

EDUCATION

University of California San Diego*Ph.D. Mechanical Engineering*

March 2016–present

- President's Dissertation Year Fellowship (2018–2019)
- San Diego Fellowship (2014–2018)
- Research interests:
 - nonlocal operators and variable order systems, control and stability, nonlinear/nonconvex optimization, fluid mechanical systems, condensed matter systems
 - generalized variable order models for anomalous optical dispersion in solid media
 - efficient numerical methods for the solution of variable order differential equations

University of California San Diego*M.S. Mechanical Engineering*

2016

- San Diego Fellowship (2014–2018)
- Courses (GPA: **3.88**):
 - MAE 280 A/B: Linear Systems and Control
 - MAE 288 A: Optimal Control
 - MAE 283 A: Open-loop System Identification
 - MAE 283 B: Closed-loop System Identification and Approximate Control
 - MAE 284: Robust and Multivariable Control
 - MATH 271 A/B/C: Nonlinear Optimization (UC/EQC/IEQC)
 - MAE 210 A/B/C: Fluid Mechanics and Hydrodynamic Stability
 - MAE 208: Engineering Mathematics

University of California San Diego*B.S. Mechanical Engineering*

2014

- Provost Honors, Warren College Honor Society
- Selected Courses:
 - MAE 143 A/B/C: Signals, CT/DT Control Systems
 - MAE 144: Embedded Control and Robotics
 - MATH 120 A: Complex Analysis

MiraCosta Community College*A.A. Pre-Engineering*

2011

- Medal of Honor Scholarship
- President's List, President's Permanent Honor Roll
- President, Phi Theta Kappa Honor Society
- All California Academic Team

RESEARCH
EXPERIENCE**Graduate Student Researcher, Coimbra Research Group**

July 2014–present

University of California San Diego

- Novel research: modeling, control, and stability of nonlocal variable-order mechanical systems

	Undergraduate Student Researcher, Coimbra Research Group 2012–2014 <i>University of California San Diego</i> <ul style="list-style-type: none"> - Clear-sky model development - Implemented irradiance data weather classification algorithm - Developed low-cost, self-sustaining portable irradiance sensing/logging station
	Independent Researcher, MAE Department Winter 2013–Spring 2013 <i>University of California San Diego</i> <ul style="list-style-type: none"> - Developed novel forecasting method for chaotic determinant time series
PUBLICATIONS	<p>Orosco, J. and Coimbra, C.F.M.: On the control and stability of variable-order mechanical systems. <i>Nonlinear Dynamics</i> (2016) Link - PDF</p> <p>Orosco, J. and Coimbra, C.F.M.: Optical response of thin amorphous films to infrared radiation. <i>Physical Review B</i> (2018) Link - PDF</p> <p>Orosco, J. and Coimbra, C.F.M.: On a causal dispersion model for the optical properties of thin metallic films. <i>Applied Optics</i> (in press)</p>
MANUSCRIPT REVIEW	<p>Elsevier’s Energy, <i>The International Journal</i> 2014–Present</p> <p>Springer’s Nonlinear Dynamics, <i>An International Journal of Nonlinear Dynamics and Chaos in Engineering Systems</i> 2016–Present</p> <p>Elsevier’s Chaos, Solitons & Fractals, <i>An interdisciplinary journal of nonlinear science</i> 2016–Present</p> <p>Springer’s Journal of Scientific Computing 2016–Present</p> <p>AIP’s Physics of Fluids 2017–Present</p> <p>Elsevier’s Solar Energy, <i>The Official Journal of the International Solar Energy Society</i> 2018–Present</p>
PROFESSIONAL MEMBERSHIPS	<p>The American Institute of Aeronautics and Astronautics (AIAA) 2018–Present</p> <p>American Society of Mechanical Engineers (ASME) 2017–Present</p> <p>Institute of Electrical and Electronics Engineers (IEEE) 2017–Present</p> <p>The Optical Society (OSA) 2018–Present</p> <p>Society of Industrial and Applied Mathematics (SIAM) 2017–Present</p>
SELECTED PROJECTS	<p>Self-balancing Robot - MIP</p> <ul style="list-style-type: none"> - Individual capstone controls project - Digital implementation of continuous time modeling and control design <p>Fly Righting Response Experimentation Device - Fly2R</p> <ul style="list-style-type: none"> - Team capstone mechanical design project - Developed for UCSD’s Pharmacology Department for use with experimentation - Received Departmental Best Project Award

	Portable Solar Powered Sensing Station - get(Sol) <ul style="list-style-type: none"> - Individual research-based design project - Self-sustaining/monitoring sensing station, internal web/data management - 6+ month uninterrupted runtime (unplugged, zero maintenance) 	
AWARDS AND DISTINCTIONS	President's Dissertation Year Fellowship	2018–2019
	- 1-Year scholarship: tuition and stipend	
	San Diego Fellowship	2014–2018
	- 4-Year scholarship: tuition and stipend	
	MAE Departmental Best Project Award: Fly2R	Spring 2014
	UCSD Alumni Leadership Scholar	July 2012
	Coca-Cola Scholar	March 2010
TECHNICAL SKILLSETS	MiraCosta College Medal of Honor Scholar	Apr 2010
	MiraCosta College Foundation Scholar	June 2010
	Programming	
	<ul style="list-style-type: none"> - Syntax: Python, Matlab, Mathematica, C/C++, Julia, Git/SVN, \LaTeX, Bibtex - Environment: *nix, Windows 	
	Design and Simulation	
	<ul style="list-style-type: none"> - Eagle PCB, Inventor and Autocad, SolidWorks, PTC Creo (Pro/E), Siemens Femap, Ansys (FEA), SolidWorks COSMOS (FEA) 	
	Circuits and Electronics	
EMPLOYMENT	<ul style="list-style-type: none"> - PCB (SMD) prototyping and design, SMD hand-soldering - Signal conditioning, sensing, actuation - μC: BeagleBone, Arduino, Raspberry Pi 	
	Rapid Prototyping	
	<ul style="list-style-type: none"> - Machining, lasercamm 	
	Graphical Design	
	<ul style="list-style-type: none"> - Adobe Photoshop and Illustrator 	
	Controls Engineer (intern)	June 2016–December 2016
	<i>Cymer / ASML</i>	
	<ul style="list-style-type: none"> - Individually undertaken project to research, design, and implement automation upgrades to existing experimental apparatus. - Machine vision driven feedback loop based on observation of a modulated hydrodynamic instability and multi-stage actuation of an imaging assembly. - Applied technical skillsets based on project deliverables: <ul style="list-style-type: none"> - mechanical design (5%) - software/hardware high and low level interfacing (15%) - hydrodynamics and hydrodynamic instabilities (15%) - control theory (25%) - machine vision (40%) 	