

# An introduction to categorical probability theory

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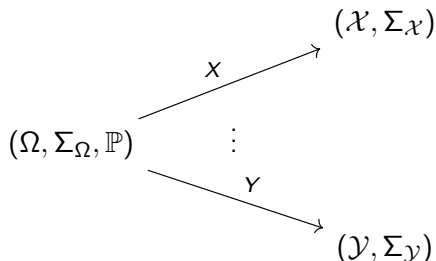
# Motivation

*It should be said: for someone trained in formal methods, the area of probability theory can be rather sloppy: everything is called 'P', types are hardly ever used, crucial ingredients (like distributions in expected values) are left implicit, basic notions (like conjugate prior) are introduced only via examples, calculation recipes and algorithms are regularly just given, without explanation, goal or justification, etc. This hurts, especially because there is so much beautiful mathematical structure around. (Jacobs [2019])*

# Classical probability theory

Start with an underlying **probability space**  $(\Omega, \Sigma_\Omega, \mathbb{P})$

Model phenomena of interest using **random variables** (i.e. **measurable functions**)  $X : \Omega \rightarrow \mathcal{X}$ , i.e.



Can consider many distinct  $\mathcal{X}$  and  $\mathcal{Y}$ , but  $\Omega$  is **fixed** throughout

Usually study the **joint** or **marginal** behaviour of  $X$ ,  $Y$ , etc.

# Problems

This picture is quite **complex**

Many seemingly different components playing **different roles**:

- The underlying measurable space  $(\Omega, \Sigma_\Omega)$
- The probability measure  $\mathbb{P}$
- Random variables  $X, Y$ , etc.
- Joint and marginal distributions of  $X, Y$ , etc.

Also somewhat at odds with how we think intuitively:

- Distributions are **secondary objects** (cf. Bayesian statistics)
- Random variables are **static** (can't "sample" from them)
  - OK for **fixed datasets**, but often ill-suited for describing **computation**
- Kolmogorov-style conditioning is **highly technical**

# Main point

Like a complex, low-level programming language, this **inhibits abstraction** and **compositionality**, and makes it difficult to say simple things

**Categorical probability** reorganises the existing theory in a way that makes reasoning about **higher-level concepts** easy and intuitive

## Case study

## PROBABILISTIC SYMMETRIES AND INVARIANT NEURAL NETWORKS

BY BENJAMIN BLOEM-REDDY<sup>1</sup> AND YEE WHYE TEH<sup>2</sup>

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## Background: group invariance

Often it is desirable for a function  $f : \mathcal{X} \rightarrow \mathcal{Y}$  to be **invariant** to the action of a group  $\mathcal{G}$

Example:

- $\mathcal{X}$  consists of sequences of profiles of subjects in an i.i.d. population
- $\mathcal{G}$  consists of permutations of the indices of these sequences
- $f : \mathcal{X} \rightarrow \mathcal{Y}$  makes some prediction about the population

**Important question:** for a given group  $\mathcal{G}$ , characterise the class of  $f : \mathcal{X} \rightarrow \mathcal{Y}$  such that

$$f(g \cdot x) = f(x) \quad \text{for all } g \in \mathcal{G} \text{ and } x \in \mathcal{X}$$



# Probabilistic Symmetries

Bloem-Reddy and Teh [2020] consider a **probabilistic** version of this

Setup:  $X : \Omega \rightarrow \mathcal{X}$  and  $Y : \Omega \rightarrow \mathcal{Y}$  are **random variables** representing data and prediction respectively

Aim is to characterise when  $Y$  is **conditionally  $\mathcal{G}$ -invariant** in the sense that

$$\mathbb{P}(Y \in B \mid X \in A) = \mathbb{P}(Y \in B \mid X \in g \cdot A)$$

for all  $g \in \mathcal{G}$ ,  $A \in \Sigma_{\mathcal{X}}$  with  $\mathbb{P}(X \in A) > 0$ , and  $B \in \Sigma_{\mathcal{Y}}$

