

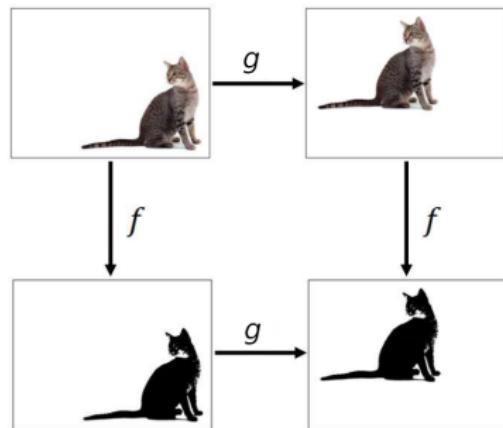
# Stochastic Neural Network Symmetrisation in Markov Categories

Rob Cornish

Department of Statistics, University of Oxford

September 23, 2025

# Motivation: symmetry



<https://www.doc.ic.ac.uk/~bkainz/teaching/DL/notes/equivariance.pdf>

## Formulation

A neural network  $f : X \rightarrow Y$  is **equivariant** with respect to the actions of a group  $G$  if

$$f(g \cdot x) = g \cdot f(x)$$

for all  $x \in X$  and  $g \in G$

## Formulation

A neural network  $f : X \rightarrow Y$  is **equivariant** with respect to the actions of a group  $G$  if

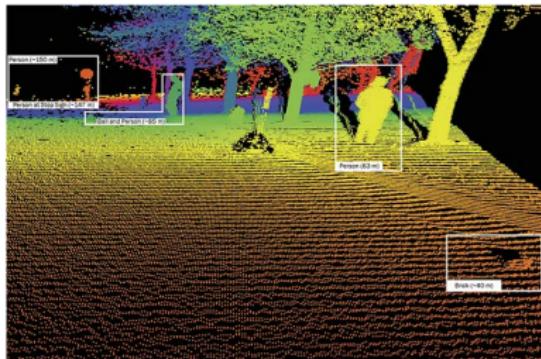
$$f(g \cdot x) = g \cdot f(x)$$

for all  $x \in X$  and  $g \in G$

In this example:

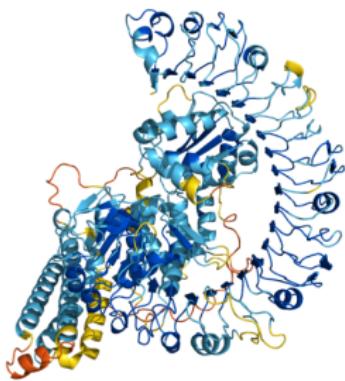
- $X$  is set of images
- $Y$  is set of binarisations
- $G$  is the group of translations

# Many other examples

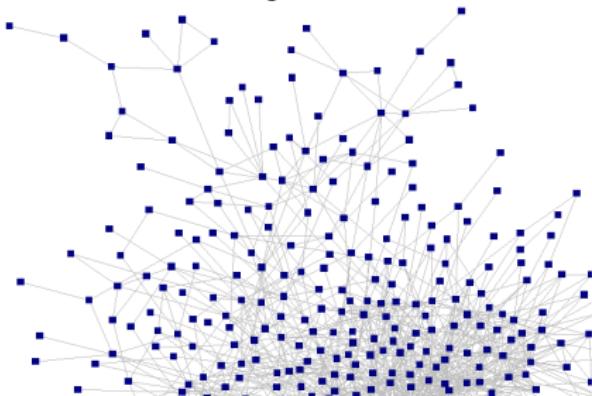


[photonics.com](http://photonics.com)

[alphafold.ebi.ac.uk](http://alphafold.ebi.ac.uk)



[orgnet.com](http://orgnet.com)



## Key question

How can we **parameterise** an equivariant neural network?

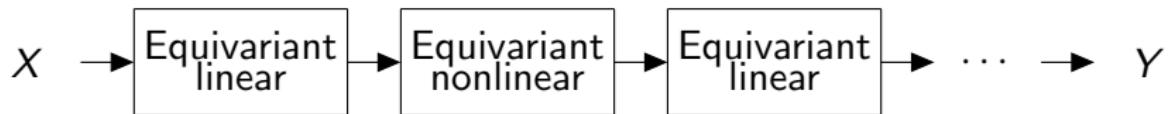
## Key question

How can we **parameterise** an equivariant neural network?

Two key approaches: **intrinsic equivariance** and **symmetrisation**

# Intrinsic equivariance

Overall model  $f : X \rightarrow Y$  has form



where the individual layers are all equivariant via e.g. **weight tying**

# Intrinsic equivariance

Overall model  $f : X \rightarrow Y$  has form



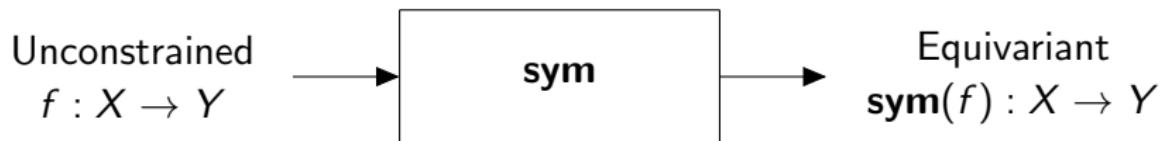
where the individual layers are all equivariant via e.g. **weight tying**

A natural idea, but:

- Requires **hand engineering** for each case
- Nonlinear layers are often **ad hoc**
- Can be **brittle** at scale (e.g. AlphaFold 2 vs. 3)

# Symmetrisation

Recent interest instead in **symmetrisation**:



# Symmetrisation

Recent interest instead in **symmetrisation**:



