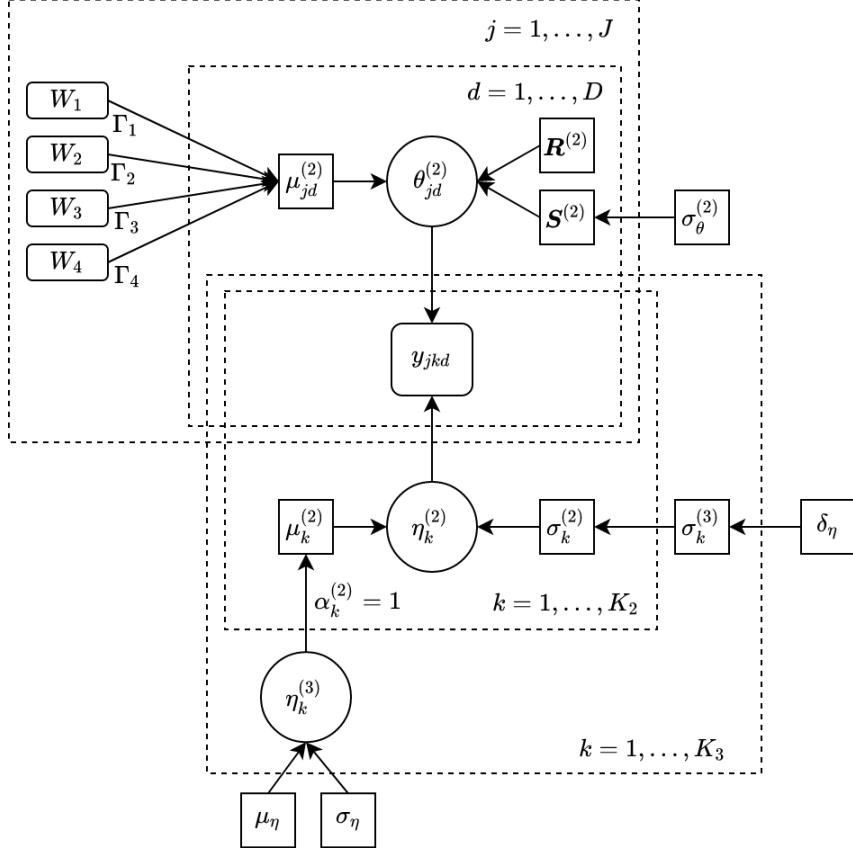


Figure 4.1: Directed Acyclic Graph (DAG). First-order latent variable model (FOLV). Circles represent latent variables. Squares represent parameters or parameters for priors. Large squares represent nesting in specific units.

with a mean vector $\boldsymbol{\mu}_j^{(2)} = [\mu_{j1}^{(2)}, \mu_{j2}^{(2)}, \mu_{j3}^{(2)}] = [\lambda_1^{(2)}\theta_j^{(3)}, \lambda_2^{(2)}\theta_j^{(3)}, \lambda_3^{(2)}\theta_j^{(3)}]$, loadings $\boldsymbol{\lambda}^{(2)} = [\lambda_1^{(2)}, \lambda_2^{(2)}, \lambda_3^{(2)}] = [0.95, 0.95, 0.95]$, and covariance matrix $\boldsymbol{\Sigma}^{(2)} = \mathbf{S}^{(2)} \cdot \mathbf{R}^{(2)} \cdot \mathbf{S}^{(2)}$. Lastly, $\mathbf{S}^{(2)} = \boldsymbol{\sigma}_\theta^{(2)} \mathbf{I}$, i.e. a diagonal standard deviation matrix with $\boldsymbol{\sigma}_\theta^{(2)} = [0.5, 0.5, 0.5]$; whereas $\mathbf{R}^{(2)} = \mathbf{I}$, i.e. an identity correlation matrix, implying the sub-dimensions are independent after accounting reading comprehension.

Third, the author defined five (5) common stimulus or texts for the items, where the mean difficulty for the texts $\boldsymbol{\eta}^{(3)} = [\eta_1^{(3)}, \eta_2^{(3)}, \eta_3^{(3)}, \eta_4^{(3)}, \eta_5^{(3)}] = [-1.50, -0.75, 0, 0.75, 1.50]$; whereas the deviation from said mean difficulties were $\sigma_k^{(3)} = 0.5$ for all texts.

Fourth, 25 items were randomly generated from independent normal distributions $N(\mu_k^{(2)}, \sigma_k^{(2)})$, with $\mu_k^{(2)} = \boldsymbol{\eta}^{(3)} \boldsymbol{\alpha}^{(2)} \mathbf{A}$ and $\sigma_k^{(2)} = \sigma_k^{(3)}$; where $\boldsymbol{\alpha}^{(2)} = \mathbf{1}$, indicating the difficulty of the common stimulus directly explained the difficulty of the items, and \mathbf{A} was a block design matrix that maps the items to its corresponding passage, defined in the previous step. Lastly, the items' measured dimensions were also generated at random.

Fifth, the author calculated the linear predictor v_{jkd} and probability of endorsing an item π_{jkd} , for each individual j on item k (belonging to dimension d), according to equations (2.5), (2.2), and (2.3), respectively; where the probability was calculated using the logistic inverse-link function.

Sixth and last, the outcome y_{jkd} was simulated from a Bernoulli distribution as in equation (2.1), with a probability of success calculated as in the previous step.

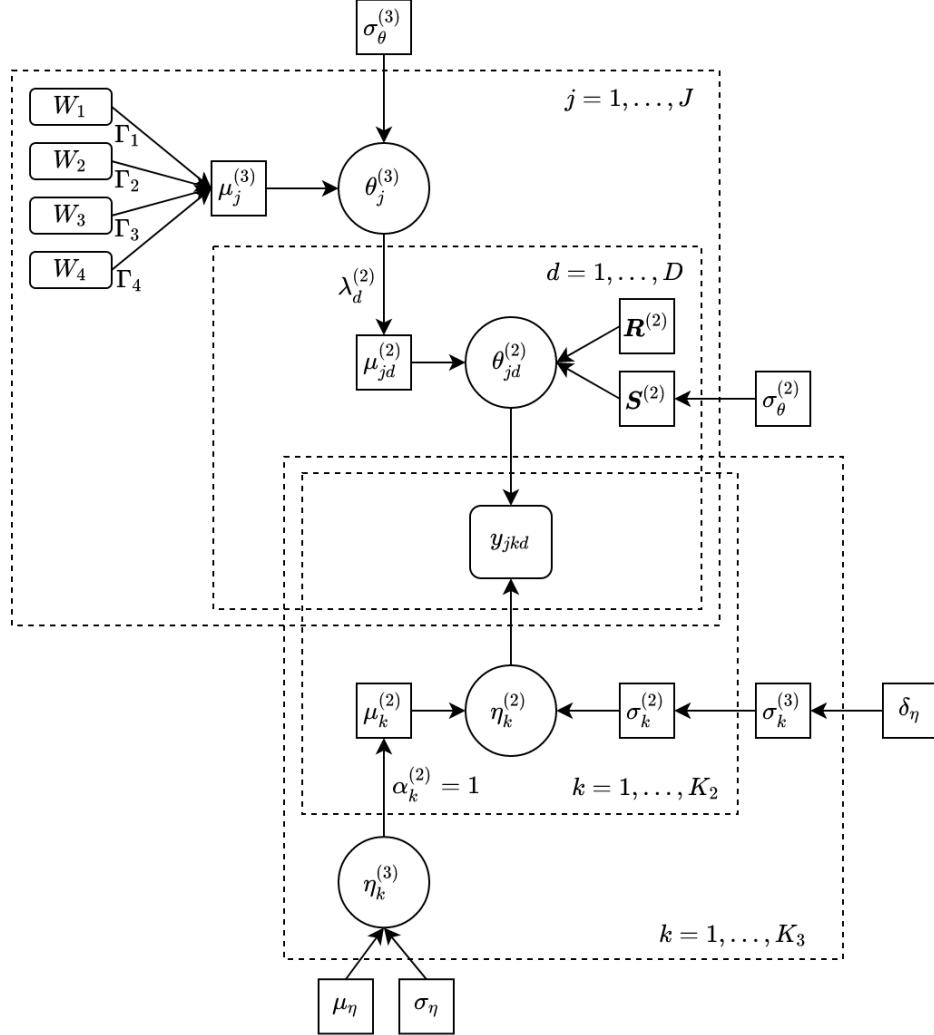


Figure 4.2: Directed Acyclic Graph (DAG). Second-order latent variable model (SOLV). Circles represent latent variables. Squares represent parameters or parameters for priors. Large squares represent nesting in specific units.

The code associated with the full simulation process can be found in Appendix B.2.1.

4.4 Parameter estimation

4.4.1 Models and identification

As stated in previous sections, we analyze two models: (i) the FOLV model depicted in figure 4.1, and (ii) the SOLV model depicted in figure 4.2. We proceed to enumerate the likelihood functions, and the full set of priors and hyper-priors used.

First, as stated in equations (3.6), (3.4), and (3.5), the distributional and systematic part of both models was defined as follows:

$$y_{jkd} \sim \text{Bernoulli}(\pi_{jkd}) \quad (4.1)$$

$$\text{logit}(\pi_{jkd}) = v_{jkd} \quad (4.2)$$

$$v_{jkd} = \theta_{jd}^{(2)} - \eta_k^{(2)} \quad (4.3)$$

Notice the linear predictor can be considered a multilevel-multidimensional extension of the well known Rasch IRT model [62]. As stated in previous chapters, the reader should keep in mind that in order to avoid the use of heavy notation, the items' indexes did not reflect the fact that some of them are set to measure specific individual's dimensions.

Second, the first-order latent variables and prior parameters were defined as follows:

$$\boldsymbol{\theta}_j^{(2)} = [\theta_{j1}^{(2)}, \theta_{j2}^{(2)}, \theta_{j3}^{(2)}] \quad (4.4)$$

$$\boldsymbol{\theta}_j^{(2)} \sim \text{MVNormal}(\boldsymbol{\mu}_j^{(2)}, \boldsymbol{\Sigma}^{(2)}) \quad (4.5)$$

where $\boldsymbol{\Sigma}^{(2)}$ is defined by:

$$\boldsymbol{\Sigma}^{(2)} = \mathbf{S}^{(2)} \cdot \mathbf{R}^{(2)} \cdot \mathbf{S}^{(2)} \quad (4.6)$$

$$\mathbf{S}^{(2)} = \boldsymbol{\sigma}_{\theta}^{(2)} \mathbf{I} = \begin{pmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \sigma_2^2 & 0 \\ 0 & 0 & \sigma_3^2 \end{pmatrix} \quad (4.7)$$

$$\mathbf{R}^{(2)} = \begin{pmatrix} 1 & \rho_{12} & \rho_{13} \\ \rho_{21} & 1 & \rho_{23} \\ \rho_{31} & \rho_{32} & 1 \end{pmatrix} \quad (4.8)$$

while $\boldsymbol{\mu}_j^{(2)}$ can be defined in two ways, depending on the model we are fitting. For the FOLV model, the mean vector is defined as follows:

$$\boldsymbol{\mu}_j^{(2)} = [\mu_{j1}^{(2)}, \mu_{j2}^{(2)}, \mu_{j3}^{(2)}] \quad (4.9)$$

$$\mu_{jd}^{(2)} = \Gamma_0 + \Gamma_1 W_{1j} + \Gamma_2 (W_{2j} - W_{2\min}) + \Gamma_3 W_{3j} + \Gamma_4 W_{4j} \quad (4.10)$$

where Γ_p and W_{jp} are defined as in section 4.3. Notice the regression parameters are not dimension specific.

On the other hand, for the SOLV model, $\boldsymbol{\mu}_j^{(2)}$ is defined by:

$$\boldsymbol{\mu}_j^{(2)} = [\mu_{j1}^{(2)}, \mu_{j2}^{(2)}, \mu_{j3}^{(2)}] \quad (4.11)$$

$$\boldsymbol{\lambda}^{(2)} = [\lambda_1^{(2)}, \lambda_2^{(2)}, \lambda_3^{(2)}] \quad (4.12)$$

$$\mu_{jd}^{(2)} = \lambda_d^{(2)} \theta_j^{(3)} \quad (4.13)$$

where d denotes the index of the individual's dimension. Lastly, because the SOLV contemplates an additional level, corresponding to the reading comprehension ability, an additional set of parameters is defined as follows:

$$\theta_j^{(3)} \sim \text{Normal}(\mu_j^{(3)}, \sigma_{\theta}^{(3)}) \quad (4.14)$$

$$\mu_j^{(3)} = \Gamma_0 + \Gamma_1 W_{1j} + \Gamma_2 (W_{2j} - W_{2\min}) + \Gamma_3 W_{3j} + \Gamma_4 W_{4j} \quad (4.15)$$

Third, turning now our attention to the items' parameters $\eta_k^{(2)}$, both models have:

$$\eta_k^{(2)} \sim \text{Normal}(\mu_k^{(2)}, \sigma_k^{(2)}) \quad (4.16)$$

$$\mu_k^{(2)} = \boldsymbol{\eta}^{(3)} \mathbf{A} \quad (4.17)$$

$$\sigma_k^{(2)} = \boldsymbol{\sigma}^{(3)} \mathbf{A} \quad (4.18)$$

where $k = 1, \dots, 25$ items, $\boldsymbol{\eta}^{(3)} = [\eta_1^{(3)}, \eta_2^{(3)}, \eta_3^{(3)}, \eta_4^{(3)}, \eta_5^{(3)}]$ represent the texts difficulties, $\boldsymbol{\sigma}^{(3)} = [\sigma_1^{(3)}, \sigma_2^{(3)}, \sigma_3^{(3)}, \sigma_4^{(3)}, \sigma_5^{(3)}]$ the text deviations from such difficulties; and \mathbf{A} is the block design matrix that maps the items with its corresponding passage. In addition, $\eta_k^{(3)}$ and $\sigma_k^{(3)}$ are distributed as:

$$\eta_k^{(3)} \sim \text{Normal}(\mu_\eta, \sigma_\eta) \quad (4.19)$$

$$\sigma_k^{(3)} \sim \text{Exponential}(\delta_\eta) \quad (4.20)$$

Fourth, we declared all the hyper-priors required:

$$\boldsymbol{R}^{(2)} \sim \text{LkjCorrelation}(2) \quad (4.21)$$

$$\beta_G \sim \text{Normal}(0, 0.5) \quad (4.22)$$

$$\beta_A \sim \text{Normal}(0, 0.5) \quad (4.23)$$

$$\beta_E \sim \text{Normal}(0, 1) \quad (4.24)$$

$$\beta_X \sim \text{Normal}(0, 0.5) \quad (4.25)$$

where $\text{LkjCorrelation}(\cdot)$ denotes the Lewandowski, Kurowicka, and Joe prior correlation distribution [37].

Finally, in order to fully specify the model and provide a scale for the latent variables, the current research decided to set the scale of the higher-order dimension and sub-dimensions to one, i.e. $\sigma_\theta^{(3)} = 1$, and $\mathbf{S}^{(2)} = \boldsymbol{\sigma}_\theta^{(2)} \mathbf{I}$ with $\boldsymbol{\sigma}_\theta^{(2)} = [1, 1, 1]^T$, commonly known as the unit variance identification scheme (UVI). Moreover, to identify the texts' and items' parameters we set $\mu_\eta = 0$, $\sigma_\eta = 1$, $\delta_\eta = 2$.

Notice we needed to set the scales for all the individuals' dimensions equal to one, because otherwise the latent structure would not be identified. At the level of the first-order latent variables in either model (level-2), we would have $(3 \times 4)/2 = 6$ pieces of information available, corresponding to the variances and covariances of the first-order latent variables. The information then will need to estimate 10 parameters, i.e. 3 loadings, 3 variances corresponding to the first-order latent variable, 1 variance for the second-order latent variable (if present), and 3 correlations among sub-dimensions. Therefore, by restricting the variances to one, we have enough information to estimate the other parameters of interest (correlations and loading, if present). Additionally, this is further justified by the fact that latent variables have no inherent unit in which they are measured, consequently, setting their scale is an arbitrary decision [5].

4.4.2 Prior predictive investigation

As it was outlined in section 3.3.5, we will use prior predictive investigation to assess and visualize the consequences of our prior assumptions. The implications will be assessed

from two perspectives: the IRT and the outcome space perspective. For the former, we will investigate what the set of priors imply for the item characteristic curves (ICC), and item information function (IIF). For the latter, we will examine how the prior assumption translate onto the outcome space.

First, it will useful to define the ICC and IIF functions. Hambleton and Swaminathan [26] defined the ICC as the mathematical function that relates the probability of success on an item, to the ability measured by that same item. In our current implementation, such function would correspond to the systematic part of the GLLAMM, as defined in equations (2.2) and (2.3):

$$\text{ICC} = \pi_{jkd} = \frac{\exp(v_{jkd})}{1 + \exp(v_{jkd})} \quad (4.26)$$

where the linear predictor v_{jkd} contains the items' dimensions $\eta_k^{(m)}$ and the individuals' abilities $\theta_{jd}^{(l)}$, as defined in equation (2.4). As previously mentioned, the ICC of our current implementation can be considered as the multilevel-multidimensional extension to the Rasch model's ICC.

On the other hand, the same authors defined the IIF as a function that measured the amount of information provided by an item. In this setting, “information” is understood as the reduction of uncertainty, resulting from using an item to measure the ability of an individual. Given the above, the IIF for the GLLAMM will be defined in a similar manner as the Rasch counterpart, in the following form:

$$\text{IIF} = \pi_{jkd} (1 - \pi_{jkd}) \quad (4.27)$$

Figure 4.3 shows the ICC and IIF for the FOLV model (figure 4.1), resulting from the assumptions integrated by the priors detailed in the previous section. From panel (A), we can notice the difficulty of the items match a wide range of the individuals' abilities (see multiple black solid lines). This means the model expect items' difficulties to be in any part of the continuous range of abilities, with no restriction. Furthermore, the priors allow the model to obtain information about individuals located in the full significant range of the abilities, as seen in panel (B) of the same figure. All of this just means that no unintended assumption has “creep” into the model, at least from the IRT perspective. A similar result can be seen for the SOLV model (figure A.4, appendix).

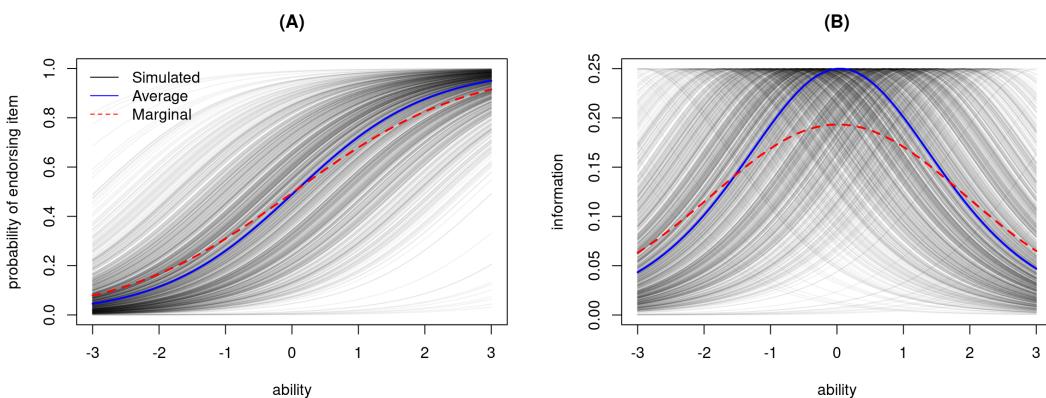


Figure 4.3: First-order latent variable model (FOLV). (A) Item Characteristics Curve, ICC. (B) Item Information Function, IIF.

Finally, from figure 4.4 and 4.5, we notice that no unintended assumption has been translated to the outcome space of the FOLV either. Panel (A) from figure 4.4 shows the individuals' proportion, of correctly answered items, can be present in the full range of possibilities. Furthermore, panel (B) of the same figure shows the proportion of individuals endorsing an item, for any item, can also be present in the full range of possibilities. Lastly, panels (C) and (D) convey similar information aggregated by texts and dimensions. On the other hand, all panels in figure 4.5 reveal the priors did not force the model to assume any apriori tendency in the covariates. A similar result can be seen for the outcome space of the SOLV model (figures A.5 and A.6, appendix).

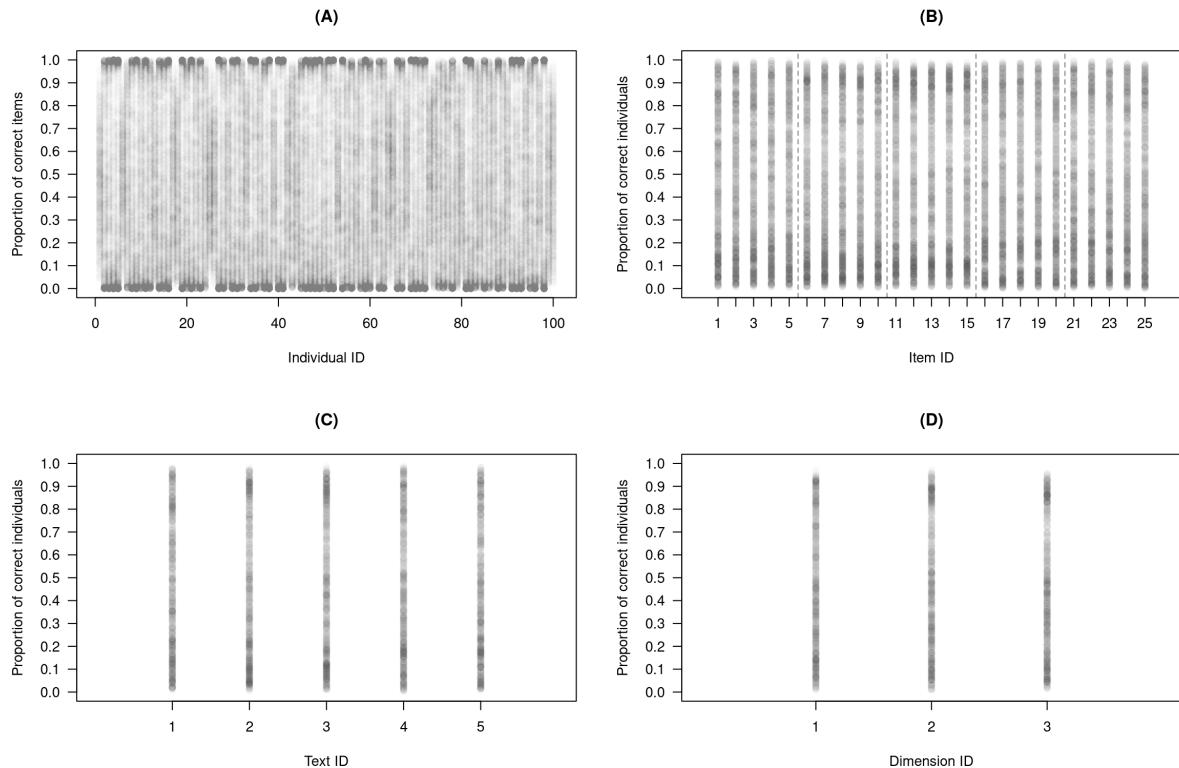


Figure 4.4: First-order latent variable model (FOLV). Aggregated endorsement rate per: (A) individuals, (B) items, (C) text or passage, and (D) measured dimension.

4.5 Evaluation criteria

As stated in section 4.2, the study was set to evaluate the performance, recovery capacity, and retrodictive accuracy of the bayesian implementation.

First, to assess the performance of the MCMC chains, in terms of achieving stationarity, convergence and good mixing, the author followed the usual visual approach. The approach involved the visual evaluation of trace plots, for stationarity and convergence, and trank and autocorrelation plots (ACF), for good mixing. Moreover, the assessment of convergence and mixing were supported by the `Rhat` and `n_eff` statistics developed by Gelman et al. [22] (pp. 284 – 287).

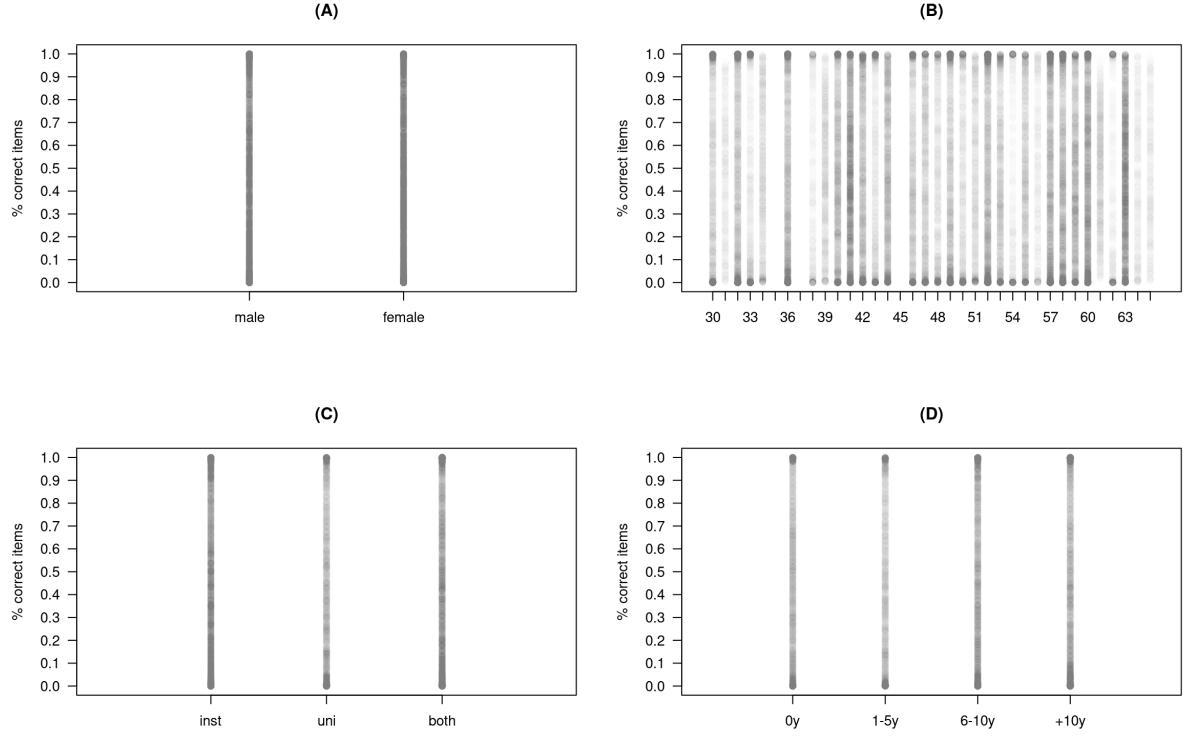


Figure 4.5: First-Order latent variable model (FOLV). Aggregated endorsement rate per simulated covariate: (A) gender, (B) age, (C) education, and (D) experience.

Second, to evaluate the recovery capacity for all the parameters $\Omega = \{\beta, \Lambda, \Theta, \Psi, \Gamma\}$, we used the between replica root mean squared error (RMSE_B), i.e. the extent of the deviation the posterior means exhibited from the true generating values, in all replicate simulations. The RMSE_B for each parameter of interest was defined as follows:

$$\text{RMSE}_B \left(\eta_k^{(m)} \right) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{\eta}_{krs}^{(m)} - \eta_k^{(m)} \right)^2} \quad (4.28)$$

$$\text{RMSE}_B \left(\theta_{jd}^{(l)} \right) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{\theta}_{jdrs}^{(l)} - \theta_{jd}^{(l)} \right)^2} \quad (4.29)$$

$$\text{RMSE}_B \left(\Gamma_w \right) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{\Gamma}_{wrs} - \Gamma_w \right)^2} \quad (4.30)$$

$$\text{RMSE}_B \left(\lambda_d^{(l)} \right) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{\lambda}_{drs}^{(l)} - \lambda_d^{(l)} \right)^2} \quad (4.31)$$

$$\text{RMSE}_B \left(\rho_{dq}^{(2)} \right) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{\rho}_{dqrs}^{(2)} - \rho_{dq}^{(2)} \right)^2} \quad (4.32)$$

where the “hat” parameters with index rs describe the parameter’s posterior sample $s = 1, \dots, S$ with $S = 3,000$, and replica $r = 1, \dots, R$ with $R = 10$. Additionally, $\rho_{dq}^{(2)}$ denotes the individuals correlations parameters in matrix $\mathbf{R}^{(2)}$, with $q > d$, where $d = 1, \dots, 3$ and $q = 1, \dots, 3$. Notice, in the case of the FOLV model, we were forced to calculate an approximate implied correlation structure between sub-dimensions, resulting from having a miss-specified model. The calculation was perform through the use of Wright’s tracing rules [5].

Finally, since IRT models are known to be invariant to the shift of the linear predictor [4, 7], i.e. the addition/subtraction of a constant to the abilities/difficulties results in the same probability value, it could happen that we observe substantial differences in the recovery of the parameters, that not necessarily implies a classification error [75]. Therefore, to avoid a mistake in the model’s assessment of fit, the current research will use posterior predictive checks, i.e. use the parameters’ posterior distribution to asses how good is the retrodictive accuracy of the implementation.

The retrodictive accuracy was measured by the root mean squared error of the responses’ predictive proportion \hat{p} , versus the observed proportion p , according to a set of aggregating dimensions. However, since there is prediction uncertainty within and between each replica, we defined two measures:

$$\overline{\text{RMSE}}_W (p_j) = \frac{1}{R} \sum_{r=1}^R \sqrt{\frac{1}{S} \sum_{s=1}^S (\hat{p}_{jrs} - p_j)^2} \quad (4.33)$$

$$\text{RMSE}_B (p_j) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{p}_{jrs} - p_j \right)^2} \quad (4.34)$$

where $\overline{\text{RMSE}}_W$ and RMSE_B denotes the average within and between prediction root mean squared error, respectively; while $j = 1, \dots, J$ defines the individual’s index, $S = 3,000$ and $R = 10$. Notice from the previous equations that we obtain two measures of deviations from the true proportion, per individual.

In a similar manner, we can calculate the same statistics for each item, text, dimension, and even per each individual and simulated covariate combination. Such statistics were defined as follows:

$$\overline{\text{RMSE}}_W (p_k) = \frac{1}{R} \sum_{r=1}^R \sqrt{\frac{1}{S} \sum_{s=1}^S (\hat{p}_{krs} - p_k)^2} \quad (4.35)$$

$$\text{RMSE}_B (p_k) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{p}_{krs} - p_k \right)^2} \quad (4.36)$$

$$\overline{\text{RMSE}}_W(p_l) = \frac{1}{R} \sum_{r=1}^R \sqrt{\frac{1}{S} \sum_{s=1}^S (\hat{p}_{lrs} - p_l)^2} \quad (4.37)$$

$$\text{RMSE}_B(p_l) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{p}_{lrs} - p_l \right)^2} \quad (4.38)$$

$$\overline{\text{RMSE}}_W(p_d) = \frac{1}{R} \sum_{r=1}^R \sqrt{\frac{1}{S} \sum_{s=1}^S (\hat{p}_{drs} - p_d)^2} \quad (4.39)$$

$$\text{RMSE}_B(p_d) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{p}_{drs} - p_d \right)^2} \quad (4.40)$$

$$\overline{\text{RMSE}}_W(p_{jw}) = \frac{1}{R} \sum_{r=1}^R \sqrt{\frac{1}{S} \sum_{s=1}^S (\hat{p}_{jwrs} - p_{jw})^2} \quad (4.41)$$

$$\text{RMSE}_B(p_{jw}) = \sqrt{\frac{1}{R} \sum_{r=1}^R \left(\frac{1}{S} \sum_{s=1}^S \hat{p}_{jwrs} - p_{jw} \right)^2} \quad (4.42)$$

where $k = 1, \dots, 25$ items; $l = 1, \dots, 5$ texts; $d = 1, 2, 3$ dimensions; and $w = 1, \dots, 4$ simulated covariates.