# Main result (on invariance)

**THEOREM 7.** *Let  $X$  and  $Y$  be random elements of Borel spaces  $\mathcal{X}$  and  $\mathcal{Y}$ , respectively, and  $\mathcal{G}$  a compact group acting measurably on  $\mathcal{X}$ . Assume that  $P_X$  is  $\mathcal{G}$ -invariant, and pick a maximal invariant  $M : \mathcal{X} \rightarrow \mathcal{S}$ , with  $\mathcal{S}$  another Borel space. Then  $P_{Y|X}$  is  $\mathcal{G}$ -invariant if and only if there exists a measurable function  $f : [0, 1] \times \mathcal{S} \rightarrow \mathcal{Y}$  such that*

$$(14) \quad (X, Y) \stackrel{\text{a.s.}}{=} (X, f(\eta, M(X))) \quad \text{with } \eta \sim \text{Unif}[0, 1] \text{ and } \eta \perp\!\!\!\perp X.$$

Here a **maximal invariant** is any measurable function  $M$  such that

$$M(x) = M(x') \Leftrightarrow x = g \cdot x' \text{ for some } g \in \mathcal{G}$$

# Proof

The proof of this is **complex** and uses **highly technical** ideas from advanced probability theory, e.g.

- Measurable cross section
- Normalised Haar measure
- Orbit law
- Conditional independence (of  $X$  and  $Y$  given  $M(X)$ )

Also only applies when  $\mathcal{G}$  is compact and  $X$  has a  $\mathcal{G}$ -invariant marginal

# Thoughts

Why is this so hard to show? (E.g. compare deterministic case)

Is it optimal to model a neural network in terms of random variables  $(X, Y)$ ? And why must  $\text{Law}[X]$  be  $\mathcal{G}$ -invariant?

With the tools of **categorical probability**, we can not only **generalise** this result, but we can prove it in a way that maps directly onto our **intuitions**

## Categorical probability theory

# Category theory

## Definition

A **category** consists of a collection of **objects** and a collection of **arrows**

Each arrow  $f$  has a **source** and **target** object, denoted  $f : \mathcal{X} \rightarrow \mathcal{Y}$

There is a **composition** operation  $\circ$  on arrows such that

$$\begin{array}{ll} g \circ f : \mathcal{X} \rightarrow \mathcal{Z} & \text{whenever } f : \mathcal{X} \rightarrow \mathcal{Y} \text{ and } g : \mathcal{Y} \rightarrow \mathcal{Z} \\ h \circ (g \circ f) = (h \circ g) \circ f & \text{when } f, g, h \text{ are appropriately typed} \end{array}$$

For every object  $\mathcal{X}$  there is an **identity** arrow  $\text{id}_{\mathcal{X}} : \mathcal{X} \rightarrow \mathcal{X}$  satisfying

$$\begin{array}{ll} f \circ \text{id}_{\mathcal{X}} = f & \text{whenever } f : \mathcal{X} \rightarrow \mathcal{Y} \\ \text{id}_{\mathcal{Z}} \circ g = g & \text{whenever } g : \mathcal{X} \rightarrow \mathcal{Z} \end{array}$$

Philosophy: **study structural properties extrinsically in terms of arrows**

# Examples

Categories are everywhere:

- **Set**, the category of sets and functions
- **Meas**, the category of measurable spaces and measurable functions
- **Stoch**, the category of measurable spaces and Markov kernels
- Even  $\mathcal{G}$  can be viewed as a category (with a single object, and inverses)

# Functors

The only other definition we will need is as follows:

## Definition

Given categories  $C$  and  $D$ , a **functor**  $F : C \rightarrow D$  assigns:

- To each object  $\mathcal{X}$  in  $C$ , an object  $F\mathcal{X}$  in  $D$
- To each arrow  $f : \mathcal{X} \rightarrow \mathcal{Y}$  in  $C$ , an arrow  $Ff : F\mathcal{X} \rightarrow F\mathcal{Y}$

Moreover:

- $Fid_{\mathcal{X}} = id_{F\mathcal{X}}$  for all objects  $\mathcal{X}$  in  $C$
- $F(g \circ f) = Fg \circ Ff$  for all suitably typed arrows  $f$  and  $g$  in  $C$



# The Giry Functor [Giry, 1982]

Denote by  $P\mathcal{X}$  the set of probability measures on  $\mathcal{X}$  (where  $\Sigma_{\mathcal{X}}$  implicit)