Here  $f$  is **completely general** and opaque

## Symmetrisation: example

Early example is **Janossy pooling** [Murphy et al., 2019]: given

$$f : X^n \rightarrow \mathbb{R}^d,$$

the following function  $X^n \rightarrow \mathbb{R}^n$  is always **permutation invariant**:

$$\frac{1}{n!} \sum_{\sigma \in S_n} f(x_{\sigma(1)}, \dots, x_{\sigma(n)})$$

## Symmetrisation: other examples

Other recent examples, given  $f : X \rightarrow \mathbb{R}^d$  and a group  $G$

$$\frac{1}{|\mathcal{F}(x)|} \sum_{g \in \mathcal{F}(x)} g \cdot f(g^{-1} \cdot x) \quad [\text{Puny et al., 2022}]$$

$$h(x) \cdot f(h(x)^{-1} \cdot x) \quad [\text{Kaba et al., 2023}]$$

$$\mathbb{E}_{\mathbf{G} \sim p(g|x)} [\mathbf{G} \cdot f(\mathbf{G}^{-1} \cdot x)] \quad [\text{Kim et al., 2023}]$$

## Symmetrisation: other examples

Other recent examples, given  $f : X \rightarrow \mathbb{R}^d$  and a group  $G$

$$\frac{1}{|\mathcal{F}(x)|} \sum_{g \in \mathcal{F}(x)} g \cdot f(g^{-1} \cdot x) \quad [\text{Puny et al., 2022}]$$

$$h(x) \cdot f(h(x)^{-1} \cdot x) \quad [\text{Kaba et al., 2023}]$$

$$\mathbb{E}_{\mathbf{G} \sim p(g|x)} [\mathbf{G} \cdot f(\mathbf{G}^{-1} \cdot x)] \quad [\text{Kim et al., 2023}]$$

Under some conditions, each is equivariant in  $x \in X$ , even if  $f$  is **arbitrarily complex**

## Some research questions

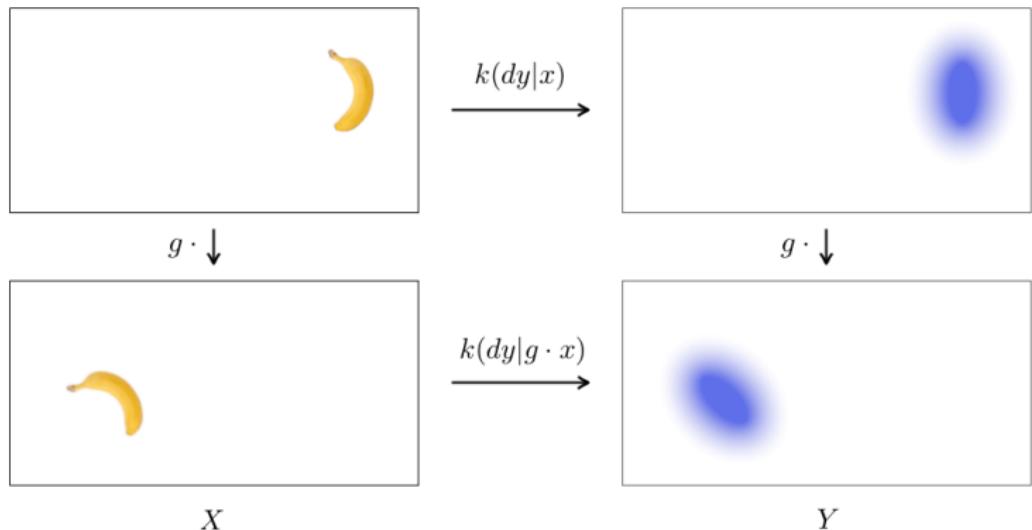
Where do these methods “come from”? Are they the **only possibilities**?

## Some research questions

Where do these methods “come from”? Are they the **only possibilities**?

What about **stochastic** models?

# Stochastic equivariance: illustration



Contribution

# Methodological contribution

## Stochastic Neural Network Symmetrisation in Markov Categories

Rob Cornish

*Department of Statistics, University of Oxford*

### Contribution

A general theory of symmetrisation procedures that extends to **stochastic models** (plus various other methodological extensions)

## Theoretical contribution

Underlying theory of [Cornish, 2024] is developed in terms of **Markov categories**

## Theoretical contribution

Underlying theory of [Cornish, 2024] is developed in terms of **Markov categories**

### Implication

Markov categories can produce **novel methodology** for AI (not just retrospective simplifications)

## Theoretical contribution

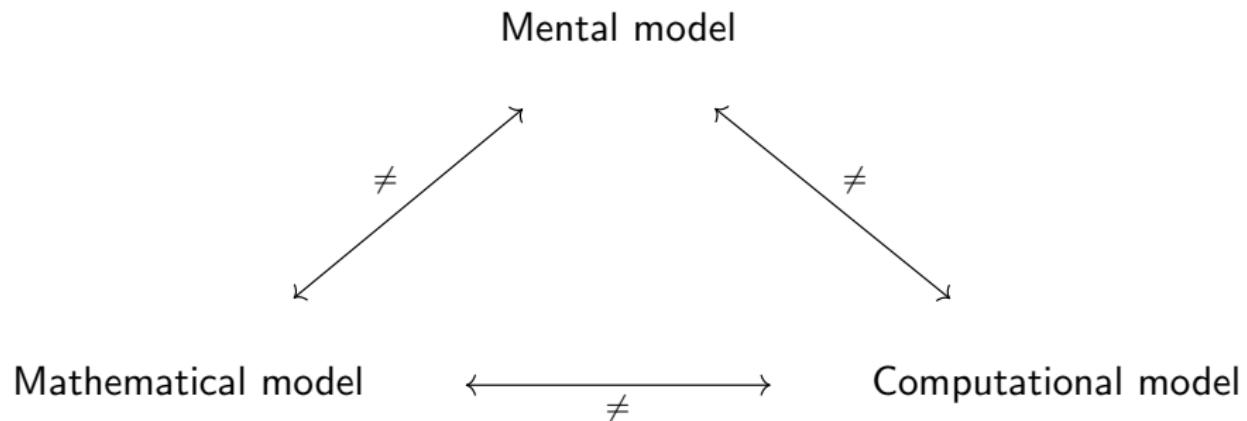
Underlying theory of [Cornish, 2024] is developed in terms of **Markov categories**

### Implication

Markov categories can produce **novel methodology** for AI (not just retrospective simplifications)

But why care in the first place?