4.6 Results

4.6.1 Chain performance

First, the CP and NCP chain performance for the texts' mean difficulties is reported in figures 4.6 and 4.7, respectively. The figures correspond to replica number two of the FOLV model, with a simulated sample size of 100.

From the figures, one can easily notice the parameters under the CP did not show signs of achieving ergodicity. The chains showed a clear lack of stationarity and convergence (left panels). Moreover, the iterations did not explore the posterior distribution appropriately, as the several divergent transitions hinted, indicating a lack of good mixing, e.g. the top trace and trank plots show chains that are “stuck” in specific areas of the distribution. In addition, the ACF plots reveal the chain iterations were highly auto-correlated, another sign of bad mixing. All of this is further confirmed by panels (A) and (C) from figure 4.8, where we can see the CP has low effective samples sizes (`n_eff`) and higher than appropriate `Rhat` values, compared to the NCP.

In contrast, the parameters from the NCP are closer to achieve ergodicity. The trace plots show chains that seem to be stationary and convergent. The trank plots show a rapid exploration of the full range of posterior distribution. No divergent transitions were registered. And finally, the ACF plots show the iterations are less auto-correlated. Again, this is further confirmed by figure 4.8, where the NCP show greater `n_eff` and appropriate `Rhat` values, versus the CP.

On the other hand, figures A.7 and A.8 (appendix) show the the CP and NCP trace, trank, and ACF plots for the the difficulties' deviations of the texts. At a simple glance, the plots seem to indicate that both parametrizations achieve a similar level of ergodicity. However, from panels (A) and (C) in figure 4.8, we can notice that while both parametrization show chains with $Rhat < 1.05$, for some parameters the CP has lower effective sample sizes than the NCP counterpart. The latter just indicates the NCP has less auto-correlated chains, and therefore a bit better mixing.

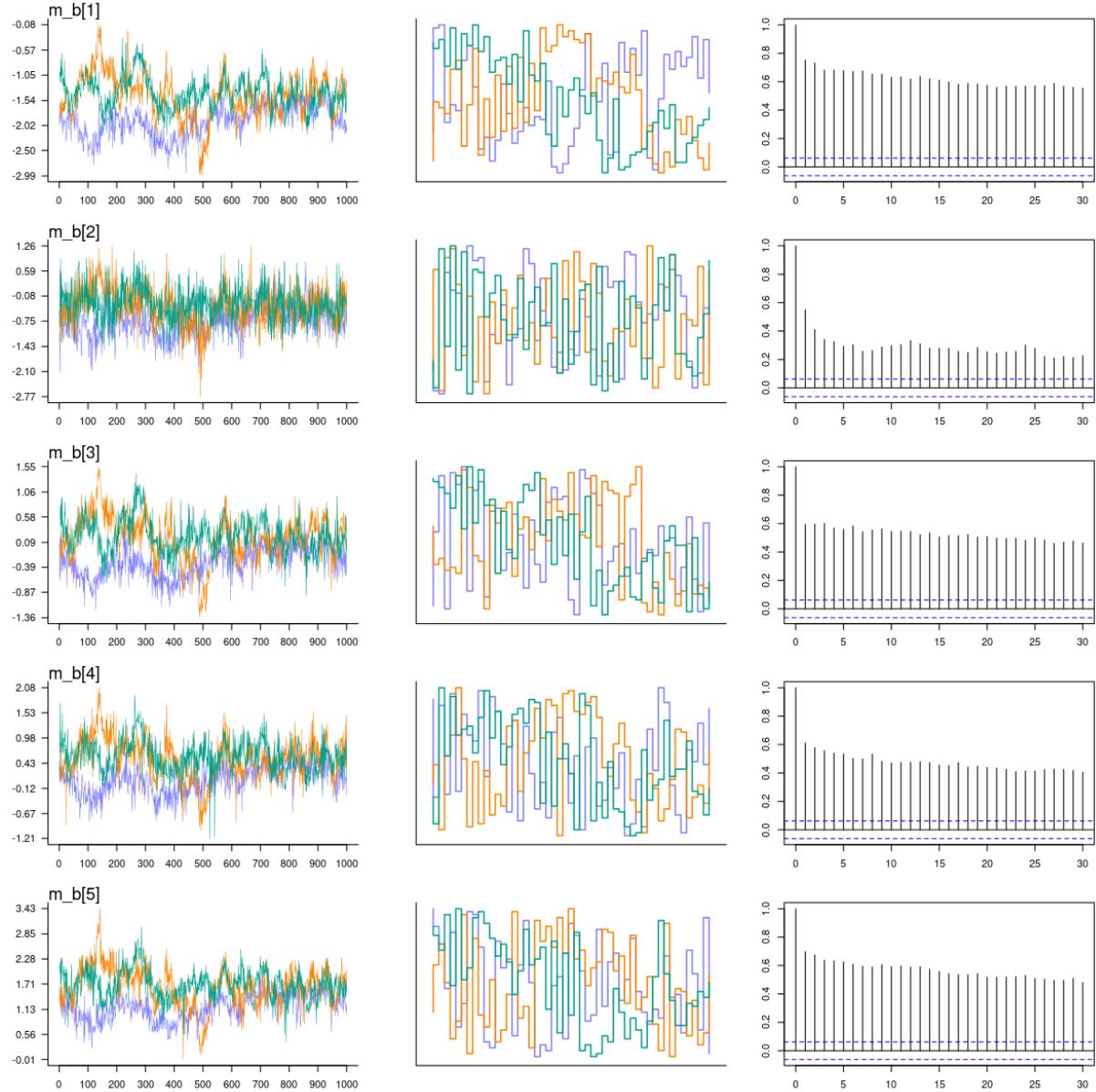


Figure 4.6: First-Order latent variable model (FOLV). Sample size 100, replica number 2. Centered parametrization. Mean difficulty per text: (Left) trace plot, (Middle) trank plot, (Right) auto-correlation plot.

Furthermore, figures A.9 and A.10 (appendix) show the chain performance for the CP and NCP item difficulties. The trace, trank and ACF plots show a similar pattern as

the one outlined for the difficulty of the texts, albeit more extreme. The CP chains did not achieve stationarity, convergence, nor good mixing; whereas the NCP does. This is further confirmed by panels (B) and (D) of figure 4.8, where one can see observe the NCP has significantly higher effective sample sizes and $Rhat < 1.05$, in contrast to the CP.

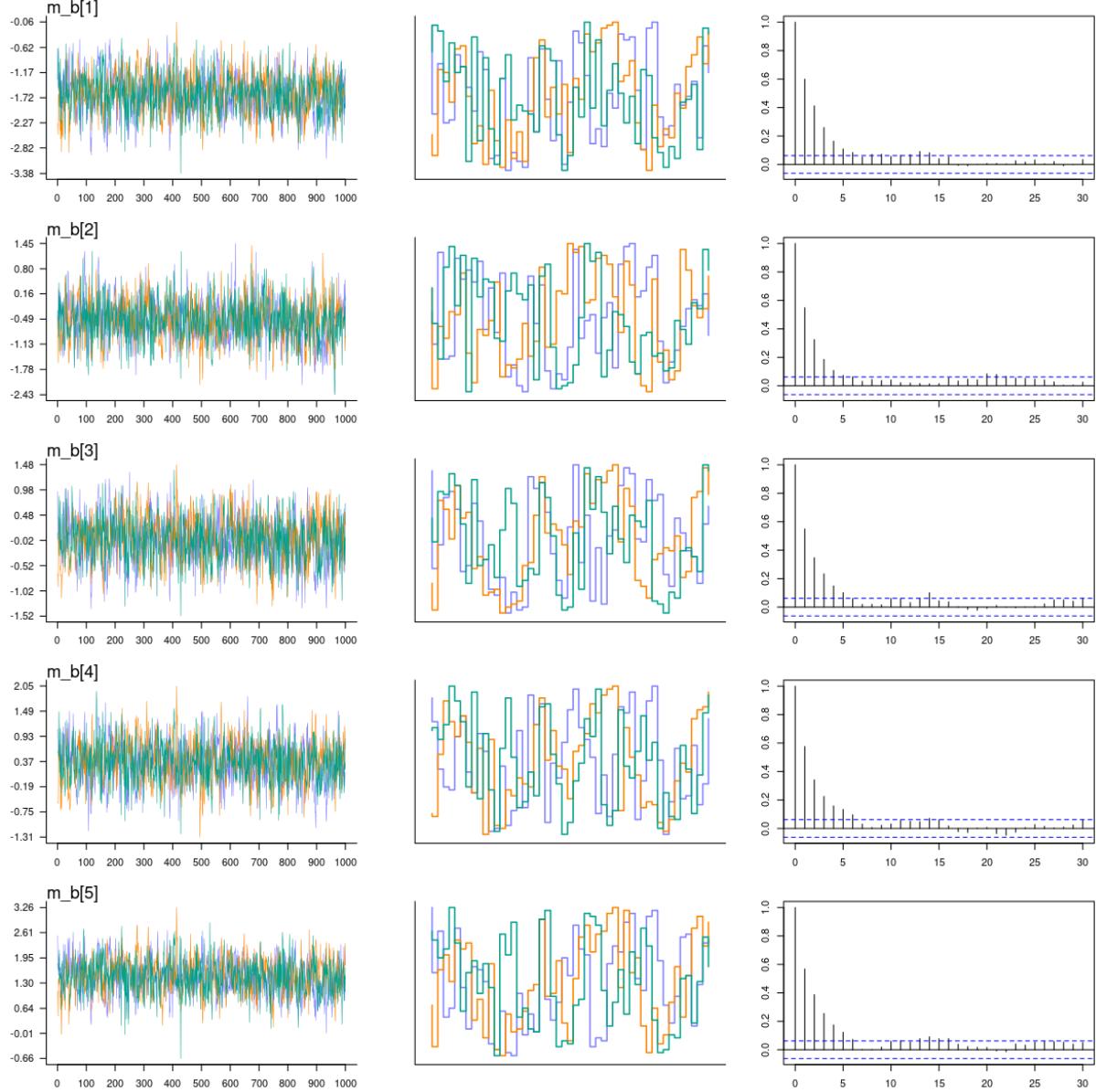


Figure 4.7: First-Order latent variable model (FOLV). Sample size 100, replica number 2. Non-centered parametrization. Mean difficulty per text: (Left) trace plot, (Middle) rank plot, (Right) auto-correlation plot.

Second, the CP chain performance for the reading comprehension sub-dimensions are reported in figures A.11, A.13, A.15 (appendix). The figures correspond to replica number six of the FOLV model, with a simulated sample size of 100. The chains also show a lack of ergodicity similar to the texts' difficulties, e.g. the left panels of figure A.15 show chains that did not explore the posterior distribution appropriately (see straight lines in the trace

plots). This is further confirmed by panels (A) through (D) in figure A.27, where the CP has low effective sample sizes, while an important proportion of the parameters is above the recommended `Rhat` threshold. In contrast, the NCP chains for the sub-dimensions achieve ergodicity, as it is shown in figures A.12, A.14, A.16, and confirmed by the `n_eff` and `Rhat` values in figure A.27.

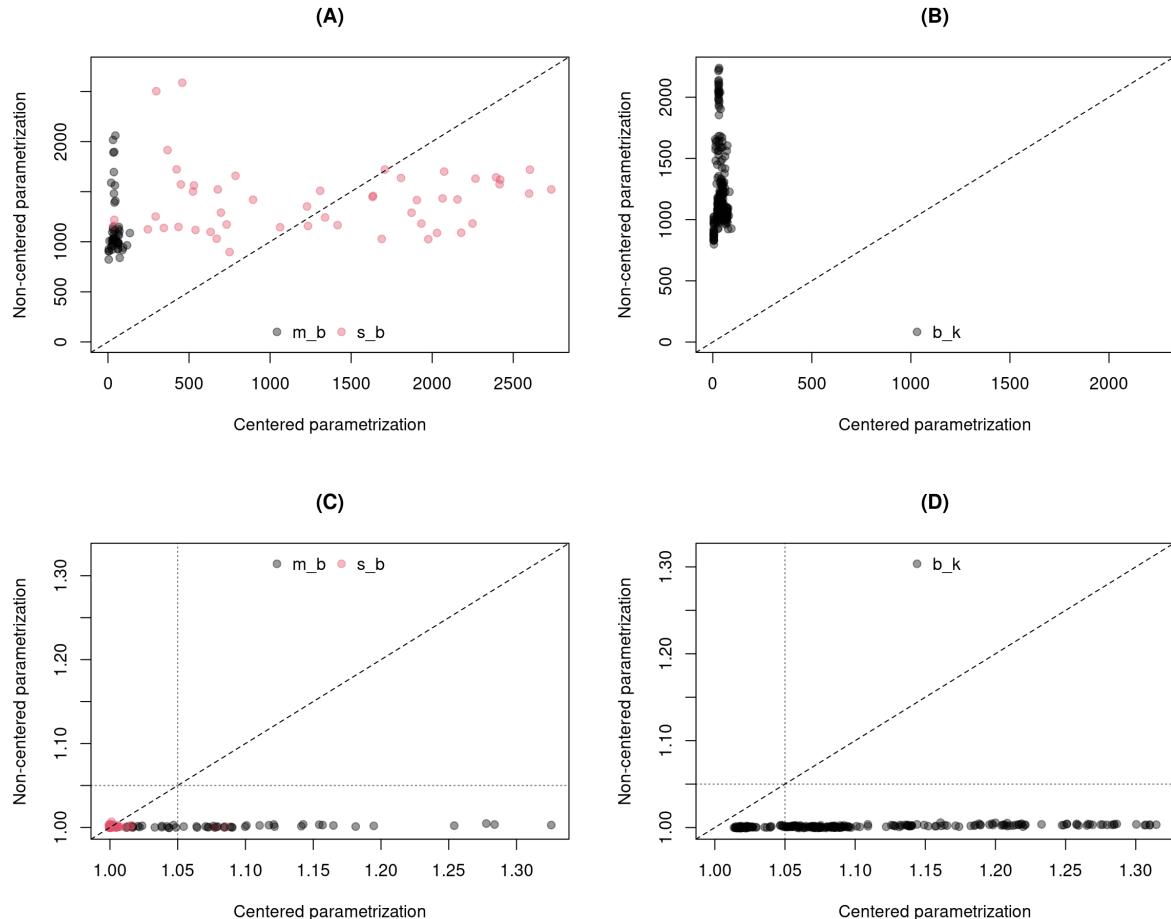


Figure 4.8: First-order latent variable model (FOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) `n_eff` for texts' mean difficulty and standard deviation of difficulty. (B) `n_eff` for items's difficulties. (C) `Rhat` for texts' mean difficulty and standard deviation of difficulty. (D) `Rhat` for items's difficulties. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $Rhat = 1.05$.

Third, similar visualizations for the CP and NCP regression parameters are shown in appendix figures A.17 and A.18. By a careful inspection of the CP trace plots, one can notice we still have chains that are “stuck” in specific part of the posterior distribution (see green lines). As a result, the CP registered lower effective samples sizes than the NCP, as figure A.28 confirms. However, neither of those things prevented the CP achieving convergence, as the `Rhat` in the same figure confirms. In contrast, the NCP parameters seem to achieve stationarity, convergence, and good mixing without any issues, with higher

effective sample sizes and $Rhat$ values close to one.

Lastly, the performance assessment plots for the FOLV sub-dimensions' correlation are shown in appendix figures A.19 and A.20. In both parametrizations, we observe the correlations seem to achieve stationarity and convergence. However, it also seems they do not manage to make a proper investigation of the posterior. This is further confirmed by panels (B) and (D) from figure A.28, where we see observe the parameters' chains remain below the $Rhat$ recommended threshold, indicating convergence; although, the effective sample sizes were low, indicating highly auto-correlated iterations.

So far we have only compared the CP and NCP performance of the FOLV model, for specific replicas and a simulated sample size of 100. However, after the inspection of the trace, trank, ACF and comparison plots¹, we notice the preceding patterns of stationarity, convergence and mixing extends to all replicas, simulated sample sizes and parametrizations of the FOLV model. Furthermore, the aforementioned patterns were also observed in the parameter set the SOLV shares with the FOLV model.

For the remaining parameters in the SOLV, i.e. the loadings and reading comprehension higher-order latent variables, we continue observing the same recurring patterns. Appendix figures A.21 and A.22 show the NCP loadings have chains that seem slightly more stationary, convergent, and well mixed than its CP counterpart. This is further confirmed by panels (B) and (D) from figure A.29. In a similar fashion, figures A.25 and A.26 show the higher-order latent variable is significantly more ergodic under the NCP than the CP, and figure A.30 confirms the hypothesis, by showing it has larger effective sample sizes, with $Rhat$ values always close to one.

Finally, panel (A) of figure A.31 show the pattern of ergodicity for the regression parameters is slightly improved under the SOLV. The chains show larger effective sample sizes under the NCP versus the CP, indicating less correlation among the iterations, and therefore, better mixing. Ultimately, the patterns for this set of parameters is also consistent across replicas and simulated sample sizes.

Consequently, all of the above just show the NCP largely improved the performance of the MCMC chains under our implementation, for all models and almost all of the parameters. It is important to point out, the result did not extend to the sub-dimensions' correlation parameters, where no large difference in performance was observed between the CP and NCP. On this matter, the issue was not related to a lack of identification of said parameters, as we were careful of ensuring this requirement.

4.6.2 Recovery capacity

Figures 4.9 and 4.10 show the the CP and NCP recovery of the regression, contrast, and correlation parameters for the first replica of the FOLV model with sample size 100. From both figures we notice the regression and contrast parameters were estimated appropriately. The true values were located within the compatibility interval of the estimates. Moreover, no remarkable difference is observed between the CP and NCP implementations. This result extends across all replicas and sample sizes, as all the recovery plots² confirm. Furthermore, table A.4 (appendix) reveal the $RMSE_B$ of the regression param-

¹To inspect the remaining trace, trank, ACF, and comparison plots follow the github accompanying page detailed in Appendix A.2.2.

²To inspect the remaining recovery plots follow the github accompanying page detailed in Appendix A.2.3.

eters under NCP were consistently lower than the CP counterpart, but the differences were negligible. In a similar fashion, table A.5 show a similar pattern in the contrast parameters, between the CP and NCP; however, we observe the contrasts were recovered with better precision with larger sample sizes.

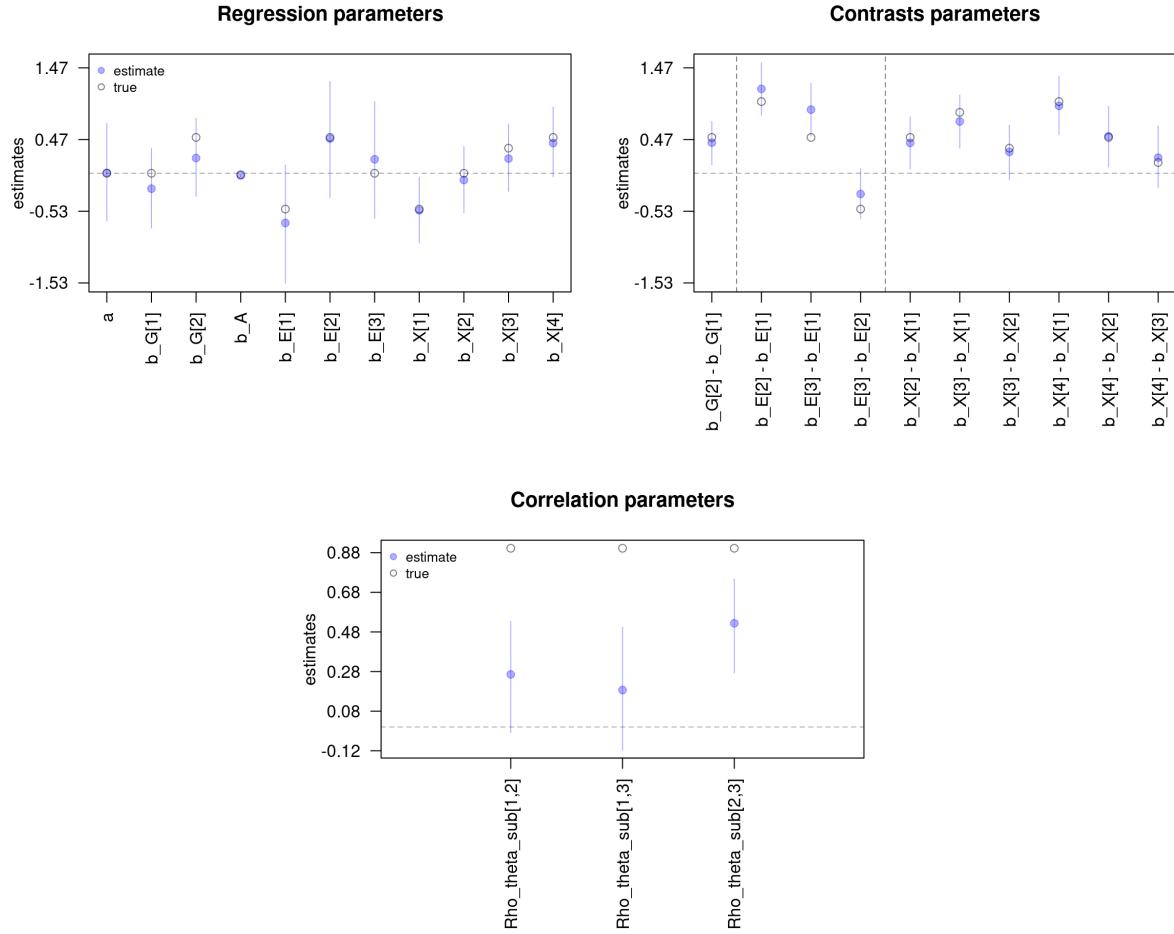


Figure 4.9: First-order latent variable model (FOLV). Centered parametrization. Sample size 100, replica 1. Regression, contrast, and correlation parameters. The “true” correlation parameters were calculated using Wright’s tracing rules, and corresponds to an approximate unconditional correlation.

On the other hand, in the same figures, we notice the CP and NCP correlation parameters were estimated similarly far from the approximate unconditional correlations. The unconditional correlations were calculated using Wright’s tracing rules [5], where as each loading $\lambda_d^{(2)} = 0.95$, the approximate correlation would correspond to $0.95 \times 0.95 = 0.9025$. However, the comparison is misleading because the correlation parameters from the model are not unconditional. Recall the FOLV model used regression covariates to explain some of the variability in the sub-dimensions, therefore, the reported correlations are the residual correlations after controlling for the aforementioned covariates. In that sense, we notice a non-negligible (and sometimes significant) amount of correlation remains present among the sub-dimensions, due to the miss-specification of the model. Again, this behavior is consistent across replicas, and samples sizes, with no discernible difference among

parametrizations (see table A.6, appendix).

Furthermore, figure A.32 show the CP and NCP items, text, and text deviation difficulty estimates. As with the previous patterns of recovery, no remarkable difference was observed among the different parametrizations. On both scenarios, the true items and text difficulties were within the compatibility intervals of the bayesian implementation, while the text difficulties and deviations were estimated with greater precision. As in the previous estimates, the pattern was consistent across replicas, and samples sizes, with no discernible difference among parametrizations (see tables A.8 and A.9, appendix).

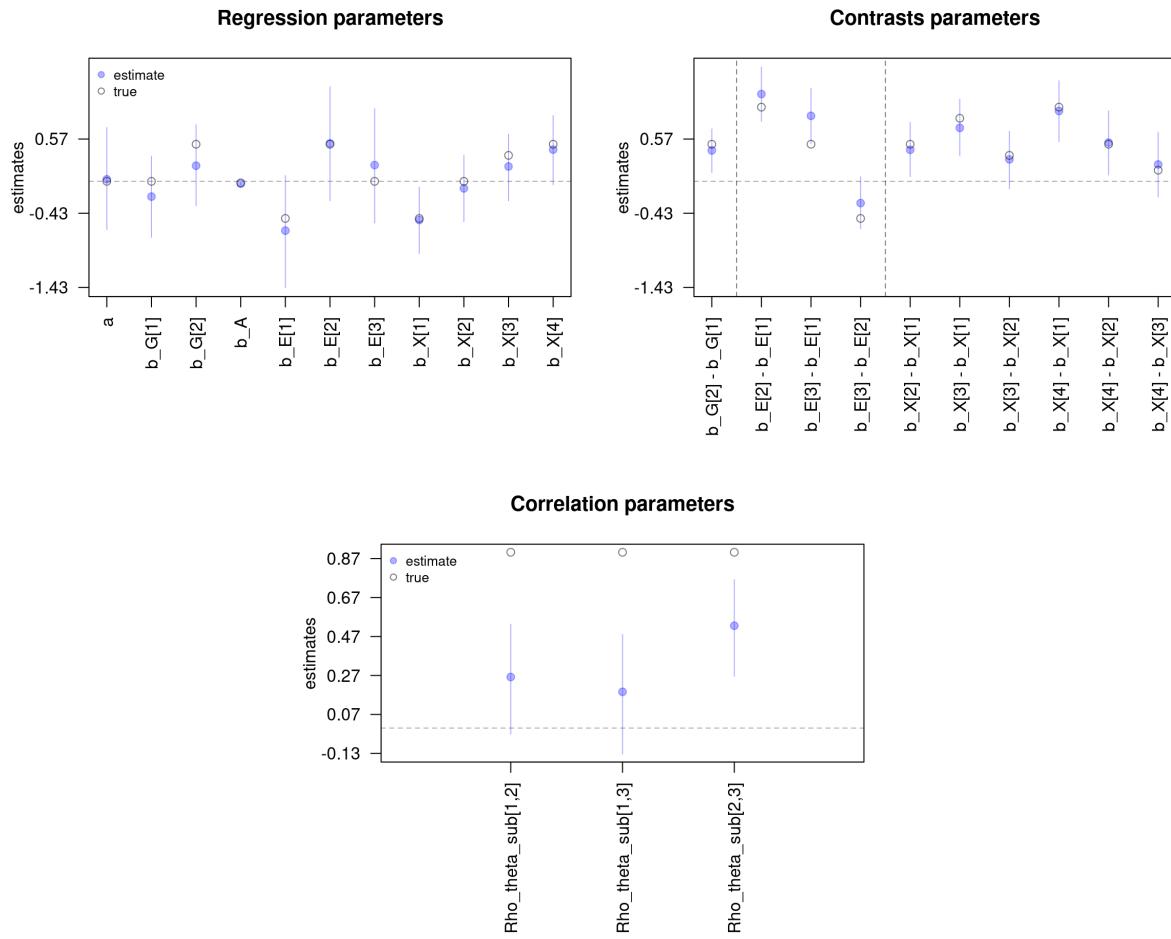


Figure 4.10: First-order latent variable model (FOLV). Non-centered parametrization. Sample size 100, replica 1. Regression, contrast, and correlation parameters. The “true” correlation parameters were calculated using Wright’s tracing rules, and corresponds to an approximate unconditional correlation.

A behavior somewhat similar is observed for the SOLV model. Figures A.33 and A.34 (appendix) show the CP and NCP regression, contrast, correlation and loading parameters. From the figures we notice the regression parameter were estimated equally well by both parametrizations. However, we notice the model had issues to appropriately recover the contrast parameters related to the education covariate. Moreover, because the model was correctly specified, the estimated correlations were close to the true simulation parameters, albeit one of them is remarkably different. Finally, the loadings were severely

underestimated, where the true values were not within any of the compatibility intervals. As with the FOLV, these patterns of recovery were consistent across replicas, samples sizes, with no discernible difference between parametrizations (see tables A.14, A.15, A.16, and [loadings table](#) appendix).

Finally, appendix A.2.3 provides the RMSE_B tables of the latent individuals' dimensions, for the FOLV and SOLV models, respectively. As with the preceding parameters, no discernible difference in the recovery capacity was observed between the CP and NCP. The results were consistent across replicas and sample sizes, as the several tables confirm.

It is surprising to observe the CP and NCP have a similar recovery capacity, as one could argue that in the case of simulation based estimation methods, like MCMC, the recovery capacity is highly tied to the performance of the procedure (conditional on the number of chosen iterations). The reader can recall from the previous section, that multiple parameter chains fail to achieve ergodicity under the CP, therefore, jeopardizing our ability to make valid inferences about them. Nevertheless, given the consistent results of this section, the researcher is led to think that even with all the issues present under the CP, the chains managed to visit the posterior distribution in a way, that allows the method to produce a proper estimation of the parameters.

The researcher also thinks the explanation for these results, can only come from the fact that we used the HMC algorithm with a higher rejection criteria (`adapt_delta=0.99`) and weakly regularizing priors. The previous chapter has described the benefits of these factors separately, so it is sensible to assume that, used in conjunction, they could benefit the posterior exploration, and therefore, the recovery capacity of the method. Further investigations manipulating these conditions could be of relative importance.

4.6.3 Retrodictive accuracy

signs of overfitting?

	Parametrization	Sample	Within RMSE			Between RMSE		
			mean	min	max	mean	min	max
1	CP	100	0.113	0.106	0.120	0.041	0.018	0.058
2	CP	250	0.114	0.107	0.127	0.041	0.023	0.070
3	CP	500	0.112	0.104	0.125	0.041	0.015	0.076
4	NCP	100	0.113	0.106	0.121	0.041	0.018	0.059
5	NCP	250	0.114	0.107	0.125	0.041	0.023	0.068
6	NCP	500	0.112	0.105	0.126	0.041	0.015	0.077

Table 4.1: First-order latent variable model (FOLV). Centered and non-centered parametrization. Within and between replicas individual predictive RMSE.

Parametrization	Sample size	Within RMSE			Between RMSE		
		mean	min	max	mean	min	max
1 CP	100	0.112	0.106	0.117	0.034	0.015	0.050
2 CP	250	0.112	0.107	0.122	0.035	0.018	0.059
3 CP	500	0.111	0.104	0.122	0.036	0.015	0.068
4 NCP	100	0.112	0.106	0.117	0.034	0.015	0.050
5 NCP	250	0.112	0.106	0.121	0.035	0.018	0.057
6 NCP	500	0.111	0.105	0.122	0.036	0.014	0.068

Table 4.2: Second-order latent variable model (SOLV). Centered and non-centered parametrization. Within and between replicas individual predictive RMSE.

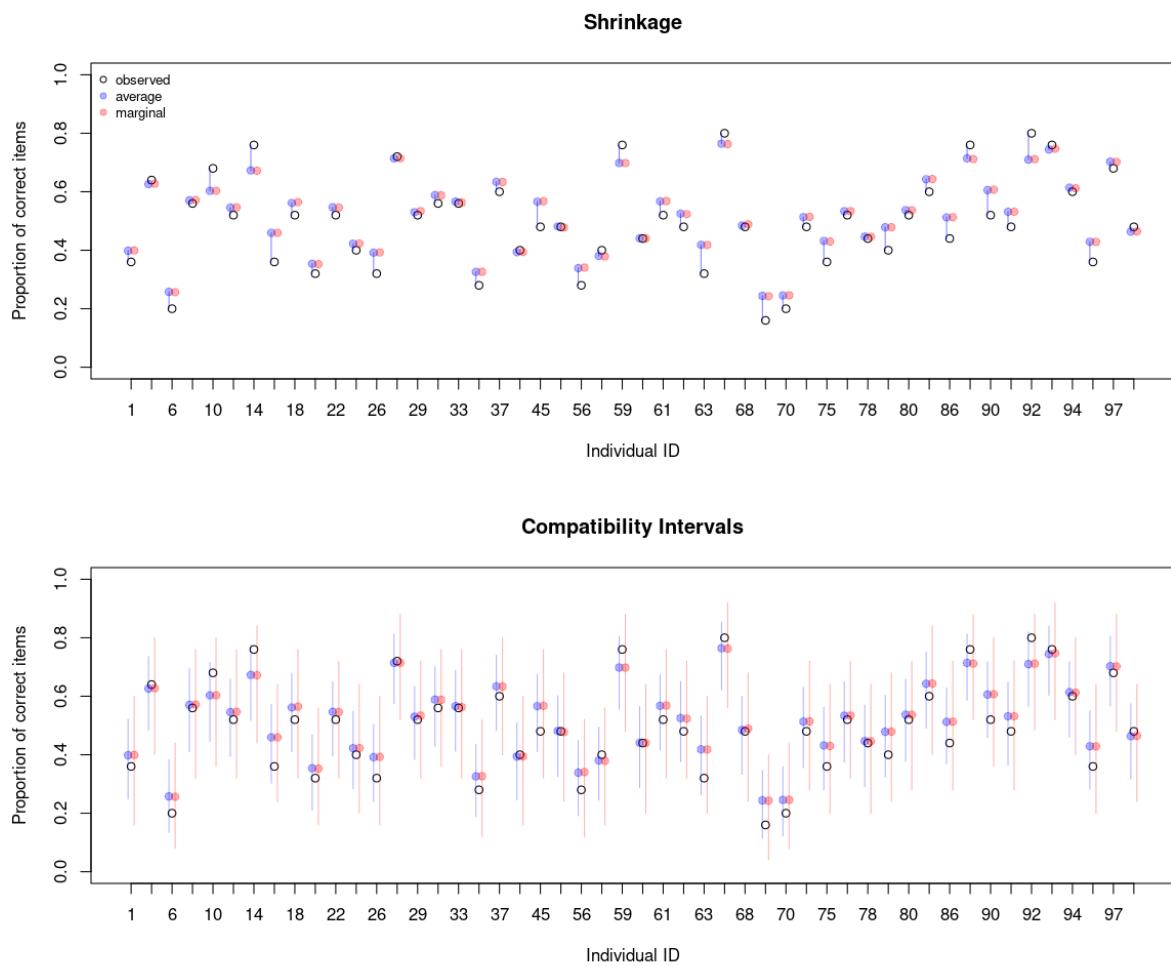


Figure 4.11: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Individual predictive plot.