It turns out  $P$  can be thought of as a **functor**  $\mathbf{Meas} \rightarrow \mathbf{Meas}$ :

- Equip  $P\mathcal{X}$  with the (initial)  $\sigma$ -algebra generated by the functions:

$$\begin{aligned} \text{eval}_A : P\mathcal{X} &\rightarrow [0, 1] && \text{where } A \in \Sigma_{\mathcal{X}} \\ p &\mapsto p(A) \end{aligned}$$

- For measurable  $f : \mathcal{X} \rightarrow \mathcal{Y}$ , define  $Pf$  by the **pushforward**, i.e.

$$\begin{aligned} Pf : P\mathcal{X} &\rightarrow P\mathcal{Y} \\ Pf(p) &\mapsto f\#p \end{aligned}$$

- Check functor axioms hold

This reduces already the complexity of our original picture (since  $\mathbb{P} \in P\Omega$ )

# Markov kernels

Consider a measurable function  $k : \mathcal{X} \rightarrow P\mathcal{Y}$

By definition of  $P$ :

- $k(x)(-)$  is a probability measure for all  $x \in \mathcal{X}$
- $k(-)(B) = \text{eval}_B \circ k$  is measurable for all  $B \in \Sigma_{\mathcal{Y}}$

Hence  $k$  is a **Markov kernel**: can think of as  $k : \mathcal{X} \times \Sigma_{\mathcal{Y}} \rightarrow [0, 1]$  such that

- $k(x, -)$  is a probability measure for all  $x \in \mathcal{X}$
- $k(-, B)$  is measurable for all  $B \in \Sigma_{\mathcal{Y}}$

(Precisely: write  $k : \mathcal{X} \rightarrow P\mathcal{Y}$  as  $k : \mathcal{X} \rightarrow (\Sigma_{\mathcal{Y}} \mapsto [0, 1])$  and **uncurry**)

# Giry monad

We can consider Markov kernels to be **generalised measurable functions**:

- Every “normal”  $f : \mathcal{X} \rightarrow \mathcal{Y}$  can be canonically identified with  $\delta_{\mathcal{Y}} \circ f : \mathcal{X} \rightarrow P\mathcal{Y}$ , where

$$\begin{aligned}\delta_{\mathcal{Y}} : \mathcal{Y} &\rightarrow P\mathcal{Y} \\ y &\mapsto \text{Dirac}(y)\end{aligned}$$

- Every “generalised generalised” function  $k : \mathcal{X} \rightarrow PP\mathcal{Y}$  can be canonically identified with  $E_{\mathcal{Y}} \circ k : \mathcal{X} \rightarrow P\mathcal{Y}$ , where

$$\begin{aligned}E_{\mathcal{Y}} : PP\mathcal{Y} &\rightarrow P\mathcal{Y} \\ p &\mapsto \int_{P\mathcal{Y}} p(dq) q(-)\end{aligned}$$

$P$ ,  $\delta_{\mathcal{Y}}$ , and  $E_{\mathcal{Y}}$  moreover satisfy coherence conditions and so give rise to a **monad structure** on **Meas**

# Kleisli composition

The monad structure on **Meas** yields a canonical notion of **composition of generalised functions** (i.e. Markov kernels)

Given  $k : \mathcal{X} \rightarrow P\mathcal{Y}$  and  $\ell : \mathcal{Y} \rightarrow P\mathcal{Z}$ , define  $\ell \circ_{\text{kl}} k : \mathcal{X} \rightarrow P\mathcal{Z}$  via the following composition:

$$\mathcal{X} \xrightarrow{k} P\mathcal{Y} \xrightarrow{P\ell} PP\mathcal{Z} \xrightarrow{E_{\mathcal{Z}}} P\mathcal{Z}$$

Can show this is the usual **Chapman-Kolmogorov equation**:

$$(\ell \circ_{\text{kl}} k)(x)(A) = \int_{\mathcal{Y}} k(x)(dy) \ell(y)(A) \quad \text{where } A \in \Sigma_{\mathcal{Z}}$$

