

A3 Assignment

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Problem Description:

The objective of this assignment is to utilize the ADC system on the MPS430 board to convert a continuous analog signal to a digital I/O signal that will be able to control the frequency in which an external LED blinks.

Pseudocode:

Initialization-

- *Clear Bits
- *Initialize used ports
- *Configure ADC system
 - Read input from POT
 - Single channel, repeated
 - output LED

Main Loop-

- *Read ADC output digital signal
- *compare reference to digital signal
- *Output proper voltage to LED port

*continuous loop

Assembly Code:

```
;-----  
; MSP430 Assembler Code Template for use with TI Code Composer Studio  
;  
;  
;-----  
    .cdecls C,LIST,"msp430.h"    ; Include device header file  
  
;-----  
    .def  RESET                ; Export program entry-point to  
                                ; make it known to linker.  
  
;-----  
  
    .text                      ; Assemble into program memory.  
    .retain                    ; Override ELF conditional linking  
                                ; and retain current section.  
    .retainrefs                ; And retain any sections that have  
                                ; references to current section.  
  
;-----  
RESET    mov.w  #__STACK_END,SP    ; Initialize stackpointer
```

```
StopWDT    mov.w  #WDTPW|WDTHOLD,&WDTCTL ; Stop watchdog timer
```

```
;-----
```

```
; Main loop here
```

```
;-----
```

```
init:
```

```
        bis.b  #BIT1, &P1DIR  ;here we set P1.0 as output for the LED2
```

```
        bic.b  #BIT1, &P1OUT  ; we make sure the LED2 is OFF
```

```
        bis.b  #BIT2, &P1SEL0  ;link P1.2 as ADC controller
```

```
        bis.b  #BIT2, &P1SEL1 ;set P1.1 as analog input
```

```
        mov.w  #0210h, &ADCCTL0 ;set ADC sampling time
```

```
        mov.w  #0220h, &ADCCTL1 ;set ADC conversion mode
```

```
        mov.w  #0020h, &ADCCTL2 ;set ADC resolution
```

```
        mov.w  #0002h, &ADCMCTL0 ;set ADC reference
```

```
        bic.w  #0001h, &PM5CTL0 ;now we unlock the I/O low_power
```

```
;-----Set up timer block
```

```
timer:
```

```

; This sets up the timer. Causing a interrupt to occur every 1
second
mov.w #7FFFh, &TB0CCR0 ; We set the max value for compare
register
bis.w #TBCLR, &TB0CTL ; we set the clear bit in the control
register
bis.w #TBSSEL__ACLK, &TB0CTL ; we select ACLK as source
bis.w #MC__UP, &TB0CTL ; We select continuos mode
counting
bis.w #TBIE, &TB0CTL ; We enable interrupt on overflow
nop
bis.w #GIE, SR ; we enable maskable interrupts
nop

convert:
mov.w #0213h, &ADCCTL0 ;we move digital signal to output pin
here:
bit.w #BIT0, &ADCIFG ;we read the digital signal from ADC
jz here
mov.w ADCMEM0, &TB0CCR0 ;we write trigger the interrupt
jmp convert
nop

```

ISR_TB0:

```

                ;we enter here everytime it interrupts

xor.b  #BIT1, &P1OUT  ;same xor trick to toggle the LED2

bic.w  #TBIFG, &TB0CTL ;We make sure to clear the interrupt flag

reti          ;we return from interrupt

```

```

;-----

```

```

; Stack Pointer definition

```

```

;-----

```

```

    .global __STACK_END

```

```

    .sect .stack

```

```

;-----

```

```

; Interrupt Vectors

```

```

;-----

```

```

    .sect ".reset"      ; MSP430 RESET Vector

```

```

    .short RESET

```

```

    .sect ".int42"

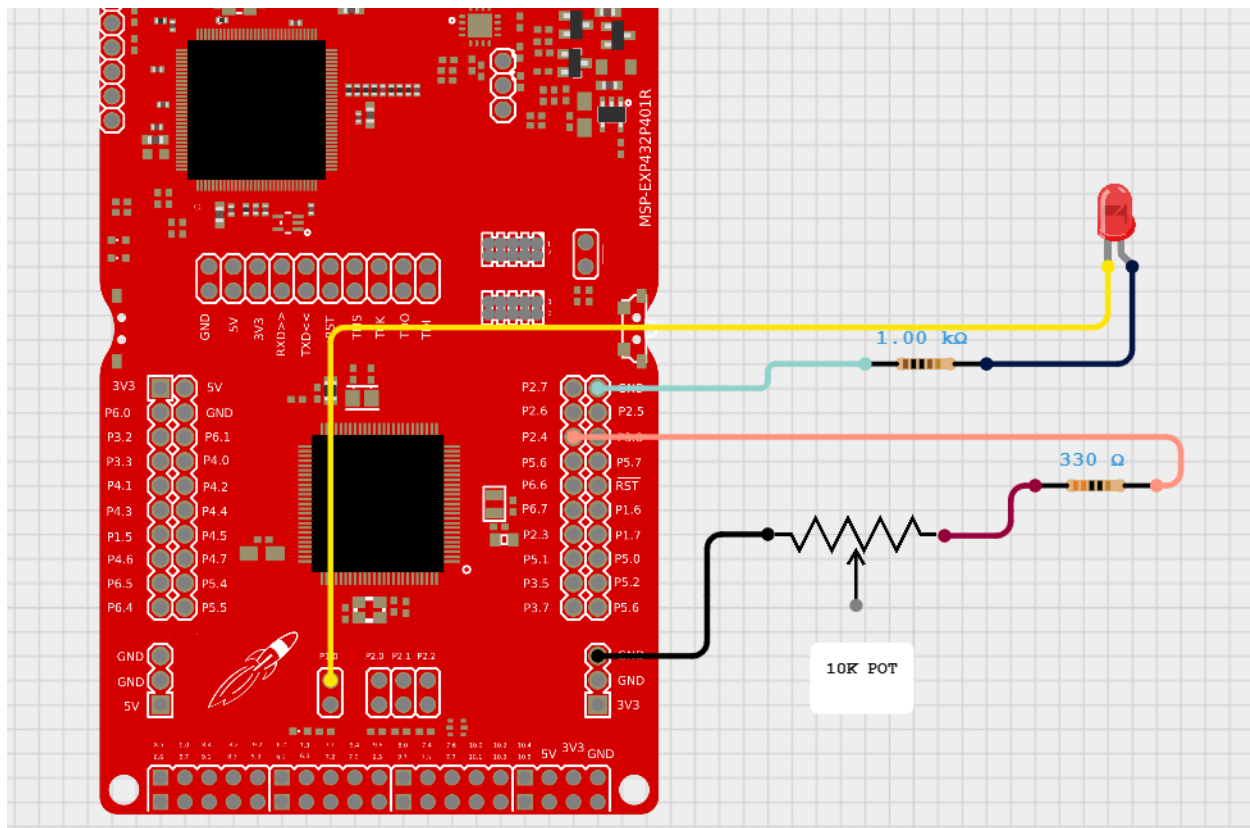
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```

    .short ISR_TB0

```

Wiring Diagram:



Video:

Additional Attachment on Canvas Submission