## Digression: three models



# Probabilistic reasoning

For probabilistic settings, a major reason for this is **measure theory**

# Probabilistic reasoning

For probabilistic settings, a major reason for this is **measure theory**

In practice, we often prefer semi-formal “density” notation, e.g.

$$p(x, y) = p(x) p(y|x)$$

# Probabilistic reasoning

For probabilistic settings, a major reason for this is **measure theory**

In practice, we often prefer semi-formal “density” notation, e.g.

$$p(x, y) = p(x) p(y|x)$$

Works well in many cases, but have to write things like

$$x \sim p_\theta(x|z \sim q_\phi(z|x, y), y)$$

which can make things actually **more complex**

## Example: stochastic equivariance in densities

A density  $p(y|x)$  is **equivariant** if (provided  $g \cdot$  has unit Jacobian)

$$p(y|x) = p(g \cdot y|g \cdot x)$$

## Example: stochastic equivariance in densities

A density  $p(y|x)$  is **equivariant** if (provided  $g \cdot$  has unit Jacobian)

$$p(y|x) = p(g \cdot y|g \cdot x)$$

Hard to see the input/output interpretation of equivariance here

# The Markov categorical approach

Markov categories **abstract away** painful technical details, but **maintains rigour**

# The Markov categorical approach

Markov categories **abstract away** painful technical details, but **maintains rigour**

Theory becomes very conceptual and diagrammatic, and closer to mental and computational models (e.g. **DisCoPy**)

# The Markov categorical approach

Markov categories **abstract away** painful technical details, but **maintains rigour**

Theory becomes very conceptual and diagrammatic, and closer to mental and computational models (e.g. **DisCoPy**)

Empirically, this was actually how this work came about!

Symmetrisation procedures in Markov categories

# Markov kernels

The key example of a Markov category is **Stoch**:

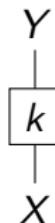
- Objects  $X$  and  $Y$  are **measurable spaces**
- Morphisms  $k : X \rightarrow Y$  are **Markov kernels**  $k(dy|x)$

# Markov kernels

The key example of a Markov category is **Stoch**:

- Objects  $X$  and  $Y$  are **measurable spaces**
- Morphisms  $k : X \rightarrow Y$  are **Markov kernels**  $k(dy|x)$

Think of kernels as **conditional distributions** or stochastic maps

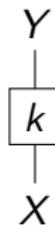


# Markov kernels

The key example of a Markov category is **Stoch**:

- Objects  $X$  and  $Y$  are **measurable spaces**
- Morphisms  $k : X \rightarrow Y$  are **Markov kernels**  $k(dy|x)$

Think of kernels as **conditional distributions** or stochastic maps



Can formalise as functions  $k : \Sigma_Y \times X \rightarrow [0, 1]$  satisfying some conditions

# Markov categories

Definition ([Fritz, 2020], [Cho and Jacobs, 2019])

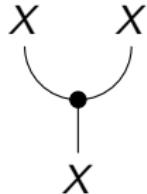
A **Markov category** is a semicartesian symmetric monoidal category  $(\mathbf{C}, \otimes, I)$  in which every object  $X$  is equipped with a commutative comonoid structure  $(\mathbf{copy}_X, \mathbf{del}_X)$  that is suitably compatible with  $\otimes$ .

# Markov categories

Definition ([Fritz, 2020], [Cho and Jacobs, 2019])

A **Markov category** is a semicartesian symmetric monoidal category  $(\mathbf{C}, \otimes, I)$  in which every object  $X$  is equipped with a commutative comonoid structure  $(\mathbf{copy}_X, \mathbf{del}_X)$  that is suitably compatible with  $\otimes$ .

Essentially, we can compose **sequentially** and **in parallel**, and can **swap**, **copy**, and **discard** information:



# Examples of Markov categories

Many examples of Markov categories including:

Category	Objects	Morphisms
<b>Stoch</b>	Measurable spaces	Markov kernels
<b>BorelStoch</b>	Standard Borel spaces	Markov kernels
<b>TopStoch</b>	Topological spaces	Continuous Markov kernels
:		

# Examples of Markov categories

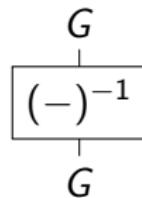
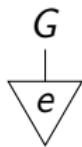
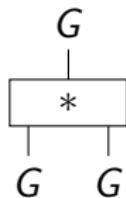
Many examples of Markov categories including:

Category	Objects	Morphisms
<b>Stoch</b>	Measurable spaces	Markov kernels
<b>BorelStoch</b>	Standard Borel spaces	Markov kernels
<b>TopStoch</b>	Topological spaces	Continuous Markov kernels
⋮		
<b>Set</b>	Sets	Functions
<b>Meas</b>	Measurable spaces	Measurable functions
<b>Top</b>	Topological spaces	Continuous functions

Theory is now “write once, run anywhere”

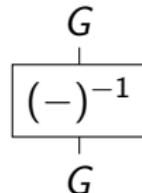
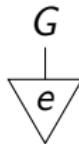
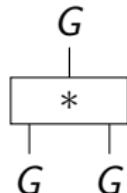
# Groups and actions

A **group** in a Markov category  $\mathbf{C}$  is an object  $G$  equipped with

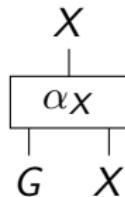


# Groups and actions

A **group** in a Markov category  $\mathbf{C}$  is an object  $G$  equipped with

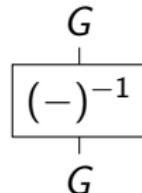
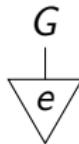
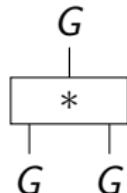


