Jack O'Neill AE 5222 Homework 6

Method

For this problem needed to generate a graph which would describe all the possible paths with their respective costs. I could then use Dijkstra's algorithm (the code I borrowed from Joseph Kirk which can be found at https://bit.ly/2Zzu1uG) to calculate the minimal cost (distance) path which would put all the pallets in the correct bins.

For this problem I defined the "6th" bin as the bin defined by b_T . Nodes in this problem are defined as a single bin and pallet configuration, of which there are 720 combinations. To define adjacency I reasoned that each configuration would have a number of adjacent nodes. They were defined by swapping each pallet to b_T . Numerically this looked like arrays, each with the next array index swapping with the last index. With these adjacent nodes I could then search the 720 combinations to find which node they were defined as. Doing this for all nodes allowed me to generate a 720x720 adjacency matrix.

To define the cost of each edge (transition from one configuration to an adjacent configuration) I used the distance matrix shown in figure 1 to find the distance between the two bins which were being swapped in that edge.

Figure 1: distance matrix

For example, say the initial configuration is: $\{1\ 2\ 3\ 4\ 5\ 6\}$. The cost to transition to the adjacent matrix $\{6\ 2\ 3\ 4\ 5\ 1\}$ would be equal to the distance from b_1 to b_T which is 124. The edge matrix is defined this way for the rest of the edges.

Results

My Matlab code generated the following optimal sequence of pallet ordering given the initial configuration and an end configuration equal to {1, 2, 3, 4, 5}:

	Cal	culate	d Minir	mum Co	st Patl	h
Path cost = 492						
	pl	p2	p3	p4	p5	
	2	5	1	3	4	6
	2	5	1	6	4	3
	2	5	3	6	4	1
	1	5	3	6	4	2
	1	2	3	6	4	5
	1	2	3	6	5	4
	1	2	3	4	5	6

Figure 2: Calculated optimal pallet ordering

Where the cost is 492, and each row represents a configuration of bins (1-5 plus 6 as b_{τ}).

Discussion

The logic I followed to complete this problem seems to make sense to me, but overall it was pretty confusing to determine the adjacency conditions and I very well could have messed up at some point along the way. However the path generated by Dijkstra's algorithm shows that it is satisfying the condition that the forklift can only hold one pallet at a time so I am happy with this result.