Dirac maps  $\delta_{\mathcal{X}} : \mathcal{X} \rightarrow P\mathcal{X}, x \mapsto \text{Dirac}(x)$  behave like **identities**

# Kleisli category

This gives rise to the **Kleisli category** of **Meas**, known as **Stoch**:

	<b>Meas</b>	<b>Stoch</b>
Objects	Measurable spaces	Measurable spaces
Arrows	Measurable functions	Markov kernels
Composition	Composition of functions	Chapman-Kolmogorov
Identities	Identity functions	Dirac maps

# Kleisli adjunction

We have a bijective correspondence (in fact an **adjunction**):

$$\text{Markov kernels } \mathcal{X} \rightarrow \mathcal{Y} \quad \longleftrightarrow \quad \text{Measurable functions } \mathcal{X} \rightarrow P\mathcal{Y}$$

We saw that identity kernels correspond to Dirac maps, i.e.

$$\text{id}_{\mathcal{X}} : \mathcal{X} \rightarrow \mathcal{X} \quad \longleftrightarrow \quad \delta_{\mathcal{X}} : \mathcal{X} \rightarrow P\mathcal{X}$$

**Interesting question:** what Markov kernel corresponds to the measurable function  $\text{id}_{P\mathcal{Y}} : P\mathcal{Y} \rightarrow P\mathcal{Y}$ ?

$$\text{samp}_{\mathcal{Y}} : P\mathcal{Y} \rightarrow \mathcal{Y} \quad \longleftrightarrow \quad \text{id}_{P\mathcal{Y}} : P\mathcal{Y} \rightarrow P\mathcal{Y}$$

Here  $\text{samp}_{\mathcal{Y}}(p)(B) = p(B)$ , i.e.  $\text{samp}_{\mathcal{Y}}$  **draws a sample** from its input

# New picture

**Stoch** unifies and generalises the elements in our original picture:

$$\begin{array}{ccccc} & & & & (\mathcal{X}, \Sigma_{\mathcal{X}}) \\ & & & \nearrow^{\delta_{\mathcal{X}} \circ X} & \\ (\{*\}, \Sigma_{\{*\}}) & \xrightarrow{\mathbb{P}} & (\Omega, \Sigma_{\Omega}) & \xrightarrow{\delta_{\mathcal{Y}} \circ Y} & (\mathcal{Y}, \Sigma_{\mathcal{Y}}) \\ & & \downarrow^{\delta_{P\mathcal{Z}} \circ k} & \searrow_k & \\ & & (P\mathcal{Z}, \Sigma_{\mathcal{Z}}) & \xrightarrow{\text{samp}_{\mathcal{Z}}} & (\mathcal{Z}, \Sigma_{\mathcal{Z}}) \end{array}$$

Although to some extent  $(\Omega, \Sigma_{\Omega})$  is redundant now ...

# Recap

We have described **two categories** of interest for probability theory:

- **Meas**, i.e. **measurable spaces** and **measurable functions**
- **Stoch**, i.e. **measurable spaces** and **Markov kernels**

We have a **functor**  $P : \mathbf{Meas} \rightarrow \mathbf{Meas}$  mapping measurable spaces to their **space of probability measures**

**Stoch** arises as the **Kleisli category** of the Giry monad (or can be shown directly to satisfy the axioms of a category)

Nothing surprising, but **structural properties** like these are powerful



Return to case study

**THEOREM 7.** *Let  $X$  and  $Y$  be random elements of Borel spaces  $\mathcal{X}$  and  $\mathcal{Y}$ , respectively, and  $\mathcal{G}$  a compact group acting measurably on  $\mathcal{X}$ . Assume that  $P_X$  is  $\mathcal{G}$ -invariant, and pick a maximal invariant  $M : \mathcal{X} \rightarrow \mathcal{S}$ , with  $\mathcal{S}$  another Borel space. Then  $P_{Y|X}$  is  $\mathcal{G}$ -invariant if and only if there exists a measurable function  $f : [0, 1] \times \mathcal{S} \rightarrow \mathcal{Y}$  such that*