An **action** of a group  $G$  is a morphism

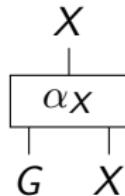


# Groups and actions

A **group** in a Markov category  $\mathbf{C}$  is an object  $G$  equipped with



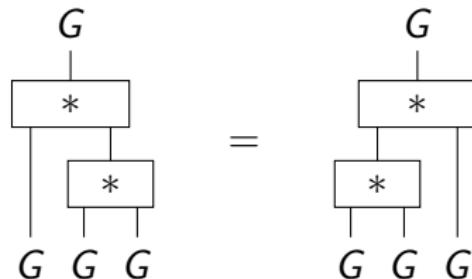
An **action** of a group  $G$  is a morphism



Both satisfy the usual axioms (expressed in diagrams)

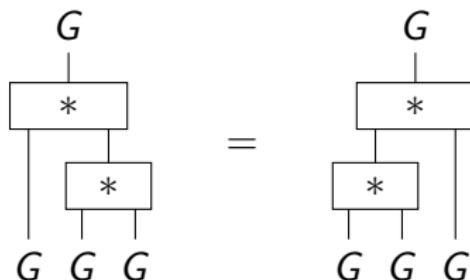
## Example: associativity

Multiplication must satisfy:



## Example: associativity

Multiplication must satisfy:



In **Set**, this just recovers **associativity**: for all  $g, g', g'' \in G$  we have

$$g(g'g'') = (gg')g''$$

# Equivariance

A morphism  $k : X \rightarrow Y$  is **equivariant** with respect to  $\alpha_X$  and  $\alpha_Y$  if

$$\begin{array}{c} Y \\ | \\ k \\ | \\ \alpha_X \\ | \\ G \quad X \end{array} = \begin{array}{c} Y \\ | \\ \alpha_Y \\ | \\ k \\ | \\ G \quad X \end{array}$$

# Equivariance

A morphism  $k : X \rightarrow Y$  is **equivariant** with respect to  $\alpha_X$  and  $\alpha_Y$  if

$$\begin{array}{ccc} Y & & Y \\ \downarrow k & = & \downarrow \alpha_Y \\ \alpha_X & & \\ \downarrow G & X & \downarrow G & X \\ \end{array}$$

When the morphisms of  $\mathbf{C}$  are functions, this gives the usual

$$k(g \cdot x) = g \cdot k(x)$$

# Equivariance

A morphism  $k : X \rightarrow Y$  is **equivariant** with respect to  $\alpha_X$  and  $\alpha_Y$  if

$$\begin{array}{c} Y \\ | \\ k \\ | \\ \alpha_X \\ | \\ G \quad X \end{array} = \begin{array}{c} Y \\ | \\ \alpha_Y \\ | \\ k \\ | \\ G \quad X \end{array}$$

When the morphisms of  $\mathbf{C}$  are functions, this gives the usual

$$k(g \cdot x) = g \cdot k(x)$$

For Markov kernels, this gives **stochastic equivariance**:

$$k(dy|g \cdot x) = g \cdot k(dy|x)$$

# Markov category of equivariant maps

## Theorem

*Given a group  $G$  in a Markov category  $\mathbf{C}$ , always obtain a Markov category  $\mathbf{C}^G$  where:*

# Markov category of equivariant maps

## Theorem

Given a group  $G$  in a Markov category  $\mathbf{C}$ , always obtain a Markov category  $\mathbf{C}^G$  where:

- Objects are pairs  $(X, \alpha_X)$ , where  $\alpha_X$  is an action of  $G$  on  $X$

# Markov category of equivariant maps

## Theorem

Given a group  $G$  in a Markov category  $\mathbf{C}$ , always obtain a Markov category  $\mathbf{C}^G$  where:

- Objects are pairs  $(X, \alpha_X)$ , where  $\alpha_X$  is an action of  $G$  on  $X$
- Morphisms  $(X, \alpha_X) \rightarrow (Y, \alpha_Y)$  are equivariant w.r.t.  $\alpha_X$  and  $\alpha_Y$

# Markov category of equivariant maps

## Theorem

Given a group  $G$  in a Markov category  $\mathbf{C}$ , always obtain a Markov category  $\mathbf{C}^G$  where:

- Objects are pairs  $(X, \alpha_X)$ , where  $\alpha_X$  is an action of  $G$  on  $X$
- Morphisms  $(X, \alpha_X) \rightarrow (Y, \alpha_Y)$  are equivariant w.r.t.  $\alpha_X$  and  $\alpha_Y$
- Other components ( $\otimes$ , copy maps, etc.) are inherited from  $\mathbf{C}$

# Symmetrisation procedures

## Definition (for today)

A **symmetrisation procedure** is a function **sym** of the following form

$$\underbrace{\mathbf{C}(X, Y)}_{\text{Morphisms } X \rightarrow Y \text{ in } \mathbf{C}} \xrightarrow{\text{sym}} \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$$

# Symmetrisation procedures

## Definition (for today)

A **symmetrisation procedure** is a function **sym** of the following form

$$\underbrace{\mathbf{C}(X, Y)}_{\text{Morphisms } X \rightarrow Y \text{ in } \mathbf{C}} \xrightarrow{\text{sym}} \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$$

Despite generality, can characterise **all such functions** of this form

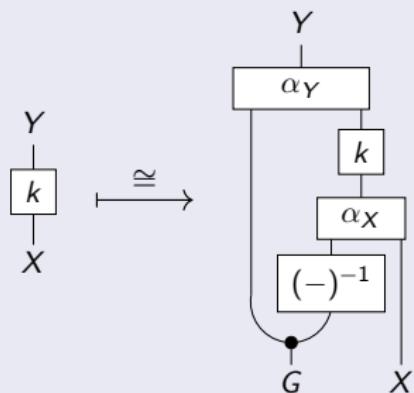
# Key result

## Theorem

*There is always a bijection*

$$\mathbf{C}(X, Y) \xrightarrow{\cong} \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y))$$