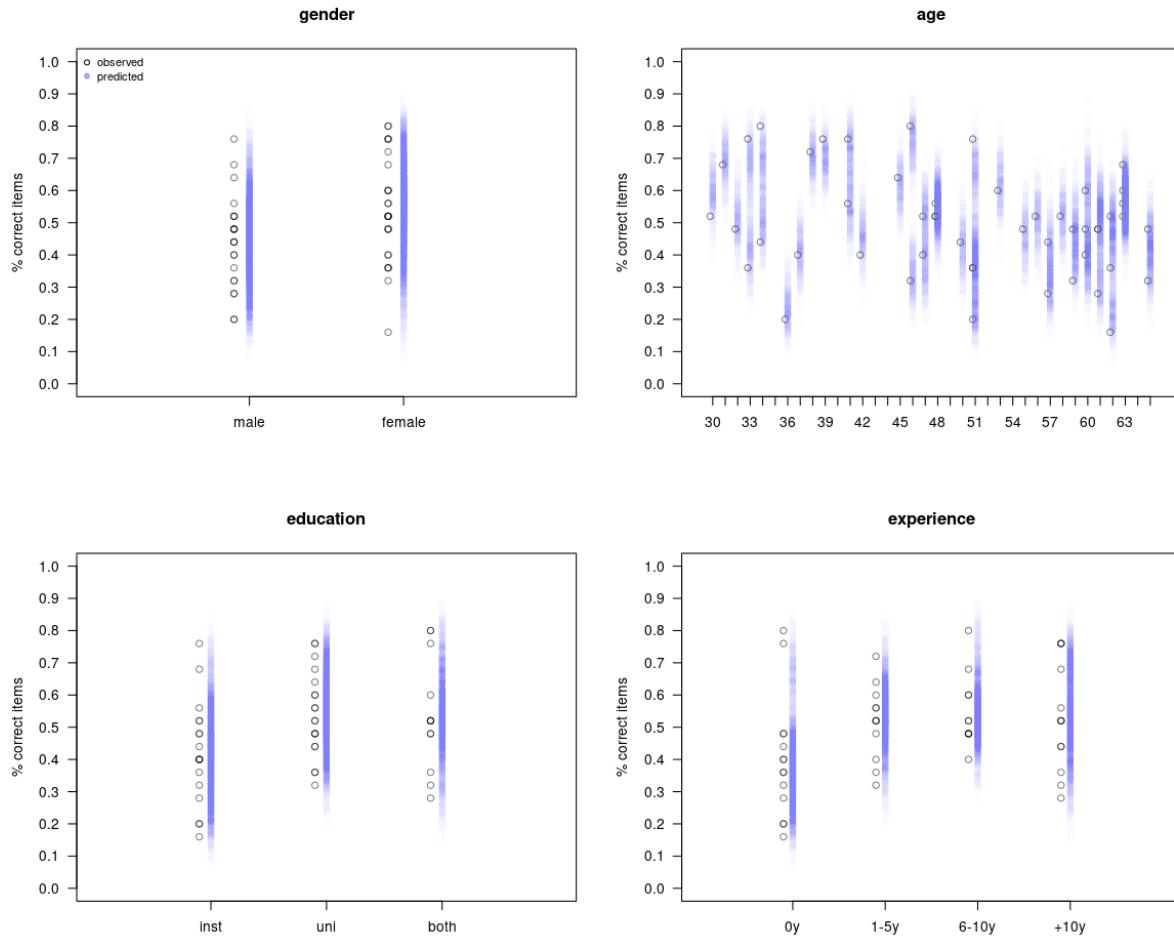


Figure 4.12: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Individual predictive plot per covariate.

4.6.4 Time

Although the assessment and comparison of the MCMC procedure's running time is not one of the main goals of the study, the researcher believes it is useful to report them, as they could serve as a benchmark of comparison for future developments of the implementation.

Tables 4.3 and 4.4 report the MCMC running time, under de CP and NCP, for the FOLV and SOLV model, respectively. We run 10 replicas for each combination of model, parametrization and sample size, where each replica consisted of 3 chains, run in parallel, with 2,000 iterations per chain. From the tables, we can see the NCP was faster than the CP for the smallest sample sizes (100 and 250). However, the differences in running time gets smaller as the sample size increases. This is true for both type of models.

The NCP being slightly faster than the CP is important, as the non-centered parametrization is more complex and requires the sampling of more parameters than the centered counterpart. This just means that improving the performance of the MCMC, through a more complex model as the NCP, does not come with a cost on running time.

			Time (min.)		
	Parametrization	Sample	mean	min	max
1	CP	100	4.80	1.89	7.56
2	CP	250	7.85	5.60	16.57
3	CP	500	19.15	17.20	22.53
4	NCP	100	1.94	1.74	2.23
5	NCP	250	7.18	6.78	8.40
6	NCP	500	22.38	20.12	28.62

Table 4.3: First-order latent variable model (FOLV). Running time statistics.

			Time (min.)		
	Parametrization	Sample	mean	min	max
1	CP	100	4.04	1.39	8.55
2	CP	250	7.13	5.22	11.49
3	CP	500	16.14	14.45	19.73
4	NCP	100	1.87	1.62	2.28
5	NCP	250	5.92	5.20	6.79
6	NCP	500	16.58	13.37	18.26

Table 4.4: Second-order latent variable model (SOLV). Running time statistics.

Chapter 5

Application

5.1 Instruments

5.2 Data

5.2.1 Collection

5.2.2 Sample scheme

5.3 Results

All of the preceding suggests one way to navigate overfitting and underfitting: Evaluate our models out-of-sample. using cross validation and information criteria

Pareto-smoothed importance sampling cross-validation (PSIS) and the Widely Applicable Information Criterion (WAIC).

Chapter 6

Conclusion and Discussion

6.1 Discussion

6.2 Conclusions

lack of correlation evidence could be due to the scale setting besides the models are more based on scientific knowledge rather than data motivated.

6.3 Future development

Investigate this, maybe you need to use Variational Inference methods

It is important to point out, the result did not extend to the sub-dimensions' correlation parameters, where no large difference was observed between the CP and NCP. On this matter, the issue was not related to a lack of identification of said parameters, as we were careful of ensuring this requirement.

CP versus NCP is a false dichotomy, because as authors mentioned they work more in a complementary way, therefore methods that seek these integrations may need to be the staple of IRT models.

Because of the setting of our simulation experiment, we cannot fully disentangle the benefits of HMC (through adapt delta), the mildly regularizing priors and the CP vs NCP. future developments could assess and compare each of these conditions separately. For example, investigate the recovery capacity under HMC and Gibbs sampling, under CP and NCP with no regularizing priors or adapt delta. as the results could be due to the HMC or the regularizing priors, and we cannot observe the true benefits of the change to NCP.

Appendix A

Figures and tables

A.1 Chapter 3: Bayesian estimation

A.1.1 To center or not to center

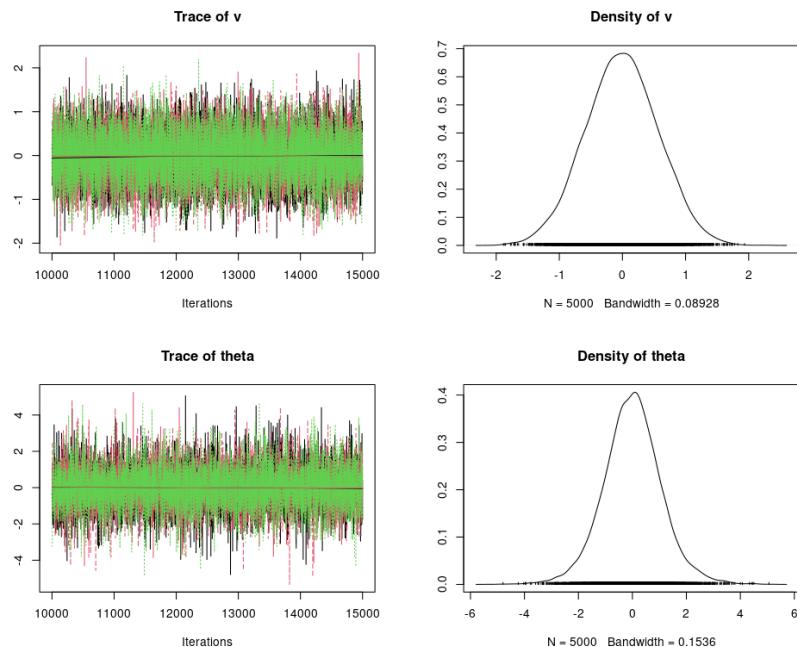


Figure A.1: The Devil's funnel. Centered Parametrization implemented in JAGS. It shows the traceplot and distribution of the parameters of interest.

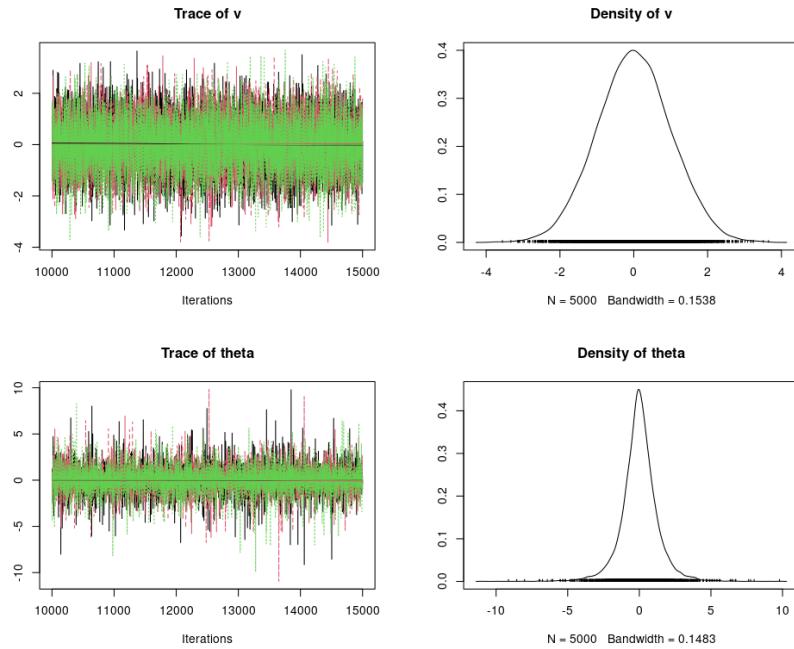


Figure A.2: The Devil's funnel. Centered Parametrization with mildly informative priors implemented in JAGS. It shows the traceplot and distribution of the parameters of interest.

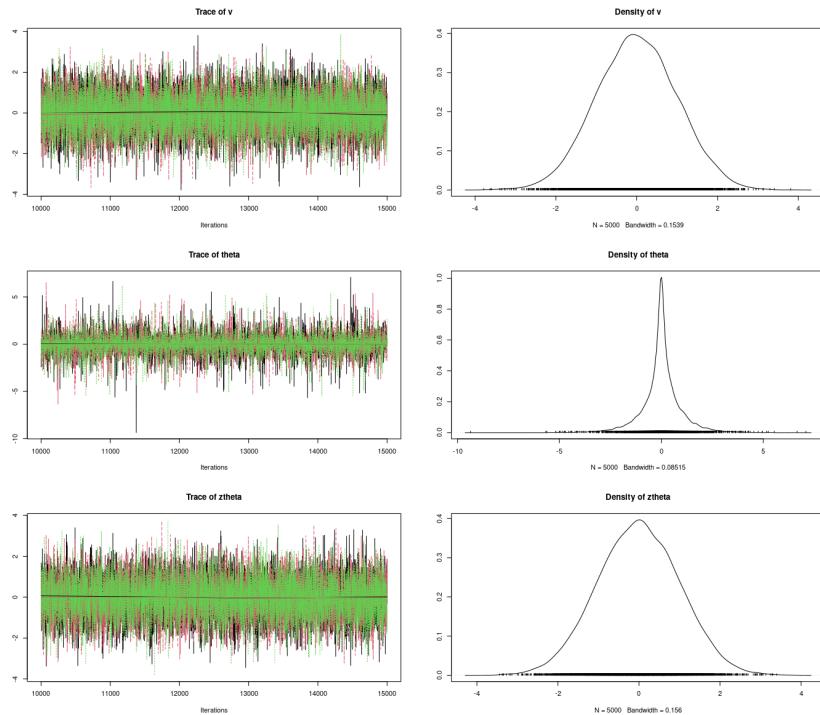


Figure A.3: The Devil's funnel. Non-Centered Parametrization implemented in JAGS. It shows the traceplot and distribution of the parameters of interest.

A.2 Chapter 4: Simulation study

A.2.1 Prior elicitation

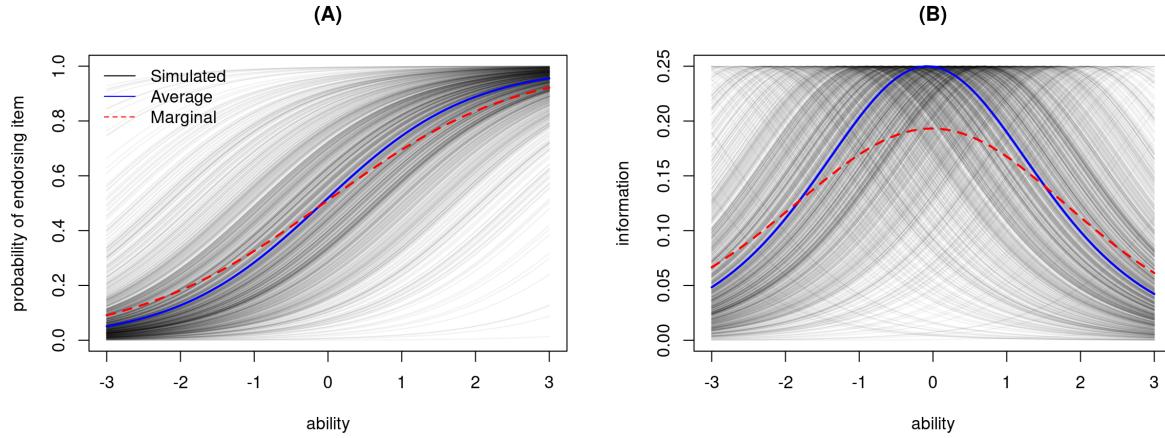


Figure A.4: Second-order latent variable model (SOLV). (A) Item Characteristics Curve, ICC. (B) Item Information Function, IIF.

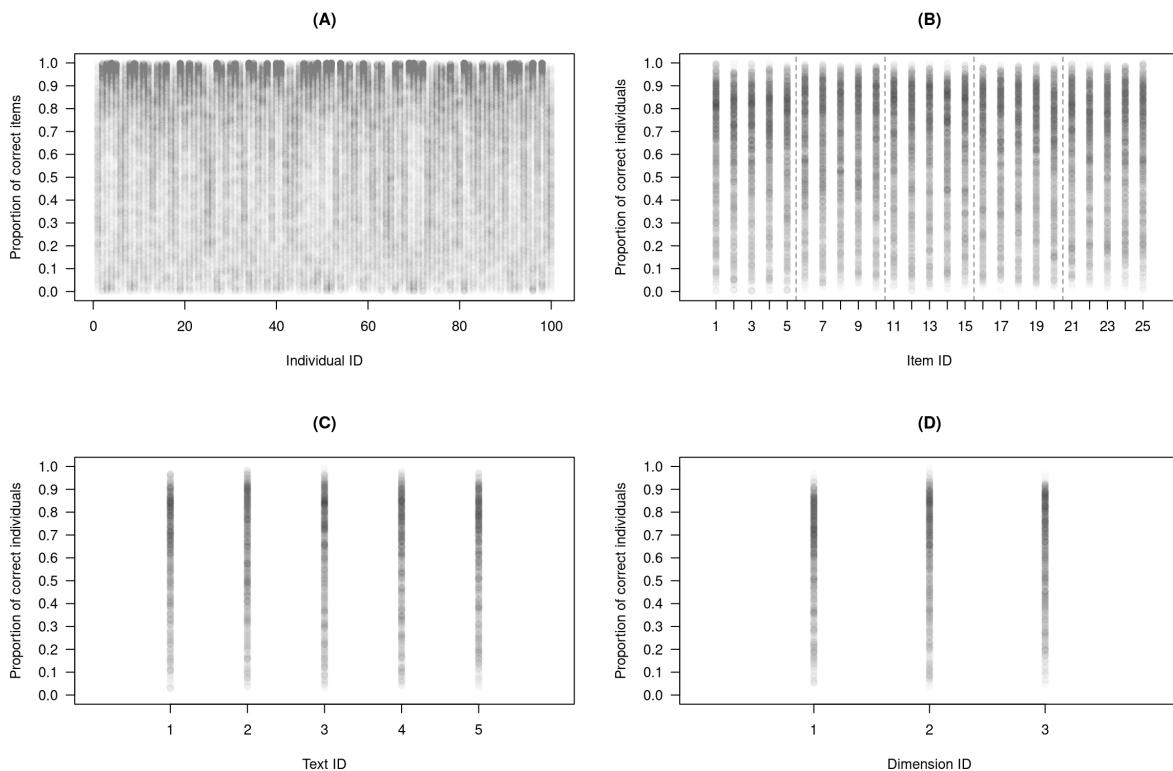


Figure A.5: Second-order latent variable model (SOLV). Aggregated endorsement rate per: (A) individuals, (B) items, (C) text or passage, and (D) measured dimension.

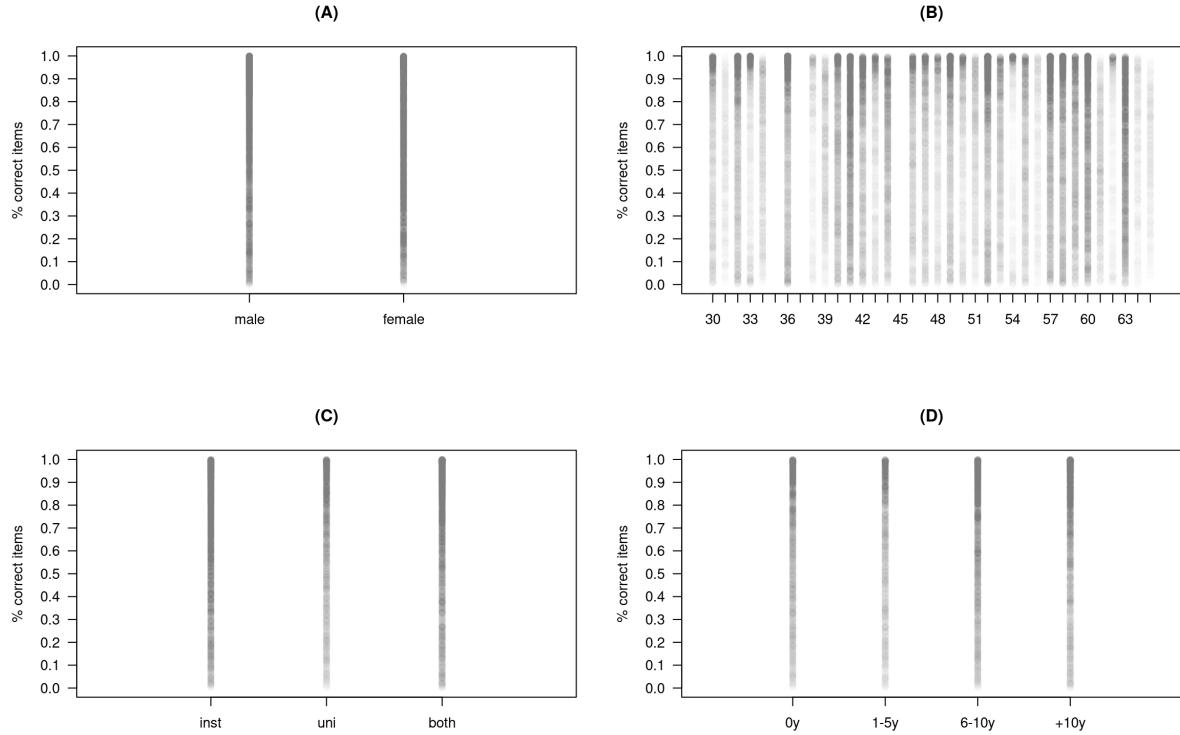


Figure A.6: Second-order latent variable model (SOLV). Aggregated endorsement rate per simulated covariate: (A) gender, (B) age, (C) education, and (D) experience.

A.2.2 Chain performance

This section shows only a small set of trace, rank and ACF plots for the parameters of interest. For all the plots across parameters, models, parametrizations, and replicas refer to the “chains” image section of the accompanying github page:

<https://github.com/jriveraespejo/thesis/tree/master/images/chains>

Similarly, the CP and NCP `n_eff` and `Rhat` comparison plots shown here is a small set of the full available plots. For the set of figures across parameters, models, and replicas refer to the “chains/stat” image section of the accompanying github page:

https://github.com/jriveraespejo/thesis/tree/master/images/chains_stat

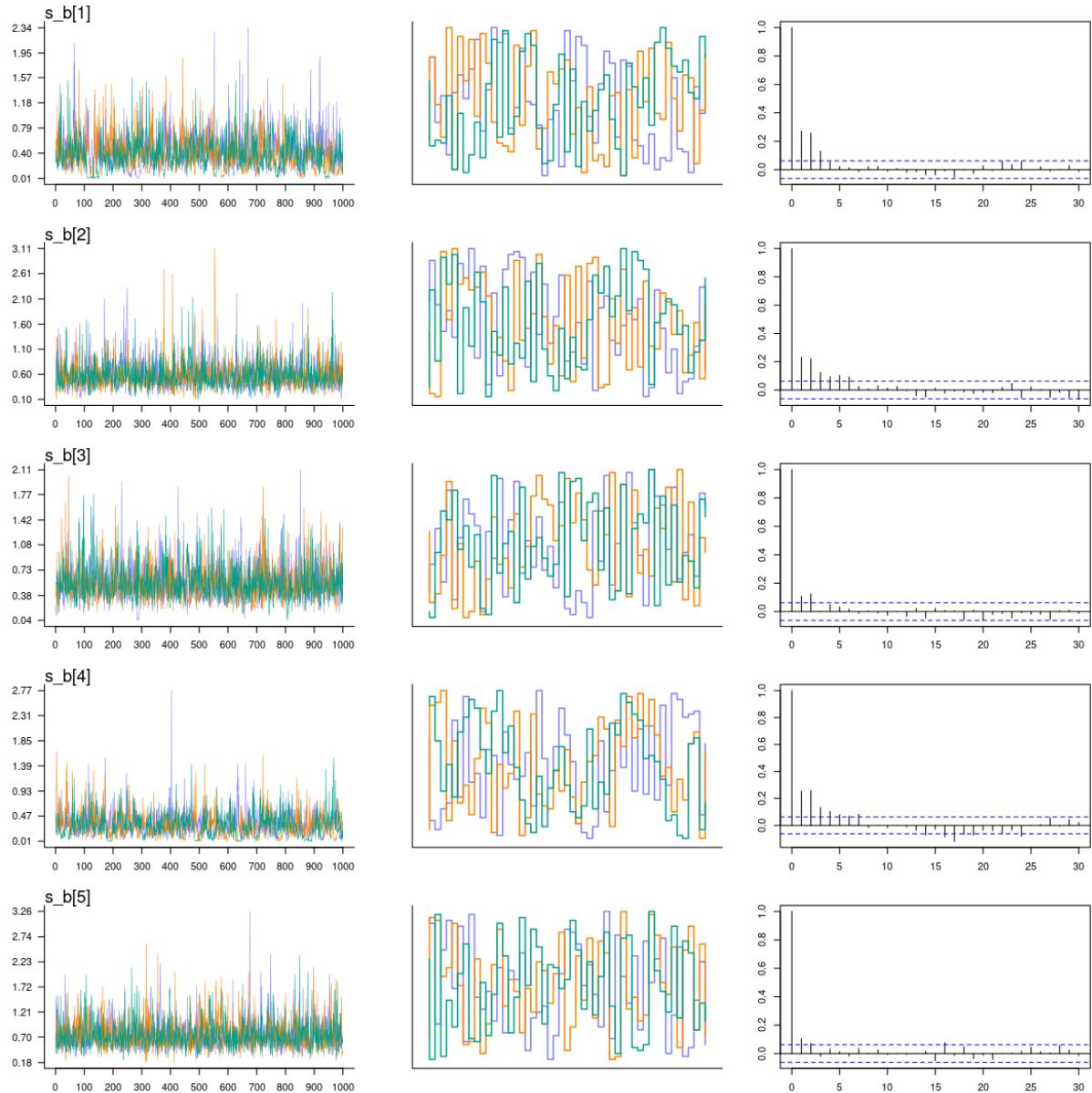


Figure A.7: First-order latent variable model (FOLV). Sample size 100, replica number 3. Centered parametrization. Difficulty deviation per text: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

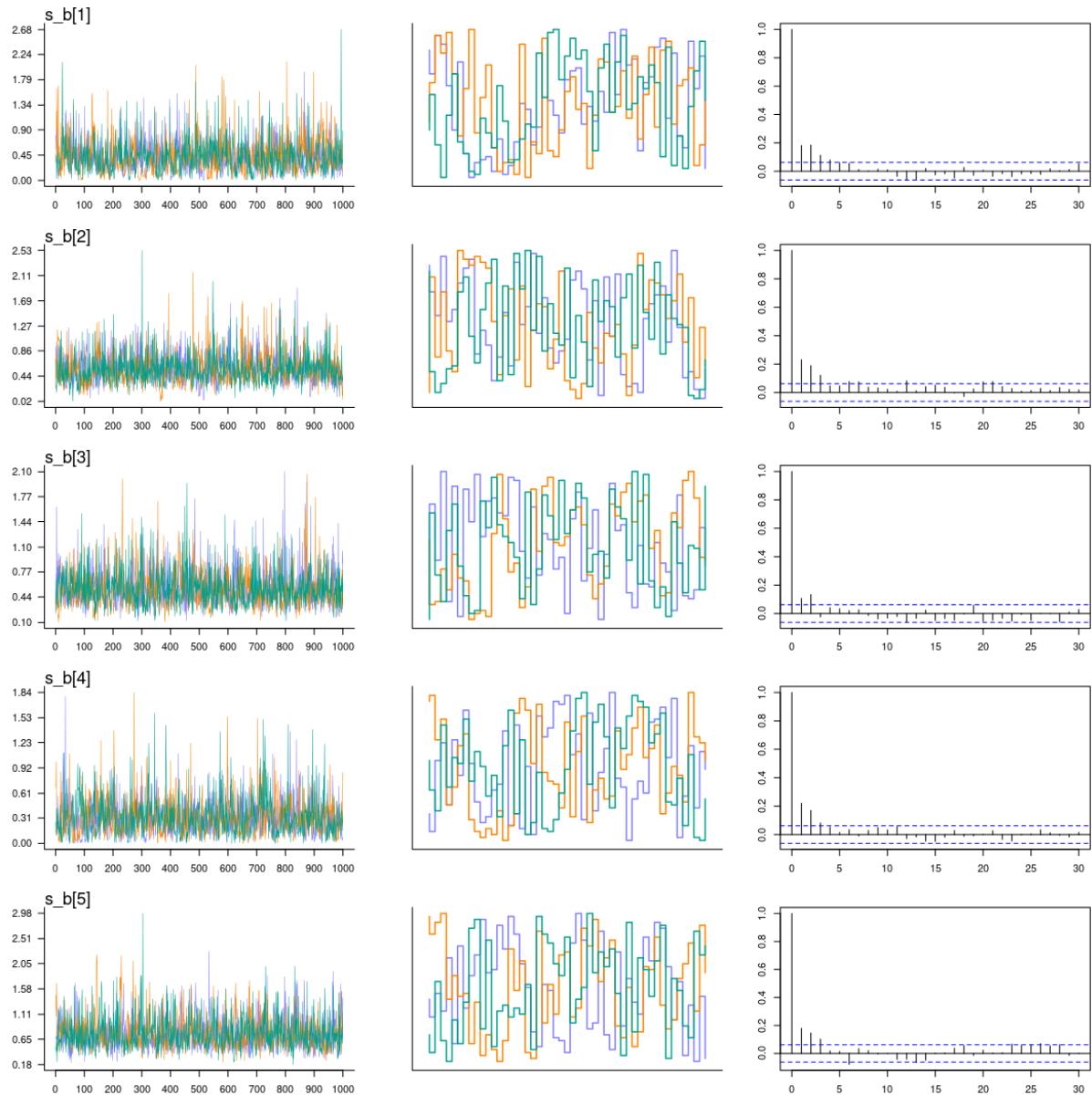


Figure A.8: First-order latent variable model (FOLV). Sample size 100, replica number 3. Non-centered parametrization. Difficulty deviation per text: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