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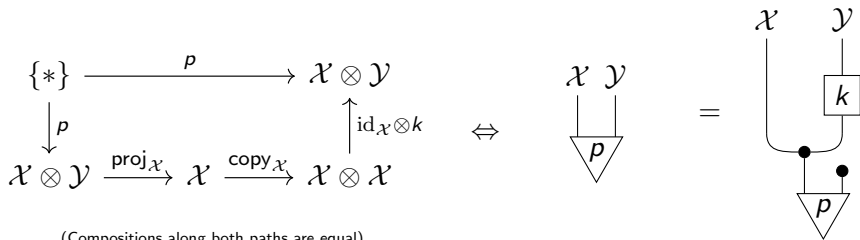
# Conditional distributions/disintegrations

## Proposition

If  $\mathcal{Y}$  is standard Borel, then for any distribution  $p$  on  $\mathcal{X} \otimes \mathcal{Y}$ , there exists a Markov kernel  $k : \mathcal{X} \rightarrow \mathcal{Y}$  such that

$$p(A \times B) = \int_A \text{proj}_{\mathcal{X}}(p)(dx) k(x)(B) \quad \text{for all } A \in \Sigma_{\mathcal{X}} \text{ and } B \in \Sigma_{\mathcal{Y}}.$$

It is convenient to have a **graphical way** to denote this. Standard **commutative diagrams** get complex, but **string diagrams** work:



(Compositions along both paths are equal)

(Read from bottom to top)

# Invariance under an equivalence relation

Suppose  $\sim$  is an arbitrary **equivalence relation** on  $\mathcal{X}$

## Definition

A distribution  $p$  on  $\mathcal{X} \otimes \mathcal{Y}$  is **conditionally  $\sim$ -invariant** if  $p$  admits a disintegration  $k : \mathcal{X} \rightarrow \mathcal{Y}$  that is  $\sim$ -invariant, i.e.  $k(x) = k(x')$  if  $x \sim x'$ .

For  $p = \text{Law}[X, Y]$ , **equivalent** to conditional invariance in sense of Bloem-Reddy and Teh [2020] under their setup, i.e.  $\mathcal{G}$  is compact,  $\text{Law}[X]$  is  $\mathcal{G}$ -invariant,  $\mathcal{Y}$  standard Borel, and

$$x \sim x' \Leftrightarrow x = g \cdot x' \text{ for some } g \in \mathcal{G},$$

Makes sense more generally – could even start with  $k$  as the **definition** of a (probabilistic) neural network

# Quotient spaces

Given any measurable space  $\mathcal{X}$  and an equivalence relation  $\sim$  on  $\mathcal{X}$ , we can form the **quotient space**  $\mathcal{X}/\sim$  of equivalence classes under  $\sim$

The  $\sigma$ -algebra is **final** with respect to the **quotient map**  $q : \mathcal{X} \rightarrow \mathcal{X}/\sim$

Explicitly,  $\Sigma_{\mathcal{X}/\sim} := \{B \subseteq \mathcal{X}/\sim \mid q^{-1}(B) \in \Sigma_{\mathcal{X}}\}$ .

# Universal property of the quotient

## Proposition

A measurable function  $g : \mathcal{X} \rightarrow \mathcal{Z}$  is  $\sim$ -invariant iff there exists a (necessarily unique) measurable function  $\tilde{g} : \mathcal{X}/\sim \rightarrow \mathcal{Z}$  such that  $\tilde{g} \circ q = g$ , i.e. the following diagram commutes:

$$\begin{array}{ccc} \mathcal{X} & \xrightarrow{g} & \mathcal{Z} \\ q \downarrow & \nearrow \tilde{g} & \\ \mathcal{X}/\sim & & \end{array}$$

Requires proof, but can do so via only elementary definitions

A very natural result in the context of category theory

# Invariant kernels via the quotient

Now take  $\mathcal{Z} = P\mathcal{Y}$  and interpret within **Stoch**

## Corollary

A Markov kernel  $k : \mathcal{X} \rightarrow \mathcal{Y}$  is  $\sim$ -invariant iff there exists a Markov kernel  $\tilde{k} : \mathcal{X}/\sim \rightarrow \mathcal{Y}$  with

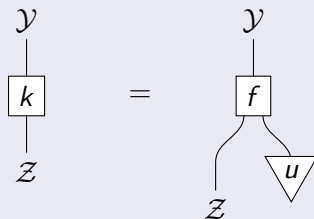
The diagram shows an equality between two vertical compositions of Markov kernels. On the left, a box labeled  $k$  is connected by a vertical line to  $\mathcal{Y}$  above and  $\mathcal{X}$  below. On the right, a box labeled  $\tilde{k}$  is connected by a vertical line to  $\mathcal{Y}$  above and another box labeled  $q$  below. The box  $q$  is then connected by a vertical line to  $\mathcal{X}$  below. An equals sign is placed between the two compositions.