*defined as follows:*



# Categorical explanation

Arises from an **adjunction** of the form

$$\mathbf{C} \begin{array}{c} \xrightarrow{F} \\ \perp \\ \xleftarrow{U} \end{array} \mathbf{C}^G$$

where  $U(X, \alpha_X) := X$ , which gives

$$\begin{aligned}\mathbf{C}(X, Y) &= \mathbf{C}(U(X, \alpha_X), U(Y, \alpha_Y)) \\ &\cong \mathbf{C}^G(FU(X, \alpha_X), (Y, \alpha_Y)) \\ &\cong \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y))\end{aligned}$$

# A general strategy for symmetrisation

## Corollary

*Every symmetrisation procedure  $\mathbf{C}(X, Y) \xrightarrow{\text{sym}} \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$  can be expressed as a composition*

$$\mathbf{C}(X, Y) \xrightarrow{\cong} \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y)) \longrightarrow \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y)),$$

*and vice versa, for some choice of function in the second step.*

# A general strategy for symmetrisation

## Corollary

*Every symmetrisation procedure  $\mathbf{C}(X, Y) \xrightarrow{\text{sym}} \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$  can be expressed as a composition*

$$\mathbf{C}(X, Y) \xrightarrow{\cong} \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y)) \longrightarrow \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y)),$$

*and vice versa, for some choice of function in the second step.*

Only (natural) choice for second step is **precomposition**:

$$(G, *) \otimes (X, \alpha_X) \xrightarrow{k} (Y, \alpha_Y)$$

# A general strategy for symmetrisation

## Corollary

*Every symmetrisation procedure  $\mathbf{C}(X, Y) \xrightarrow{\text{sym}} \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$  can be expressed as a composition*

$$\mathbf{C}(X, Y) \xrightarrow{\cong} \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y)) \longrightarrow \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y)),$$

*and vice versa, for some choice of function in the second step.*

Only (natural) choice for second step is **precomposition**:

$$(X, \alpha_X) \xrightarrow{\Gamma} (G, *) \otimes (X, \alpha_X) \xrightarrow{k} (Y, \alpha_Y)$$

i.e.  $k \mapsto k \circ \Gamma$

## Precomposition morphism

Natural to require that if  $k$  is already  $G$ -equivariant, then

$$\mathbf{sym}(k) = k$$

i.e. procedure is **stable** on equivariant inputs

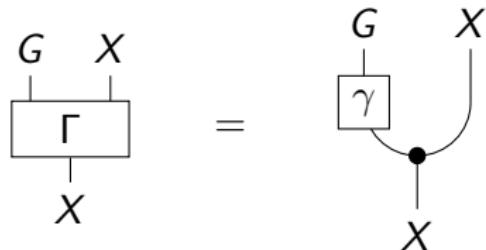
## Precomposition morphism

Natural to require that if  $k$  is already  $G$ -equivariant, then

$$\mathbf{sym}(k) = k$$

i.e. procedure is **stable** on equivariant inputs

Can show: holds iff precomposition morphism has the form



where  $\gamma : (X, \alpha_X) \rightarrow (G, *)$  in  $\mathbf{C}^G$

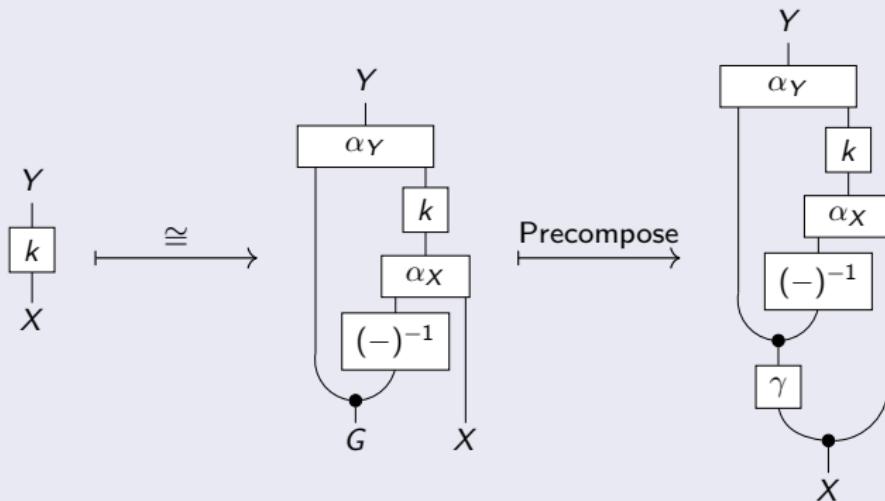
# End-to-end procedure

## Algorithm

Given a suitable  $\gamma$ , overall procedure now has form

$$\mathbf{C}(X, Y) \xrightarrow{\cong} \mathbf{C}^G((G, *) \otimes (X, \alpha_X), (Y, \alpha_Y)) \longrightarrow \mathbf{C}^G((X, \alpha_X), (Y, \alpha_Y))$$

where these steps are computed as follows:



# Instantiation in **Set**

## Corollary

Suppose  $G$  is a group acting on  $X$  and  $Y$ . If  $k : X \rightarrow Y$  is any function, and  $\gamma : X \rightarrow G$  is equivariant (where  $G$  acts on itself by left multiplication), then the following defines an equivariant function  $X \rightarrow Y$  given  $x \in X$ :

$$\gamma(x) \cdot k(\gamma(x)^{-1} \cdot x)$$

# Instantiation in **Set**

## Corollary

Suppose  $G$  is a group acting on  $X$  and  $Y$ . If  $k : X \rightarrow Y$  is any function, and  $\gamma : X \rightarrow G$  is equivariant (where  $G$  acts on itself by left multiplication), then the following defines an equivariant function  $X \rightarrow Y$  given  $x \in X$ :

$$\gamma(x) \cdot k(\gamma(x)^{-1} \cdot x)$$

Exactly recovers **canonicalisation** [Kaba et al., 2023]

