ITF22519: Introduction to Operating Systems

Fall Semester, 2022

Lab11: InterProcess Communication(IPC) 1

Submission Deadline: November $8^{\rm th}$, 2022 23:59

You need to get at least 50 points to pass this lab assignment

In lab7 (Thread Synchronization), you have learned how different threads in **one process** coordinate with each other to solve **a common problem**. In some applications, different processes may have to coordinate with each other to solve the problem. These processes can be at the same computer or at different computers. In this lab, you will look at several approaches that two (or more) processes in **one machine** or in the same system communicate or coordinate their activities with each other. A quick question raised is: can two processes in the same computer communicate the same way as they are at two different computers?

IPC is nothing but a way for one process to exchange a piece of information with another process. They can communicate by using **Pipe**, **Signal**, **Shared Memory**, **Socket**, **Message Queue and Semaphores**. In this lab, we will go through the first three approaches.

1 Pipe

The simplest form of IPC is a **pipe**. In the textbook, page 44, "a pipe is a sort of pseudofile that can be used to connect two processes', as shown in Fig. 1. There are unnamed pipe and named pipe. The later is also called FIFO.

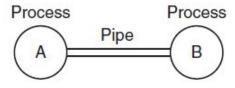


Figure 1: Two processes connected by a pipe (Figure 1-16 in the Textbook).

1.1 Unnamed Pipe

You have a bit experience with Pipe in lab1 assignment. When you pipe the output of one program into the input of another, you are creating an unnamed pipe. For example, this command in Bash would take output from ps and pipe it to less so that you can see it.

\$./ps -el | less

Another way to create an unnamed pipe is to use a special system call in C. If processes A and B wish to talk using a pipe, they must set it up in advance. When process A wants to send data to process B, it writes on the pipe as though it were an output file. In fact, the implementation of a pipe is very much like that of a file. Process B can read the data by reading from the pipe as though it were an input file. Thus, communication between processes in UNIX looks very much like ordinary file reads and writes. Stronger yet, the only way a process can discover that the output file it is writing on is not really a file, but a pipe, is by making a pipe(2) system call [Textbook].

The function in C to be used to create a pipe is pipe. This function creates a **unidirectional** pipe and returns a two element array where the first element is the read and the second element is to write end of the pipe. The pipe() function can be called before the fork() system call. Then, the child and parent processes can use it to communicate. Data written to the write end of the pipe is buffered by the kernel until it is read from the read end of the pipe. For more information about pipes, use pipe(2) and pipe(7).

Task 1

The program pipe_test.c uses unnamed pipe. Run the code example and explain the output.

- Run the code example and explain the output.
- Explain the code and the output of the program.
- How many processes are running?

1.2 Named Pipe

Another approach to create a pipe is a named pipe by using mkfifo command in your terminal or mkfifo(3) library call in C. A FIFO behaves exactly the same way as a pipe except that it has a name so that any process can reference to it.

Now, open two terminals in the same directory and create a new FIFO using mkfifo.

\$ mkfifo fifo_test

In one terminal, run the following command:

\$ cat fifo_test

This command is now watching FIFO and will show anything written to the FIFO. Now, in another terminal, type the following command:

```
$ echo "Hi FIFO" > fifo_test
```

2 Signals

You have been using signal so far but you may not be aware of it. Signal is a special command that a program receives from kernel mode in operating system. A signal is triggered by the CPU or the software (program) that runs on the CPU. When a process receives a signal, the default action happens unless the process has arranged to handle the signal. Here is one example of signal. When you press Ctrl-C in your terminal to close a program, you send SIGNIT (or kill) signal to that program. When you press Ctrl - Q to quit a program, you send SIGQUIT to the program. Another example of signal is the kill which you

look at in lab5. In this lab, the kill system call is the way users and user processes send signals. If a process is prepared to catch a particular signal, then when it arrives, a signal handler is run. If the process is not prepared to handle a signal, then its arrival kills the process (hence the name of the call) [Textbook]. Signal is used for communication among different processes in the the system. However, unlike other kind of IPC, signal does not send any data from one process to another, it only sends the signal. For more information about signal, use man page signal. Signals are well defined in Linux. However, you can define your own signals and signal handlers and use them for IPC. Lets do simple practice with Ctrl-C in Task 2.