(Note that we are identifying  $q$  with its lifted version  $\delta_{\mathcal{X}/\sim} \circ q$ )

# Noise outsourcing

## Proposition

*For any Markov kernel  $k : \mathcal{Z} \rightarrow \mathcal{Y}$  with  $\mathcal{Y}$  standard Borel, there exists a measurable function  $f : \mathcal{Z} \otimes [0, 1] \rightarrow \mathcal{Y}$  such that*



where  $u = \text{Uniform}(0, 1)$ .

Standard result (e.g. Lemma 3.22 of Kallenberg [2002])



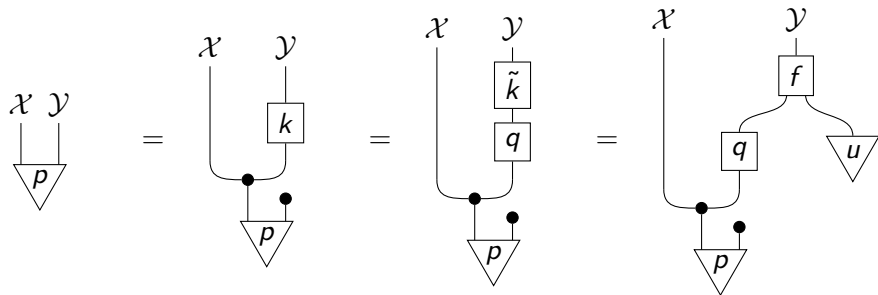
# Combining these results

## Proposition

If  $\mathcal{Y}$  is standard Borel, then  $\text{Law}[X, Y]$  is conditionally  $\sim$ -invariant iff there exists a measurable function  $f : \mathcal{X}/\sim \otimes [0, 1] \rightarrow \mathcal{Y}$  such that

$$(X, Y) \stackrel{d}{=} (X, f(q(X), \eta)) \quad \text{where } \eta \sim \text{Uniform}(0, 1), \eta \perp\!\!\!\perp X$$

**Proof:** writing  $p := \text{Law}[X, Y]$ , conditional  $\sim$ -invariance implies



Conversely, right-hand side is conditionally  $\sim$ -invariant since  $q$  is.

# Comparison with original result

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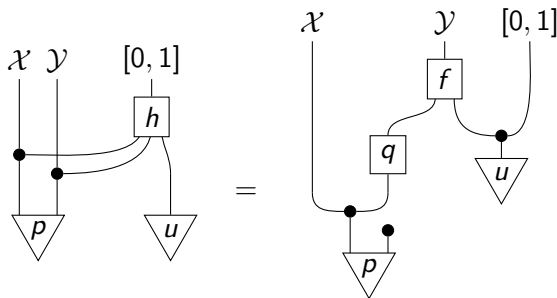
$$(14) \quad (X, Y) \stackrel{\text{a.s.}}{=} (X, f(\eta, M(X))) \quad \text{with } \eta \sim \text{Unif}[0, 1] \text{ and } \eta \perp\!\!\!\perp X .$$

Not quite done:

$$(X, Y) \stackrel{\text{d}}{=} (X, f(q(X), \eta)) \quad \not\Rightarrow \quad Y \stackrel{\text{a.s.}}{=} f(q(X), \eta)$$