## Instantiation in **Stoch**

Also obtain a novel procedure for **stochastic symmetrisation**

# Instantiation in Stoch

Also obtain a novel procedure for **stochastic symmetrisation**

## Corollary

Suppose  $G$  is a measurable group acting measurably on  $X$  and  $Y$ . If  $k : X \rightarrow Y$  is any Markov kernel, and  $\gamma : X \rightarrow G$  is stochastically equivariant (where  $G$  acts on itself by left multiplication), then the following sampling process given  $x \in X$  defines a stochastically equivariant Markov kernel  $X \rightarrow Y$ :

$$\mathbf{G} \sim \gamma(dg|x) \quad \mathbf{Y} \sim k(dy|\mathbf{G}^{-1} \cdot x) \quad \text{return } \mathbf{G} \cdot \mathbf{Y}$$

# Instantiation in Stoch

Also obtain a novel procedure for **stochastic symmetrisation**

## Corollary

Suppose  $G$  is a measurable group acting measurably on  $X$  and  $Y$ . If  $k : X \rightarrow Y$  is any Markov kernel, and  $\gamma : X \rightarrow G$  is stochastically equivariant (where  $G$  acts on itself by left multiplication), then the following sampling process given  $x \in X$  defines a stochastically equivariant Markov kernel  $X \rightarrow Y$ :

$$\mathbf{G} \sim \gamma(dg|x) \quad \mathbf{Y} \sim k(dy|\mathbf{G}^{-1} \cdot x) \quad \text{return } \mathbf{G} \cdot \mathbf{Y}$$

Note: technically should define this kernel as a function  $\Sigma_Y \times X \rightarrow [0, 1]$  satisfying a measurability condition...

# Extensions

The paper contains various extensions:

- Deterministic symmetrisation via **averaging**
- Symmetrisation **along a homomorphism**  $\varphi : H \rightarrow G$
- **Compositional** usage
- **Recursive** usage to obtain  $\gamma$

# Extensions

The paper contains various extensions:

- Deterministic symmetrisation via **averaging**
- Symmetrisation **along a homomorphism**  $\varphi : H \rightarrow G$
- **Compositional** usage
- **Recursive** usage to obtain  $\gamma$

Also many examples:

- Compact groups
- Translation groups
- Direct and semidirect products
- Even  $GL(d, \mathbb{R})$

# Extensions

The paper contains various extensions:

- Deterministic symmetrisation via **averaging**
- Symmetrisation **along a homomorphism**  $\varphi : H \rightarrow G$
- **Compositional** usage
- **Recursive** usage to obtain  $\gamma$

Also many examples:

- Compact groups
- Translation groups
- Direct and semidirect products
- Even  $GL(d, \mathbb{R})$

Markov categories allow describing all this in a **uniform** and coherent way

## Numerical results

## Follow-up work

# SYMDIFF: EQUIVARIANT DIFFUSION VIA STOCHASTIC SYMMETRISATION

**Leo Zhang, Kianoosh Ashouritaklimi, Yee Whye Teh, Rob Cornish**  
Department of Statistics, University of Oxford



# Overview

Recall that **denoising diffusion models** consist of forward and backwards processes defined as

$$q(\mathbf{z}_{0:T}) = q(\mathbf{z}_0) \prod_{t=1}^T q(\mathbf{z}_t | \mathbf{z}_{t-1}) \quad p_\theta(\mathbf{z}_{0:T}) = p(\mathbf{z}_T) \prod_{t=1}^T p_\theta(\mathbf{z}_{t-1} | \mathbf{z}_t)$$

# Overview

Recall that **denoising diffusion models** consist of forward and backwards processes defined as

$$q(\mathbf{z}_{0:T}) = q(\mathbf{z}_0) \prod_{t=1}^T q(\mathbf{z}_t | \mathbf{z}_{t-1}) \quad p_\theta(\mathbf{z}_{0:T}) = p(\mathbf{z}_T) \prod_{t=1}^T p_\theta(\mathbf{z}_{t-1} | \mathbf{z}_t)$$

The idea is:

- $q(\mathbf{z}_0)$  is the data distribution
- $q(\mathbf{z}_T) \approx p(\mathbf{z}_T)$  is Gaussian
- Try to learn  $p_\theta(\mathbf{z}_0) \approx q(\mathbf{z}_0)$

# Overview

Recall that **denoising diffusion models** consist of forward and backwards processes defined as

$$q(\mathbf{z}_{0:T}) = q(\mathbf{z}_0) \prod_{t=1}^T q(\mathbf{z}_t | \mathbf{z}_{t-1}) \quad p_\theta(\mathbf{z}_{0:T}) = p(\mathbf{z}_T) \prod_{t=1}^T p_\theta(\mathbf{z}_{t-1} | \mathbf{z}_t)$$

The idea is:

- $q(\mathbf{z}_0)$  is the data distribution
- $q(\mathbf{z}_T) \approx p(\mathbf{z}_T)$  is Gaussian
- Try to learn  $p_\theta(\mathbf{z}_0) \approx q(\mathbf{z}_0)$

Often want  $p_\theta(\mathbf{z}_{t-1} | \mathbf{z}_t)$  to be equivariant (e.g. molecular data)

## Strategy for equivariant diffusion

Previous work has enforced stochastic equivariance by setting

$$p_{\theta}(\mathbf{z}_{t-1}|\mathbf{z}_t) := \mathcal{N}(\mathbf{z}_{t-1}; \mu_{\theta}(\mathbf{z}_t), \sigma_t^2 I)$$

where  $\mu_{\theta}$  is **intrinsically equivariant** (e.g. a graph neural network)