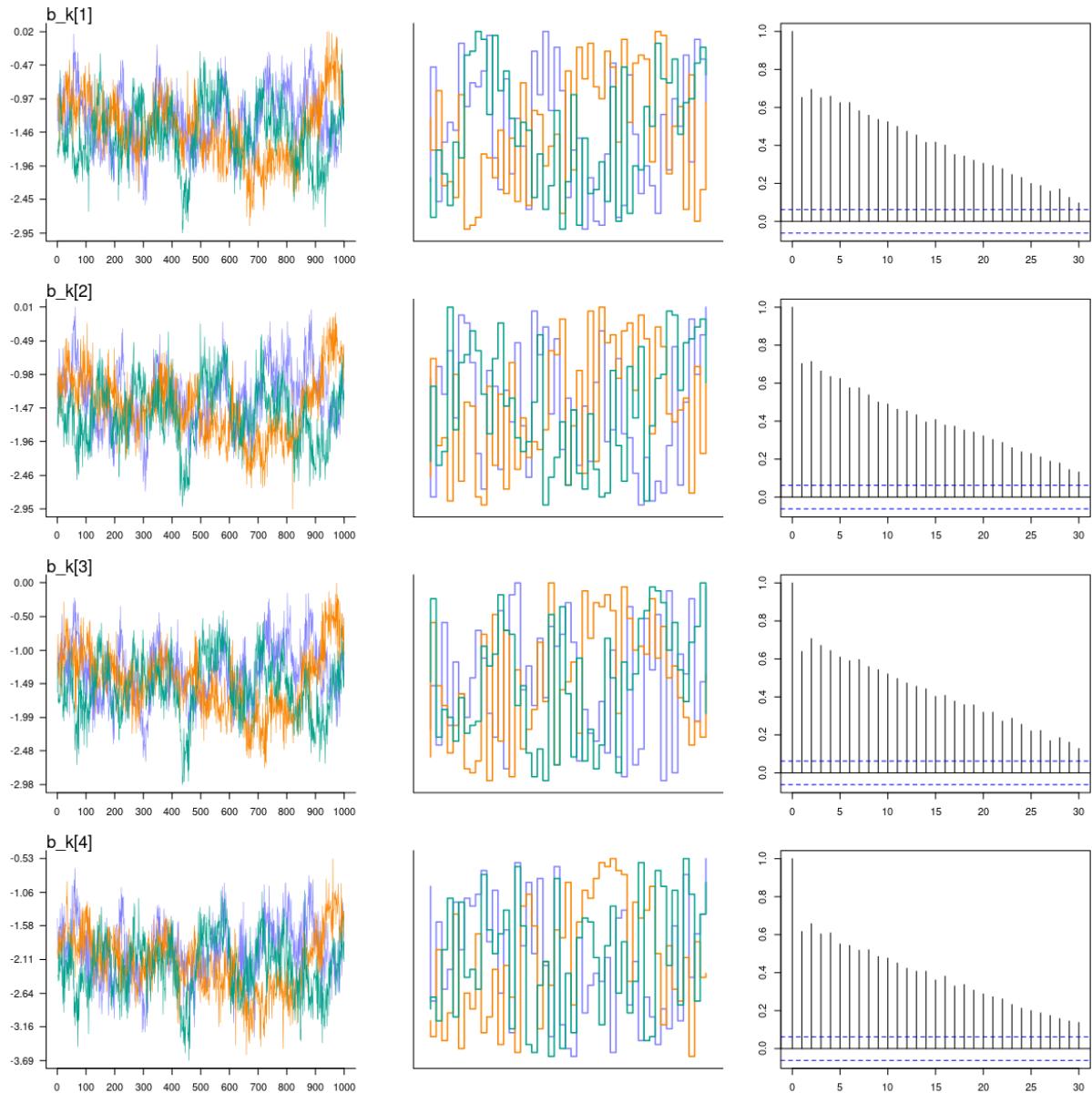


Figure A.9: First-order latent variable model (FOLV). Sample size 100, replica number 1. Centered parametrization. Difficulty per item: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

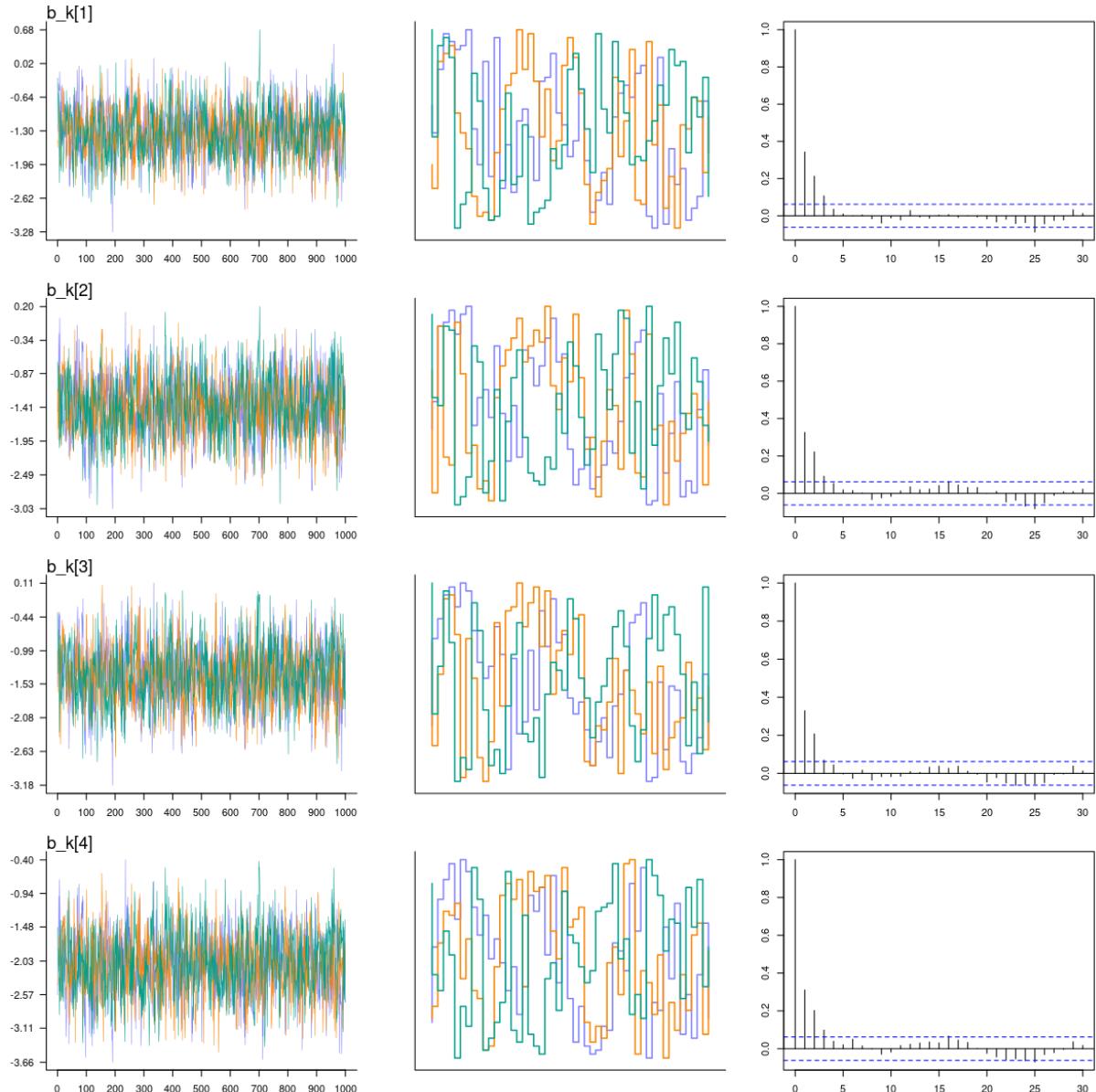


Figure A.10: First-order latent variable model (FOLV). Sample size 100, replica number 1. Non-centered parametrization. Difficulty per item: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

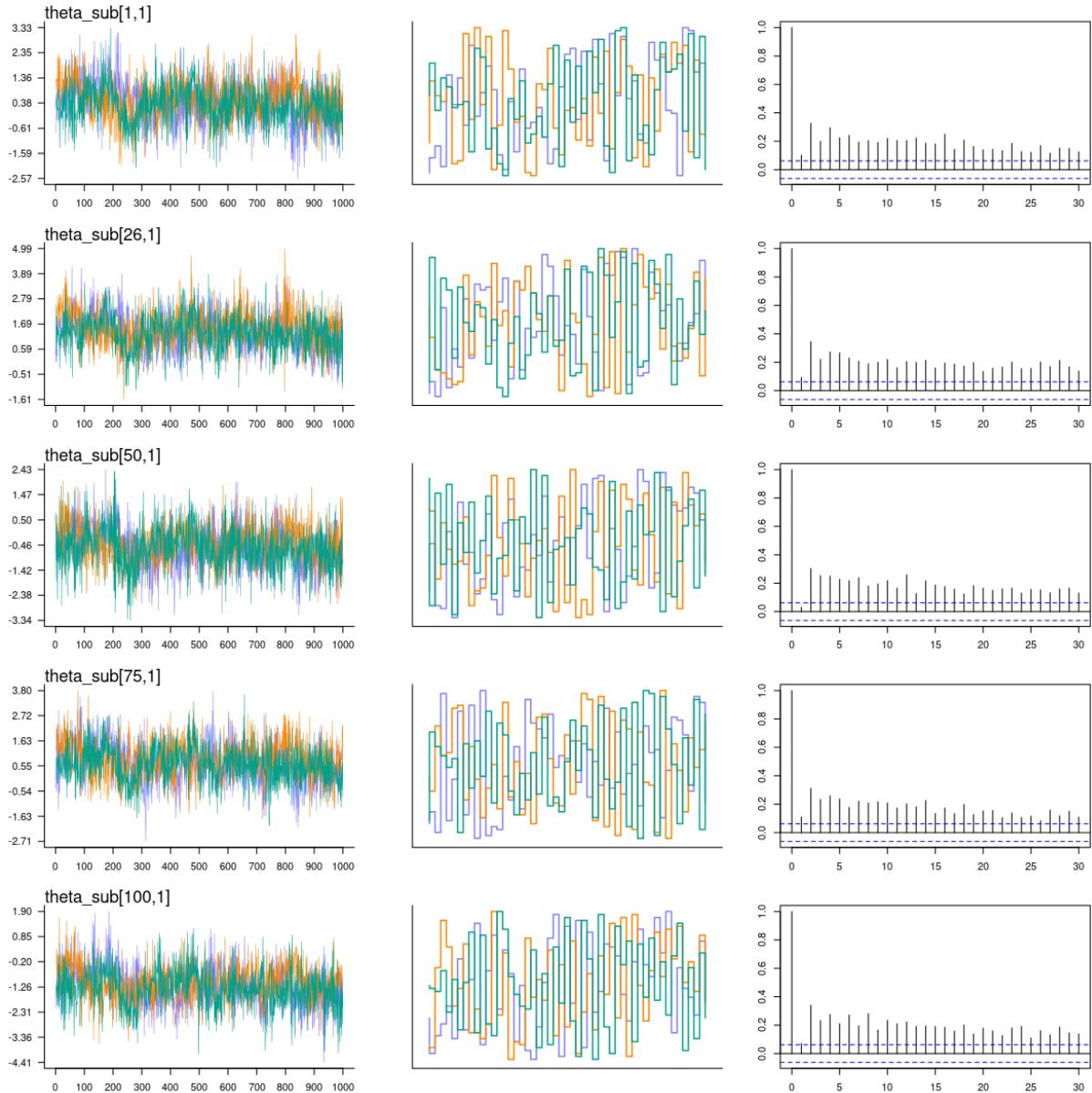


Figure A.11: First-order latent variable model (FOLV). Sample size 100, replica number 6. Centered parametrization. Individual's first sub-dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

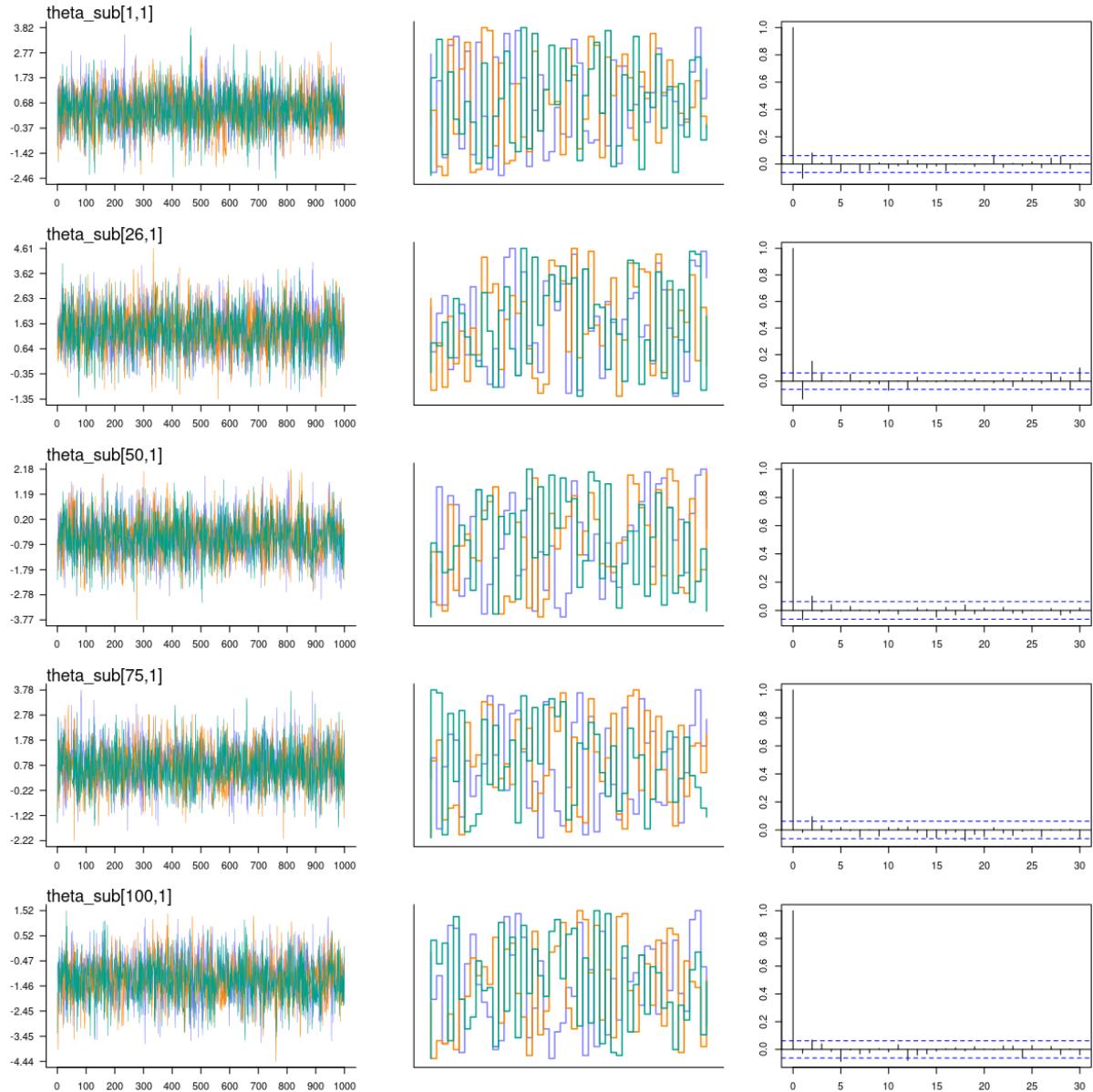


Figure A.12: First-order latent variable model (FOLV). Sample size 100, replica number 6. Non-centered parametrization. Individual's first sub-dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

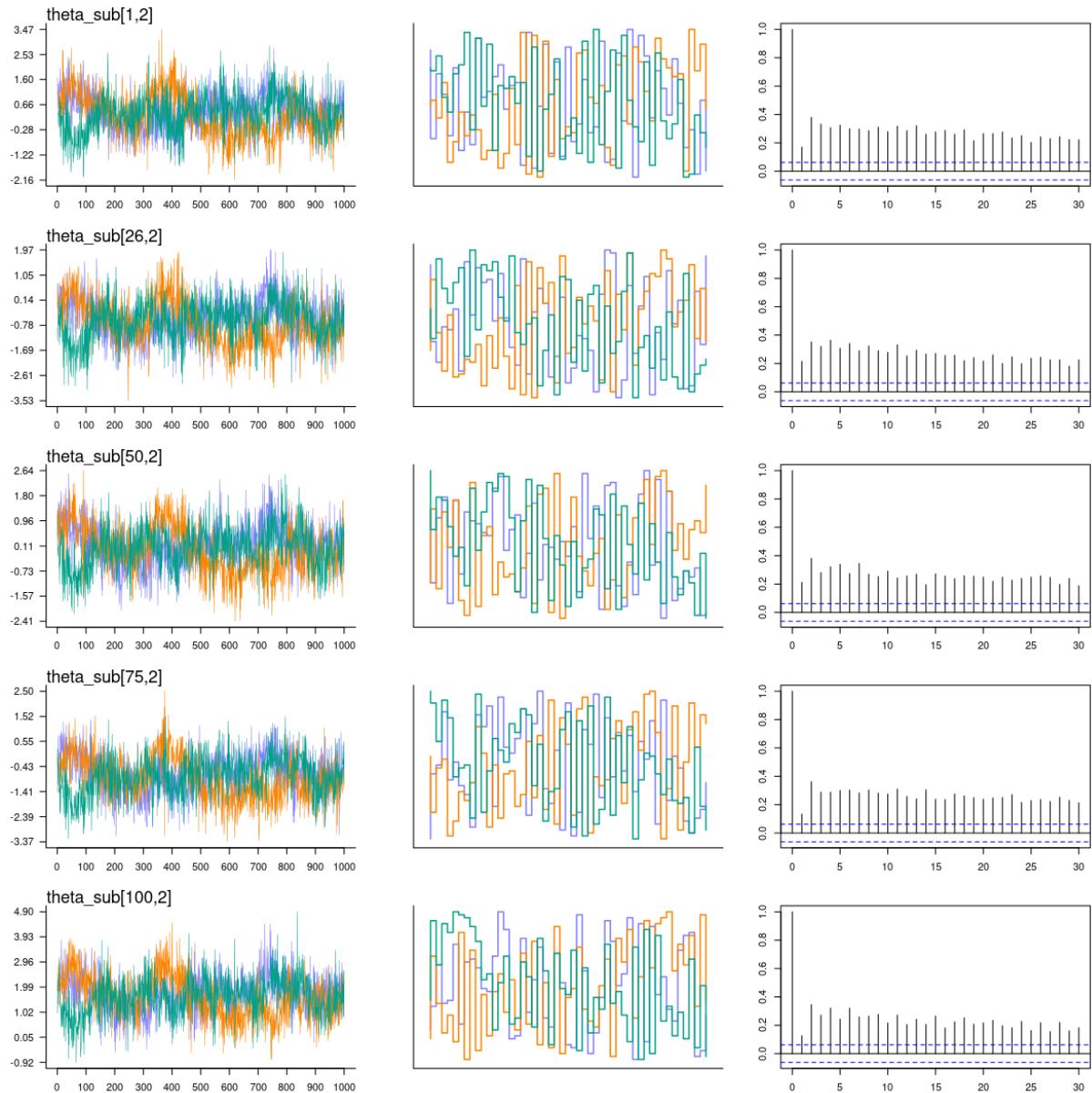


Figure A.13: First-order latent variable model (FOLV). Sample size 100, replica number 7. Centered parametrization. Individual's second sub-dimension: (Left) trace plot, (Middle) rank plot, (Right) auto-correlation plot.

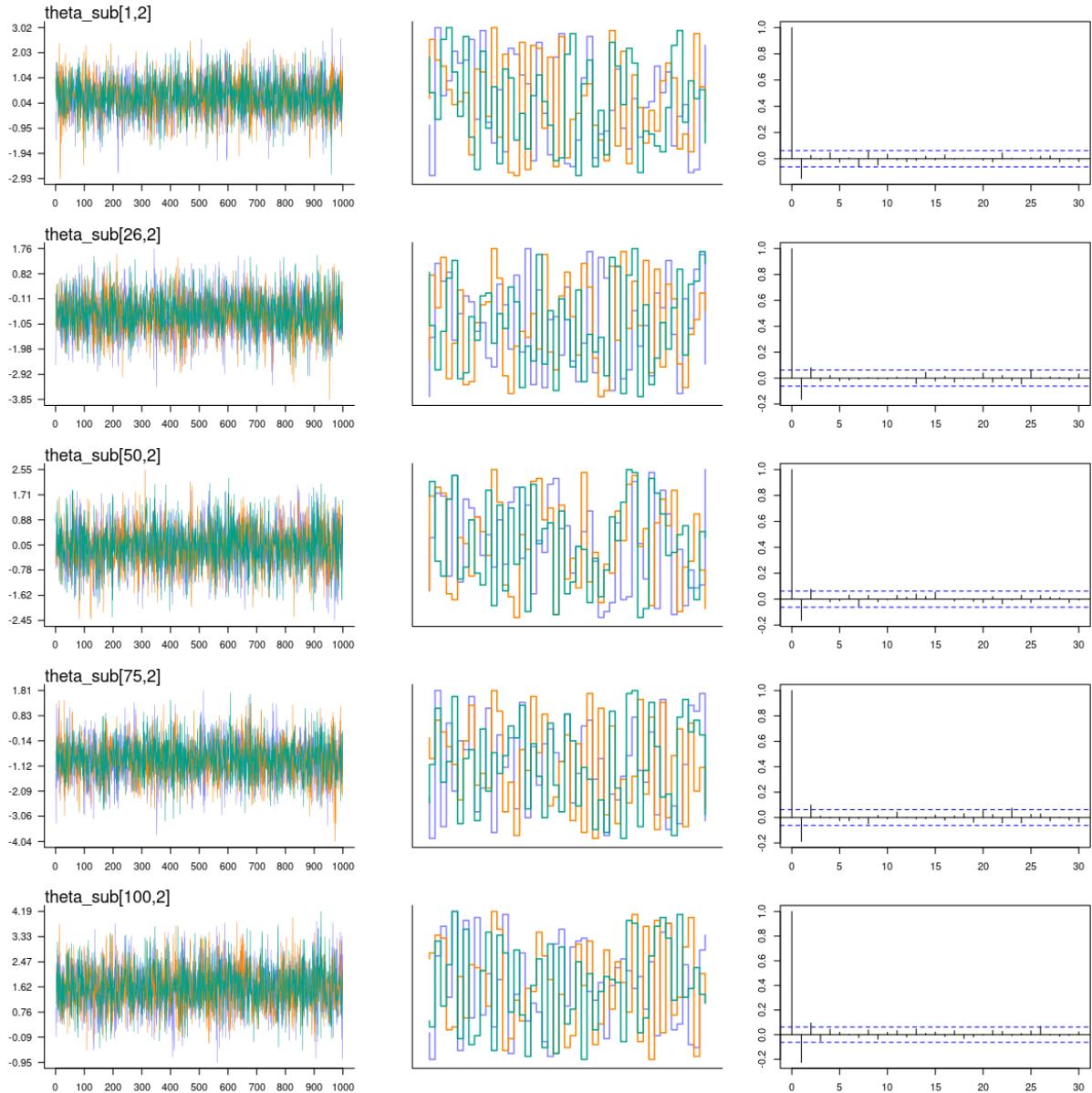


Figure A.14: First-order latent variable model (FOLV). Sample size 100, replica number 7. Non-centered parametrization. Individual's second sub-dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

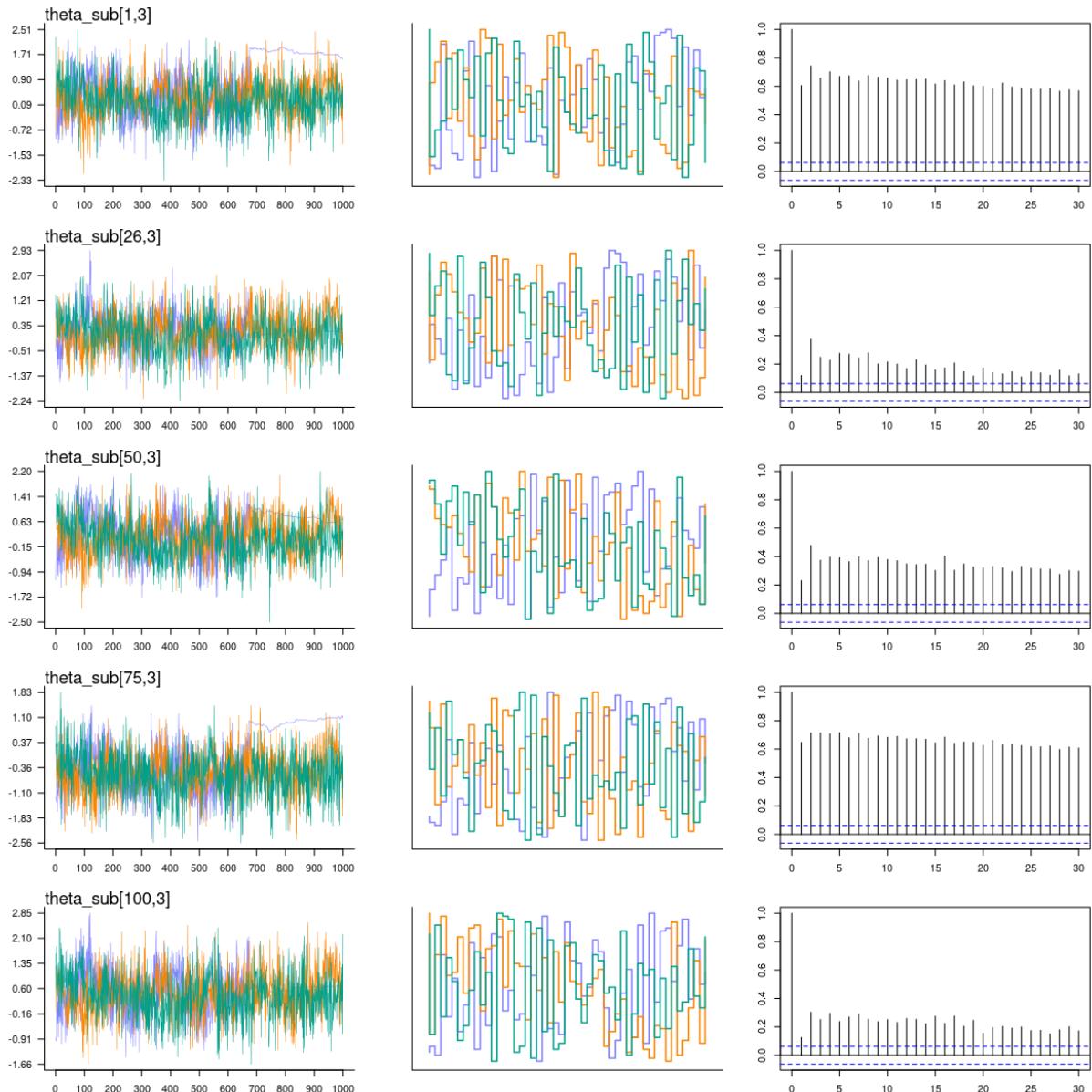


Figure A.15: First-order latent variable model (FOLV). Sample size 100, replica number 8. Centered parametrization. Individual's third sub-dimension: (Left) trace plot, (Middle) rank plot, (Right) auto-correlation plot.

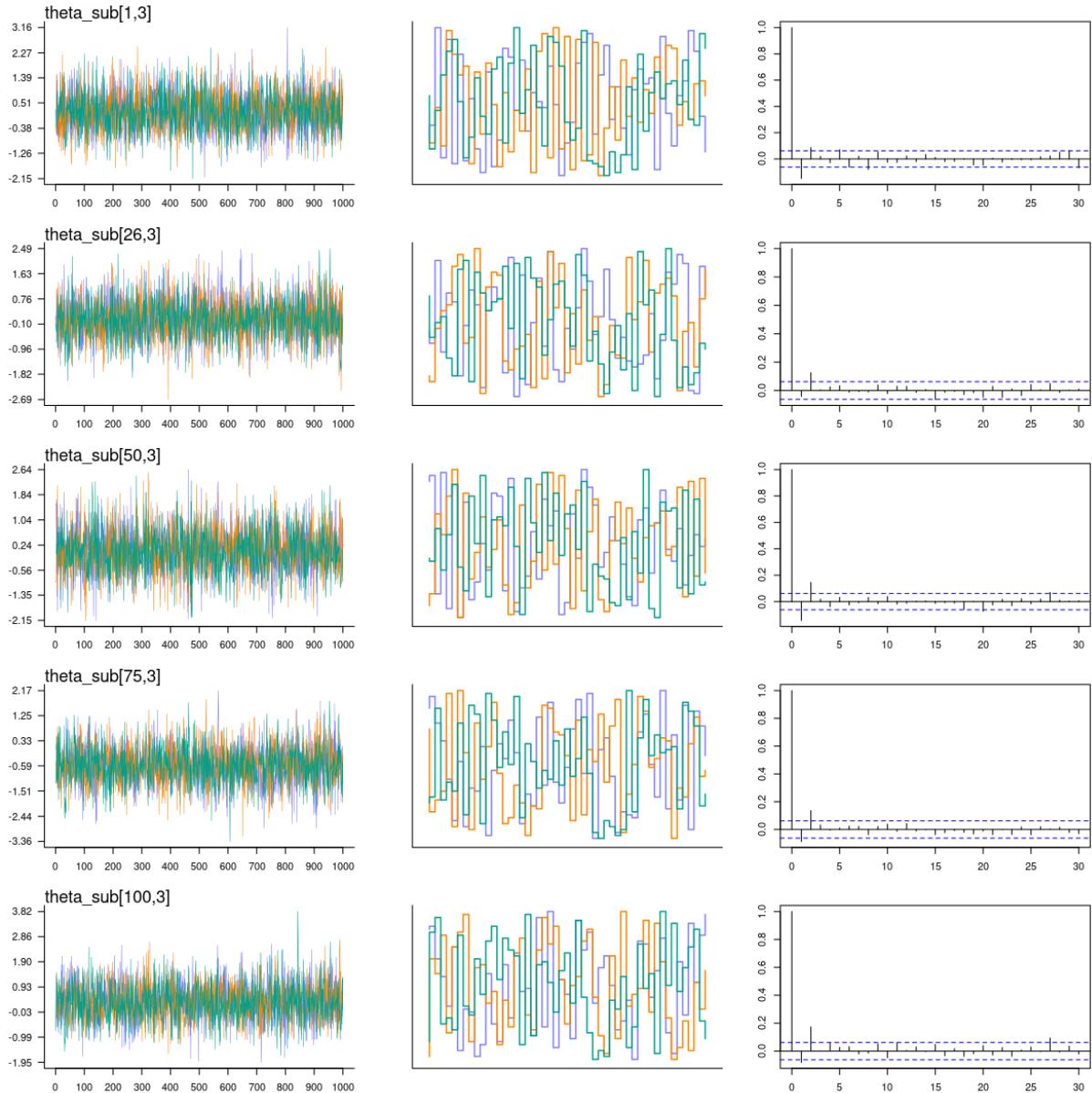


Figure A.16: First-order latent variable model (FOLV). Sample size 100, replica number 8. Non-centered parametrization. Individual's third sub-dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

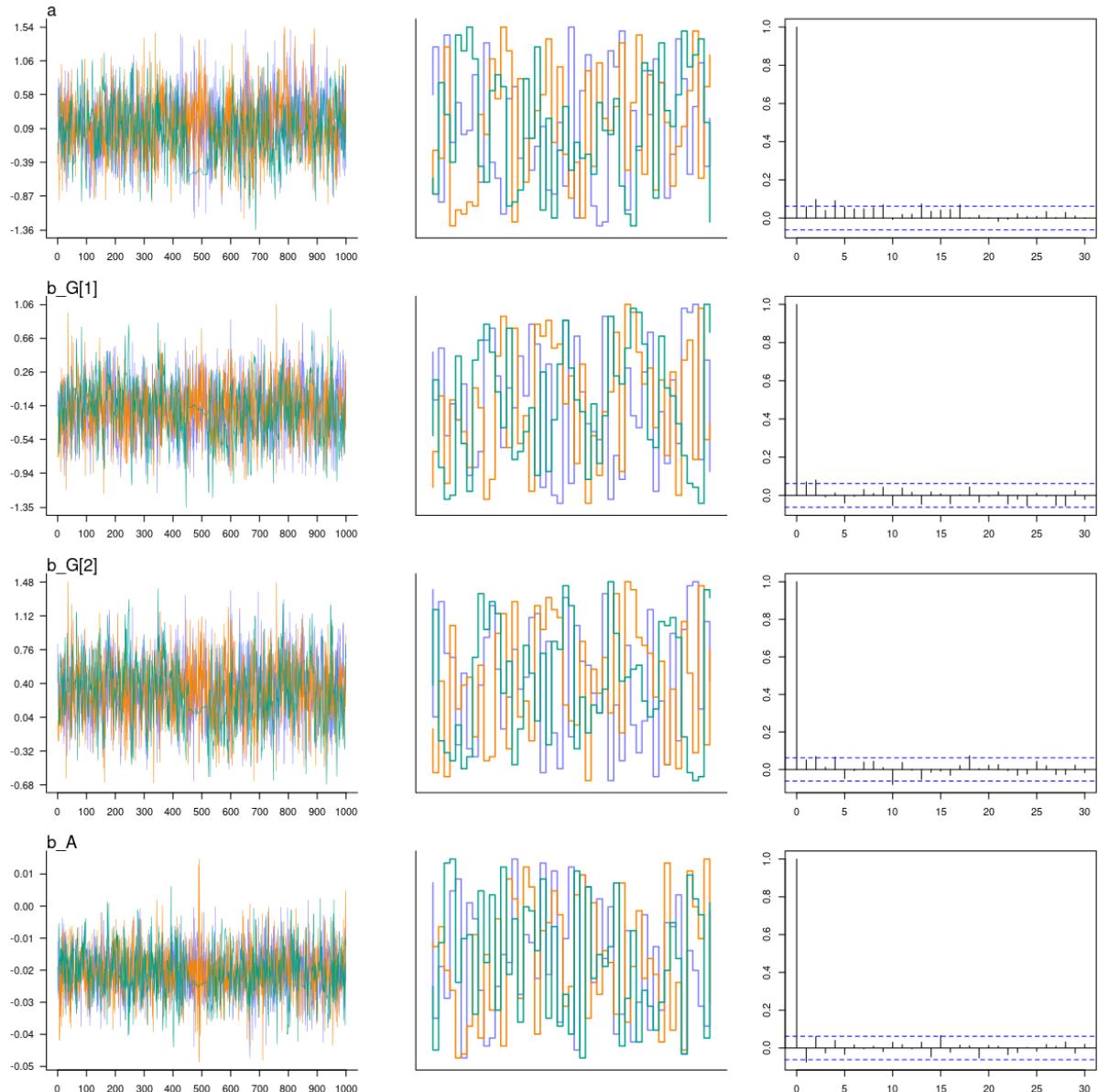


Figure A.17: First-order latent variable model (FOLV). Sample size 100, replica number 4. Centered parametrization. Regression parameters: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

