Jeremy Orosco jrorosco@eng.ucsd.edu

#### CITIZENSHIP

U.S. Citizen

#### **EDUCATION**

# University of California San Diego

Ph.D. Mechanical Engineering

March 2016-present

- President's Dissertation Year Fellowship (2018–2019)
- San Diego Fellowship (2014–2018)
- Interests and expertise:
  - applied math, control and stability, identification and estimation, nonlinear/nonconvex optimization, fluid mechanical systems, condensed matter systems, radiative mechanics
  - predictive analytics with machine learning models / feature engineering
  - generalized variable order models for anomalous spectroscopic dispersion
  - statistical models for emergent nonlocal dynamics in many-body systems

## University of California San Diego

M.S. Mechanical Engineering

2016

- San Diego Fellowship (2014–2018)
- Courses (GPA: **3.88**):
  - MAE 280 A/B: Linear Systems and Control
  - MAE 288 A: Optimal Control
  - MAE 283 A: Open-loop System Identification
  - MAE 283 B: Closed-loop System Identification and Approximate Control
  - MAE 284: Robust and Multivariable Control
  - MATH 271 A/B/C: Nonlinear Optimization (UC/EQC/IEQC)
  - MAE 210 A/B/C: Fluid Mechanics and Hydrodynamic Stability
  - MAE 208: Engineering Mathematics

#### University of California San Diego

B.S. Mechanical Engineering

2014

- Provost Honors, Warren College Honor Society
- Selected Courses:
  - MAE 143 A/B/C: Signals, CT/DT Control Systems
  - MAE 144: Embedded Control and Robotics
  - MATH 120 A: Complex Analysis

#### MiraCosta Community College

A.A. Pre-Engineering

2011

- Medal of Honor Scholarship
- President's List, President's Permanent Honor Roll
- President, Phi Theta Kappa Honor Society
- All California Academic Team

#### EMPLOYMENT

## **Controls Engineer (intern)**

June 2016–December 2016

Cymer / ASML

- Individually undertaken project to research, design, and implement automation upgrades to existing experimental apparatus.
- Machine vision driven feedback loop based on observation of a modulated hydrodynamic instability and multi-stage actuation of an imaging assembly.
- Applied technical skillsets based on project deliverables:
  - mechanical design (5%)
  - software/hardware high and low level interfacing (15%)
  - hydrodynamics and hydrodynamic instabilities (15%)
  - control theory (25%)
  - machine vision (40%)

#### **Publications**

Orosco, J. and Coimbra, C. F. M.: Variable order modeling of nonlocal emergence in many-body systems: Application to radiative dispersion. Physical Review E (in press)

Orosco, J. and Coimbra, C. F. M.: On a causal dispersion model for the optical properties of metals. Applied Optics (2018) Link - PDF

Orosco, J. and Coimbra, C. F. M.: Optical response of thin amorphous films to infrared radiation. Physical Review B (2018) Link - PDF

Orosco, J. and Coimbra, C. F. M.: On the control and stability of variable-order mechanical systems. Nonlinear Dynamics (2016) Link - PDF

## Manuscript Review

# Elsevier's Energy, The International Journal

2014-Present

Springer's Nonlinear Dynamics, An International Journal of Nonlinear Dynamics and Chaos in Engineering Systems

2016–Present

Elsevier's Chaos, Solitons & Fractals, An interdisciplinary journal of nonlinear science 2016-Present

Springer's Journal of Scientific Computing

2016-Present

AIP's Physics of Fluids

2017-Present

Elsevier's Solar Energy, The Official Journal of the International Solar Energy Society 2018–Present

The Optical Society's Applied Optics

2018-Present

Elsevier's International Journal of Non-Linear Mechanics

2018-Present

#### Professional Memberships

The American Institute of Aeronautics and Astronautics (AIAA)

2018-Present

American Society of Mechanical Engineers (ASME)

2017-Present

Institute of Electrical and Electronics Engineers (IEEE)

2017-Present

The Optical Society (OSA)

2018-Present

Society of Industrial and Applied Mathematics (SIAM)

2017-Present

# SELECTED PROJECTS

#### **Real Time Solar Power Forecasting**

- In use at large-scale (200+ MW commercial grid supplier) solar power plant
- State of the art machine learning models for power output forecasts
- Utilizes novel feature sets generated with cutting-edge mathematics

#### **Self-balancing Robot - MIP**

- Individual capstone controls project
- Digital implementation of continuous time modeling and control design

#### Fly Righting Response Experimentation Device - Fly2R

- Team capstone mechanical design project
- Developed for UCSD's Pharmacology Department for use with experimentation
- Received Departmental Best Project Award

## Portable Solar Powered Sensing Station - get(Sol)

- Individual research-based design project
- Self-sustaining/monitoring sensing station, internal web/data management
- 6+ month uninterrupted runtime (unplugged, zero maintenance)

# Awards and Distinctions

# President's Dissertation Year Fellowship

2018-2019

- 1-Year scholarship: tuition and stipend

# San Diego Fellowship

2014-2018

- 4-Year scholarship: tuition and stipend

MAE Departmental Best Project Award: Fly2R UCSD Alumni Leadership Scholar Coca-Cola Scholar

March 2010

Spring 2014

July 2012

MiraCosta College Medal of Honor Scholar MiraCosta College Foundation Scholar

Apr 2010 June 2010

#### TECHNICAL SKILLSETS

#### **Programming**

- Syntax: Python, Matlab, Mathematica, C/C++, Julia, Git/SVN, LATEX, Bibtex
- Environment: \*nix, Windows
- Frameworks: XGBoost, SKLearn, Pandas, CVXPY

#### **Data Science**

- Data quality assessment
- Feature engineering
- Regressive models
- Time series analysis

#### Design and Simulation

- Eagle PCB, Inventor and Autocad, SolidWorks

#### **Circuits and Electronics**

- PCB (SMD) prototyping and design, SMD hand-soldering
- Signal conditioning, sensing, actuation
- μC: BeagleBone, Arduino, Raspberry Pi

#### Rapid Prototyping

- Machining, lasercamm

#### **Graphical Design**

- Adobe Photoshop and Illustrator