## Strategy for equivariant diffusion

Previous work has enforced stochastic equivariance by setting

$$p_\theta(\mathbf{z}_{t-1}|\mathbf{z}_t) := \mathcal{N}(\mathbf{z}_{t-1}; \mu_\theta(\mathbf{z}_t), \sigma_t^2 I)$$

where  $\mu_\theta$  is **intrinsically equivariant** (e.g. a graph neural network)

We instead take

$$p_\theta(\mathbf{z}_{t-1}|\mathbf{z}_t) := \mathbf{sym}_{\gamma_\theta}(k_\theta)(\mathbf{z}_{t-1}|\mathbf{z}_t)$$

where  $k_\theta$  and  $\gamma_\theta$  may leverage **arbitrary neural networks**

# SymDiff training for $E(3)$ -equivariance

---

**Algorithm 1** SYMDIFF training step

---

- 1: Sample  $\mathbf{z}_0 \sim p_{\text{data}}(\mathbf{z}_0)$ ,  $t \sim \text{Unif}(\{1, \dots, T\})$  and  $\epsilon \sim \mathcal{N}_{\mathcal{U}}(0, \mathbf{I})$
  - 2:  $\mathbf{z}_t \leftarrow \alpha_t \mathbf{z}_0 + \sigma_t \epsilon$
  - 3: Sample  $R_0$  from the Haar measure on  $O(3)$  and  $\eta \sim \nu(d\eta)$
  - 4:  $R \leftarrow R_0 \cdot f_{\theta}(R_0^T \cdot \mathbf{z}_t, \eta)$
  - 5: Take gradient descent step with  $\nabla_{\theta} \frac{1}{2} w(t) \|\epsilon - R \cdot \epsilon_{\theta}(R^T \cdot \mathbf{z}_t)\|^2$
-

# SymDiff training for $E(3)$ -equivariance

---

**Algorithm 1** SYMDIFF training step

---

- 1: Sample  $\mathbf{z}_0 \sim p_{\text{data}}(\mathbf{z}_0)$ ,  $t \sim \text{Unif}(\{1, \dots, T\})$  and  $\epsilon \sim \mathcal{N}_{\mathcal{U}}(0, \mathbf{I})$
  - 2:  $\mathbf{z}_t \leftarrow \alpha_t \mathbf{z}_0 + \sigma_t \epsilon$
  - 3: Sample  $R_0$  from the Haar measure on  $O(3)$  and  $\eta \sim \nu(d\eta)$
  - 4:  $R \leftarrow R_0 \cdot f_{\theta}(R_0^T \cdot \mathbf{z}_t, \eta)$
  - 5: Take gradient descent step with  $\nabla_{\theta} \frac{1}{2} w(t) \| \epsilon - R \cdot \epsilon_{\theta}(R^T \cdot \mathbf{z}_t) \|^2$
- 

Resembles a **learned data augmentation** that is deployed at sampling time

## Results

We obtained better performance compared with an intrinsic baseline (EDM [Hoogeboom et al., 2022]), and on par or better results compared with more sophisticated molecular models

# Results

We obtained better performance compared with an intrinsic baseline (EDM [Hoogeboom et al., 2022]), and on par or better results compared with more sophisticated molecular models

Table 1: Test NLL, atom stability, molecular stability, validity and uniqueness on QM9 for 10,000 samples and 3 evaluation runs. We omit the results for NLL where not available.

Method	NLL ↓	Atm. stability (%) ↑	Mol. stability (%) ↑	Val. (%) ↑	Uniq. (%) ↑
GeoLDM	–	98.90 ± 0.10	89.40 ± 0.50	93.80 ± 0.40	92.70 ± 0.50
MUDiff	<b>-135.50</b> ± 2.10	98.80 ± 0.20	<b>89.90</b> ± 1.10	95.30 ± 1.50	<b>99.10</b> ± 0.50
END	–	98.90 ± 0.00	89.10 ± 0.10	94.80 ± 0.10	92.60 ± 0.20
EDM	-110.70 ± 1.50	98.70 ± 0.10	82.00 ± 0.40	91.90 ± 0.50	90.70 ± 0.60
SymDiff*	-133.79 ± 1.33	<b>98.92</b> ± 0.03	89.65 ± 0.10	<b>96.36</b> ± 0.27	97.66 ± 0.22
SymDiff	-129.35 ± 1.07	98.74 ± 0.03	87.49 ± 0.23	95.75 ± 0.10	97.89 ± 0.26
SymDiff-H	-126.53 ± 0.90	98.57 ± 0.07	85.51 ± 0.18	95.22 ± 0.18	97.98 ± 0.09
DiT-Aug	-126.81 ± 1.69	98.64 ± 0.03	85.85 ± 0.24	95.10 ± 0.17	97.98 ± 0.08
DiT	-127.78 ± 2.49	98.23 ± 0.04	81.03 ± 0.25	94.71 ± 0.31	97.98 ± 0.12
Data		99.00	95.20	97.8	100

Thank you!

# References I

- Ryan L. Murphy, Balasubramaniam Srinivasan, Vinayak Rao, and Bruno Ribeiro. Janossy pooling: Learning deep permutation-invariant functions for variable-size inputs. In *International Conference on Learning Representations*, 2019. URL <https://openreview.net/forum?id=BJluy2RcFm>.
- Omri Puny, Matan Atzmon, Edward J. Smith, Ishan Misra, Aditya Grover, Heli Ben-Hamu, and Yaron Lipman. Frame averaging for invariant and equivariant network design. In *International Conference on Learning Representations*, 2022. URL <https://openreview.net/forum?id=zIUyj55nXR>.
- Sékou-Oumar Kaba, Arnab Kumar Mondal, Yan Zhang, Yoshua Bengio, and Siamak Ravanbakhsh. Equivariance with learned canonicalization functions. In Andreas Krause, Emma Brunskill, Kyunghyun Cho, Barbara Engelhardt, Sivan Sabato, and Jonathan Scarlett, editors, *Proceedings of the 40th International Conference on Machine Learning*, volume 202 of *Proceedings of Machine Learning Research*, pages 15546–15566. PMLR, 23–29 Jul 2023. URL <https://proceedings.mlr.press/v202/kaba23a.html>.