# Completing the proof

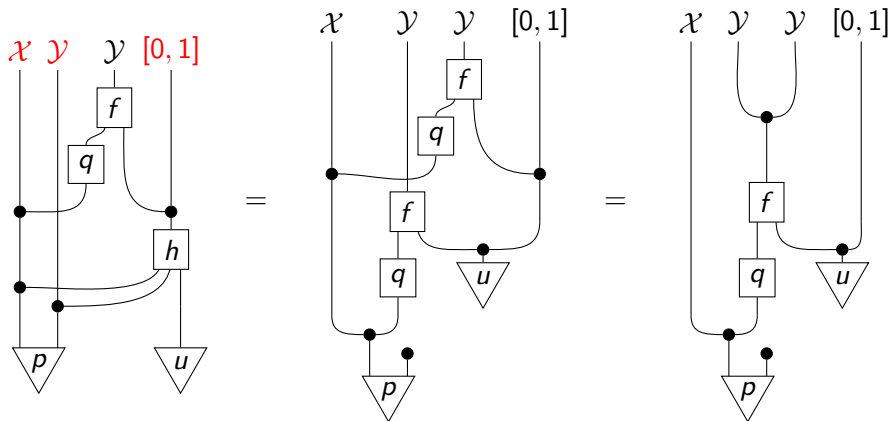
Choose  $h : \mathcal{X} \otimes \mathcal{Y} \otimes [0, 1] \rightarrow [0, 1]$  such that



Existence of  $h$  follows by **disintegrating** right-hand side along  $\mathcal{X} \times \mathcal{Y}$  and then applying **noise outsourcing** result

# Completing the proof

Now affix the same  $(q, f)$  construction to both sides:



$\Rightarrow$  If  $\xi \sim \text{Uniform}(0, 1)$  with  $\xi \perp\!\!\!\perp (X, Y)$ , then letting  $\eta := h(X, Y, \xi)$ , have  $(X, Y, f(q(X), \eta), \eta) \stackrel{d}{=} (X, f(q(X), \xi), f(q(X), \xi), \xi)$

$\Rightarrow Y \stackrel{\text{a.s.}}{=} f(q(X), \eta)$  and  $\eta \stackrel{d}{=} \xi \sim \text{Uniform}(0, 1)$  with  $\eta \perp\!\!\!\perp X$

# Combining these results

**THEOREM 7.** *Let  $X$  and  $Y$  be random elements of Borel spaces  $\mathcal{X}$  and  $\mathcal{Y}$ , respectively, and  $\mathcal{G}$  a compact group acting measurably on  $\mathcal{X}$ . Assume that  $P_X$  is  $\mathcal{G}$ -invariant, and pick a maximal invariant  $M : \mathcal{X} \rightarrow \mathcal{S}$ , with  $\mathcal{S}$  another Borel space. Then  $P_{Y|X}$  is  $\mathcal{G}$ -invariant if and only if there exists a measurable function  $f : [0, 1] \times \mathcal{S} \rightarrow \mathcal{Y}$  such that*

$$(14) \quad (X, Y) \stackrel{\text{a.s.}}{=} (X, f(\eta, M(X))) \quad \text{with } \eta \sim \text{Unif}[0, 1] \text{ and } \eta \perp\!\!\!\perp X.$$

## Theorem (Our version)

*If  $\mathcal{Y}$  is Borel, then  $\text{Law}[X, Y]$  is conditionally  $\sim$ -invariant iff there exists a measurable function  $f : \mathcal{X}/\sim \otimes [0, 1] \rightarrow \mathcal{Y}$  such that*

$$(X, Y) \stackrel{\text{a.s.}}{=} (X, f(q(X), \eta)) \quad \text{where } \eta \sim \text{Uniform}(0, 1) \text{ with } \eta \perp\!\!\!\perp X$$

(More precisely, both statements should refer to the existence of an extension of the underlying probability space that admits suitable choices of  $\eta$  and  $f$ )

Possibly better to express entirely via **Markov kernels**

## Conclusion

# Summary and Outlook

Categorical probability offers a **high-level perspective** on the classical theory that makes **abstraction easier** and helps **theory follow intuition**

The outlook is very positive:

- **Lots of activity** in categorical probability, e.g. Perrone [2018], Cho and Jacobs [2019], Jacobs [2019], Fritz [2020]
- Category theory has been **hugely successful elsewhere**, e.g. pure maths, computer science, quantum mechanics

Also **not difficult** to learn! Just a new way of thinking about things you already know...

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