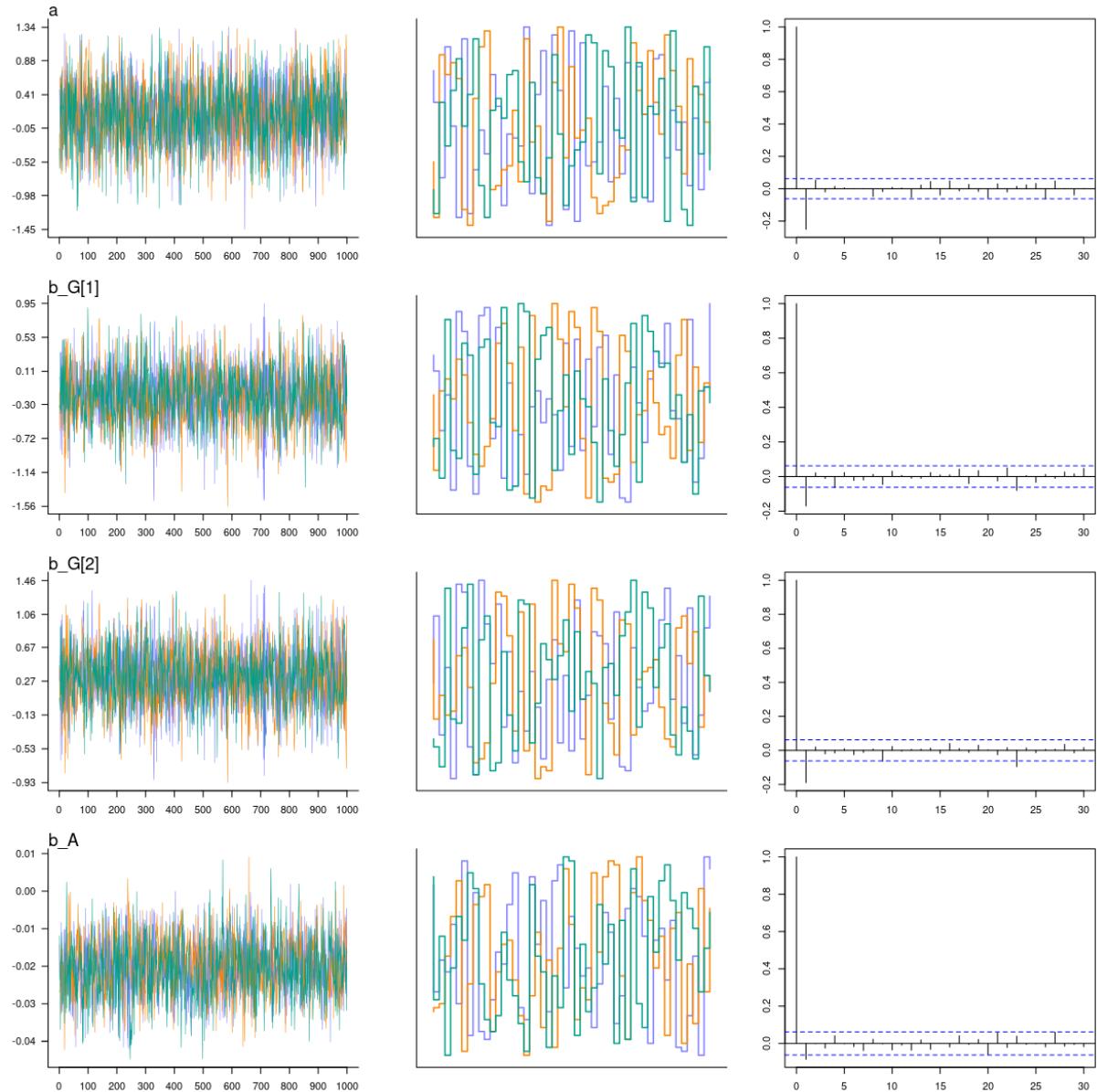


Figure A.18: First-order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Regression parameters: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

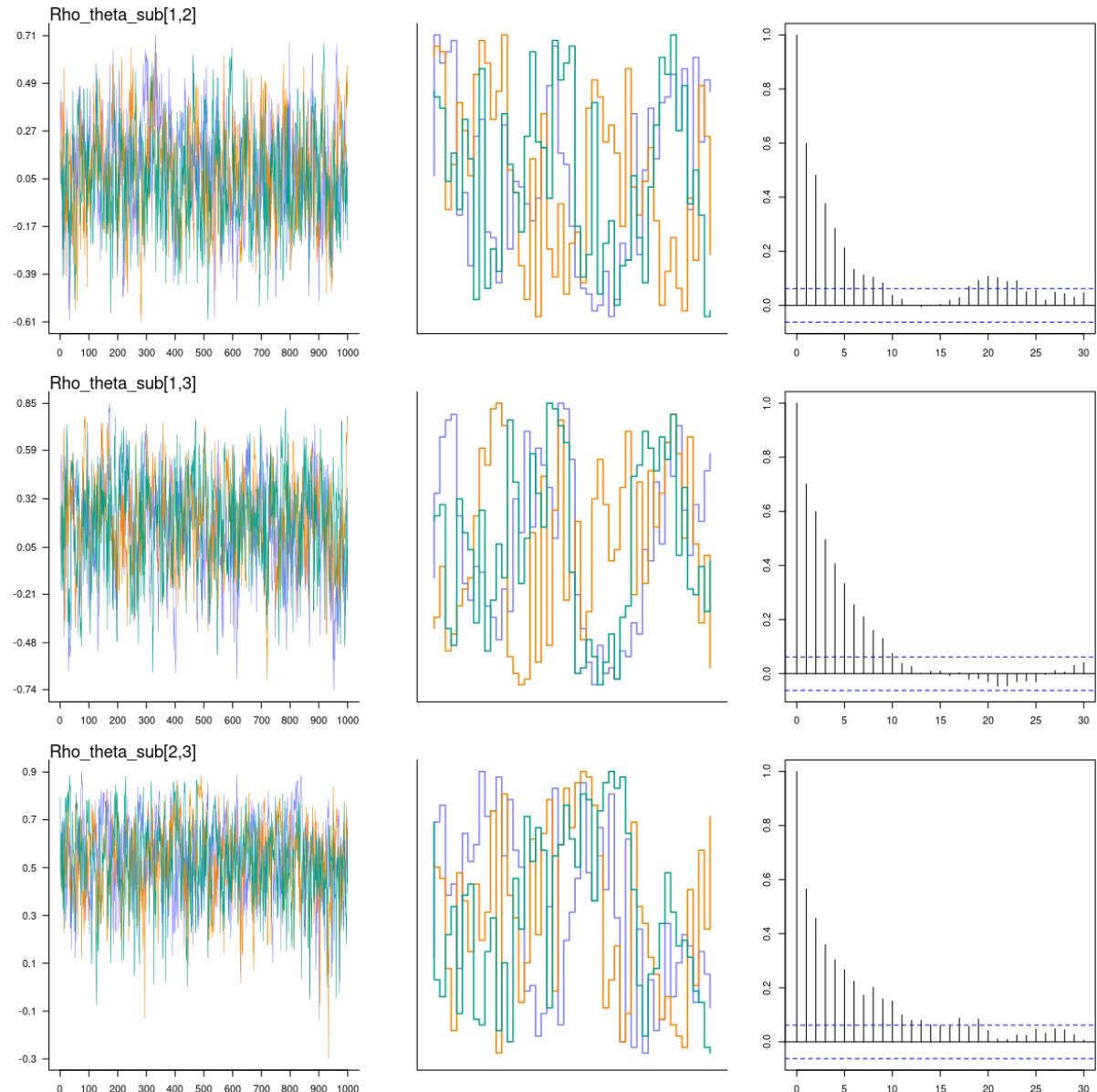


Figure A.19: First-order latent variable model (FOLV). Sample size 100, replica number 5. Centered parametrization. Correlation of sub-dimensions: (Left) trace plot, (Middle) rank plot, (Right) auto-correlation plot.

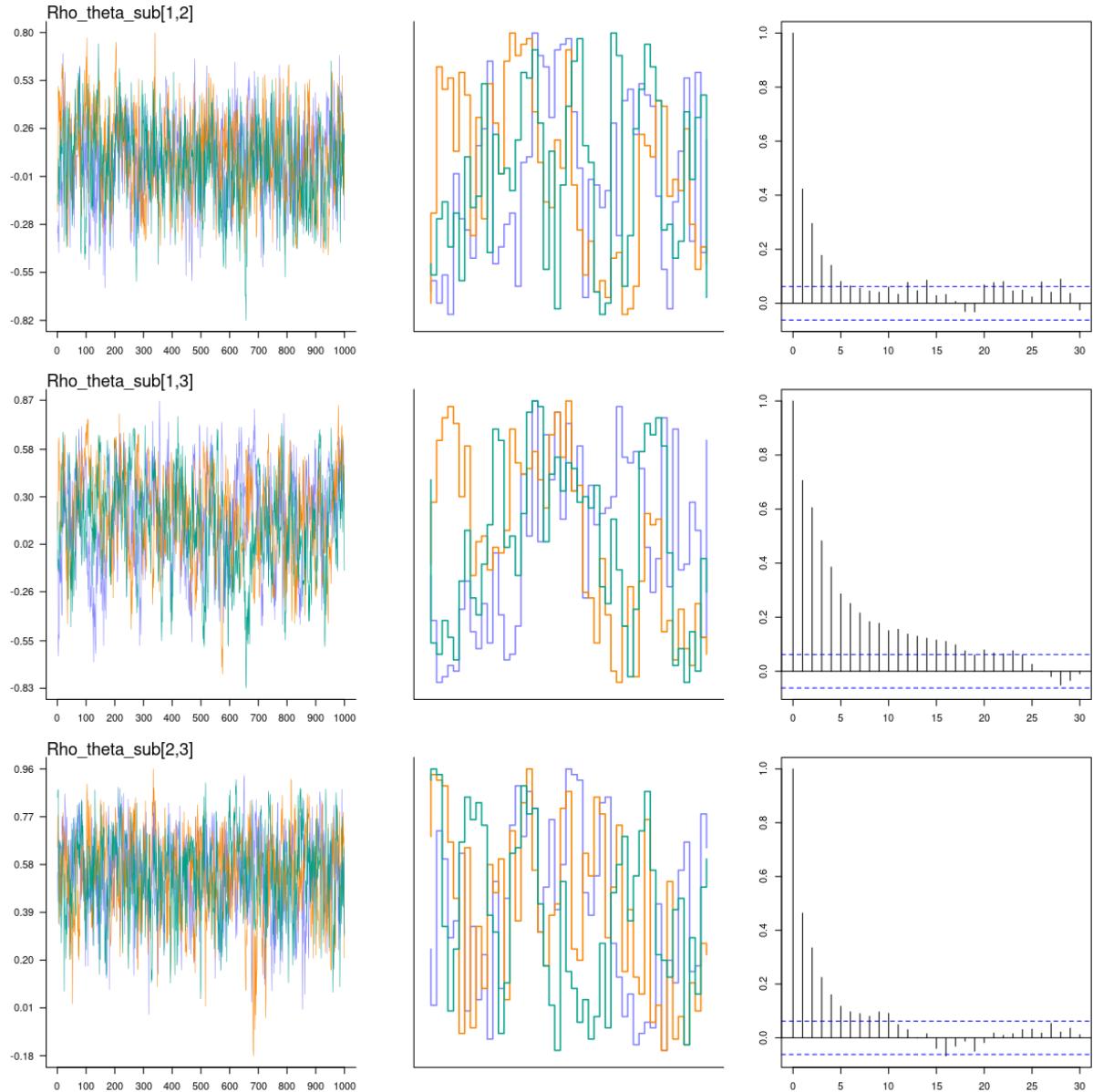


Figure A.20: First-order latent variable model (FOLV). Sample size 100, replica number 5. Non-centered parametrization. Correlation of sub-dimensions: (Left) trace plot, (Middle) rank plot, (Right) auto-correlation plot.

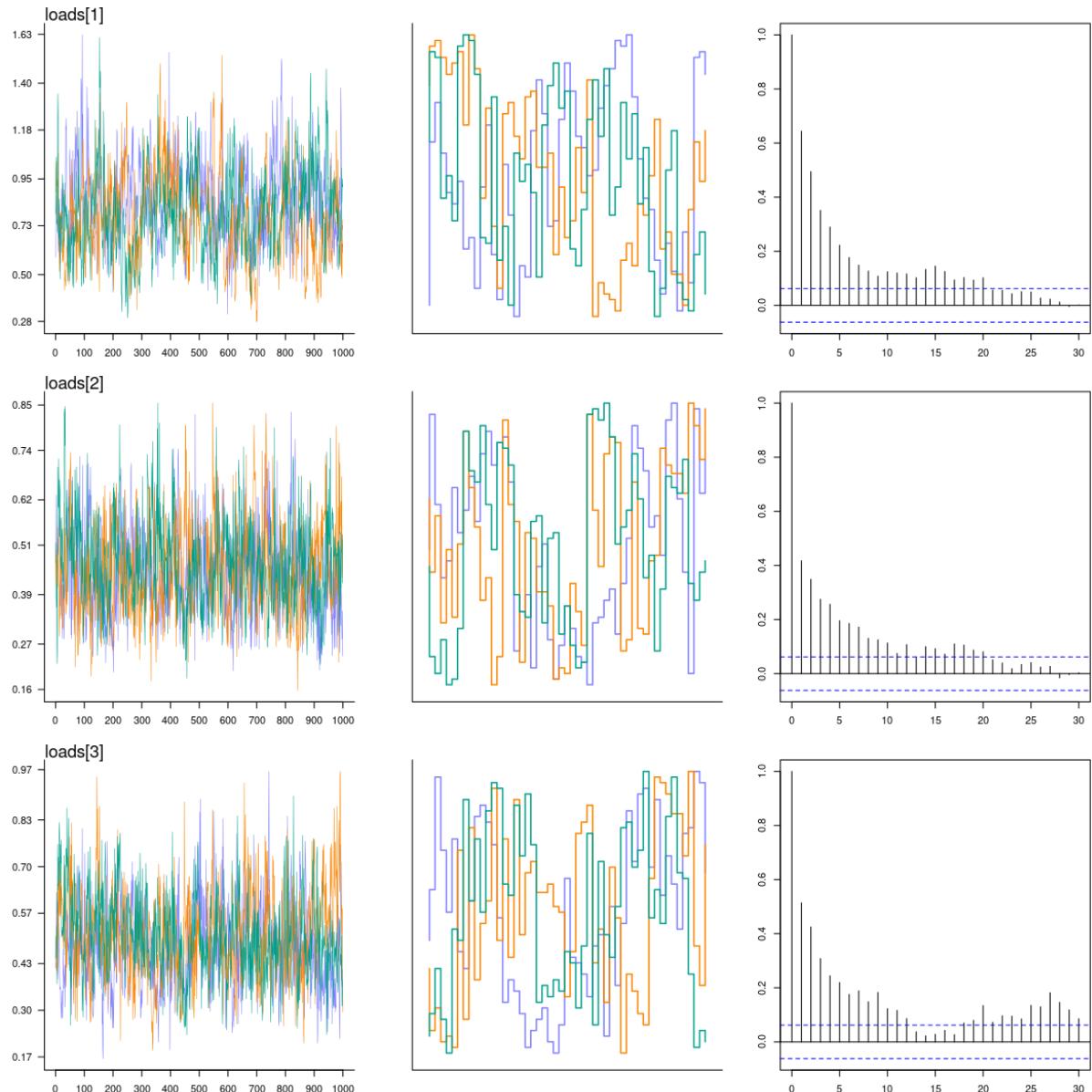


Figure A.21: Second-order latent variable model (SOLV). Sample size 100, replica number 9. Centered parametrization. Loadings: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

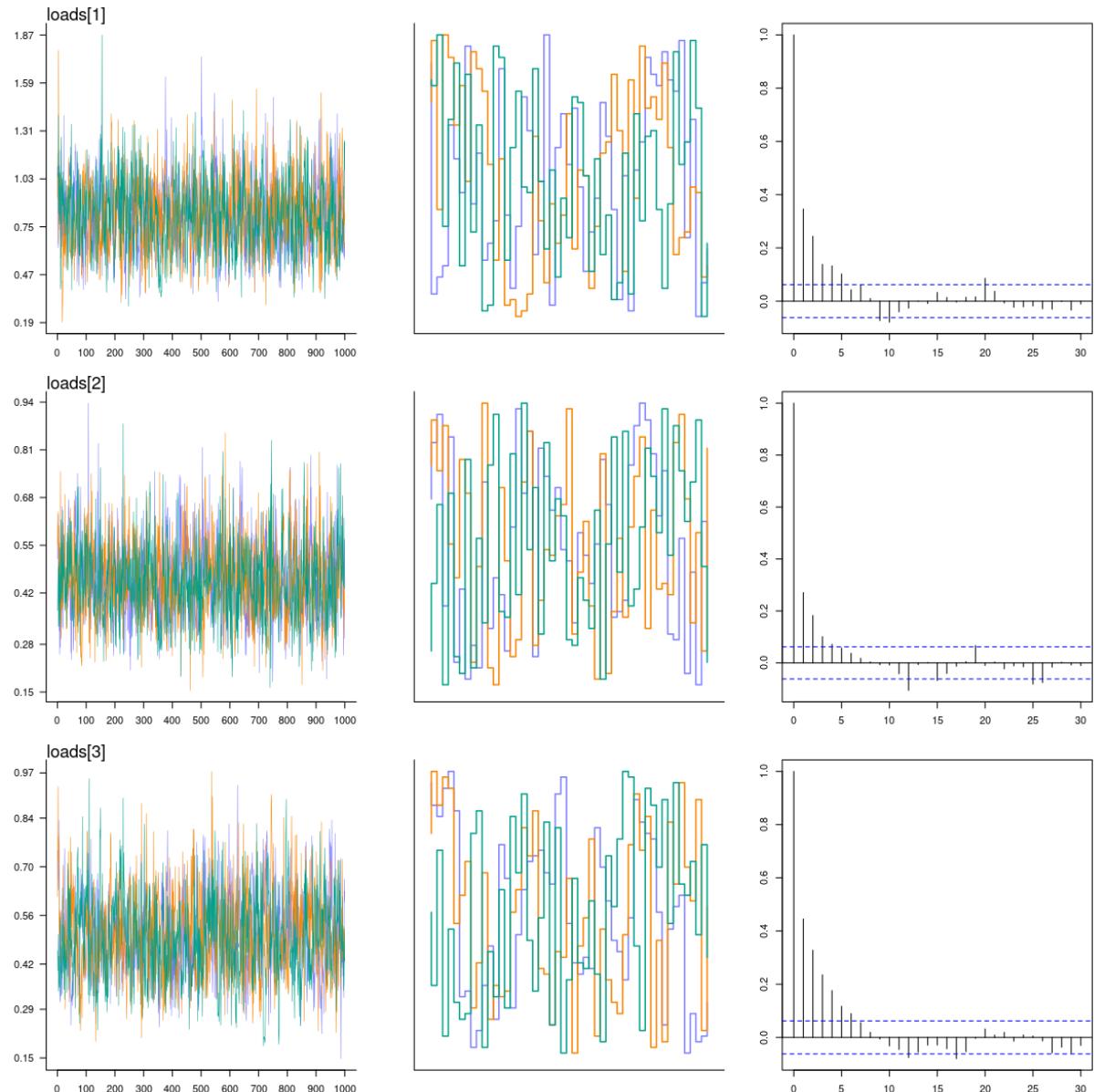


Figure A.22: Second-order latent variable model (SOLV). Sample size 100, replica number 9. Non-centered parametrization. Loadings: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

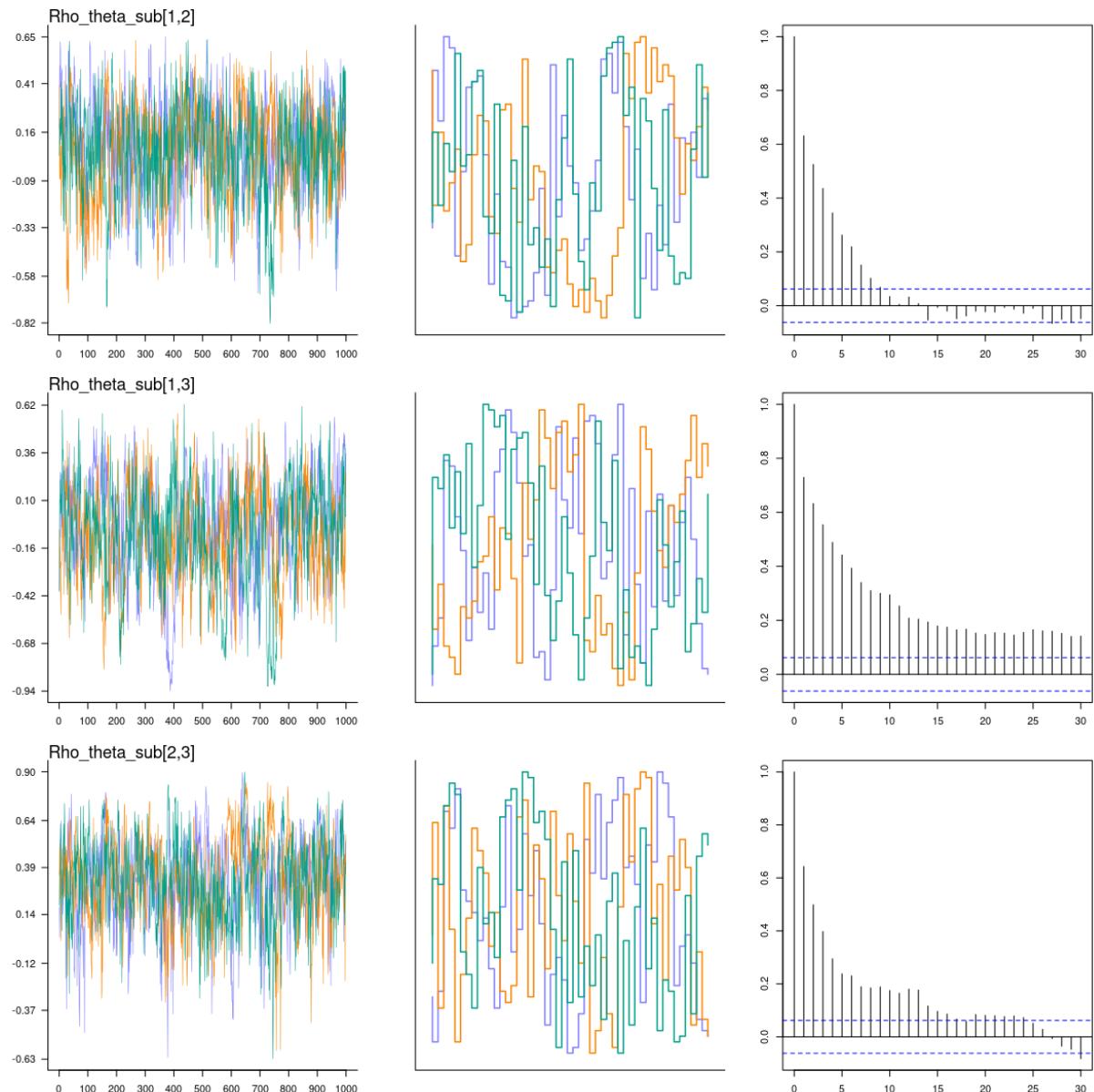


Figure A.23: Second-order latent variable model (SOLV). Sample size 100, replica number 1. Centered parametrization. Correlation of sub-dimensions: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

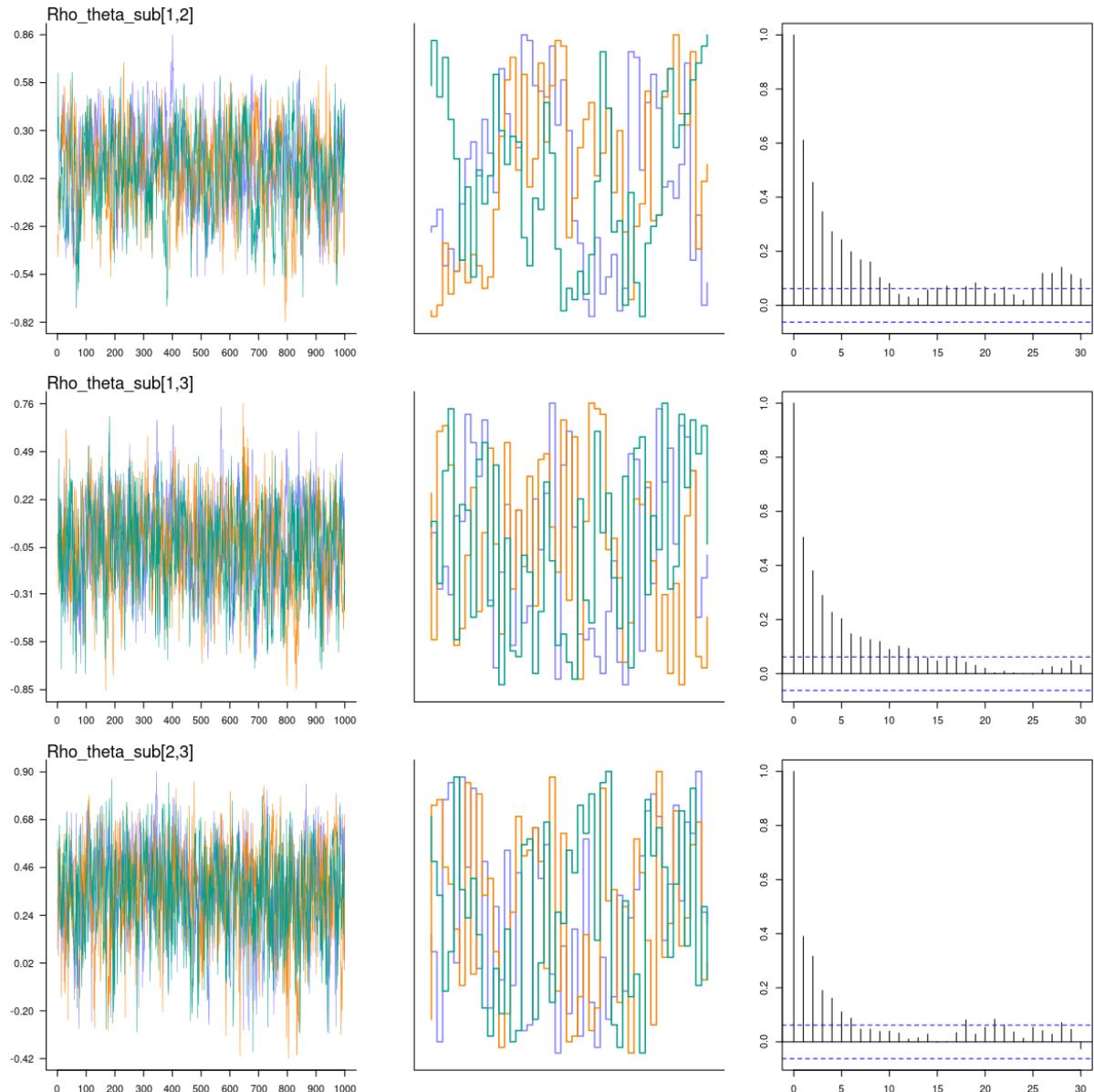


Figure A.24: Second-order latent variable model (SOLV). Sample size 100, replica number 1. Non-centered parametrization. Correlation of sub-dimensions: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

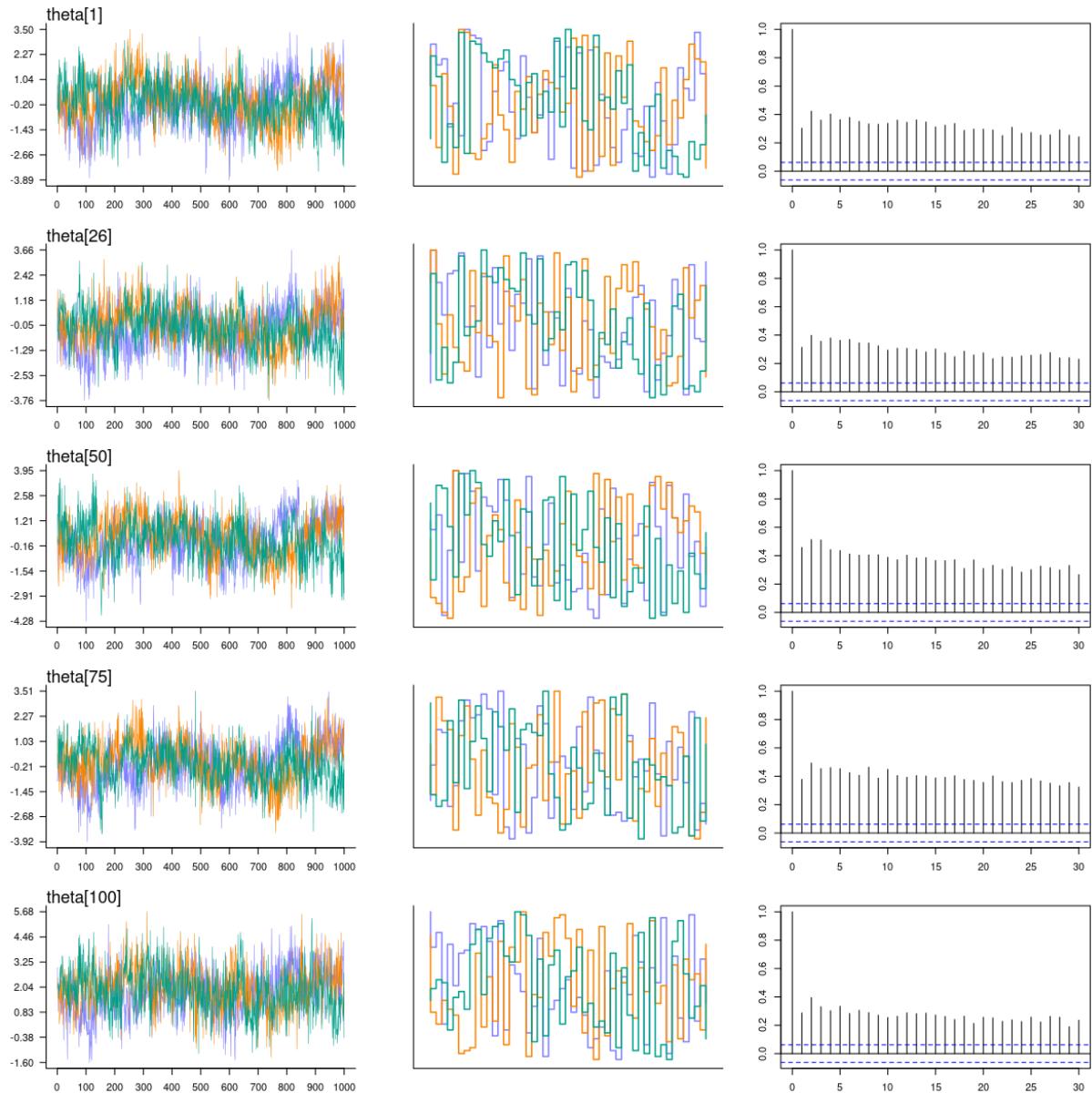


Figure A.25: Second-order latent variable model (SOLV). Sample size 100, replica number 10. Centered parametrization. Highest-order dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

