

Assignment 7

(1) $dS_t = \mu S_t dt + \sigma S_t dz_t$, $dR_t = r R_t dt$

I know I'm repeating a lot of work from the textbook but I wanted to work through this on my own

Suppose we allocate a fraction π_t of wealth at any time into the risky asset, and we have a consumption c_t . Then our change in wealth is:

$$dW_t = \mu \pi_t W_t dt + \sigma \pi_t W_t dz_t + r(1 - \pi_t) W_t dt - c_t dt$$

$$= ((\mu - r)\pi_t + r) W_t dt - c_t dt + \sigma \pi_t W_t dz_t$$

Our utility is increasing like

$$dU_t = \log(c_t) dt$$

Our total utility summed & discounted from t to T is:

$$U_{tot} = \int_t^T \log(c_s) e^{-\rho(s-t)} ds + B(T) e^{-\rho(T-t)} \log(W_T)$$

We want to maximize the following by choosing π_t, c_t intelligently:

$$\mathbb{E}[U_{tot} | W_t] = \mathbb{E}\left[\int_t^T \log(c_s) e^{-\rho(s-t)} ds + B(T) \log(W_T) e^{-\rho(T-t)} \mid W_t\right]$$

This is modeled nicely as a continuous-time MDP, where our state is (W_t, t) , our actions are pairs (π_t, c_t) , and the discount rate is ρ , and rewards are $U(c_t) dt$. The discrete-time Bellman optimality equation in the short time step limit is:

$$V(W_t, t) = \max_{\pi_t, c_t} \{ \log(c_t) dt + (1 - \rho dt) \cdot \mathbb{E}[V(W_{t+dt}, t+dt)] \}$$

We can expand:

$$\begin{aligned} V^*(W_t, t) &= \max_{\pi_t, c_t} \left\{ \log(c_t) dt + (1-p) dt \left(V^*(W_t, t) + E[\Delta V^*(W_t, t, \pi_t, c_t)] \right) \right\} \\ &= V^*(W_t, t) - p dt V^*(W_t, t) + \max_{\pi_t, c_t} \left\{ \log(c_t) dt + E[\Delta V^*(W_t, t, \pi_t, c_t)] \right\} \end{aligned}$$

$$\Rightarrow p V^*(W_t, t) dt = \max_{\pi_t, c_t} \left\{ \log(c_t) dt + E[dV^*(W_t, t | \pi_t, c_t)] \right\}$$

Itô's lemma lets us expand:

$$\begin{aligned} p V^*(W_t, t) dt &= \max_{\pi_t, c_t} \left\{ \log(c_t) dt + E_t \left[\frac{\partial V^*}{\partial t} dt + \frac{\partial V^*}{\partial W_t} dW_t + \frac{1}{2} \frac{\partial^2 V^*}{\partial W_t^2} (dW_t)^2 \right] \right\} \\ &= \max_{\pi_t, c_t} \left\{ \log(c_t) dt + \frac{\partial V^*}{\partial t} dt + \frac{\partial V^*}{\partial W_t} E[dW_t] + \frac{1}{2} \frac{\partial^2 V^*}{\partial W_t^2} E[(dW_t)^2] \right\} \end{aligned}$$

Notice:

$$E[dW_t] = \underbrace{((\mu-r)\pi_t + r)W_t - c_t}_{A(W_t, t)} dt + \underbrace{\sigma \pi_t W_t}_{B(W_t, t)} E[dz_t] \quad dt = dz_t^2$$

$$\begin{aligned} E[(dW_t)^2] &= \underbrace{A^2(W_t, t)}_{\rightarrow 0} dt^2 + 2 \underbrace{A(W_t, t)}_{\rightarrow 0} \underbrace{B(W_t, t)}_{\rightarrow 0} dt E[dz_t] + \underbrace{B^2(W_t, t)}_{\rightarrow 0} dz_t^2 \\ &= \sigma^2 \pi_t^2 W_t^2 dt \end{aligned}$$

So:

$$p V^*(W_t, t) = \max_{\pi_t, c_t} \left\{ \log(c_t) + \frac{\partial V^*}{\partial t} + \frac{\partial V^*}{\partial W_t} \cdot ((r + (\mu-r)\pi_t)W_t - c_t) + \frac{1}{2} \frac{\partial^2 V^*}{\partial W_t^2} \sigma^2 \pi_t^2 W_t^2 \right\}$$

Let's solve this maximum by taking derivatives w.r.t. c_t & π_t . Notice that we require $\frac{\partial^2 V^*}{\partial W_t^2} < 0$ for this to work.

