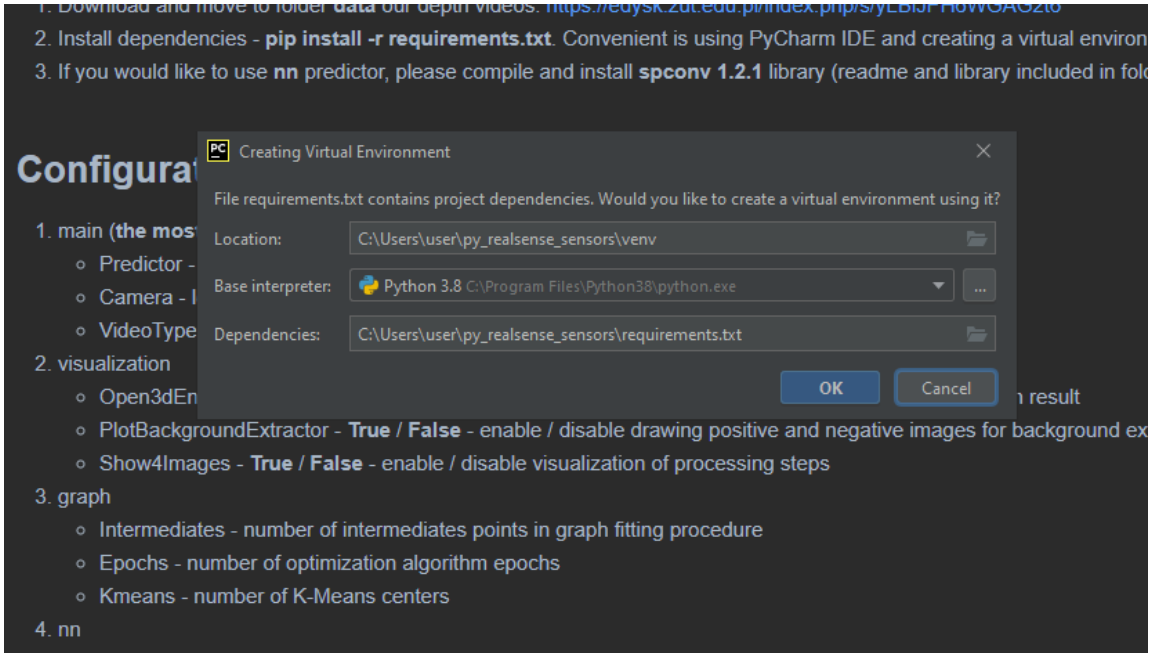
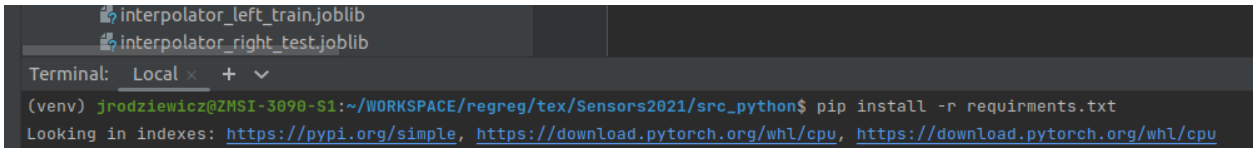
py_realsense_sensors – installation guide

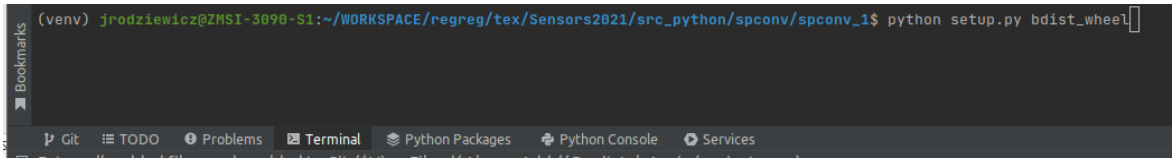
1. Please open the project in the Pycharm environment.
2. Create a Python virtual environment:



3. If you have problems with torch installation, please open Terminal in Pycharm and execute command **pip install -r requirements.txt**



4. If you would like use nn predictor, please install the **spconv** library as follows:
    a. In Terminal execute command **sudo apt-get install libboost-all-dev**
    b. Download **cmake** >= 3.13.2, then add cmake executables to PATH
    c. Extract archive **spconv/spconv1.zip**
    d. Open in Terminal directory containing extracted archive and run the command **python .\setup.py bdist_wheel**



    e. If library compilation is finished, please open the **dist** directory and install the library using the command **pip install spconv-1.2.1-cp38-cp38-linux_x86_64.whl**