## References II

- Jinwoo Kim, Dat Nguyen, Ayhan Suleymanzade, Hyeokjun An, and Seunghoon Hong. Learning probabilistic symmetrization for architecture agnostic equivariance. In A. Oh, T. Neumann, A. Globerson, K. Saenko, M. Hardt, and S. Levine, editors, *Advances in Neural Information Processing Systems*, volume 36, pages 18582–18612. Curran Associates, Inc., 2023. URL [https://proceedings.neurips.cc/paper\\_files/paper/2023/file/3b5c7c9c5c7bd77eb73d0baec7a07165-Paper-Conference.pdf](https://proceedings.neurips.cc/paper_files/paper/2023/file/3b5c7c9c5c7bd77eb73d0baec7a07165-Paper-Conference.pdf).
- Rob Cornish. Stochastic neural network symmetrisation in markov categories, 2024. URL <https://arxiv.org/abs/2406.11814>.
- Tobias Fritz. A synthetic approach to markov kernels, conditional independence and theorems on sufficient statistics. *Advances in Mathematics*, 370:107239, August 2020. ISSN 0001-8708. doi: 10.1016/j.aim.2020.107239. URL <http://dx.doi.org/10.1016/j.aim.2020.107239>.
- Kenta Cho and Bart Jacobs. Disintegration and bayesian inversion via string diagrams. *Mathematical Structures in Computer Science*, 29(7):938–971, March 2019. ISSN 1469-8072. doi: 10.1017/s0960129518000488. URL <http://dx.doi.org/10.1017/S0960129518000488>.

## References III

Emiel Hoogeboom, Víctor Garcia Satorras, Clément Vignac, and Max Welling.  
Equivariant diffusion for molecule generation in 3D. In Kamalika Chaudhuri,  
Stefanie Jegelka, Le Song, Csaba Szepesvari, Gang Niu, and Sivan Sabato,  
editors, *Proceedings of the 39th International Conference on Machine Learning*,  
volume 162 of *Proceedings of Machine Learning Research*, pages 8867–8887.  
PMLR, 17–23 Jul 2022. URL  
<https://proceedings.mlr.press/v162/hoogeboom22a.html>.

## Appendix

## Example $\gamma$

When  $G$  is compact, can choose  $\gamma : (X, \alpha_X) \rightarrow (G, *)$  as

$$\begin{array}{ccc} (G, *) & & (G, *) \\ \boxed{\gamma} & := & \nabla \lambda \\ (X, \alpha_X) & & (X, \alpha_X) \end{array}$$

where here  $\lambda : (I, \epsilon) \rightarrow (G, *)$  satisfies

$$\begin{array}{ccc} G & & G \\ * & = & * \\ \nabla \lambda & & \bullet \\ G & & G \end{array}$$

# Determinism via averaging

## Proposition

Suppose  $Y = \mathbb{R}^d$ , and denote

$$\mathbf{ave}(k)(x) := \int y k(dy|x)$$

If  $G$  acts linearly on  $Y$ , then this corresponds to a function

$$\mathbf{Stoch}^G((X, \alpha_X), (Y, \alpha_Y)) \xrightarrow{\mathbf{ave}} \mathbf{Stoch}_{\det}^G((X, \alpha_X), (Y, \alpha_Y)).$$

# Deterministic symmetrisation via averaging

Can combine averaging with stochastic symmetrisation:

$$\begin{aligned}\mathbf{Stoch}(X, Y) &\xrightarrow{\text{sym}} \mathbf{Stoch}^G((X, \alpha_X), (Y, \alpha_Y)) \\ &\xrightarrow{\text{ave}} \mathbf{Stoch}_{\text{det}}^G((X, \alpha_X), (Y, \alpha_Y))\end{aligned}$$

# Deterministic symmetrisation via averaging

Can combine averaging with stochastic symmetrisation:

$$\begin{aligned}\mathbf{Stoch}(X, Y) &\xrightarrow{\text{sym}^\gamma} \mathbf{Stoch}^G((X, \alpha_X), (Y, \alpha_Y)) \\ &\xrightarrow{\text{ave}} \mathbf{Stoch}_{\text{det}}^G((X, \alpha_X), (Y, \alpha_Y))\end{aligned}$$

When applied to a deterministic function  $f$ , the result is

$$\mathbb{E}_{\mathbf{G} \sim \gamma(dg|x)}[\mathbf{G} \cdot f(\mathbf{G}^{-1} \cdot x)]$$

which recovers the methods of Kim et al. [2023] and Puny et al. [2022]

# Deterministic symmetrisation via averaging

Can combine averaging with stochastic symmetrisation:

$$\begin{aligned}\mathbf{Stoch}(X, Y) &\xrightarrow{\text{sym}^\gamma} \mathbf{Stoch}^G((X, \alpha_X), (Y, \alpha_Y)) \\ &\xrightarrow{\text{ave}} \mathbf{Stoch}_{\text{det}}^G((X, \alpha_X), (Y, \alpha_Y))\end{aligned}$$

When applied to a deterministic function  $f$ , the result is

$$\mathbb{E}_{\mathbf{G} \sim \gamma(dg|x)}[\mathbf{G} \cdot f(\mathbf{G}^{-1} \cdot x)]$$

which recovers the methods of Kim et al. [2023] and Puny et al. [2022]

Note however that averaging is **expensive**, **approximate**, and **requires convexity** of  $Y$