Task 2

The program in sig_test.c handles the signal Ctrl - C when the signal is received. Compile and run the program sig_test.c and answer the following questions.

- What happens when you try to quit the program by using CTRL + C? Explain why.
- How the process is defined to handle the signal CTRL + C?
- How to exit the program?

3 Shared Memory

Shared memory or share memory space (SHM) is an IPC approach that allows different processes or applications to access to the shared memory region. All data in this area is accessible to any process which opens the SHM. Linux provides you with several POSIX shared memory APIs to practice with shared memory. As usual, man page is your best friend in Linux. Please use the man page for sgn_overview(7) and shm_open(3) for more information.

Note: In this lab, we only use POSIX shared memory APIs. If you use other share memory functions, it is likely that you are using System V Share memory. That may cause a bug that you do not know how to fix. Now, lets do a simple practice. Suppose that you have a data structure which consists of one string and one array of integer as the following:

```
struct SHM_SHARED_MEMORY {
    char a_string[100];
    int an_array[5];
};
```

If you want to put this data in the SHM, you first need to create a memory region which can be accessed by other processes. Use shm_open to open a SHM and name the SHM, for example "SharedMemory", as the following:

```
fd = shm_open("SharedMemory", O_CREAT | O_RDWR, S_IRUSR | S_IWUSR | S_IRGRP);
if (!fd) {
   perror("shm_open\n");
   return -1;
}
```

shm_open often goes with ftruncate. This function is used to set the size of the SHM. Noted that a newly created SHM has a length of zero.

```
if(ftruncate(fd, sizeof(struct SHM_SHARED_MEMORY))){
perror("ftruncate\n");
return -1;
}
```

```
process. POSIX API provides mmap() to do this.
shared_mem = mmap(NULL, sizeof(struct SHM_SHARED_MEMORY), PROT_READ | PROT_WRITE, MAP_SHARED, fd, 0);
It is better to check if mmap() is done or not
if(!shared_mem){
        perror("mmap\n");
        return -1;
}
if(close(fd)){
perror("close\n");
return -1;
Now that you have a shared memory region. Let put values for the string and for the integer array. You
can do this by
strcpy(shared_mem->a_string, "Hello");
for (i = 0; i < 5; i++){
shared_mem->an_array[i] = i*i;
Then, check if the SHM has the correct information you just have put in:
printf("Printing values stored in the shared memory ...\n");
printf("String is %s \n", shared_mem->a_string);
printf("Integers are %d  %d
                                                                                                   %d %d\n", shared_mem->an_array[0], shared_mem->an_array[1], shared_mem->array[1], sh
                                                                                     %d
Remember to unmap() the SHM after using
 int res = munmap(NULL, sizeof(struct SHM_SHARED_MEMORY));
if (res == -1){}
           perror("munmap");
           return 40;
}
The completed code for the example above as below
#include <stdio.h>
#include <stdlib.h>
#include <sys/mman.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <unistd.h>
#include <sys/wait.h>
#include <string.h>
struct SHM_SHARED_MEMORY{
              char a_string[100];
```

After creating the new SHM, you need to map the SHM into the virtual address space of the calling

int an_array[5];

};

```
int main(){
int fd;
// open the shared memory area, create it if it doesn't exist
fd = shm_open("SharedMemory", O_CREAT | O_RDWR, S_IRUSR | S_IWUSR | S_IRGRP);
            perror("shm_open\n");
            return -1;
}
// extend shared memory object as by default it's initialized with size 0
if(ftruncate(fd, sizeof(struct SHM_SHARED_MEMORY))){
            perror("ftruncate\n");
           return -1;
}
struct SHM_SHARED_MEMORY* shared_mem; //variable declaration
                        // map shared memory to process address space
shared_mem = mmap(NULL, sizeof(struct SHM_SHARED_MEMORY), PROT_READ | PROT_WRITE, MAP_SHARED, fd, 0);
 if(!shared_mem){
perror("mmap\n");
return -1;
if(close(fd)){
perror("close\n");
return -1;
strcpy(shared_mem->a_string, "Hello");
for (i = 0; i < 5; i++){
shared_mem->an_array[i] = i*i;
printf("Printing values stored in the shared memory ...\n");
printf("String is %s \n", shared_mem->a_string);
                                                                                                              %d\n", shared_mem->an_array[0], shared_mem->an_array[1], shared_mem->array[1], shared_mem->an_array[1], shared_mem->array[1], shared_mem->ar
printf("Integers are %d %d %d
                                                                                               %d
 int res = munmap(NULL, sizeof(struct SHM_SHARED_MEMORY));
 if (res == -1){}
perror("munmap");
return 40;
}
return 0;
}
```