$$\frac{1}{c_t^*} - \frac{\partial V^*}{\partial W_t} = 0 \Rightarrow c_t^* = \left(\frac{\partial V^*}{\partial W_t} \right)^{-1}$$

$$(\mu-r)W_t \frac{\partial V^*}{\partial W_t} + \frac{\partial^2 V^*}{\partial W_t^2} \sigma^2 W_t^2 \pi_t^* = 0 \Rightarrow \pi_t^* = \frac{\mu-r}{\sigma^2 W_t} \cdot \frac{\partial V^*}{\left(-\frac{\partial^2 V^*}{\partial W_t^2} \right)}$$

$$(1 + (p\epsilon - 1)e^{-p(T-t)}) / (1 + e^{-pT})$$

$$PV^*(W_t, t) = -\log\left(\frac{\partial V^*}{\partial W_t}\right) + \frac{\partial V^*}{\partial t} - 1 + rW_t \frac{\partial V^*}{\partial W_t} + \frac{1}{2}\left(\frac{\mu-r}{\sigma}\right)^2 \frac{(\partial V^* / \partial W_t)^2}{(\partial^2 V^* / \partial W_t^2)} + \frac{1}{2}\left(\frac{\mu-r}{\sigma}\right)^2 \frac{(\partial V^* / \partial W_t)^2}{(\partial^2 V^* / \partial W_t^2)}$$

This is a PDE we can solve

$$PV^*(W_t, t) = -\log\left(\frac{\partial V^*}{\partial W_t}\right) + \frac{\partial V^*}{\partial t} + rW_t \frac{\partial V^*}{\partial W_t} + \frac{1}{2}\left(\frac{\mu-r}{\sigma}\right)^2 \frac{(\partial V^* / \partial W_t)^2}{(\partial^2 V^* / \partial W_t^2)} - 1$$

subject to $V^*(W_T, T) = B(T) \cdot \log(W_T) = \epsilon \log(W_T)$

Suppose $V^*(W_t, t) = B(t) \log(W_t) + f(t)$. We can plug in the guess:

$$\frac{\partial V^*}{\partial t} = f'(t), \quad \frac{\partial V^*}{\partial W_t} = \frac{\epsilon}{W_t}, \quad \frac{\partial^2 V^*}{\partial W_t^2} = -\frac{\epsilon}{W_t^2}$$

$$\epsilon \log W_t + p f(t) = -\log \epsilon + \log W_t + f'(t) + rW_t \cdot \frac{\epsilon}{W_t} - 1 + \frac{1}{2}\left(\frac{\mu-r}{\sigma}\right)^2 \frac{(\epsilon/W_t)^2}{\epsilon/W_t^2}$$

$t \log t$

$$= -\log \epsilon + \log W_t + p\epsilon + \frac{\epsilon}{2}\left(\frac{\mu-r}{\sigma}\right)^2 - 1$$

$e^{p \log t}$

$$(\epsilon p - 1) \log W_t + \log \epsilon + p\epsilon - \frac{\epsilon}{2}\left(\frac{\mu-r}{\sigma}\right)^2 + 1 = -p f(t) + f'(t)$$

$\propto t - \log W_t$

$$f(t) =$$

$1 - f(t)$

$$V^* = \epsilon \log W_t + f(t) \log(W_t)$$

$$\frac{pW_t}{1 + (p\epsilon - 1)e^{-p(T-t)}} - \frac{1 + (p\epsilon - 1)e^{-p(T-t)}}{pW_t} = 0$$

Let me copy this PDE to this page for reference:

$$\left\{ \frac{\partial V^*}{\partial t} + \frac{(\mu-r)^2}{2\sigma^2} \cdot \frac{(\frac{\partial V^*}{\partial W_t})^2}{\frac{\partial^2 V^*}{\partial W_t^2}} + \frac{\partial V^*}{\partial W_t} \cdot r \cdot W_t - 1 - \log\left(\frac{\partial V^*}{\partial W_t}\right) = \rho V^* \right.$$

$$\left. \text{Subject to } V^*(W_T, T) = 1 + \epsilon \log W_T \right.$$

where $\epsilon \equiv B(T)$

Suppose V^* has the form $V^*(W_t, t) = f(t) \log W_t + g(t)$. Then:

$$\frac{\partial V^*}{\partial t} = f'(t) \log W_t + g'(t); \quad \frac{\partial V^*}{\partial W_t} = \frac{f(t)}{W_t}; \quad \frac{\partial^2 V^*}{\partial W_t^2} = -\frac{f(t)}{W_t^2}$$