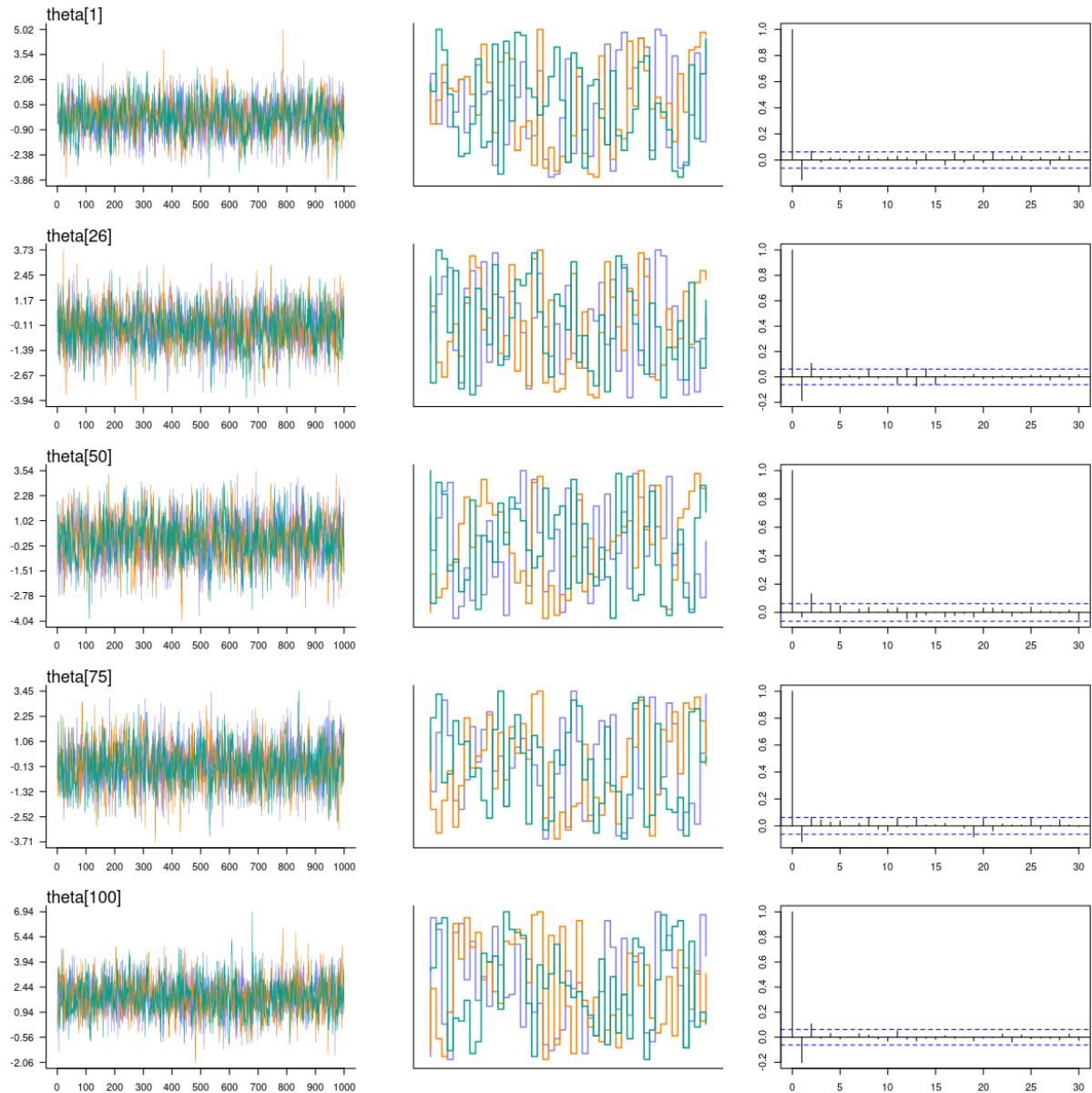


Figure A.26: Second-order latent variable model (SOLV). Sample size 100, replica number 10. Non-centered parametrization. Highest-order dimension: (Left) trace plot, (Middle) trunk plot, (Right) auto-correlation plot.

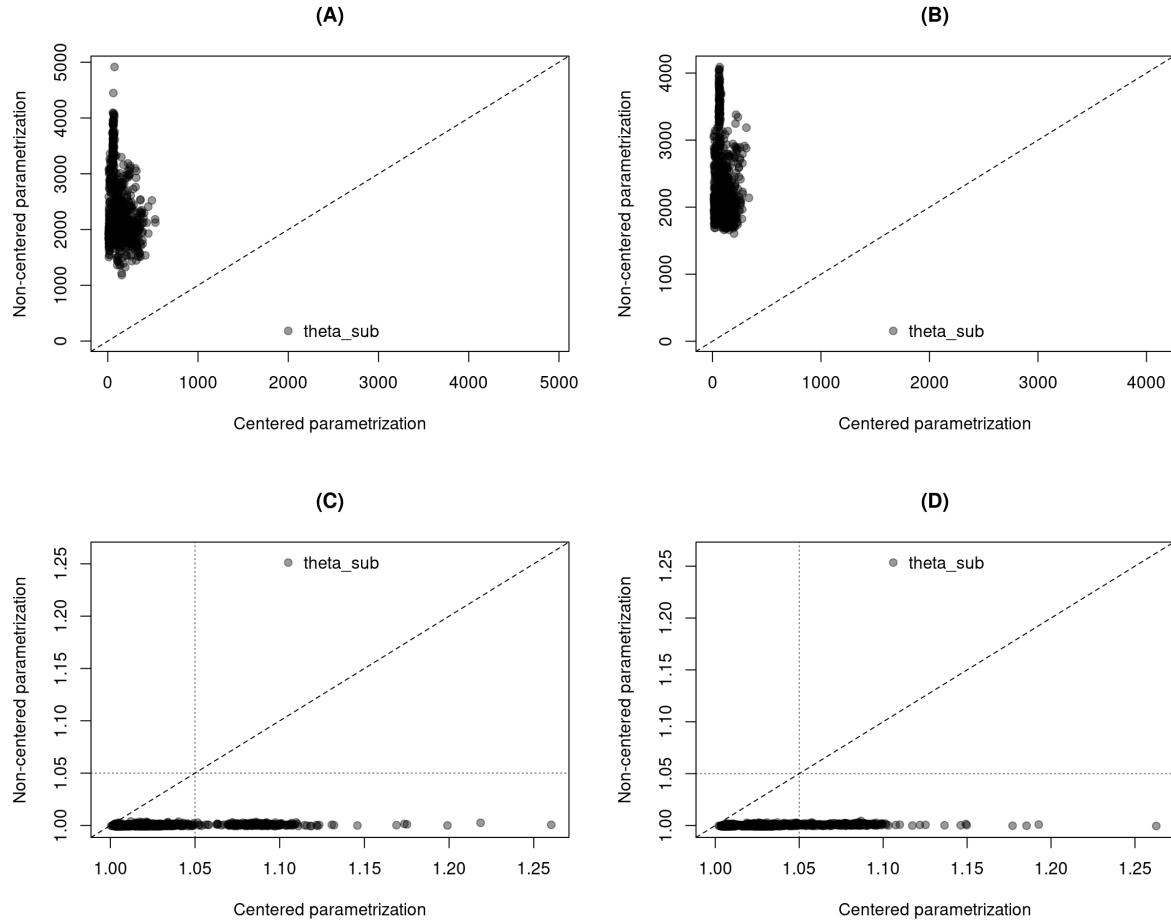


Figure A.27: First-order latent variable model (FOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) n_{eff} for the first sub-dimension. (B) n_{eff} for the second sub-dimensions. (C) Rhat for the first sub-dimension. (D) Rhat for the second sub-dimensions. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $\text{Rhat} = 1.05$.

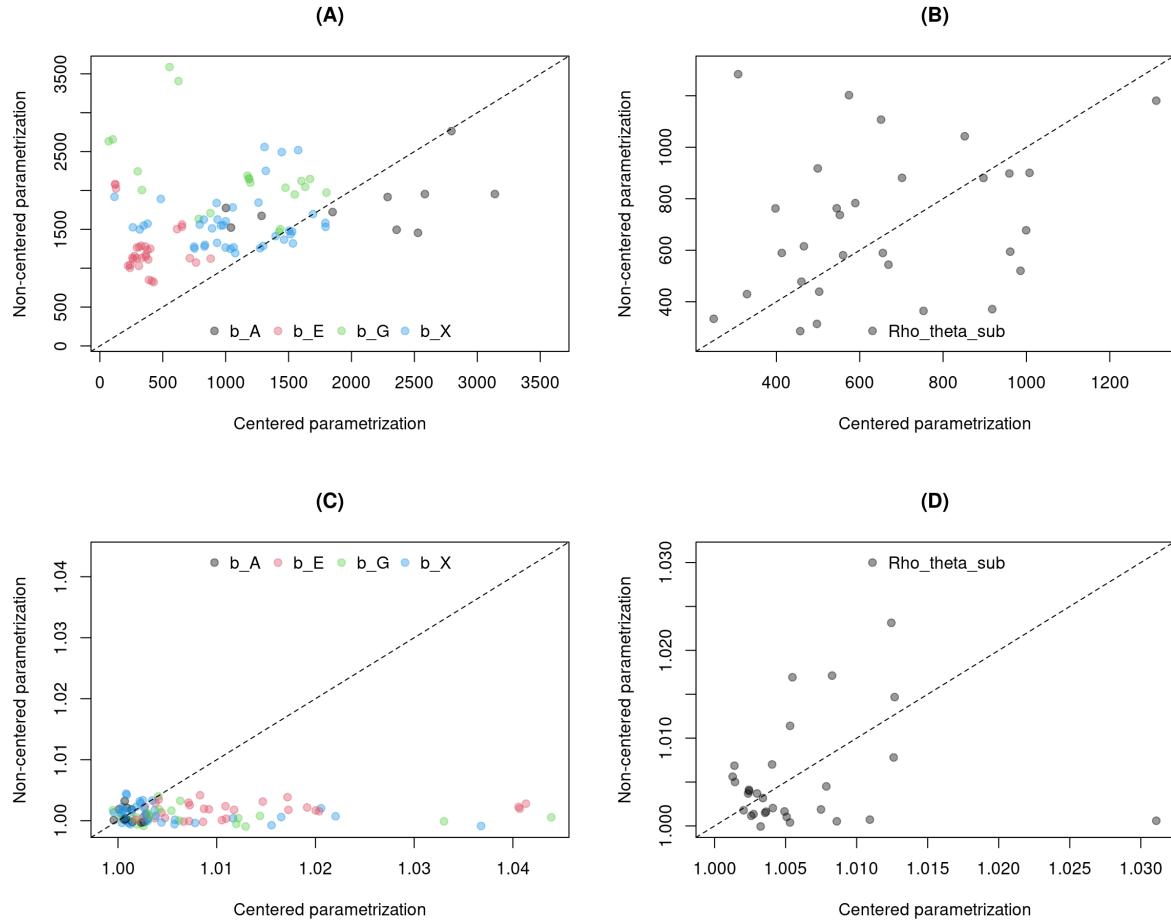


Figure A.28: First-order latent variable model (FOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) n_{eff} for regression parameters. (B) n_{eff} for correlations among sub-dimensions. (C) $Rhat$ for regression parameters. (D) $Rhat$ for correlations among sub-dimensions. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $Rhat = 1.05$.

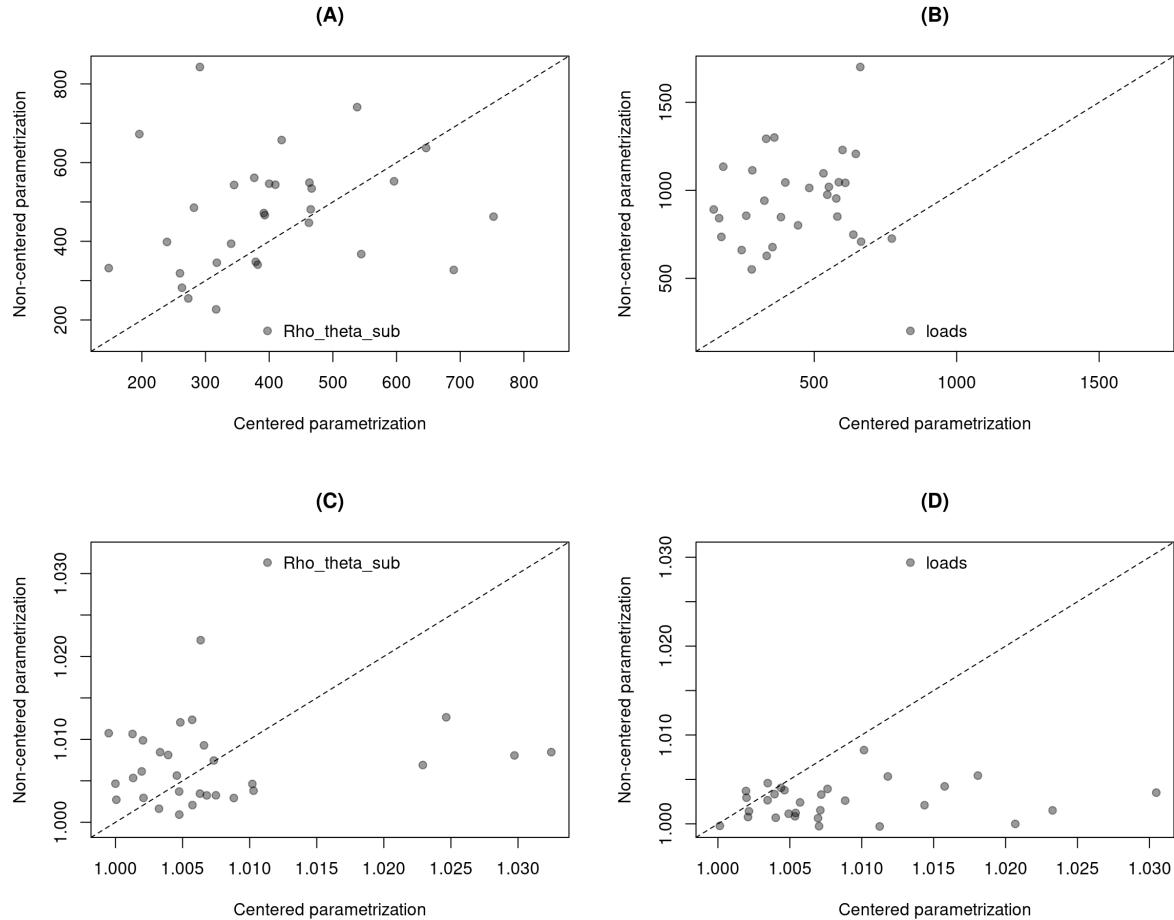


Figure A.29: Second-order latent variable model (SOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) n_{eff} for the correlations among sub-dimension. (B) n_{eff} for the loadings. (C) Rhat for the correlation among sub-dimensions. (D) Rhat for the loadings. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $\text{Rhat} = 1.05$.

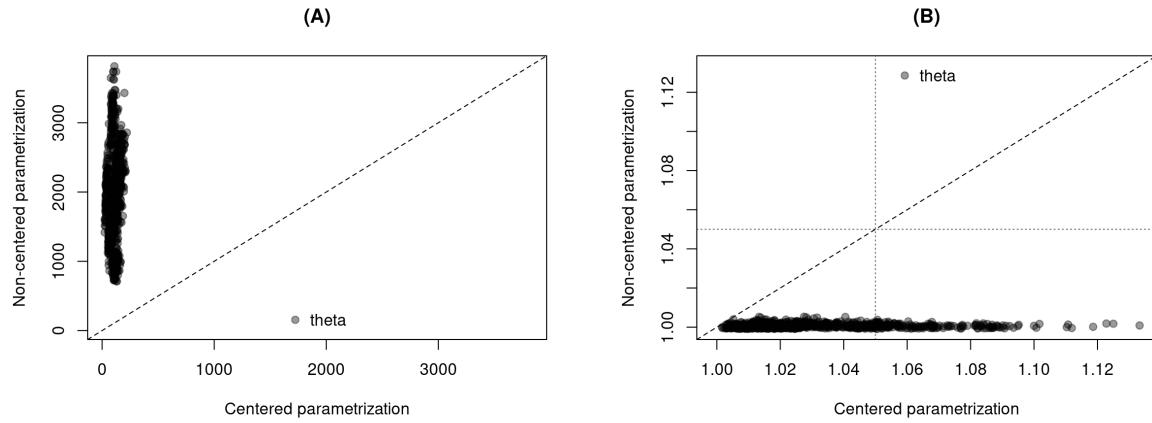


Figure A.30: Second-order latent variable model (SOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) n_{eff} for the higher-order latent variable. (B) $Rhat$ for the higher-order latent variable. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $Rhat = 1.05$.

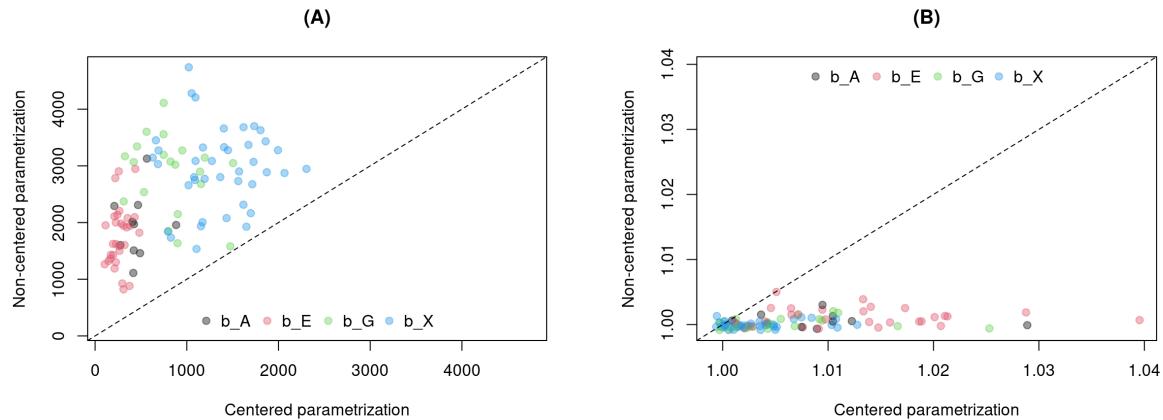


Figure A.31: Second-order latent variable model (SOLV). Sample size 100, all replicas. CP and NCP comparison plot. (A) n_{eff} for regression parameters. (B) $Rhat$ for the first sub-dimension. (C) $Rhat$ for regression parameters. (D) $Rhat$ for the second sub-dimensions. Diagonal discontinuous line describes equality between CP and NCP. Vertical and horizontal discontinuous lines is set at $Rhat = 1.05$.

A.2.3 Recovery capacity

This section shows only a small set of tables about the recovery capacity of the model. In case the reader wants to replicate the calculations or access the full set of statistics refer to the “data/tables” section of the accompanying github page:

https://github.com/jriveraespejo/thesis/tree/master/data_tables

Moreover, in case the reader wants to inspect the recovery plots per model, parametrization, sample size, and replica refer to the “recovery plots” image section of the accompanying github page:

https://github.com/jriveraespejo/thesis/tree/master/images/recovery_plots

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_{j1}^{(2)}$)			
		mean	sd	min	max
1 CP	100(10)	0.639	0.151	0.223	1.069
2 CP	250(10)	0.594	0.138	0.254	1.103
3 CP	500(10)	0.623	0.145	0.215	1.079
4 NCP	100(10)	0.632	0.148	0.256	1.032
5 NCP	250(10)	0.589	0.136	0.271	1.066
6 NCP	500(10)	0.610	0.143	0.214	1.087

Table A.1: First-order latent variable model (FOLV). Aggregated RMSE_B for the first individual sub-dimension.

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_{j2}^{(2)}$)			
		mean	sd	min	max
1 CP	100(10)	0.608	0.148	0.318	0.930
2 CP	250(10)	0.599	0.134	0.256	0.939
3 CP	500(10)	0.618	0.143	0.228	1.056
4 NCP	100(10)	0.601	0.145	0.295	0.911
5 NCP	250(10)	0.593	0.135	0.253	0.963
6 NCP	500(10)	0.607	0.138	0.202	1.055

Table A.2: First-order latent variable model (FOLV). Aggregated RMSE_B for the second individual sub-dimension.

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_{j3}^{(2)}$)			
		mean	sd	min	max
1 CP	100	0.604	0.142	0.257	1.000
2 CP	250	0.612	0.128	0.321	0.973
3 CP	500	0.612	0.150	0.172	1.079
4 NCP	100	0.595	0.139	0.245	0.968
5 NCP	250	0.609	0.131	0.288	0.990
6 NCP	500	0.601	0.147	0.220	1.082

Table A.3: First-order latent variable model (FOLV). Aggregated RMSE_B for the third individual sub-dimension.

Parametrization	Variable	Parameter	Number of replicas	Sample size		
				100	250	500
1 CP	Intercept	Γ_0	10	0.097	0.070	0.082
2 CP	gender(male)	$\Gamma_1[1]$	10	0.203	0.223	0.205
3 CP	gender(female)	$\Gamma_1[2]$	10	0.240	0.232	0.241
4 CP	age	Γ_2	10	0.008	0.006	0.003
5 CP	education(institute)	$\Gamma_3[1]$	10	0.249	0.113	0.119
6 CP	education(university)	$\Gamma_3[2]$	10	0.127	0.135	0.115
7 CP	education(both)	$\Gamma_3[3]$	10	0.157	0.113	0.110
8 CP	experience(0y)	$\Gamma_4[1]$	10	0.119	0.064	0.102
9 CP	experience(5y)	$\Gamma_4[2]$	10	0.157	0.082	0.082
10 CP	experience(10y)	$\Gamma_4[3]$	10	0.163	0.156	0.071
11 CP	experience(11+y)	$\Gamma_4[4]$	10	0.148	0.132	0.100
12 NCP	Intercept	Γ_0	10	0.089	0.065	0.083
13 NCP	gender(males)	$\Gamma_1[1]$	10	0.199	0.221	0.200
14 NCP	gender(females)	$\Gamma_1[2]$	10	0.247	0.229	0.235
15 NCP	age	Γ_2	10	0.008	0.006	0.003
16 NCP	education(institute)	$\Gamma_3[1]$	10	0.232	0.125	0.118
17 NCP	education(university)	$\Gamma_3[2]$	10	0.123	0.130	0.107
18 NCP	education(both)	$\Gamma_3[3]$	10	0.164	0.126	0.128
19 NCP	experience(0y)	$\Gamma_4[1]$	10	0.114	0.065	0.096
20 NCP	experience(5y)	$\Gamma_4[2]$	10	0.155	0.085	0.076
21 NCP	experience(10y)	$\Gamma_4[3]$	10	0.162	0.154	0.066
22 NCP	experience(11+y)	$\Gamma_4[4]$	10	0.150	0.133	0.095

Table A.4: First-order latent variable model (FOLV). RMSE_B of regression parameters.

	Parametrization	Variable	Parameter	Number of replicas	Sample size		
					100	250	500
1	CP	females - males	$\Gamma_1[2] - \Gamma_1[1]$	10	0.131	0.112	0.088
2	CP	university - institute	$\Gamma_3[2] - \Gamma_3[1]$	10	0.239	0.167	0.081
3	CP	both - institute	$\Gamma_3[3] - \Gamma_3[1]$	10	0.267	0.079	0.084
4	CP	both - university	$\Gamma_3[3] - \Gamma_3[2]$	10	0.183	0.138	0.111
5	CP	$5y - 0y$	$\Gamma_4[2] - \Gamma_4[1]$	10	0.228	0.089	0.102
6	CP	$10y - 0y$	$\Gamma_4[3] - \Gamma_4[1]$	10	0.241	0.155	0.099
7	CP	$10y - 5y$	$\Gamma_4[3] - \Gamma_4[2]$	10	0.208	0.163	0.075
8	CP	$11+y - 0y$	$\Gamma_4[4] - \Gamma_4[1]$	10	0.196	0.147	0.076
9	CP	$11+y - 5y$	$\Gamma_4[4] - \Gamma_4[2]$	10	0.199	0.164	0.102
10	CP	$11+y - 10y$	$\Gamma_4[4] - \Gamma_4[3]$	10	0.197	0.137	0.087
11	NCP	females - males	$\Gamma_1[2] - \Gamma_1[1]$	10	0.134	0.113	0.088
12	NCP	university - institute	$\Gamma_3[2] - \Gamma_3[1]$	10	0.239	0.168	0.083
13	NCP	both - institute	$\Gamma_3[3] - \Gamma_3[1]$	10	0.267	0.079	0.083
14	NCP	both - university	$\Gamma_3[3] - \Gamma_3[2]$	10	0.182	0.139	0.111
15	NCP	$5y - 0y$	$\Gamma_4[2] - \Gamma_4[1]$	10	0.231	0.090	0.101
16	NCP	$10y - 0y$	$\Gamma_4[3] - \Gamma_4[1]$	10	0.239	0.155	0.097
17	NCP	$10y - 5y$	$\Gamma_4[3] - \Gamma_4[2]$	10	0.201	0.162	0.074
18	NCP	$11+y - 0y$	$\Gamma_4[4] - \Gamma_4[1]$	10	0.194	0.147	0.075
19	NCP	$11+y - 5y$	$\Gamma_4[4] - \Gamma_4[2]$	10	0.192	0.163	0.101
20	NCP	$11+y - 10y$	$\Gamma_4[4] - \Gamma_4[3]$	10	0.195	0.134	0.085

Table A.5: First-order latent variable model (FOLV). RMSE_B of contrast parameters.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
1	CP	$\rho_{1,2}$	10	0.704	0.585	0.606
2	CP	$\rho_{1,3}$	10	0.719	0.591	0.617
3	CP	$\rho_{2,3}$	10	0.638	0.623	0.615
4	NCP	$\rho_{1,2}$	10	0.700	0.585	0.605
5	NCP	$\rho_{1,3}$	10	0.721	0.591	0.617
6	NCP	$\rho_{2,3}$	10	0.636	0.623	0.615

Table A.6: First-order latent variable model (FOLV). RMSE_B of correlations among sub-dimensions.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
1	CP	$\eta_1^{(3)}$	10	0.133	0.185	0.305
2	CP	$\eta_2^{(3)}$	10	0.242	0.183	0.258
3	CP	$\eta_3^{(3)}$	10	0.197	0.144	0.180
4	CP	$\eta_4^{(3)}$	10	0.261	0.214	0.310
5	CP	$\eta_5^{(3)}$	10	0.191	0.343	0.245
6	NCP	$\eta_1^{(3)}$	10	0.115	0.147	0.256
7	NCP	$\eta_2^{(3)}$	10	0.228	0.193	0.190
8	NCP	$\eta_3^{(3)}$	10	0.219	0.141	0.170
9	NCP	$\eta_4^{(3)}$	10	0.266	0.204	0.252
10	NCP	$\eta_5^{(3)}$	10	0.189	0.318	0.230

Table A.7: First-order latent variable model (FOLV). RMSE_B of texts difficulties.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
1	CP	$\sigma_1^{(3)}$	10	0.200	0.126	0.231
2	CP	$\sigma_2^{(3)}$	10	0.229	0.155	0.163
3	CP	$\sigma_3^{(3)}$	10	0.196	0.127	0.197
4	CP	$\sigma_4^{(3)}$	10	0.198	0.147	0.150
5	CP	$\sigma_5^{(3)}$	10	0.243	0.223	0.184
6	NCP	$\sigma_1^{(3)}$	10	0.202	0.134	0.236
7	NCP	$\sigma_2^{(3)}$	10	0.235	0.159	0.163
8	NCP	$\sigma_3^{(3)}$	10	0.202	0.129	0.196
9	NCP	$\sigma_4^{(3)}$	10	0.200	0.152	0.144
10	NCP	$\sigma_5^{(3)}$	10	0.242	0.220	0.181

Table A.8: First-order latent variable model (FOLV). RMSE_B of texts difficulty deviations.

Parametrization	Sample size	items(replicas)	Number of	RMSE _B ($\eta_k^{(2)}$)			
				mean	sd	min	max
1	CP	100	25(10)	0.301	0.061	0.159	0.389
2	CP	250	25(10)	0.203	0.039	0.138	0.278
3	CP	500	25(10)	0.201	0.031	0.137	0.275
4	NCP	100	25(10)	0.289	0.055	0.159	0.391
5	NCP	250	25(10)	0.188	0.036	0.130	0.268
6	NCP	500	25(10)	0.155	0.037	0.090	0.264

Table A.9: First-order latent variable model (FOLV). Aggregated RMSE_B for items difficulties.

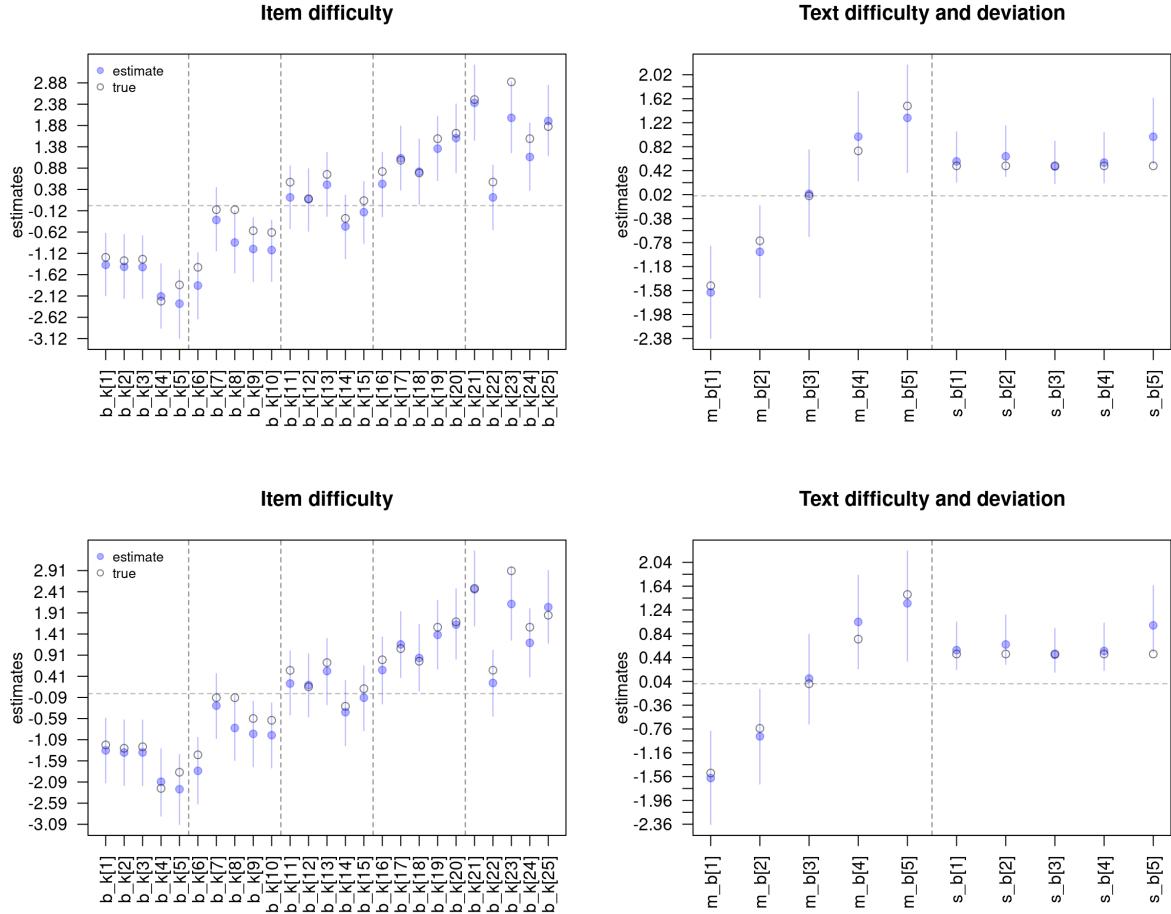


Figure A.32: First-order latent variable model (FOLV). Sample size 100, replica 1. Items and text parameters. Top two panels correspond to the centered parametrization (CP). Top bottom panels correspond to the non-centered parametrization (NCP).