- Create the source code file shm_open.c in your lab9 repository.
- Compile the code by using following command

```
$ gcc shm_open.c -lrt -o open
```

Note: Remember -lrt compilation command. In this command, -l flag is to link with the library whose name follows the flag, in this case is rt. Hence, the command -lrt is to tell the compiler to link with the rt library, or librt.

Now, make another process that reads the SHM created by your program in *shm_open.c* and then modifies the values in the SHM. The code below is for that purpose.

```
#include <stdlib.h>
#include <stdio.h>
#include <sys/mman.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <unistd.h>
#include <sys/wait.h>
#include <string.h>
struct SHM_SHARED_MEMORY{
     char a_string[100];
     int an_array[5];
};
int main(){
int fd;
// open the shared memory area, create it if it doesn't exist
fd = shm_open("SharedMemory", O_CREAT | O_RDWR, S_IRUSR | S_IWUSR | S_IRGRP);
if (!fd) {
     perror("shm_open\n");
     return -1;
}
// extend shared memory object as by default it's initialized with size 0
if(ftruncate(fd, sizeof(struct SHM_SHARED_MEMORY))){
        perror("ftruncate\n");
        return -1;
}
struct SHM_SHARED_MEMORY* shared_mem;
// map shared memory to process address space
shared_mem = mmap(NULL, sizeof(struct SHM_SHARED_MEMORY), PROT_READ | PROT_WRITE, MAP_SHARED, fd, 0);
if(!shared_mem){
        perror("mmap\n");
        return -1;
if(close(fd)){
        perror("close\n");
        return -1;
// Read from the shared memory
```

```
printf("Reading values from the shared memory\n");
 printf("String is %s \n", shared_mem->a_string);
 printf("Integers are %d %d
                                                                                                                                                                                                                                                                            %d
                                                                                                                                                                                                                                                                                                                                 %d
                                                                                                                                                                                                                                                                                                                                                                              %d\n", shared_mem->an_array[0], shared_mem->an_array[1], shared_mem->array[1], shared_mem->array[1]
 printf("Now, change the value of the first element...\n");
  shared_mem->an_array[0] = 42;
                                                                                                                                                                                                                                                                                                                                                                                 %d\n", shared_mem->an_array[0], shared_mem->an_array[1], shared_mem->array[1], shared_m
 printf("Integers are %d
                                                                                                                                                                                                                                          %d
                                                                                                                                                                                                                                                                                       %d
                                                                                                                                                                                                                                                                                                                                     %d
 // unmap
  int res = munmap(NULL, sizeof(struct SHM_SHARED_MEMORY));
  if (res == -1){
                                                                        perror("munmap");
                                                                        return 40;
return 0;
```

Task 3

- Create the source code file *shm_read.c* in your lab11 repository.
- Compile the code by using following command

```
$ gcc shm_read.c -lrt -o read
```

• Run ./open in one terminal and ./read in another terminal. Add output in your report and explain how two programs work.

4 Exercises

4.1 Exercise 1 (33 pts)

Write two programs read_fifo.c and write_fifo.c which will be run on two terminals:

- write_fifo.c (while true): reads one line that user enters into one terminal and writes it to a named fifo.
- read_fifo.c (while true): reads any input from the same named fifo and print them out to the other terminal.
- Do we need to synchronize the two programs to ensure that the read operation will always happen after the write operation?

4.2 Exercise 2 (33 pts)

Compile and run the program sig_fork.c and answer the following questions:

- Explain the output?
- Why the variable count has different values?
- Specify how variable count is increased in child and parent processes.

4.3 Exercise 3 (34 pts)

Compile and run the files shm_test1.c and shm_test2.c. Observe the output by running both applications at the same time. Answer the following questions:

- What is the output if you run both at the same time and calling shm_test1.c first?
- What is the output if you run both at the same time and calling shm_test2.c first?
- Why is shm_test2.c causing a segfault? How could this be fixed?

5 What To Submit

Upload your related files and reports to GitHub repository.