Substituting in, we get:

simplify $\left\{ \begin{aligned} f'(t) \log W_t + g'(t) + \frac{(\mu-r)^2}{2\sigma^2} f(t) + r f(t) - 1 - \log f(t) + \log W_t \\ = \rho f(t) \log W_t + \rho g(t) \end{aligned} \right.$

$$(f'(t) - \rho f(t) + 1) \log W_t + g'(t) - \rho g(t) + h(t) = 0$$

where we define $h(t) \equiv \left(r + \frac{(\mu-r)^2}{2\sigma^2}\right) f(t) - \log f(t) - 1$

This diff eq. is solved by $f(t), g(t)$ which are solutions to the ODEs:

$$\begin{cases} f'(t) - \rho f(t) + 1 = 0 \\ g'(t) - \rho g(t) + h(t) = 0 \end{cases}$$

This ODE system has a general solution:

$$\left\{ \begin{aligned} f(t) &= C_1 e^{\rho t} + 1/\rho \\ g(t) &= C_2 e^{\rho t} - e^{\rho t} \int h(t) e^{-\rho t} dt \end{aligned} \right.$$

subject
to
B.C.'s

$$\left\{ \begin{aligned} f(T) &= \epsilon \\ g(T) &= 0 \end{aligned} \right.$$

Applying the boundary conditions, we get the solution:

$$\begin{aligned} f(t) &= \epsilon + \frac{1}{p}(1 - e^{-p(T-t)}) \\ g(t) &= e^{pt} \int_t^T e^{-ps} h(s) ds \end{aligned}$$

This gives us a value function:

$$\begin{aligned} V^*(W_t, t) &= \left(\epsilon + \frac{1 - e^{-p(T-t)}}{p} \right) \log W_t + e^{pt} \int_t^T e^{-ps} h(s) ds \\ \text{where } h(s) &\equiv \left(r + \frac{(\mu - r)^2}{2\sigma^2} \right) \left(\epsilon + \frac{1 - e^{-p(T-t)}}{p} \right) - \log \left(\epsilon + \frac{1 - e^{-p(T-t)}}{p} \right) - 1 \end{aligned}$$

From the value function, we can recover the optimal policy:

$$\pi_t^* = \frac{\mu - r}{\sigma^2 W_t} \cdot \frac{\partial V^* / \partial W_t}{-\partial^2 V^* / \partial W_t^2} = \boxed{\frac{\mu - r}{\sigma^2}}$$

$$c_t^* = \left(\frac{\partial V^*}{\partial W_t} \right)^{-1} = \boxed{\frac{W_t}{\epsilon + \frac{1 - e^{-p(T-t)}}{p}}}$$

③ States:

Your state is a tuple (s, J) where $s \in \mathbb{R}^+$ is your current skill level, and $J \in \{0, 1\}$ is 1 if you are currently employed and zero otherwise.

Actions:

Your action space is continuous: $\alpha \in [0, 1]$ if $J=1$, but is null otherwise (you have no decisions if unemployed). We could also allow for consistency $A = \{\{\alpha \in [0, 1]\}$ even if $J=0$ for consistency, as long as it is not included in the state transition probability calculation.

Rewards:

$R(s, J) = J \cdot \alpha \cdot L \cdot f(s)$, where L is the length of the day in min, & $f(s)$ is wage per min

Transitions:

s varies deterministically: your next day's skill level s' , given your current skill level s , your job status J , and your action α , is:

$$s' = \left(J \cdot g(s)^{\alpha L} + (1-J) \cdot \frac{1}{2^{1/2}} \right) s$$

J varies stochastically: your next days job status J' is a random variable which is a function of both your current job status J & current skill s :

$$J' = J \cdot (1 - \Pi_p) + (1-J) \cdot \Pi_{h(s)}$$

where Π_x is a bernoulli which is 1 w/ prob x

1	2	3	4	5
25	20	10	5	2

 $e^{-1/x}$

Let's plug in some realistic-sounding numbers here. Let $L \approx 60.9 \approx 5+10$,
 let $f(s) = 100,000/250 \cdot L \cdot s$. Let $\lambda \approx 100$. Let $p \approx \frac{1}{250 \cdot 3}$.
 Let $h(s) = \frac{s^2}{s^2+25}$. Let $g(s) = 1 + \frac{1}{s} \cdot \frac{1}{250} \cdot \frac{1}{L/3}$

The limiting factors here are ^{primarily} the size of the action space/state space,
 the long time horizon compared to the frequency of decisions. W/ a
 clever choice of $f(s), g(s), h(s)$, I'm sure this problem can be
 analytically tractable. If we wanted to do it numerically, we could
 restrict α to $\{0, 0.1, \dots, 1\}$, and we could do some kind of linear function
 approx