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_{j1}^{(2)}$)			
		mean	sd	min	max
1 CP	100(10)	0.693	0.152	0.293	1.014
2 CP	250(10)	0.628	0.143	0.289	1.115
3 CP	500(10)	0.669	0.157	0.289	1.212
4 NCP	100(10)	0.683	0.148	0.308	1.016
5 NCP	250(10)	0.616	0.142	0.298	1.108
6 NCP	500(10)	0.667	0.156	0.267	1.185

Table A.10: Second-order latent variable model (SOLV). Aggregated RMSE_B for the first individual sub-dimension.

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_{j2}^{(2)}$)			
		mean	sd	min	max
1 CP	100(10)	0.628	0.158	0.276	0.955
2 CP	250(10)	0.653	0.135	0.318	1.087
3 CP	500(10)	0.649	0.145	0.257	1.133
4 NCP	100(10)	0.623	0.157	0.250	0.955
5 NCP	250(10)	0.631	0.135	0.276	1.059
6 NCP	500(10)	0.645	0.144	0.270	1.139

Table A.11: Second-order latent variable model (SOLV). Aggregated RMSE_B for the second individual sub-dimension.

Parametrization	Number of individulas(replicas)	RMSE _B ($\theta_{j3}^{(2)}$)			
		mean	sd	min	max
1 CP	100(10)	0.617	0.137	0.279	0.992
2 CP	250(10)	0.664	0.142	0.352	1.119
3 CP	500(10)	0.651	0.153	0.263	1.163
4 NCP	100(10)	0.606	0.137	0.247	0.962
5 NCP	250(10)	0.647	0.138	0.324	1.089
6 NCP	500(10)	0.648	0.153	0.252	1.175

Table A.12: Second-order latent variable model (SOLV). Aggregated RMSE_B for the third individual sub-dimension.

Parametrization	Number of individuals(replicas)	RMSE _B ($\theta_j^{(3)}$)			
		mean	sd	min	max
1 CP	100(10)	0.736	0.166	0.390	1.077
2 CP	250(10)	0.908	0.185	0.489	1.388
3 CP	500(10)	1.131	0.232	0.438	1.857
4 NCP	100(10)	0.717	0.156	0.362	1.072
5 NCP	250(10)	0.831	0.179	0.468	1.281
6 NCP	500(10)	1.119	0.224	0.501	1.746

Table A.13: Second-order latent variable model (SOLV). Aggregated RMSE_B for the individual higher-order dimension.

	Parametrization	Variable	Parameter	Number of replicas	Sample size		
					100	250	500
1	CP	Intercept	Γ_0	10	0.11	0.12	0.16
2	CP	gender(male)	$\Gamma_1[1]$	10	0.31	0.48	0.48
3	CP	gender(female)	$\Gamma_1[2]$	10	0.17	0.12	0.13
4	CP	age	Γ_2	10	0.02	0.01	0.03
5	CP	education(institute)	$\Gamma_3[1]$	10	0.37	0.51	0.56
6	CP	education(university)	$\Gamma_3[2]$	10	0.49	0.59	0.81
7	CP	education(both)	$\Gamma_3[3]$	10	0.27	0.18	0.24
8	CP	experience(0y)	$\Gamma_4[1]$	10	0.22	0.46	0.77
9	CP	experience(5y)	$\Gamma_4[2]$	10	0.21	0.16	0.18
10	CP	experience(10y)	$\Gamma_4[3]$	10	0.18	0.13	0.30
11	CP	experience(11+y)	$\Gamma_4[4]$	10	0.14	0.27	0.39
12	NCP	Intercept	Γ_0	10	0.11	0.12	0.16
13	NCP	gender(males)	$\Gamma_1[1]$	10	0.31	0.47	0.48
14	NCP	gender(females)	$\Gamma_1[2]$	10	0.16	0.10	0.12
15	NCP	age	Γ_2	10	0.02	0.01	0.03
16	NCP	education(institute)	$\Gamma_3[1]$	10	0.35	0.46	0.56
17	NCP	education(university)	$\Gamma_3[2]$	10	0.50	0.63	0.79
18	NCP	education(both)	$\Gamma_3[3]$	10	0.27	0.19	0.22
19	NCP	experience(0y)	$\Gamma_4[1]$	10	0.22	0.45	0.77
20	NCP	experience(5y)	$\Gamma_4[2]$	10	0.21	0.15	0.19
21	NCP	experience(10y)	$\Gamma_4[3]$	10	0.19	0.13	0.30
22	NCP	experience(11+y)	$\Gamma_4[4]$	10	0.14	0.28	0.39

Table A.14: Second-order latent variable model (SOLV). RMSE_B of regression parameters.

	Parametrization	Contrast	Parameter	Number of replicas	Sample size		
					100	250	500
1	CP	females - males	$\Gamma_1[2] - \Gamma_1[1]$	10	0.29	0.51	0.56
2	CP	university - institute	$\Gamma_3[2] - \Gamma_3[1]$	10	0.78	1.06	1.32
3	CP	bboth - institute	$\Gamma_3[3] - \Gamma_3[1]$	10	0.57	0.58	0.72
4	CP	both - university	$\Gamma_3[3] - \Gamma_3[2]$	10	0.43	0.52	0.67
5	CP	$5y - 0y$	$\Gamma_4[2] - \Gamma_4[1]$	10	0.30	0.41	0.65
6	CP	$10y - 0y$	$\Gamma_4[3] - \Gamma_4[1]$	10	0.34	0.50	1.07
7	CP	$10y - 5y$	$\Gamma_4[3] - \Gamma_4[2]$	10	0.29	0.23	0.46
8	CP	$11+y - 0y$	$\Gamma_4[4] - \Gamma_4[1]$	10	0.24	0.70	1.15
9	CP	$11+y - 5y$	$\Gamma_4[4] - \Gamma_4[2]$	10	0.30	0.41	0.56
10	CP	$11+y - 10y$	$\Gamma_4[4] - \Gamma_4[3]$	10	0.28	0.32	0.21
11	NCP	females - males	$\Gamma_1[2] - \Gamma_1[1]$	10	0.29	0.51	0.57
12	NCP	university - institute	$\Gamma_3[2] - \Gamma_3[1]$	10	0.79	1.05	1.33
13	NCP	both - institute	$\Gamma_3[3] - \Gamma_3[1]$	10	0.57	0.58	0.72
14	NCP	both - university	$\Gamma_3[3] - \Gamma_3[2]$	10	0.43	0.51	0.68
15	NCP	$5y - 0y$	$\Gamma_4[2] - \Gamma_4[1]$	10	0.30	0.41	0.65
16	NCP	$10y - 0y$	$\Gamma_4[3] - \Gamma_4[1]$	10	0.34	0.49	1.06
17	NCP	$10y - 5y$	$\Gamma_4[3] - \Gamma_4[2]$	10	0.30	0.23	0.46
18	NCP	$11+y - 0y$	$\Gamma_4[4] - \Gamma_4[1]$	10	0.24	0.69	1.15
19	NCP	$11+y - 5y$	$\Gamma_4[4] - \Gamma_4[2]$	10	0.30	0.40	0.56
20	NCP	$11+y - 10y$	$\Gamma_4[4] - \Gamma_4[3]$	10	0.28	0.32	0.21

Table A.15: Second-order latent variable model (SOLV). RMSE_B of contrast parameters.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
1	CP	$\rho_{1,2}$	10	0.20	0.26	0.23
2	CP	$\rho_{1,3}$	10	0.15	0.27	0.21
3	CP	$\rho_{2,3}$	10	0.27	0.22	0.22
4	NCP	$\rho_{1,2}$	10	0.20	0.26	0.23
5	NCP	$\rho_{1,3}$	10	0.15	0.26	0.20
6	NCP	$\rho_{2,3}$	10	0.27	0.22	0.22

Table A.16: Second-order latent variable model (SOLV). RMSE_B of correlations among sub-dimensions.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
1	CP	$\eta_1^{(3)}$	10	0.133	0.185	0.305
2	CP	$\eta_2^{(3)}$	10	0.242	0.183	0.258
3	CP	$\eta_3^{(3)}$	10	0.197	0.144	0.180
4	CP	$\eta_4^{(3)}$	10	0.261	0.214	0.310
5	CP	$\eta_5^{(3)}$	10	0.191	0.343	0.245
11	NCP	$\eta_1^{(3)}$	10	0.115	0.147	0.256
12	NCP	$\eta_2^{(3)}$	10	0.228	0.193	0.190
13	NCP	$\eta_3^{(3)}$	10	0.219	0.141	0.170
14	NCP	$\eta_4^{(3)}$	10	0.266	0.204	0.252
15	NCP	$\eta_5^{(3)}$	10	0.189	0.318	0.230

Table A.17: Second-order latent variable model (SOLV). RMSE_B of texts difficulties.

	Parametrization	Parameter	Number of replicas	Sample size		
				100	250	500
6	CP	$\sigma_1^{(3)}$	10	0.200	0.126	0.231
7	CP	$\sigma_2^{(3)}$	10	0.229	0.155	0.163
8	CP	$\sigma_3^{(3)}$	10	0.196	0.127	0.197
9	CP	$\sigma_4^{(3)}$	10	0.198	0.147	0.150
10	CP	$\sigma_5^{(3)}$	10	0.243	0.223	0.184
16	NCP	$\sigma_1^{(3)}$	10	0.202	0.134	0.236
17	NCP	$\sigma_2^{(3)}$	10	0.235	0.159	0.163
18	NCP	$\sigma_3^{(3)}$	10	0.202	0.129	0.196
19	NCP	$\sigma_4^{(3)}$	10	0.200	0.152	0.144
20	NCP	$\sigma_5^{(3)}$	10	0.242	0.220	0.181

Table A.18: Second-order latent variable model (SOLV). RMSE_B of texts difficulty deviations.

Parametrization	Sample size	items(replicas)	Number of	RMSE _B ($\eta_k^{(2)}$)			
				mean	sd	min	max
1	CP	100	25(10)	0.203	0.060	0.147	0.267
2	CP	250	25(10)	0.248	0.027	0.217	0.266
3	CP	500	25(10)	0.218	0.011	0.206	0.227
4	NCP	100	25(10)	0.206	0.059	0.152	0.268
5	NCP	250	25(10)	0.246	0.026	0.216	0.264
6	NCP	500	25(10)	0.218	0.012	0.204	0.227

Table A.19: Second-order latent variable model (SOLV). Aggregated RMSE_B for items difficulties.

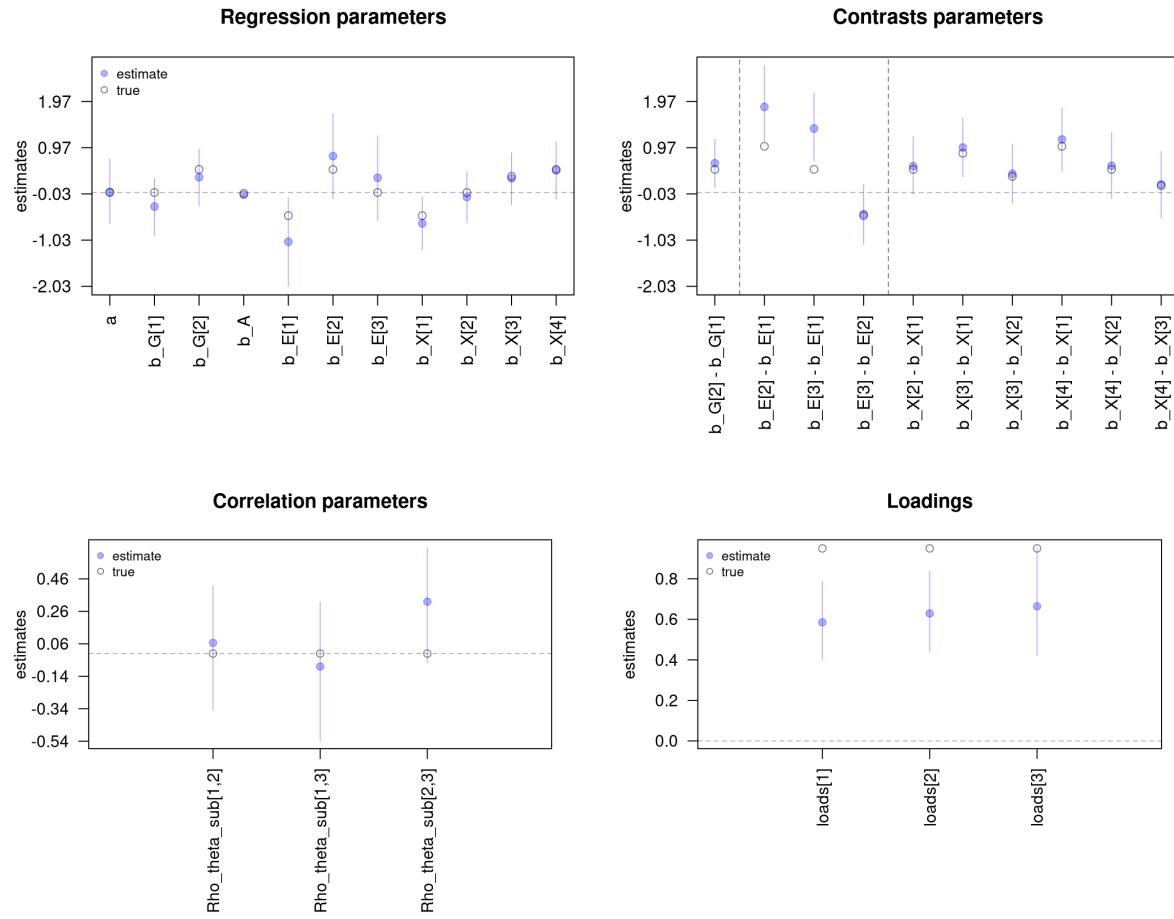


Figure A.33: Second-order latent variable model (SOLV). Centered parametrization. Sample size 100, replica 1. Regression, contrast, correlation, and loading parameters. The true correlation parameters corresponds to simulation values.

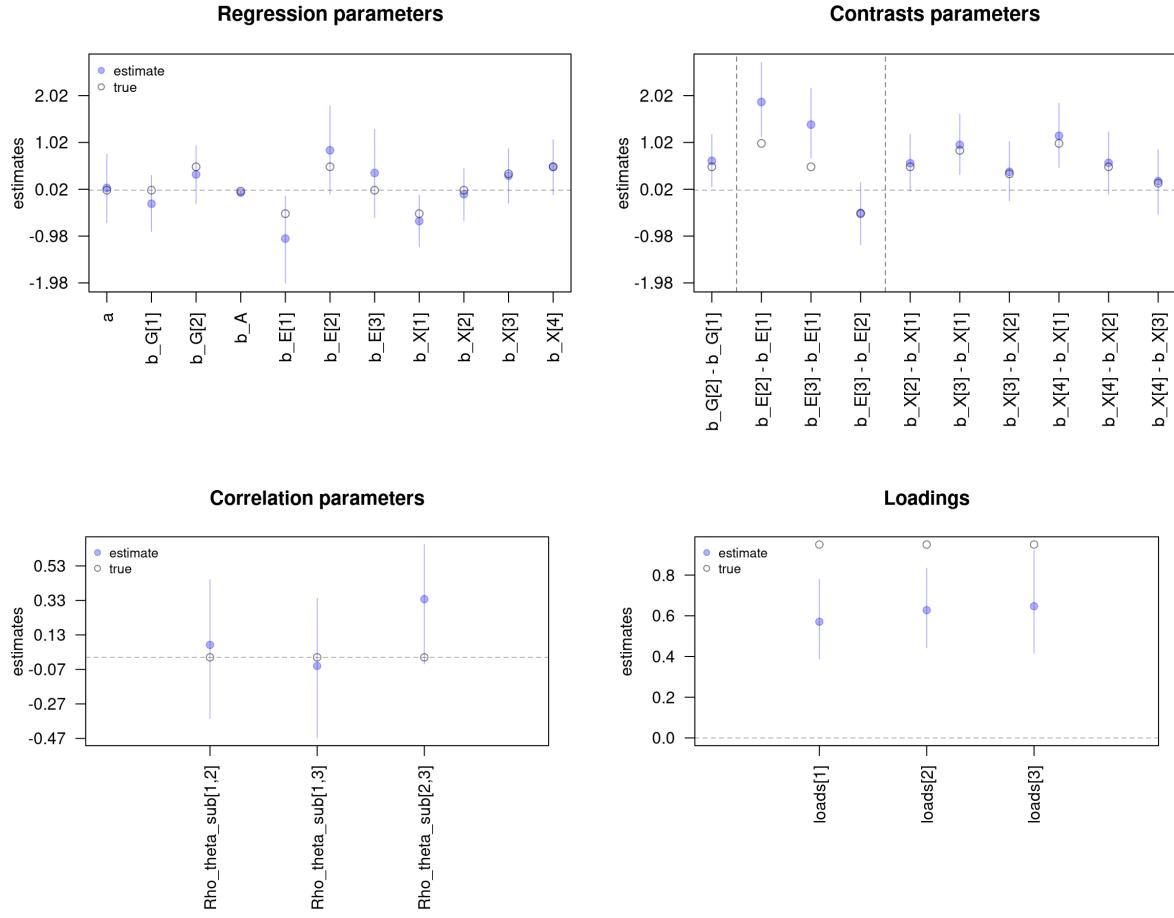


Figure A.34: Second-order latent variable model (SOLV). Centered parametrization. Sample size 100, replica 1. Regression, contrast, correlation, and loading parameters. The true correlation parameters corresponds to simulation values.

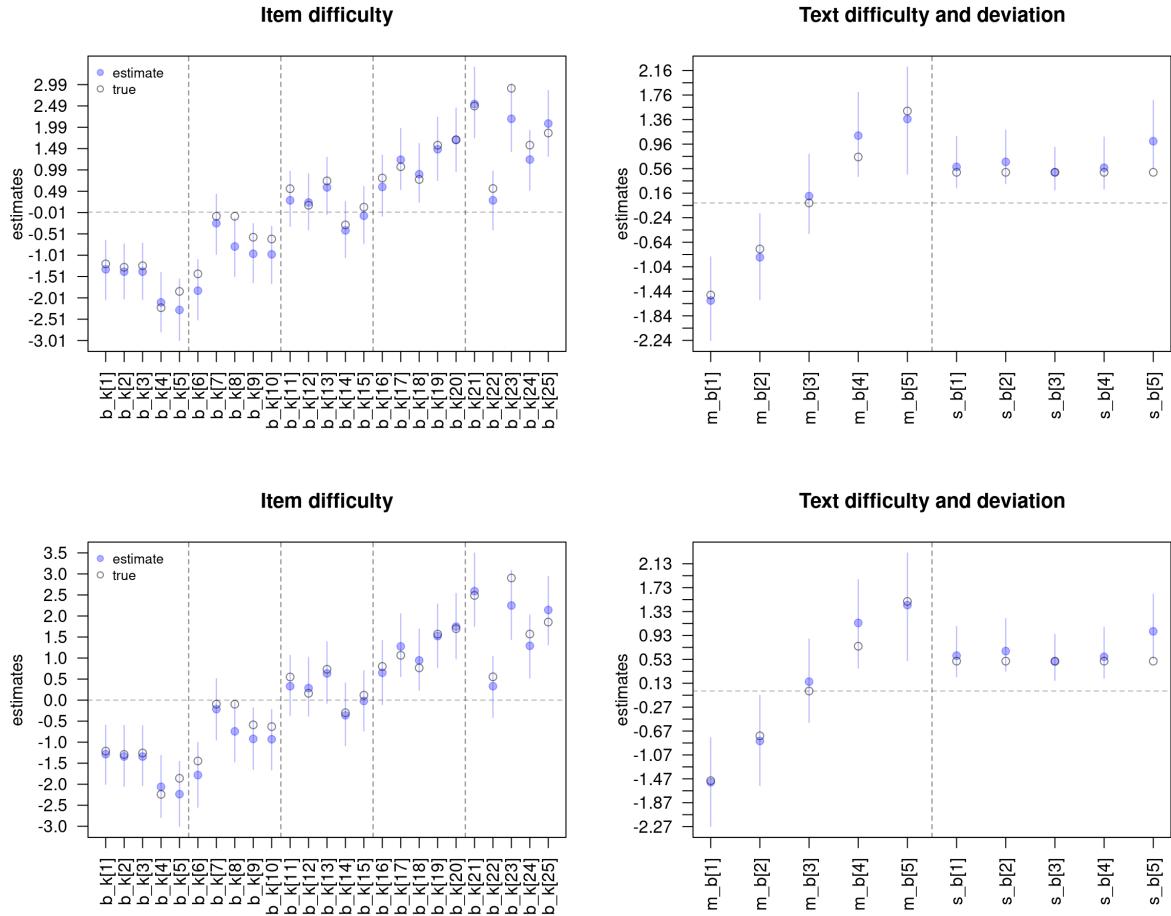


Figure A.35: Second-order latent variable model (SOLV). Sample size 100, replica 1. Items and text parameters. Top two panels correspond to the centered parametrization (CP). Top bottom panels correspond to the non-centered parametrization (NCP).

A.2.4 Retrodictive accuracy

The current section shows only a small set of figures related to the retrodictive accuracy of the model. In case the reader wants to inspect the full set of figures refer to the “retrodictive plots” image section of the accompanying github page:

https://github.com/jriveraespejo/thesis/tree/master/images/retrodictive_plots

On the other hand, if the reader wants to replicate or inspect the retrodictive tables refer to the “data/tables” section of the accompanying github page:

https://github.com/jriveraespejo/thesis/tree/master/data_tables

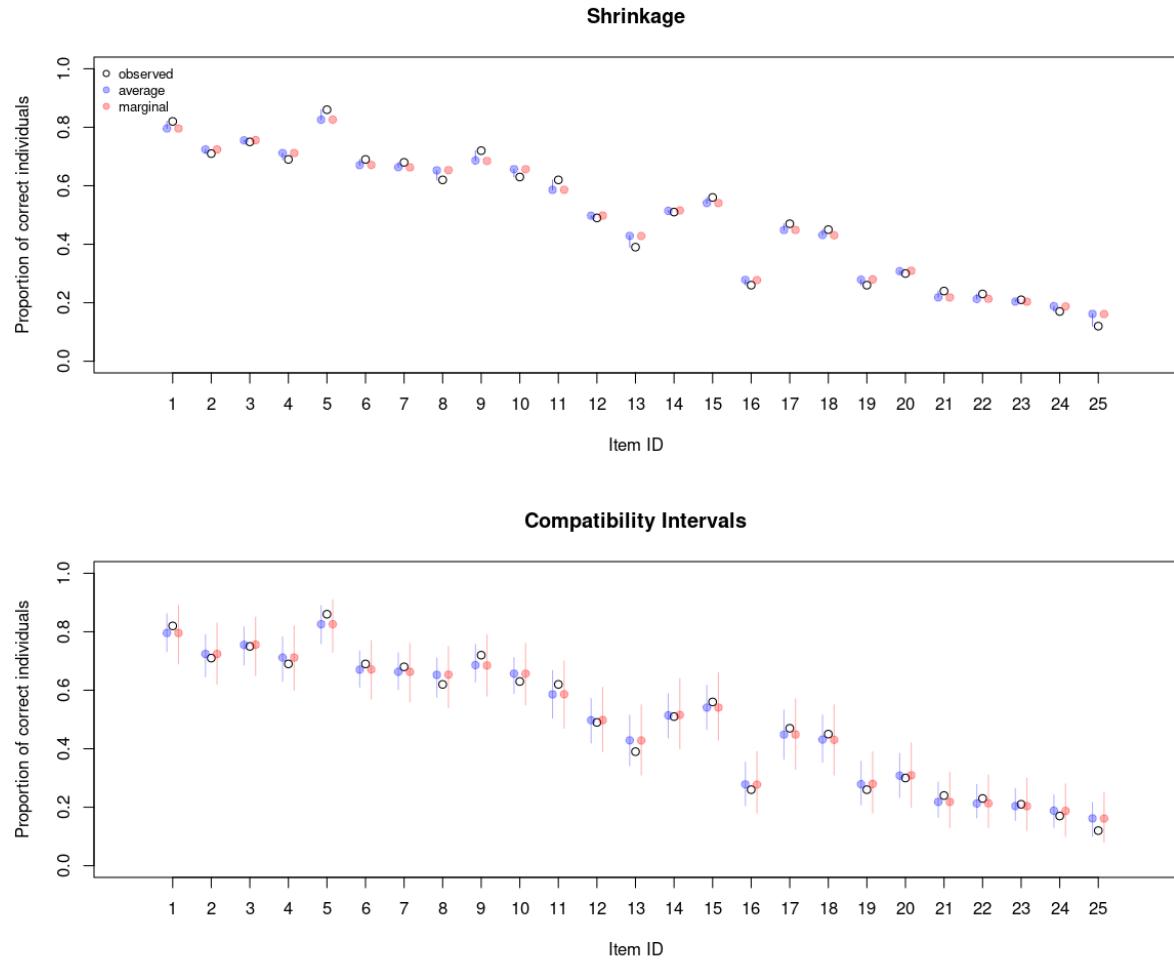


Figure A.36: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Items predictive plot.

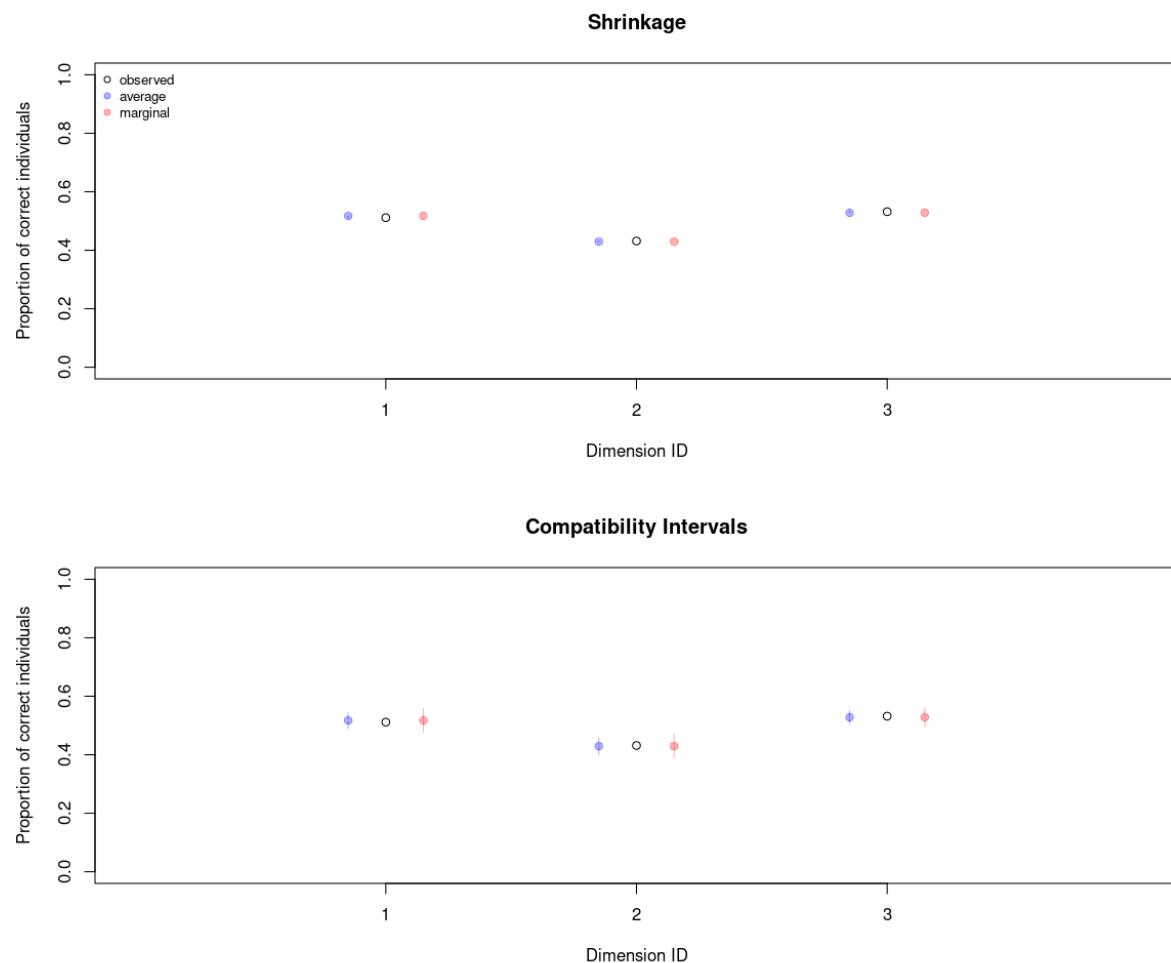


Figure A.37: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Dimension predictive plot.

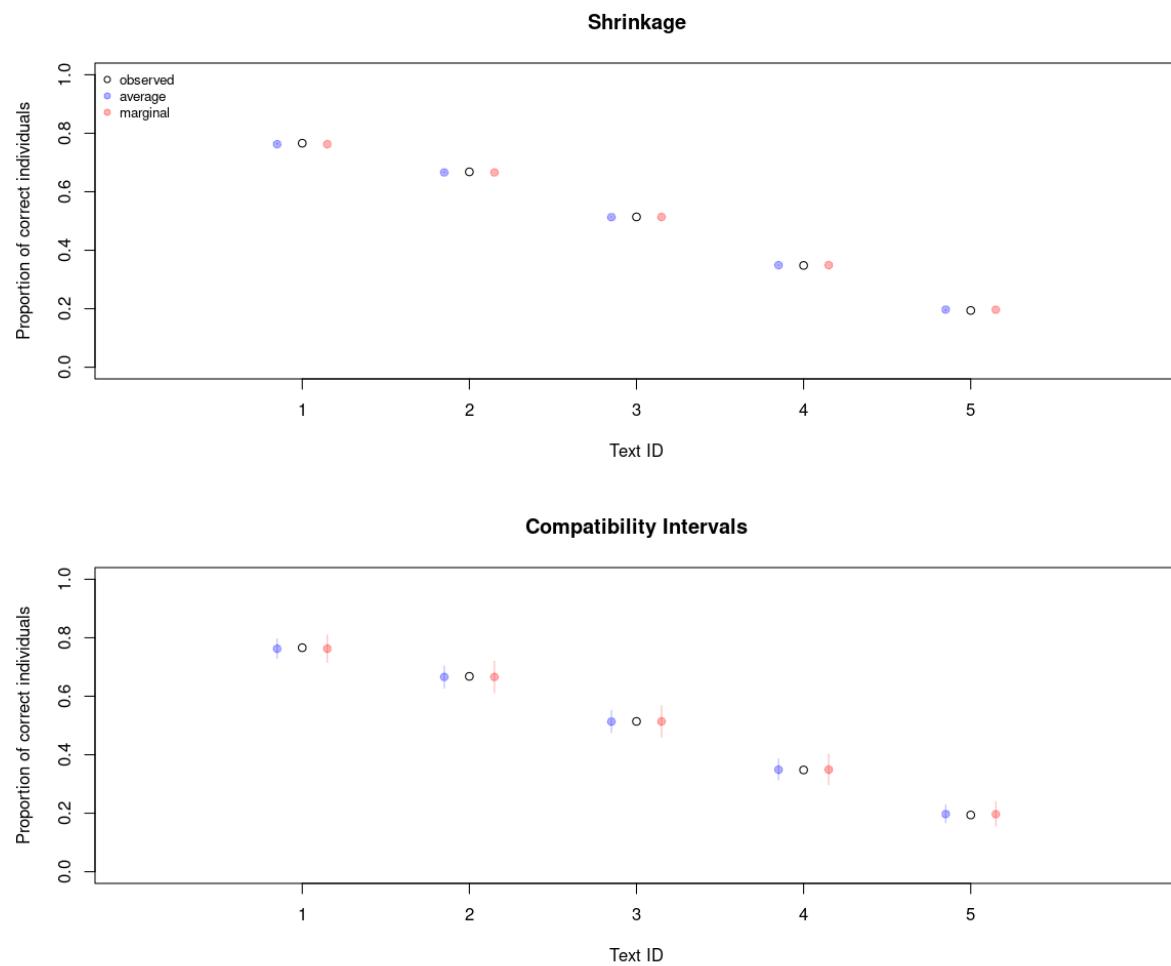


Figure A.38: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Text predictive plot.

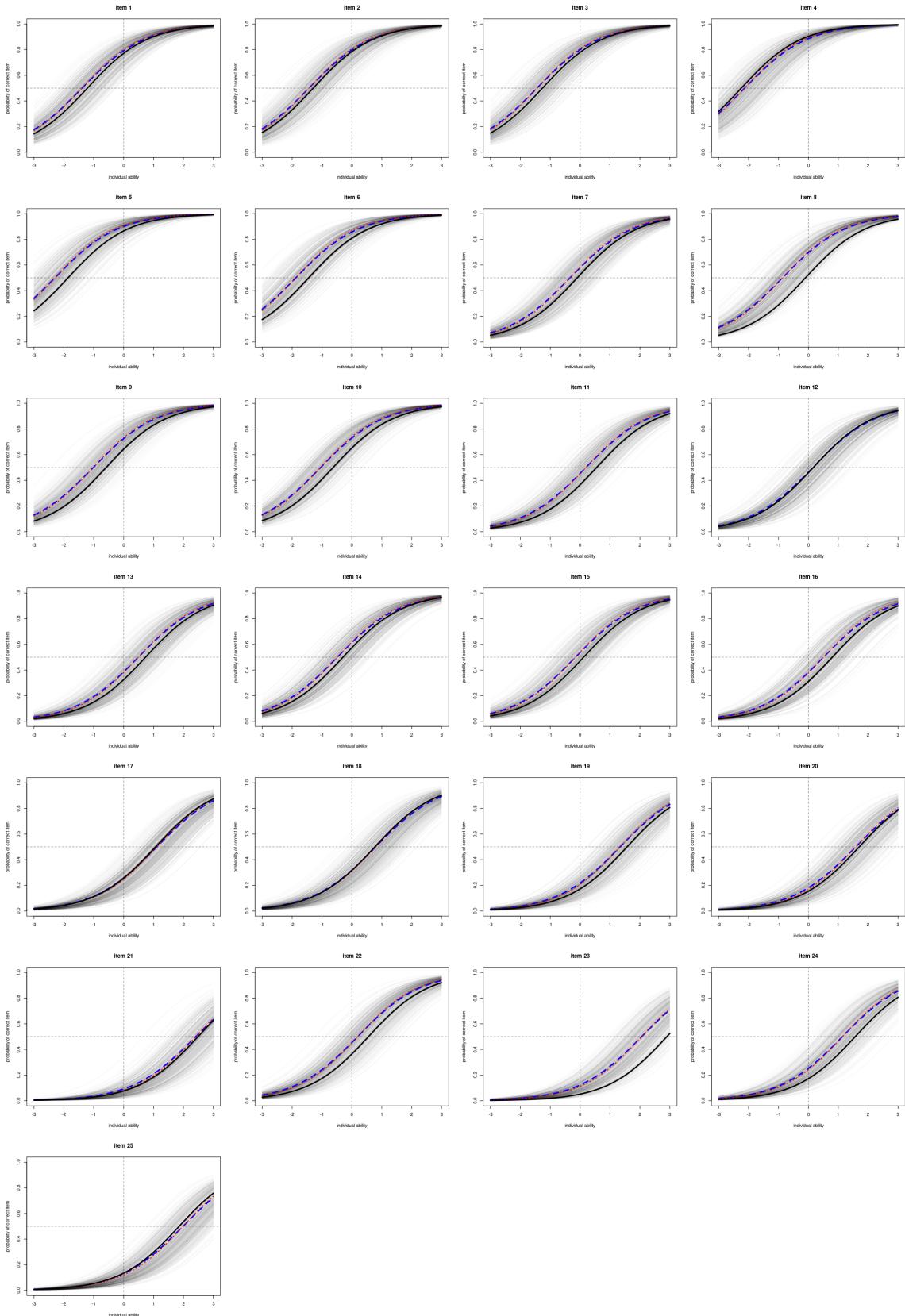


Figure A.39: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Centered parametrization. Item characteristic curves (ICC)

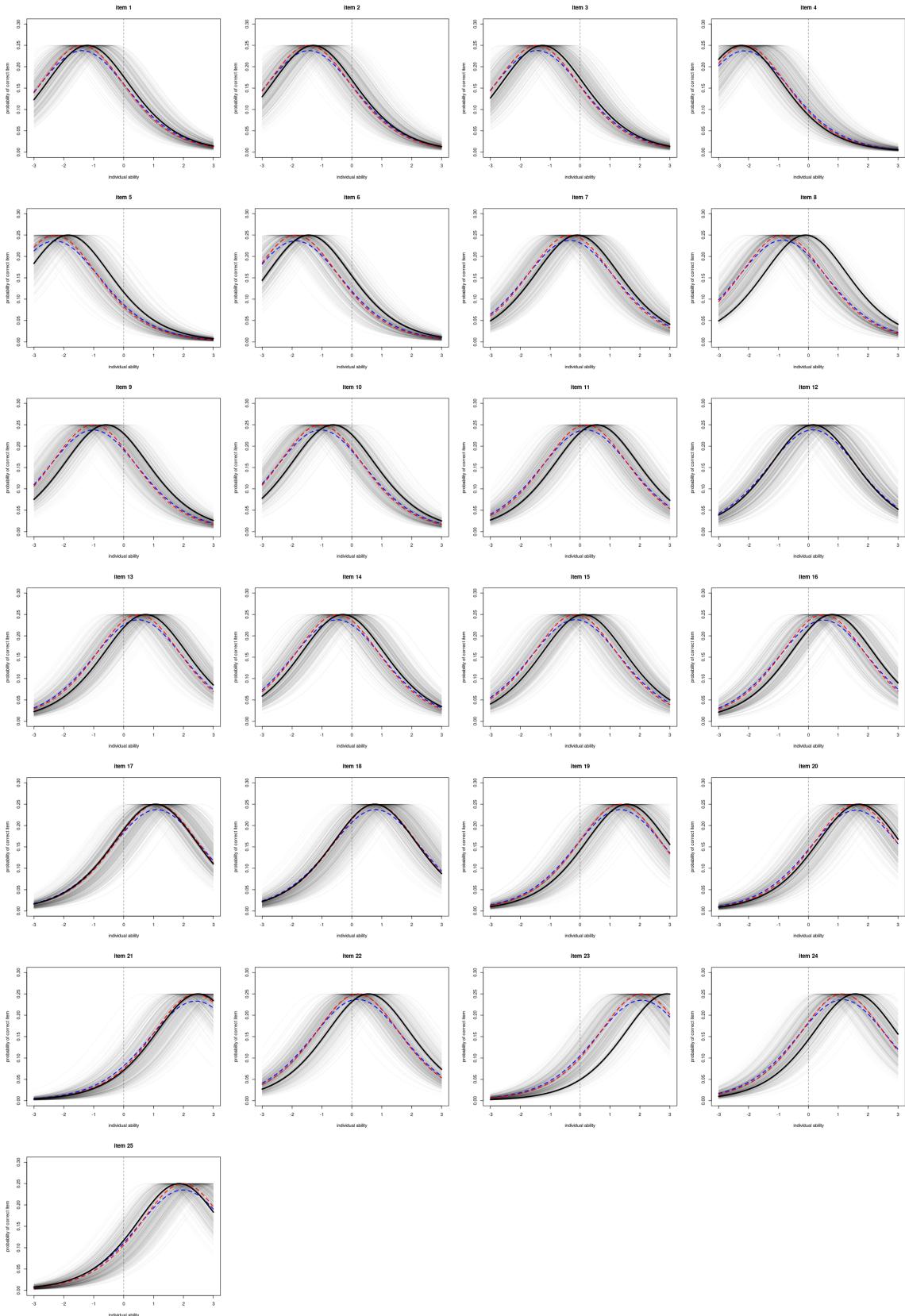


Figure A.40: First-Order latent variable model (FOLV). Sample size 100, replica number 4. Non-centered parametrization. Item information function (IIF).

Appendix B

Code

This section provides the most important set of codes used throughout the current research. However, in case the reader wants to replicate the full simulation analysis, we provide the full set of codes in the “simulation” section of the accompanying github page: <https://github.com/jriveraespejo/thesis/tree/master/simulation>

B.1 Chapter 3: Bayesian estimation

B.1.1 To center or not to center

The devil’s funnel, centered parametrization.

Stan

```
transformed data {
    int<lower=0> J;
    J = 1;
}
parameters {
    real theta[J];
    real v;
}
model {
    v ~ normal(0, 3);
    theta ~ normal(0, exp(v));
}
```

JAGS

```
model{
    v ~ dnorm(0,3)
    theta ~ dnorm(0, exp(v))
}
```

The devil’s funnel, centered parametrization with priors.

Stan

```

transformed data {
    int<lower=0> J;
    J = 1;
}
parameters {
    real theta[J];
    real v;
}
model {
    v ~ normal(0, 1);
    theta ~ normal(0, exp(v));
}

```

JAGS

```

model{
    v ~ dnorm(0,1)
    theta ~ dnorm(0, exp(v))
}
```

The devil's funnel, non-centered parametrization.

Stan

```

transformed data {
    int<lower=0> J;
    J = 1;
}
parameters {
    real ztheta[J];
    real v;
}
transformed parameters{
    vector[J] theta;
    theta = exp(v) * to_vector(ztheta);
}
model {
    v ~ normal(0, 3);
    ztheta ~ normal(0, 1);
}
```

JAGS

```

model{
    v ~ dnorm(0,1)
    ztheta ~ dnorm(0,1)
    theta = v * ztheta
}
```

B.2 Chapter 4: Simulation study

B.2.1 Algorithm

Data generation

```
S = 10 # ten data sets
condition = expand_grid( J = c(100, 250, 500), load=0.95)
for(i in 1:nrow(condition)){
  for(s in 1:S){
    with(condition[i,],
         data_generation( J=J, loads=rep(load, 3),
                         Ndata=s, seed=4587+s+i, # different seeds
                         file_dir=file.path(getwd(), 'data') ) )
  }
}
```

Data generation function

```
# function:
#   data_generation
# description:
#   To generate data based on different parameter settings.
#   Only two parameters are effectively controlled in the experimentation:
#   sample size (J), and the loading from the SOLV to the FOLV (loads).
# characteristics of the sample design:
#   - one instrument
#   - hierarchical measurement scales with FOLV and SOLV
#   - one evaluation time
#   - one sample of individuals
#   - testlet items, multiple items come from one text
#   - with covariates
#   - NO missingness
# arguments:
#   J = individual sample sizes
#   loads = loadings from SOLV to FOLV (it control correlation)
#   Ndata = defines the number of data generated
#   file_dir = path to save generated data
#   s_theta = sd to simulate SOLV and FOLV
#   s_text = sd in generating items from a specific text
#   D = number of dimensions (default 3)
#   K = number of items (default 25)
#   L = number of texts (default 5), it has to be a multiple of K
#   seed = seed used to generate the simulation (default 1)
#   prec = rounding in abilities and item parameters (default 3)

data_generation =function( J=100, loads=rep(0.95, 3), Ndata=1, file_dir,
                           s_theta=0.5, s_text=0.5, D=3, K=25, L=5, seed=1, prec=3){

#-----
# 1. generation
#-----
```

```

set.seed(seed)

## 1.1. regression parameters
mom = expand_grid(a=loads[-3], b=loads[-1])
mom = mom[-3,]

betas = list( gender = c(0, 0.5),
             age = -0.02,
             edu = c(-0.5, 0.5, 0),
             exp = c(-0.5, 0, 0.35, 0.5),
             loads = loads, # loadings
             exp_corr = with(mom, a*b) ) # expected correlation

## 1.2 covariates
abilities = data.frame( IDind=1:J,
                         gender = sample(c(1,2), size=J, replace=T),
                         age = sample(30:65, size=J, replace=T),
                         edu = sample(c(1,2,3), size=J, replace=T),
                         exp = sample(c(1,2,3,4), size=J, replace=T),
                         theta=rep(NA,J), theta1=rep(NA,J),
                         theta2=rep(NA,J), theta3=rep(NA,J) )

# variable indices
SOLV_loc = which(names(abilities)=='theta')
FOLV_loc = which(names(abilities)=='theta1'):
            which(names(abilities)==paste0('theta', D))

## 1.3. abilities
# SOLV
m_theta = rep(NA, J)
for(j in 1:J){
  ageC = with(abilities, age[j] - min(age) + 1 )

  m_theta[j] = with(abilities,
                    betas$gender[ gender[j] ] +
                    betas$age * ageC +
                    betas$edu[ edu[j] ] +
                    betas$exp[ exp[j] ] )
}
abilities[, SOLV_loc] = round( rnorm(J, m_theta, s_theta), prec)

# FOLV
# independent after considering SOLV
s_mult = diag( rep(s_theta, D) )
m_mult = data.frame( theta1=rep(NA, J),
                      theta2=rep(NA, J),
                      theta3=rep(NA, J) )

```

```

for(j in 1:J){
    m_mult[j,] = betas$loads * abilities$theta[j]
    abilities[j, FOLV_loc] = round(
        mvnrnorm(n=1, mu=unlist(m_mult[j,]), Sigma=s_mult), prec)
}

## 1.4 texts
texts = data.frame(IDtext=1:L, m_b=rep(NA, L), s_b=rep(NA, L))
texts$m_b = seq(-1.5, 1.5, length.out=L)
texts$s_b = rep(s_text, L)

## 1.5 items
items = data.frame(IDitem=1:K, IDtext=rep(NA,K),
    IDdim=rep(NA,K), b=rep(NA, K))
kl = K/L # items per text
for(k in 1:nrow(texts)){
    items$b[(1:kl) + (k-1)*kl] = with(texts,
        round( rnorm(kl, m_b[k], s_b[k]), prec ) )
    items$IDtext[(1:kl) + (k-1)*kl] = k
}

## 1.6 dimensions
items$IDdim = sample(1:3, K, replace=T)

# -----
# 2. storage
# -----
## 2.1 parameters
data_true = list(
    seed=seed,
    # indices
    J = J,
    D = D,
    K = K,
    L = L,
    # abilities
    betas = betas,
    abilities = abilities,
    # texts and items
    texts = texts,
    items = items)

```

```

file_name = paste0('Parameters_J', J, '_l', loads[1],
                  '_Ndata', Ndata, '.RData')
save(data_true, file=file.path(file_dir, file_name) )

## 2.2 long format
data_eval = data.frame(
    # individual data
    IDind = rep(abilities$IDind, K),
    gender = rep(abilities$gender, K),
    age = rep(abilities$age, K),
    edu = rep(abilities$edu, K),
    exp = rep(abilities$exp, K),
    theta = rep(abilities$theta, K),
    theta1 = rep(abilities$theta1, K),
    theta2 = rep(abilities$theta2, K),
    theta3 = rep(abilities$theta3, K),

    # items
    IDitem = rep(items$IDitem, each=J),
    IDtext = rep(items$IDtext, each=J),
    IDdim = rep(items$IDdim, each=J),
    b = rep(items$b, each=J) )

# appropriate ability
data_eval$theta_jkld = NA
for(i in 1:nrow(data_eval)){
    data_eval$theta_jkld[i] = data_eval[i, FOLV_loc[ data_eval$IDdim[i] ] ] }

# linear predictor, probability, and outcome
data_eval$v_jkld = with(data_eval, theta_jkld - b)
data_eval$p_jkld = inv_logit( data_eval$v )
data_eval$y_jkld = rbinom( nrow(data_eval), 1, prob=data_eval$p)

file_name = paste0('LongFormat_J', J, '_l', loads[1],
                  '_Ndata', Ndata, '.RData')
save(data_eval, file=file.path(file_dir, file_name) )

## 2.3 estimation data
data_post = list(
    # evaluation data
    N = nrow(data_eval),
    J = J,
    K = K,
    L = L,
    )

```

```

D = D,
IDj = data_eval$IDind,
IDk = data_eval$IDitem,
IDl = data_eval$IDtext,
IDd = data_eval$IDdim,
GE = data_eval$gender,
AG = data_eval$age,
ED = data_eval$edu,
XP = data_eval$exp,
y = data_eval$y_jkld,

# individual data
IDind = abilities$IDind,
G = abilities$gender,
A = abilities$age,
E = abilities$edu,
X = abilities$exp,

# items
IDitem = items$IDitem,
IDtext = items$IDtext,
IDdim = items$IDdim )

file_name = paste0('ListFormat_J', J, '_l', loads[1],
                   '_Ndata', Ndata, '.RData')
save(data_post, file=file.path(file_dir, file_name) )

}

```

B.2.2 Results

Models

it has the stan model used to analize the data

FOLV CP

```

data{
    // evaluation
    int N;
    int J;
    int K;
    int L;
    int D;
    int IDj[N];
    int IDk[N];
    int IDl[N];
    int IDd[N];
    int GE[N];
    real AG[N];

```

```

int ED[N];
int XP[N];
int y[N];

// individuals
int IDind[J];
int G[J];
real A[J];
int E[J];
int X[J];

// items
int IDitem[K];
int IDtext[K];
int IDdim[K];
}

parameters{
    // items
    real m_b[L];
    real<lower=0> s_b[L];
    real b_k[K];

    // betas
    real a;
    real b_G[2];
    real b_A;
    real b_E[3];
    real b_X[4];

    // abilities
    // sub-dimensions: lit, inf, ref
    corr_matrix[D] Rho_theta_sub;
    vector[D] theta_sub[J];
}

model{
    // declare
    vector[D] m_mult[J];
    real v;
    real p;

    // items
    m_b ~ normal(0, 1);
    s_b ~ exponential(2);
    for(k in 1:K){           // priors
        b_k[k] ~ normal( m_b[ IDtext[k] ], s_b[ IDtext[k] ] );
    }

    // abilities
    a ~ normal(0, 0.5);
    b_G ~ normal(0, 0.5);
}

```

```

b_A ~ normal(0, 0.5);
b_E ~ normal(0, 1);
b_X ~ normal(0, 0.5);
Rho_theta_sub ~ lkj_corr(2);
for(j in 1:J){
    m_mult[j,] = rep_vector( a + b_G[ G[j] ] +
        b_A * ( A[j] - min(A) ) +
        b_E[ E[j] ] +
        b_X[ X[j] ], D);
    // using the same predictor for the three latents
}
theta_sub ~ multi_normal( m_mult, Rho_theta_sub );

// model
for( i in 1:N ) {
    v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
    p = inv_logit(v);
    y[i] ~ bernoulli(p);
}
## generated quantities{
##     vector[N] log_lik;
##     real v;
##     real p;
##
##     // likelihood
##     for( i in 1:N ) {
##         v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
##         p = inv_logit(v);
##         log_lik[i] = bernoulli_lpmf( y[i] | p);
##     }
## }

```

FOLV NCP

```

data{
    // evaluation
    int N;
    int J;
    int K;
    int L;
    int D;
    int IDj[N];
    int IDk[N];
    int IDl[N];
    int IDd[N];
    int GE[N];
    real AG[N];
    int ED[N];
    int XP[N];
    int y[N];

```

```

// individuals
int IDind[J];
int G[J];
real A[J];
int E[J];
int X[J];

// items
int IDitem[K];
int IDtext[K];
int IDdim[K];
}

parameters{
    // items
    real m_b[L];
    real<lower=0> s_b[L];
    real zb_k[K];

    // betas
    real a;
    real b_G[2];
    real b_A;
    real b_E[3];
    real b_X[4];

    // abilities
    // sub-dimensions: lit, inf, ref
    cholesky_factor_corr[D] L_Rho_theta_sub;
    matrix[D, J] ztheta_sub;
}

transformed parameters{
    real b_k[K];
    matrix[D, D] Rho_theta_sub;
    matrix[J, D] m_mult;
    matrix[J, D] theta_sub;

    // items
    for(k in 1:K){
        b_k[k] = m_b[ IDtext[k] ] + s_b[ IDtext[k] ] * zb_k[k];
    }

    // abilities
    Rho_theta_sub = multiply_lower_tri_self_transpose(L_Rho_theta_sub);
    for(j in 1:J){
        m_mult[j,] = rep_row_vector( a + b_G[ G[j] ] +
            b_A * (A[j] - min(A) ) +
            b_E[ E[j] ] +
            b_X[ X[j] ], D);
    }
}

```

```

    theta_sub = (L_Rho_theta_sub * ztheta_sub)';
    theta_sub = theta_sub + m_mult;
}

model{
    // declare
    real v;
    real p;

    // items
    m_b ~ normal(0, 1);
    s_b ~ exponential(2);
    zb_k ~ normal(0, 1);

    // abilities
    a ~ normal(0, 0.5);
    b_G ~ normal(0, 0.5);
    b_A ~ normal(0, 0.5);
    b_E ~ normal(0, 1);
    b_X ~ normal(0, 0.5);
    L_Rho_theta_sub ~ lkj_corr_cholesky(2);
    to_vector(ztheta_sub) ~ normal(0,1);

    // model
    for( i in 1:N ) {
        v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
        p = inv_logit(v);
        y[i] ~ bernoulli(p);
    }
}

## generated quantities{
##     vector[N] log_lik;
##     real v;
##     real p;
##
##     // likelihood
##     for( i in 1:N ) {
##         v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
##         p = inv_logit(v);
##         log_lik[i] = bernoulli_lpmf( y[i] | p);
##     }
## }
```

SOLV CP

```

data{
    // evaluation
    int N;
    int J;
    int K;
    int L;
    int D;
```

```

int IDj[N];
int IDk[N];
int IDl[N];
int IDd[N];
int GE[N];
real AG[N];
int ED[N];
int XP[N];
int y[N];

// individuals
int IDind[J];
int G[J];
real A[J];
int E[J];
int X[J];

// items
int IDitem[K];
int IDtext[K];
int IDdim[K];
}

parameters{
    // items
    real m_b[L];
    real<lower=0> s_b[L];
    real b_k[K];

    // betas
    real a;
    real b_G[2];
    real b_A;
    real b_E[3];
    real b_X[4];

    // abilities
    vector[J] theta;           // reading comprehension
    real<lower=0> loads[D];   // loadings
    corr_matrix[D] Rho_theta_sub; // sub-dimensions: lit, inf, ref
    vector[D] theta_sub[J];
}

model{
    // declare
    vector[J] m_theta;
    vector[D] m_mult[J];
    real v;
    real p;

    // items
    m_b ~ normal(0, 1);
}

```

```

s_b ~ exponential(2);
for(k in 1:K){           // priors
    b_k[k] ~ normal( m_b[ IDtext[k] ], s_b[ IDtext[k] ] );
}

// SOLV
a ~ normal(0, 0.5);
b_G ~ normal(0, 0.5);
b_A ~ normal(0, 0.5);
b_E ~ normal(0, 1);
b_X ~ normal(0, 0.5);
for(j in 1:J){
    m_theta[j] = a + b_G[ G[j] ] +
        b_A * ( A[j] - min(A) ) +
        b_E[ E[j] ] +
        b_X[ X[j] ];
}
theta ~ normal(m_theta, 1);
// setting the scale at this level

// FOLV
loads ~ lognormal(0, 0.5);
for(j in 1:J){
    m_mult[j,] = [ loads[1]*theta[j],
                    loads[2]*theta[j],
                    loads[3]*theta[j] ];
}
Rho_theta_sub ~ lkj_corr(2);
theta_sub ~ multi_normal( m_mult, Rho_theta_sub );
// also setting scale here

// model
for( i in 1:N ) {
    v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
    p = inv_logit(v);
    y[i] ~ bernoulli(p);
}
}

## generated quantities{
##     vector[N] log_lik;
##     real v;
##     real p;
##
##     // likelihood
##     for( i in 1:N ) {
##         v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
##         p = inv_logit(v);
##         log_lik[i] = bernoulli_lpmf( y[i] | p);
##     }
## }

```

SOLV NCP

```

data{
    // evaluation
    int N;
    int J;
    int K;
    int L;
    int D;
    int IDj[N];
    int IDk[N];
    int IDl[N];
    int IDd[N];
    int GE[N];
    real AG[N];
    int ED[N];
    int XP[N];
    int y[N];

    // individuals
    int IDind[J];
    int G[J];
    real A[J];
    int E[J];
    int X[J];

    // items
    int IDitem[K];
    int IDtext[K];
    int IDdim[K];
}

parameters{
    // items
    real m_b[L];
    real<lower=0> s_b[L];
    real zb_k[K];

    // betas
    real a;
    real b_G[2];
    real b_A;
    real b_E[3];
    real b_X[4];

    // abilities
    vector[J] ztheta;           // reading comprehension
    real<lower=0> loads[D];    // loadings
    cholesky_factor_corr[D] L_Rho_theta_sub; // sub-dimensions
    matrix[D, J] ztheta_sub;
}

transformed parameters{

```

```

real b_k[K];
vector[J] m_theta;
vector[J] theta; // reading comprehension
matrix[D, D] Rho_theta_sub;
matrix[J, D] m_mult;
matrix[J, D] theta_sub;

// items
for(k in 1:K){
    b_k[k] = m_b[ IDtext[k] ] + s_b[ IDtext[k] ] * zb_k[k];
}

// SOLV
for(j in 1:J){
    m_theta[j] = a + b_G[ G[j] ] +
        b_A * ( A[j] - min(A) ) +
        b_E[ E[j] ] +
        b_X[ X[j] ];
}
theta = m_theta + 1 * ztheta;
// setting the scale at this level

// FOLV
Rho_theta_sub = multiply_lower_tri_self_transpose(L_Rho_theta_sub);
for(j in 1:J){
    m_mult[j,] = to_row_vector( [ loads[1]*theta[j] ,
        loads[2]*theta[j] ,
        loads[3]*theta[j] ] );
}
theta_sub = m_mult + (L_Rho_theta_sub * ztheta_sub)';
// also setting scale here
}

model{
    // declare
    real v;
    real p;

    // items
    m_b ~ normal(0, 1);
    s_b ~ exponential(2);
    zb_k ~ normal(0, 1);

    // abilities
    a ~ normal(0, 0.5);
    b_G ~ normal(0, 0.5);
    b_A ~ normal(0, 0.5);
    b_E ~ normal(0, 1);
    b_X ~ normal(0, 0.5);
    ztheta ~ normal(0,1);
    L_Rho_theta_sub ~ lkj_corr_cholesky(2);
}

```

```

    loads ~ lognormal(0, 0.5);
    to_vector(ztheta_sub) ~ normal(0,1);

    // model
    for( i in 1:N ) {
        v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
        p = inv_logit(v);
        y[i] ~ bernoulli(p);
    }
}

## generated quantities{
##     vector[N] log_li;
##     real v;
##     real p;
##
##     // likelihood
##     for( i in 1:N ) {
##         v = theta_sub[ IDj[i], IDd[i] ] - b_k[ IDk[i] ];
##         p = inv_logit(v);
##         log_li[i] = bernoulli_lpmf( y[i] | p);
##     }
## }

```

Prior predictive investigation

Prior predictive

```

model_path = file.path(getwd(), 'models_prior')
model_list = list.files( model_path )
model_list = model_list[ str_detect(model_list, '.stan') ]

run_prior( models = model_list,
model_path = model_path,
model_out = file.path(getwd(), 'chains_prior'),
data_path = file.path(getwd(), 'data') )

```

Prior predictive function

```

# function:
#   run_prior
# description:
#   To run each prior simulation for each model
# arguments:
#   models = list of model to run located in model_path
#   model_path = path where all models are located
#   model_out = path where chains have to be saved
#   data_path = path where data per condition is located

run_prior = function(models, model_path, model_out, data_path){

# data list

```

```

data_list = list.files( data_path )
data_list = data_list[str_detect(data_list, 'ListFormat')]

for(j in 1:length(models) ){

  # compile model
  set_cmdstan_path('~/cmdstan')
  mod = cmdstan_model( file.path(model_path, models[j] ) )

  # generate base name
  base_nam = str_replace( data_list[1], 'ListFormat_',
    str_replace( models[j], '.stan', '_' ) )
  base_nam = str_replace( base_nam, '.RData', '' )

  # load data
  load( file.path(data_path, data_list[1] ) )

  # run model
  mod$sample(data = data_post,
    output_dir = model_out,
    output_basename = base_nam,
    chains=1, parallel_chains=1, adapt_delta=0.99)
}

}

```

Posterior predictive**Posterior predictive**

```

model_path = file.path(getwd(), 'models_post')
model_list = list.files( model_path )
model_list = model_list[ str_detect(model_list, '.stan') ]
model_list = model_list[c(1:2,5:6,3:4)]

run_post( models = model_list,
model_path = model_path,
model_out = file.path(getwd(), 'chains_post'),
data_path = file.path(getwd(), 'data') )

```

Posterior predictive function

```

# function:
#   run_post
# description:
#   To run each model for each data in all conditions
# arguments:
#   models = list of model to run located in model_path
#   model_path = path where all models are located
#   model_out = path where chains have to be saved
#   data_path = path where data per condition is located

```

```

run_post = function(models, model_path, model_out, data_path){

# data list
data_list = list.files( data_path )
data_list = data_list[str_detect(data_list, 'ListFormat')]

for(j in 1:length(models) ){

    # compile model
    set_cmdstan_path('~/cmdstan')
    mod = cmdstan_model( file.path(model_path, models[j] ) )

    for(i in 1:length(data_list) ){

        # generate base name
        base_nam = str_replace( data_list[i], 'ListFormat_',
                               str_replace(models[j], '.stan', '_') )
        base_nam = str_replace( base_nam, '.RData', '' )

        # load data
        load( file.path(data_path, data_list[i] ) )

        # run model
        t0 = proc.time()
        mod$sample(data = data_post,
                   output_dir = model_out,
                   output_basename = base_nam,
                   chains=3, parallel_chains=3, adapt_delta=0.99)
        t1 = proc.time()

        # saving time
        start = str_locate(base_nam, 'J')[2]
        m = str_sub( base_nam, start=1, end=(start-2) )
        J = str_sub( base_nam, start=start+1, end=(start+3) )

        start = str_locate(base_nam, 'l')[2]
        l = str_sub( base_nam, start=start+1, end=(start+3) )

        start = str_locate(base_nam, 'Ndata')[2]
        S = str_sub( base_nam, start=start+1, end=(start+2) )

        elapsed = (t1-t0)

        if(j==1 & i==1){
            time_elap = data.frame(
                Model=m,
                J=J,
                load=l,
                data=S,
                time=unlist(elapsed['elapsed']) )
        }
    }
}
}

```

```
    } else{
        time_elap = rbind(time_elap,
                           c(m, J, l, S,
                             unlist(elapsed['elapsed'])) )
    }

    # save time elapsed (saved at each iteration)
    write.csv( time_elap, row.names=F,
               file=file.path(model_out, 'time_elapsed.csv') )

}

}

}
```

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